```
1
     #ifndef LABO_1_MATRIX_H
     #define LABO 1 MATRIX H
 2
 3
 4
     #include <iostream>
 5
     #include "operations/Operation.h"
 6
 7
     using DataType = unsigned int; // Data type of the matrix
 8
     /**
 9
10
      * Matrix class
      * This class is used to represent a matrix.
11
12
      * @author Maxime Scharwath
13
      * @author Nicolas Crausaz
14
15
     class Matrix {
16
     public:
          /**
17
           ^{\star} Output Flux Operators for the Matrix Class
18
19
           ^{\star} \mbox{\em 0param} os The output stream
20
           * \ensuremath{\text{\textbf{Qparam}}} m The matrix to output
21
           * @return The output stream
22
23
          friend std::ostream& operator<<(std::ostream& os, const Matrix& m);</pre>
24
          /**
25
           * Addition operator return a new matrix
26
27
           * @param other The matrix to add
28
             @return the new matrix
29
30
          friend Matrix add(const Matrix& lhs, const Matrix& rhs);
31
32
           * Addition operator dynamic version
33
           * \ensuremath{\mathbf{0param}} other The matrix to add
34
3.5
           ^{\star} \mbox{\em Greturn} the new matrix pointer
36
37
          friend Matrix* addDyn(const Matrix& lhs, const Matrix& rhs);
38
39
          /**
40
           * Subtraction operator return a new matrix
           * @param other The matrix to substract
41
42
           * @return the new matrix
43
           */
44
          friend Matrix sub (const Matrix& lhs, const Matrix& rhs);
45
          /**
46
           * Subtraction operator dynamic version
47
           ^{\star} \mbox{\em {\bf Gparam}} other The matrix to substract
48
           ^{\star} \mbox{\em Greturn} the new matrix pointer
49
50
51
          friend Matrix* subDyn(const Matrix& lhs, const Matrix& rhs);
52
53
54
           * Multiplication operator return a new matrix
           ^{\star} @param other The matrix to multiply
55
56
           * @return the new matrix
57
58
          friend Matrix mult (const Matrix& lhs, const Matrix& rhs);
59
60
           * Multiplication operator dynamic version
61
           * @param other The matrix to multiply
62
           ^{\star} \mbox{\em Greturn} the new matrix pointer
63
64
          friend Matrix* multDyn(const Matrix& lhs, const Matrix& rhs);
6.5
66
67
68
           * Main Constructor for the Matrix Class
69
           * @param rows The number of rows
70
           * @param cols The number of columns
71
           * @param modulo The modulo to use
```

```
*/
 72
 73
           Matrix (unsigned int rows, unsigned int cols, unsigned int modulo);
 74
 75
 76
            ^{\star} Square Constructor for the Matrix Class
 77
            * @param size The size of the square matrix
 78
            ^{\star} \mbox{\em 0param} modulo The modulo to use
 79
 80
          Matrix (unsigned int size, unsigned int modulo);
 81
           /**
 82
 83
            * Allocator operator for the Matrix Class
 84
            * @param other The matrix to copy
 85
            * @return The new matrix
 86
 87
           Matrix& operator=(const Matrix& other);
 88
 89
            \ensuremath{^{\star}} Copy constructor for the Matrix Class
 90
 91
            * \ensuremath{\text{@param}} other The matrix to copy
 92
 93
           Matrix (const Matrix & other);
 94
           /**
 95
 96
            * Destructor for the Matrix Class
 97
 98
           ~Matrix();
 99
100
            * Addition operator edit the current matrix
101
102
            * @param other The matrix to add
            \star @return the edited matrix
103
            * /
104
105
           Matrix& add(const Matrix& other);
106
107
            ^{\star} Subtraction operator edit the current matrix
108
109
            * @param other The matrix to substract
110
            \star @return the edited matrix
111
            * /
112
          Matrix& sub(const Matrix& other);
113
           /**
114
115
            * Multiplication operator edit the current matrix
            ^{\star} @param other The matrix to multiply
116
            ^{\star} \mbox{\em Greturn} the edited matrix
117
            * /
118
119
           Matrix& mult(const Matrix& other);
120
121
      private:
122
           unsigned int rows, cols;
123
           unsigned int modulo;
124
           DataType** data;
125
126
127
            * Allocate a new matrix with random values
128
            * @return the matrix data pointer
129
130
           DataType** allocateMatrixData() const;
131
           /**
132
            ^{\star} Allocate a new matrix with the values of another matrix
133
            * @warning No check is done on the dimensions
134
            * @param other The matrix to copy
135
            ^{\star} @return the matrix data pointer
136
137
138
           DataType** allocateMatrixData(const Matrix& other) const;
139
140
141
            * Deallocate the matrix data
142
            * @warning cols and rows must be set before
```

```
* /
143
144
          void deallocateMatrixData();
145
146
            ^{\star} Initialize the matrix with values from another matrix
147
            * @details Used by the copy constructor and the operator=
148
            * \ensuremath{\text{@param}} other The matrix to copy
149
150
151
          void initFrom(const Matrix& other);
152
           /**
153
154
            * Execute an operation on the current matrix
            * @param operation The operation to execute
155
            * \texttt{@param} other The matrix to use with
156
            * @throw std::runtime_error if matrix modulo are different
157
158
159
          void operation (const Operation < DataType > € operation, const Matrix € other);
160
      };
161
162
      #endif //LABO_1_MATRIX_H
163
```

```
1
     #include "Matrix.h"
     #include "operations/AdditionOperation.h"
 2
     #include "operations/SubstrationOperation.h"
 3
     #include "operations/MultiplicationOperation.h"
 4
 5
 6
     // Friend
7
8
     std::ostream& operator<<(std::ostream& os, const Matrix& m) {</pre>
         for (unsigned i = 0; i < m.rows; i++) {</pre>
9
10
             for (unsigned j = 0; j < m.cols; j++) {
11
                  os << m.data[i][j] << " ";
12
13
             os << std::endl;
14
         }
15
         return os;
16
17
18
     Matrix add(const Matrix& lhs, const Matrix& rhs) {
19
         Matrix result(lhs);
20
         return result.add(rhs);
21
     }
22
23
     Matrix* addDyn(const Matrix& lhs, const Matrix& rhs) {
24
         Matrix* result = new Matrix(lhs);
25
         result->add(rhs);
26
         return result;
27
     }
28
29
     Matrix sub (const Matrix & lhs, const Matrix & rhs) {
30
         Matrix result(lhs);
31
         return result.sub(rhs);
32
33
34
     Matrix* subDyn(const Matrix& lhs, const Matrix& rhs) {
3.5
         Matrix* result = new Matrix(lhs);
36
         result->sub(rhs);
37
         return result;
38
     }
39
40
     Matrix mult(const Matrix& lhs, const Matrix& rhs) {
41
         Matrix result(lhs);
42
         return result.mult(rhs);
43
     }
44
45
     Matrix* multDyn(const Matrix& lhs, const Matrix& rhs) {
46
         Matrix* result = new Matrix(lhs);
47
         result->mult(rhs);
48
         return result;
49
     }
50
51
     // Public
52
53
    Matrix::Matrix(unsigned int rows, unsigned int cols, unsigned int modulo) :
54
             rows (rows), cols(cols), modulo (modulo) {
         // Verify params
55
56
         if (rows <= 0 || cols <= 0) {</pre>
57
             throw std::runtime error("Matrix dimensions must be greater than 0");
58
         }
59
60
         if (modulo <= 0) {
61
             throw std::runtime error("Matrix modulo must be greater than 0");
62
63
64
         data = allocateMatrixData();
65
     }
66
67
     Matrix::Matrix(unsigned int size, unsigned int modulo) :
68
             Matrix(size, size, modulo) {}
69
70
     Matrix::~Matrix() {
71
         deallocateMatrixData();
```

Labo 1

```
72
 73
 74
      Matrix& Matrix::operator=(const Matrix& other) {
 75
          if (this != &other) {
 76
              deallocateMatrixData();
 77
              initFrom(other);
 78
          }
 79
          return *this;
 80
      }
 81
 82
      Matrix::Matrix(const Matrix& other) {
 83
          initFrom(other);
 84
 85
      // Private
 86
 87
 88
      void Matrix::initFrom(const Matrix& other) {
 89
          rows = other.rows;
 90
          cols = other.cols;
 91
          modulo = other.modulo;
 92
          data = allocateMatrixData(other);
 93
      }
 94
 95
      DataType** Matrix::allocateMatrixData() const {
 96
          DataType** tmpData = new DataType* [rows];
 97
 98
          for (unsigned i = 0; i < rows; ++i) {
 99
              tmpData[i] = new DataType[cols];
100
              for (unsigned j = 0; j < cols; ++j) {
101
                   tmpData[i][j] = (DataType) (rand() / (RAND_MAX + 1.0) * modulo);
102
103
          }
104
          return tmpData;
105
106
107
      DataType** Matrix::allocateMatrixData(const Matrix& other) const {
108
          DataType** tmpData = new DataType* [rows];
109
110
          for (unsigned i = 0; i < rows; ++i) {
111
              tmpData[i] = new DataType[cols];
112
              for (unsigned j = 0; j < cols; ++j) {
113
                   tmpData[i][j] = other.data[i][j];
114
115
          }
116
          return tmpData;
117
118
119
      void Matrix::deallocateMatrixData() {
120
          for (unsigned i = 0; i < rows; ++i) {
121
              delete[] this->data[i];
122
123
          delete[] data;
124
      }
125
126
      Matrix& Matrix::add(const Matrix& other) {
127
          static AdditionOperation<DataType> op;
128
          operation(op, other);
129
          return *this;
130
      }
131
132
      Matrix& Matrix::sub(const Matrix& other) {
133
          static SubstractionOperation<DataType> op;
134
          operation (op, other);
135
          return *this;
136
      }
137
138
      Matrix& Matrix::mult(const Matrix& other) {
139
          static MultiplicationOperation<DataType> op;
140
          operation (op, other);
141
          return *this;
142
```

```
143
144
      void Matrix::operation(const Operation<DataType>& operation, const Matrix& other) {
145
          if (modulo != other.modulo) {
              throw std::runtime_error("Matrices must have the same modulo");
146
147
          }
148
149
          unsigned maxRows = std::max(rows, other.rows);
150
          unsigned maxCols = std::max(cols, other.cols);
151
152
          DataType** tmp = new DataType* [maxRows];
153
154
          for (unsigned i = 0; i < maxRows; ++i) {</pre>
155
              tmp[i] = new DataType[maxCols];
156
              for (unsigned j = 0; j < maxCols; ++j) {
                  DataType a = (i < rows && j < cols) ? data[i][j] : 0;
157
158
                  DataType b = (i < other.rows && j < other.cols) ? other.data[i][j] : 0;
159
                  tmp[i][j] = operation.execute(a, b) % modulo;
160
              }
161
          }
162
          deallocateMatrixData();
163
          data = tmp;
164
          rows = maxRows;
165
          cols = maxCols;
166
      }
```

```
#ifndef LABO_1_OPERATION_H
#define LABO_1_OPERATION_H
 1
 2
 3
 4
 5
      /**
 6
       * Operation class
 7
       ^{\star} \mbox{\tt @brief} The Operation class is the base class for all operations.
 8
       * @tparam {\mathbb T}
 9
       * @author Maxime Scharwath
10
       * @author Nicolas Crausaz
       */
11
12
      template<typename T>
13
      class Operation {
14
      public:
           /**
15
            ^{\star} execute the operation
16
            \star @param a - first operand
17
            \star @param b - second operand
18
19
            ^{\star} \mbox{\ensuremath{\mbox{\bf @return}}} the result of the operation
20
21
           virtual T execute(T a, T b) const = 0;
22
      };
23
24
      #endif //LABO_1_OPERATION_H
25
```

```
#ifndef LABO_1_ADDITIONOPERATION_H
#define LABO_1_ADDITIONOPERATION_H
 2
 3
 4
     #include "Operation.h"
 5
 6
      * Addition operation.
 7
 8
      * @tparam {\mathbb T}
 9
      * @author Maxime Scharwath
      * @author Nicolas Crausaz
10
      */
11
12
     template<typename T>
     class AdditionOperation : public Operation<T> {
13
14
15
          T execute(T a, T b) const override {
16
               return a + b;
17
          }
18
     };
19
20
     #endif //LABO_1_ADDITIONOPERATION_H
21
```

```
#ifndef LABO_1_SUBSTRATIONOPERATION_H
#define LABO_1_SUBSTRATIONOPERATION_H
 2
 3
 4
     #include "Operation.h"
 5
 6
 7
      * Subtraction operation.
 8
      ^\star @tparam ^{
m T}
 9
      * @author Maxime Scharwath
      * @author Nicolas Crausaz
10
      */
11
12
     template<typename T>
     class SubstractionOperation : public Operation<T> {
13
14
15
         T execute(T a, T b) const override {
16
            return a - b;
17
         }
18
     };
19
20
     #endif //LABO_1_SUBSTRATIONOPERATION_H
21
```

```
#ifndef LABO_1_MULTIPLICATIONOPERATION_H
#define LABO_1_MULTIPLICATIONOPERATION_H
 2
 3
 4
     #include "Operation.h"
 5
 6
 7
      * Multiplication operation.
 8
      ^\star @tparam ^{
m T}
 9
      * @author Maxime Scharwath
      * @author Nicolas Crausaz
10
      */
11
12
     template<typename T>
     class MultiplicationOperation : public Operation<T> {
13
14
15
          T execute(T a, T b) const override {
16
               return a * b;
17
          }
18
     };
19
20
     #endif //LABO_1_MULTIPLICATIONOPERATION_H
21
```

```
1
     #include <iostream>
 2
     #include <ctime>
     #include "Matrix.h"
 3
4
5
     using namespace std;
6
     /**
7
      ^{\star} Unit test for Matrix class.
8
9
10
     void unit tests() {
11
         const unsigned MOD = 8;
12
          cout << "TESTS" << endl;</pre>
13
          // TEST la
14
          cout << "TEST 1a" << endl;</pre>
15
          try {
              // Should throw
16
17
              Matrix mInvalidModulo2(2, 3, 0);
18
          }
19
          catch (const std::exception& e) {
20
              cout << e.what() << endl;</pre>
21
          }
22
23
          // TEST 1b
          cout << "TEST 1b" << endl;</pre>
24
25
          try {
              // Should throw
26
27
              Matrix mInvalidModulo1(2, 0);
28
          }
29
          catch (const std::exception& e) {
30
              cout << e.what() << endl;</pre>
31
          }
32
          // TEST 2a
33
          cout << "TEST 2a" << endl;</pre>
34
3.5
          try {
              // Should throw
36
37
              Matrix mInvalidRowsAndCols(0, 0, MOD);
38
39
          catch (const std::exception& e) {
40
              cout << e.what() << endl;</pre>
41
          }
42
43
          // TEST 2b
44
          cout << "TEST 2b" << endl;</pre>
45
          try {
              // Should throw
46
47
              Matrix mInvalidRows(0, 2, MOD);
48
49
          catch (const std::exception& e) {
50
              cout << e.what() << endl;</pre>
51
          }
52
53
          // TEST 2c
          cout << "TEST 2c" << endl;</pre>
54
          try {
55
56
              // Should throw
57
              Matrix mInvalidCols(2, 0, MOD);
58
          }
59
          catch (const std::exception& e) {
60
              cout << e.what() << endl;</pre>
61
62
          // TEST 2d
63
          cout << "TEST 2d" << endl;
64
65
          try {
              // Should throw
66
67
              Matrix mInvalidCols(0, MOD);
68
          }
69
          catch (const std::exception& e) {
70
              cout << e.what() << endl;</pre>
71
```

```
72
 73
           // TEST 3a
           cout << "TEST 3a" << endl;</pre>
 74
 75
          Matrix validMatrix = Matrix(4, 5, MOD);
 76
           cout << validMatrix << endl;</pre>
 77
 78
           // TEST 3b
           cout << "TEST 3b" << endl;</pre>
 79
 80
           Matrix validSquareMatrix = Matrix(4, MOD);
 81
           cout << validSquareMatrix << endl;</pre>
 82
           // TEST 4a
 83
 84
           cout << "TEST 4a" << endl;</pre>
 85
           Matrix mOneRow (1, 2, MOD);
 86
           cout << mOneRow << endl;</pre>
 87
           // TEST 4b
 88
 89
           cout << "TEST 4b" << endl;</pre>
 90
          Matrix mOneCol(3, 1, MOD);
 91
           cout << mOneCol << endl;</pre>
 92
           // TEST 5a
 93
 94
           cout << "TEST 5a" << endl;</pre>
          Matrix m1(3, 4, MOD);
 95
 96
          Matrix m2 (m1);
 97
           cout << m1 << endl << m2 << endl;
 98
 99
           // TEST 5b
100
           cout << "TEST 5b" << endl;</pre>
101
          Matrix m3(3, MOD);
102
           cout << m1 << endl << m3 << endl;</pre>
103
          m1 = m3;
104
           cout << m1 << endl << m3 << endl;</pre>
105
106
           // TEST 6a
107
           cout << "TEST 6a" << endl;</pre>
108
          Matrix add1 = Matrix(4, 5, MOD);
          Matrix toAdd1 = Matrix(4, 5, MOD);
109
           cout << add1 << "+" << end1 << toAdd1 << "=" << end1;</pre>
110
111
           add1.add(toAdd1);
112
          cout << add1 << endl;</pre>
113
           // TEST 6b
114
115
           cout << "TEST 6b" << endl;</pre>
116
          Matrix add2 = Matrix(2, 4, MOD);
117
          Matrix toAdd2 = Matrix(3, 2, MOD);
           cout << add2 << "+" << end1 << toAdd2 << "=" << end1 << add2.add(toAdd2) << end1;
118
119
           // TEST 6c
120
           cout << "TEST 6c" << endl;</pre>
121
122
          Matrix addCopy1 = Matrix(4, 5, MOD);
123
          Matrix toAddCopy1 = Matrix(4, 5, MOD);
124
           cout << addCopy1 << "+" << endl << toAddCopy1 << "=" << endl << add(addCopy1,</pre>
           toAddCopy1) << endl;</pre>
125
126
           // TEST 6d
127
           cout << "TEST 6d" << endl;</pre>
128
          Matrix addCopy2 = Matrix(2, 4, MOD);
129
          Matrix toAddCopy2 = Matrix(3, 2, MOD);
           cout << addCopy2 << "+" << endl << toAddCopy2 << "=" << endl << add(addCopy2,</pre>
130
           toAddCopy2) << endl;
131
132
           // TEST 6e
           cout << "TEST 6e" << endl;</pre>
133
134
           Matrix addDyn1 = Matrix(4, 5, MOD);
135
          Matrix toAddDyn1 = Matrix(4, 5, MOD);
136
          Matrix* dyn1 = addDyn(addDyn1, toAddDyn1);
137
           cout << addDyn1 << "+" << endl << toAddDyn1 << "=" << endl << *dyn1 << endl;
138
           delete dyn1;
139
140
           // TEST 6f
```

main.cpp

```
141
          cout << "TEST 6f" << endl;</pre>
142
          Matrix addDyn2 = Matrix(2, 4, MOD);
143
          Matrix toAddDyn2 = Matrix(3, 2, MOD);
144
          Matrix* dyn2 = addDyn(addDyn2, toAddDyn2);
          cout << addDyn2 << "+" << endl << toAddDyn2 << "=" << endl << *dyn2 << endl;
145
146
          delete dyn2;
147
148
          // TEST 7a
          cout << "TEST 7a" << endl;</pre>
149
150
          Matrix sub1 = Matrix(4, 5, MOD);
1.51
          Matrix toSub1 = Matrix(4, 5, MOD);
152
          cout << sub1 << "-" << end1 << toSub1 << "=" << end1 << end1;
153
          sub1.sub(toSub1);
154
          cout << sub1 << endl;</pre>
155
          // TEST 7b
156
          cout << "TEST 7b" << endl;</pre>
1.57
158
          Matrix sub2 = Matrix(2, 4, MOD);
159
          Matrix toSub2 = Matrix(3, 2, MOD);
          cout << sub2 << "-" << endl << toSub2 << "=" << endl << endl;
160
161
          sub2.sub(toSub2);
162
          cout << sub2 << endl;</pre>
163
          // TEST 7c
164
          cout << "TEST 7c" << endl;</pre>
165
166
          Matrix subCopy1 = Matrix(4, 5, MOD);
167
          Matrix toSubCopy1 = Matrix(4, 5, MOD);
168
          cout << subCopy1 << "-" << endl << toSubCopy1 << "=" << endl << sub(subCopy1,</pre>
          toSubCopy1) << endl;
169
           // TEST 7d
170
          cout << "TEST 7d" << endl;</pre>
171
172
          Matrix subCopy2 = Matrix(2, 4, MOD);
173
          Matrix toSubCopy2 = Matrix(3, 2, MOD);
174
          cout << subCopy2 << "-" << endl << toSubCopy2 << "=" << endl << sub(subCopy2,</pre>
          toSubCopy2) << endl;</pre>
175
          // TEST 7e
176
177
          cout << "TEST 7e" << endl;</pre>
178
          Matrix subDyn1 = Matrix(4, 5, MOD);
179
          Matrix toSubDyn1 = Matrix(4, 5, MOD);
180
          Matrix* dyn3 = subDyn(subDyn1, toSubDyn1);
181
          cout << subDyn1 << "-" << endl << toSubDyn1 << "=" << endl << *dyn3 << endl;
182
          delete dyn3;
183
          // TEST 6f
184
          cout << "TEST 6f" << endl;</pre>
185
186
          Matrix subDyn2 = Matrix(2, 4, MOD);
187
          Matrix toSubDyn2 = Matrix(3, 2, MOD);
188
          Matrix* dyn4 = subDyn(subDyn2, toSubDyn2);
189
          cout << subDyn2 << "-" << endl << toSubDyn2 << "=" << endl << *dyn4 << endl;
190
          delete dyn4;
191
192
          // TEST 8a
          cout << "TEST 8a" << endl;</pre>
193
          Matrix mult1 = Matrix(4, 5, MOD);
194
195
          Matrix toMult1 = Matrix(4, 5, MOD);
196
          cout << mult1 << "*" << end1 << toMult1 << "=" << end1 << end1;
          mult1.mult(toMult1);
197
198
          cout << mult1 << endl;</pre>
199
           // TEST 8b
200
          cout << "TEST 8b" << endl;</pre>
201
          Matrix mult2 = Matrix(4, 5, MOD);
202
          Matrix toMult2 = Matrix(4, 5, MOD);
203
          cout << mult2 << "*" << endl << toMult2 << "=" << endl << endl;</pre>
204
205
          mult2.mult(toMult2);
206
          cout << mult2 << endl;</pre>
207
208
           // TEST 8c
209
          cout << "TEST 8c" << endl;</pre>
```

```
main.cpp
  210
            Matrix multCopy1 = Matrix(4, 5, MOD);
  211
            Matrix toMultCopy1 = Matrix(4, 5, MOD);
            cout << multCopy1 << "*" << endl << toMultCopy1 << "=" << endl <<</pre>
  212
            mult(multCopy1, toMultCopy1) << endl;</pre>
  213
             // TEST 8d
  214
            cout << "TEST 8d" << endl;</pre>
  215
            Matrix multCopy2 = Matrix(2, 4, MOD);
  216
  217
            Matrix toMultCopy2 = Matrix(3, 2, MOD);
            cout << multCopy2 << "*" << endl << toMultCopy2 << "=" << endl <<</pre>
  218
            mult(multCopy2, toMultCopy2) << endl;</pre>
  219
  220
            // TEST 8e
  221
            cout << "TEST 8e" << endl;</pre>
  222
            Matrix multDyn1 = Matrix(4, 5, MOD);
  223
            Matrix toMultDyn1 = Matrix(4, 5, MOD);
  224
            Matrix* dyn5 = multDyn(multDyn1, toMultDyn1);
  225
            cout << multDyn1 << "*" << endl << toMultDyn1 << "=" << endl << *dyn5 << endl;
  226
            delete dyn5;
  227
            // TEST 8f
  228
            cout << "TEST 8f" << endl;</pre>
  229
            Matrix multDyn2 = Matrix(2, 4, MOD);
  230
            Matrix toMultDyn2 = Matrix(3, 2, MOD);
  231
  232
            Matrix* dyn6 = multDyn(multDyn2, toMultDyn2);
            cout << multDyn2 << "*" << endl << toMultDyn2 << "=" << endl << *dyn6 << endl;
  233
  234
            delete dyn6;
  235
        }
  236
        /**
  237
  238
         * Main program entry point
         * @author Maxime Scharwath
  239
         * @author Nicolas Crausaz
  240
         * @return
  241
  242
         * /
  243
        int main() {
  244
            srand(time(nullptr)); // Initialize random seed
  245
  246
            const unsigned MOD = 5;
  247
  248
            cout << "The modulus is " << MOD << endl;</pre>
            cout << "one" << endl;</pre>
  249
  250
            Matrix one = Matrix(3, 4, MOD);
  251
            cout << one << endl;</pre>
  252
            cout << "two" << endl;</pre>
  253
  254
            Matrix two = Matrix(3, 5, MOD);
  255
            cout << two << endl;</pre>
  256
  257
            cout << "one + two" << endl << add(one, two) << endl;</pre>
  258
  259
            cout << "one - two" << endl << sub(one, two) << endl;</pre>
  260
  261
            cout << "one x two" << endl << mult(one, two) << endl;</pre>
  262
  263
             // More specific tests
  264
            unit tests();
  265
            return 0;
  266
        }
  267
```