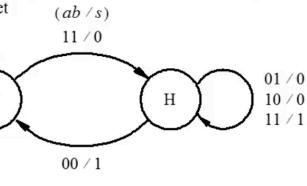
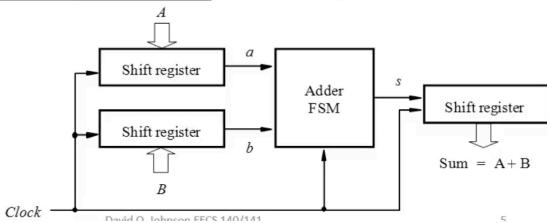


State Table:

Present state	Next state		Outputs	
	ab=00	01	10	11
G	G	G	H	0 1 1 0
H	G	H	H	1 0 0 1

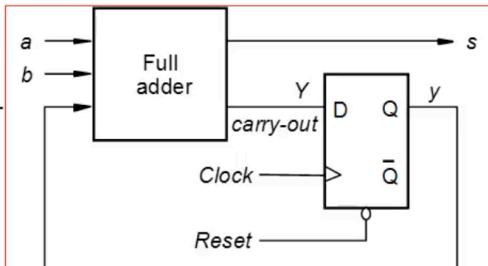


G: carry-in = 0
H: carry-in = 1

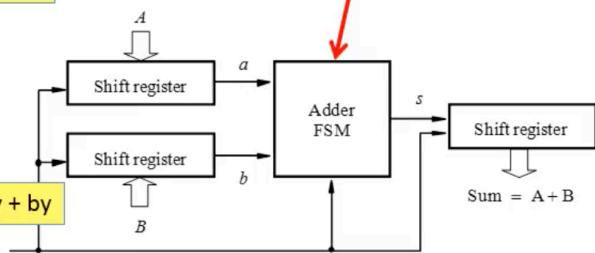


Microcontroller

ne logical
or a full-adder (FA).
the FSM with a full-

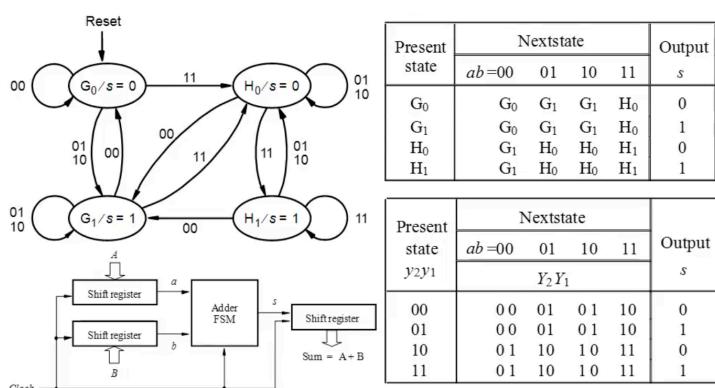


$$s = a \oplus b \oplus y$$



$$Y = ab + ay + by$$

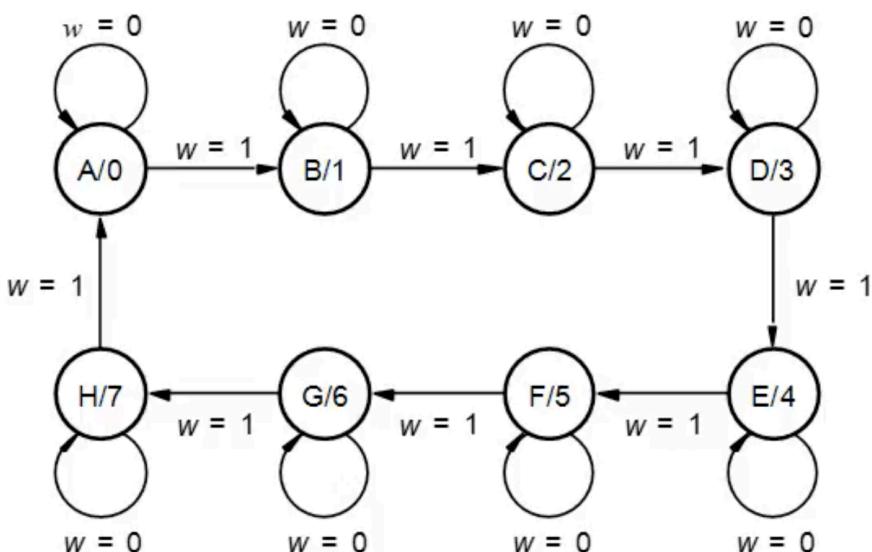
Present state	Next state				Output			
	ab=00	01	10	11	00	01	10	11
y								
0	0	0	0	1	0	1	1	0
1	0	1	1	1	1	0	0	1



Present state	Nextstate				Output
	ab=00	01	10	11	
G0	G0	G1	G1	H0	0
G1	G0	G1	G1	H0	1
H0	G1	H0	H0	H1	0
H1	G1	H0	H0	H1	1

Present state	Nextstate				Output
	ab=00	01	10	11	
y2y1					
00	00	01	01	10	0
01	00	01	01	10	1
10	01	10	10	11	0
11	01	10	10	11	1

FSM Counter



Present state	Next state		Output
	w = 0	w = 1	
A	A	B	0
B	B	C	1
C	C	D	2
D	D	E	3
E	E	F	4
F	F	G	5
G	G	H	6
H	H	A	7

Present state $y_2y_1y_0$	Next state		Count $z_2z_1z_0$
	$w = 0$	$w = 1$	
	$Y_2 Y_1 Y_0$	$Y_2 Y_1 Y_0$	
A	000	000	000
B	001	001	001
C	010	010	010
D	011	011	011
E	100	100	100
F	101	101	101
G	110	110	110
H	111	111	111

$$\begin{aligned} z_2 &= y_2 \\ z_1 &= y_1 \\ z_0 &= y_0 \end{aligned}$$

y_1y_0	00	01	11	10
00	0	1	1	0
01	0	1	1	0
11	1	0	0	1
10	1	0	0	1

$$Y_0 = \bar{w}y_0 + w\bar{y}_0$$

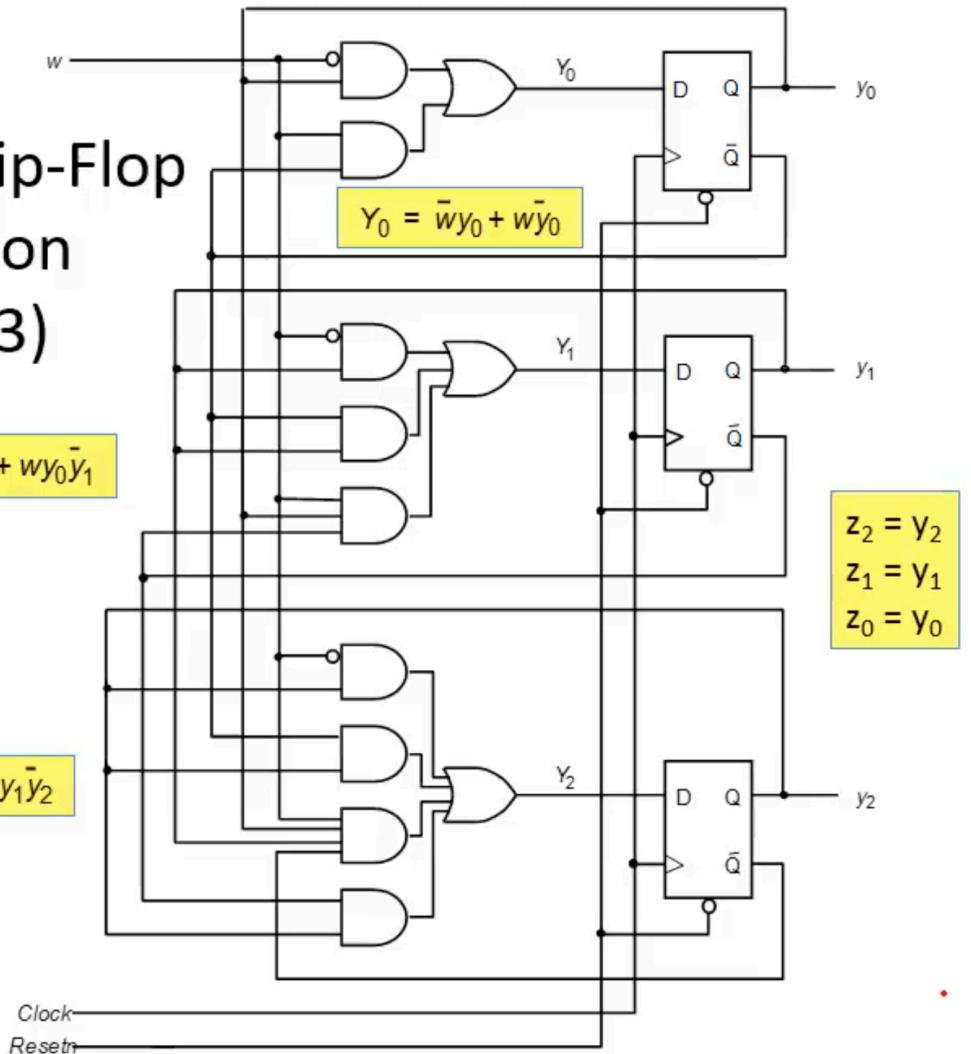
y_1y_0	00	01	11	10
00	0	0	1	1
01	0	0	1	1
11	0	1	0	1
10	0	1	0	1

$$Y_1 = \bar{w}y_1 + y_1\bar{y}_0 + w\bar{y}_0\bar{y}_1$$

y_1y_0	00	01	11	10
00	0	0	0	0
01	1	1	1	1
11	1	1	0	1
10	0	0	1	0

$$Y_2 = \bar{w}y_2 + \bar{y}_0y_2 + \bar{y}_1y_2 + w\bar{y}_0\bar{y}_1\bar{y}_2$$

Counter FSM D Flip-Flop Implementation (Section 8.7.3)



- Using JK flip-flops requires derivation of inputs J and K for each flip-flop.
- If a flip-flop in state 0 is to remain in state 0, then $J = 0$ and $K = d$ (don't care)
- If a flip-flop in state 0 is to change to state 1, then $J = 1$ and $K = d$
- If a flip-flop in state 1 is to remain in state 1, then $J = d$ and $K = 0$
- If a flip-flop in state 1 is to change to state 0, then $J = d$ and $K = 1$

Present state $y_2y_1y_0$	Flip-flop inputs								Count $z_2z_1z_0$	
	$w = 0$				$w = 1$					
	$Y_2 Y_1 Y_0$	$J_2 K_2$	$J_1 K_1$	$J_0 K_0$	$Y_2 Y_1 Y_0$	$J_2 K_2$	$J_1 K_1$	$J_0 K_0$		
A 000	000	0d	0d	0d	001	0d	0d	1d	000	
B 001	001	0d	0d	d0	010	0d	1d	d1	001	
C 010	010	0d	d0	0d	011	0d	d0	1d	010	
D 011	011	0d	d0	d0	100	1d	d1	d1	011	
E 100	100	d0	0d	0d	101	d0	0d	1d	100	
F 101	101	d0	0d	d0	110	d0	1d	d1	101	
G 110	110	d0	d0	0d	111	d0	d0	1d	110	
H 111	111	d0	d0	d0	000	d1	d1	d1	111	

wy_2	y_1y_0
00	00 01 11 10
01	0 d d 0
11	1 d d 1
10	1 d d 1

$$J_0 = w$$

wy_2	y_1y_0
00	0 0 0 d
01	0 d d 0
11	1 d d 1
10	1 d d 1

$$J_1 = wy_0$$

wy_2	y_1y_0
00	0 0 0 0
01	d d d d
11	d d d d
10	0 0 1 0

$$J_2 = wy_0y_1$$

wy_2	y_1y_0
00	d 0 0 d
01	d 0 0 d
11	d 1 1 d
10	d 1 1 d

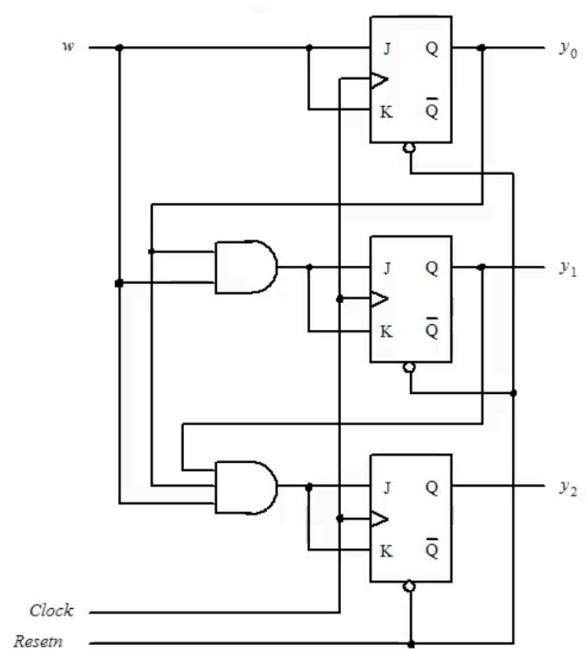
$$K_0 = w$$

wy_2	y_1y_0
00	d d 0 0
01	d d 0 0
11	d d 1 0
10	d d 1 0

$$K_1 = wy_0$$

wy_2	y_1y_0
00	d d d d
01	0 0 0 0
11	0 0 1 0
10	d d d d

$$K_2 = wy_0y_1$$



Count any sequence

- The counting sequence is:
0, 4, 2, 6, 1, 5, 3, 7, 0, 4, ...
- Count is represented directly by flip-flop outputs themselves, without using any extra gates: $Q_2Q_1Q_0$

Present state	Next state	Output $z_2z_1z_0$	Present state $y_2y_1y_0$	Next state $Y_2Y_1Y_0$	Output $z_2z_1z_0$
A	B	000	000	100	000
B	C	100	100	010	100
C	D	010	010	110	010
D	E	110	110	001	110
E	F	001	001	101	001
F	G	101	101	011	101
G	H	011	011	111	011
H	A	111	111	000	111

$$D_2 = Y_2 = !y_2$$

$$D_1 = Y_1 = y_1 \oplus y_2$$

$$D_0 = Y_0 = y_0!y_1 + y_0!y_2 + !y_0y_1y_2$$

$$= y_0(!y_1 + !y_2) + !y_0y_1y_2$$

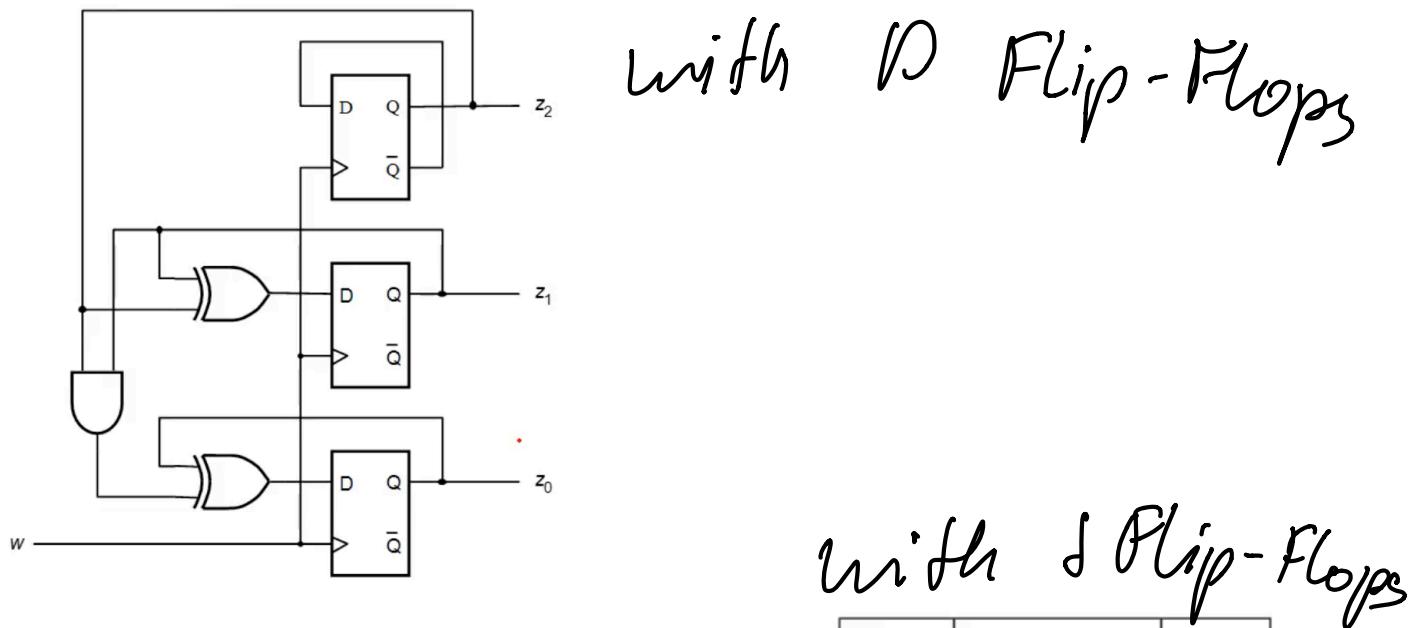
$$= y_0!(y_1y_2) + !y_0(y_1y_2)$$

$$= y_0 \oplus (y_1y_2)$$

$$z_2 = y_2$$

$$z_1 = y_1$$

$$z_0 = y_0$$



Design a counter that counts pulses on line w and outputs the count in the sequence:

0, 2, 1, 3, 0, 2 ...

Use JK flip-flops.

Present state	Next state	Output z_1z_0	Present state y_1y_0	Flip-flop inputs J_1K_1 J_0K_0	Output z_1z_0
A	B	0 0	0 0	1 d 0 d	0 0
B	C	1 0	1 0	d 1 1 d	1 0
C	D	0 1	0 1	1 d d 0	0 1
D	A	1 1	1 1	d 1 d 1	1 1

with 4 Flip-Flops

$$\begin{aligned} J_1 &= K_1 = 1 \\ J_0 &= K_0 = y_1 \\ z_1 &= y_1 \\ z_0 &= y_0 \end{aligned}$$

