

### \*\*\* Q-3, Location of Neutral point \*\*\*

#### # Problem

Find the location of Neutral Point from nose of the projectile.

#### # PROCEDURE

Step 1: Find the values of  $C_{My}$  for different values of  $x$  (center of gravity).

Step 2: Plot  $C_{My}$  v/s  $\alpha$  for different values of  $x$ .

Step 3: The location of  $x$  for which the plot has zero slope is the location of Neutral point.

Step 4: Considering  $SM = +15\%$  find CG of bomb.

Step 5: Use the value of  $x$  (location of cg) to find the plots of question-01.

#### # MATLAB code

##### (1) Body alone case

%% Neutral Point estimation for Body alone configuration

clc

clear all

close all

% Geometrical data (constant)

q = 974.329545; % for 1st vaelocity

S = 0.009677;

l = 0.884;

Q1 = 1/q/S;

Q2 = 1/q/S/l;

% Balance center location(m)

% x = -0.465;

y = 0;

z = 0;

% Measured Voltage signal

CM = [63.080043	0.144499	-0.206795	1.354260	1.630051	4.275882
-0.123649	150.309342	0.592082	-0.725847	0.030856	0.393628
0.024098	-0.689773	151.831777	0.096597	-0.571799	-4.414537

0.152944	-2.334107	0.037781	77.595997	0.445712	5.841784
-0.006030	0.114642	-0.574072	-0.065800	79.176337	0.322466
0.047415	0.466131	0.099431	0.208017	0.190935	44.877349];

% No wind data

% NW = [-0.001023; 0.001298; 0.001474; -0.000501; -0.000191; -0.000147];

NW = [-0.001023 0.001298 0.001474 -0.000501 -0.000191 -0.000147];

NW = NW';

% k = [Pitch af      n1      n2      s1      s2      rm]

% Data for 40 m/s

k = [-9.947917	0.002673	-0.006420	0.005058	-0.001114	0.000491	-
0.000003						
-8.052083	0.002539	-0.004903	0.004606	-0.000981	0.000274	-
0.000041						
-6.052083	0.002434	-0.003329	0.003960	-0.000981	0.000253	-
0.000068						
-4.062500	0.002377	-0.001724	0.003177	-0.000968	0.000107	-
0.000071						
-2.052083	0.002325	-0.000170	0.002245	-0.000885	0.000153	-
0.000090						
-0.052083	0.002249	0.001322	0.001340	-0.000831	0.000072	-
0.000128						
0.052083	0.002201	0.001334	0.001344	-0.000864	0.000120	-
0.000131						
1.947917	0.002324	0.002779	0.000499	-0.000783	0.000108	-
0.000153						
3.947917	0.002385	0.004320	-0.000380	-0.000745	-0.000003	-
0.000158						
5.947917	0.002458	0.005940	-0.001250	-0.000692	-0.000010	-
0.000191						
7.947917	0.002611	0.007523	-0.001939	-0.000602	-0.000087	-
0.000206						
9.947917	0.002765	0.009013	-0.002427	-0.000612	-0.000136	-
0.000233						
11.947917	0.002850	0.010588	-0.002839	-0.000578	-0.000102	-
0.000257						
13.947917	0.002862	0.012207	-0.003176	-0.000626	-0.000078	-
0.000250						
15.937500	0.002895	0.013871	-0.003436	-0.000631	-0.000056	-
0.000280						
17.937500	0.002860	0.015556	-0.003610	-0.000583	-0.000413	-
0.000303						
19.947917	0.002808	0.017221	-0.003662	-0.000535	-0.000676	-
0.000332						
21.947917	0.002689	0.018903	-0.003702	-0.000579	-0.000642	-
0.000360						
23.947917	0.002521	0.020650	-0.003677	-0.000634	-0.000730	-
0.000392						

```
25.947917    0.002294    0.022447    -0.003645    -0.000538    -0.001077    -
0.000409];
```

```
a = transpose(k);
v = [a(2,:); a(3,:); a(4,:); a(5,:); a(6,:); a(7,:)];    % a = [af; n1;    n2;    s1;    s2;    rm]
(6x20)
```

```
alpha_dummy = [];
Cmy_dummy1=[];
Cmy_dummy2=[];
Cmy_dummy3=[];
Cmy_dummy4=[];
Cmy_dummy5=[];
Cmy_dummy6=[];
Cmy_dummy7=[];
Cmy_dummy8=[];
Cmy_dummy9=[];
Cmy_dummy10=[];
```

```
x = [-0.465:0.093:(0.465-0.093)];    % The CG is varied from 0.45 to -0.45 to find NP of
configuration
```

```
y1 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(1) 0 1 0; -y x(1) 0 0 0 1];
y2 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(2) 0 1 0; -y x(2) 0 0 0 1];
y3 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(3) 0 1 0; -y x(3) 0 0 0 1];
y4 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(4) 0 1 0; -y x(4) 0 0 0 1];
y5 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(5) 0 1 0; -y x(5) 0 0 0 1];
y6 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(6) 0 1 0; -y x(6) 0 0 0 1];
y7 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(7) 0 1 0; -y x(7) 0 0 0 1];
y8 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(8) 0 1 0; -y x(8) 0 0 0 1];
y9 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(9) 0 1 0; -y x(9) 0 0 0 1];
y10 = [-1 0 0 0 0 0; 0 1 0 0 0 0; 0 0 -1 0 0 0; 0 -z y 1 0 0; z 0 -x(10) 0 1 0; -y x(10) 0 0 0
1];
```

```
for i = 1:1:20
```

```
af = v(1,i);
n1 = v(2,i);
n2 = v(3,i);
s1 = v(4,i);
s2 = v(5,i);
rm = v(6,i);
```

```
a = [af; n1; n2; s1; s2; rm];
alpha = k(:,1);
```

```
A = CM*[a - NW];    % A=[Ax;N1;N2;S1;S2;Rm] in kg and kg-m
Af = A(1);
N1 = A(2);
N2 = A(3);
```

```
S1 = A(4);  
S2 = A(5);  
Rm = A(6);
```

```
% Transform the forces and moments to the body axis
```

```
% FM = [fx; fy; fz; mx; my; mz]
```

```
FM = [Af; (S1+S2); (N1+N2); Rm; (N1-N2)*0.065; (S1-S2)*0.065]*9.81;
```

```
% Transform the forces and moments to the C.G the flight vehicle
```

```
% CG = [Fx Fy Fz Mx My Mz] @cg
```

```
CG1 = y1*FM;
```

```
CG2 = y2*FM;
```

```
CG3 = y3*FM;
```

```
CG4 = y4*FM;
```

```
CG5 = y5*FM;
```

```
CG6 = y6*FM;
```

```
CG7 = y7*FM;
```

```
CG8 = y8*FM;
```

```
CG9 = y9*FM;
```

```
CG10 = y10*FM;
```

```
% Mxyz = [Mx My Mz]
```

```
Mxyz1 = CG1(4:6,1);
```

```
Mxyz2 = CG2(4:6,1);
```

```
Mxyz3 = CG3(4:6,1);
```

```
Mxyz4 = CG4(4:6,1);
```

```
Mxyz5 = CG5(4:6,1);
```

```
Mxyz6 = CG6(4:6,1);
```

```
Mxyz7 = CG7(4:6,1);
```

```
Mxyz8 = CG8(4:6,1);
```

```
Mxyz9 = CG9(4:6,1);
```

```
Mxyz10 = CG10(4:6,1);
```

```
% Cmxyz = [Cmx Cmy Cmz]
```

```
Cmxyz1 = (1/(q*S*I))*Mxyz1;
```

```
Cmxyz2 = (1/(q*S*I))*Mxyz2;
```

```
Cmxyz3 = (1/(q*S*I))*Mxyz3;
```

```
Cmxyz4 = (1/(q*S*I))*Mxyz4;
```

```
Cmxyz5 = (1/(q*S*I))*Mxyz5;
```

```
Cmxyz6 = (1/(q*S*I))*Mxyz6;
```

```
Cmxyz7 = (1/(q*S*I))*Mxyz7;
```

```
Cmxyz8 = (1/(q*S*I))*Mxyz8;
```

```
Cmxyz9 = (1/(q*S*I))*Mxyz9;
```

```
Cmxyz10 = (1/(q*S*I))*Mxyz10;
```

```
Cmy1 = Cmxyz1(2);
```

```
Cmy2 = Cmxyz2(2);
```

```
Cmy3 = Cmxyz3(2);
```

```
Cmy4 = Cmxyz4(2);
```

```
Cmy5 = Cmxyz5(2);
```

```

Cmy6 = Cmxyz6(2);
Cmy7 = Cmxyz7(2);
Cmy8 = Cmxyz8(2);
Cmy9 = Cmxyz9(2);
Cmy10 = Cmxyz10(2);

```

```

Cmy_dummy1 = [Cmy_dummy1, Cmy1];
Cmy_dummy2 = [Cmy_dummy2, Cmy2];
Cmy_dummy3 = [Cmy_dummy3, Cmy3];
Cmy_dummy4 = [Cmy_dummy4, Cmy4];
Cmy_dummy5 = [Cmy_dummy5, Cmy5];
Cmy_dummy6 = [Cmy_dummy6, Cmy6];
Cmy_dummy7 = [Cmy_dummy7, Cmy7];
Cmy_dummy8 = [Cmy_dummy8, Cmy8];
Cmy_dummy9 = [Cmy_dummy9, Cmy9];
Cmy_dummy10 = [Cmy_dummy10, Cmy10];

```

```

alpha_dummy = [alpha_dummy, alpha];

```

```

end

```

```

figure('Name','Neutral Point estimation for Bomb Model-II_Body Alone','NumberTitle','off')
plot(alpha_dummy,Cmy_dummy1)
hold on
plot(alpha_dummy,Cmy_dummy2)
hold on
plot(alpha_dummy,Cmy_dummy3)
hold on
plot(alpha_dummy,Cmy_dummy4)
hold on
plot(alpha_dummy,Cmy_dummy5)
hold on
plot(alpha_dummy,Cmy_dummy6)
hold on
plot(alpha_dummy,Cmy_dummy7)
hold on
plot(alpha_dummy,Cmy_dummy8)
hold on
plot(alpha_dummy,Cmy_dummy9)
hold on
plot(alpha_dummy,Cmy_dummy10)
hold off
title('Neutral point estimation for (6680 Bomb Model-II Body Alone) using C_m_y v/s  $\alpha$ ')
grid on
xlabel('α (deg)')
ylabel('C_M_y')
legend({'x1','x2','x3','x4','x5','x6','x7','x8','x9','x10'},'Location','northwest','NumColumns',2)

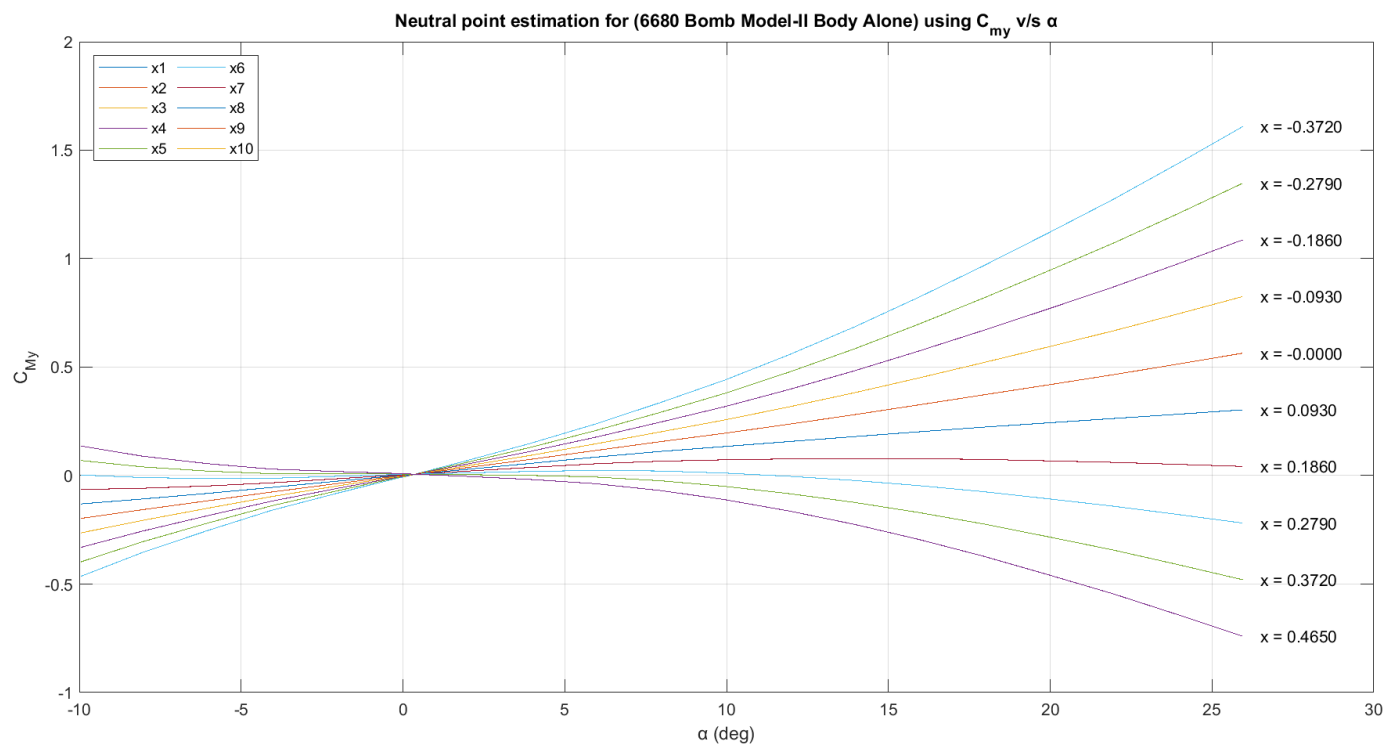
y_text_location = [Cmy_dummy1(20), Cmy_dummy2(20), Cmy_dummy3(20),
Cmy_dummy4(20), Cmy_dummy5(20),...

```

```
Cmy_dummy6(20), Cmy_dummy7(20), Cmy_dummy8(20), Cmy_dummy9(20),  
Cmy_dummy10(20)]
```

```
for i=1:10  
    j = i-1;  
    x(i) = -0.465 + i*0.093  
    textString = sprintf('x = %.4f', x(i));  
    text(26.5, y_text_location(i), textString, 'FontSize', 10);  
    hold on;  
end
```

## # Output Plot

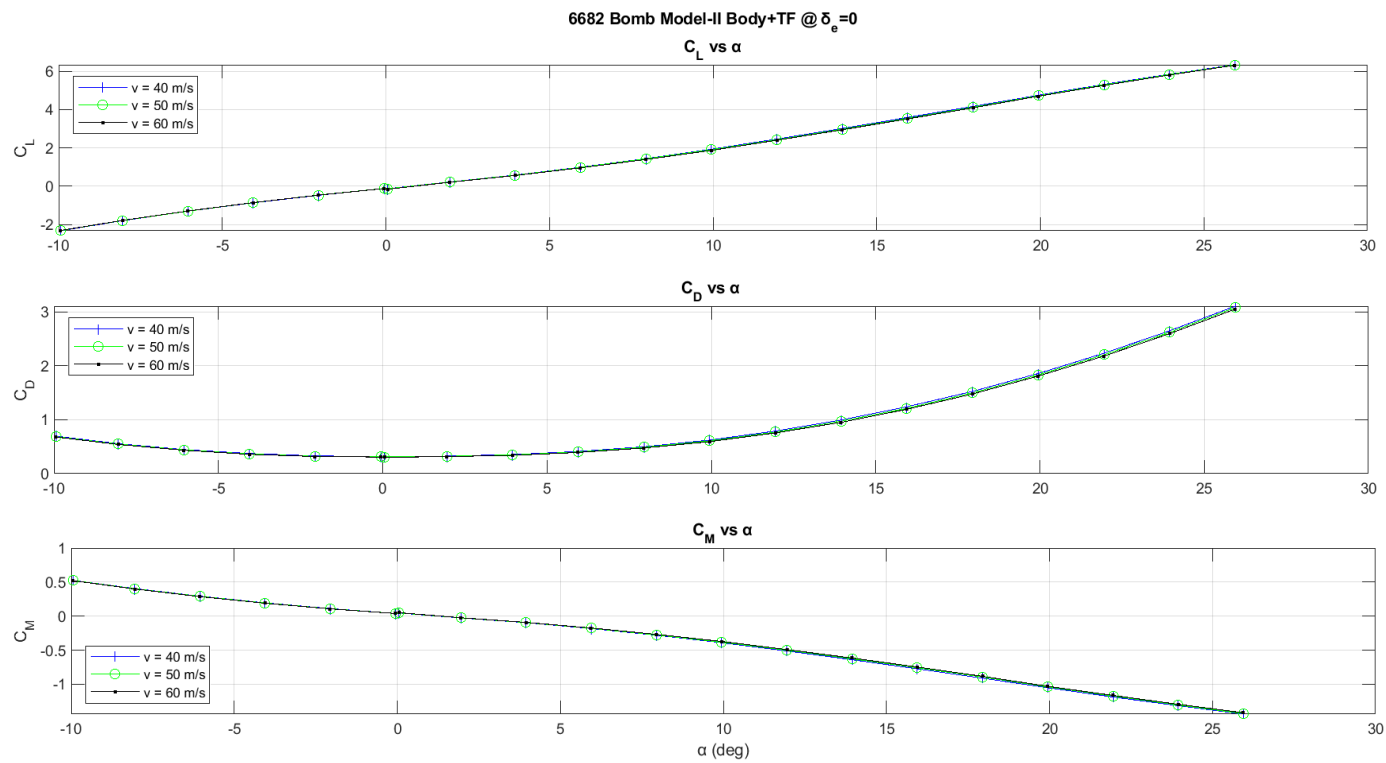


$C_{My}$  v/s  $\alpha$  for different locations of CG (Body alone)

## (2) Body + Tail fin

- The MATLAB code is similar as shown for Body alone configuration, Only No wind data, Wind tunnel data and dynamic head will change.

### # Output Plot

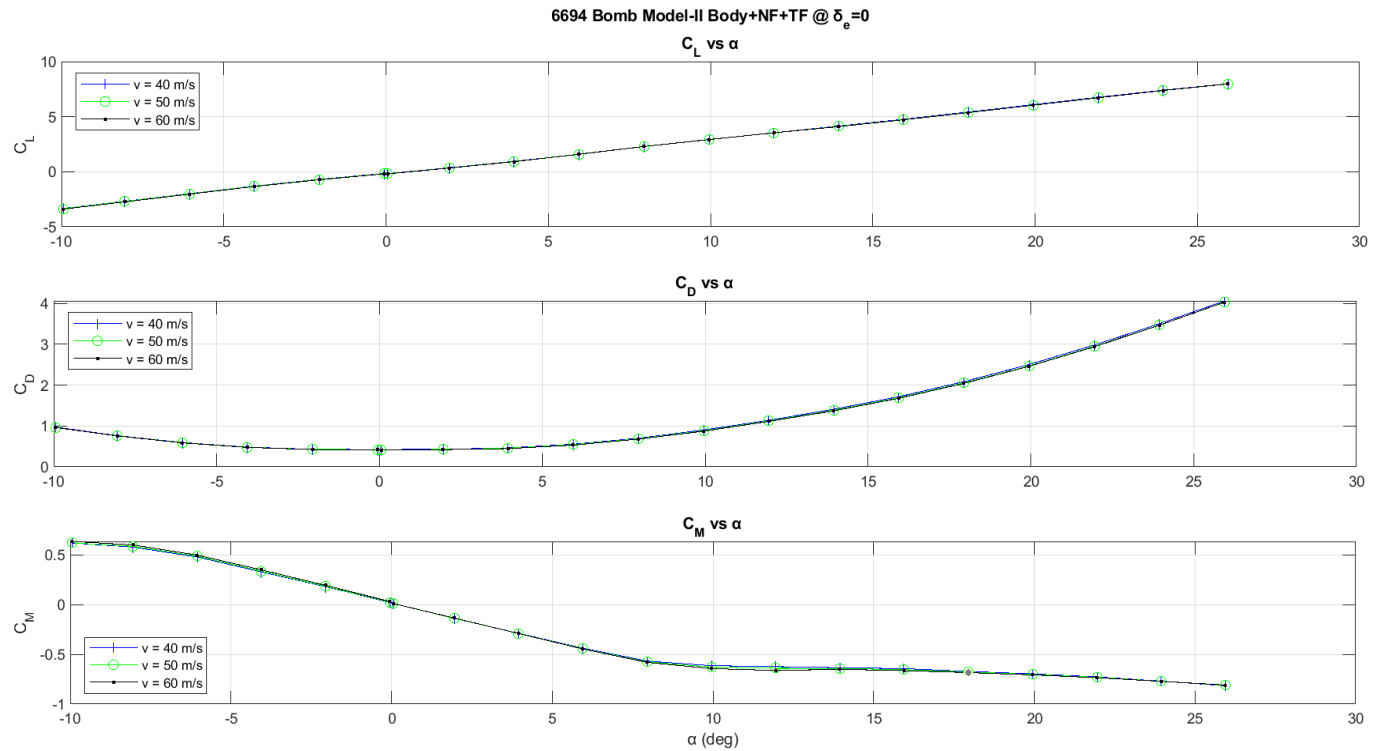


$C_{My}$  v/s  $\alpha$  for different locations of CG (Body alone + TF)

### (3) Body + Nose fin + Tail fin

- The MATLAB code is similar as shown for Body alone configuration, Only No wind data, Wind tunnel data and dynamic head will change.

#### # Output Plot



$C_{M_y}$  v/s  $\alpha$  for different locations of CG (Body alone + NF + TF)



## # Observations

### 1. 6680\_Bomb Model-II\_Body Alone

==> CMy v/s  $\alpha$  curve is fairly flat (i.e Slope is zero) within range of NP [0.186, 0.279].

Approximate location of **NP** from balance load center is 0.2325m. (i.e  $0.465 - 0.2325 =$   
**0.2325 behind nose**).

==> Considering SM of +15%, the CG should lie at 0.01665 m ahead of NP.

(i.e. 0.24915 m from balance load center and 0.21585 m behind nose)

$$x = -0.24915 \text{ m}$$

### 2. 6682\_Bomb Model-II\_Body\_TF\_0

==> Cmy v/s alpha curve is fairly flat (i.e Slope is zero) within range of NP [-0.093, 0].

Approximate location of **NP** from balance load center is -0.0465m

(i.e  $0.465 - (-0.0465) =$  **0.5115 behind nose**).

==> Considering SM of +15%, the CG should lie at 0.01665 m ahead of NP.

(i.e. -0.02985 m from balance load center and 0.49485 m behind nose)

$$x = 0.02985 \text{ m}$$

### 3. 6694\_Bomb Model-II\_Body\_NF\_TF\_0

==> Cmy v/s alpha curve is fairly flat (i.e Slope is zero) at NP location of 0.093.

Approximate location of **NP** from balance load center is 0.093m

(i.e  $0.465 - 0.093 =$  **0.372 m behind nose**).

==> Considering SM of +15%, the CG should lie at 0.01665 m ahead of NP.

(i.e. 0.10965 m from balance load center and 0.35535 m behind nose)