Linear Algebra

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Linear Transformation

A Useful Observation about Linear Transformations

Proposition 26

Let V be a finite dimensional vector space of dimension n and let $\{v_1, \ldots, v_n\}$ be a basis of V.

- ⓐ A linear transformation $T:V\longrightarrow W$ is completely determined by its action on a basis of V.
- Oconversely, given a list of n vectors w_1, \ldots, w_n (not necessarily distinct) in the co-domain space W, there is a unique linear transformation T s. t. $T(v_1) = w_1, T(v_2) = w_2, \ldots, T(v_n) = w_n$.

Proof of 26 (a): If $\{v_1, \ldots, v_n\}$ is a basis of V, then T is completely determined by the n vectors $w_1 = T(v_1), w_2 = T(v_2), \ldots, w_n = T(v_n)$. For if $v \in V$, then $v = c_1v_1 + \cdots + c_nv_n$ for some scalars c_i , and so

$$T(v) = T(c_1v_1 + c_2v_2 + \cdots + c_nv_n) = c_1T(v_1) + c_2T(v_2) + \cdots + c_nT(v_n)$$

:= $c_1w_1 + c_2w_2 + \cdots + c_nw_n$.

Note that the vectors w_1, \ldots, w_n need not be distinct,

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Proposition 26 (b): Conversely, given a list of n vectors w_1, \ldots, w_n (not necessarily distinct) in the co-domain space W, there is a unique linear transformation T such that $T(v_1) = w_1, T(v_2) = w_2, \ldots, T(v_n) = w_n$.

Proof: Let $B = \{v_1, \dots, v_n\}$ be a basis of V, and let w_1, \dots, w_n be a list of n vectors in W, not necessarily distinct.

Existence:

Let v be any vector in V. Then, v can be uniquely expressed as $v=c_1v_1+\cdots+c_nv_n$, where $c_i's$ are scalars. Now, we define a map $T:V\longrightarrow W$ as follows:

$$T(v) = T(c_1v_1 + \cdots + c_nv_n) = c_1w_1 + \cdots + c_nw_n.$$
 (1)

Since $v_i = 0v_1 + \cdots + 0v_{i-1} + 1.v_i + 0v_{i+1} + \cdots + 0v_n$, therefore by the definition (1) of the map, we have

$$T(v_i) = w_i$$
 for all the vectors $v_i \in B$ (2)

Proof of Proposition 26 (b) (Cont'd)

It is easy to see that T is a well-defined function. We need to show that T is actually a linear transformation i.e. we need to prove that T satisfies additivity and homogeneity properties.

Additivity: Suppose $u = d_1v_1 + \cdots + d_nv_n$ and $v = e_1v_1 + \cdots + e_nv_n$ are any two vectors of V. Then

$$T(u+v) = T((d_1v_1 + \dots + d_nv_n) + (e_1v_1 + \dots + e_nv_n))$$

$$= T((d_1 + e_1)v_1 + \dots + (d_n + e_n)v_n)$$

$$= (d_1 + e_1)w_1 + \dots + (d_n + e_n)w_n, \text{ by the def } (1)$$

$$= (d_1w_1 + \dots + d_nw_n) + (e_1w_1 + \dots + e_nw_n)$$

$$= T(u) + T(v), \text{ again by the def } (1).$$

Momogeneity: For any scalar c,

$$T(cu) = T(c(d_1v_1 + \dots + d_nv_n)) = T(cd_1v_1 + \dots + cd_nv_n)$$

= $cd_1w_1 + \dots + cd_nw_n$, by the def (1)
= $c(d_1w_1 + \dots + d_nw_n) = cT(u)$, again by the def (1).

Proof of Proposition 26 (b) (Cont'd)

Uniqueness: Finally, we need to prove uniqueness. Suppose there exists another linear transformation $\bar{T}:V\longrightarrow W$ such that $\bar{T}(v_i)=w_i$ for all $v_i\in B$. Let $v=c_1v_1+\cdots+c_nv_n$ be any vector in V. Then

$$ar{\mathcal{T}}(v) = c_1 \, ar{\mathcal{T}}(v_1) + \dots + c_n \, ar{\mathcal{T}}(v_n)$$
 by Remark (ii)
$$= c_1 w_1 + \dots + c_n w_n$$
$$= \mathcal{T}(v)$$

Since $T(v) = \overline{T}(v)$ for all $v \in V$, it follows that $T = \overline{T}$, proving uniqueness.