

PS 4.3

[4]

$$E = (C - 0)^2 + (C + D - 8)^2 + (C + 3D - 8)^2 + (C + 4D - 20)^2$$

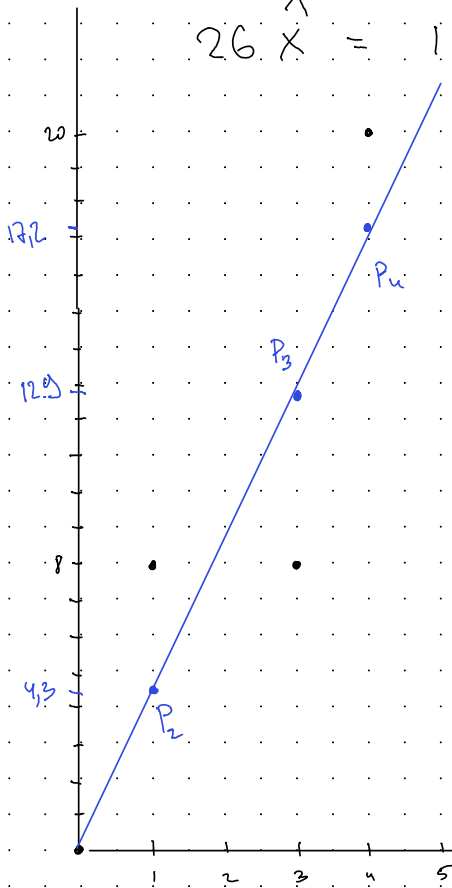
$$\textcircled{B} \quad b = Dt \quad \checkmark$$

$$A = \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 8 \\ 8 \\ 20 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \hat{x} = \begin{bmatrix} 0 & 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 8 \\ 8 \\ 20 \end{bmatrix}$$

$$26 \hat{x} = 112$$

$$\hat{x} = 112/26$$



$$e = p - b = \begin{bmatrix} 0 \\ -3.7 \\ 4.9 \\ -2.8 \end{bmatrix}$$

g) equation $b = C + Dt + Et^2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 3 & 9 \\ 1 & 4 & 16 \end{bmatrix} \begin{bmatrix} C \\ D \\ E \end{bmatrix} = \begin{bmatrix} 0 \\ 8 \\ 8 \\ 20 \end{bmatrix}$$

A x b

$$A^T A = \begin{bmatrix} 4 & 8 & 26 \\ 8 & 26 & 82 \\ 26 & 82 & 202 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 26 \\ 112 \\ 112 \end{bmatrix}$$

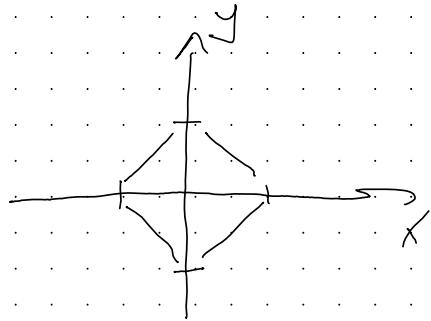
Анализ
график, где
мы спроецируем b

26 ✓

eq. $C + Dx + Ey = b$

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix}$$

$$b = \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix}$$



$$\hat{x} = (A^T A)^{-1} A^T b = \begin{bmatrix} 2,0 \\ -1,5 \\ -1,5 \end{bmatrix}$$

* Коррелирующие
BA \Rightarrow нагрузка генерального
напряжения

$$A^T A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

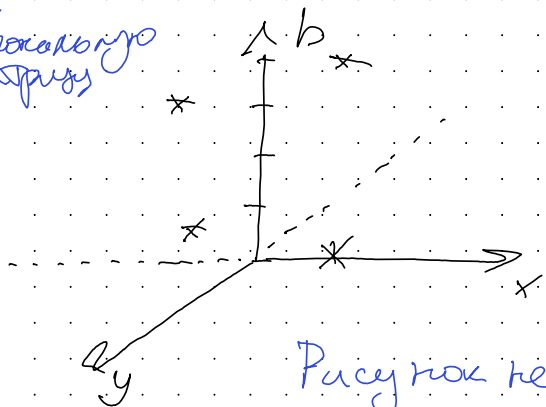


Рисунок не
успешен.

$$A^T b = \begin{bmatrix} 8 \\ -3 \\ -3 \end{bmatrix}$$

$$C = \frac{8}{4}$$

$$D = \frac{-3}{2}$$

$$E = \frac{-3}{2}$$

* Если бы в вопросе не было бы точки $x=0, y=0$
а бы другое b , то не было бы вопроса.

29 ✓ unless linearly dependant or points are colinear

A hyperplane in R^n is defined by eq:

$$C_1 x_1 + C_2 x_2 + \dots + C_n x_n = d$$

$$C [n \times 1] \times [n \times 1]$$

if d is 0
then hyperplane
contains z

$$C^T X = 0$$

↑
normal
vector
to hyperplane

$$\begin{matrix} \text{---} \\ C^T \end{matrix} \begin{matrix} \text{---} \\ X \end{matrix}$$

$$C^T \cdot 0 = 0$$

$$C^T a_1 = 0$$

⋮

$$C^T a_n = 0$$

$${}^{n-1} \begin{bmatrix} -a_1^T & - \\ -a_2^T & - \\ \vdots & \\ -a_n^T & - \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{matrix} n \\ 1 \\ C \end{matrix}$$

A

The hyperplane containing all point a_1, a_2
is unique if all vectors are
independent.

Section 4.4

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$$Q = \begin{bmatrix} 1 & 1 & 1 \\ q_1 & q_2 & q_3 \\ 1 & 1 & 1 \end{bmatrix}$$

18

seems easy

35

How to scale \mathbb{Q} components to integers

Think how to make decomposition

36

Section 5.1

10

Entries of every row of A adds up to 0.

$Ax = 0 \Rightarrow x$ of \mathbb{R}^2 is in nullspace
so A is singular (non zero nullspace)

if entries adds up to 1

$$(A - I)x = 0$$

x of \mathbb{R}^2 is in nullspace

Does this mean $\det(A - I) = 0$
 $\det A = 1$?

Proof by example

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad |A| = -1$$

[18] it was in recitation

[31]

$$\frac{1}{1+1-1}$$

$$\frac{1}{1+2-1}$$

$$\frac{1}{1+3-1}$$

$$\frac{1}{2+1-1}$$

$$\frac{1}{2+2-1}$$

$$\frac{1}{2+3-1}$$

$$\frac{1}{3+1-1}$$

$$\frac{1}{3+2-1}$$

$$\frac{1}{3+3-1}$$

$$\frac{1}{2}$$

$$\frac{1}{2}$$

$$\frac{1}{3}$$

$$\frac{1}{2}$$

$$\frac{1}{3}$$

$$\frac{1}{4}$$

$$\frac{1}{3}$$

$$\frac{1}{4}$$

$$\frac{1}{5}$$