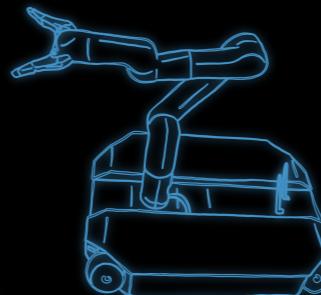


Trajectory Generation for Mobile Manipulators with Differential Geometry

Behavior Encoding beyond
Model Predictive Control

Trajectory Generation for Mobile Manipulators with Differential Geometry

Max Spahn



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