

ECEN 222

Maxx Seminario

Introduction to  
Frequency  
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Phasor  
Representation

Impedance

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# Frequency Domain Analysis of Circuits

Maxx Seminario

University of Nebraska-Lincoln

Spring 2026

# Why Frequency Domain Analysis?

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## Limitations of Time Domain:

- Differential equations for AC circuits
- Complex trig math
- Difficult for sinusoidal steady-state

## Frequency Domain Advantages:

- Converts differential equations to algebra
- Easy handling of sinusoidal signals
- Simplifies AC circuit analysis

## Applications:

- AC power systems (60 Hz)
- Audio systems (20 Hz - 20 kHz)
- Radio frequency circuits (MHz - GHz)
- Signal processing and filtering

## Domain Transformation Tool

**Phasor transform** converts time-domain sinusoids to frequency-domain complex numbers

## Goal for this lecture

Review frequency domain (phasor) analysis for AC circuits

# Sinusoidal Signals: The Foundation

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## General Sinusoidal Signal:

$$v(t) = V_m \cos(\omega t + \phi)$$

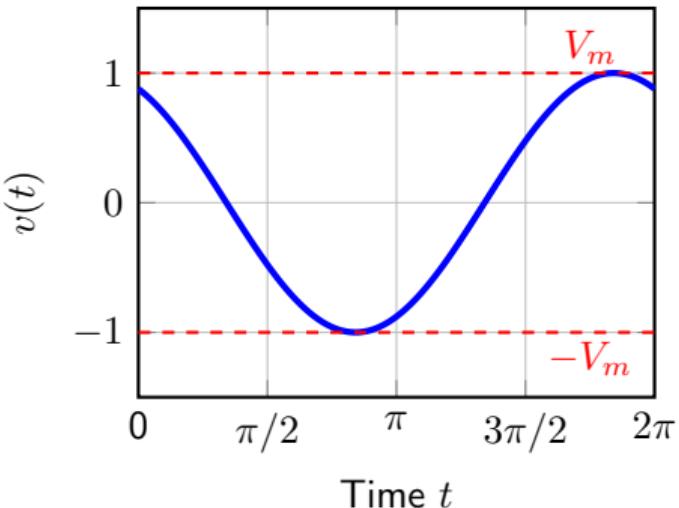
where:

- $V_m$  = amplitude (peak value)
- $\omega$  = angular frequency (rad/s)
- $\phi$  = phase angle (radians or degrees)

## Related Parameters:

- Frequency:  $f = \omega/(2\pi)$  (Hz)
- Period:  $T = 1/f = 2\pi/\omega$  (s)
- RMS value:  $V_{rms} = V_m/\sqrt{2}$

## Sinusoidal Waveform:



# Phasor Concept: From Time to Frequency Domain

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## Euler's Identity:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

## Sinusoid as Complex Exponential:

$$v(t) = V_m \cos(\omega t + \phi)$$

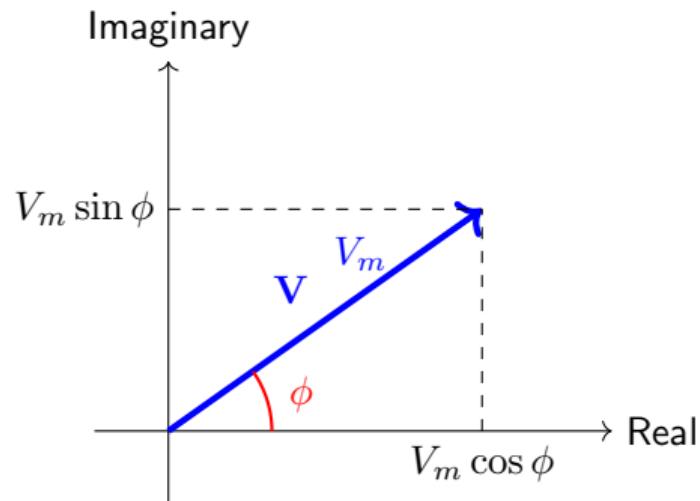
$$v(t) = \operatorname{Re}\{V_m e^{j(\omega t + \phi)}\}$$

$$v(t) = \operatorname{Re}\{V_m e^{j\phi} e^{j\omega t}\}$$

## Phasor Definition

$$\mathbf{V} = V_m e^{j\phi} = V_m \angle \phi$$

## Phasor Diagram:



## Rectangular Form:

$$\mathbf{V} = V_m \cos \phi + j V_m \sin \phi$$

# Phasor Transform: Summary

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Time Domain	Phasor Domain	Operation
$V_m \cos(\omega t + \phi)$	$\mathbf{V} = V_m \angle \phi$	Domain transformation
$\frac{d}{dt}$	$j\omega$	Differentiation $\rightarrow$ multiplication
$\int dt$	$\frac{1}{j\omega}$	Integration $\rightarrow$ division
Addition	Addition	Same (LTI Systems)

## Key Advantage

- 😊 **Differentiation** in time domain  $\rightarrow$  **Multiplication** by  $j\omega$  in phasor domain.
- 😊 Phasor analysis only works for **linear circuits** with **sinusoidal sources** at the **same frequency** in **steady-state**

# Electrical Impedance

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## Definition:

Impedance is the ratio of phasor voltage to phasor current:

$$Z = \frac{V}{I}$$

## Polar Form:

$$Z = |Z| \angle \theta$$

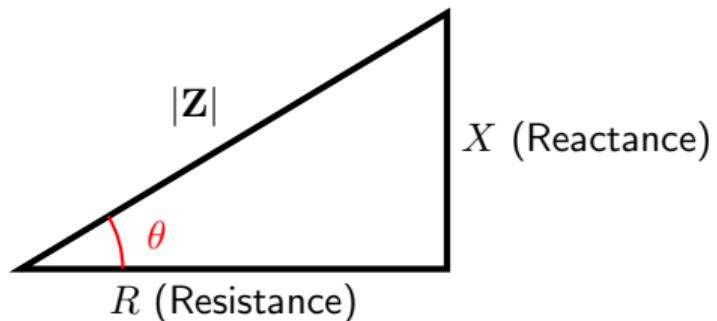
## Rectangular Form:

$$Z = R + jX$$

where:

- $R$  = resistance (real part)
- $X$  = reactance (imaginary part)

## Impedance in Complex Plane:



## Relationships:

$$|Z| = \sqrt{R^2 + X^2}$$

$$\theta = \tan^{-1} \left( \frac{X}{R} \right)$$

# Impedance of R, L, and C

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Element	Time Domain	Impedance	Phase
Resistor	$v = iR$	$\mathbf{Z}_R = R$	0
Inductor	$v = L \frac{di}{dt}$	$\mathbf{Z}_L = j\omega L$	+90
Capacitor	$i = C \frac{dv}{dt}$	$\mathbf{Z}_C = \frac{1}{j\omega C} = \frac{-j}{\omega C}$	-90

## Resistor:

- Real impedance
- V and I in phase
- Frequency independent

## Inductor:

- Imaginary impedance
- V leads I by 90°
- $|\mathbf{Z}_L| = \omega L$  increases with  $\omega$

## Capacitor:

- Imaginary impedance
- I leads V by 90°
- $|\mathbf{Z}_C| = 1/(\omega C)$  decreases with  $\omega$

# Frequency Behavior of Impedance

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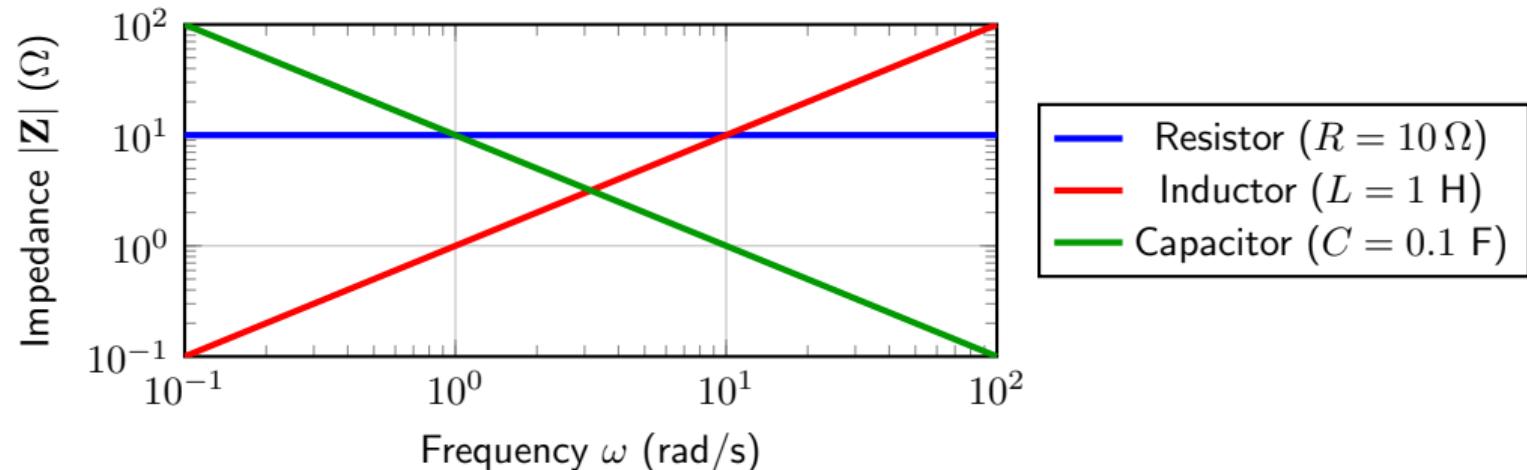
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## Frequency Behavior

- **Resistor:** Constant impedance (frequency independent)
- **Inductor:** High impedance at high frequencies (blocks AC, passes DC)
- **Capacitor:** Low impedance at high frequencies (blocks DC, passes AC)

# Phasor Analysis: Circuit Laws

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All DC circuit analysis techniques apply to phasors

**Kirchhoff's Voltage Law (KVL):**

$$\sum \mathbf{V}_k = 0$$

**Series Impedances:**

$$\mathbf{Z}_{eq} = \mathbf{Z}_1 + \mathbf{Z}_2 + \cdots + \mathbf{Z}_n$$

**Kirchhoff's Current Law (KCL):**

$$\sum \mathbf{I}_k = 0$$

**Parallel Impedances:**

$$\mathbf{Z}_{eq}^{-1} = \mathbf{Z}_1^{-1} + \mathbf{Z}_2^{-1} + \cdots + \mathbf{Z}_n^{-1}$$

**Ohm's Law:**

$$\mathbf{V} = \mathbf{I}\mathbf{Z}$$

**Voltage Divider:**

$$\mathbf{V}_k = \mathbf{V}_s \mathbf{Z}_k (\mathbf{Z}_1 + \mathbf{Z}_2)^{-1}$$

**Key Point**

Replace resistances with impedances, and voltages/currents with phasors. Then use the standard DC techniques

# Example: Series RC Circuit

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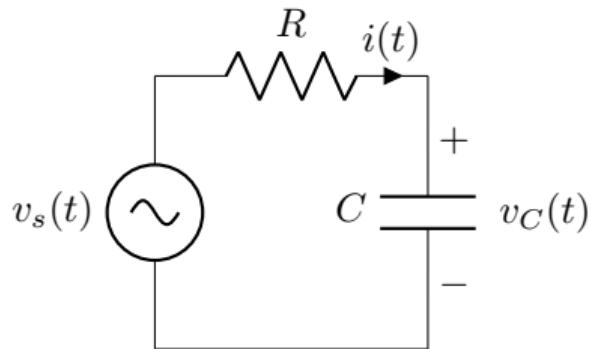
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**Circuit:**



**Given:**

- $v_s(t) = V_m \cos(\omega t)$
- $R = 100 \Omega$
- $C = 10 \mu\text{F}$
- $\omega = 1000 \text{ rad/s}$

**Phasor Analysis:**

Source phasor:  $\mathbf{V}_s = V_m \angle 0$

Impedances:

$$\mathbf{Z}_R = 100 \Omega$$

$$\mathbf{Z}_C = \frac{-j}{\omega C} = \frac{-j}{0.01} = -j100 \Omega$$

Total impedance:

$$\begin{aligned}\mathbf{Z}_{eq} &= R - jX_C = 100 - j100 \\ &= 141.4 \angle -45^\circ\end{aligned}$$

Current:

$$\mathbf{I} = \frac{\mathbf{V}_s}{\mathbf{Z}_{eq}} = \frac{V_m \angle 0}{141.4 \angle -45^\circ} = \frac{V_m}{141.4} \angle 45^\circ$$

# Example: Phasor Diagram

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## Voltage Divider:

Capacitor voltage:

$$\mathbf{V}_C = \mathbf{V}_s \frac{\mathbf{Z}_C}{\mathbf{Z}_R + \mathbf{Z}_C}$$

$$= \mathbf{V}_s \frac{-j100}{100 - j100}$$

$$= \mathbf{V}_s \frac{100 \angle -90^\circ}{141.4 \angle -45^\circ}$$

$$= 0.707V_m \angle -45^\circ$$

Resistor voltage:

$$\mathbf{V}_R = \mathbf{I}R = 0.707V_m \angle 45^\circ$$

## Phasor Diagram:

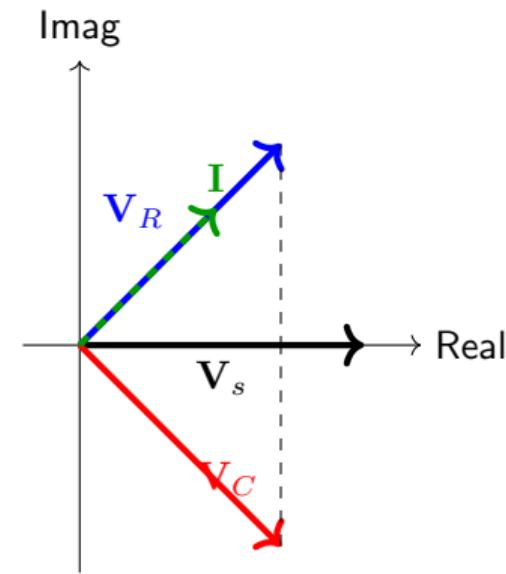


Figure 1:  $\mathbf{V}_R + \mathbf{V}_C = \mathbf{V}_s$  (KVL)

# Example: Series RLC Circuit

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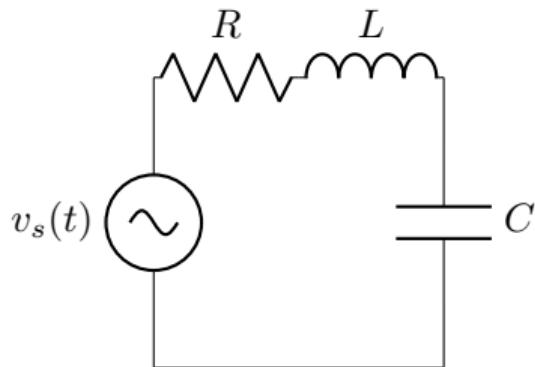
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## Circuit:



## Total Impedance:

$$\begin{aligned} \mathbf{Z} &= R + j\omega L + \frac{1}{j\omega C} = R + j \left( \omega L - \frac{1}{\omega C} \right) \\ &= R + j(X_L - X_C) \end{aligned}$$

## Three Cases:

### 1. Inductive ( $X_L > X_C$ ):

- Net reactance is positive
- Voltage leads current
- Behaves like RL circuit

### 2. Capacitive ( $X_L < X_C$ ):

- Net reactance is negative
- Current leads voltage
- Behaves like RC circuit

### 3. Resonant ( $X_L = X_C$ ):

- Net reactance is zero
- $\mathbf{Z} = R$  (purely resistive)
- V and I in phase

# Resonance in RLC Circuits

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## Resonance Condition:

At resonance:  $X_L = X_C$

$$\omega_0 L = \frac{1}{\omega_0 C}$$

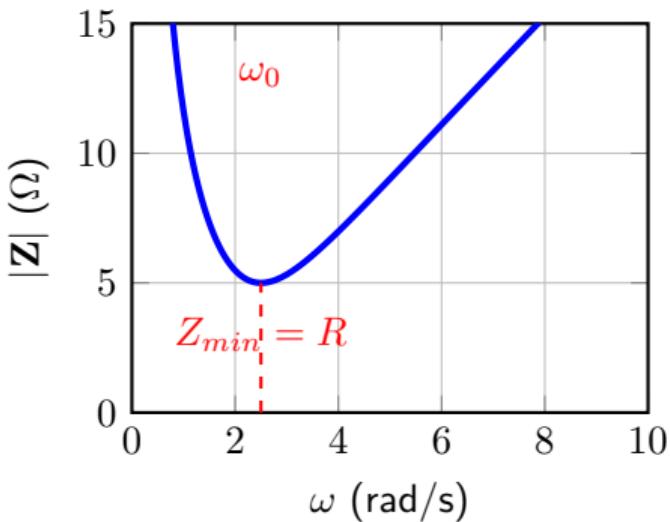
## Resonant Frequency

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

## At Resonance:

- $Z = R$  (minimum impedance)
- Maximum current
- Zero phase angle

## Impedance vs. Frequency:



# AC Power: Instantaneous and Average

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## Instantaneous Power:

For  $v(t) = V_m \cos(\omega t)$  and  
 $i(t) = I_m \cos(\omega t - \theta)$ :

$$p(t) = v(t) \cdot i(t)$$

$$= V_m I_m \cos(\omega t) \cos(\omega t - \theta)$$

Using trig identity:

$$p(t) = \frac{V_m I_m}{2} \cos \theta + \frac{V_m I_m}{2} \cos(2\omega t - \theta)$$

## Average Power:

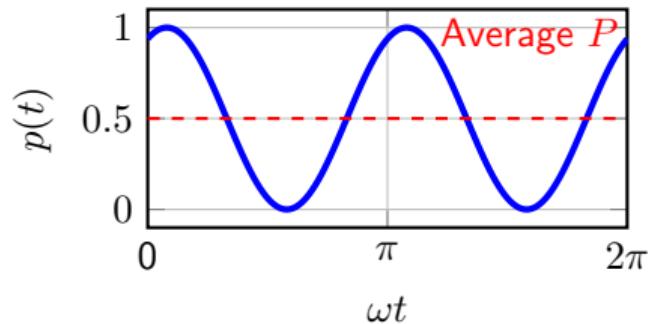
$$P = \frac{1}{T} \int_0^T p(t) dt = \frac{V_m I_m}{2} \cos \theta$$

## Using RMS Values:

$$V_{rms} = \frac{V_m}{\sqrt{2}}, \quad I_{rms} = \frac{I_m}{\sqrt{2}}$$

## Average (Real) Power

$$P = V_{rms} I_{rms} \cos \theta$$



# Reactive and Apparent Power

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## Power Components:

### 1. Real (Average) Power:

$$P = V_{rms} I_{rms} \cos \theta \quad (\text{W})$$

- Power dissipated (resistors)

### 2. Reactive Power:

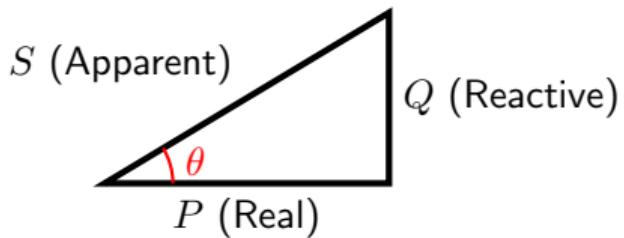
$$Q = V_{rms} I_{rms} \sin \theta \quad (\text{VAR})$$

- Power stored/returned (L/C)

### 3. Apparent Power:

$$S = V_{rms} I_{rms} \quad (\text{VA})$$

## Power Triangle:



$$S = \sqrt{P^2 + Q^2}$$

$$P = S \cos \theta, \quad Q = S \sin \theta$$

## Power Factor:

$$\text{pf} = \cos \theta = \frac{P}{S}$$

# Power Factor and Its Importance

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## Power Factor Definition:

$$\text{pf} = \cos \theta = \frac{P}{S}$$

Range:  $0 \leq \text{pf} \leq 1$

## Special Cases:

- 😊 **pf = 1** (unity): purely resistive,  $\theta = 0$
- 😢 **pf = 0**: purely reactive,  $\theta = \pm 90^\circ$

## Leading vs. Lagging:

- Lagging pf: inductive load (current lags voltage)
- Leading pf: capacitive load (current leads voltage)

## Low Power Factor Problems

- 😢 Higher current required
- 😢 Larger conductor sizes needed
- 😢 More  $I^2R$  losses in transmission

## Power Factor Correction:

Add capacitors in parallel with inductive loads to:

- 😊 Increase power factor
- 😊 Reduce reactive power
- 😊 Lower current draw

# Power in Circuit Elements

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Element	Phase	Real Power $P$	Reactive Power $Q$	pf
Resistor	$\theta = 0$	$I^2R$	0	1
Inductor	$\theta = 90$	0	$I^2X_L$ (positive)	0
Capacitor	$\theta = -90$	0	$-I^2X_C$ (negative)	0

## Key Observations

- Only **resistors** dissipate real power (convert to heat · or light if you mess up)
- **Inductors** and **capacitors** store and return energy (reactive power)
- Reactive power from L and C have opposite signs (can cancel to form resonant networks)

# Summary: Frequency Domain Analysis

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## Phasor Analysis:

- Transform:  $V_m \cos(\omega t + \phi) \leftrightarrow V_m \angle \phi$
- ☺ Differential equations → algebra
- $d/dt \rightarrow j\omega$ ,  $\int dt \rightarrow 1/(j\omega)$

## Impedance:

- $\mathbf{Z} = R + jX$
- Resistor:  $\mathbf{Z}_R = R$
- Inductor:  $\mathbf{Z}_L = j\omega L$
- Capacitor:  $\mathbf{Z}_C = 1/(j\omega C)$

## Circuit Analysis:

- ☺ All DC techniques apply
- KVL, KCL, voltage/current dividers
- Series/parallel combinations

## AC Power:

- Real power:  $P = V_{rms} I_{rms} \cos \theta$
- Reactive power:  $Q = V_{rms} I_{rms} \sin \theta$
- Apparent power:  $S = V_{rms} I_{rms}$

## Power Factor:

- pf =  $\cos \theta = P/S$
- Lagging pf: inductive
- Leading pf: capacitive
- ☺ Low pf → higher losses

## Resonance:

- Occurs when  $X_L = X_C$
- $\omega_0 = 1/\sqrt{LC}$
- ☺ Minimum Z, maximum I

# Comparison: Time vs. Frequency Domain

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Aspect	Time Domain	Frequency Domain
Signals	$v(t)$ , $i(t)$ (real functions)	$\mathbf{V}$ , $\mathbf{I}$ (complex phasors)
Math	Differential equations	Algebraic equations
Circuit elements	R, L, C (time relations)	$Z_R$ , $Z_L$ , $Z_C$ (impedances)
Analysis	Initial conditions, transients	Steady-state, magnitude/phase
Advantages	Shows time evolution	Simplifies sinusoidal analysis
Limitations	Complex for AC steady-state	Only sinusoidal steady-state

## When to Use Each

**Time Domain:** Transients, switching, initial conditions, non-sinusoidal signals

**Frequency Domain:** AC steady-state, sinusoidal sources, impedance analysis

# Example 1: Phasor Conversions

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**Problem:** Convert the following time-domain signals to phasors, then perform the operations.

**Given:**

$$v_1(t) = 10 \cos(1000t + 30) \text{ V}$$

$$v_2(t) = 5 \cos(1000t - 45) \text{ V}$$

$$i(t) = 2 \cos(1000t + 60) \text{ A}$$

**Find:**

- 1 Phasor forms of  $v_1$ ,  $v_2$ , and  $i$
- 2  $\mathbf{V}_1 + \mathbf{V}_2$
- 3  $\mathbf{V}_1 - \mathbf{V}_2$
- 4  $\mathbf{V}_1/\mathbf{I}$

**Solution:**

**Part 1:** Phasor forms

$$\mathbf{V}_1 = 10\angle 30 \text{ V}$$

$$\mathbf{V}_2 = 5\angle -45 \text{ V}$$

$$\mathbf{I} = 2\angle 60 \text{ A}$$

**Part 2:**  $\mathbf{V}_1 + \mathbf{V}_2$

Convert to rectangular:

$$\mathbf{V}_1 = 10 \cos(30) + j10 \sin(30)$$

$$= 8.66 + j5.00 \text{ V}$$

$$\mathbf{V}_2 = 5 \cos(-45) + j5 \sin(-45)$$

$$= 3.54 - j3.54 \text{ V}$$

# Example 1: Solution (continued)

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## Part 2 (continued):

$$\begin{aligned}\mathbf{V}_1 + \mathbf{V}_2 &= (8.66 + j5.00) + (3.54 - j3.54) \\ &= 12.20 + j1.46 \text{ V}\end{aligned}$$

Convert to polar:

$$\begin{aligned}|\mathbf{V}| &= \sqrt{12.20^2 + 1.46^2} = 12.29 \text{ V} \\ \angle \mathbf{V} &= \tan^{-1} \left( \frac{1.46}{12.20} \right) = 6.83\end{aligned}$$

$$\boxed{\mathbf{V}_1 + \mathbf{V}_2 = 12.29 \angle 6.83 \text{ V}}$$

## Part 3: $\mathbf{V}_1 - \mathbf{V}_2$

$$\begin{aligned}\mathbf{V}_1 - \mathbf{V}_2 &= (8.66 + j5.00) - (3.54 - j3.54) \\ &= 5.12 + j8.54 \text{ V} \\ &= 9.96 \angle 59.05 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_1 - \mathbf{V}_2 = 9.96 \angle 59.05 \text{ V}}$$

## Part 4: $\mathbf{V}_1/\mathbf{I}$ (This is impedance!)

$$\begin{aligned}\frac{\mathbf{V}_1}{\mathbf{I}} &= \frac{10 \angle 30}{2 \angle 60} = \frac{10}{2} \angle (30 - 60) \\ &= 5 \angle -30 \Omega\end{aligned}$$

$$\boxed{\mathbf{Z} = 5 \angle -30 \Omega = 4.33 - j2.50 \Omega}$$

## Example 2: Impedance at Different Frequencies

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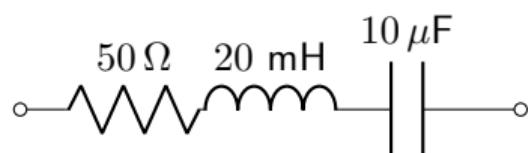
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**Problem:** A series circuit contains  $R = 50 \Omega$ ,  $L = 20 \text{ mH}$ , and  $C = 10 \mu\text{F}$ . Find the total impedance at the following frequencies.

**Circuit:**



**Given:**

- $R = 50 \Omega$
- $L = 20 \text{ mH}$
- $C = 10 \mu\text{F}$

**Find the total impedance at:**

- (a)  $f = 100 \text{ Hz}$
- (b)  $f = 500 \text{ Hz}$
- (c)  $f = 1000 \text{ Hz}$

**For each frequency, determine:**

- 1 Magnitude  $|Z|$
- 2 Phase angle  $\theta$
- 3 Whether the circuit is inductive or capacitive

## Example 2: Solution - Setup and Part (a)

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### General Formula for Series RLC:

$$\mathbf{Z} = R + j\omega L + \frac{1}{j\omega C} = R + j \left( \omega L - \frac{1}{\omega C} \right)$$

where  $X_L = \omega L$  (inductive reactance) and  $X_C = \frac{1}{\omega C}$  (capacitive reactance)

**Part (a):**  $f = 100 \text{ Hz}$

$$\omega = 2\pi f = 2\pi(100) = 628.3 \text{ rad/s}$$

$$X = X_L - X_C = -146.6 \Omega$$

$$\mathbf{Z} = 50 - j146.6 \Omega$$

$$\boxed{\mathbf{Z} = 154.9 \angle -71.2 \Omega}$$

*Capacitive behavior (negative reactance,  
current leads)*

$$X_L = \omega L = 628.3 \times 0.02 = 12.57 \Omega$$

$$X_C = \frac{1}{\omega C} = \frac{1}{628.3 \times 10^{-5}} = 159.2 \Omega$$

## Example 2: Solution - Parts (b) and (c)

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**Part (b):**  $f = 500 \text{ Hz}$

$$\omega = 2\pi(500) = 3141.6 \text{ rad/s}$$

$$X_L = 3141.6 \times 0.02 = 62.83 \Omega$$

$$X_C = \frac{1}{3141.6 \times 10^{-5}} = 31.83 \Omega$$

$$X = 62.83 - 31.83 = 31.0 \Omega$$

$$\mathbf{Z} = 50 + j31.0 \Omega$$

$$\boxed{\mathbf{Z} = 59.0\angle31.8 \Omega}$$

*Inductive behavior (positive reactance,  
current lags)*

**Part (c):**  $f = 1000 \text{ Hz}$

$$\omega = 2\pi(1000) = 6283.2 \text{ rad/s}$$

$$X_L = 6283.2 \times 0.02 = 125.7 \Omega$$

$$X_C = \frac{1}{6283.2 \times 10^{-5}} = 15.92 \Omega$$

$$X = 125.7 - 15.92 = 109.8 \Omega$$

$$\mathbf{Z} = 50 + j109.8 \Omega$$

$$\boxed{\mathbf{Z} = 120.7\angle65.5 \Omega}$$

*Inductive behavior (positive reactance,  
current lags)*

# Example 3: Series RL Circuit

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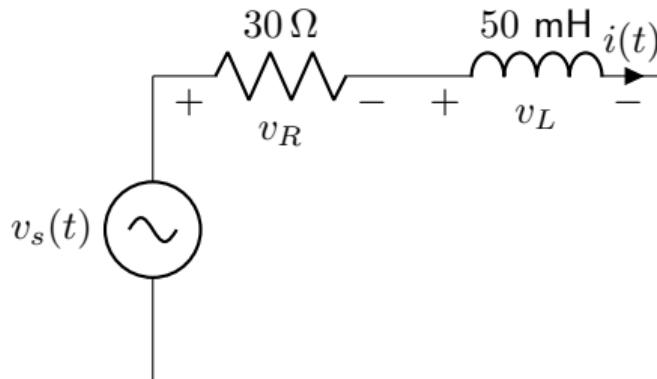
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**Problem:** For the circuit shown, find the current, voltage across each element, and draw the phasor diagram.

**Circuit:**



**Given:**

- $v_s(t) = 100 \cos(2000t) \text{ V}$
- $R = 30 \Omega$
- $L = 50 \text{ mH} = 0.05 \text{ H}$
- $\omega = 2000 \text{ rad/s}$

**Find:**

- 1 Total impedance  $Z_{tot}$
- 2 Current  $i(t)$  (phasor and time domain)
- 3 Voltage across resistor  $v_R(t)$
- 4 Voltage across inductor  $v_L(t)$
- 5 Draw the phasor diagram
- 6 Verify KVL

# Example 3: Solution - Impedance and Current

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## Step 1: Convert to phasor domain

Source phasor:

$$\mathbf{V}_s = 100\angle 0^\circ \text{ V}$$

## Step 2: Calculate impedances

Resistor impedance:

$$\mathbf{Z}_R = R = 30 \Omega$$

Inductor impedance:

$$\begin{aligned}\mathbf{Z}_L &= j\omega L \\ &= j(2000)(0.05) \\ &= j100 \Omega\end{aligned}$$

## Step 3: Total impedance

Rectangular form:

$$\mathbf{Z}_{tot} = \mathbf{Z}_R + \mathbf{Z}_L = 30 + j100 \Omega$$

Polar form:

$$|\mathbf{Z}_{tot}| = \sqrt{30^2 + 100^2} = 104.4 \Omega$$

$$\theta_Z = \tan^{-1} \left( \frac{100}{30} \right) = 73.3^\circ$$

$$\boxed{\mathbf{Z}_{tot} = 104.4\angle 73.3^\circ \Omega}$$

# Example 3: Solution - Current (continued)

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## Step 4: Calculate current

Using Ohm's law:

$$\begin{aligned} \mathbf{I} &= \frac{\mathbf{V}_s}{\mathbf{Z}_{tot}} \\ &= \frac{100\angle 0}{104.4\angle 73.3} \\ &= \frac{100}{104.4}\angle(0 - 73.3) \\ &= 0.958\angle -73.3 \text{ A} \end{aligned}$$

$$\boxed{\mathbf{I} = 0.958\angle -73.3 \text{ A}}$$

## Step 5: Convert to time domain

$$\boxed{i(t) = 0.958 \cos(2000t - 73.3) \text{ A}}$$

### Interpretation

Current **lags** the voltage by 73.3, which is expected for an inductive circuit (RL circuit).

# Example 3: Solution - Element Voltages

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## Step 6: Voltage across resistor

Using Ohm's law:

$$\begin{aligned}\mathbf{V}_R &= \mathbf{I} \cdot \mathbf{Z}_R \\ &= (0.958\angle -73.3)(30\angle 0) \\ &= 0.958 \times 30\angle(-73.3 + 0) \\ &= 28.7\angle -73.3 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_R = 28.7\angle -73.3 \text{ V}}$$

Time domain:

$$v_R(t) = 28.7 \cos(2000t - 73.3) \text{ V}$$

*Note:  $\mathbf{V}_R$  is in phase with  $\mathbf{I}$  (both at  $-73.3$ )*

## Step 7: Voltage across inductor

Using Ohm's law:

$$\begin{aligned}\mathbf{V}_L &= \mathbf{I} \cdot \mathbf{Z}_L \\ &= (0.958\angle -73.3)(100\angle 90) \\ &= 0.958 \times 100\angle(-73.3 + 90) \\ &= 95.8\angle 16.7 \text{ V}\end{aligned}$$

$$\boxed{\mathbf{V}_L = 95.8\angle 16.7 \text{ V}}$$

Time domain:

$$v_L(t) = 95.8 \cos(2000t + 16.7) \text{ V}$$

*Note:  $\mathbf{V}_L$  leads  $\mathbf{I}$  by 90° (as expected for an inductor)*

# Example 3: Solution - Phasor Diagram and Verification

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## Step 8: Verify KVL

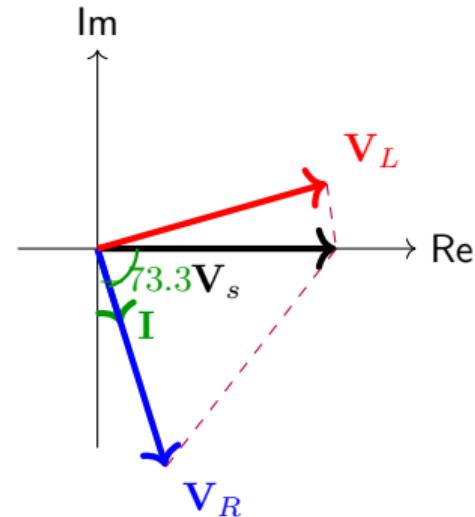
Check:  $\mathbf{V}_R + \mathbf{V}_L = \mathbf{V}_s$

Convert to rectangular:

$$\begin{aligned}\mathbf{V}_R &= 28.7\angle -73.3 \\ &= 28.7 \cos(-73.3) + j28.7 \sin(-73.3) \\ &= 8.26 - j27.49 \text{ V}\end{aligned}$$

$$\begin{aligned}\mathbf{V}_L &= 95.8\angle 16.7 \\ &= 95.8 \cos(16.7) + j95.8 \sin(16.7) \\ &= 91.74 + j27.49 \text{ V}\end{aligned}$$

$$\begin{aligned}\mathbf{V}_R + \mathbf{V}_L &= (8.26 - j27.49) + (91.74 + j27.49) \\ &= 100 + j0 = 100\angle 0 \text{ V}\end{aligned}$$



## Key Observations

- $\mathbf{V}_R \parallel \mathbf{I}$  (resistor)
- $\mathbf{V}_L \perp \mathbf{I}$ , leads by 90 (inductor)
- $\mathbf{V}_R + \mathbf{V}_L = \mathbf{V}_s$  (KVL)

# Example 4: RC Voltage Divider

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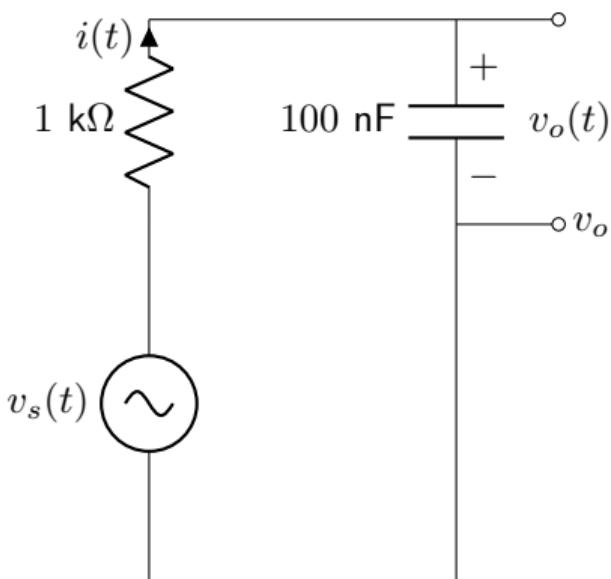
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**Problem:** Analyze the following RC voltage divider circuit.

**Circuit:**



**Given:**

- $v_s(t) = 10 \cos(10000t)$  V
- $R = 1 \text{ k}\Omega$
- $C = 100 \text{ nF}$

**Find:**

- 1 The impedance of each element
- 2 The output voltage  $\mathbf{V}_o$
- 3 The output voltage  $v_o(t)$
- 4 The magnitude ratio  $|\mathbf{V}_o|/|\mathbf{V}_s|$
- 5 The phase shift between input and output
- 6 The current  $i(t)$

# Example 4: Solution

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## Solution:

Source phasor:  $\mathbf{V}_s = 10\angle 0^\circ \text{ V}$   
 $\omega = 10000 \text{ rad/s}$

## 1. Impedances:

$$\mathbf{Z}_R = 1000 \Omega$$

$$\mathbf{Z}_C = \frac{1}{j\omega C} = \frac{1}{j(10^4)(10^{-7})} = -j1000 \Omega$$

## 2. Output Voltage (voltage divider)

$$\begin{aligned}\mathbf{V}_o &= \mathbf{V}_s \frac{\mathbf{Z}_C}{\mathbf{Z}_R + \mathbf{Z}_C} \\ &= 10\angle 0^\circ \cdot \frac{-j1000}{1000 - j1000} \\ &= 10 \cdot \frac{1000\angle -90^\circ}{1414.2\angle -45^\circ} \\ &= 10 \cdot 0.707\angle -45^\circ \\ &= \boxed{7.07\angle -45^\circ \text{ V}}\end{aligned}$$

# Example 4: Solution (continued)

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## 3. Time domain:

$$v_o(t) = 7.07 \cos(10000t - 45) \text{ V}$$

## 4. Magnitude ratio:

$$\frac{|V_o|}{|V_s|} = \frac{7.07}{10} = 0.707$$

## 5. Phase shift: -45 (output lags input)

## 6. Current:

$$\begin{aligned} I &= \frac{V_s}{Z_R + Z_C} = \frac{10\angle 0}{1414.2\angle -45} \\ &= 7.07\angle 45 \text{ mA} \end{aligned}$$

$$i(t) = 7.07 \cos(10000t + 45) \text{ mA}$$

# Example 5: AC Power Calculation

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**Problem:** Calculate the real, reactive, and apparent power for a load with the following voltage and current.

**Given:**

$$v(t) = 120\sqrt{2} \cos(377t) \text{ V}$$

$$i(t) = 10\sqrt{2} \cos(377t - 36.87) \text{ A}$$

*Note: The coefficients include  $\sqrt{2}$  to indicate peak values*

**Find:**

- 1 RMS voltage and current
- 2 Real power  $P$
- 3 Reactive power  $Q$
- 4 Apparent power  $S$
- 5 Power factor (and type)
- 6 Load impedance  $Z$

# Example 5: Solution - RMS Values and Powers

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## Step 1: RMS values

Convert from peak to RMS:

$$V_{rms} = \frac{V_m}{\sqrt{2}} = \frac{120\sqrt{2}}{\sqrt{2}} = 120 \text{ V}$$

$$I_{rms} = \frac{I_m}{\sqrt{2}} = \frac{10\sqrt{2}}{\sqrt{2}} = 10 \text{ A}$$

## Step 2: Determine phase angle

From the time-domain expressions:

- Voltage phase:  $\phi_v = 0$
- Current phase:  $\phi_i = -36.87$

Phase difference:

$$\theta = \phi_v - \phi_i = 0 - (-36.87) = 36.87$$

*Current lags voltage  $\Rightarrow$  inductive load*

## Step 3: Real power

$$\begin{aligned} P &= V_{rms} I_{rms} \cos \theta \\ &= (120)(10) \cos(36.87) = 960 \text{ W} \end{aligned}$$

## Step 4: Reactive power

$$\begin{aligned} Q &= V_{rms} I_{rms} \sin \theta \\ &= (120)(10) \sin(36.87) = 720 \text{ VAR} \end{aligned}$$

## Step 5: Apparent power

$$S = V_{rms} I_{rms} = 1200 \text{ VA}$$

**Verify:**

$$S = \sqrt{P^2 + Q^2} = \sqrt{960^2 + 720^2} = 1200$$

# Example 5: Solution - Power Factor and Impedance

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## Step 6: Power factor

Method 1 - From angle:

$$\begin{aligned} \text{pf} &= \cos \theta = \cos(36.87) \\ &= \boxed{0.8 \text{ lagging}} \end{aligned}$$

Method 2 - From powers:

$$\begin{aligned} \text{pf} &= \frac{P}{S} = \frac{960}{1200} \\ &= 0.8 \text{ lagging} \end{aligned}$$

*“Lagging” because current lags voltage  
(inductive)*

## Step 7: Load impedance

Convert to phasor form:

$$\begin{aligned} \mathbf{V} &= 120\angle 0 \text{ V} \\ \mathbf{I} &= 10\angle -36.87 \text{ A} \end{aligned}$$

Calculate impedance:

$$\begin{aligned} \mathbf{Z} &= \frac{\mathbf{V}}{\mathbf{I}} = \frac{120\angle 0}{10\angle -36.87} \\ &= 12\angle 36.87 \Omega \end{aligned}$$

$$\begin{aligned} \mathbf{Z} &= 12(\cos 36.87 + j \sin 36.87) \\ &= \boxed{9.6 + j7.2 \Omega} \end{aligned}$$

*This represents  $R = 9.6 \Omega$  in series with  $X_L = 7.2 \Omega$*

# Example 6: Parallel RLC Circuit

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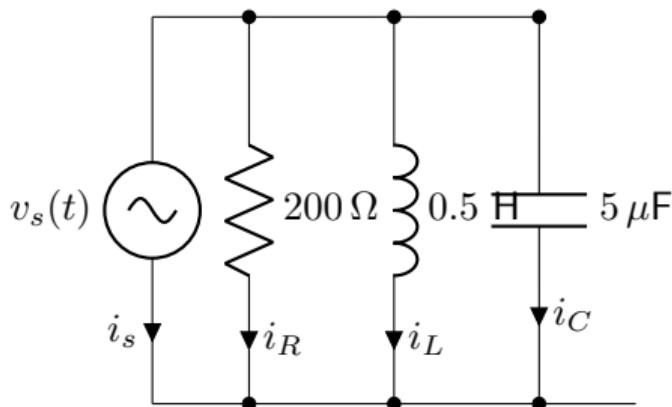
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**Problem:** Analyze the parallel RLC circuit shown below.

**Circuit:**



**Given:**

- $v_s(t) = 50 \cos(1000t) \text{ V}$

**Find:**

- 1 Impedance of each branch
- 2 Total impedance
- 3 Source current  $i_s(t)$
- 4 Current through each branch
- 5 Total real power
- 6 Total reactive power
- 7 Is the circuit inductive or capacitive?

# Example 6: Solution

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**Solution:**

$$\mathbf{V}_s = 50\angle 0 \text{ V}, \omega = 1000 \text{ rad/s}$$

**1. Branch impedances:**

$$\mathbf{Z}_R = 200 \Omega$$

$$\mathbf{Z}_L = j\omega L = j(1000)(0.5) = j500 \Omega$$

$$\begin{aligned}\mathbf{Z}_C &= \frac{1}{j\omega C} = \frac{1}{j(1000)(5 \times 10^{-6})} \\ &= -j200 \Omega\end{aligned}$$

**2. Total impedance:**

$$\begin{aligned}\frac{1}{\mathbf{Z}_{tot}} &= \frac{1}{200} + \frac{1}{j500} + \frac{1}{-j200} \\ &= 0.005 + j0.003\end{aligned}$$

$$\begin{aligned}\mathbf{Z}_{tot} &= \frac{1}{0.005 + j0.003} = \frac{1}{0.00583\angle 30.96} \\ &= \boxed{171.5\angle -30.96 \Omega} \\ &= 147.1 - j88.0 \Omega\end{aligned}$$

**3. Source current:**

$$\begin{aligned}\mathbf{I}_s &= \frac{\mathbf{V}_s}{\mathbf{Z}_{tot}} = \frac{50\angle 0}{171.5\angle -30.96} \\ &= 0.292\angle 30.96 \text{ A}\end{aligned}$$

$$\boxed{i_s(t) = 0.292 \cos(1000t + 30.96) \text{ A}}$$

# Example 6: Solution (continued)

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## 4. Branch currents:

$$\mathbf{I}_R = \frac{\mathbf{V}_s}{\mathbf{Z}_R} = \frac{50}{200} = 0.25\angle 0 \text{ A}$$

$$\mathbf{I}_L = \frac{50\angle 0}{500\angle 90} = 0.1\angle -90 \text{ A}$$

$$\mathbf{I}_C = \frac{50\angle 0}{200\angle -90} = 0.25\angle 90 \text{ A}$$

## 5. Total real power:

Only resistor dissipates real power:

$$P = I_R^2 R = 12.5 \text{ W}$$

or using  $P = V_{rms} I_{s,rms} \cos \theta$ :

$$P = 50 \times 0.292 \times \cos(30.96) = 12.5 \text{ W}$$

## 6. Total reactive power:

$$Q_L = I_L^2 X_L = (0.1)^2 \times 500 = 5 \text{ VAR}$$

$$Q_C = -I_C^2 X_C = -(0.25)^2 \times 200 = -12.5 \text{ VAR}$$

$$Q_{tot} = Q_L + Q_C = -7.5 \text{ VAR}$$

or:

$$\begin{aligned} Q &= V_{rms} I_{s,rms} \sin \theta \\ &= 50 \times 0.292 \times \sin(30.96) = -7.5 \text{ VAR} \end{aligned}$$

## 7. Circuit behavior:

$Q_{tot} < 0$  and current leads voltage ( $\theta > 0$ )

Capacitor reactive power dominates