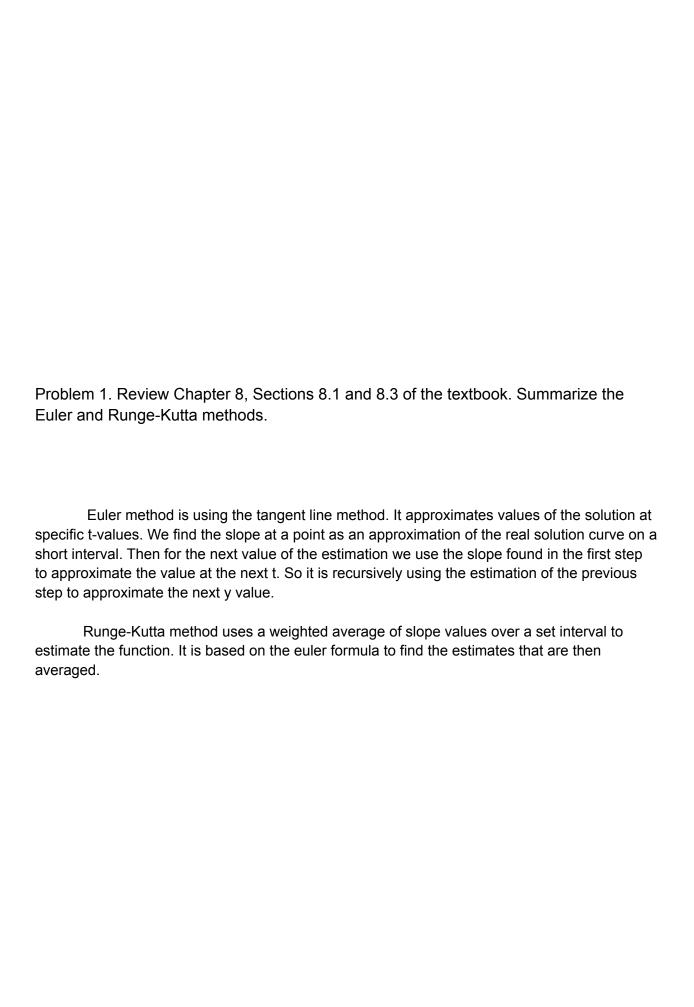
MATH 345L - Spring 2022

LAB Project- Solving ODEs using Euler and Runge-Kutta methods

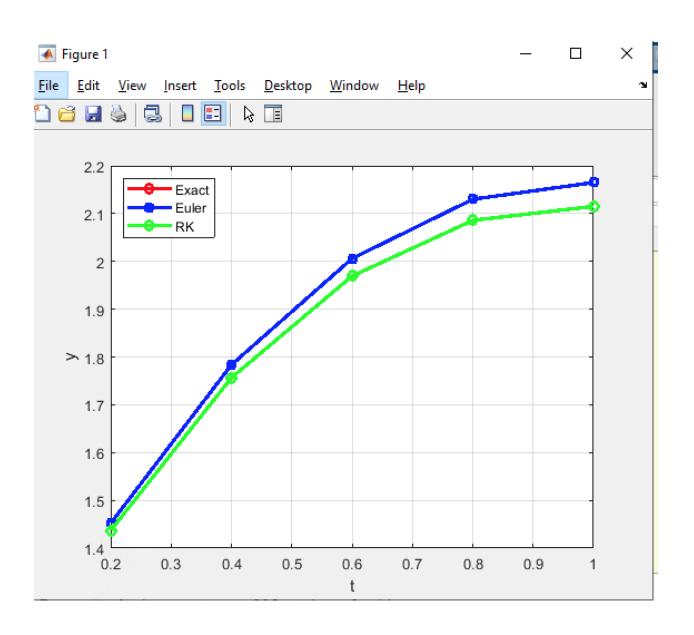
Maxwell Griffith



h=.05					
t	exact	euler	Rk	euler abs error	rk abs error
0.2	1.4371	1.4521	1.4371	0.0149	0
0.4	1.7565	1.7835	1.7565	0.027	0
0.6	1.9694	2.006	1.9694	0.0367	0
0.8	2.0858	2.13	2.0858	0.0442	0
1	2.1151	2.1651	2.1151	0.05	0
h=.1					
t	exact	euler	Rk	euler abs error	rk abs error
0.2	1.4371	1.4675	1.4371	0.0304	0
0.4	1.7565	1.8114	1.7565	0.0549	0
0.6	1.9694	2.0438	1.9694	0.0744	0
0.8	2.0858	2.1755	2.0858	0.0897	0
1	2.1151	2.2164	2.1151	0.1013	0
h=.025					
t	exact	euler	Rk	euler abs error	rk abs error
0.2	1.4371	1.4445	1.4371	0.0074	0
0.4	1.7565	1.7699	1.7565	0.0134	0
0.6	1.9694	1.9876	1.9694	0.0182	0
0.8	2.0858	2.1078	2.0858	0.0219	0
1	2.1151	2.1399	2.1151	0.0248	0

Problem 4. Compare the results obtained from the Euler method with the RK method (i.e., using the absolute error).

The RK method is much more accurate because the absolute error values are almost zero.



## APPENDIX 1

```
%INPUT - ODE (string), y0=init cond (init), T=t_values (array), h= step size (int)
%OUTPT - euler values = estimaties of y (array)
function [euler values] = Euler Method(ODE, y0, T, h)
0/_____
% Define the differential equation y'=f(t,y)
%-----
f=inline(ODE,'t','y');
%-----
% Set initial condition
%_____
t0=0:
% Loop to solve the IVP four times -- once for each entry in T
% Use Euler method.
0/0-----
for j=1:length(T)
     % We need this many iterations to get to T with a stepsize of h.
     steps=round(T(j)/h);
     % Start at initial condition each time through
     y_n=y0;
     t_n=t0;
```

```
% Implement the Euler method
       for i=1:steps
       y_np1=y_n+f(t_n,y_n)*h;
       t_n=t_n+h;
       y_n=y_np1;
       end
       euler_values{j}=y_n; %returns y values as array
end
APPENDIX 2
%INPUT - ODE (string), y0=init cond (init), T=t_values (array), h= step size (int), t0
%OUTPT - euler_values = estimaties of y (array)
function [rk_values] = RK_Method(ODE, y0, T, h, t0)
f=inline(ODE,'t','y');
for j=1:length(T)
 steps=round(T(j)/h);
 y=y0;
 t=t0;
       for i=1:steps
       k1=f(t,y);
       k2=f(t + h/2, y + h*k1/2);
       k3=f(t + h/2, y + h*k2/2);
       k4=f(t+h, y + h*k3);
       next_y=y + h^*(k1 + 2^*k2 + 2^*k3 + k4)/6;
       t=t+h;
       y=next_y;
       end
 %add y value to rk values
 rk_values{j}=y; %returns y values as array
end
```

```
APPENDIX 3
% INPUT - ODE (text), y0 (init), t_values (array)
% Output - exact_values (array)

function [exact_values] = Exact_Method(ODE, y0, t_values)

eqn = strcat('Dy=',ODE)
inits = sprintf('y(0)=%0.2g',y0)

t = t_values;
y = dsolve(eqn,inits, 't');
exact_values = eval(vectorize(y));

%test values y' = 2y-3t; y(0)=1, at t=0.1, 0.2, 0.3
%exact_values = [1.2054,1.4230,1.6555,1.9064]
```

## clc; clear all; close all;

**APPENDIX 4** 

%% Find absolute error using |y\_exact-y\_n\_tot|
EulerAbsError = abs(y\_exact - cell2mat(y\_euler))
RKAbsError = abs(y\_exact - cell2mat(y\_rk))

y\_rk = RK\_Method(ODE, y0, t\_values, step\_size, t0)

%%Create Table-how to export as csv?
%Euler Sol, RK Sol, Exact Sol, Euler Error, RK Error

%%Sketch Graph

figure;

plot(t\_values,y\_exact, '-ro','Linewidth',2.5); hold on; plot(t\_values,cell2mat(y\_euler),'-bs', 'Linewidth',2.5); plot(t\_values,cell2mat(y\_rk),'-go', 'Linewidth',2.5);

```
legend('Exact','Euler','RK', 'Location','NorthWest'); xlabel('t'); ylabel('y'); grid on;
```