

Linear Algebra and Applications

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Lecture 01

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Course Information

- **Instructor: Sartaj UI Hasan**

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- **Course Webpage:**

<https://sites.google.com/site/sartajulhasan/csd001p5m>

- **Evaluation:**

- Tests: 40 % [two tests each 20%]
- Med-semester: 20 %
- End-semester: 40 %

Course Information (Cont ...)

- **Gradescope:** A paperless grading system. Use the course code 9X2B5Y to register in the course on Gradescope. Use only your IIT Jammu email address to register on Gradescope.
- **Reference Books:**
 - Linear Algebra and Its Applications, 3rd (Indian Edition), Pearson by David C Lay
 - Matrix Computations, John Hopkins University Press by Golub and Loan
 - Matrix Analysis and Applied Liner Algebra, SIAM by Carl. D. Meyer
 - Linear Algebra and Its Applications, 4th Edn, Cengange by G. Strang
- **Policy on cheating:** As per rules and regulations of the institute.
- **Policy on attendance:** As per rules and regulations of the institute.

System of Linear Equations

- A system of equations of the form:

$$\begin{aligned}a_{11}X_1 + a_{12}X_2 + \cdots + a_{1n}X_n &= b_1 \\a_{21}X_1 + a_{22}X_2 + \cdots + a_{2n}X_n &= b_2 \\&\vdots \\a_{m1}X_1 + a_{m2}X_2 + \cdots + a_{mn}X_n &= b_m\end{aligned}\tag{1}$$

where the unknowns a_{ij} and b_i are scalars and the X_j are “unknown” variables is called a **system of m linear equations in n unknowns**.

- Any (ordered) n -tuple (s_1, s_2, \dots, s_n) of scalars which satisfies all of the equations is called a **solution** of the system. The set of all solutions is called the **solution set** of the system.

Matrix Formulation

- A system of linear equations can be more compactly expressed in matrix notation as: $AX = b$, where $A = [a_{ij}]$ is called coefficient matrix, and

$$X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} \quad \text{and} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} \quad \text{are vectors.}$$

- Recall that a vector is an ordered k -tuple of scalars. Vectors are represented in various ways: (X_1, X_2, \dots, X_n) or $[X_1, X_2, \dots, X_n]$ (referred to as a row vector)

$$X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} \quad (\text{referred to as column vector}).$$