## SVM (Contd), Multiclass and One-Class SVM

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Introduction to Machine Learning (CS771A)

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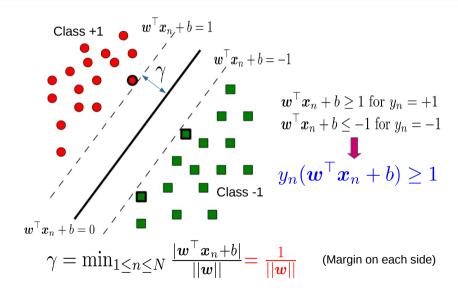
#### **Recap: Hyperplane-based Classification**

• Basic idea: Learn to separate by a hyperplane  $\mathbf{w}^{\top}\mathbf{x} + b = 0$ 



- Predict the label of a test input  $x_*$  as:  $\hat{y}_* = \text{sign}(w^\top x_* + b)$
- The hyperplane may be "implied" by the model, or learned directly
  - Implied: Prototype-based classification, nearest neighbors, generative classification, etc.
  - Directly learned: Logistic regression, Perceptron, Support Vector Machine, etc.
- The "direct" approach defines a model with parameters  $\boldsymbol{w}$  (and optionally b) and learns them by minimizing a suitable loss function (and doesn't model  $\boldsymbol{x}$ , i.e., purely discriminative)
- The hyperplane need not be linear (e.g., can be made nonlinear using kernel methods next class)

## Recap: Hyperplanes and Margin



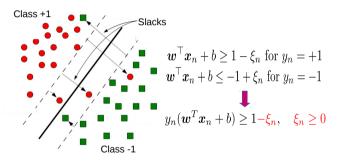


### Recap: Maximum-Margin Hyperplane

$$(\hat{\boldsymbol{w}}, \hat{b}) = \arg\max_{\boldsymbol{w}, b} \frac{2}{||\boldsymbol{w}||}, \quad \text{s.t.} \quad y_n(\boldsymbol{w}^\top \boldsymbol{x}_n + b) \geq 1$$
 
$$(\hat{\boldsymbol{w}}, \hat{b}) = \arg\min_{\boldsymbol{w}, b} \frac{||\boldsymbol{w}||^2}{2}, \quad \text{s.t.} \quad y_n(\boldsymbol{w}^\top \boldsymbol{x}_n + b) \geq 1$$
 Hard-margin SVM ("hard" = want all points to satisfy the margin constraint)

## Recap: Maximum-Margin Hyperplane with Slacks

- Still want a max-margin hyperplane but want to relax the hard constraint  $y_n(\mathbf{w}^{\top}\mathbf{x}_n + b) \geq 1$
- Let's allow every point  $x_n$  to "slack the constraint" by a distance  $\xi_n \geq 0$



- Points with  $\xi_n \ge 0$  will be either in the margin region or totally on the wrong side
- New Objective: Maximize the margin while keeping the sum of slacks  $\sum_{n=1}^{N} \xi_n$  small
- Note: Can also think of the sum of slacks as the total training error



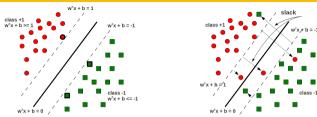
### Recap: Maximum-Margin Hyperplane with Slacks

$$(\hat{\boldsymbol{w}}, \hat{b}, \boldsymbol{\xi}) = \arg\min_{\boldsymbol{w}, b} \frac{||\boldsymbol{w}||^2}{2} + C\sum_{n=1}^{N} \xi_n \text{ Minimize the sum of slacks (don't have too many violations)}}{2}$$
 
$$\mathrm{s.t.} \quad y_n(\boldsymbol{w}^{\top}\boldsymbol{x}_n + b) \geq 1 - \xi_n \quad \text{Slack-relaxed constraints}}$$
 
$$\xi_n \geq 0$$

- This formulation is known as the "soft-margin" SVM
- Very small C: Large margin but also large training error. :-(
- Very large C: Small training error but also small margin. :-(
- C controls the trade-off between large margin and small training error



#### Summary: Hard-Margin SVM vs Soft-Margin SVM



• Objective for the hard-margin SVM (unknowns are  $\boldsymbol{w}$  and b)

$$| \text{arg } \min_{\boldsymbol{w},b} \frac{||\boldsymbol{w}||^2}{2}$$
 subject to  $y_n(\boldsymbol{w}^T\boldsymbol{x}_n + b) \geq 1, \qquad n = 1, \dots, N$ 

ullet Objective for the soft-margin SVM (unknowns are  $oldsymbol{w},b$ , and  $\{\xi_n\}_{n=1}^N)$ 

$$\arg\min_{\mathbf{w},b,\xi} \frac{||\mathbf{w}||^2}{2} + C \sum_{n=1}^{N} \xi_n$$
 subject to  $y_n(\mathbf{w}^T \mathbf{x}_n + b) \ge 1 - \xi_n, \quad \xi_n \ge 0 \quad n = 1, \dots, N$ 

In either case, we have to solve a constrained, convex optimization problem



## Solving SVM Objectives



#### **Solving Hard-Margin SVM**

• The hard-margin SVM optimization problem is:

$$| \arg \min_{\boldsymbol{w},b} \frac{||\boldsymbol{w}||^2}{2}$$
 subject to  $1 - y_n(\boldsymbol{w}^T \boldsymbol{x}_n + b) \le 0, \qquad n = 1, \dots, N$ 

- A constrained optimization problem. Can solve using Lagrange's method
- Introduce Lagrange Multipliers  $\alpha_n$  ( $n = \{1, ..., N\}$ ), one for each constraint, and solve

$$\min_{\mathbf{w},b} \max_{\alpha \geq 0} \mathcal{L}(\mathbf{w},b,\alpha) = \frac{||\mathbf{w}||^2}{2} + \sum_{n=1}^{N} \alpha_n \{1 - y_n(\mathbf{w}^T \mathbf{x}_n + b)\}$$

- Note:  $\alpha = [\alpha_1, \dots, \alpha_N]$  is the vector of Lagrange multipliers
- Note: It is easier (and helpful; we will soon see why) to solve the dual problem: min and then max

## **Solving Hard-Margin SVM**

• The dual problem (min then max) is

$$\max_{\alpha \geq 0} \min_{\mathbf{w}, b} \mathcal{L}(\mathbf{w}, b, \alpha) = \frac{\mathbf{w}^{\top} \mathbf{w}}{2} + \sum_{n=1}^{N} \alpha_n \{1 - y_n(\mathbf{w}^{T} \mathbf{x}_n + b)\}$$

• Take (partial) derivatives of  $\mathcal{L}$  w.r.t.  $\boldsymbol{w}$ , b and set them to zero

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = 0 \Rightarrow \left| \mathbf{w} = \sum_{n=1}^{N} \alpha_n y_n \mathbf{x}_n \right| \quad \frac{\partial \mathcal{L}}{\partial b} = 0 \Rightarrow \sum_{n=1}^{N} \alpha_n y_n = 0$$

- Important: Note the form of the solution  $\boldsymbol{w}$  it is simply a weighted sum of all the training inputs  $\boldsymbol{x}_1, \dots, \boldsymbol{x}_N$  (and  $\alpha_n$  is like the "importance" of  $\boldsymbol{x}_n$ )
- Substituting  $\mathbf{w} = \sum_{n=1}^{N} \alpha_n y_n \mathbf{x}_n$  in Lagrangian, we get the dual problem as (verify)

$$\max_{\alpha \geq 0} \mathcal{L}_D(\alpha) = \sum_{n=1}^N \alpha_n - \frac{1}{2} \sum_{m,n=1}^N \alpha_m \alpha_n y_m y_n (\mathbf{x}_m^\mathsf{T} \mathbf{x}_n)$$



### **Solving Hard-Margin SVM**

• Can write the objective more compactly in vector/matrix form as

$$\max_{\boldsymbol{\alpha} \geq 0} \ \mathcal{L}_D(\boldsymbol{\alpha}) = \boldsymbol{\alpha}^\top \mathbf{1} - \frac{1}{2} \boldsymbol{\alpha}^\top \mathbf{G} \boldsymbol{\alpha}$$

where **G** is an  $N \times N$  matrix with  $G_{mn} = y_m y_n \mathbf{x}_m^{\top} \mathbf{x}_n$ , and **1** is a vector of 1s

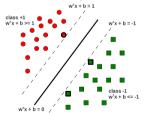
- **Good news:** This is maximizing a concave function (or minimizing a convex function verify that the Hessian is **G**, which is p.s.d.). Note that our original SVM objective was also convex
- Important: Inputs x's only appear as inner products (helps to "kernelize"; more on this later)
- ullet Can solve the above objective function for lpha using various methods, e.g.,
  - Treating the objective as a Quadratic Program (QP) and running some off-the-shelf QP solver such as quadprog (MATLAB), CVXOPT, CPLEX, etc.
  - Using (projected) gradient methods (projection needed because the  $\alpha$ 's are constrained). Gradient methods will usually be much faster than QP methods.
  - Using co-ordinate ascent methods (optimize for one  $\alpha_n$  at a time); often very fast

#### Hard-Margin SVM: The Solution

• Once we have the  $\alpha_n$ 's, **w** and **b** can be computed as:

$$m{w} = \sum_{n=1}^{N} lpha_n y_n m{x}_n$$
 (we already saw this) 
$$b = -\frac{1}{2} \left( \min_{n:y_n = +1} m{w}^T m{x}_n + \max_{n:y_n = -1} m{w}^T m{x}_n \right)$$
 (exercise)

• A nice property: Most  $\alpha_n$ 's in the solution will be zero (sparse solution)



- Reason: Karush-Kuhn-Tucker (KKT) conditions
- For the optimal  $\alpha_n$ 's

$$\alpha_n\{1-y_n(\mathbf{w}^T\mathbf{x}_n+b)\}=0$$

- $\alpha_n$  is non-zero only if  $x_n$  lies on one of the two margin boundaries, i.e., for which  $y_n(w^Tx_n + b) = 1$
- These examples are called support vectors
- Recall the support vectors "support" the margin boundaries





• Recall the soft-margin SVM optimization problem:

$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} f(\boldsymbol{w},b,\boldsymbol{\xi}) = \frac{||\boldsymbol{w}||^2}{2} + C \sum_{n=1}^{N} \xi_n$$
subject to  $1 \le y_n(\boldsymbol{w}^T \boldsymbol{x}_n + b) + \xi_n, \quad -\xi_n \le 0 \quad n = 1,\dots, N$ 

- Note:  $\boldsymbol{\xi} = [\xi_1, \dots, \xi_N]$  is the vector of slack variables
- Introduce Lagrange Multipliers  $\alpha_n, \beta_n$  ( $n = \{1, \dots, N\}$ ), for constraints, and solve the Lagrangian:

$$\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \max_{\alpha \geq 0,\boldsymbol{\beta} \geq 0} \mathcal{L}(\boldsymbol{w},b,\boldsymbol{\xi},\alpha,\boldsymbol{\beta}) = \frac{||\boldsymbol{w}||^2}{2} + C\sum_{n=1}^{N} \xi_n + \sum_{n=1}^{N} \alpha_n \{1 - y_n(\boldsymbol{w}^T\boldsymbol{x}_n + b) - \xi_n\} - \sum_{n=1}^{N} \beta_n \xi_n$$

- Note: The terms in red above were not present in the hard-margin SVM
- Two sets of dual variables  $\alpha = [\alpha_1, \dots, \alpha_N]$  and  $\beta = [\beta_1, \dots, \beta_N]$ . We'll eliminate the primal variables  $\mathbf{w}, b, \boldsymbol{\xi}$  to get dual problem containing the dual variables (just like in the hard margin case)

• The Lagrangian problem to solve

$$\min_{\boldsymbol{w}, \boldsymbol{b}, \boldsymbol{\xi}} \max_{\alpha \geq 0, \beta \geq 0} \mathcal{L}(\boldsymbol{w}, \boldsymbol{b}, \boldsymbol{\xi}, \alpha, \beta) = \frac{\boldsymbol{w}^{\top} \boldsymbol{w}}{2} + + C \sum_{n=1}^{N} \xi_{n} + \sum_{n=1}^{N} \alpha_{n} \{1 - y_{n}(\boldsymbol{w}^{T} \boldsymbol{x}_{n} + \boldsymbol{b}) - \xi_{n}\} - \sum_{n=1}^{N} \beta_{n} \xi_{n}$$

• Take (partial) derivatives of  $\mathcal{L}$  w.r.t.  $\boldsymbol{w}$ , b,  $\xi_n$  and set them to zero

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = 0 \Rightarrow \boxed{\mathbf{w} = \sum_{n=1}^{N} \alpha_n y_n \mathbf{x}_n}, \quad \frac{\partial \mathcal{L}}{\partial \mathbf{b}} = 0 \Rightarrow \sum_{n=1}^{N} \alpha_n y_n = 0, \quad \frac{\partial \mathcal{L}}{\partial \xi_n} = 0 \Rightarrow C - \alpha_n - \beta_n = 0$$

- Note: Solution of  $\mathbf{w}$  again has the same form as in the hard-margin case (weighted sum of all inputs with  $\alpha_n$  being the importance of input  $\mathbf{x}_n$ )
- Note: Using  $C \alpha_n \beta_n = 0$  and  $\beta_n \ge 0 \Rightarrow \alpha_n \le C$  (recall that, for the hard-margin case,  $\alpha \ge 0$ )
- ullet Substituting these in the Lagrangian  ${\cal L}$  gives the Dual problem

$$\max_{\boldsymbol{\alpha} \leq C, \boldsymbol{\beta} \geq 0} \mathcal{L}_{D}(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \sum_{n=1}^{N} \alpha_{n} - \frac{1}{2} \sum_{m,n=1}^{N} \alpha_{m} \alpha_{n} y_{m} y_{n} (\boldsymbol{x}_{m}^{T} \boldsymbol{x}_{n})$$



- ullet Interestingly, the dual variables  $oldsymbol{eta}$  don't appear in the objective!
- Just like the hard-margin case, we can write the dual more compactly as

$$\max_{\boldsymbol{\alpha} \leq \boldsymbol{C}} \ \mathcal{L}_D(\boldsymbol{\alpha}) = \boldsymbol{\alpha}^\top \mathbf{1} - \frac{1}{2} \boldsymbol{\alpha}^\top \mathbf{G} \boldsymbol{\alpha}$$

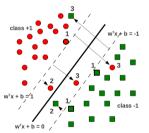
where **G** is an  $N \times N$  matrix with  $G_{mn} = y_m y_n \mathbf{x}_m^{\top} \mathbf{x}_n$ , and **1** is a vector of 1s

- Like hard-margin case, solving the dual requires concave maximization (or convex minimization)
- ullet Can be solved $^{\dagger}$  the same way as hard-margin SVM (except that  $lpha \leq {\it C}$ )
  - ullet Can solve for lpha using QP solvers or (projected) gradient methods
- ullet Given  $oldsymbol{lpha}$ , the solution for  $oldsymbol{w},b$  has the same form as hard-margin case
- Note:  $\alpha$  is again sparse. Nonzero  $\alpha_n$ 's correspond to the support vectors



## **Support Vectors in Soft-Margin SVM**

- The hard-margin SVM solution had only one type of support vectors
  - .. ones that lie on the margin boundaries  $\mathbf{w}^T \mathbf{x} + \mathbf{b} = -1$  and  $\mathbf{w}^T \mathbf{x} + \mathbf{b} = +1$
- The soft-margin SVM solution has three types of support vectors



- Lying on the margin boundaries  $\mathbf{w}^T \mathbf{x} + \mathbf{b} = -1$  and  $\mathbf{w}^T \mathbf{x} + \mathbf{b} = +1$  ( $\xi_n = 0$ )
- 2 Lying within the margin region  $(0 < \xi_n < 1)$  but still on the correct side
- **3** Lying on the wrong side of the hyperplane  $(\xi_n \ge 1)$



#### **SVMs via Dual Formulation: Some Comments**

• Recall the final dual objectives for hard-margin and soft-margin SVM

$$\boxed{ \text{Hard-Margin SVM:} \quad \max_{\boldsymbol{\alpha} \geq 0} \ \mathcal{L}_D(\alpha) = \boldsymbol{\alpha}^\top \mathbf{1} - \frac{1}{2} \boldsymbol{\alpha}^\top \mathbf{G} \boldsymbol{\alpha} }$$

Soft-Margin SVM: 
$$\max_{\boldsymbol{\alpha} \leq \mathcal{C}} \ \mathcal{L}_{\mathcal{D}}(\boldsymbol{\alpha}) = \boldsymbol{\alpha}^{\top} \mathbf{1} - \frac{1}{2} \boldsymbol{\alpha}^{\top} \mathbf{G} \boldsymbol{\alpha}$$

- The dual formulation is nice due to two primary reasons:
  - Allows conveniently handling the margin based constraint (via Lagrangians)
  - Important: Allows learning nonlinear separators by replacing inner products (e.g.,  $G_{mn} = y_m y_n \mathbf{x}_m^{\top} \mathbf{x}_n$ ) by kernelized similarities (kernelized SVMs)
- However, the dual formulation can be expensive if N is large. Have to solve for N variables  $\alpha = [\alpha_1, \dots, \alpha_N]$ , and also need to store an  $N \times N$  matrix G
- ullet A lot of work $^{\dagger}$  on speeding up SVM in these settings (e.g., can use co-ord. descent for lpha)



#### **SVM:** The Regularized Loss Function View

Maximize the margin subject to constraints led to the soft-margin formulation of SVM

$$\arg\min_{\boldsymbol{w},b,\boldsymbol{\xi}} \frac{||\boldsymbol{w}||^2}{2} + C \sum_{n=1}^{N} \xi_n$$
 subject to  $y_n(\boldsymbol{w}^T \boldsymbol{x}_n + b) \ge 1 - \xi_n, \quad \xi_n \ge 0 \quad n = 1, \dots, N$ 

- Note that the slack  $\xi_n$  is the same as  $\max\{0, 1 y_n(\mathbf{w}^\top \mathbf{x}_n + b)\}$ , i.e., hinge loss for  $(\mathbf{x}_n, y_n)$
- Another View: Thus the above is equivalent to minimizing the  $\ell_2$  regularized hinge loss

$$\mathcal{L}(\boldsymbol{w},b) = \sum_{n=1}^{N} \max\{0, 1 - y_n(\boldsymbol{w}^{\top}\boldsymbol{x}_n + b)\} + \frac{\lambda}{2}\boldsymbol{w}^{\top}\boldsymbol{w}$$

- Comparing the two: Sum of slacks is like sum of hinge losses, C and  $\lambda$  play similar roles
- Can learn (w, b) directly by minimizing  $\mathcal{L}(w, b)$  using (stochastic)(sub)gradient descent
  - Hinge-loss version preferred for linear SVMs, or with other regularizers on w (e.g.,  $\ell_1$ )



#### **Multiclass SVM**

• Multiclass SVMs use K weight vectors  $\mathbf{W} = [\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_K]$  (similar to softmax regression)

$$\hat{y}_* = \arg\max_k \boldsymbol{w}_k^{\top} \boldsymbol{x}_n$$
 (predition rule)

• Just like binary case, we can formulate a maximum-margin problem (without or with slacks)

$$\hat{\mathbf{W}} = \arg\min_{\mathbf{W}} \sum_{k=1}^{K} \frac{||\mathbf{w}_k||^2}{2} \qquad \hat{\mathbf{W}} = \arg\min_{\mathbf{W}} \sum_{k=1}^{K} \frac{||\mathbf{w}_k||^2}{2} + C \sum_{n=1}^{N} \xi_n$$
s.t. 
$$\mathbf{w}_{y_n}^{\top} \mathbf{x}_n \ge \mathbf{w}_k^{\top} \mathbf{x}_n + 1 \quad \forall k \ne y_n \qquad \text{s.t.} \quad \mathbf{w}_{y_n}^{\top} \mathbf{x}_n \ge \mathbf{w}_k^{\top} \mathbf{x}_n + 1 - \xi_n \quad \forall k \ne y_n$$

- Want score w.r.t. correct class to be at least 1 more than score w.r.t. all other classes
- The version with slack corresponds to minimizing a multi-class hinge loss

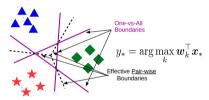
$$\boxed{ \mathcal{L}(\mathbf{W}) = \max\{0, 1 + \max_{k \neq y_n} \mathbf{w}_k^{\top} \mathbf{x}_n - \mathbf{w}_{y_n}^{\top} \mathbf{x}_n \} } \quad \text{(Crammer-Singer multiclass SVM)}$$

- ullet Loss = 0 if score on correct class is at least 1 more than score on next best scoring class
- Can optimize these similar to how we did it for binary SVM



### Multiclass SVM using Binary SVM?

- Can use binary classifiers to solve multiclass problems
- Note: These approaches can be used with other binary classifiers too (e.g., logistic regression)
- One-vs-All (also called One-vs-Rest): Construct K binary classification problems



• All-Pairs: Learn K-choose-2 binary classifiers, one for each pair of classes (j, k)

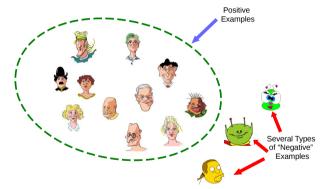
$$y_* = \arg\max_k \sum_{j \neq k} oldsymbol{w}_{j,k}^ op oldsymbol{x}_*$$
 (predict  $k$  that wins over all others the most)

• All-Pairs approach can be expensive at training and test time (but ways to speed up)



#### **One-Class Classification**

- Can we learn from examples of just one class, say positive examples?
- May be desirable if there are many types of negative examples

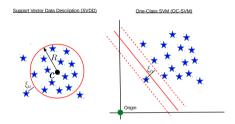


"Outlier/Novelty Detection" problems can also be formulated like this



#### One-Class Classification via SVM-like methods

• There are two popular SVM-type approaches to solve one-class problems



- Approach 1: Assume positives lie within a ball with smallest possible radius (and allow slacks)
  - Known as "Support Vector Data Description" (SVDD). Proposed by [Tax and Duin, 2004]
- Approach 2: Find a max-marg hyperplane separating positives from origin (representing negatives)
  - Known as "One-Class SVM" (OC-SVM). Proposed by [Schölkopf et al., 2001]
- Optimization problems for both cases can be solved similary as in binary SVM (e.g., via Lagrangian)

#### One-Class Classification via SVM-like methods

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$$\begin{array}{ll} \text{Support Vector Data Description (SVDD)} & \underline{\text{One-Class SVM (OC-SVM)}} \\ \arg\min_{R,c,\xi} R^2 + \frac{1}{\nu N} \sum_{n=1}^N \xi_n & \arg\min_{\boldsymbol{w},\rho,\xi} ||\boldsymbol{w}||^2 + \frac{1}{\nu N} \sum_{n=1}^N \xi_n - \rho \\ \text{s.t. } ||\boldsymbol{x}_n - \boldsymbol{c}||^2 \leq R^2 + \xi_n \quad \forall n \\ \xi_n \geq 0 & \xi_n \geq 0 \\ \\ \text{Prediction Rule: } y_* = +1 \quad \text{if } |\boldsymbol{x}_* - \boldsymbol{c}||^2 - R^2 < 0 \end{array}$$

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#### Nonlinear SVM?

- A nice property of SVM (and many other models) is that inputs only appear as inner products
- For example, recall the dual problem for soft-margin SVM had the form

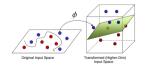
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where **G** is an  $N \times N$  matrix with  $G_{mn} = y_m y_n \mathbf{x}_m^{\top} \mathbf{x}_n$ , and **1** is a vector of 1s

• We can replace each inner-product by any general form of inner product, e.g.

$$k(\boldsymbol{x}_n, \boldsymbol{x}_m) = \phi(\boldsymbol{x}_n)^{\top} \phi(\boldsymbol{x}_m)$$

.. where  $\phi$  is some transformation (e.g., a higher-dimensional mapping) of the data



- ullet Note: Often the mapping  $\phi$  doesn't need to be explicitly computed ("kernel" magic next class)!
- Can still learn a linear model in the new space but be nonlinear in the original space (wondeful!)

#### **SVM: Some Notes**

- A hugely (perhaps the most!) popular classification algorithm
- Reasonably mature, highly optimized SVM softwares freely available (perhaps the reason why it is more popular than various other competing algorithms)
  - Some popular ones: libSVM, LIBLINEAR, scikit-learn also provides SVM
- Lots of work on scaling up SVMs $^{\dagger}$  (both large N and large D)
- Extensions beyond binary classification (e.g., multiclass, one-class, structured outputs)
- Can even be used for regression problems (Support Vector Regression)
  - The  $\epsilon$ -insensitive loss for regression does precisely that!
- Nonlinear extensions possible via kernels (next class)



<sup>†</sup>See: "Support Vector Machine Solvers" by Bottou and Lin