Max Zuo

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github.com/maxzuo



/in/max-zuo/



/users/7871685

Skills

Software Development Python, Java, Go, C, SQL, JavaScript, TypeScript, HTML, CSS

Libraries OpenCV, NumPy, Keras, Tensorflow, PyTorch, Scikit-Learn Firebase, React, Flask, JQuery

Machine Learning Computer vision, Object detection, Few/one-shot learning, Open-vocabulary detection,

Convolutional Neural Networks, Graph Neural Networks, Transformers, HMMs,

Autoencoders, SVM, Random Forests, Word2Vec, LSTM, Text/PageRank

Robotics SLAM, Planning (PDDL/PDDLStream), Scene graphs, Learning from demonstrations

Foreign Languages Fluent Mandarin, Spanish (National Spanish Exam 3 Bronze, NSE2 Silver)

Misc JSON, Git, VSTS, Agile, Jenkins, IBM cloud

Work Experience

GOOGLE MTV. CA

Software Engineering Intern

May '22 - Aug '22

- Worked on the machine learning research teams Tensorflow Model Garden & Tensorflow **Vision** under CoreML to code, train, and improve open-vocabulary object detection models.
 - Worked on implementing the VILD object detection framework.
- Presented papers to help keep the team updated on state-of-the-art works in different areas, including object detection, panoptic segmentation, and general vision techniques.
 - Papers presented to the team included: CMT-Deeplab, kMeans Mask Transformer

OCULOGYX (OX)

Bentonville, AR

Research Engineer

May '21 – Sep '21

- Leading the development of mapping warehouse floors with SKU-level info to ~1m accuracy.
- Involved in business decisions with the CTO and CEO of the company.
- Worked on developing **Ox Orion**, a near real-time computer vision recognition for groceries.
 - o 2-pass KNN combining approximate nearest neighbors for faster lookup speeds
 - Deep learning one-stage one-shot object detection
 - Pipelined algorithm using SIFT features, RANSAC homography, and triplet loss for object recognition and geometric verification
- Developed Ox Automapper product from scratch, a pedestrian GraphSLAM algorithm mapping warehouse and supermarket store floors with SKU-level information
 - GraphSLAM for pedestrian data using inertial (IMU) odometry
 - Deep learning sensor correction and sensor fusion for natural pedestrian walk routines.

GEORGIA INSTITUTE OF TECHNOLOGY

Atlanta, GA

Graduate Researcher (AI/ML & Robotics)

Aug '21 – Present

- Conducting research under Prof. Sonia Chernova on semantic rearrangement: the ability for a robot/planner to organize a scene without explicit detailed human instruction.
 - Working with PDDLStream, Graph NNs, and pose graphs

Graduate Researcher (Computer Vision & Unsupervised Learning)

Aug '20 - Present

- Conducting research under Prof. Thad Starner on AI Through Symbiosis (wearable technology, unsupervised learning) specializing in computer vision and SLAM.
 - Researching a new HMM-based algorithm, utilizing its model capacity to recover event labels in a weakly supervised manner, used to train deep vision and time-series models.

Graduate Teaching Assistant

Aug '21 - Dec '21

TA/Head TA of the Mobile & Ubiquitous Computing course (i.e. wearables, HCI)

Jan '22 - May '22 (HEAD TA)

focus on teaching applied research methods, conducting user studies, prototyping

Undergraduate Teaching Assistant

• Lead teaching assistant for Machine Learning (CS 4641), a fourth-year level course

IBM Littleton, MA

Software Engineering Intern

Jun '20 - Aug '20

- Worked on IBM Food Trust Blockchain Transparent Supply
- Significantly expanded open-source Recall Assistant capabilities
 - Worked directly with customers to support complex, real recall scenario types
 - Currently in use by real IBM Food Trust customers including Walmart for faster, more accurate recall assistance
- Developed IBM cloud solutions for improving internal production pipeline
- Led "Farming Insights" application, designed app stack (database, server, and front-end)

SALLIE MAE INC Newton, MA

Software Development Intern

May '19 - Aug '19

- Spearheaded project developing Chatbot Integration Manager (JS/Python Web App), Al
 integration tool for moving to AWS Lex chatbot from human chat using NLP, from scratch.
 - NLP logic developed in Python, using word2vec to calculate semantic text-similarity of Q&A pairs and rank answers using a proprietary ranking algorithm based on PageRank.

Publications

ATCON: Attention Consistency for Vision Models 🗹

2022

Mirzazadeh, A., Dubost, F., Pike, M., Maniar, K., **Zuo, M.**, Lee-Messer, C., & Rubin, D. (2022). *arXiv preprint arXiv:2210.09705*. **(To be presented at WACV 2023)**

Efficient Exploration via First-Person Behavior Cloning Assisted Rapidly-Exploring Random Trees **2022 200, M.**, Schick, L., Gombolay, M., & Gopalan, N. (2022). *HRI 2022 Workshop - MLHRC*

Education

GEORGIA INSTITUTE OF TECHNOLOGY

Atlanta, GA

College of Computing

BS: Aug '18 – May '21

 Relevant courses: OOP, Data Structures & Algorithms, Artificial Intelligence, Machine Learning, Probability & Statistics, Combinatorics, Networking, Algorithms Honors, Computer Vision, NLP, Machine Learning Theory, Interactive Robot Learning, Human Machine Learning, Deep Learning, Cognitive Science

Candidate for MS, Computer Science with a specialization in Machine Learning

GPA: 4.00 / 4.00 *MS: Aug '21 – Dec '22*

GPA: 4.00 / 4.00

Personal Projects

All: github.com/maxzuo

Hypercut (HackGT, Oct 2021) ☑ – Video summary generator

- Using sentence transformers MPNet and TextRank to reduce the content of a video while maintaining as much pertinent information as possible.
- Wav2Vec2 + CTC for offline transcription, Google Cloud Speech API for online transcription

Datalytics (GT Sports Innovation, Mar 2020) 🖸 – Computer vision tool to automatically analyze football footage

- Yard line extraction, score information extraction, and team formation extraction
- Action segmentation (detects start and end of plays)

Awards & Achievements

GVU Distinguished Masters' Finalist '22 (Out of 3 in School)

HackGT '21 – First place overall & best design **GT Highest Honors '21 – 4.00 GPA** for BS in CS

GT Sports Innovation '20 – Winner, computer vision football analysis

HackGT '19– NSA: Secure Code Challenge Winner **MIT Blueprint 2017** – First place