Mayalen Etcheverry

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RESEARCH INTERESTS

Curiosity-Driven Artificial Intelligence • Representation Learning • Automated Discovery in Science • Healthcare

EDUCATION

INRIA, <u>Flowers</u> team <u>Poietis</u> company Ph.D. in Machine Learning, Advisor: Dr. <u>Pierre-Yves Oudeyer</u>	Bordeaux, FR 2020–Current
- Thesis: "Automated Discovery of Self-Organized Structures in Morphogenetic Systems"	
 University College of London (distinctions, GPA: 4.0/4.0) M.Sc. in Computer Vision, Computer Graphics and Imaging Thesis: "Making parametric models of buildings easier to edit by predicting future edit patterns in the Open3D platform", Thesis Supervisor: Dr. Paul Guerrero 	London, GB 2016–2017
Télécom ParisTech , Top-ranked French school in digital technologies (GPA: 3.6/4.0) M.Eng . in Computer Graphics (major) and Data Science (minor) B.Sc. in Computer Science	Paris, FR 2014–2017
Engineering School Preparatory Classes (GPA: 3.8/4.0) Undergraduate program in mathematics and physics to prepare the national competitive entrance exams to the <i>Grandes écoles</i>	Bordeaux, FR 2012–2014

R&D WORK EXPERIENCE

INRIA, in the **Flowers** project-team

Bordeaux, FR

Research Engineer, Supervisor: Dr. Pierre-Yves Oudeyer

2018 - 2020

- Unsupervised Representation Learning for Intrinsically-Motivated Exploration of Complex Systems.
- Development of a modular and dynamic network architecture where a hierarchy of behavioral characterization spaces is progressively constructed, allowing flexible representations and intuitive guidance during the discovery process.

Siemens Healthineers Princeton, USA

Research Scientist Intern, Supervisor: Dr. <u>Bogdan Georgescu</u> and Dr. <u>Sasa Grbic</u>

2017-2018

- Deep Learning for organ segmentation in 3D CT Scans: responsible for implementing the preprocessing/training/evaluation pipeline for 10 organs. Practical Experience with Large Databases.
- Research and development of a deep reinforcement-learning algorithm for localizing anatomical structures in 3D images.

PUBLICATIONS

- [1] **M. Etcheverry**, C. Moulin-Frier, and P.-Y. Oudeyer, "Hierarchically organized latent modules for exploratory search in morphogenetic systems", *Neural Information Processing Systems (NeurIPS)*, 2020.
- [2] C. Reinke*, **M. Etcheverry***, and P.-Y. Oudeyer, "Intrinsically motivated discovery of diverse patterns in self-organizing systems", in *International Conference on Learning Representations (ICLR)*, 2020.
- [3] **M. Etcheverry**, B. Georgescu, B. Odry, T. J. Re, S. Kaushik, B. Geiger, N. Mariappan, S. Grbic, and D. Comaniciu, "Nonlinear adaptively learned optimization for object localization in 3d medical images", in *Deep Learning in Medical Image Analysis and Multimodal Learning for Clinical Decision Support*, Springer, 2018, pp. 254–262.

WORKSHOP PAPERS AND ABSTRACTS

- [4] **M. Etcheverry**, P.-Y. Oudeyer, and C. Reinke, "Progressive growing of self-organized hierarchical representations for exploration", *ICLR Workshop Beyond "Tabula Rasa" in Reinforcement Learning (BeTR-RL)*, 2020.
- [5] **M. Etcheverry**, B. Georgescu, B. Odry, T. J. Re, S. Kaushik, B. Geiger, N. Mariappan, S. Grbic, and D. Comaniciu, "Nonlinear adaptively learned optimization for object localization in 3d medical images", *NeurIPS Workshop Medical Imaging Meets NeurIPS (MED-NeurIPS)*, 2018.

PATENTS

[6] **M. Etcheverry**, B. Georgescu, S. Grbic, D. Comaniciu, B. L. Odry, T. Re, S. Kaushik, B. Geiger, and M. S. Nadar, *Adaptive nonlinear optimization of shape parameters for object localization in 3d medical images*, US Patent App. 16/270,918, 2019.

ACADEMIC PROJECTS

See full list of projects and corresponding resources <u>here</u>.

- Open-Innovation Program (FIRST, 2016)
 Selected and coached by BNP-Parisbas, Orange and Nokia.
 Interdisciplinary team of engineers, designers and managers.
 Designed and implemented an interactive Runner Game in
 C++/OpenGL. Tracking of the player's finger with infrared LED.
 Project was displayed at Paris Center for digital creation.
- M.Sc. Final Research Project (May-Sep 2017)
 Learning edit patterns of a procedural model's parameters to assist in modeling buildings in the Open3D plaform.
 (C++/Eigen/QT).
- M.Sc. main projects (2017)
 - **Vision:** Segmentation, panoramas, tracking systems, dense stereo, 3D reconstruction, visual SLAM (Matlab)
 - Image/Video: Poisson Editing, NLM, restoration of old films, multiview video textures (Matlab)
 - 3D Geometry: ICP, Smoothing (C++/Eigen/OpenGL)
- Inverse Kinematics (Team of 4, June 2016)
 - IK system to predict the most likely 3D body pose given a set of constraints, learned model of human poses.
 - Tool to visualize the resulting animations (QT/OpenGL).

SKILLS

- · Programming:
 - Python, PyTorch
 - C / C++, openGL, GLSL
 - Matlab, Qt
 - Flask, HTML, CSS, JavaScript
 - Git
- Typesetting: LaTex
- Operating Systems: Linux / macOS

LANGUAGES

• French: native speaker

• English: advanced

- TOEFL: score of 102/120

• Spanish: advanced

- **OIB:** International Option Baccalaureate with Honors

• Serbo-Croatian: elementary

EXTRACURRICULAR ACTIVITIES

• Co-founder of the video association of Telecom ParisTech

Film realisations and projection events attended by all the students. Now taken over by other students.

Spring 2016

2015 - 2016

Realisation of a poster about gender stereotypes
 National competition for all Grandes écoles students to reflect on persistent stereotypes.
 Won the jury "coup de coeur" prize.

• Mathematics private classes to high-school student girls

2016-2018