



Recurrent neural network



Deep learning

ANN



CNN



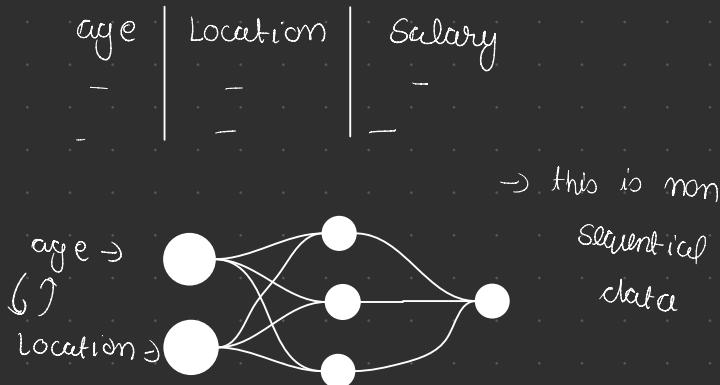
RNN

RNN

Recurrent neural network

This RNN works on sequential data and creates a sequential model.

Sequential Data



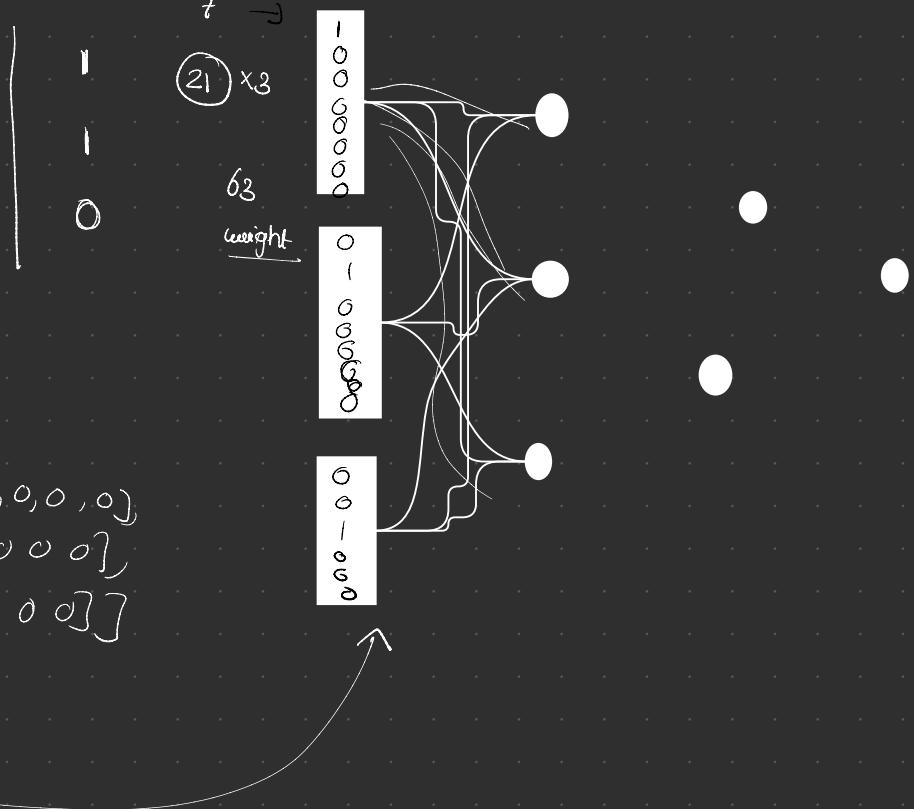
Text

→ hello subscribe to SAS

when we have textual data we will use
sequential model or RNN

Why use RNN instead of ANN

- 1) → (I love sherylans)
- 2) → Sherylans provide quality content
- 3) → I hate sherylans



OHE

Vocabulary size → [7 words]

Sentence 1 →
[1, 0, 0, 0, 0, 0, 0]
[0, 1, 0, 0, 0, 0, 0]
[0, 0, 1, 0, 0, 0, 0]

Sentence 2 → []
[]
[]

- ① Text input size may vary
- ② Computational Power
- ③ Prediction Problem \Rightarrow Input \rightarrow Testing Input
- ④ Semantic meaning - Sequence is not retained

RNN Architecture

→ Data feeding

comments	sentiment
[you, are, good]	1
You are Bad	0
you are not good	0

vocabulary = 5

Timestamp = ③

Input features = ⑤

you are good

[1,0,0,0,0] [0,1,000], [0,0,1,00]

Bad not

[0,0,0,1,0] [0,0,0,0,1]

first review

[[1,0,0,0,0], [0,1,000], [0,0,1,00]]

Keras \Rightarrow (batchsize, timestamp, input features)

(3, 4, 6)

→ RNN Architecture

comments	sentiment
[you, are, good]	1
You are Bad	0
you are not good	0

vocabulary = 5

you are good

[1,0,0,0,0] [0,1,000], [0,0,1,00]

Bad not

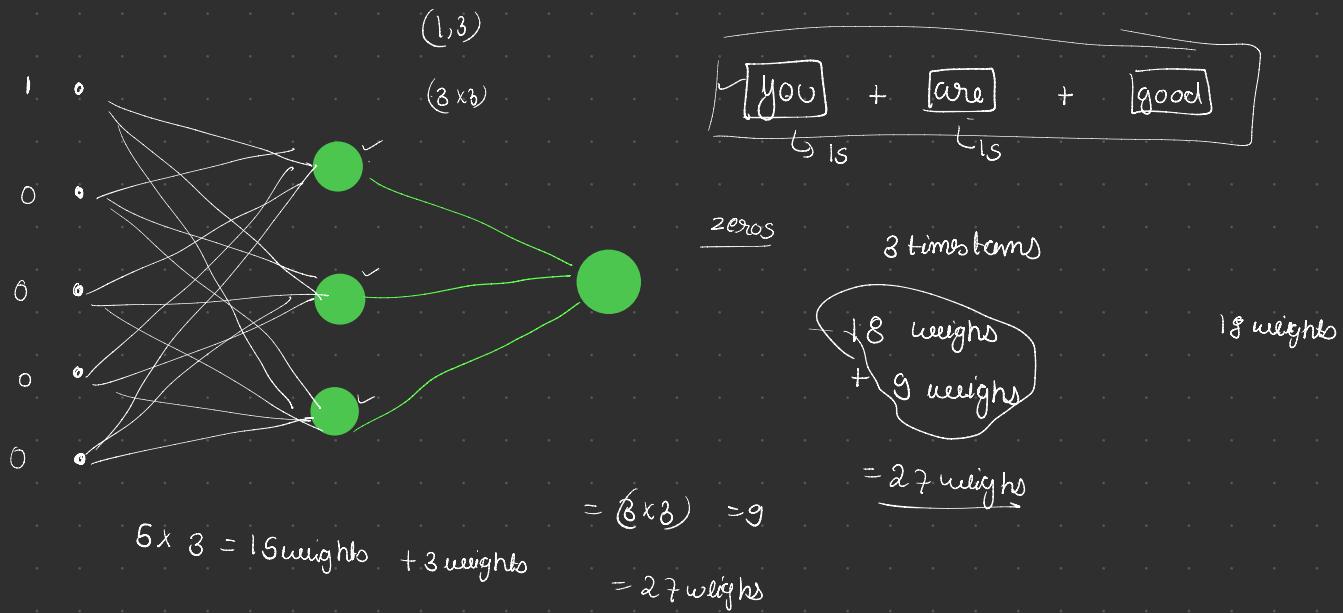
[0,0,0,1,0] [0,0,0,0,1]



Feed forward Network



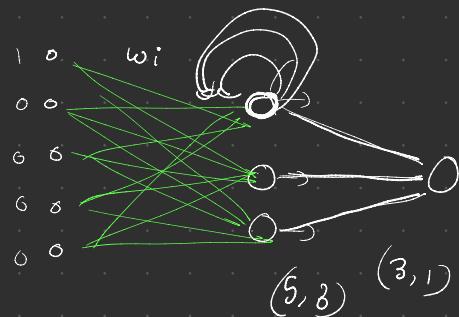
Feed back Network
Recurrent



you $\boxed{\text{are}}$ good

$$T=1 \quad \underline{y_{00}} \rightarrow [1, 0, 0, 0, 0]$$

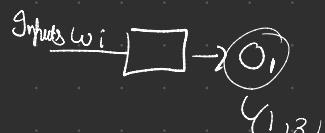
$\hookrightarrow (1, 5)$



Recurrent neural network have an activation function inside their hidden node default (tanh)

$$\theta(w_i \cdot x + w_i + b_i)$$

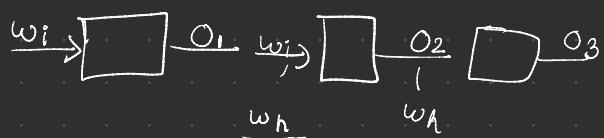
$$(1, 5) \times (5, 3) = (1, 3)$$



$$T_2$$

are

$\hookrightarrow [0, 1, 0, 0, 0]$



$$\theta((w_{\text{are}(i)} \times w_i) + (w_h O_i) + b)$$

$$(1, 5) \times (5, 3) + [(3, 3) + 1, 3] + b$$

$$(1, 3) + (1, 3) \rightarrow (1, 3)$$

$$T_3 \rightarrow f(y_{001} \times w_i) + (w_h O_2) + b$$

good

$$\Rightarrow (1, 3)$$

$$(1, 3) (3, 1)$$

$$\approx (1, 1) \rightarrow$$

Backpropagation

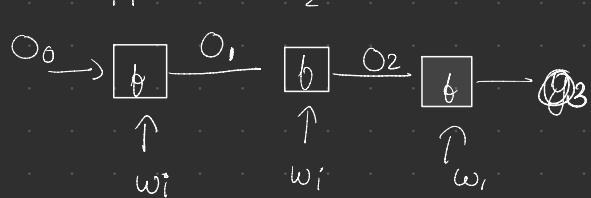
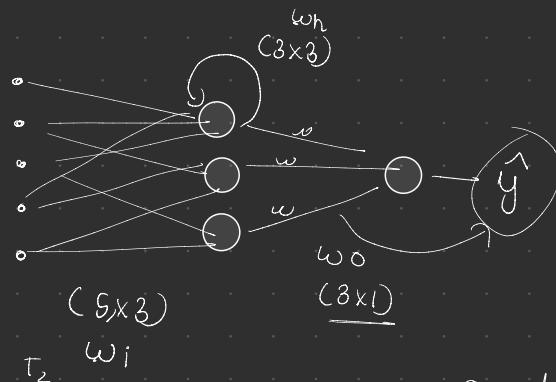
BPTT \rightarrow Backpropagation through time

text

Sheryians	coding	School	<u>1</u>
Sheryian	AI	School	<u>1</u>
Sheryians	cyber	School	<u>0</u>

[10000] [01000] [00100]
[10000] [00010] [00100]
[10000] [00001] [00100]

[Sheryians coding School AI cyber]



$$O_1 = f(x_{11} \times w_i + O_0 \times w_h) + b$$

$$O_2 = f(x_{12} \times w_i + O_1 \times w_h) + b$$

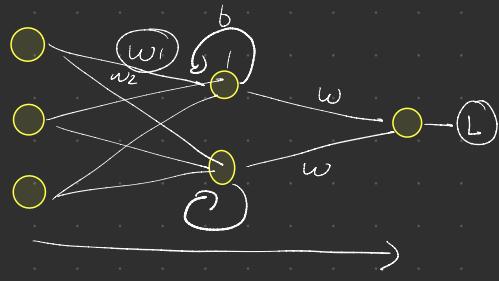
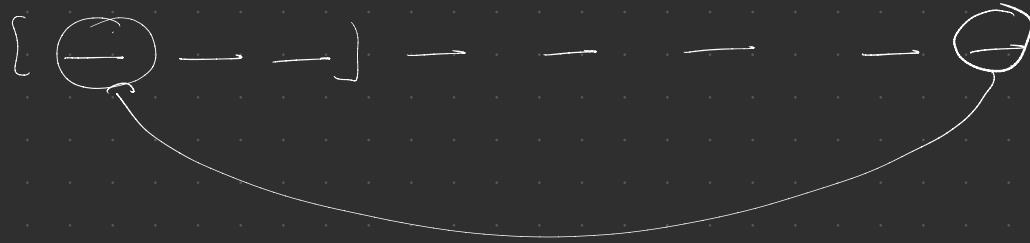
$$O_3 = f(x_{13} \times w_i + O_2 \times w_h) + b$$

$$\hat{y} = \sigma(O_3 \times w_o)$$

$y - \hat{y}$ ← loss function

Problems with RNN

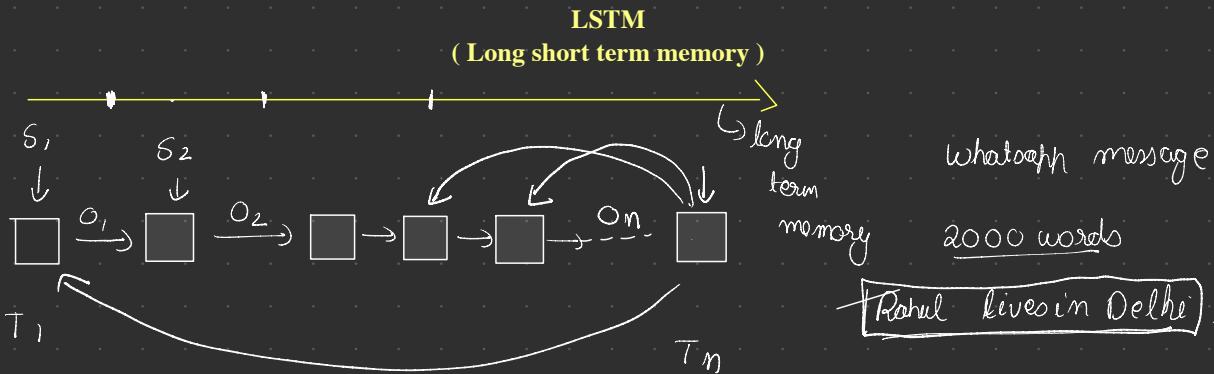
- ① Long term memory is weak.
- ② Vanishing Gradient problem
- ③ Exploding Gradient
- ④ No long dependencies are getting captured
- ⑤ Sequential process is slow.



$$w_{\text{new}} = w_{\text{old}} - \eta \left(\frac{\partial \text{loss}}{\partial w_{\text{old}}} \right)$$

$$\frac{\partial \text{loss}}{\partial w_{\text{old}}} = \underbrace{\frac{\partial \text{loss}}{\partial o_3} \times \frac{\partial o_3}{\partial o_2} \times \frac{\partial o_2}{\partial o_1} \times \frac{\partial o_1}{\partial w_{\text{old}}}}_{\text{gradient flow}}$$

We don't use simple RNNs much today because they forget information very fast and can't handle long sentences or long-term patterns the gradients either vanish or explode. LSTM and GRU were invented to solve exactly this problem. They have special gates that decide what to remember and what to forget, so they can learn long-range dependencies, capture context better, and train more stably. In simple words: **RNN gets confused in long sequences, but LSTM/GRU remember things smartly**, which is why we prefer them now.



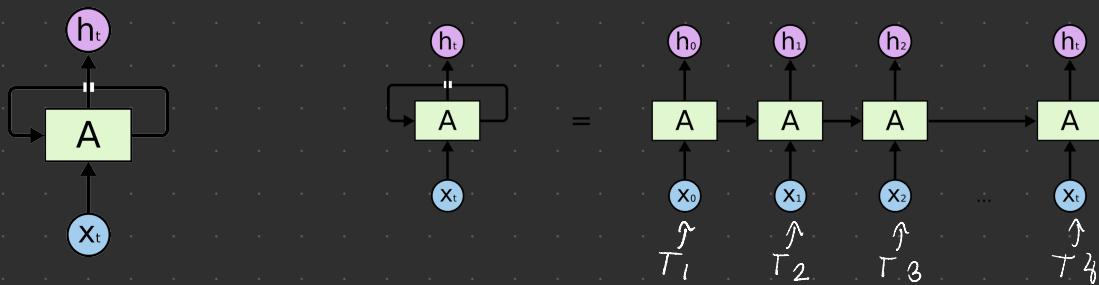
RNNX → (short term memory)

LSTM → long term memory
short term memory

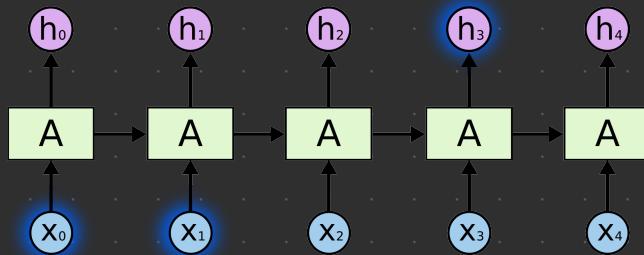
where Rahul lives?

Architecture

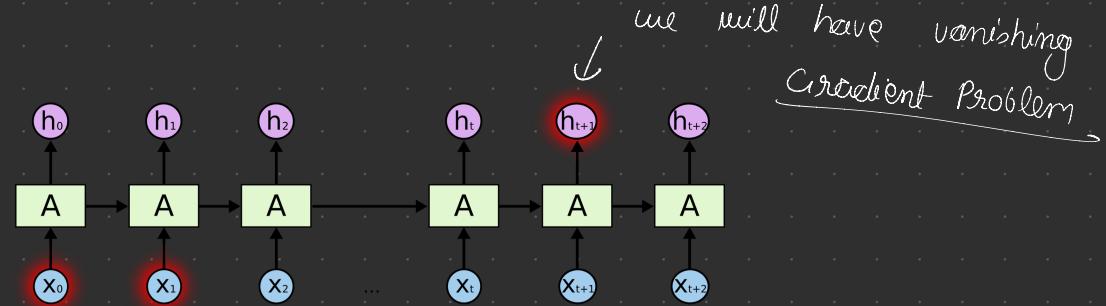
RNN



① The clouds are in the sky,

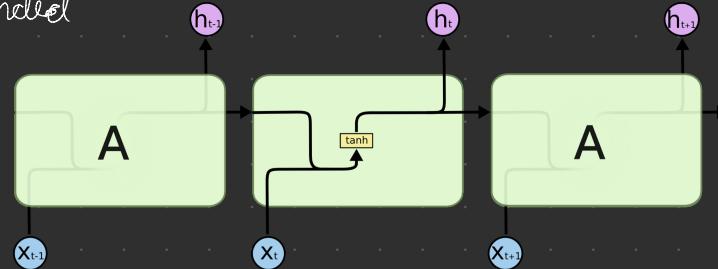


② long sentences -

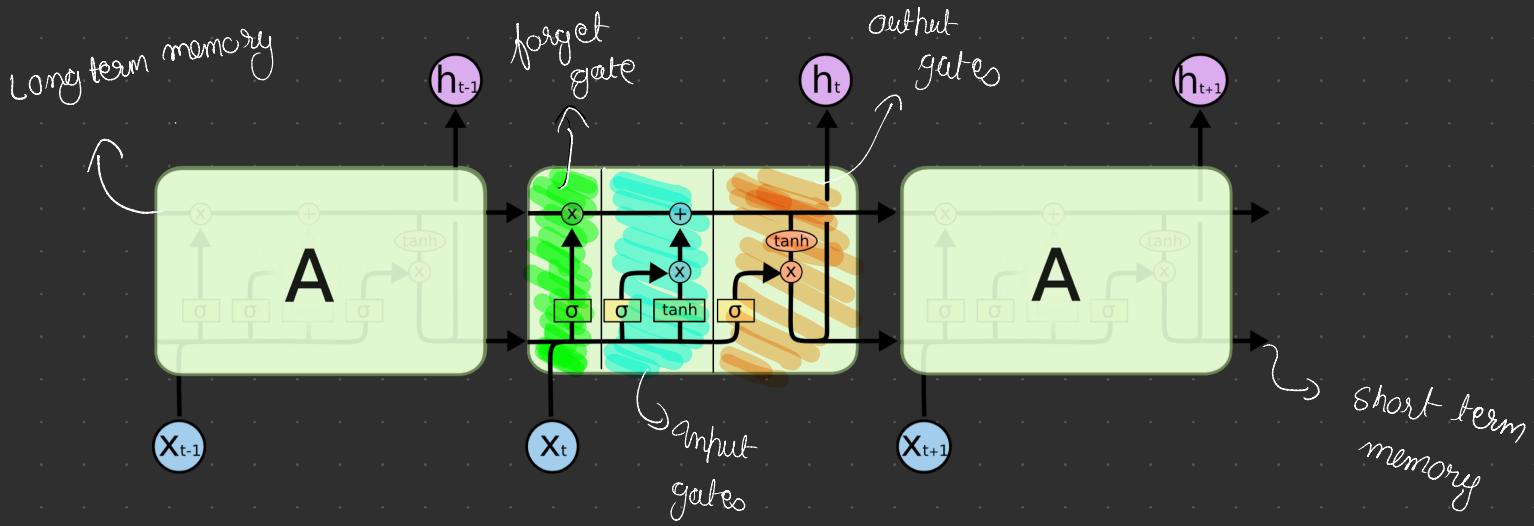


RNN more expanded

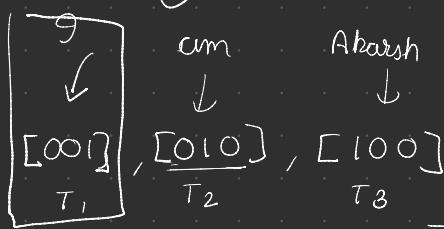
Version



LSTM → Arch,



Understanding Gates



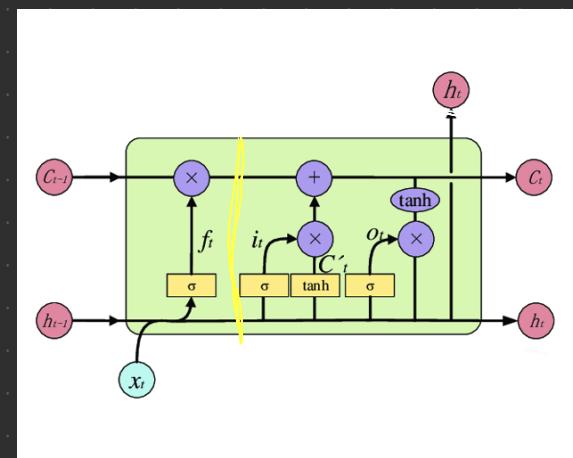
C_{t-1} - Previous cell state \rightarrow long term memory

h_{t-1} \rightarrow Previous hidden state \rightarrow short term memory

x_t \rightarrow Input at t_2

h_t \rightarrow current hidden state

c_t \rightarrow current cell state



T_2

① forget gate.

Riya is a doctor.

She lives in Delhi.

She works at a hospital.

| Last year, Riya moved to London.

Now she works at a research lab

$$f_t = \sigma(W_f [h_{t-1}, x_t] + b_f)$$

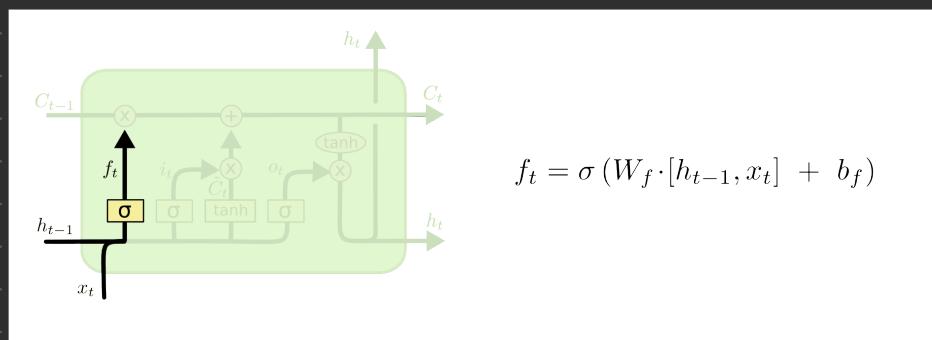
Gender $\rightarrow 0.99$

Profession $\rightarrow 0.95$

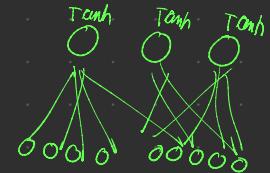
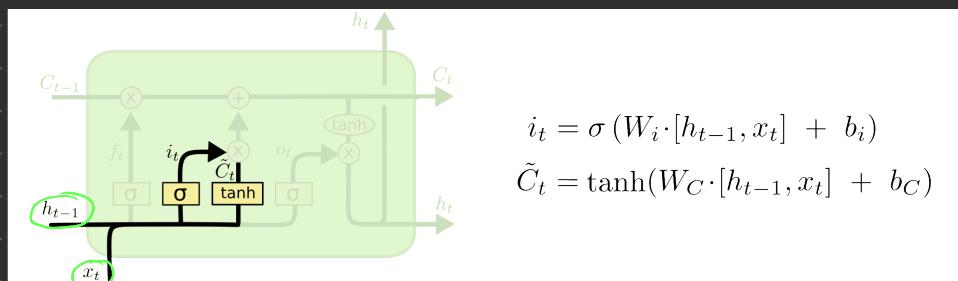
Delhi $\rightarrow 0.10$

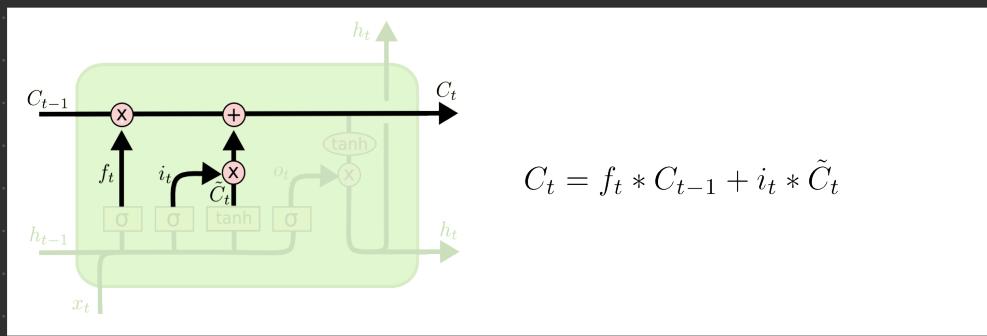
Hospital $\rightarrow 0.85$

London $\rightarrow 0.90$



② Input gate.



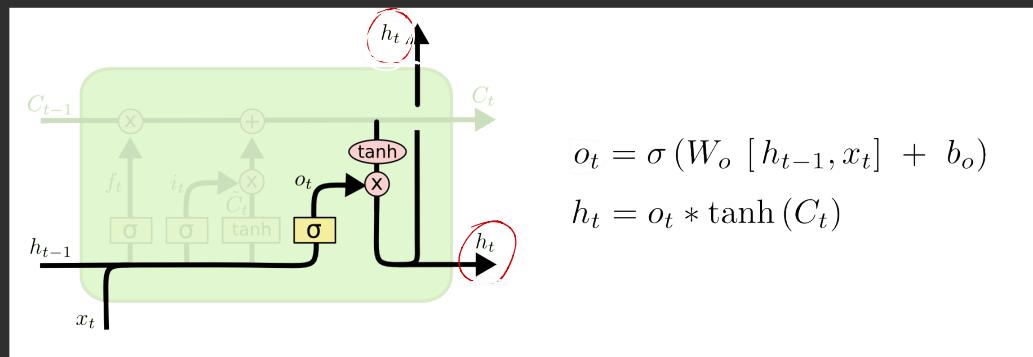


$\tilde{C}_t \rightarrow$ candidate cell state \rightarrow filter out what we should add in cell state.

$i_t \rightarrow$ 2nd filtering

$C_t \rightarrow$ cell state

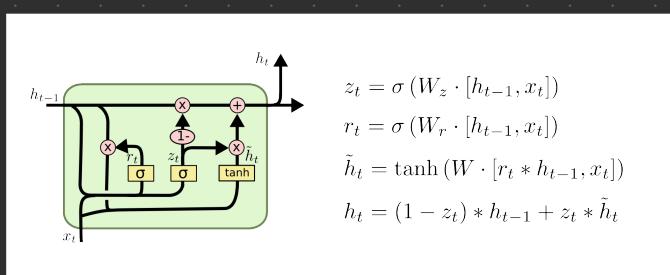
③ output gates.



$[C_t] \rightarrow [h_t] \rightarrow \tanh(C_t) \rightarrow [-1, 1]$

$o_t =$

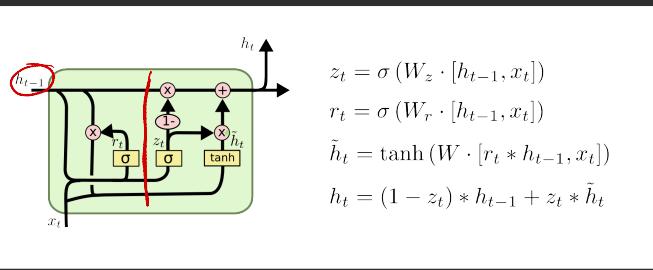
GRU (Gated Recurrent unit)



Problems with LSTM

- ① Complex Architecture
- ② Training Parameters
- ③ time complexity ↑

GRU \rightarrow LSTM had 3 gates GRU has 2 gates



$$z_t = \sigma(W_z \cdot [h_{t-1}, x_t])$$

$$r_t = \sigma(W_r \cdot [h_{t-1}, x_t])$$

$$\tilde{h}_t = \tanh(W \cdot [r_t * h_{t-1}, x_t])$$

$$h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h}_t$$

$[0, 1]$

$\boxed{\sigma}$

- Sigmoid Activation function.

$\boxed{\tanh}$ → tanh Activation function

} neural network layers

$[-1, 1]$

$h_{t-1} \rightarrow$ Previous hidden state

$x_t \rightarrow$ Input current

$h_t \rightarrow$ Current hidden state

$r_t \rightarrow$ Reset gate

$z_t \rightarrow$ Update gate

$\tilde{h}_t \rightarrow$ Candidate hidden state

\times → element wise multiplication

$+$ → element wise addition

\ominus →

$$\times \rightarrow [1, 2, 3], [3, 4, 5]$$

$$= [3, 8, 15]$$

Riya lives in Delhi

Riya moved to London

\downarrow \downarrow \downarrow

T₁

T₂

T₃

$[100] [010] [001]$

$\underline{h_{t-1}} = [0.65, 0.30]$

① $x_t = [100]$ } $[1, 0, 0, 0.65, 0.30]$

②, ③ → Update gate (dog keep the old memory or update it)

$z_t = [0.9, 0.9]$ - high value

(keep the past)

T₃ $\rightarrow [0.1, 0.1] \rightarrow$ low val

(update the past) \rightarrow Delhi $\times \rightarrow$ London

