Weekly report of lessons

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The topics covered:

Determine optimal K for clustering: Cluster Validity Indices, External indices, Internal indices, Stability check based clustering, Wang's method of cross-validation; Generalizing K-Means: mixture densities: Mixture of Gaussians; Expectation-Maximization (EM) Algorithm: Parameter re-estimation; Hierarchical clustering: Hierarchical clustering algorithm, distance between a pair of clusters; Graph-based approaches: Clique Graphs, Transforming into Clique Graphs, Distance Graphs, Corrupted Cliques Problem, Parallel Classification with Cores (PCC): Algorithm, Time Complexity; Cluster Affinity Search Technique (CAST): Algorithm; DBSCAN

Summary topic wise:

Determine optimal K: By maximizing or minimizing cluster validity index depending upon the nature of metric, or by checking stable clustering results with random initialization.

<u>Cluster Validity Indices:</u> Finds optimal K.

- External indices when reference partitioning information is given.
 Methods Normalized Mutual Interface (NMI), FM Index, Set matching measures.
 NMI = 2I(Y;C)/(H(Y) + H(C)), where H is entropy, Y is cluster label, C is class label and I(Y;C) = H(Y) H(Y|C)
- <u>Internal indices</u> from variance distribution and structure of clusters.

 Methods Silhouette index: average of (a-b)/max(a,b), where a is average intra-cluster distance and b is average nearest cluster distance.

Calinski-Harabasz (CH) Index: $CH(K) = \frac{(J(1)-J(K))/(K-1)}{J(K)/(n-K)}$; J(i) is SSE (K=i), K is no. of clusters

<u>Stability check based clustering:</u> For appropriate K, similar partitioning is seen for repeated clustering. <u>Wang's method of cross-validation:</u> Input data is permuted c times and each time, data is divided into S_1 , S_2 and S_3 such that $|S_1|=|S_2|=m$. K-means is performed on S_1 and S_2 and tested on S_3 . Average of number of disagreements is computed for c observations, and such K is chosen which minimizes this average.

Generalizing K-Means: mixture densities: $P(x) = \sum_{i=1}^{K} P(x|G_i)P(G_i)$, where G_i represents ith cluster and K is number of components (hyperparameter). For multivariate Gaussian distribution, $P(x|G_i) \sim N(\mu_i, \Sigma_i)$

<u>Mixture of Gaussians:</u> The cluster centers are augmented by covariance matrix and their values are re-estimated from corresponding samples.

Mahalanobis distance $d(x, \mu_k; \Sigma_k) = (x - \mu_k)^T \Sigma_k^{-1} (x - \mu_k); \mu_k -> \text{cluster center}, \Sigma_k -> \text{covariance matrix}$

Parametric pdf $p(x|\{\pi_k, \mu_k, \Sigma_k\}) = \sum_k \pi_k N(x \mid \mu_k, \Sigma_k)$, where π_k is mixing coefficients

<u>Expectation-Maximization Algorithm:</u> Used to find local maximum likelihood parameters iteratively. The E and M steps are integrated till convergence. E-Step: Each x is assigned to cluster whose probability of belongingness for x is maximum. M-Step: Re-estimate parameters from class distribution.

<u>Parameter re-estimation:</u> $z_{ik} = \frac{1}{z_i} \pi_k N(x \mid \mu_k, \Sigma_k)$, Expected no. of pixels in class $k N_k = \Sigma_i z_{ik}$

$$\mu_k = \frac{1}{N_k} \Sigma_i z_{ik} x_i, \qquad \Sigma_k = \frac{1}{N_k} \Sigma_i z_{ik} (x_i - \mu_k) (x_i - \mu_k)^T, \quad \pi_k = \frac{N_k}{N}$$

<u>Hierarchical clustering</u>: A nonprobabilistic approach to build hierarchy of groups from data similarities using distance matrix among the samples.

<u>Hierarchical clustering algorithm:</u> Start with a separate cluster for each element. Iteratively identify a pair of clusters closest together and merge two most similar clusters until all the clusters are merged together.

<u>Graph-based approaches:</u> Connected components, cliques, etc are computed by forming graphs from the given input data

<u>Clique Graphs:</u> Here, each connected component is a clique. A clique has every vertex is connected to every other vertex.

<u>Transforming into Clique Graphs:</u> Add/remove some edges in a graph to transform into a clique graph. For minimum such operations, use Corrupted Cliques Problem.

<u>Distance Graphs:</u> If the distance between two vertices is below a chosen distance threshold θ , an edge is added between them.

Corrupted Cliques Problem: NP-hard problem. Approximate methods: PCC and CAST

<u>Parallel Classification with Cores (PCC):</u> Let $\{C_1, C_2, ..., C_k\}$ be clustering on subset S' of S, $j \in S$ -S' and $N(j,C_i)$ be no. of edges from j to C_i . Assign j to cluster with max affinity. Affinity $(j,C_i) = N(j,C_i)/|C_i|$ <u>Algorithm for PCC:</u> PCC(S, G, k)

S -> set of n elements forming vertices of G, G -> distance graph and k -> no. of clusters.

Randomly select subsets S' and S'' from S and S-S' such that $|S'| = \log(\log(n))$ and $|S''| = \log(n)$. For all k partitions in S', get extended partitions in S through S' -> S'' -> (S - (S' U S'')), and choose the one with a minimum score to get the required Clique graph.

Time Complexity for PCC: $O(n^2 (\log n)^{\log_2 k})$

Cluster Affinity Search Technique (CAST): It is based on the distance of a feature i from a cluster C. The cluster is close if distance d(i, C) is less than the distance threshold θ .

d(i, C) = avg distance between feature i and all other features in C

CAST Algorithm: CAST(S, G, θ)

S -> set of elements, G -> distance graph, θ -> distance threshold

Get a cluster C corresponding to maximal degree vertex in G. For each close feature not in C or distant feature in C, add the nearest close feature i not in C and remove the farthest distant feature in C. Add C to partition P and remove its vertices from G. Repeat until S is empty and return P.

DBSCAN: Density-based spatial clustering of applications with noise

It is a non-parametric algorithm that groups together core samples of high-density points that are closely packed with many nearby neighbors and expand clusters from them. It works well for data that contains clusters of similar density.

Concepts challenging to comprehend:

None

Interesting and exciting concepts:

I found Corrupted Cliques Problem interesting as it was totally new to me and also an NP-hard problem. The two approximation methods were astute for finding a solution to the NP problem.

Concepts not understood:

None

Any novel idea of yours out of the lessons:

The Hierarchical Clustering algorithm provides better clustering results than the K-means algorithm and is easy to implement. But this algorithm seems to involve a lot of arbitrary decisions if the training set has mixed data types or the dataset is large. It might also make a wrong merging choice at an initial stage which can't be undone and hence give a poor outcome in the end. So, there is a need for an even better method for unsupervised learning. An approach could be that instead of finding clusters according to arbitrary distance, we can use a probabilistic model that describes the distribution of the dataset, and the data points are assigned to a cluster based on maximum likelihood estimation.
