

PVS by Example¹

César A. Muñoz

NASA's Langley Research Center

Cesar.A.Munoz@nasa.gov



Formal Proofs in PVS – Tutorial
18th Conference on Intelligent Computer Mathematics
October 6, 2025

¹Approved for public release STRIVES # 20250009059

The Prototype Verification System (PVS)

PVS consists of a specification language to write **formal models** of

- ▶ system requirements (internal and external),
- ▶ functional algorithms

and a (highly automated) interactive theorem prover to verify that these models are *correct*.

To have in mind:

All models are wrong; the practical question is how wrong they have to be to not be useful²

²G. Box and N. Draper, Empirical Model Building and Response Surfaces, 1987.

The Prototype Verification System (PVS)

PVS consists of a specification language to write **formal models** of

- ▶ system requirements (internal and external),
- ▶ functional algorithms

and a (highly automated) interactive theorem prover to verify that these models are *correct*.

To have in mind:

All models are wrong; the practical question is how wrong they have to be to not be useful²

²G. Box and N. Draper, Empirical Model Building and Response Surfaces, 1987.

PVS in a Nutshell

- ▶ PVS³ is developed by SRI International with the support of the Formal Methods Team at NASA's Langley Research Center
- ▶ **Strongly typed** specification language based on **classical higher-order logic**
- ▶ Extensible theorem prover with built-in decision procedures and soundness-preserving strategy language
- ▶ Modern graphical development interface⁴ based on Microsoft Visual Studio Code
- ▶ De-facto library⁵ consisting of 53 libraries and about 30K formally proven lemmas
- ▶ Batch proving and animation capabilities

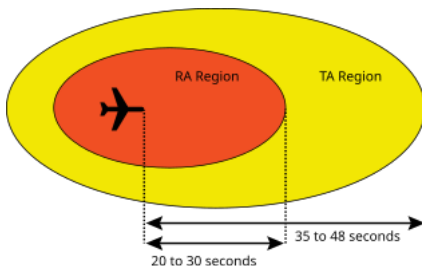
³<http://pvs.csl.sri.com>

⁴<https://shemesh.larc.nasa.gov/fm/VSCoDe-PVS>

⁵<https://shemesh.larc.nasa.gov/fm/pvs/PVS-library>

Traffic Alert and Collision Avoidance System (TCAS)

- ▶ Family of of airborne systems designed to reduce the risk of mid-air collisions between *cooperative* aircraft.
- ▶ Mandated in the US for aircraft with greater than 30 seats or a maximum takeoff weight greater than 33,000 pounds.
- ▶ Current version, TCAS II V7.1, provides⁶:
 - ▶ **Traffic Alerts (TAs).**
 - ▶ **(Vertical) Resolution Advisories (RAs).**



⁶Graphics released under Creative Commons License (https://en.wikipedia.org/wiki/Traffic_collision_avoidance_system)

TCAS Alerting Logic

- ▶ TCAS alerting logic is pairwise, i.e., it provides alerting information for one aircraft (the **ownship**) against a traffic aircraft (the **intruder**).
- ▶ TCAS logic uses 3-dimensional tracking of aircraft position and velocity.
- ▶ TCAS logic predicts aircraft trajectories using a linear projection of current aircraft position and velocity.
- ▶ Predicted trajectories are checked against time and distance thresholds, whose values depend on **sensitivity level**.

TCAS 2D Core Alerting Logic

(Simplified 2D version of the logic!)

A Traffic Alert (TA) is issued in the ownship aircraft, with respect to an intruder aircraft, when

- ▶ The **range** between the two aircraft is below DMOD threshold for ownship sensitivity level **or**
- ▶ Aircraft are **converging** **and** time **Tau** between the two aircraft is below TAU threshold for ownship sensitivity level.⁷

Henceforth, it will be assumed that both aircraft have the same sensitivity level.

⁷Tau is related to the time to closest point approach (TCPA).

Range, Closure Rate, and τ

- ▶ Range (r): Horizontal distance between 2 aircraft.
- ▶ Closure rate ($-\dot{r}$): Negative of range rate.
- ▶ Tau (τ): Range over closure rate

$$\tau \equiv -\frac{r}{\dot{r}}$$

Aircraft State Information

2D Euclidean Airspace

- ▶ $\mathbf{s}_o, \mathbf{v}_o$: Ownship's current position and velocity (2D Vectors).
- ▶ $\mathbf{s}_i, \mathbf{v}_i$: Intruder's current position and velocity (2D Vectors).
- ▶ It is convenient to express aircraft states in a relative coordinate system where the intruder is fixed at the center:
 - ▶ $\mathbf{s} = \mathbf{s}_o - \mathbf{s}_i$
 - ▶ $\mathbf{v} = \mathbf{v}_o - \mathbf{v}_i$

$$r(\mathbf{s}) \equiv \|\mathbf{s}\|,$$

$$\dot{r}(\mathbf{s}, \mathbf{v}) \equiv \frac{\mathbf{s} \cdot \mathbf{v}}{\|\mathbf{s}\|}$$

$$\text{converging?}(\mathbf{s}, \mathbf{v}) \equiv \mathbf{s} \cdot \mathbf{v} < 0$$

$$\tau(\mathbf{s}, \mathbf{v}) \equiv -\frac{\mathbf{s}^2}{\mathbf{s} \cdot \mathbf{v}}$$

...in PVS

```
TCAS_tau : THEORY
```

```
BEGIN
```

```
IMPORTING vectors@vectors_2D
```

```
% s is a 2D relative position
```

```
% v is a 2D relative velocity
```

```
s,v : VAR Vect2
```

```
range(s) : nnreal = norm(s)
```

```
closure_rate(nzs:Nz_vect2,v): real =  
  -(nzs*v)/norm(nzs)
```

```
...
```

```
END TCAS_tau
```

...in PVS

```
TCAS_tau : THEORY
```

```
BEGIN
```

```
  IMPORTING vectors@vectors_2D
```

```
  % s is a 2D relative position
```

```
  % v is a 2D relative velocity
```

```
  s,v : VAR Vect2
```

```
  range(s) : nnreal = norm(s)
```

```
  closure_rate(nzs:Nz_vect2,v): real =  
    -(nzs*v)/norm(nzs)
```

```
  ...
```

```
END TCAS_tau
```

...in PVS

```
TCAS_tau : THEORY
```

```
BEGIN
```

```
  IMPORTING vectors@vectors_2D
```

```
  % s is a 2D relative position
```

```
  % v is a 2D relative velocity
```

```
  s,v : VAR Vect2
```

```
  range(s) : nnreal = norm(s)
```

```
  closure_rate(nzs:Nz_vect2,v): real =  
    -(nzs*v)/norm(nzs)
```

```
  ...
```

```
END TCAS_tau
```

Converging Aircraft

```
converging?(s)(v) :bool =  
  s*v < 0
```

```
% nzv is a non-zero 2D vector  
nzs : VAR Nz_vect2
```

```
converging_closure_rate : LEMMA  
  closure_rate(nzs,v) > 0 IFF converging?(nzs)(v)
```

```
%|- converging_closure_rate : PROOF  
%|- (then (skip)  
%|-   (spread (grind) ((grind-reals) (grind-reals))))  
%|- QED converging_closure_rate
```

Converging Aircraft

```
converging?(s)(v) :bool =  
  s*v < 0
```

```
% nzv is a non-zero 2D vector  
nzs : VAR Nz_vect2
```

```
converging_closure_rate : LEMMA  
  closure_rate(nzs,v) > 0 IFF converging?(nzs)(v)
```

```
%|- converging_closure_rate : PROOF  
%|- (then (skip)  
%|-   (spread (grind) ((grind-reals) (grind-reals))))  
%|- QED converging_closure_rate
```

Converging Aircraft

```
converging?(s)(v) :bool =  
  s*v < 0
```

```
% nzv is a non-zero 2D vector  
nzs : VAR Nz_vect2
```

```
converging_closure_rate : LEMMA  
  closure_rate(nzs,v) > 0 IFF converging?(nzs)(v)
```

```
%|- converging_closure_rate : PROOF  
%|- (then (skip)  
%|-   (spread (grind) ((grind-reals) (grind-reals))))  
%|- QED converging_closure_rate
```

Converging Aircraft

```
converging?(s)(v) :bool =  
  s*v < 0
```

```
% nzv is a non-zero 2D vector  
nzs : VAR Nz_vect2
```

```
converging_closure_rate : LEMMA  
  closure_rate(nzs,v) > 0 IFF converging?(nzs)(v)
```

```
%|- converging_closure_rate : PROOF  
%|- (then (skip)  
%|-   (spread (grind) ((grind-reals) (grind-reals))))  
%|- QED converging_closure_rate
```


TCAS Tau

```
% Time tau is only defined when aircraft are converging
tau(s:Vect2,v:(converging?(s))) : nnreal =
  -sqv(s)/(s*v)
```

► Type Correctness Conditions:

```
tau_TCC1: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    (s*v) /= 0;
```

```
tau_TCC2: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    -sqv(s)/(s*v) >= 0;
```

► TCAS Tau is range over closure rate

```
tau_def : LEMMA
  converging?(s)(v) IMPLIES
  tau(s,v) = range(s)/closure_rate(s,v)
```

TCAS Tau

```
% Time tau is only defined when aircraft are converging
tau(s:Vect2,v:(converging?(s))) : nnreal =
  -sqv(s)/(s*v)
```

► Type Correctness Conditions:

```
tau_TCC1: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    (s*v) /= 0;
```

```
tau_TCC2: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    -sqv(s)/(s*v) >= 0;
```

► TCAS Tau is range over closure rate

```
tau_def : LEMMA
  converging?(s)(v) IMPLIES
  tau(s,v) = range(s)/closure_rate(s,v)
```

TCAS Tau

```
% Time tau is only defined when aircraft are converging
tau(s:Vect2,v:(converging?(s))) : nnreal =
  -sqv(s)/(s*v)
```

► Type Correctness Conditions:

```
tau_TCC1: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    (s*v) /= 0;
```

```
tau_TCC2: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    -sqv(s)/(s*v) >= 0;
```

► TCAS Tau is range over closure rate

```
tau_def : LEMMA
  converging?(s)(v) IMPLIES
  tau(s,v) = range(s)/closure_rate(s,v)
```

TCAS Tau

```
% Time tau is only defined when aircraft are converging
tau(s:Vect2,v:(converging?(s))) : nnreal =
  -sqv(s)/(s*v)
```

► Type Correctness Conditions:

```
tau_TCC1: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    (s*v) /= 0;
```

```
tau_TCC2: OBLIGATION
  FORALL (s: Vect2, v: (converging?(s))):
    -sqv(s)/(s*v) >= 0;
```

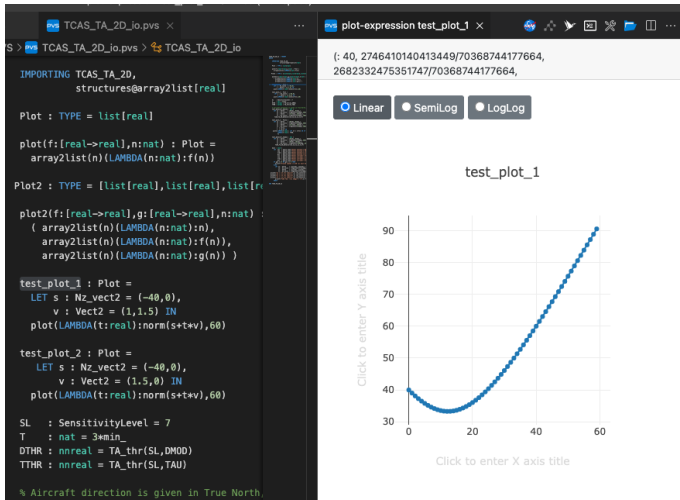
► TCAS Tau is range over closure rate

```
tau_def : LEMMA
  converging?(s)(v) IMPLIES
  tau(s,v) = range(s)/closure_rate(s,v)
```

Range as a Function of Time

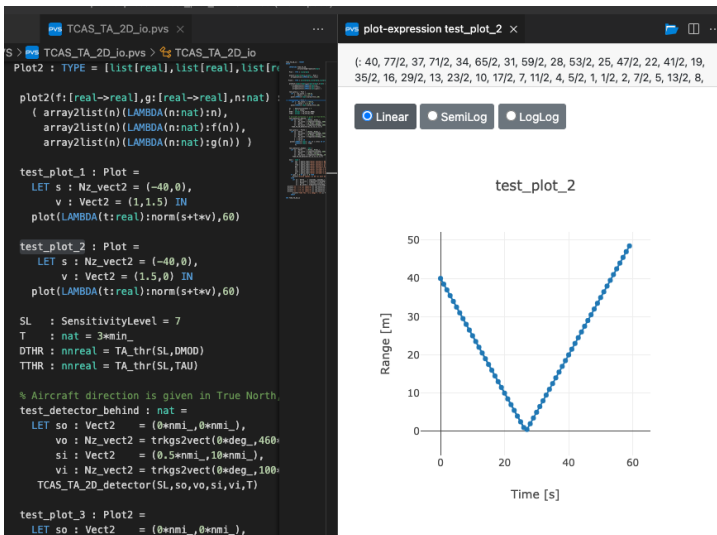
Let \mathbf{s} and \mathbf{v} be initial position and constant velocity:

$$t \mapsto \|\mathbf{s} + t * \mathbf{v}\|.$$



(Used with permission from Microsoft.)

Derivative of Range May Not Exist!



(Used with permission from Microsoft.)

Subtyping, Dependent Types, Auto Rewrites, Judgements

```
RangeDomain(nzs,v) : TYPE =  
  {t:real | det(nzs,v) = 0 IMPLIES t*sqr(v) /= -nzs*v}
```

```
range_deriv_domain : LEMMA  
  deriv_domain?[RangeDomain(nzs,v)]
```

```
AUTO_REWRITE+ range_deriv_domain
```

```
range_at(nzs,v)(t:RangeDomain(nzs, v)) : nnreal =  
  range(nzs+t*v)
```

```
derivable_range_at : JUDGEMENT  
  range_at(nzs,v) HAS_TYPE  
    (differentiable?[RangeDomain(nzs, v)])
```

Subtyping, Dependent Types, Auto Rewrites, Judgements

```
RangeDomain(nzs,v) : TYPE =  
  {t:real | det(nzs,v) = 0 IMPLIES t*sqr(v) /= -nzs*v}
```

```
range_deriv_domain : LEMMA  
  deriv_domain?[RangeDomain(nzs,v)]
```

```
AUTO_REWRITE+ range_deriv_domain
```

```
range_at(nzs,v)(t:RangeDomain(nzs, v)) : nnreal =  
  range(nzs+t*v)
```

```
derivable_range_at : JUDGEMENT  
  range_at(nzs,v) HAS_TYPE  
    (differentiable?[RangeDomain(nzs, v)])
```


Subtyping, Dependent Types, Auto Rewrites, Judgements

```
RangeDomain(nzs,v) : TYPE =  
  {t:real | det(nzs,v) = 0 IMPLIES t*sqr(v) /= -nzs*v}
```

```
range_deriv_domain : LEMMA  
  deriv_domain?[RangeDomain(nzs,v)]
```

```
AUTO_REWRITE+ range_deriv_domain
```

```
range_at(nzs,v)(t:RangeDomain(nzs, v)) : nnreal =  
  range(nzs+t*v)
```

```
derivable_range_at : JUDGEMENT  
  range_at(nzs,v) HAS_TYPE  
    (differentiable?[RangeDomain(nzs, v)])
```

Subtyping, Dependent Types, Auto Rewrites, Judgements

```
RangeDomain(nzs,v) : TYPE =  
  {t:real | det(nzs,v) = 0 IMPLIES t*sqv(v) /= -nzs*v}
```

```
range_deriv_domain : LEMMA  
  deriv_domain?[RangeDomain(nzs,v)]
```

```
AUTO_REWRITE+ range_deriv_domain
```

```
range_at(nzs,v)(t:RangeDomain(nzs, v)) : nnreal =  
  range(nzs+t*v)
```

```
derivable_range_at : JUDGEMENT  
  range_at(nzs,v) HAS_TYPE  
    (differentiable?[RangeDomain(nzs, v)])
```

Subtyping, Dependent Types, Auto Rewrites, Judgements

```
RangeDomain(nzs,v) : TYPE =  
  {t:real | det(nzs,v) = 0 IMPLIES t*sqv(v) /= -nzs*v}
```

```
range_deriv_domain : LEMMA  
  deriv_domain?[RangeDomain(nzs,v)]
```

```
AUTO_REWRITE+ range_deriv_domain
```

```
range_at(nzs,v)(t:RangeDomain(nzs, v)) : nnreal =  
  range(nzs+t*v)
```

```
derivable_range_at : JUDGEMENT  
  range_at(nzs,v) HAS_TYPE  
    (differentiable?[RangeDomain(nzs, v)])
```

Derivatives

```
%|- derivable_range_at : PROOF
%|- (then (skeep) (rewrite "range_at_eq"))
%|=   (derivable :use "sq_range_at")
%|- (hide 2) (skeep :preds? t) (assert))
%|- QED derivable_range_at
```

```
derivative_range_at : LEMMA
  deriv[RangeDomain(nzs,v)](range_at(nzs,v)) =
  LAMBDA(t:RangeDomain(nzs,v)):(nzs*v+t*sqv(v))/norm(nzs+t*v)
```

```
%|- derivative_range_at : PROOF
%|- (then (skeep) (rewrite "range_at_eq"))
%|- (spread (deriv :use "sq_range_at")
%|-   ((then (expand "sq_range_at" 1)(expand "norm" 1)(propax))
%|-     (then (hide -)(skeep)(lemma "range_domain_pos")(inst?)
%|-       (expand "norm") (assert))))))
%|- QED derivative_range_at
```

Derivatives

```
%|- derivable_range_at : PROOF
%|- (then (skeep) (rewrite "range_at_eq"))
%|=   (derivable :use "sq_range_at")
%|-   (hide 2) (skeep :preds? t) (assert))
%|- QED derivable_range_at
```

```
derivative_range_at : LEMMA
  deriv[RangeDomain(nzs,v)](range_at(nzs,v)) =
  LAMBDA(t:RangeDomain(nzs,v)):(nzs*v+t*sqv(v))/norm(nzs+t*v)
```

```
%|- derivative_range_at : PROOF
%|- (then (skeep) (rewrite "range_at_eq"))
%|-   (spread (deriv :use "sq_range_at")
%|-     ((then (expand "sq_range_at" 1)(expand "norm" 1)(propax))
%|-       (then (hide -)(skeep)(lemma "range_domain_pos")(inst?)
%|-         (expand "norm") (assert))))))
%|- QED derivative_range_at
```

Closure Rate is the Neg. Derivative of Range Over Time

```
closure_rate_def : LEMMA
  (det(nzs,v) /= 0 OR v /= zero) IMPLIES
  closure_rate(nzs,v) =
    -deriv[RangeDomain(nzs,v)](range_at(nzs,v))(0)
```

```
%|- closure_rate_def : PROOF
%|- (then (skip)(rewrite "derivative_range_at"))(beta)
%|- (expand "closure_rate")(assert))
%|- QED closure_rate_def
```

TCAS TA 2D Core Logic

```
TCAS_TA_2D_core[DTHR,TTHR:nnreal]: THEORY
BEGIN

  IMPORTING TCAS_tau

  TCAS_TA_2D_core(s,v:Vect2) : bool =
    LET s2 = sqv(s) IN
      s2 < sq(DTHR) OR
      (converging?(s)(v) AND s2 < -TTHR*(s*v))

  % Requirement: Both aircraft have the same TA status
  TCAS_TA_2D_core_sym : LEMMA
    FORALL (s,v:Vect2):
      TCAS_TA_2D_core(s,v) = TCAS_TA_2D_core(-s,-v)
  ...
END TCAS_TA_2D_core
```

TCAS TA 2D Core Logic

```
TCAS_TA_2D_core[DTHR,TTHR:nnreal]: THEORY
BEGIN

  IMPORTING TCAS_tau

  TCAS_TA_2D_core(s,v:Vect2) : bool =
    LET s2 = sqv(s) IN
      s2 < sq(DTHR) OR
      (converging?(s)(v) AND s2 < -TTHR*(s*v))

  % Requirement: Both aircraft have the same TA status
  TCAS_TA_2D_core_sym : LEMMA
    FORALL (s,v:Vect2):
      TCAS_TA_2D_core(s,v) = TCAS_TA_2D_core(-s,-v)
  ...
END TCAS_TA_2D_core
```


TCAS TA 2D Core Logic

```
TCAS_TA_2D_core[DTHR,TTHR:nnreal]: THEORY
BEGIN

  IMPORTING TCAS_tau

  TCAS_TA_2D_core(s,v:Vect2) : {b : bool | b IFF
    norm(s) < DTHR OR
    (converging?(s)(v) AND tau(s,v) < TTHR)} =
    LET s2 = sqv(s) IN
      s2 < sq(DTHR) OR
      (converging?(s)(v) AND s2 < -TTHR*(s*v))

  % Requirement: Both aircraft have the same TA status
  TCAS_TA_2D_core_sym : LEMMA
    FORALL (s,v:Vect2):
      TCAS_TA_2D_core(s,v) = TCAS_TA_2D_core(-s,-v)
  ...
END TCAS_TA_2D_core
```

Types as Specifications

```
% Returns first time when a TA is issued up to T
% or T+1 if TA won't be issued
TCAS_TA_2D_det_rec(s,v:Vect2,T:nat) (t:upto(T+1)) :
  RECURSIVE upto(T+1) =
    IF t > T OR TCAS_TA_2D_core(s+t*v,v) THEN t
    ELSE TCAS_TA_2D_det_rec(s,v,T)(t+1)
    ENDIF
  MEASURE T+1-t

TCAS_TA_2D_detector(s,v:Vect2,T:nat): {k:upto(T+1) |
  (FORALL (i:below(k)) : NOT TCAS_TA_2D_core(s+i*v,v)) AND
  (k <= T IMPLIES TCAS_TA_2D_core(s+k*v,v))} =
  TCAS_TA_2D_det_rec(s,v,T)(0)
```

Types as Specifications

```
% Returns first time when a TA is issued up to T
% or T+1 if TA won't be issued
TCAS_TA_2D_det_rec(s,v:Vect2,T:nat) (t:upto(T+1) |
    FORALL (i:below(t)) : NOT TCAS_TA_2D_core(s+i*v,v)) :
    RECURSIVE upto(T+1) =
    IF t > T OR TCAS_TA_2D_core(s+t*v,v) THEN t
    ELSE TCAS_TA_2D_det_rec(s,v,T)(t+1)
    ENDIF
MEASURE T+1-t

TCAS_TA_2D_detector(s,v:Vect2,T:nat): {k:upto(T+1) |
    (FORALL (i:below(k)) : NOT TCAS_TA_2D_core(s+i*v,v)) AND
    (k <= T IMPLIES TCAS_TA_2D_core(s+k*v,v))} =
    TCAS_TA_2D_det_rec(s,v,T)(0)
```

Types as Specifications

```
% Returns first time when a TA is issued up to T
% or T+1 if TA won't be issued
TCAS_TA_2D_det_rec(s,v:Vect2,T:nat)(t:upto(T+1) |
  FORALL (i:below(t)) : NOT TCAS_TA_2D_core(s+i*v,v)) :
  RECURSIVE {k:upto(T+1) |
    (FORALL (i:below(k)) : NOT TCAS_TA_2D_core(s+i*v,v)) AND
    (k <= T IMPLIES TCAS_TA_2D_core(s+k*v,v))} =
  IF t > T OR TCAS_TA_2D_core(s+t*v,v) THEN t
  ELSE TCAS_TA_2D_det_rec(s,v,T)(t+1)
  ENDIF
MEASURE T+1-t

TCAS_TA_2D_detector(s,v:Vect2,T:nat): {k:upto(T+1) |
  (FORALL (i:below(k)) : NOT TCAS_TA_2D_core(s+i*v,v)) AND
  (k <= T IMPLIES TCAS_TA_2D_core(s+k*v,v))} =
  TCAS_TA_2D_det_rec(s,v,T)(0)
```

Sensitivity Levels and Thresholds

Ownship Altitude (feet)	SL	TAU (sec)	DMOD (nmi)	ZTHR (feet)
Below 1000	2	20	0.30	850
1000 - 2350	3	25	0.33	850
2350 - 5000	4	30	0.48	850
5000 - 10000	5	40	0.75	850
10000 - 20000	6	45	1.0	850
20000 - 42000	7	48	1.3	850
Above 42000	8	48	1.3	1200

Sensitivity Levels and Thresholds

Ownship Altitude (feet)	SL	TAU (sec)	DMOD (nmi)	ZTHR (feet)
Below 1000	2	20	0.30	850
1000 - 2350	3	25	0.33	850
2350 - 5000	4	30	0.48	850
5000 -10000	5	40	0.75	850
10000 - 20000	6	45	1.0	850
20000 - 42000	7	48	1.3	850
Above 42000	8	48	1.3	1200

A Basic Theory of Units

Units : THEORY

BEGIN

```
m_      :  posreal = 1           % 1 meter
km_      :  posreal = 1000        % 1 kilometer in meters
ft_      :  posreal = 0.3048      % 1 foot in meters
nmi_     :  posreal = 1852        % 1 nautical mile in meters

s_       :  posreal = 1           % 1 second
min_     :  posreal = 60          % 1 minute in seconds
hour_    :  posreal = 60*min_     % 1 hour in seconds

knt_     :  posreal = nmi_/hour_  % 1 knot in m/s
fpm_     :  posreal = ft_/min_    % 1 foot per minute in m/s
kph_     :  posreal = km_/hour_   % 1 km per hour in m/s
...
to_units(val:real,unit:posreal) : real = val/unit
...
```

END Units

A Basic Theory of Units

Units : THEORY

BEGIN

```
m_      :  posreal = 1           % 1 meter
km_      :  posreal = 1000        % 1 kilometer in meters
ft_      :  posreal = 0.3048      % 1 foot in meters
nmi_     :  posreal = 1852        % 1 nautical mile in meters

s_       :  posreal = 1           % 1 second
min_     :  posreal = 60          % 1 minute in seconds
hour_    :  posreal = 60*min_     % 1 hour in seconds

knt_     :  posreal = nmi_/hour_  % 1 knot in m/s
fpm_     :  posreal = ft_/min_    % 1 foot per minute in m/s
kph_     :  posreal = km_/hour_   % 1 km per hour in m/s
...
to_units(val:real,unit:posreal) : real = val/unit
...
```

END Units

A Basic Theory of Units

Units : THEORY

BEGIN

```
m_      : MACRO posreal = 1           % 1 meter
km_     : MACRO posreal = 1000        % 1 kilometer in meters
ft_     : MACRO posreal = 0.3048     % 1 foot in meters
nmi_    : MACRO posreal = 1852       % 1 nautical mile in meters
```

```
s_      : MACRO posreal = 1           % 1 second
min_    : MACRO posreal = 60          % 1 minute in seconds
hour_   : MACRO posreal = 60*min_    % 1 hour in seconds
```

```
knt_    : MACRO posreal = nmi_/hour_ % 1 knot in m/s
fpm_    : MACRO posreal = ft_/min_    % 1 foot per minute in m/s
kph_    : MACRO posreal = km_/hour_   % 1 km per hour in m/s
```

...

```
to_units(val:real,unit:posreal) : real = val/unit
```

...

END Units

A Basic Theory of Units

Units : THEORY

BEGIN

```
m_      : MACRO posreal = 1          % 1 meter
km_     : MACRO posreal = 1000       % 1 kilometer in meters
ft_     : MACRO posreal = 0.3048     % 1 foot in meters
nmi_    : MACRO posreal = 1852       % 1 nautical mile in meters
```

```
s_      : MACRO posreal = 1          % 1 second
min_    : MACRO posreal = 60         % 1 minute in seconds
hour_   : MACRO posreal = 60*min_    % 1 hour in seconds
```

```
knt_    : MACRO posreal = nmi_/hour_ % 1 knot in m/s
fpm_    : MACRO posreal = ft_/min_    % 1 foot per minute in m/s
kph_    : MACRO posreal = km_/hour_   % 1 km per hour in m/s
```

...

```
to_units(val:real,unit:posreal) : real = val/unit
```

...

END Units

TCAS Tables: Sensitivity Level

```
TCAS_tables : THEORY
```

```
BEGIN
```

```
  IMPORTING Units
```

```
  SensitivityLevel : TYPE = subrange(2,8)
```

```
  sensitivity_level(alt:nnreal) : SensitivityLevel =  
    TABLE
```

```
    |      0*ft_ <= alt AND alt < 1000*ft_ | 2 ||
```

```
    | 1000*ft_ <= alt AND alt < 2350*ft_ | 3 ||
```

```
    | 2350*ft_ <= alt AND alt < 5000*ft_ | 4 ||
```

```
    | 5000*ft_ <= alt AND alt < 10000*ft_ | 5 ||
```

```
    | 10000*ft_ <= alt AND alt < 20000*ft_ | 6 ||
```

```
    | 20000*ft_ <= alt AND alt < 42000*ft_ | 7 ||
```

```
    | ELSE                                     | 8 ||
```

```
  ENDTABLE
```

TCAS Tables: Sensitivity Level

```
TCAS_tables : THEORY
```

```
BEGIN
```

```
  IMPORTING Units
```

```
  SensitivityLevel : TYPE = subrange(2,8)
```

```
  sensitivity_level(alt:nnreal) : SensitivityLevel =
```

```
    TABLE
```

```
%+-----++
|      0*ft_ <= alt AND alt <  1000*ft_ | 2 ||
%+-----++
|  1000*ft_ <= alt AND alt <  2350*ft_ | 3 ||
%+-----++
|  2350*ft_ <= alt AND alt <  5000*ft_ | 4 ||
%+-----++
|  5000*ft_ <= alt AND alt < 10000*ft_ | 5 ||
%+-----++
| 10000*ft_ <= alt AND alt < 20000*ft_ | 6 ||
%+-----++
| 20000*ft_ <= alt AND alt < 42000*ft_ | 7 ||
%+-----++
| ELSE                                     | 8 ||
%+-----++
```

```
  ENDTABLE
```

TCAS Tables: Sensitivity Level

```
TCAS_tables : THEORY
```

```
BEGIN
```

```
  IMPORTING Units
```

```
  SensitivityLevel : TYPE = subrange(2,8)
```

```
  sensitivity_level(alt:nnreal) : SensitivityLevel =
```

```
    TABLE
```

```
    %+-----+--+
    |      0*ft_ <= alt AND alt <  1000*ft_ | 2 ||
```

```
    %+-----+--+
    |  1000*ft_ <= alt AND alt <  2350*ft_ | 3 ||
```

```
    %+-----+--+
    |  2350*ft_ <= alt AND alt <  5000*ft_ | 4 ||
```

```
    %+-----+--+
    |  5000*ft_ <= alt AND alt < 10000*ft_ | 5 ||
```

```
    %+-----+--+
    | 10000*ft_ <= alt AND alt < 20000*ft_ | 6 ||
```

```
    %+-----+--+
    | 20000*ft_ <= alt AND alt < 42000*ft_ | 7 ||
```

```
    %+-----+--+
    | ELSE                                     | 8 ||
```

```
    %+-----+--+
    ENDTABLE
```

TCAS Tables: Sensitivity Level

```
TCAS_tables : THEORY
```

```
BEGIN
```

```
  IMPORTING Units
```

```
  SensitivityLevel : TYPE = subrange(2,8)
```

```
  sensitivity_level(alt:nnreal) : SensitivityLevel =
```

```
    TABLE
```

```
    %+-----+-----+
    |      0*ft_ <= alt AND alt <  1000*ft_ | 2 ||
    %+-----+-----+
    |  1000*ft_ <= alt AND alt <  2350*ft_ | 3 ||
    %+-----+-----+
    |  2350*ft_ <= alt AND alt <  5000*ft_ | 4 ||
    %+-----+-----+
    |  5000*ft_ <= alt AND alt < 10000*ft_ | 5 ||
    %+-----+-----+
    | 10000*ft_ <= alt AND alt < 20000*ft_ | 6 ||
    %+-----+-----+
    | 20000*ft_ <= alt AND alt < 42000*ft_ | 7 ||
    %+-----+-----+
    | ELSE                                     | 8 ||
    %+-----+-----+
```

```
  ENDTABLE
```

TCAS Tables: Sensitivity Level

```
TCAS_tables : THEORY
BEGIN
  IMPORTING Units

  SensitivityLevel : TYPE = subrange(2,8)

  sensitivity_level(alt:nnreal) : SensitivityLevel =
    TABLE
      %+-----+-----+
      |      0*ft_ <= alt AND alt <  1000*ft_ | 2 ||
      %+-----+-----+
      |  1000*ft_ <= alt AND alt <  2350*ft_ | 3 ||
      %+-----+-----+
      |  2350*ft_ <= alt AND alt <  5000*ft_ | 4 ||
      %+-----+-----+
      |  5000*ft_ <= alt AND alt < 10000*ft_ | 5 ||
      %+-----+-----+
      | 10000*ft_ <= alt AND alt < 20000*ft_ | 6 ||
      %+-----+-----+
      | 20000*ft_ <= alt AND alt < 42000*ft_ | 7 ||
      %+-----+-----+
      | ELSE                                     | 8 ||
      %+-----+-----+
    ENDTABLE
```

TCAS Tables: TAU, DMOD, and ZTHR

ThresholdSymbol : TYPE = { TAU, DMOD, ZTHR }

TA_thr(sl:SensitivityLevel,thr:ThresholdSymbol) : nnreal =

TABLE sl , thr

%--	+	+	+	+	+	+
		[TAU		DMOD		ZTHR]
%--	+	+	+	+	+	+
	2		20		0.30*nmi_	850*ft_
%--	+	+	+	+	+	+
	3		25		0.33*nmi_	850*ft_
%--	+	+	+	+	+	+
	4		30		0.48*nmi_	850*ft_
%--	+	+	+	+	+	+
	5		40		0.75*nmi_	850*ft_
%--	+	+	+	+	+	+
	6		45		1.0*nmi_	850*ft_
%--	+	+	+	+	+	+
	7		48		1.3*nmi_	850*ft_
%--	+	+	+	+	+	+
	8		48		1.3*nmi_	1200*ft_
%--	+	+	+	+	+	+

ENDTABLE

TCAS Tables: TAU, DMOD, and ZTHR

ThresholdSymbol : TYPE = { TAU, DMOD, ZTHR }

TA_thr(sl:SensitivityLevel,thr:ThresholdSymbol) : nnreal =

TABLE sl , thr

%--	+	-----	+	-----	+	-----	++
		[TAU		DMOD		ZTHR]
%--	+	-----	+	-----	+	-----	++
		2	20	0.30*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		3	25	0.33*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		4	30	0.48*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		5	40	0.75*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		6	45	1.0*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		7	48	1.3*nmi_		850*ft_	
%--	+	-----	+	-----	+	-----	++
		8	48	1.3*nmi_		1200*ft_	
%--	+	-----	+	-----	+	-----	++

ENDTABLE

TCAS Tables: TAU, DMOD, and ZTHR

ThresholdSymbol : TYPE = { TAU, DMOD, ZTHR }

TA_thr(sl:SensitivityLevel,thr:ThresholdSymbol) : nnreal =

```
TABLE sl ,      thr
%--- +-----+-----+-----++
      |[ TAU |      DMOD      |      ZTHR      ]|
%--- +-----+-----+-----++
| 2 |   20 | 0.30*nmi_ |   850*ft_ ||
%--- +-----+-----+-----++
| 3 |   25 | 0.33*nmi_ |   850*ft_ ||
%--- +-----+-----+-----++
| 4 |   30 | 0.48*nmi_ |   850*ft_ ||
%--- +-----+-----+-----++
| 5 |   40 | 0.75*nmi_ |   850*ft_ ||
%--- +-----+-----+-----++
| 6 |   45 | 1.0*nmi_  |   850*ft_ ||
%--- +-----+-----+-----++
| 7 |   48 | 1.3*nmi_  |   850*ft_ ||
%--- +-----+-----+-----++
| 8 |   48 | 1.3*nmi_  |  1200*ft_ ||
%--- +-----+-----+-----++
```

ENDTABLE

TCAS Tables: Type Correctness Conditions

```
% Disjointness TCC generated (at line 10, column 4) for
% TABLE
%  %-----+-----++
%  | 0 * 0.3048 <= alt AND alt < 1000 * 0.3048      | 2 ||
%  ...
% ENDTABLE
% proved - complete
sensitivity_level_TCC1: OBLIGATION
  FORALL (alt: nnreal):
    NOT ((0*0.3048 <= alt AND alt < 1000*0.3048) AND
          1000*0.3048 <= alt AND alt < 2350*0.3048) ...

% Coverage TCC generated (at line 34, column 5) for
% TABLE sl, thr
%  %+-----+-----++
%  |[ TAU | DMOD      | ZTHR      ]|
%  ...
% ENDTABLE
% proved - complete
TA_thr_TCC1: OBLIGATION
  FORALL (sl: SensitivityLevel):
    sl=2 OR sl=3 OR sl=4 OR sl=5 OR sl=6 OR sl=7 OR sl=8;
```

A Maneuver Guidance Algorithm

TCAS_TA_2D: THEORY

BEGIN

IMPORTING TCAS_TA_2D_core, TCAS_tables, aviation@track

sl : VAR SensitivityLevel

so,si : VAR Vect2 % 2D ownship's and intruder's position

vo,vi : VAR Nz_vect2 % 2D ownship's and intruder's velocity

T : VAR nat

gso : VAR posreal

TCAS_TA_2D_detector(sl,so,vo,si,vi,T) : upto(T+1) =

LET DTHR = TA_thr(sl,DMOD),

TTHR = TA_thr(sl,TAU) IN

TCAS_TA_2D_detector[DTHR,TTHR](so-si,vo-vi,T)

% Returns a list of degrees that issues a TA alert

TCAS_TA_bands_rec(sl,so,gso,si,vi,T)(trk:upto(360)) : RECURSIVE list[below(360)] =

LET vo = trkgs2vect(trk*deg_,gso) IN

IF trk = 360 THEN null

ELIF TCAS_TA_2D_detector(sl,so,vo,si,vi,T) <= T THEN

cons(trk,TCAS_TA_bands_rec(sl,so,gso,si,vi,T)(trk+1))

ELSE TCAS_TA_bands_rec(sl,so,gso,si,vi,T)(trk+1)

ENDIF

MEASURE 360-trk

TCAS_TA_2D_bands(sl,so,vo,si,vi,T) : list[below(360)] =

TCAS_TA_bands_rec(sl,so,norm(vo),si,vi,T)(0)

END TCAS_TA_2D

Animation of Functional Specifications ...

```
TCAS_TA_2D_io : THEORY
BEGIN
  SL    : SensitivityLevel = 7
  T      : nat = 3*min_
  DTHR  : nnreal = TA_thr(SL,DMOD)
  TTHR  : nnreal = TA_thr(SL,TAU)

  % Aircraft direction is given in True North, clockwise convention
  test_detector_behind : nat =
    LET so : Vect2      = (0*nmi_,0*nmi_),
        vo : Nz_vect2 = trkgs2vect(0*deg_,460*knt_),
        si : Vect2      = (0.5*nmi_,10*nmi_),
        vi : Nz_vect2 = trkgs2vect(0*deg_,100*knt_) IN
      TCAS_TA_2D_detector(SL,so,vo,si,vi,T)

  test_detector_headon : nat =
    LET so : Vect2      = (0*nmi_,0*nmi_),
        vo : Nz_vect2 = trkgs2vect(0*deg_,460*knt_),
        si : Vect2      = (0*nmi_,10*nmi_),
        vi : Nz_vect2 = trkgs2vect(180*deg_,100*knt_) IN
      TCAS_TA_2D_detector(SL,so,vo,si,vi,T)
END TCAS_TA_2D_io
```

...in PVSio

```
<PVSio> test_detector_behind;
```

```
==>
```

```
53
```

```
<PVSio> test_detector_headon;
```

```
==>
```

```
17
```

Programming in PVSio with I/O

```
main : void =
  LET  sox  = query_real("Enter ownship's WE position [nmi]:"),
      soy  = query_real("Enter ownship's SN position [nmi]:"),
      trko = query_real("Enter ownship's ground track [deg]:"),
      gso  = query_real("Enter ownship's ground speed [knt]:"),
      six  = query_real("Enter intruder's WE position [nmi]:"),
      siy  = query_real("Enter intruder's SN position [nmi]:"),
      trki = query_real("Enter intruder's ground track [deg]:"),
      gsi  = query_real("Enter intruder's ground speed [knot]:") IN
  IF gso <= 0 OR gsi <= 0 THEN
    printf("Ground speeds must be strictly positive!")
  ELSE
    LET so : Vect2      = (sox*nmi_,soy*nmi_),
        vo : Nz_vect2 = trkgs2vect(trko*deg_,gso*knt_),
        si : Vect2      = (six*nmi_,siy*nmi_),
        vi : Nz_vect2 = trkgs2vect(trki*deg_,gsi*knt_) IN
    printf("TCAS TAs: ~{~a [deg]~^, ~}",
           {|TCAS_TA_2D_bands(SL,so,vo,si,vi,T)|})
  ENDIF
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
```

```
Enter ownship's WE position [nmi]:
```

```
0
```

```
Enter ownship's SN position [nmi]:
```

```
0
```

```
Enter ownship's ground track [deg]:
```

```
0
```

```
Enter ownship's ground speed [knt]:
```

```
300
```

```
Enter intruder's WE position [nmi]:
```

```
10
```

```
Enter intruder's SN position [nmi]:
```

```
10
```

```
Enter intruder's ground track [deg]:
```

```
180
```

```
Enter intruder's ground speed [knot]:
```

```
300
```

```
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],  
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],  
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],  
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],  
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],  
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],  
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```


PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```


PVSio From Command Line

```
$ pvsio @TCAS_TA_2D_io:
Enter ownship's WE position [nmi]:
0
Enter ownship's SN position [nmi]:
0
Enter ownship's ground track [deg]:
0
Enter ownship's ground speed [knt]:
300
Enter intruder's WE position [nmi]:
10
Enter intruder's SN position [nmi]:
10
Enter intruder's ground track [deg]:
180
Enter intruder's ground speed [knot]:
300
TCAS TAs: 62 [deg], 63 [deg], 64 [deg], 65 [deg], 66 [deg], 67 [deg],
68 [deg], 69 [deg], 70 [deg], 71 [deg], 72 [deg], 73 [deg], 74 [deg],
75 [deg], 76 [deg], 77 [deg], 78 [deg], 79 [deg], 80 [deg], 81 [deg],
82 [deg], 83 [deg], 84 [deg], 85 [deg], 86 [deg], 87 [deg], 88 [deg],
89 [deg], 90 [deg], 91 [deg], 92 [deg], 93 [deg], 94 [deg], 95 [deg],
96 [deg], 97 [deg], 98 [deg], 99 [deg], 100 [deg], 101 [deg], 102 [deg],
103 [deg], 104 [deg], 105 [deg], 106 [deg], 107 [deg], 108 [deg]
```

Finally

```
top : THEORY
BEGIN

    IMPORTING TCAS_tau,           % Definition of tau and TCPA
              TCAS_TA_2D_core,    % 2-D core traffic alerting logic
              Units,              % Unit conversion functions
              TCAS_tables,        % TCAS threshold tables
              TCAS_TA_2D,         % TCAS TA 2-D logic
              TCAS_TA_2D_io

END top

$ proveit -a
Processing TutorialPVS.
Writing output to file ./TutorialPVS.summary
Grand Totals: 45 proofs, 45 attempted, 45 succeeded (46.75 s)
```

Finally

```
top : THEORY
BEGIN

    IMPORTING TCAS_tau,           % Definition of tau and TCPA
              TCAS_TA_2D_core,    % 2-D core traffic alerting logic
              Units,              % Unit conversion functions
              TCAS_tables,        % TCAS threshold tables
              TCAS_TA_2D,         % TCAS TA 2-D logic
              TCAS_TA_2D_io

END top

$ proveit -a
Processing TutorialPVS.
Writing output to file ./TutorialPVS.summary
Grand Totals: 45 proofs, 45 attempted, 45 succeeded (46.75 s)
```

Finally

```
top : THEORY
BEGIN

    IMPORTING TCAS_tau,           % Definition of tau and TCPA
              TCAS_TA_2D_core, % 2-D core traffic alerting logic
              Units,           % Unit conversion functions
              TCAS_tables,     % TCAS threshold tables
              TCAS_TA_2D,      % TCAS TA 2-D logic
              TCAS_TA_2D_io

END top

$ proveit -a
Processing TutorialPVS.
Writing output to file ./TutorialPVS.summary
Grand Totals: 45 proofs, 45 attempted, 45 succeeded (46.75 s)
```

To Know More

- ▶ PVS: <https://pvs.csl.sri.com>
- ▶ VSCode-PVS:
<https://shemesh.larc.nasa.gov/fm/VSCode-PVS>
- ▶ PVS @ NASA: <https://shemesh.larc.nasa.gov/fm/pvs>
- ▶ NASALib:
<https://shemesh.larc.nasa.gov/fm/pvs/PVS-library>
- ▶ Formalization of Detect and Avoid:
<https://shemesh.larc.nasa.gov/fm/DAIDALUS>