

# **Develop the Campus Navigation and Utility Planner**

## **Theme: Trees and Graph Algorithms**

### **GitHub:**

[https://github.com/mayank24000/University\\_Assignments/tree/main/Ds\\_%20Assignments/Lab\\_Assignments/Lab\\_Assignment\\_4](https://github.com/mayank24000/University_Assignments/tree/main/Ds_%20Assignments/Lab_Assignments/Lab_Assignment_4)

### **Code:**

```
#include <iostream>
#include <string>
#include <vector>
#include <queue>
#include <stack>
#include <algorithm>
#include <climits>
#include <iomanip>

using namespace std;

class Building {
public:
    int buildingID;
    string buildingName;
    string locationDetails;
```

```
Building() {
    buildingID = 0;
    buildingName = "";
    locationDetails = "";
}

Building(int id, string name, string location) {
    buildingID = id;
    buildingName = name;
    locationDetails = location;
}

void display() {
    cout << "ID: " << buildingID
        << ", Name: " << buildingName
        << ", Location: " << locationDetails << endl;
}

// ====== BINARY SEARCH TREE =====

class BSTNode {
public:
    Building data;
    BSTNode* left;
    BSTNode* right;

    BSTNode(Building building) {
```

```

        data = building;
        left = nullptr;
        right = nullptr;
    }

};

class BinarySearchTree {
private:
    BSTNode* root;

    // Helper function for insertion
    BSTNode* insertHelper(BSTNode* node, Building building) {
        if (node == nullptr) {
            return new BSTNode(building);
        }

        if (building.buildingID < node->data.buildingID) {
            node->left = insertHelper(node->left, building);
        } else if (building.buildingID > node->data.buildingID) {
            node->right = insertHelper(node->right, building);
        }
    }

    return node;
}

// Helper functions for traversals
void inorderHelper(BSTNode* node) {
    if (node != nullptr) {
        inorderHelper(node->left);

```

```

        node->data.display();
        inorderHelper(node->right);
    }

}

void preorderHelper(BSTNode* node) {
    if (node != nullptr) {
        node->data.display();
        preorderHelper(node->left);
        preorderHelper(node->right);
    }
}

void postorderHelper(BSTNode* node) {
    if (node != nullptr) {
        postorderHelper(node->left);
        postorderHelper(node->right);
        node->data.display();
    }
}

// Helper function for search
BSTNode* searchHelper(BSTNode* node, int id) {
    if (node == nullptr || node->data.buildingID == id) {
        return node;
    }

    if (id < node->data.buildingID) {
        return searchHelper(node->left, id);
    }
}

```

```
    }

    return searchHelper(node->right, id);
}

public:

BinarySearchTree() {

    root = nullptr;
}

void insertBuilding(Building building) {

    root = insertHelper(root, building);

    cout << "Building inserted successfully in BST!" << endl;
}

void inorderTraversal() {

    cout << "\n--- Inorder Traversal (Sorted by ID) ---" <<
endl;

    inorderHelper(root);
}

void preorderTraversal() {

    cout << "\n--- Preorder Traversal ---" << endl;

    preorderHelper(root);
}

void postorderTraversal() {

    cout << "\n--- Postorder Traversal ---" << endl;

    postorderHelper(root);
}
```

```
}

Building* searchBuilding(int id) {
    BSTNode* result = searchHelper(root, id);
    if (result != nullptr) {
        return &(result->data);
    }
    return nullptr;
}
};
```

```
// ===== AVL TREE =====
```

```
class AVLNode {
public:
    Building data;
    AVLNode* left;
    AVLNode* right;
    int height;

AVLNode(Building building) {
    data = building;
    left = nullptr;
    right = nullptr;
    height = 1;
}
};
```

```
class AVLTree {
```

```
private:
```

```
    AVLNode* root;
```

```
    int getHeight(AVLNode* node) {  
        if (node == nullptr) return 0;  
        return node->height;  
    }
```

```
    int getBalance(AVLNode* node) {  
        if (node == nullptr) return 0;  
        return getHeight(node->left) - getHeight(node->right);  
    }
```

```
    AVLNode* rotateRight(AVLNode* y) {  
        AVLNode* x = y->left;  
        AVLNode* T2 = x->right;  
  
        x->right = y;  
        y->left = T2;
```

```
        y->height = max(getHeight(y->left), getHeight(y->right)) +  
1;  
        x->height = max(getHeight(x->left), getHeight(x->right)) +  
1;
```

```
        return x;  
    }
```

```
    AVLNode* rotateLeft(AVLNode* x) {
```

```

AVLNode* y = x->right;
AVLNode* T2 = y->left;

y->left = x;
x->right = T2;

x->height = max(getHeight(x->left), getHeight(x->right)) +
1;
y->height = max(getHeight(y->left), getHeight(y->right)) +
1;

return y;
}

AVLNode* insertHelper(AVLNode* node, Building building) {
    // Standard BST insertion
    if (node == nullptr) {
        return new AVLNode(building);
    }

    if (building.buildingID < node->data.buildingID) {
        node->left = insertHelper(node->left, building);
    } else if (building.buildingID > node->data.buildingID) {
        node->right = insertHelper(node->right, building);
    } else {
        return node; // Duplicate keys not allowed
    }

    // Update height

```

```

        node->height = 1 + max(getHeight(node->left),
getHeight(node->right));

        // Get balance factor
        int balance = getBalance(node);

        // Left Left Case
        if (balance > 1 && building.buildingID < node->left-
>data.buildingID) {
            return rotateRight(node);
        }

        // Right Right Case
        if (balance < -1 && building.buildingID > node->right-
>data.buildingID) {
            return rotateLeft(node);
        }

        // Left Right Case
        if (balance > 1 && building.buildingID > node->left-
>data.buildingID) {
            node->left = rotateLeft(node->left);
            return rotateRight(node);
        }

        // Right Left Case
        if (balance < -1 && building.buildingID < node->right-
>data.buildingID) {
            node->right = rotateRight(node->right);
            return rotateLeft(node);
        }
    }
}
```

```
    }

    return node;
}

void inorderHelper(AVLNode* node) {
    if (node != nullptr) {
        inorderHelper(node->left);
        node->data.display();
        inorderHelper(node->right);
    }
}

public:
AVLTree() {
    root = nullptr;
}

void insertBuilding(Building building) {
    root = insertHelper(root, building);
    cout << "Building inserted successfully in AVL Tree!" <<
endl;
}

void displayInorder() {
    cout << "\n--- AVL Tree Inorder Traversal ---" << endl;
    inorderHelper(root);
}
};
```

```
// ===== GRAPH REPRESENTATION =====

class Graph {
private:
    int numBuildings;
    vector<vector<int>> adjacencyMatrix;
    vector<vector<pair<int, int>>> adjacencyList; // pair<destination, weight>
    vector<Building> buildings;

public:
    Graph(int n) {
        numBuildings = n;
        adjacencyMatrix.resize(n, vector<int>(n, 0));
        adjacencyList.resize(n);
    }

    void addBuilding(Building building) {
        if (buildings.size() < numBuildings) {
            buildings.push_back(building);
        }
    }

    void addEdge(int src, int dest, int weight) {
        // For adjacency matrix
        adjacencyMatrix[src][dest] = weight;
        adjacencyMatrix[dest][src] = weight; // Undirected graph
    }
}
```

```

// For adjacency list
adjacencyList[src].push_back({dest, weight});
adjacencyList[dest].push_back({src, weight}); // Undirected
graph
}

void displayAdjacencyMatrix() {
    cout << "\n--- Adjacency Matrix ---" << endl;
    cout << "      ";
    for (int i = 0; i < numBuildings; i++) {
        cout << setw(4) << i;
    }
    cout << endl;

    for (int i = 0; i < numBuildings; i++) {
        cout << setw(4) << i;
        for (int j = 0; j < numBuildings; j++) {
            cout << setw(4) << adjacencyMatrix[i][j];
        }
        cout << endl;
    }
}

void displayAdjacencyList() {
    cout << "\n--- Adjacency List ---" << endl;
    for (int i = 0; i < numBuildings; i++) {
        cout << "Building " << i << ":" ;
        for (auto& edge : adjacencyList[i]) {

```

```

        cout << "(" << edge.first << ", " << edge.second <<
") ";
    }

    cout << endl;
}

}

// Dijkstra's Algorithm for shortest path
void dijkstra(int start, int end) {

    vector<int> distance(numBuildings, INT_MAX);

    vector<int> parent(numBuildings, -1);

    vector<bool> visited(numBuildings, false);

    distance[start] = 0;

    for (int count = 0; count < numBuildings - 1; count++) {

        int minDist = INT_MAX, minIndex;

        for (int v = 0; v < numBuildings; v++) {

            if (!visited[v] && distance[v] <= minDist) {

                minDist = distance[v];

                minIndex = v;
            }
        }

        visited[minIndex] = true;

        for (int v = 0; v < numBuildings; v++) {
            if (!visited[v] && adjacencyMatrix[minIndex][v] &&

```

```

        distance[minIndex] != INT_MAX &&
        distance[minIndex] +
adjacencyMatrix[minIndex][v] < distance[v]) {

            distance[v] = distance[minIndex] +
adjacencyMatrix[minIndex][v];
            parent[v] = minIndex;
        }
    }

}

cout << "\n--- Shortest Path from Building " << start << "
to Building " << end << " ---" << endl;

if (distance[end] == INT_MAX) {

    cout << "No path exists!" << endl;
    return;
}

cout << "Distance: " << distance[end] << " units" << endl;
cout << "Path: ";

// Reconstruct path
vector<int> path;
int curr = end;
while (curr != -1) {

    path.push_back(curr);
    curr = parent[curr];
}

reverse(path.begin(), path.end());
for (int i = 0; i < path.size(); i++) {

```

```

        cout << path[i];
        if (i < path.size() - 1) cout << " -> ";
    }
    cout << endl;
}

// Edge structure for Kruskal's algorithm
struct Edge {

    int src, dest, weight;

    bool operator<(const Edge& other) const {
        return weight < other.weight;
    }
};

// Find operation for Union-Find
int find(vector<int>& parent, int i) {
    if (parent[i] != i) {
        parent[i] = find(parent, parent[i]);
    }
    return parent[i];
}

// Union operation for Union-Find
void unionSet(vector<int>& parent, vector<int>& rank, int x, int y) {
    int xroot = find(parent, x);
    int yroot = find(parent, y);

    if (rank[xroot] < rank[yroot]) {

```

```

        parent[xroot] = yroot;
    } else if (rank[xroot] > rank[yroot]) {
        parent[yroot] = xroot;
    } else {
        parent[yroot] = xroot;
        rank[xroot]++;
    }
}

// Kruskal's Algorithm for Minimum Spanning Tree
void kruskal() {
    vector<Edge> edges;

    // Collect all edges
    for (int i = 0; i < numBuildings; i++) {
        for (int j = i + 1; j < numBuildings; j++) {
            if (adjacencyMatrix[i][j] != 0) {
                edges.push_back({i, j, adjacencyMatrix[i][j]});
            }
        }
    }

    // Sort edges by weight
    sort(edges.begin(), edges.end());

    vector<int> parent(numBuildings);
    vector<int> rank(numBuildings, 0);
    for (int i = 0; i < numBuildings; i++) {
        parent[i] = i;
    }
}

```

```

    }

    cout << "\n--- Minimum Spanning Tree (Cable Layout) ---" <<
endl;

    int totalCost = 0;
    int edgesAdded = 0;

    for (const Edge& e : edges) {
        int x = find(parent, e.src);
        int y = find(parent, e.dest);

        if (x != y) {
            cout << "Connect Building " << e.src << " to
Building "
                << e.dest << " (Cost: " << e.weight << ")" <<
endl;

            totalCost += e.weight;
            unionSet(parent, rank, x, y);
            edgesAdded++;
        }

        if (edgesAdded == numBuildings - 1) break;
    }

    cout << "Total Cable Cost: " << totalCost << " units" <<
endl;
}
};

// ===== EXPRESSION TREE =====

```

```
class ExprNode {  
public:  
    string value;  
    ExprNode* left;  
    ExprNode* right;  
  
    ExprNode(string val) {  
        value = val;  
        left = nullptr;  
        right = nullptr;  
    }  
};  
  
class ExpressionTree {  
private:  
    ExprNode* root;  
  
    bool isOperator(string s) {  
        return (s == "+" || s == "-" || s == "*" || s == "/");  
    }  
  
    double evaluate(ExprNode* node) {  
        if (node == nullptr) return 0;  
  
        // Leaf node (operand)  
        if (node->left == nullptr && node->right == nullptr) {  
            return stod(node->value);  
        }  
    }  
};
```

```
// Evaluate left and right subtrees
double leftVal = evaluate(node->left);
double rightVal = evaluate(node->right);

// Apply operator
if (node->value == "+") return leftVal + rightVal;
if (node->value == "-") return leftVal - rightVal;
if (node->value == "*") return leftVal * rightVal;
if (node->value == "/") return leftVal / rightVal;

return 0;
}

void inorderHelper(ExprNode* node) {
    if (node != nullptr) {
        if (isOperator(node->value)) cout << "(";
        inorderHelper(node->left);
        cout << node->value << " ";
        inorderHelper(node->right);
        if (isOperator(node->value)) cout << ")";
    }
}

public:
    ExpressionTree() {
        root = nullptr;
    }
}
```

```
// Build expression tree from postfix expression
void buildFromPostfix(vector<string> postfix) {
    stack<ExprNode*> st;

    for (string token : postfix) {
        ExprNode* newNode = new ExprNode(token);

        if (isOperator(token)) {
            newNode->right = st.top(); st.pop();
            newNode->left = st.top(); st.pop();

        }

        st.push(newNode);
    }

    root = st.top();
}

double evaluateExpression() {
    return evaluate(root);
}

void displayInfix() {
    cout << "Infix Expression: ";
    inorderHelper(root);
    cout << endl;
}

};
```

```
// ===== CAMPUS NAVIGATION SYSTEM
=====

class CampusNavigationSystem {
private:
    BinarySearchTree bst;
    AVLTree avl;
    Graph* campusGraph;
    ExpressionTree exprTree;
    int buildingCount;

public:
    CampusNavigationSystem() {
        campusGraph = nullptr;
        buildingCount = 0;
    }

    void addBuildingRecord() {
        int id;
        string name, location;

        cout << "\nEnter Building ID: ";
        cin >> id;
        cin.ignore();

        cout << "Enter Building Name: ";
        getline(cin, name);

        cout << "Enter Location Details: ";
```

```
getline(cin, location);

Building newBuilding(id, name, location);

bst.insertBuilding(newBuilding);
avl.insertBuilding(newBuilding);

if (campusGraph != nullptr) {
    campusGraph->addBuilding(newBuilding);
}

buildingCount++;

}

void listCampusLocations() {

    cout << "\n--- Tree Traversal Options ---" << endl;
    cout << "1. Inorder Traversal (BST)" << endl;
    cout << "2. Preorder Traversal (BST)" << endl;
    cout << "3. Postorder Traversal (BST)" << endl;
    cout << "4. AVL Tree Inorder Traversal" << endl;
    cout << "Enter choice: ";

    int choice;
    cin >> choice;

    switch (choice) {
        case 1:
            bst.inorderTraversal();
            break;
    }
}
```

```
        case 2:
            bst.preorderTraversal();
            break;
        case 3:
            bst.postorderTraversal();
            break;
        case 4:
            avl.displayInorder();
            break;
        default:
            cout << "Invalid choice!" << endl;
    }
}

void constructCampusGraph() {
    int n, edges;

    cout << "\nEnter number of buildings in graph: ";
    cin >> n;

    campusGraph = new Graph(n);

    cout << "Enter number of paths (edges): ";
    cin >> edges;

    cout << "Enter paths (source destination weight):" << endl;
    for (int i = 0; i < edges; i++) {
        int src, dest, weight;
        cin >> src >> dest >> weight;
    }
}
```

```
    campusGraph->addEdge(src, dest, weight);

}

cout << "Campus graph constructed successfully!" << endl;

}

void displayGraph() {
    if (campusGraph == nullptr) {
        cout << "Please construct the campus graph first!" <<
endl;
        return;
    }

    cout << "\n--- Graph Display Options ---" << endl;
    cout << "1. Adjacency Matrix" << endl;
    cout << "2. Adjacency List" << endl;
    cout << "Enter choice: ";

    int choice;
    cin >> choice;

    switch (choice) {
        case 1:
            campusGraph->displayAdjacencyMatrix();
            break;
        case 2:
            campusGraph->displayAdjacencyList();
            break;
        default:
```

```
        cout << "Invalid choice!" << endl;
    }
}

void findOptimalPath() {
    if (campusGraph == nullptr) {
        cout << "Please construct the campus graph first!" <<
endl;
        return;
    }

    int start, end;
    cout << "\nEnter start building ID: ";
    cin >> start;
    cout << "Enter destination building ID: ";
    cin >> end;

    campusGraph->dijkstra(start, end);
}

void planUtilityLayout() {
    if (campusGraph == nullptr) {
        cout << "Please construct the campus graph first!" <<
endl;
        return;
    }

    campusGraph->kruskal();
}
```

```
void calculateEnergyBill() {  
    cout << "\n--- Energy Bill Calculator ---" << endl;  
    cout << "Enter expression in postfix notation" << endl;  
    cout << "Example: For (10 + 5) * 2, enter: 10 5 + 2 *" <<  
    endl;  
    cout << "Enter number of tokens: ";  
  
    int n;  
    cin >> n;  
  
    vector<string> postfix(n);  
    cout << "Enter tokens separated by space: ";  
    for (int i = 0; i < n; i++) {  
        cin >> postfix[i];  
    }  
  
    exprTree.buildFromPostfix(postfix);  
  
    exprTree.displayInfix();  
    cout << "Result: " << exprTree.evaluateExpression() << endl;  
}  
  
void searchBuilding() {  
    int id;  
    cout << "\nEnter Building ID to search: ";  
    cin >> id;  
  
    Building* result = bst.searchBuilding(id);
```

```
    if (result != nullptr) {
        cout << "Building found in BST:" << endl;
        result->display();
    } else {
        cout << "Building not found!" << endl;
    }
}

void addSampleData() {
    // Add sample buildings
    bst.insertBuilding(Building(1, "Main Library", "Central Campus"));
    bst.insertBuilding(Building(2, "Engineering Block", "North Campus"));
    bst.insertBuilding(Building(3, "Science Lab", "East Campus"));
    bst.insertBuilding(Building(4, "Admin Building", "Central Campus"));
    bst.insertBuilding(Building(5, "Cafeteria", "South Campus"));

    avl.insertBuilding(Building(1, "Main Library", "Central Campus"));
    avl.insertBuilding(Building(2, "Engineering Block", "North Campus"));
    avl.insertBuilding(Building(3, "Science Lab", "East Campus"));
    avl.insertBuilding(Building(4, "Admin Building", "Central Campus"));
    avl.insertBuilding(Building(5, "Cafeteria", "South Campus"));
}
```

```

        // Create sample graph
        campusGraph = new Graph(5);
        campusGraph->addEdge(0, 1, 10);
        campusGraph->addEdge(0, 3, 5);
        campusGraph->addEdge(1, 2, 8);
        campusGraph->addEdge(1, 3, 2);
        campusGraph->addEdge(2, 4, 6);
        campusGraph->addEdge(3, 4, 15);

        cout << "Sample data added successfully!" << endl;
    }

};

int main() {
    CampusNavigationSystem system;
    int choice;

    cout << "===== CAMPUS NAVIGATION AND UTILITY PLANNER =====" <<
endl;

    while (true) {
        cout << "\n--- Main Menu ---" << endl;
        cout << "1. Add Building Record" << endl;
        cout << "2. List Campus Locations (Tree Traversals)" <<
endl;
        cout << "3. Search Building" << endl;
        cout << "4. Construct Campus Graph" << endl;
        cout << "5. Display Graph" << endl;
        cout << "6. Find Optimal Path (Dijkstra's)" << endl;
    }
}

```

```
cout << "7. Plan Utility Layout (Kruskal's MST)" << endl;
cout << "8. Calculate Energy Bill (Expression Tree)" <<
endl;
cout << "9. Add Sample Data" << endl;
cout << "10. Exit" << endl;
cout << "Enter your choice: ";
cin >> choice;

switch (choice) {
    case 1:
        system.addBuildingRecord();
        break;
    case 2:
        system.listCampusLocations();
        break;
    case 3:
        system.searchBuilding();
        break;
    case 4:
        system.constructCampusGraph();
        break;
    case 5:
        system.displayGraph();
        break;
    case 6:
        system.findOptimalPath();
        break;
    case 7:
        system.planUtilityLayout();
```

```
        break;

    case 8:
        system.calculateEnergyBill();
        break;

    case 9:
        system.addSampleData();
        break;

    case 10:
        cout << "Thank you for using Campus Navigation
System!" << endl;
        return 0;

    default:
        cout << "Invalid choice! Please try again." << endl;
    }

}

return 0;
}
```

## OUTPUT:

```
===== CAMPUS NAVIGATION AND UTILITY PLANNER =====
```

```
--- Main Menu ---
```

1. Add Building Record
2. List Campus Locations (Tree Traversals)
3. Search Building
4. Construct Campus Graph
5. Display Graph
6. Find Optimal Path (Dijkstra's)
7. Plan Utility Layout (Kruskal's MST)
8. Calculate Energy Bill (Expression Tree)
9. Add Sample Data
10. Exit

```
Enter your choice: 1
```

```
Enter Building ID: 001
```

```
Enter Building Name: A Block
```

```
Enter Location Details: Centre
```

```
Building inserted successfully in BST!
```

```
Building inserted successfully in AVL Tree!
```

```
--- Main Menu ---
```

1. Add Building Record
2. List Campus Locations (Tree Traversals)
3. Search Building
4. Construct Campus Graph
5. Display Graph
6. Find Optimal Path (Dijkstra's)
7. Plan Utility Layout (Kruskal's MST)
8. Calculate Energy Bill (Expression Tree)