## Chapter 2: Divide and Conquer

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Design and Analysis of Algorithms IIT Jammu, Jammu

Introduction

2 The Merge-sort Algorithm

Merge-sort Applications

• Divide-and-conquer basic paradigm

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#### Motivation

#### DC algorithms often

- have lesser running times
- their running time can be determined by the standard tech to solve recurrences.

### Obvious sorting applications

- List files in a directory.
- Organize an MP3/MPEG library.
- List names in a phone book.
- Display Google PageRank results.

#### Not so obvious sorting applications

- Data compression.
- Computer graphics.
- Interval scheduling.
- Computational biology.
- Minimum spanning tree.
- Supply chain management.
- Simulate a system of particles.
- Book recommendations on Amazon.
- Load balancing on a parallel computer

### The problem becomes easier if sorting applied

• Find the median.

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- Find the closest pair.

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- Binary search in a database.

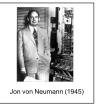
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- Find the closest pair.
- Binary search in a database.
- Identify statistical outliers.

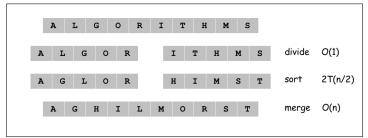
- Find the median.
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- Binary search in a database.
- Identify statistical outliers.
- Find duplicates in a mailing list.

### Merge Sort: The Basic Logic

### Overall Logic

• Divide array into two halves.



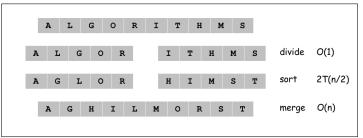


## Merge Sort: The Basic Logic

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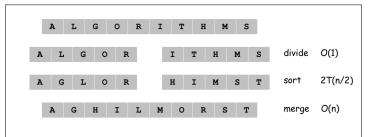


### Merge Sort: The Basic Logic

### Overall Logic

- Divide array into two halves.
- Recursively sort each half.
- Merge two halves to make sorted whole.



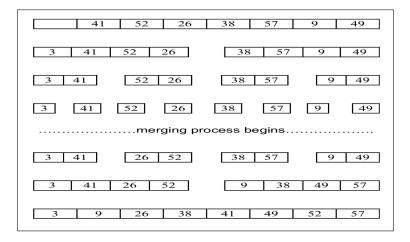


## The Conquer Logic: Merging

### Merging. Combine two pre-sorted lists into a sorted whole.

- How to merge efficiently?
- Linear number of comparisons.
- Use temporary array.
- The Challenge: In-place merge. [Kronrud, 1969]
- The Demo of Merge

## Viewing Merge-sort in execution



### The Merge-sort pseudocode

```
The Algorithm Merge-sort (A,p, r) 
1 if (p < r) 
2 then q \leftarrow \lfloor (p+r)/2 \rfloor 
3 MERGE-SORT (A, p, q) 
4 MERGE-SORT (A, q+1, r) 
5 MERGE(A, p, q, r)
```

### The Merge procedure

```
Algorithm MERGE (A, p, q, r)
        let i = p and j = q+1 and k = 1
2
        while (i \le q) and (j \le r)
3
                 do if A[i] \leq A[j]
4
                          then B[k] = A[i]
5
                                  i = i + 1, k = k + 1
6
7
                          else B[k] = A[i]
                                  i = i + 1, k = k + 1
   here one f the subarrays is in B
8
        if i > q then
9
        for index = i to r
10
                 do B[k] = A[index]
                         k - k + 1
11
                 else for index = i to a
12
13
                 do B[k] = A[index]
                         k = k + 1
14
15
        for index = p to r
                 do A[index] = B[index]
16
17
        return
```

## The Merge Demo

Run the Demo MergeDemoFromPPT.mp4

• MERGE does 3n-1+1 comparisons i.e. time taken is  $\theta(n)$  time . a constant

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- MERGE-SORT is a recursive procedure i.e. a recurrence relation is to be framed.
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  - expresses the resources used by the recursive procedures

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#### C(n) - time to combine into solutions

 $\theta(1)$  - time to solve the atomic subproblems - for small inputs such that n < c for some c.



• Then, the recurrence relation can be expressed as follows:

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#### T(n)

- $= \theta(1)$  for  $n \le c$  for some c.
- = aT(n/b) + D(n) + C(n)..... otherwise. recurrence relation using boundary conditions and without it

#### The Merge-sort recurrence relation

T(n) = number of comparisons to mergesort an input of size
 n.

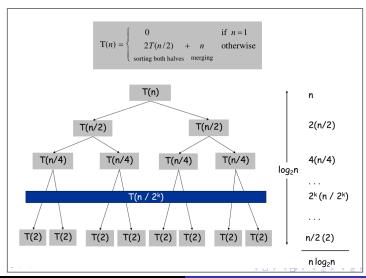
$$T(n) \leq \begin{cases} 0 & \text{if } n=1 \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + n & \text{otherwise} \\ \text{solve left half} & \text{solve right half} & \text{merging} \end{cases}$$

Figure: Mergesort Recurrence Relation

- Guess solution  $T(n) = O(n \lg n)$
- We now show number of ways to prove this result



## Solving the recurrence: The Recursion Tree method



## Solving the recurrence: By iterative substitution

$$T(n) = \begin{cases} 0 & \text{if } n = 1\\ 2T(n/2) + n & \text{otherwise} \\ \text{sorting both halves} & \text{merging} \end{cases}$$

Claim: If T(n) satisfies this recurrence, then  $T(n)=n\ log_2\ n$  - assuming n is a power of 2

Proof: ... ... ... ... ... ... ... ...

# Solving the recurrence: Proof by telescoping

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# Solving the recurrence : Proof by Mathematical Induction

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Claim: If T(n) satisfies this recurrence, then  $T(n) = n \log_2 n$  - assuming n is a power of 2

- Base case: n = 1.
- Inductive hypothesis:  $T(n) = n \lg n$ .
- Goal: show that  $T(2n) = 2n \lg (2n)$ .

Proof : ... ... ... ...

... ... ... ...

#### Analysis of the Merge-sort recurrence

• What if n is not assumed to be a power of 2?

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#### Proof by induction on n

- Base case: n = 1.
- Define  $n_1 = \lfloor n/2 \rfloor$  ,  $n_2 = \lceil n/2 \rceil$
- Induction step: assume true for 1, 2, ..., n1.
- Proof: ... ... ...

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## Counting Inversion: Motivation

#### Collaborative Flitering

- A number of websites use collaborative filtering to "identify" people with similar taste and then push the related contents to the entire collection.
- The meta-search engines execute the same query on many different search engines and then try to synthesize the results by looking for similarities.

There are many such other applications where *finding similarity* is required. What could be the metric ?

• how to measure how similar are two peoples rankings

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- Find the items *out of order*

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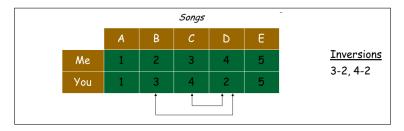
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- Songs i and j inverted if i < j, but  $a_i > a_j$ .
- Suppose your ranking of five songs is 5,4,3,2,1 and mine is in ascending order. How many are out of order?

## Counting the items out of order



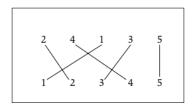


Figure: Similarity metric:Inversion:number of inversions between two rankings.

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- there can be a quadratic number of inversions.
- However, we need faster algorithms.....
- Asymptotically faster algorithm must compute total number without even looking at each inversion individually.

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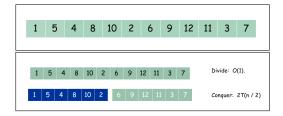
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- Nonparametric statistics (e.g., Kendall's Tau distance).

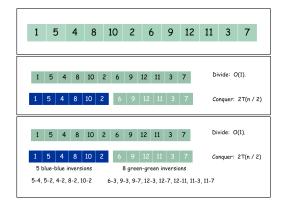
# Counting Inversions : Logic

1 5 4 8 10 2 6 9 12 11 3 7

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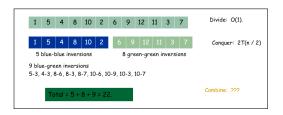


# Counting Inversions: Logic



# Counting Inversions: Divide and Conquer

- Divide: separate list into two pieces.
- Conquer: recursively count inversions in each half.
- Combine: count inversions where  $a_i$  and  $a_j$  are in different halves, and return sum of three quantities. Complexity ??

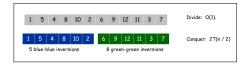


# Dry running Merge-and-count(A,B)

Given the two sorted subhalves A and B

- Combine: count blue-green inversions
- Assume each half is sorted.
- Count inversions where ai and aj are in different halves.
- Merge two sorted halves into sorted whole.

Apply the logic to the given two subhalves as below

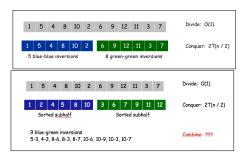


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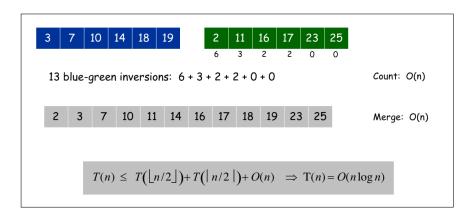
# Counting Inversions pseudocode: MergeandCount(A,B)

```
Algorithm Merge-and-count (A, B)
Maintain a Current pointer into each list,
                initialized to point to the front elements
Maintain a variable Count for the number of inversions,
                initialized to O
While both lists are empty {
        Let a_i and b_i be the elements pointed to
                by the Current pointer
        Append the smaller of these two to the output list
        If b_i < a_i then
                increment Count by the number of
                         elements remaining in A
                Advance the Current pointer in the list from
                         which the smaller element
                         was selected.
```

#### The Merge-Invert Demo

Run the Demo MergeInvertFromPPT

#### Complexity



# Counting Inversion: Implementation

```
Algorithm Sort—and—Count(L):
\ Pre-condition: [Merge-and-Count] A and B are sorted.
\\ Post-condition. [Sort-and-Count] L is sorted.
1.
         if list L has one element
2.
                  return O and the list L
3.
         Divide the list into two halves A and B
4.
         (r_A, A) \leftarrow Sort-and-Count(A)
5.
         (r_B, B) \leftarrow Sort-and-Count(B)
         (r_B, L) \leftarrow Merge-and-Count(A, B)
6.
7.
         return r = r_A + r_B + r and the sorted list L
```

#### Mergesort Applications: Closest Pairs of Points

#### Closest pair

Given n points in the plane, find a pair with smallest Euclidean distance between them.

What is the Euclidean distance between points  $p_1(x_1, y_1)$  and  $p_2(x_2, y_2)$  ?

#### Closest Pairs of Points: Applications

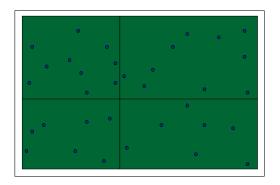
- Fundamental geometric primitive in
  - graphics, pattern recognition
  - computer vision, image processing, VLSI design
  - geographic information systems,
  - molecular modeling,
  - air traffic control.
  - Special case of nearest neighbor, Euclidean MST, Voronoi.

#### Finding Closest Pairs..: Approaches

- Brute force: What will be the time for a brute force approach ?
- How would it work ?
- 1-D version....What is a 1-D version?
- Approach..
  - Divide into two parts and compute within each.
  - O(n log n) easy if points are on a line.
  - Assumption: No two points have different x coordinate.
- What do learn from this exercise ?

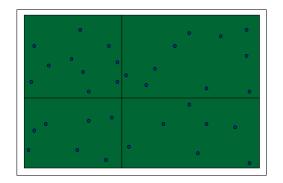
#### Closest Pairs...First attempt

• Divide. Sub-divide region into 4 quadrants.



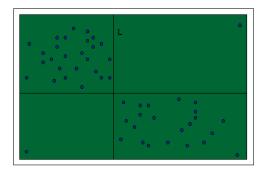
## Closest Pairs...First attempt

- Divide. Sub-divide region into 4 quadrants.
- What is the obstacle in this case ?

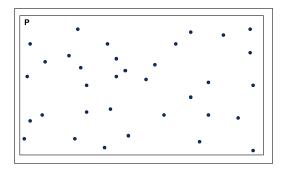


# Closest Pairs...First attempt...

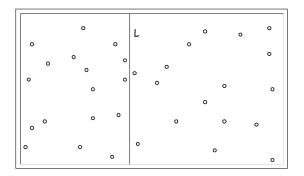
• The obstacle



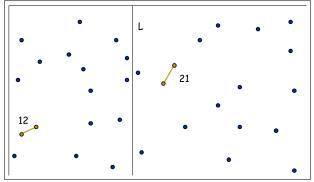
• Suppose we are given a sample point set P as shown below:



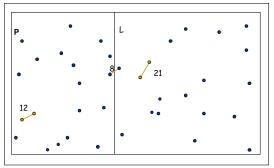
- Suppose we are given a sample point set P as shown below:
- Divide: Draw a vertical line L so that roughly (1/2)n points are there on each side.



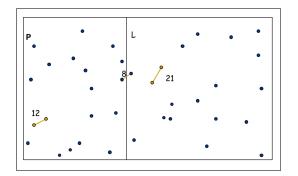
- Divide: Draw a vertical line L so that roughly (1/2)n points are there on each side.
- Conquer: Find the closest pair in each side recursively.
- What is the partial recurrence relation ?



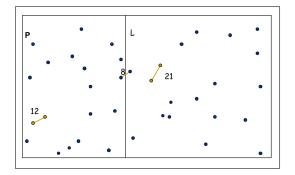
- Divide: Draw a vertical line L so that roughly (1/2)n points are there on each side.
- Conquer: Find the closest pair in each side recursively.
- Combine: Find closest pair with one point in each side.
- Return the best of 3 solutions.



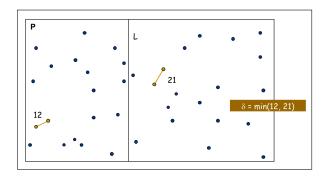
• How does the recurrence relation now take shape ?



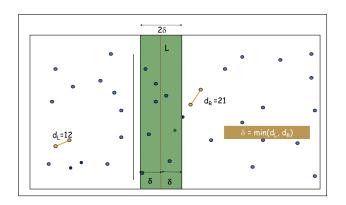
• What is the time required for combining ?



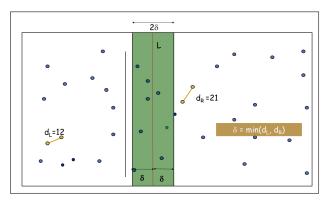
• Find closest pair with one point in each side, assuming that distance  $< \delta$  i.e.  $\delta = \min(d_L, d_R)$ 



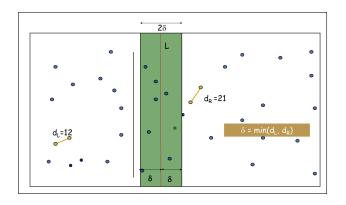
• What is the primary observation and inference ?



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- How many points could be there in this strip?



• Then, how to compute the distance  $min(\delta(dL, dR)), dC)$  ?



• Then, how to compute the distance  $min(\delta(d_L, d_R)), d_C)$ ?

```
Algorithm ComputeMin()

1. for i = 1 to Num_points_in_the_strip

2 for j = (i+1) to Num_points_in_the_strip

3. if (dist(P_i, P_j) < \delta)

4. \delta = dist(P_i, P_j)
```

#### Not efficient

- With all the points located in the strip, the complexity is  $\theta(n^2)$
- Thus, there is a need to improve upon this approach

#### Two approaches

- We assume that with n points in the entire plane, there are only  $O(n^{0.5})$  points in the strip on an average..
- We can do a brute force on the points lying in the strip.
- What will be the time taken by this approach for brute force then?
- What will be the total run time?
- But, then is it possible ?? Can it be assumed in the worst case ?

 Improved approach: Sort the points in the strip based on their y coordintaes....

```
Algorithm ComputeMinImproved()

1. for i = 1 to Num_points_in_the_strip

2. for j = (i+1) to Num_points_in_the_strip

3. if (P_i \text{ and } P_j \text{ 's y coordinates differ by more than } \delta)

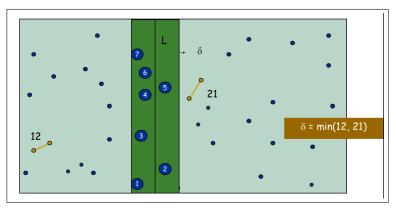
4. break; //Go to the next P

5. else

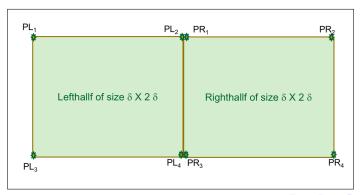
6. if (dist(P_i, P_j) < \delta)

7. \delta = dist(P_i, P_i)
```

- ullet only need to consider points within  $\delta$  of line L.
- Sort points in  $2\delta$ -strip by their y coordinate.



- ullet only need to consider points within  $\delta$  of line L.
- Sort points in  $2\delta$ -strip by their y coordinate.
- How many points to be considered in the worst case ?



- Let  $s_i$  be the point in the  $2\delta$ -strip, with the i\_th smallest y-coordinate.
- Claim. If  $|i-j| \ge 7$ , then the distance between the distinct points  $s_i$  and  $s_j$  is at least  $\delta$
- Proof.

#### Proof

Proof to be worked out.

	δ/2	δ/2	δ/2	δ/2	
δ/2					
δ/2					

#### Time for computing $d_C$

Because only seven points are considered for each pi, the time for computing  $d_C$  that is better than  $\delta$  is O(n).

Thus, we appear to have a  $O(n \log n)$  solution to the closest pairs of points problem.

#### Closest Pairs algorithm

```
Algorithm ClosestPair(p1, , pn)

1. Compute separation line L such that half the points

are on one side and half on the
```

- 2.  $\delta_1 = \mathsf{Closest} \mathsf{Pair}(\mathsf{left} \; \mathsf{half})$
- 3.  $\delta_2 = \text{Closest-Pair(right half)}$
- 4.  $\delta = \min(\delta_1, \delta_2)$
- 5. Delete all points further than  $\delta$  from separation line L
- 6. Sort remaining points by y-coordinate.
- 7. Scan points in y-order and compare distance between each point and next 11 neighbors. If any of these distances is less than  $\delta$ , update  $\delta$ .
- 8. return  $\delta$ .

#### Algorithm Closest Pairs

Running time

$$\mathsf{T}(n) \leq 2T \big( n/2 \big) + \mathit{O}(n \log n) \ \, \Rightarrow \, \mathsf{T}(n) \, = \, \mathit{O}(n \log^2 n)$$

#### Algorithm Closest Pairs

- Can we achieve O(n log n)?
- Yes. Don't sort points in strip from scratch each time.
- Each recursive returns two lists: all points sorted by y coordinate, and all points sorted by x coordinate.
- Sort by merging two pre-sorted lists

$$T(n) \le 2T(n/2) + O(n) \implies T(n) = O(n \log n)$$