

Frequency Domain Analysis of Circuits

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University of Nebraska-Lincoln

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Why Frequency Domain Analysis?

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Introduction to
Frequency
Domain

Phasor
Representation

Impedance

Phasor Circuit
Analysis

AC Power
Analysis

Summary

Phasor Basics
Problems

Impedance
Calculation
Problems

Circuit Analysis

AC Power
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Limitations of Time Domain:

- Differential equations for AC circuits
- Complex trig math
- Difficult for sinusoidal steady-state

Frequency Domain Advantages:

- Converts differential equations to algebra
- Easy handling of sinusoidal signals
- Simplifies AC circuit analysis

Applications:

- AC power systems (60 Hz)
- Audio systems (20 Hz - 20 kHz)
- Radio frequency circuits (MHz - GHz)
- Signal processing and filtering

Domain Transformation Tool

Phasor transform converts time-domain sinusoids to frequency-domain complex numbers

Goal for this lecture

Review frequency domain (phasor) analysis for AC circuits

Sinusoidal Signals: The Foundation

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General Sinusoidal Signal:

$$v(t) = V_m \cos(\omega t + \phi)$$

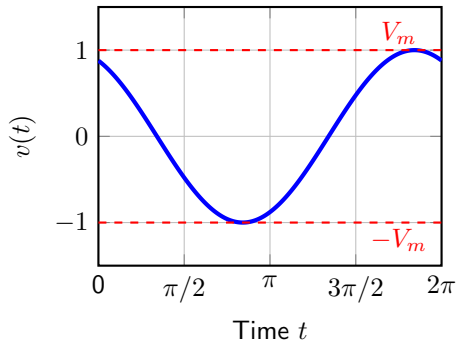
where:

- V_m = amplitude (peak value)
- ω = angular frequency (rad/s)
- ϕ = phase angle (radians or degrees)

Related Parameters:

- Frequency: $f = \omega/(2\pi)$ (Hz)
- Period: $T = 1/f = 2\pi/\omega$ (s)
- RMS value: $V_{rms} = V_m/\sqrt{2}$

Sinusoidal Waveform:



Phasor Concept: From Time to Frequency Domain

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Euler's Identity:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

Sinusoid as Complex Exponential:

$$v(t) = V_m \cos(\omega t + \phi)$$

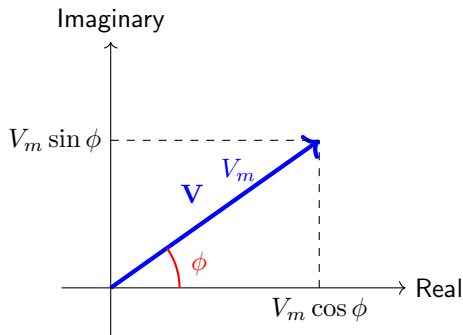
$$v(t) = \operatorname{Re}\{V_m e^{j(\omega t + \phi)}\}$$

$$v(t) = \operatorname{Re}\{V_m e^{j\phi} e^{j\omega t}\}$$

Phasor Definition

$$\mathbf{V} = V_m e^{j\phi} = V_m \angle \phi$$

Phasor Diagram:



Rectangular Form:

$$\mathbf{V} = V_m \cos \phi + j V_m \sin \phi$$

Phasor Transform: Summary

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Time Domain	Phasor Domain	Operation
$V_m \cos(\omega t + \phi)$	$\mathbf{V} = V_m \angle \phi$	Domain transformation
$\frac{d}{dt}$	$j\omega$	Differentiation \rightarrow multiplication
$\int dt$	$\frac{1}{j\omega}$	Integration \rightarrow division
Addition	Addition	Same (LTI Systems)

Key Advantage

- 😊 **Differentiation** in time domain \rightarrow **Multiplication** by $j\omega$ in phasor domain.
- 😞 Phasor analysis only works for **linear circuits** with **sinusoidal sources** at the **same frequency** in **steady-state**

Electrical Impedance

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Definition:

Impedance is the ratio of phasor voltage to phasor current:

$$\mathbf{Z} = \frac{\mathbf{V}}{\mathbf{I}}$$

Polar Form:

$$\mathbf{Z} = |\mathbf{Z}| \angle \theta$$

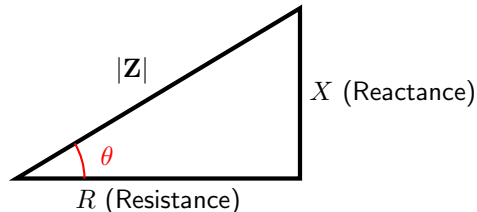
Rectangular Form:

$$\mathbf{Z} = R + jX$$

where:

- R = resistance (real part)
- X = reactance (imaginary part)

Impedance in Complex Plane:



Relationships:

$$|\mathbf{Z}| = \sqrt{R^2 + X^2}$$

$$\theta = \tan^{-1} \left(\frac{X}{R} \right)$$

Impedance of R, L, and C

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Element	Time Domain	Impedance	Phase
Resistor	$v = iR$	$\mathbf{Z}_R = R$	0
Inductor	$v = L \frac{di}{dt}$	$\mathbf{Z}_L = j\omega L$	+90
Capacitor	$i = C \frac{dv}{dt}$	$\mathbf{Z}_C = \frac{1}{j\omega C} = \frac{-j}{\omega C}$	-90

Resistor:

- Real impedance
- V and I in phase
- Frequency independent

Inductor:

- Imaginary impedance
- V leads I by 90°
- $|\mathbf{Z}_L| = \omega L$ increases with ω

Capacitor:

- Imaginary impedance
- I leads V by 90°
- $|\mathbf{Z}_C| = 1/(\omega C)$ decreases with ω

Frequency Behavior of Impedance

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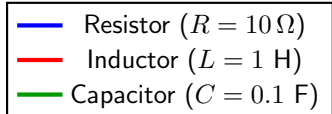
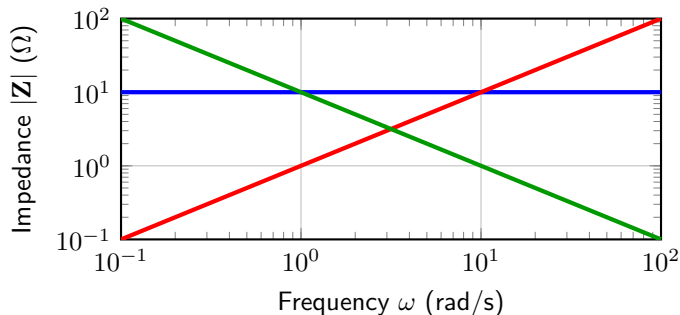
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Frequency Behavior

- **Resistor:** Constant impedance (frequency independent)
- **Inductor:** High impedance at high frequencies (blocks AC, passes DC)
- **Capacitor:** Low impedance at high frequencies (blocks DC, passes AC)

Phasor Analysis: Circuit Laws

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All DC circuit analysis techniques apply to phasors

Kirchhoff's Voltage Law (KVL):

$$\sum \mathbf{V}_k = 0$$

Kirchhoff's Current Law (KCL):

$$\sum \mathbf{I}_k = 0$$

Ohm's Law:

$$\mathbf{V} = \mathbf{I}\mathbf{Z}$$

Series Impedances:

$$\mathbf{Z}_{eq} = \mathbf{Z}_1 + \mathbf{Z}_2 + \cdots + \mathbf{Z}_n$$

Parallel Impedances:

$$\mathbf{Z}_{eq}^{-1} = \mathbf{Z}_1^{-1} + \mathbf{Z}_2^{-1} + \cdots + \mathbf{Z}_n^{-1}$$

Voltage Divider:

$$\mathbf{V}_k = \mathbf{V}_s \mathbf{Z}_k (\mathbf{Z}_1 + \mathbf{Z}_2)^{-1}$$

Key Point

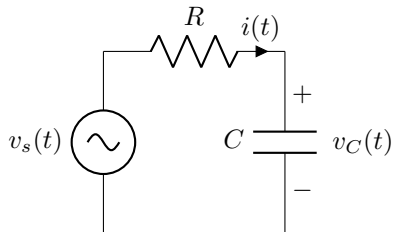
Replace resistances with impedances, and voltages/currents with phasors. Then use the standard DC techniques

Example: Series RC Circuit

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Circuit:



Given:

- $v_s(t) = V_m \cos(\omega t)$
- $R = 100 \Omega$
- $C = 10 \mu\text{F}$
- $\omega = 1000 \text{ rad/s}$

Phasor Analysis:

Source phasor: $\mathbf{V}_s = V_m \angle 0$

Impedances:

$$\mathbf{Z}_R = 100 \Omega$$

$$\mathbf{Z}_C = \frac{-j}{\omega C} = \frac{-j}{0.01} = -j100 \Omega$$

Total impedance:

$$\begin{aligned}\mathbf{Z}_{eq} &= R - jX_C = 100 - j100 \\ &= 141.4 \angle -45^\circ \Omega\end{aligned}$$

Current:

$$\mathbf{I} = \frac{\mathbf{V}_s}{\mathbf{Z}_{eq}} = \frac{V_m \angle 0}{141.4 \angle -45^\circ} = \frac{V_m}{141.4} \angle 45^\circ$$

Example: Phasor Diagram

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Voltage Divider:

Capacitor voltage:

$$\begin{aligned}\mathbf{V}_C &= \mathbf{V}_s \frac{\mathbf{Z}_C}{\mathbf{Z}_R + \mathbf{Z}_C} \\ &= \mathbf{V}_s \frac{-j100}{100 - j100} \\ &= \mathbf{V}_s \frac{100 \angle -90}{141.4 \angle -45} \\ &= 0.707V_m \angle -45\end{aligned}$$

Resistor voltage:

$$\mathbf{V}_R = \mathbf{I}R = 0.707V_m \angle 45$$

Phasor Diagram:

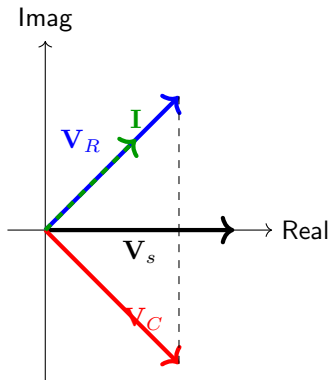


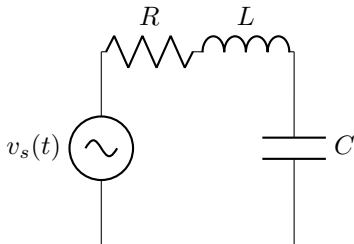
Figure 1: $\mathbf{V}_R + \mathbf{V}_C = \mathbf{V}_s$ (KVL)

Example: Series RLC Circuit

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Circuit:



Total Impedance:

$$\begin{aligned}\mathbf{Z} &= R + j\omega L + \frac{1}{j\omega C} = R + j\left(\omega L - \frac{1}{\omega C}\right) \\ &= R + j(X_L - X_C)\end{aligned}$$

Three Cases:

1. Inductive ($X_L > X_C$):

- Net reactance is positive
- Voltage leads current
- Behaves like RL circuit

2. Capacitive ($X_L < X_C$):

- Net reactance is negative
- Current leads voltage
- Behaves like RC circuit

3. Resonant ($X_L = X_C$):

- Net reactance is zero
- $\mathbf{Z} = R$ (purely resistive)
- \mathbf{V} and \mathbf{I} in phase

Resonance in RLC Circuits

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Resonance Condition:

At resonance: $X_L = X_C$

$$\omega_0 L = \frac{1}{\omega_0 C}$$

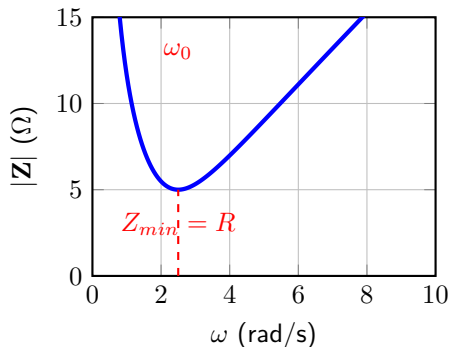
Resonant Frequency

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

At Resonance:

- $Z = R$ (minimum impedance)
- Maximum current
- Zero phase angle

Impedance vs. Frequency:



AC Power: Instantaneous and Average

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Instantaneous Power:

For $v(t) = V_m \cos(\omega t)$ and
 $i(t) = I_m \cos(\omega t - \theta)$:

$$p(t) = v(t) \cdot i(t)$$

$$= V_m I_m \cos(\omega t) \cos(\omega t - \theta)$$

Using trig identity:

$$p(t) = \frac{V_m I_m}{2} \cos \theta + \frac{V_m I_m}{2} \cos(2\omega t - \theta)$$

Average Power:

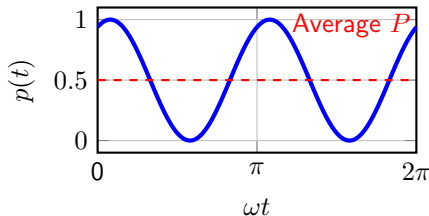
$$P = \frac{1}{T} \int_0^T p(t) dt = \frac{V_m I_m}{2} \cos \theta$$

Using RMS Values:

$$V_{rms} = \frac{V_m}{\sqrt{2}}, \quad I_{rms} = \frac{I_m}{\sqrt{2}}$$

Average (Real) Power

$$P = V_{rms} I_{rms} \cos \theta$$



Reactive and Apparent Power

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Power Components:

1. Real (Average) Power:

$$P = V_{rms} I_{rms} \cos \theta \quad (\text{W})$$

- Power dissipated (resistors)

2. Reactive Power:

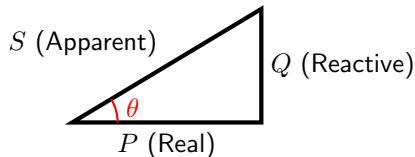
$$Q = V_{rms} I_{rms} \sin \theta \quad (\text{VAR})$$

- Power stored/returned (L/C)

3. Apparent Power:

$$S = V_{rms} I_{rms} \quad (\text{VA})$$

Power Triangle:



$$S = \sqrt{P^2 + Q^2}$$

$$P = S \cos \theta, \quad Q = S \sin \theta$$

Power Factor:

$$\text{pf} = \cos \theta = \frac{P}{S}$$

Power Factor and Its Importance

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Power Factor Definition:

$$\text{pf} = \cos \theta = \frac{P}{S}$$

Range: $0 \leq \text{pf} \leq 1$

Special Cases:

😊 **pf = 1** (unity): purely resistive, $\theta = 0$

☹️ **pf = 0**: purely reactive, $\theta = \pm 90$

Leading vs. Lagging:

- Lagging pf: inductive load (current lags voltage)
- Leading pf: capacitive load (current leads voltage)

Low Power Factor Problems

- ☹️ Higher current required
- ☹️ Larger conductor sizes needed
- ☹️ More I^2R losses in transmission

Power Factor Correction:

Add capacitors in parallel with inductive loads to:

- 😊 Increase power factor
- 😊 Reduce reactive power
- 😊 Lower current draw

Power in Circuit Elements

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Element	Phase	Real Power P	Reactive Power Q	pf
Resistor	$\theta = 0$	$I^2 R$	0	1
Inductor	$\theta = 90$	0	$I^2 X_L$ (positive)	0
Capacitor	$\theta = -90$	0	$-I^2 X_C$ (negative)	0

Key Observations

- Only **resistors** dissipate real power (convert to heat · or light if you mess up)
- **Inductors** and **capacitors** store and return energy (reactive power)
- Reactive power from L and C have opposite signs (can cancel to form resonant networks)

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Phasor Analysis:

- Transform: $V_m \cos(\omega t + \phi) \leftrightarrow V_m \angle \phi$
- ☺ Differential equations \rightarrow algebra
- $d/dt \rightarrow j\omega$, $\int dt \rightarrow 1/(j\omega)$

Impedance:

- $\mathbf{Z} = R + jX$
- Resistor: $\mathbf{Z}_R = R$
- Inductor: $\mathbf{Z}_L = j\omega L$
- Capacitor: $\mathbf{Z}_C = 1/(j\omega C)$

Circuit Analysis:

- ☺ All DC techniques apply
- KVL, KCL, voltage/current dividers
- Series/parallel combinations

AC Power:

- Real power: $P = V_{rms} I_{rms} \cos \theta$
- Reactive power: $Q = V_{rms} I_{rms} \sin \theta$
- Apparent power: $S = V_{rms} I_{rms}$

Power Factor:

- $\text{pf} = \cos \theta = P/S$
- Lagging pf: inductive
- Leading pf: capacitive
- ☹ Low pf \rightarrow higher losses

Resonance:

- Occurs when $X_L = X_C$
- $\omega_0 = 1/\sqrt{LC}$
- ☺ Minimum Z , maximum I

Comparison: Time vs. Frequency Domain

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Aspect	Time Domain	Frequency Domain
Signals	$v(t)$, $i(t)$ (real functions)	\mathbf{V} , \mathbf{I} (complex phasors)
Math	Differential equations	Algebraic equations
Circuit elements	R, L, C (time relations)	\mathbf{Z}_R , \mathbf{Z}_L , \mathbf{Z}_C (impedances)
Analysis	Initial conditions, transients	Steady-state, magnitude/phase
Advantages	Shows time evolution	Simplifies sinusoidal analysis
Limitations	Complex for AC steady-state	Only sinusoidal steady-state

When to Use Each

Time Domain: Transients, switching, initial conditions, non-sinusoidal signals

Frequency Domain: AC steady-state, sinusoidal sources, impedance analysis

Example 1: Phasor Conversions

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Problem: Convert the following time-domain signals to phasors, then perform the operations.

Given:

$$v_1(t) = 10 \cos(1000t + 30) \text{ V}$$

$$v_2(t) = 5 \cos(1000t - 45) \text{ V}$$

$$i(t) = 2 \cos(1000t + 60) \text{ A}$$

Find:

- 1 Phasor forms of v_1 , v_2 , and i
- 2 $\mathbf{V}_1 + \mathbf{V}_2$
- 3 $\mathbf{V}_1 - \mathbf{V}_2$
- 4 \mathbf{V}_1/\mathbf{I}

Solution:

Part 1: Phasor forms

$$\mathbf{V}_1 = 10 \angle 30^\circ \text{ V}$$

$$\mathbf{V}_2 = 5 \angle -45^\circ \text{ V}$$

$$\mathbf{I} = 2 \angle 60^\circ \text{ A}$$

Part 2: $\mathbf{V}_1 + \mathbf{V}_2$

Convert to rectangular:

$$\begin{aligned} \mathbf{V}_1 &= 10 \cos(30^\circ) + j10 \sin(30^\circ) \\ &= 8.66 + j5.00 \text{ V} \end{aligned}$$

$$\begin{aligned} \mathbf{V}_2 &= 5 \cos(-45^\circ) + j5 \sin(-45^\circ) \\ &= 3.54 - j3.54 \text{ V} \end{aligned}$$

Example 1: Solution (continued)

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Part 2 (continued):

$$\begin{aligned}\mathbf{V}_1 + \mathbf{V}_2 &= (8.66 + j5.00) + (3.54 - j3.54) \\ &= 12.20 + j1.46 \text{ V}\end{aligned}$$

Convert to polar:

$$|\mathbf{V}| = \sqrt{12.20^2 + 1.46^2} = 12.29 \text{ V}$$

$$\angle \mathbf{V} = \tan^{-1} \left(\frac{1.46}{12.20} \right) = 6.83$$

$$\boxed{\mathbf{V}_1 + \mathbf{V}_2 = 12.29 \angle 6.83 \text{ V}}$$

Part 3: $\mathbf{V}_1 - \mathbf{V}_2$

$$\begin{aligned}\mathbf{V}_1 - \mathbf{V}_2 &= (8.66 + j5.00) - (3.54 - j3.54) \\ &= 5.12 + j8.54 \text{ V} \\ &= 9.96 \angle 59.05 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_1 - \mathbf{V}_2 = 9.96 \angle 59.05 \text{ V}}$$

Part 4: \mathbf{V}_1/\mathbf{I} (This is impedance!)

$$\begin{aligned}\frac{\mathbf{V}_1}{\mathbf{I}} &= \frac{10 \angle 30}{2 \angle 60} = \frac{10}{2} \angle (30 - 60) \\ &= 5 \angle -30 \Omega\end{aligned}$$

$$\boxed{\mathbf{Z} = 5 \angle -30 \Omega = 4.33 - j2.50 \Omega}$$

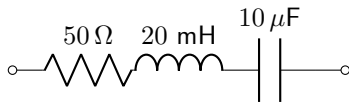
Example 2: Impedance at Different Frequencies

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Problem: A series circuit contains $R = 50\ \Omega$, $L = 20\ \text{mH}$, and $C = 10\ \mu\text{F}$. Find the total impedance at the following frequencies.

Circuit:



Given:

- $R = 50\ \Omega$
- $L = 20\ \text{mH}$
- $C = 10\ \mu\text{F}$

Find the total impedance at:

- (a) $f = 100\ \text{Hz}$
- (b) $f = 500\ \text{Hz}$
- (c) $f = 1000\ \text{Hz}$

For each frequency, determine:

- 1 Magnitude $|\mathbf{Z}|$
- 2 Phase angle θ
- 3 Whether the circuit is inductive or capacitive

Example 2: Solution - Setup and Part (a)

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General Formula for Series RLC:

$$\mathbf{Z} = R + j\omega L + \frac{1}{j\omega C} = R + j\left(\omega L - \frac{1}{\omega C}\right)$$

where $X_L = \omega L$ (inductive reactance) and $X_C = \frac{1}{\omega C}$ (capacitive reactance)

Part (a): $f = 100 \text{ Hz}$

$$\omega = 2\pi f = 2\pi(100) = 628.3 \text{ rad/s}$$

$$X = X_L - X_C = -146.6 \Omega$$

$$\mathbf{Z} = 50 - j146.6 \Omega$$

$$\boxed{\mathbf{Z} = 154.9 \angle -71.2^\circ \Omega}$$

$$X_L = \omega L = 628.3 \times 0.02 = 12.57 \Omega$$

Capacitive behavior (negative reactance, current leads)

$$X_C = \frac{1}{\omega C} = \frac{1}{628.3 \times 10^{-5}} = 159.2 \Omega$$

Example 2: Solution - Parts (b) and (c)

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Part (b): $f = 500 \text{ Hz}$

$$\omega = 2\pi(500) = 3141.6 \text{ rad/s}$$

$$X_L = 3141.6 \times 0.02 = 62.83 \Omega$$

$$X_C = \frac{1}{3141.6 \times 10^{-5}} = 31.83 \Omega$$

$$X = 62.83 - 31.83 = 31.0 \Omega$$

$$\mathbf{Z} = 50 + j31.0 \Omega$$

$$\boxed{\mathbf{Z} = 59.0 \angle 31.8 \Omega}$$

Inductive behavior (positive reactance, current lags)

Part (c): $f = 1000 \text{ Hz}$

$$\omega = 2\pi(1000) = 6283.2 \text{ rad/s}$$

$$X_L = 6283.2 \times 0.02 = 125.7 \Omega$$

$$X_C = \frac{1}{6283.2 \times 10^{-5}} = 15.92 \Omega$$

$$X = 125.7 - 15.92 = 109.8 \Omega$$

$$\mathbf{Z} = 50 + j109.8 \Omega$$

$$\boxed{\mathbf{Z} = 120.7 \angle 65.5 \Omega}$$

Inductive behavior (positive reactance, current lags)

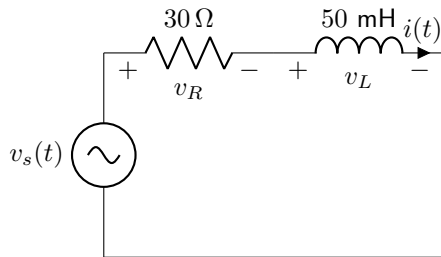
Example 3: Series RL Circuit

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Problem: For the circuit shown, find the current, voltage across each element, and draw the phasor diagram.

Circuit:



Given:

- $v_s(t) = 100 \cos(2000t)\text{ V}$
- $R = 30\ \Omega$
- $L = 50\text{ mH} = 0.05\text{ H}$
- $\omega = 2000\text{ rad/s}$

Find:

- 1 Total impedance \mathbf{Z}_{tot}
- 2 Current $i(t)$ (phasor and time domain)
- 3 Voltage across resistor $v_R(t)$
- 4 Voltage across inductor $v_L(t)$
- 5 Draw the phasor diagram
- 6 Verify KVL

Example 3: Solution - Impedance and Current

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Step 1: Convert to phasor domain

Source phasor:

$$\mathbf{V}_s = 100\angle 0^\circ \text{ V}$$

Step 2: Calculate impedances

Resistor impedance:

$$\mathbf{Z}_R = R = 30 \Omega$$

Inductor impedance:

$$\begin{aligned}\mathbf{Z}_L &= j\omega L \\ &= j(2000)(0.05) \\ &= j100 \Omega\end{aligned}$$

Step 3: Total impedance

Rectangular form:

$$\mathbf{Z}_{tot} = \mathbf{Z}_R + \mathbf{Z}_L = 30 + j100 \Omega$$

Polar form:

$$|\mathbf{Z}_{tot}| = \sqrt{30^2 + 100^2} = 104.4 \Omega$$

$$\theta_Z = \tan^{-1} \left(\frac{100}{30} \right) = 73.3^\circ$$

$$\boxed{\mathbf{Z}_{tot} = 104.4\angle 73.3^\circ \Omega}$$

Example 3: Solution - Current (continued)

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Step 4: Calculate current

Using Ohm's law:

$$\begin{aligned}\mathbf{I} &= \frac{\mathbf{V}_s}{\mathbf{Z}_{tot}} \\ &= \frac{100\angle 0}{104.4\angle 73.3} \\ &= \frac{100}{104.4}\angle (0 - 73.3) \\ &= 0.958\angle -73.3 \text{ A}\end{aligned}$$

$$\boxed{\mathbf{I} = 0.958\angle -73.3 \text{ A}}$$

Step 5: Convert to time domain

$$\boxed{i(t) = 0.958 \cos(2000t - 73.3) \text{ A}}$$

Interpretation

Current **lags** the voltage by 73.3, which is expected for an inductive circuit (RL circuit).

Example 3: Solution - Element Voltages

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Step 6: Voltage across resistor

Using Ohm's law:

$$\begin{aligned}\mathbf{V}_R &= \mathbf{I} \cdot \mathbf{Z}_R \\ &= (0.958 \angle -73.3)(30 \angle 0) \\ &= 0.958 \times 30 \angle (-73.3 + 0) \\ &= 28.7 \angle -73.3 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_R = 28.7 \angle -73.3 \text{ V}}$$

Time domain:

$$v_R(t) = 28.7 \cos(2000t - 73.3) \text{ V}$$

Note: \mathbf{V}_R is in phase with \mathbf{I} (both at -73.3)

Step 7: Voltage across inductor

Using Ohm's law:

$$\begin{aligned}\mathbf{V}_L &= \mathbf{I} \cdot \mathbf{Z}_L \\ &= (0.958 \angle -73.3)(100 \angle 90) \\ &= 0.958 \times 100 \angle (-73.3 + 90) \\ &= 95.8 \angle 16.7 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_L = 95.8 \angle 16.7 \text{ V}}$$

Time domain:

$$v_L(t) = 95.8 \cos(2000t + 16.7) \text{ V}$$

Note: \mathbf{V}_L leads \mathbf{I} by 90 (as expected for an inductor)

Example 3: Solution - Phasor Diagram and Verification

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Step 8: Verify KVL

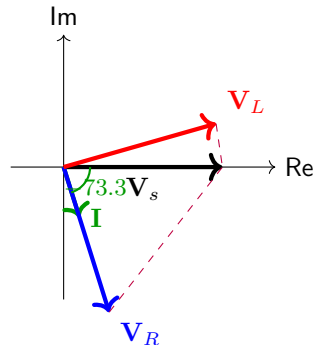
Check: $\mathbf{V}_R + \mathbf{V}_L = \mathbf{V}_s$

Convert to rectangular:

$$\begin{aligned}\mathbf{V}_R &= 28.7 \angle -73.3 \\ &= 28.7 \cos(-73.3) + j28.7 \sin(-73.3) \\ &= 8.26 - j27.49 \text{ V}\end{aligned}$$

$$\begin{aligned}\mathbf{V}_L &= 95.8 \angle 16.7 \\ &= 95.8 \cos(16.7) + j95.8 \sin(16.7) \\ &= 91.74 + j27.49 \text{ V}\end{aligned}$$

$$\begin{aligned}\mathbf{V}_R + \mathbf{V}_L &= (8.26 - j27.49) + (91.74 + j27.49) \\ &= 100 + j0 = 100 \angle 0 \text{ V}\end{aligned}$$



Key Observations

- $\mathbf{V}_R \parallel \mathbf{I}$ (resistor)
- $\mathbf{V}_L \perp \mathbf{I}$, leads by 90 (inductor)
- $\mathbf{V}_R + \mathbf{V}_L = \mathbf{V}_s$ (KVL)

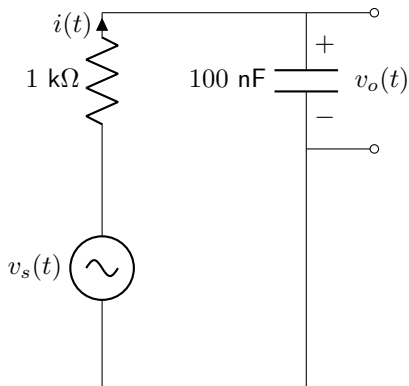
Example 4: RC Voltage Divider

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Problem: Analyze the following RC voltage divider circuit.

Circuit:



Given:

- $v_s(t) = 10 \cos(10000t)\text{ V}$
- $R = 1\text{ k}\Omega$
- $C = 100\text{ nF}$

Find:

- 1 The impedance of each element
- 2 The output voltage \mathbf{V}_o
- 3 The output voltage $v_o(t)$
- 4 The magnitude ratio $|\mathbf{V}_o|/|\mathbf{V}_s|$
- 5 The phase shift between input and output
- 6 The current $i(t)$

Example 4: Solution

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Solution:

Source phasor: $V_s = 10\angle 0 \text{ V}$
 $\omega = 10000 \text{ rad/s}$

1. Impedances:

$$Z_R = 1000 \Omega$$

$$Z_C = \frac{1}{j\omega C} = \frac{1}{j(10^4)(10^{-7})} = -j1000 \Omega$$

2. Output Voltage (voltage divider)

$$\begin{aligned} V_o &= V_s \frac{Z_C}{Z_R + Z_C} \\ &= 10\angle 0 \cdot \frac{-j1000}{1000 - j1000} \\ &= 10 \cdot \frac{1000\angle -90}{1414.2\angle -45} \\ &= 10 \cdot 0.707\angle -45 \\ &= \boxed{7.07\angle -45 \text{ V}} \end{aligned}$$

Example 4: Solution (continued)

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3. Time domain:

$$v_o(t) = 7.07 \cos(10000t - 45) \text{ V}$$

4. Magnitude ratio:

$$\frac{|V_o|}{|V_s|} = \frac{7.07}{10} = 0.707$$

5. Phase shift: -45 (output lags input)

6. Current:

$$\mathbf{I} = \frac{\mathbf{V}_s}{\mathbf{Z}_R + \mathbf{Z}_C} = \frac{10 \angle 0}{1414.2 \angle -45} \\ = 7.07 \angle 45 \text{ mA}$$

$$i(t) = 7.07 \cos(10000t + 45) \text{ mA}$$

Example 5: AC Power Calculation

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Problem: Calculate the real, reactive, and apparent power for a load with the following voltage and current.

Given:

$$v(t) = 120\sqrt{2} \cos(377t) \text{ V}$$

$$i(t) = 10\sqrt{2} \cos(377t - 36.87) \text{ A}$$

Note: The coefficients include $\sqrt{2}$ to indicate peak values

Find:

- 1 RMS voltage and current
- 2 Real power P
- 3 Reactive power Q
- 4 Apparent power S
- 5 Power factor (and type)
- 6 Load impedance \mathbf{Z}

Example 5: Solution - RMS Values and Powers

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Step 1: RMS values

Convert from peak to RMS:

$$V_{rms} = \frac{V_m}{\sqrt{2}} = \frac{120\sqrt{2}}{\sqrt{2}} = \boxed{120 \text{ V}}$$

$$I_{rms} = \frac{I_m}{\sqrt{2}} = \frac{10\sqrt{2}}{\sqrt{2}} = \boxed{10 \text{ A}}$$

Step 2: Determine phase angle

From the time-domain expressions:

- Voltage phase: $\phi_v = 0$
- Current phase: $\phi_i = -36.87$

Phase difference:

$$\theta = \phi_v - \phi_i = 0 - (-36.87) = 36.87$$

Current lags voltage \Rightarrow inductive load

Step 3: Real power

$$\begin{aligned} P &= V_{rms} I_{rms} \cos \theta \\ &= (120)(10) \cos(36.87) = \boxed{960 \text{ W}} \end{aligned}$$

Step 4: Reactive power

$$\begin{aligned} Q &= V_{rms} I_{rms} \sin \theta \\ &= (120)(10) \sin(36.87) = \boxed{720 \text{ VAR}} \end{aligned}$$

Step 5: Apparent power

$$S = V_{rms} I_{rms} = \boxed{1200 \text{ VA}}$$

Verify:

$$S = \sqrt{P^2 + Q^2} = \sqrt{960^2 + 720^2} = 1200$$

Example 5: Solution - Power Factor and Impedance

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Step 6: Power factor

Method 1 - From angle:

$$\begin{aligned}\text{pf} &= \cos \theta = \cos(36.87) \\ &= \boxed{0.8 \text{ lagging}}\end{aligned}$$

Method 2 - From powers:

$$\begin{aligned}\text{pf} &= \frac{P}{S} = \frac{960}{1200} \\ &= 0.8 \text{ lagging}\end{aligned}$$

“Lagging” because current lags voltage (inductive)

Step 7: Load impedance

Convert to phasor form:

$$\begin{aligned}\mathbf{V} &= 120\angle 0^\circ \text{ V} \\ \mathbf{I} &= 10\angle -36.87^\circ \text{ A}\end{aligned}$$

Calculate impedance:

$$\begin{aligned}\mathbf{Z} &= \frac{\mathbf{V}}{\mathbf{I}} = \frac{120\angle 0^\circ}{10\angle -36.87^\circ} \\ &= 12\angle 36.87^\circ \Omega \\ \mathbf{Z} &= 12(\cos 36.87^\circ + j \sin 36.87^\circ) \\ &= \boxed{9.6 + j7.2 \Omega}\end{aligned}$$

This represents $R = 9.6 \Omega$ in series with $X_L = 7.2 \Omega$

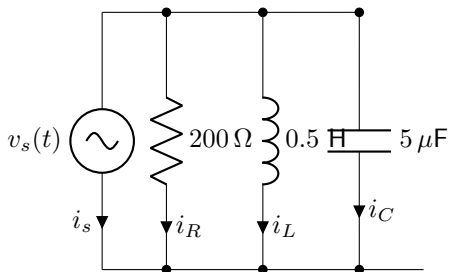
Example 6: Parallel RLC Circuit

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Problem: Analyze the parallel RLC circuit shown below.

Circuit:



Given:

■ $v_s(t) = 50 \cos(1000t)\ \text{V}$

Find:

- 1 Impedance of each branch
- 2 Total impedance
- 3 Source current $i_s(t)$
- 4 Current through each branch
- 5 Total real power
- 6 Total reactive power
- 7 Is the circuit inductive or capacitive?

Example 6: Solution

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Solution:

$$\mathbf{V}_s = 50\angle 0^\circ \text{ V}, \omega = 1000 \text{ rad/s}$$

1. Branch impedances:

$$\mathbf{Z}_R = 200 \Omega$$

$$\mathbf{Z}_L = j\omega L = j(1000)(0.5) = j500 \Omega$$

$$\begin{aligned}\mathbf{Z}_C &= \frac{1}{j\omega C} = \frac{1}{j(1000)(5 \times 10^{-6})} \\ &= -j200 \Omega\end{aligned}$$

2. Total impedance:

$$\begin{aligned}\frac{1}{\mathbf{Z}_{tot}} &= \frac{1}{200} + \frac{1}{j500} + \frac{1}{-j200} \\ &= 0.005 + j0.003\end{aligned}$$

$$\begin{aligned}\mathbf{Z}_{tot} &= \frac{1}{0.005 + j0.003} = \frac{1}{0.00583\angle 30.96^\circ} \\ &= \boxed{171.5\angle -30.96^\circ \Omega} \\ &= 147.1 - j88.0 \Omega\end{aligned}$$

3. Source current:

$$\begin{aligned}\mathbf{I}_s &= \frac{\mathbf{V}_s}{\mathbf{Z}_{tot}} = \frac{50\angle 0^\circ}{171.5\angle -30.96^\circ} \\ &= 0.292\angle 30.96^\circ \text{ A}\end{aligned}$$

$$\boxed{i_s(t) = 0.292 \cos(1000t + 30.96^\circ) \text{ A}}$$

Example 6: Solution (continued)

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4. Branch currents:

$$\mathbf{I}_R = \frac{\mathbf{V}_s}{\mathbf{Z}_R} = \frac{50}{200} = 0.25 \angle 0^\circ \text{ A}$$

$$\mathbf{I}_L = \frac{50 \angle 0^\circ}{500 \angle 90^\circ} = 0.1 \angle -90^\circ \text{ A}$$

$$\mathbf{I}_C = \frac{50 \angle 0^\circ}{200 \angle -90^\circ} = 0.25 \angle 90^\circ \text{ A}$$

5. Total real power:

Only resistor dissipates real power:

$$P = I_R^2 R = \boxed{12.5 \text{ W}}$$

or using $P = V_{rms} I_{s,rms} \cos \theta$:

$$P = 50 \times 0.292 \times \cos(30.96) = 12.5 \text{ W}$$

6. Total reactive power:

$$Q_L = I_L^2 X_L = (0.1)^2 \times 500 = 5 \text{ VAR}$$

$$Q_C = -I_C^2 X_C = -(0.25)^2 \times 200 = -12.5 \text{ VAR}$$

$$Q_{tot} = Q_L + Q_C = \boxed{-7.5 \text{ VAR}}$$

or:

$$\begin{aligned} Q &= V_{rms} I_{s,rms} \sin \theta \\ &= 50 \times 0.292 \times \sin(30.96) = -7.5 \text{ VAR} \end{aligned}$$

7. Circuit behavior:

$Q_{tot} < 0$ and current leads voltage ($\theta > 0$)
Capacitor reactive power dominates