

DELAY PROGRAM:

MVI B, FF 7T

L1: DCR B 4T

JNZ L1 10T/7T

HLT 5T

**Delay count: FF LENGTH OF DELAY
COUNT: 8 BIT**

CALCULATION:

$$FF_H = 255_{10}$$

TOTAL T-STATE OF LOOP: $(4+10)=14T$

LOOP WILL ROTATE 254 TIMES

**COMPLETE LOOP T STATE:
 $254*14=3556T$**

**AT 255TH CYCLE THE LOOP T STATE:
 $(4+7)= 11T$**

OUTSIDE LOOP T STATE: $7+5=12T$

COMPLETE PROGRAM T STATE :

$$3556+11+12=3579T$$

CLOCK FREQUENCY OF 8085 : 3MHz

**TIME PERIOD OF CLOCK : .333Micro
Second**

**So delay amount: $(3579 \times .333) = 1191$
Micro Second**

Q. CALCULATE THE DELAY AMOUNT.

C.F=2MHz

MVI B, AB 7T

L1: DCR B 4T

JNZ L1 10T/7T

HLT 5T

**Delay count: AB, LENGTH OF DELAY
COUNT: 8 BIT**

CALCULATION:

$AB_H = 171_{10}$

TOTAL T-STATE OF LOOP: $(4+10)=14T$

LOOP WILL ROTATE 170 TIMES

COMPLETE LOOP T STATE:

$170 \times 14 = 2380T$

AT 171^{TH} CYCLE THE LOOP T STATE:

$(4+7) = 11T$

OUTSIDE LOOP T STATE: $7+5=12T$

COMPLETE PROGRAM T STATE :

$$2380+11+12=2403T$$

CLOCK FREQUENCY OF 8085 : 2MHz

**TIME PERIOD OF CLOCK : .5Micro
Second**

**So delay amount: $(2403 \times .5) = 1201.5$
Micro Second**

9.2.2 Delay Subroutine Using Register Pair

PROGRAM			
Label	Mnemonics	Operands	Comments
	LXI	D, FFFF	Get FFFF in register pair D-E.
	DCX	D	Decrement count.
LOOP	* MOV	A, D	Move content of register D to accumulator.
	ORA	E	Check if D and E are zero.
	JNZ	LOOP	If D-E is not zero, jump to LOOP.
	RET		Return to main program.

States required for each instruction of the above program are:

Instruction	States
LXI	10
DCX	6
MOV	4
ORA	4
JNZ	7/10
RET	10

If the count in register pair D-E is N the total number of states are:

$$\begin{aligned}\text{States} &= 10 + N(6 + 4 + 4) + (N-1) \times 10 + 1 \times 7 + 10 \\ &= 24N + 17\end{aligned}$$

$$\text{Delay} = (24N + 17) \times \text{time for one state.}$$

Maximum delay will occur when count N = FFF hex
= 65,535 decimal.

$$\begin{aligned}\text{Maximum delay} &= (24 \times 65,535 + 17) \times 320 \times 10^{-9} \text{ second} \\ &= 20.97664 \text{ milliseconds.}\end{aligned}$$

This delay subroutine is given in the monitor program of 8085 microprocessor-kits. The count in register pair D-E is to be stored by the programmer. From DCX D to RET of the program are stored in the monitor program, the memory location being 03BC to 03C2. One can call the delay subroutine as shown below:

```
LXI    D, 5000H    Get count = 5000H
CALL   03BC        Call DELAY
```

5000H is a typical count value desired by the programmer. One can take any count value in between 0000-FFFF as required. If the required delay is of a few milliseconds the delay subroutine given in monitor's program may be called. For greater delay one can write his own delay subroutine as discussed in subsequent subsections.

RET

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The states for the execution of each instruction of the program are as follows:

Instructions	How many times the instruction is executed	States
MVI B, 10 H	1	7×1
LOOP I MVI C, 78H	16	7×16
LOOP II DCR C	120×16	$4 \times 120 \times 16$
JNZ LOOP II	120×16	$10 \times (120 - 1) \times 16 + 7 \times 16$
DCR B	16	4×16
JNZ LOOP I	16	$10 \times (16 - 1) + 7 \times 1$
RET	1	1×10

$$\begin{aligned}
 \text{Total states} &= 7 \times 1 + 7 \times 16 + 4 \times 120 \times 16 + 10 \times (120 - 1) \times 16 \\
 &\quad + 7 \times 16 + 4 \times 16 + 10 \times (16 - 1) + 7 \times 1 + 10 \times 1 \\
 &= 7 + 112 + 7680 + 19040 + 112 + 64 + 150 + 7 + 10 \\
 &= 27182 \text{ states}
 \end{aligned}$$

$$\text{Delay time} = 27182 \times 320 \times 10^{-9} \text{ second} = 8.6912 \text{ milliseconds.}$$

To get maximum delay using two registers both registers B and C are loaded by FF.
Total number of states for the maximum delay is

$$\begin{aligned}
 &7 \times 1 + 7 \times 255 + 4 \times 255 \times 255 + 10 \times (255 - 1) \times 255 + 7 \times 255 \\
 &\quad + 4 \times 255 + 10 \times (255 - 1) + 7 \times 1 + 10 \times 1 \\
 &= 7 + 1785 + 260100 + 647700 + 1785 + 1020 + 2540 + 7 + 10 \\
 &= 914954 \text{ states.}
 \end{aligned}$$

$$\begin{aligned}
 \text{Delay time} &= 914954 \times 320 \times 10^{-9} \text{ second} \\
 &= 0.29278528 \text{ second.} \\
 &= 0.293 \text{ second (approximately).}
 \end{aligned}$$

The approximate delay time is calculated as follows:

States for instructions in the program are: