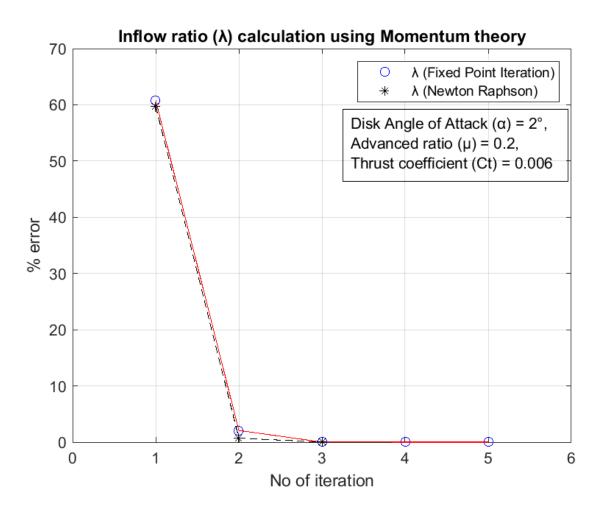
## Q-4: MATLAB CODE

Program numerical solutions to this inflow equation using both the fixed point iterative method and the Newton - Raphson method. Plot the % error for each iteration step for both the methods v/s iteration number on the same graph.

```
%% Calculation of the inflow ratio at the rotor disk in forward flight from
momentum theory
clear all
close all
clc
% Given Data
alpha = 2*pi/180;
                               % Disk Angle of Attack (\alpha)
                               % Advanced ratio (μ)
mu = 0.2;
Ct = 0.006;
                                % Thrust coefficient
%% Fixed Point Iteration
lambda_0 = sqrt(Ct/2);
                                % Initial guess of inflow ratio (typically hover
                                inflow ratio)
lambda = lambda 0;
lambda old = lambda 0;
                                % Old value of Inflow ratio
maxerrper = 0.0001;
                                % Maximum error
n = 10;
                                % No. of iterations
for i=1:n
    lambda = mu*tan(alpha) + Ct/(2*sqrt(mu^2 + lambda^2));
    errper(i) = abs((lambda - lambda_old)/lambda_old)*100;
    errper_fpi(i) = errper(i);
    if (errper_fpi(i) < maxerrper)</pre>
        break;
    end
    lambda_old = lambda;
    i = i+1;
end
% Plotting of data (Fixed Point Iteration)
plot(1:i,errper_fpi,'bo',1:i,errper_fpi,'-r')
xlim([0,6])
ylim([0,70])
title('Inflow ratio (\lambda) calculation using Momentum theory')
ylabel('% error');
xlabel('No of iteration');
grid on
hold on
%% Newton Raphson Iteration
                                % Initial guess of inflow ratio (typically hover
lambda_0 = sqrt(Ct/2);
                                 inflow ratio)
lambda = lambda 0;
                                % Old value of Inflow ratio
lambda old = lambda 0;
maxerrper = 0.0001;
                                % Maximum error
n = 10;
                                % No. of iterations
```

```
for i=1:n
    f = lambda - mu*tan(alpha) - 0.5*Ct/sqrt(mu^2 + lambda^2);
    df = 1 + 0.5*(Ct*lambda)/((mu^2 + lambda^2)^1.5);
    lambda = lambda - (f/df);
    errper(i) = abs((lambda - lambda_old)/lambda_old)*100;
    errper_nr(i) = errper(i);
    if (errper nr(i) < maxerrper)</pre>
        break;
    end
    lambda old = lambda;
    i = i+1;
end
% Plotting of data (Newton Raphson Iteration)
plot(1:i,errper_nr,'k*',1:i,errper_nr,'--k')
legend({'λ (Fixed Point Iteration)','','λ (Newton
Raphson)'},'Location','northeast')
annotation('textbox', [0.55, 0.65, 0.35, 0.15], 'String', "Disk Angle of Attack
(\alpha) = 2°, Advanced ratio (\mu) = 0.2, Thrust coefficient (Ct) = 0.006")
```



**Figure 1 :** Plot of the % error for each iteration step using Fixed point iterative method & Newton-Raphson method v/s Iteration Number

- 2] Describe all the steps and state the convergence criteria used.
- **Step 1:** First declare the given values (Initial conditions).
- **Step 2:** Set an number of iterations (Approximately).
- **Step 3:** To start the fixed point iteration or Newton Raphson method set an initial value (here we typically start with inflow ratio of hovering condition).
- **Step 4:** Set an error value (here taken 10^-6, randomly), iteration said to be converged if calculation error is below this value.
- **Step 5 :** Start iteration based on the methods of Fixed point Iteration or Newton Raphson method.
- **Step 6:** For each iteration calculate the percentage error between calculated  $\lambda$  and previous iteration value.
- Step 7: Plot the error in percentage in each step against number of iterations.
- 3] Check if final answer is affected by choice of initial guess for the inflow ratio on the numerical solution.

Iterations	Percentage Error (Fixed Point Iteration)				
$\lambda_{}$ initial	sqrt(2*Ct)	sqrt(Ct)	sqrt(Ct/2)	sqrt(Ct/5)	
1	81.6148	72.9256	60.8352	37.1725	
2	8.7818	4.4376	2.0846	0.6066	
3	0.0626	0.0336	0.0163	0.0048	
4	0.0005	0.0003	0.0001	0	
5	0	0	0		

Iterations	Percentage Error (Newton Raphson)				
$\lambda_{}$ initial	sqrt(2*Ct)	sqrt(Ct)	sqrt(Ct/2)	sqrt(Ct/5)	
1	79.4138	71.2475	59.7344	36.7162	
2	2.9083	1.6906	0.7223	0.1235	
3	0.0003	0.0001	0	0	
4	0	0			

• We initially guessed our induced inflow value to be similar to that of the hover condition, i.e.  $\lambda = \lambda h = \operatorname{sqrt}(Ct/2)$ .

- For our exploration of initial guess we have tried our two methods with different initial guesses like,  $\lambda = \operatorname{sqrt}(2*Ct)$ ,  $\lambda = \operatorname{sqrt}(Ct)$ ,  $\lambda = \operatorname{sqrt}(Ct/2)$  and also  $\lambda = \operatorname{sqrt}(Ct/5)$ .
- Results from all algorithm:  $\lambda = 0.0219$
- Any initial guess will give the same result of  $\lambda$ , only the number of iterations will change.
- 4] For the given CT and  $\alpha$  plot  $\lambda$  vs  $\mu$  using one of the methods and compare it with the approximate solution of  $\lambda$  valid for  $\mu > 0.2$  by plotting it on the same graph using different line types.

## **4-A**] Fixed Point Iteration

%% Calculation of inflow ratio at the rotor disk in forward flight from the momentum theory and Solution of  $\lambda$  using Fixed Point Iteration compared with the approximate (valid for  $\mu$  > 0.2) solution of  $\lambda$ 

```
clear all
close all
clc
% Given Data
alpha = 2*pi/180;
                               % Disk Angle of Attack (\alpha)
                                 % Thrust coefficient
Ct = 0.006;
%% Fixed Point Iteration
lambda 0 = sqrt(Ct/2);
                               % Initial guess of inflow ratio (typically hover
inflow ratio)
lambda(1) = lambda_0;
for i = 1:1:301
                                                                               %
    mu(i) = 0.002*i - 0.002;
0<=µ<=0.6 ~~ varying Advanced ratio (Incompressible Subsonic regime)</pre>
    lambda_apprx(i) = mu(i)*tan(alpha) + Ct/(2*mu(i));
    lambda(i+1) = mu(i)*tan(alpha) + Ct/(2*sqrt(mu(i)^2 + lambda(i)^2));
    lambda_fpi(i) = lambda(i+1);
% Plotting of data (Fixed Point Iteration)
plot(mu,lambda fpi,'r')
hold on
plot(mu,lambda_apprx,'--k')
xlim([0 0.6])
ylim([0 0.08])
title('\mu v/s \lambda (Fixed Point Iteration & Approximate Solution)')
xlabel('Advance Ratio, μ')
ylabel('Inflow Ratio, λ')
legend('Fixed Point Iteration', 'Approximate Solution')
grid on
hold off
annotation('textbox', [0.55, 0.68, 0.34, 0.1], 'String', "Disk Angle of Attack (\alpha)
= 2°, Thrust coefficient (Ct) = 0.006")
```

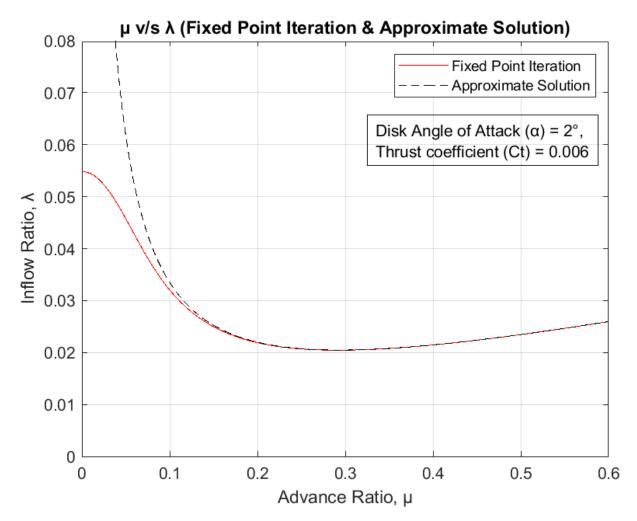


Figure 2 : Comparison of Fixed Point Iteration & Approximate Solution for  $\lambda$  with varying  $\mu$ 

## **4-B**] Newton-Raphson method

%% Calculation of inflow ratio at the rotor disk in forward flight from the momentum theory and Solution of  $\lambda$  using Fixed Point Iteration compared with the approximate (valid for  $\mu$  > 0.2) solution of  $\lambda$ 

```
clear all
close all
clc
% Given Data
alpha = 2*pi/180;
                               % Disk Angle of Attack (α)
                                % Thrust coefficient
Ct = 0.006;
%% Newton Raphson
lambda_0 = sqrt(Ct/2);
                               % Initial guess of inflow ratio (typically hover
inflow ratio)
lambda(1) = lambda_0;
for i = 1:1:301
                                                                              %
    mu(i) = 0.002*i - 0.002;
0<=μ<=0.6 ~~ varying Advanced ratio (Incompressible Subsonic regime)</pre>
    lambda\_apprx(i) = mu(i)*tan(alpha) + Ct/(2*mu(i));
    f = lambda(i) - mu(i)*tan(alpha) - 0.5*Ct/sqrt(mu(i)^2 + lambda(i)^2);
    df = 1 + 0.5*(Ct*lambda(i))/((mu(i)^2 + lambda(i)^2)^1.5);
    lambda(i+1) = lambda(i) - (f/df);
    lambda_nr(i) = lambda(i+1);
% Plotting of data (Newton Raphson)
plot(mu,lambda_nr,'r')
hold on
plot(mu,lambda apprx,'--k')
xlim([0 0.6])
ylim([0 0.08])
title('\mu v/s \lambda (Newton Raphson method & Approximate Solution)')
xlabel('Advance Ratio, μ')
ylabel('Inflow Ratio, λ')
legend('Newton Raphson','Approximate Solution')
grid on
hold off
annotation('textbox', [0.55, 0.68, 0.34, 0.1], 'String', "Disk Angle of Attack (\alpha)
= 2°, Thrust coefficient (Ct) = 0.006")
```

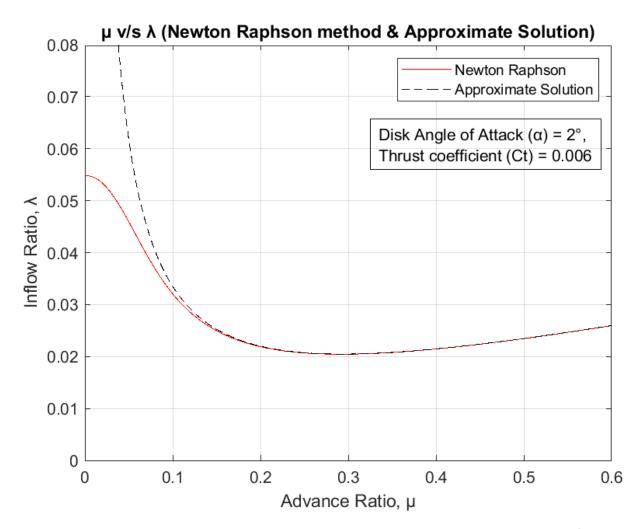


Figure 3 : Comparison of Newton Raphson & Approximate Solution for  $\lambda$  with varying  $\mu$