Assignment 2: Implicit Neural Representation

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Link to Google Drive: https://drive.google.com/file/d/1vbWCA-YL9edBhQS0Zibeh_p61bGRLz0W/view?usp=sharing

Please submit a PDF containing all outputs to gradescope by October 31, 11:59pm

In this assignment, you will get some hands-on experience with implicit neural representation (INR). With INR, we parameterize some signal (in our case images) with a neural network (in this assignment, we will use a basic feed-forward network). While in practice this might be useful for outpainting, super-resolution, and compression, in this assignment we will mainly focus on the basics, with some proof-of-concept outpainting at the end. Your outputs might not look great, this is okay as long as they are at least as good as the examples.

Dataset

As always, we start with the data. In this section, you will need to complete the following steps:

- 1. Choose an image. If you're working in colab, you will need to either mount your Google Drive, or else upload the file directly.
- 2. Write SingleImageDataset. This is how you'll convert your image into model inputs and targets. You will instantiate the dataset and a dataloader to check and make sure you did this part correctly.

Question 1: Selecting an image (5 points)

Free points! Just show your image here. One catch- make sure the image is less than 62500 pixels, total. We do not want you to waste time waiting for your model to train.

```
# from google.colab import drive
# drive.mount('/content/drive', force_remount=True)

# FOLDERNAME = 'CMSC828i/HW2'
# assert FOLDERNAME is not None, "[!] Enter the foldername."

# # Now that we've mounted your Drive, this ensures that
# # the Python interpreter of the Colab VM can load
# # python files from within it.
# import sys
# sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
```

```
!wget --no-check-certificate "https://drive.google.com/uc?
export=download&id=1TvD6ybPj1NiJgm5bLPzG31HbwA3 LncY" -0 mypeacock.jpg
--2023-10-31 19:47:09-- https://drive.google.com/uc?
export=download&id=1TvD6ybPj1NiJgm5bLPzG31HbwA3 LncY
Resolving drive.google.com (drive.google.com)... 172.253.115.101,
172.253.115.100, 172.253.115.113, ...
Connecting to drive.google.com (drive.google.com)|
172.253.115.101|:443... connected.
HTTP request sent, awaiting response...
303 See Other
Location:
https://doc-08-00-docs.googleusercontent.com/docs/securesc/ha0ro937gcu
c7l7deffksulhg5h7mbp1/
lplj6ij4k23t42vq2c2c34ct305dk4v8/1698795975000/10921789810122388020/
*/1TvD6ybPj1NiJgm5bLPzG31HbwA3 LncY?e=download&uuid=851fde1b-61b6-
4a9a-a8be-7fcd5e5c5f06 [following]
Warning: wildcards not supported in HTTP.
--2023-10-31 19:47:10--
                         https://doc-08-0o-
docs.googleusercontent.com/docs/securesc/ha0ro937gcuc7l7deffksulhg5h7m
bp1/
lplj6ij4k23t42vq2c2c34ct305dk4v8/1698795975000/10921789810122388020/
*/1TvD6ybPj1NiJqm5bLPzG31HbwA3 LncY?e=download&uuid=851fde1b-61b6-
4a9a-a8be-7fcd5e5c5f06
Resolving doc-08-0o-docs.googleusercontent.com (doc-08-0o-
docs.googleusercontent.com)... 172.253.63.132, 2607:f8b0:4004:c08::84
Connecting to doc-08-0o-docs.googleusercontent.com (doc-08-0o-
docs.googleusercontent.com) | 172.253.63.132 | :443... connected.
HTTP request sent, awaiting response... 200 OK
Length: 44029 (43K) [image/jpeg]
Saving to: 'mypeacock.jpg'
mypeacock.jpg 100%[============] 43.00K --.-KB/s in
0.008s
2023-10-31 19:47:10 (5.07 MB/s) - 'mypeacock.jpg' saved [44029/44029]
from torchvision.io import read image ## Note: feel free to use
another loader
import matplotlib.pyplot as plt
image = read image("/home/mayank/828i/HW2/mypeacock.jpg")
plt.imshow(image.permute(1, 2, 0).numpy())
plt.axis('off')
plt.show()
plt.close()
```



```
print(image.shape)
num_pix=image.shape[1]*image.shape[2]
print(num_pix)

torch.Size([3, 224, 224])
50176
```

Question 2: Writing the dataset (20 points)

For this part, you need to fill in the blanks for the dataset provided below. Alternatively, feel free to write it from scratch, the scaffolding was provided to help you, not to trap you in a box.

You will also need to write a loop to construct the image, using a dataloader for your SingleImageDataset. We provide more details in comments below.

We will be grading your code and your image outputs. In Gradescope, make sure both are fully visible.

```
from torchvision.io import read_image
from torch.utils.data import Dataset

class SingleImageDataset(Dataset):
    def __init__(self, img_path):
        self.image = read_image(img_path)
        self.num_channels, self.h, self.w = self.image.shape

def __len__(self):
```

```
### TODO: 1 line of code for returning the number of pixels
        num pix=self.h*self.w
        return num pix
    def getitem (self, idx):
        ### \overline{\text{TODO}}: 2-3 lines of code for x, y, and pixel values
        x=idx//self.w
        y=idx%self.w
        intensity =image[:,y,x]
        return {"x": x, "y": y, "intensity": intensity}
import torch
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
import numpy as np
dataset = SingleImageDataset('/home/mayank/828i/HW2/mypeacock.jpg')
### TODO: 1 line of code for initializing a DataLoader
dataloader =DataLoader(dataset,batch size=4096,shuffle=True)
height, width=dataset.h, dataset.w
print(height)
### TODO: 6-10 lines of code for using your dataloader to retrieve,
reassemble.
###
          and display your image
#creat a zeros np array
peacock image = np.zeros((dataset.h,dataset.w,3),dtype=np.uint8)
for batch in dataloader:
    x, y, intensity = batch["x"], batch["y"], batch["intensity"]
    #detach so that tensor is without gradient and converting to numpy
array
    x= x.detach().numpy()
    y = y.detach().numpy()
    intensity = intensity.detach().numpy()
    #get intensity for y,x pixel values
    for idx, (y_, x_) in enumerate(zip(y,x)):
        peacock_image[y_,x_,:] = intensity[idx]
plt.imshow(peacock image)
plt.axis('off')
plt.show()
224
```



Network

Question 3: Defining the Network (15 points)

Define a feedforward neural network. Remember that the last layer output dimension should be equal to the number of color channels.

A very basic network might have a linear layer, followed by a ReLU, followed by another linear layer.

```
class FFN(torch.nn.Module):
    def __init__(self,number_input=2):
        super(FFN, self).__init__()
    ### TODO: define and initialize some layers with weights
    #created 2 hidden layers
    self.layers = torch.nn.Sequential(
        torch.nn.Linear(number_input, 1024),
        torch.nn.ReLU(),
        torch.nn.Linear(1024, 2048),
        torch.nn.ReLU(),
        torch.nn.ReLU(),
        torch.nn.ReLU(),
        torch.nn.ReLU(),
        torch.nn.Linear(1024, 3))

def forward(self, coord):
```

```
out = self.layers(coord)
    return out

is_cuda_available = torch.cuda.is_available()
if is_cuda_available:
    print("Using CUDA")
device = torch.device("cuda:0" if is_cuda_available else "cpu")
print(device)

Using CUDA
cuda:0
```

Training

Now that you have a dataset and model, time to put it together!

Instantiate an optimizer and a criterion. Loop over your dataset until the network converges. Track your loss. We will be asking you to plot it later.

```
from tgdm import tgdm
from torch.optim.lr scheduler import ReduceLROnPlateau
import time
net = FFN()
net=net.to(device)
# since we are training the network for pixels,
# we will do a pixelwise MSE loss
criterion = torch.nn.MSELoss()
### TODO: 2 lines of code for optimizer, number of epochs
optimizer = torch.optim.Adam(net.parameters(),lr=1e-2)
#Reduce learning rate when a metric has stopped improving
scheduler = ReduceLROnPlateau(optimizer, factor=0.1, patience=5,
verbose=True)
NUM EPOCHS = 200
losses=[]
### TODO: set up mechanism for storing loss values
for epoch in tqdm(range(NUM_EPOCHS)):
      list losses = []
      running corrects=0
      n \text{ sample} = 0
      for batch in dataloader:
            x, y, actual = batch["x"], batch["y"], batch["intensity"]
            #USIng GPU so moving data to device
            x = x.to(device)
            y = y.to(device)
            actual = actual.float().to(device)
            #normalize from 0 to 1
            x = x / dataset.w
```

```
v = v / dataset.h
           ### TODO: 3 lines of code to assemble coord from x and y,
pass to net,
                     compute loss
           coord =torch.vstack([x, y]).T
           pred = net(coord)
            loss =criterion(pred, actual)
            list losses.append(loss.item())
            optimizer.zero grad()
           loss.backward()
           optimizer.step()
           ### TODO: track loss
           losses.append(loss.item())
     # data.set description(f'Epoch [{epoch}/{NUM EPOCHS}]')
     # data.set postfix(acc=(running corrects/n sample).item())
      average loss = sum(list losses)/len(list losses)
      scheduler.step(average loss)
      time diff = time.time() - starting time
      print("Epoch: [{}/{}] Time: {}min:{}sec Loss:
{:.4f}".format(epoch, NUM EPOCHS, time diff//60, time diff%60,
average loss))
       | 1/200 [00:03<10:24, 3.14s/it]
Epoch: [0/200] Time: 0.0min:3.135509490966797sec Loss: 3788.6218
  1%|
               | 2/200 [00:04<06:53, 2.09s/it]
Epoch: [1/200] Time: 0.0min:1.3537671566009521sec Loss: 2603.5746
  2%||
              | 3/200 [00:05<05:55, 1.81s/it]
Epoch: [2/200] Time: 0.0min:1.4696547985076904sec Loss: 2403.8772
               | 4/200 [00:07<05:15, 1.61s/it]
  2%||
Epoch: [3/200] Time: 0.0min:1.3046929836273193sec Loss: 2086.7291
        | 5/200 [00:08<04:48, 1.48s/it]
  2%||
Epoch: [4/200] Time: 0.0min:1.2495806217193604sec Loss: 1778.1659
  3%||
      | 6/200 [00:09<04:34, 1.42s/it]
Epoch: [5/200] Time: 0.0min:1.2926790714263916sec Loss: 1676.3879
  4%|
               | 7/200 [00:11<04:21, 1.35s/it]
Epoch: [6/200] Time: 0.0min:1.2210519313812256sec Loss: 1626.4784
  4%|
               | 8/200 [00:12<04:12, 1.31s/it]
```

```
Epoch: [7/200] Time: 0.0min:1.2319309711456299sec Loss: 1439.4777
 4%| | 9/200 [00:13<04:05, 1.29s/it]
Epoch: [8/200] Time: 0.0min:1.2235777378082275sec Loss: 1333.3139
 5%| | 10/200 [00:14<03:57, 1.25s/it]
Epoch: [9/200] Time: 0.0min:1.1675832271575928sec Loss: 1225.8263
 6%| | 11/200 [00:15<03:54, 1.24s/it]
Epoch: [10/200] Time: 0.0min:1.2235393524169922sec Loss: 1157.0521
 6%| | 12/200 [00:17<03:53, 1.24s/it]
Epoch: [11/200] Time: 0.0min:1.2474498748779297sec Loss: 1102.2501
 6%| | 13/200 [00:18<03:50, 1.23s/it]
Epoch: [12/200] Time: 0.0min:1.208313226699829sec Loss: 1065.3828
 7%| | 14/200 [00:19<03:48, 1.23s/it]
Epoch: [13/200] Time: 0.0min:1.221627950668335sec Loss: 1000.3791
 8%| | 15/200 [00:20<03:44, 1.21s/it]
Epoch: [14/200] Time: 0.0min:1.1667072772979736sec Loss: 952.4100
 8%| | 16/200 [00:22<03:48, 1.24s/it]
Epoch: [15/200] Time: 0.0min:1.3102400302886963sec Loss: 924.3752
 8%| | 17/200 [00:23<03:46, 1.24s/it]
Epoch: [16/200] Time: 0.0min:1.2337658405303955sec Loss: 897.7581
 9%| | 18/200 [00:24<03:51, 1.27s/it]
Epoch: [17/200] Time: 0.0min:1.3413007259368896sec Loss: 876.0740
10%| | 19/200 [00:25<03:50, 1.27s/it]
Epoch: [18/200] Time: 0.0min:1.2819209098815918sec Loss: 842.6161
10% | 20/200 [00:27<03:42, 1.24s/it]
Epoch: [19/200] Time: 0.0min:1.1528453826904297sec Loss: 901.4050
10% | 21/200 [00:28<03:41, 1.24s/it]
Epoch: [20/200] Time: 0.0min:1.2421834468841553sec Loss: 882.7867
11%| | 22/200 [00:29<03:36, 1.22s/it]
```

```
Epoch: [21/200] Time: 0.0min:1.1578662395477295sec Loss: 818.1167
12%| | 23/200 [00:30<03:40, 1.25s/it]
Epoch: [22/200] Time: 0.0min:1.3225724697113037sec Loss: 832.5837
             | 24/200 [00:32<03:43, 1.27s/it]
12%|
Epoch: [23/200] Time: 0.0min:1.3293328285217285sec Loss: 813.2245
12%| | 25/200 [00:33<03:36, 1.24s/it]
Epoch: [24/200] Time: 0.0min:1.1583597660064697sec Loss: 801.1717
13%| | 26/200 [00:34<03:35, 1.24s/it]
Epoch: [25/200] Time: 0.0min:1.2298734188079834sec Loss: 786.5365
14%| | 27/200 [00:35<03:29, 1.21s/it]
Epoch: [26/200] Time: 0.0min:1.1567137241363525sec Loss: 813.2420
14%| | 28/200 [00:36<03:29, 1.22s/it]
Epoch: [27/200] Time: 0.0min:1.231433391571045sec Loss: 825.3330
14%| | 29/200 [00:38<03:29, 1.22s/it]
Epoch: [28/200] Time: 0.0min:1.2375802993774414sec Loss: 743.6691
15%| | 30/200 [00:39<03:33, 1.25s/it]
Epoch: [29/200] Time: 0.0min:1.3239176273345947sec Loss: 759.0732
16% | 31/200 [00:40<03:31, 1.25s/it]
Epoch: [30/200] Time: 0.0min:1.2449188232421875sec Loss: 728.5509
16% | 32/200 [00:42<03:33, 1.27s/it]
Epoch: [31/200] Time: 0.0min:1.3090271949768066sec Loss: 713.6526
16% | 33/200 [00:43<03:25, 1.23s/it]
Epoch: [32/200] Time: 0.0min:1.1480731964111328sec Loss: 709.5783
17% | 34/200 [00:44<03:24, 1.23s/it]
Epoch: [33/200] Time: 0.0min:1.2316629886627197sec Loss: 733.4759
18% | 35/200 [00:45<03:25, 1.24s/it]
Epoch: [34/200] Time: 0.0min:1.2673778533935547sec Loss: 738.8306
18%| | 36/200 [00:46<03:22, 1.23s/it]
```

```
Epoch: [35/200] Time: 0.0min:1.2034988403320312sec Loss: 754.3849
18% | 37/200 [00:48<03:22, 1.24s/it]
Epoch: [36/200] Time: 0.0min:1.2574512958526611sec Loss: 773.6418
              | 38/200 [00:49<03:20, 1.24s/it]
19%|
Epoch: [37/200] Time: 0.0min:1.239457368850708sec Loss: 808.1753
              | 39/200 [00:50<03:19, 1.24s/it]
20%|
Epoch 00039: reducing learning rate of group 0 to 1.0000e-03.
Epoch: [38/200] Time: 0.0min:1.2331323623657227sec Loss: 744.9838
20%| 40/200 [00:51<03:18, 1.24s/it]
Epoch: [39/200] Time: 0.0min:1.2376821041107178sec Loss: 667.9452
20%|
              | 41/200 [00:53<03:17, 1.24s/it]
Epoch: [40/200] Time: 0.0min:1.2439610958099365sec Loss: 660.2486
21%|
              | 42/200 [00:54<03:15, 1.24s/it]
Epoch: [41/200] Time: 0.0min:1.2295887470245361sec Loss: 659.8045
              | 43/200 [00:55<03:10, 1.21s/it]
Epoch: [42/200] Time: 0.0min:1.1564958095550537sec Loss: 648.6868
              | 44/200 [00:56<03:09, 1.22s/it]
Epoch: [43/200] Time: 0.0min:1.2186639308929443sec Loss: 654.1182
22%| 45/200 [00:57<03:09, 1.22s/it]
Epoch: [44/200] Time: 0.0min:1.232266902923584sec Loss: 651.2106
              | 46/200 [00:59<03:09, 1.23s/it]
23%|
Epoch: [45/200] Time: 0.0min:1.246570110321045sec Loss: 642.1797
              | 47/200 [01:00<03:07, 1.23s/it]
24%|
Epoch: [46/200] Time: 0.0min:1.2218456268310547sec Loss: 647.9054
24%|
              | 48/200 [01:01<03:07, 1.23s/it]
Epoch: [47/200] Time: 0.0min:1.2455973625183105sec Loss: 645.6041
     | 49/200 [01:02<03:07, 1.24s/it]
24%|
Epoch: [48/200] Time: 0.0min:1.250978946685791sec Loss: 645.4810
```

```
Epoch: [49/200] Time: 0.0min:1.2335126399993896sec Loss: 644.6602
26% | 51/200 [01:05<03:00, 1.21s/it]
Epoch: [50/200] Time: 0.0min:1.1488959789276123sec Loss: 633.2019
            | 52/200 [01:06<02:59, 1.21s/it]
26%|
Epoch: [51/200] Time: 0.0min:1.2193613052368164sec Loss: 642.2940
Epoch: [52/200] Time: 0.0min:1.1524333953857422sec Loss: 643.3905
    | 54/200 [01:08<02:56, 1.21s/it]
Epoch: [53/200] Time: 0.0min:1.2463898658752441sec Loss: 638.2942
28% | 55/200 [01:10<02:57, 1.22s/it]
Epoch: [54/200] Time: 0.0min:1.249770164489746sec Loss: 638.7918
Epoch: [55/200] Time: 0.0min:1.1641063690185547sec Loss: 635.3687
28%| | 57/200 [01:12<02:53, 1.21s/it]
Epoch: [56/200] Time: 0.0min:1.2346045970916748sec Loss: 630.6343
            | 58/200 [01:13<02:55, 1.23s/it]
29%|
Epoch: [57/200] Time: 0.0min:1.280195713043213sec Loss: 631.4443
30%| 59/200 [01:14<02:51, 1.21s/it]
Epoch: [58/200] Time: 0.0min:1.1632168292999268sec Loss: 634.2031
30%| 60/200 [01:16<02:50, 1.22s/it]
Epoch: [59/200] Time: 0.0min:1.2347464561462402sec Loss: 635.8896
30% | 61/200 [01:17<02:50, 1.23s/it]
Epoch: [60/200] Time: 0.0min:1.24119234085083sec Loss: 637.4935
31% | 62/200 [01:18<02:54, 1.27s/it]
Epoch: [61/200] Time: 0.0min:1.3556139469146729sec Loss: 636.4495
32%| | 63/200 [01:20<02:53, 1.27s/it]
Epoch: [62/200] Time: 0.0min:1.2663471698760986sec Loss: 629.4854
```

```
32%| | 64/200 [01:21<02:51, 1.26s/it]
Epoch: [63/200] Time: 0.0min:1.2514855861663818sec Loss: 621.7760
     | 65/200 [01:22<02:49, 1.25s/it]
32%||
Epoch: [64/200] Time: 0.0min:1.2316734790802002sec Loss: 631.1841
              | 66/200 [01:24<02:57, 1.33s/it]
33%|
Epoch: [65/200] Time: 0.0min:1.4961879253387451sec Loss: 623.6454
34%| | 67/200 [01:25<02:50, 1.28s/it]
Epoch: [66/200] Time: 0.0min:1.1757431030273438sec Loss: 617.7020
     | 68/200 [01:26<02:49, 1.28s/it]
Epoch: [67/200] Time: 0.0min:1.2809276580810547sec Loss: 626.8711
             | 69/200 [01:27<02:47, 1.28s/it]
Epoch: [68/200] Time: 0.0min:1.272148847579956sec Loss: 618.4045
35% | 70/200 [01:29<02:48, 1.30s/it]
Epoch: [69/200] Time: 0.0min:1.3374419212341309sec Loss: 620.0683
     | 71/200 [01:30<02:46, 1.29s/it]
36%|
Epoch: [70/200] Time: 0.0min:1.2771823406219482sec Loss: 621.6935
              | 72/200 [01:31<02:41, 1.26s/it]
36%
Epoch: [71/200] Time: 0.0min:1.1806979179382324sec Loss: 624.1589
36% | 73/200 [01:32<02:39, 1.26s/it]
Epoch 00073: reducing learning rate of group 0 to 1.0000e-04.
Epoch: [72/200] Time: 0.0min:1.2603414058685303sec Loss: 619.2128
37%| | 74/200 [01:34<02:35, 1.23s/it]
Epoch: [73/200] Time: 0.0min:1.1715710163116455sec Loss: 618.3342
              | 75/200 [01:35<02:34, 1.23s/it]
38%|
Epoch: [74/200] Time: 0.0min:1.2330801486968994sec Loss: 618.9860
     | 76/200 [01:36<02:33, 1.24s/it]
38%|
Epoch: [75/200] Time: 0.0min:1.2582175731658936sec Loss: 617.2442
              | 77/200 [01:37<02:33, 1.25s/it]
38%||
```

```
Epoch: [76/200] Time: 0.0min:1.2648401260375977sec Loss: 622.2029
39%| | 78/200 [01:39<02:34, 1.27s/it]
Epoch: [77/200] Time: 0.0min:1.3172764778137207sec Loss: 621.3791
              | 79/200 [01:40<02:30, 1.24s/it]
40%|
Epoch: [78/200] Time: 0.0min:1.1817705631256104sec Loss: 616.9208
             | 80/200 [01:41<02:30, 1.25s/it]
40%||
Epoch: [79/200] Time: 0.0min:1.280810832977295sec Loss: 617.8215
40%| 81/200 [01:42<02:29, 1.26s/it]
Epoch: [80/200] Time: 0.0min:1.260545253753662sec Loss: 617.9098
41%| 82/200 [01:44<02:25, 1.24s/it]
Epoch: [81/200] Time: 0.0min:1.190896987915039sec Loss: 619.0059
     | 83/200 [01:45<02:25, 1.24s/it]
Epoch: [82/200] Time: 0.0min:1.247424840927124sec Loss: 617.7538
42%| 84/200 [01:46<02:24, 1.25s/it]
Epoch: [83/200] Time: 0.0min:1.2659904956817627sec Loss: 609.7474
42%| | 85/200 [01:47<02:21, 1.23s/it]
Epoch: [84/200] Time: 0.0min:1.1752328872680664sec Loss: 622.2654
             | 86/200 [01:48<02:21, 1.24s/it]
43%||
Epoch: [85/200] Time: 0.0min:1.2655293941497803sec Loss: 611.3241
44%| 87/200 [01:50<02:20, 1.24s/it]
Epoch: [86/200] Time: 0.0min:1.2443408966064453sec Loss: 611.7873
44%|
     | 88/200 [01:51<02:19, 1.24s/it]
Epoch: [87/200] Time: 0.0min:1.2535600662231445sec Loss: 615.5173
44%| 89/200 [01:52<02:18, 1.25s/it]
Epoch: [88/200] Time: 0.0min:1.2641031742095947sec Loss: 615.3481
45% | 90/200 [01:53<02:15, 1.23s/it]
Epoch 00090: reducing learning rate of group 0 to 1.0000e-05.
Epoch: [89/200] Time: 0.0min:1.1922810077667236sec Loss: 614.6141
```

```
46% | 91/200 [01:55<02:15, 1.24s/it]
Epoch: [90/200] Time: 0.0min:1.258512020111084sec Loss: 612.1209
     | 92/200 [01:56<02:15, 1.26s/it]
46%||
Epoch: [91/200] Time: 0.0min:1.2929601669311523sec Loss: 618.4169
              | 93/200 [01:57<02:12, 1.24s/it]
46%|
Epoch: [92/200] Time: 0.0min:1.191450595855713sec Loss: 618.1463
47%| 94/200 [01:58<02:12, 1.25s/it]
Epoch: [93/200] Time: 0.0min:1.2623686790466309sec Loss: 616.2202
       | 95/200 [02:00<02:11, 1.26s/it]
Epoch: [94/200] Time: 0.0min:1.2806215286254883sec Loss: 616.5289
              | 96/200 [02:01<02:10, 1.26s/it]
Epoch 00096: reducing learning rate of group 0 to 1.0000e-06.
Epoch: [95/200] Time: 0.0min:1.2627439498901367sec Loss: 612.8900
     | 97/200 [02:02<02:09, 1.26s/it]
48%|
Epoch: [96/200] Time: 0.0min:1.2684576511383057sec Loss: 619.2078
49%| 98/200 [02:03<02:06, 1.24s/it]
Epoch: [97/200] Time: 0.0min:1.2002899646759033sec Loss: 616.9749
          | 99/200 [02:05<02:06, 1.25s/it]
Epoch: [98/200] Time: 0.0min:1.2572860717773438sec Loss: 616.2019
50%| | 100/200 [02:06<02:02, 1.23s/it]
Epoch: [99/200] Time: 0.0min:1.1858282089233398sec Loss: 616.4232
50% | 101/200 [02:07<02:02, 1.24s/it]
Epoch: [100/200] Time: 0.0min:1.2621114253997803sec Loss: 618.5805
              | 102/200 [02:09<02:04, 1.27s/it]
51%|
Epoch: [101/200] Time: 0.0min:1.3325812816619873sec Loss: 609.5305
              | 103/200 [02:10<02:00, 1.24s/it]
52%|
Epoch: [102/200] Time: 0.0min:1.1807615756988525sec Loss: 614.0664
              | 104/200 [02:11<02:00, 1.25s/it]
 52%|
```

```
Epoch: [103/200] Time: 0.0min:1.271183967590332sec Loss: 619.0173
     | 105/200 [02:12<01:59, 1.25s/it]
52%|
Epoch: [104/200] Time: 0.0min:1.2596302032470703sec Loss: 621.8454
             | 106/200 [02:14<01:58, 1.26s/it]
53%||
Epoch: [105/200] Time: 0.0min:1.2895183563232422sec Loss: 616.2960
54% | 107/200 [02:15<01:58, 1.27s/it]
Epoch: [106/200] Time: 0.0min:1.292299509048462sec Loss: 617.7241
     | 108/200 [02:16<01:54, 1.25s/it]
54%|
Epoch 00108: reducing learning rate of group 0 to 1.0000e-07.
Epoch: [107/200] Time: 0.0min:1.180102825164795sec Loss: 619.9808
55% | 109/200 [02:17<01:53, 1.25s/it]
Epoch: [108/200] Time: 0.0min:1.26633882522583sec Loss: 615.5437
55%| | 110/200 [02:19<01:53, 1.26s/it]
Epoch: [109/200] Time: 0.0min:1.2744576930999756sec Loss: 617.6359
     | 111/200 [02:20<01:51, 1.25s/it]
Epoch: [110/200] Time: 0.0min:1.2221360206604004sec Loss: 625.1294
 56%| | 112/200 [02:21<01:51, 1.26s/it]
Epoch: [111/200] Time: 0.0min:1.2991840839385986sec Loss: 620.8562
56% | 113/200 [02:22<01:50, 1.27s/it]
Epoch: [112/200] Time: 0.0min:1.2919750213623047sec Loss: 619.8311
57% | 114/200 [02:24<01:47, 1.25s/it]
Epoch 00114: reducing learning rate of group 0 to 1.0000e-08.
Epoch: [113/200] Time: 0.0min:1.194382905960083sec Loss: 617.9140
57% | 115/200 [02:25<01:46, 1.25s/it]
Epoch: [114/200] Time: 0.0min:1.2613825798034668sec Loss: 611.4271
58% | 116/200 [02:26<01:44, 1.24s/it]
Epoch: [115/200] Time: 0.0min:1.208559274673462sec Loss: 609.6812
58% | 117/200 [02:27<01:43, 1.25s/it]
Epoch: [116/200] Time: 0.0min:1.2710285186767578sec Loss: 620.5427
```

```
59%| | 118/200 [02:29<01:43, 1.26s/it]
Epoch: [117/200] Time: 0.0min:1.275571584701538sec Loss: 616.4275
60% | 119/200 [02:30<01:40, 1.25s/it]
Epoch: [118/200] Time: 0.0min:1.2168972492218018sec Loss: 612.9193
60% | 120/200 [02:31<01:40, 1.25s/it]
Epoch: [119/200] Time: 0.0min:1.275137186050415sec Loss: 615.4663
60%| | 121/200 [02:32<01:37, 1.24s/it]
Epoch: [120/200] Time: 0.0min:1.189347743988037sec Loss: 613.4592
     | 122/200 [02:34<01:37, 1.24s/it]
Epoch: [121/200] Time: 0.0min:1.2661890983581543sec Loss: 621.9325
62%| | 123/200 [02:35<01:37, 1.26s/it]
Epoch: [122/200] Time: 0.0min:1.2965545654296875sec Loss: 610.1649
62%| | 124/200 [02:36<01:34, 1.25s/it]
Epoch: [123/200] Time: 0.0min:1.209820032119751sec Loss: 611.1327
     | 125/200 [02:37<01:34, 1.25s/it]
62%|
Epoch: [124/200] Time: 0.0min:1.2740585803985596sec Loss: 613.5614
63%| | 126/200 [02:39<01:31, 1.24s/it]
Epoch: [125/200] Time: 0.0min:1.1975233554840088sec Loss: 613.7775
64% | 127/200 [02:40<01:31, 1.25s/it]
Epoch: [126/200] Time: 0.0min:1.2678520679473877sec Loss: 612.8349
     | 128/200 [02:41<01:30, 1.25s/it]
Epoch: [127/200] Time: 0.0min:1.2700259685516357sec Loss: 610.2138
64% | 129/200 [02:42<01:27, 1.23s/it]
Epoch: [128/200] Time: 0.0min:1.1842925548553467sec Loss: 613.6702
Epoch: [129/200] Time: 0.0min:1.256087303161621sec Loss: 614.0246
66% | 131/200 [02:45<01:24, 1.23s/it]
Epoch: [130/200] Time: 0.0min:1.1920249462127686sec Loss: 615.9255
```

```
66% | 132/200 [02:46<01:24, 1.24s/it]
Epoch: [131/200] Time: 0.0min:1.2726376056671143sec Loss: 615.3475
66% | 133/200 [02:47<01:23, 1.25s/it]
Epoch: [132/200] Time: 0.0min:1.281592845916748sec Loss: 614.8596
67% | 134/200 [02:48<01:21, 1.24s/it]
Epoch: [133/200] Time: 0.0min:1.2020447254180908sec Loss: 609.2893
68%| | 135/200 [02:50<01:21, 1.25s/it]
Epoch: [134/200] Time: 0.0min:1.2920660972595215sec Loss: 616.6820
     | 136/200 [02:51<01:20, 1.26s/it]
Epoch: [135/200] Time: 0.0min:1.2737152576446533sec Loss: 616.6149
68% | 137/200 [02:52<01:18, 1.25s/it]
Epoch: [136/200] Time: 0.0min:1.2137691974639893sec Loss: 612.7080
69%| | 138/200 [02:53<01:17, 1.25s/it]
Epoch: [137/200] Time: 0.0min:1.2582454681396484sec Loss: 612.0081
70% | 139/200 [02:55<01:16, 1.26s/it]
Epoch: [138/200] Time: 0.0min:1.288588285446167sec Loss: 618.9433
70% | 140/200 [02:56<01:14, 1.24s/it]
Epoch: [139/200] Time: 0.0min:1.2027857303619385sec Loss: 619.5169
70% | 141/200 [02:57<01:14, 1.26s/it]
Epoch: [140/200] Time: 0.0min:1.2805774211883545sec Loss: 614.6838
     | 142/200 [02:58<01:12, 1.24s/it]
Epoch: [141/200] Time: 0.0min:1.216404914855957sec Loss: 621.2365
72%| | 143/200 [03:00<01:11, 1.25s/it]
Epoch: [142/200] Time: 0.0min:1.2739450931549072sec Loss: 614.1746
72%| | 144/200 [03:01<01:10, 1.26s/it]
Epoch: [143/200] Time: 0.0min:1.2667298316955566sec Loss: 614.7372
72%| | 145/200 [03:02<01:08, 1.24s/it]
Epoch: [144/200] Time: 0.0min:1.1958401203155518sec Loss: 613.5521
```

```
73%| | 146/200 [03:03<01:07, 1.25s/it]
Epoch: [145/200] Time: 0.0min:1.2756335735321045sec Loss: 620.0312
74% | 147/200 [03:05<01:05, 1.23s/it]
Epoch: [146/200] Time: 0.0min:1.189086675643921sec Loss: 613.4095
74% | 148/200 [03:06<01:04, 1.24s/it]
Epoch: [147/200] Time: 0.0min:1.2608208656311035sec Loss: 611.6802
74% | 149/200 [03:07<01:04, 1.26s/it]
Epoch: [148/200] Time: 0.0min:1.2903704643249512sec Loss: 610.7065
          | 150/200 [03:08<01:01, 1.23s/it]
Epoch: [149/200] Time: 0.0min:1.180795669555664sec Loss: 614.5043
76% | 151/200 [03:10<01:01, 1.25s/it]
Epoch: [150/200] Time: 0.0min:1.2750194072723389sec Loss: 618.6613
76% | 152/200 [03:11<00:59, 1.24s/it]
Epoch: [151/200] Time: 0.0min:1.208871841430664sec Loss: 615.5531
76% | 153/200 [03:12<00:58, 1.24s/it]
Epoch: [152/200] Time: 0.0min:1.2607793807983398sec Loss: 618.8026
77%| | 154/200 [03:13<00:57, 1.25s/it]
Epoch: [153/200] Time: 0.0min:1.2771086692810059sec Loss: 612.3008
78%| | 155/200 [03:15<00:55, 1.24s/it]
Epoch: [154/200] Time: 0.0min:1.19342041015625sec Loss: 608.3020
     | 156/200 [03:16<00:55, 1.25s/it]
Epoch: [155/200] Time: 0.0min:1.284383773803711sec Loss: 613.3276
78%| | 157/200 [03:17<00:53, 1.23s/it]
Epoch: [156/200] Time: 0.0min:1.194223403930664sec Loss: 613.6167
79%| | 158/200 [03:18<00:52, 1.25s/it]
Epoch: [157/200] Time: 0.0min:1.294665813446045sec Loss: 614.4694
80% | 159/200 [03:20<00:51, 1.26s/it]
Epoch: [158/200] Time: 0.0min:1.2826769351959229sec Loss: 617.3578
```

```
80% | 160/200 [03:21<00:49, 1.24s/it]
Epoch: [159/200] Time: 0.0min:1.2001335620880127sec Loss: 613.7005
80%| | | 161/200 [03:22<00:48, 1.25s/it]
Epoch: [160/200] Time: 0.0min:1.2689824104309082sec Loss: 612.4003
81%| | 162/200 [03:23<00:47, 1.25s/it]
Epoch: [161/200] Time: 0.0min:1.2610793113708496sec Loss: 612.9127
82%| | 163/200 [03:25<00:45, 1.24s/it]
Epoch: [162/200] Time: 0.0min:1.1948082447052002sec Loss: 607.1605
           | 164/200 [03:26<00:44, 1.25s/it]
Epoch: [163/200] Time: 0.0min:1.269695520401001sec Loss: 611.4056
82%| | 165/200 [03:27<00:44, 1.26s/it]
Epoch: [164/200] Time: 0.0min:1.2906053066253662sec Loss: 611.5633
83%| | 166/200 [03:28<00:42, 1.24s/it]
Epoch: [165/200] Time: 0.0min:1.1914258003234863sec Loss: 612.7163
84%| | 167/200 [03:30<00:41, 1.25s/it]
Epoch: [166/200] Time: 0.0min:1.259981632232666sec Loss: 607.3486
84% | 168/200 [03:31<00:39, 1.23s/it]
Epoch: [167/200] Time: 0.0min:1.2021129131317139sec Loss: 614.8322
84% | 169/200 [03:32<00:38, 1.25s/it]
Epoch: [168/200] Time: 0.0min:1.2756996154785156sec Loss: 613.8027
     | 170/200 [03:33<00:37, 1.26s/it]
Epoch: [169/200] Time: 0.0min:1.2963371276855469sec Loss: 613.7630
86% | 171/200 [03:35<00:36, 1.24s/it]
Epoch: [170/200] Time: 0.0min:1.2007877826690674sec Loss: 613.8788
86%| | | 172/200 [03:36<00:35, 1.27s/it]
Epoch: [171/200] Time: 0.0min:1.3250515460968018sec Loss: 614.8392
86% | 173/200 [03:37<00:33, 1.25s/it]
Epoch: [172/200] Time: 0.0min:1.2029712200164795sec Loss: 612.0630
```

```
87%| | 174/200 [03:38<00:32, 1.26s/it]
Epoch: [173/200] Time: 0.0min:1.2853710651397705sec Loss: 614.6591
     | 175/200 [03:40<00:31, 1.27s/it]
Epoch: [174/200] Time: 0.0min:1.2880525588989258sec Loss: 616.9437
88%| | 176/200 [03:41<00:30, 1.25s/it]
Epoch: [175/200] Time: 0.0min:1.218247413635254sec Loss: 620.9437
88%| | 177/200 [03:42<00:28, 1.26s/it]
Epoch: [176/200] Time: 0.0min:1.2749018669128418sec Loss: 613.2409
           | 178/200 [03:43<00:27, 1.24s/it]
Epoch: [177/200] Time: 0.0min:1.1932368278503418sec Loss: 621.3762
90%| | | 179/200 [03:45<00:26, 1.25s/it]
Epoch: [178/200] Time: 0.0min:1.2731056213378906sec Loss: 616.2659
90% | 180/200 [03:46<00:25, 1.26s/it]
Epoch: [179/200] Time: 0.0min:1.274886131286621sec Loss: 613.5072
     | 181/200 [03:47<00:23, 1.24s/it]
90%1
Epoch: [180/200] Time: 0.0min:1.2103054523468018sec Loss: 608.7015
91%| | 182/200 [03:48<00:22, 1.25s/it]
Epoch: [181/200] Time: 0.0min:1.2693488597869873sec Loss: 613.7120
92%| | 183/200 [03:50<00:21, 1.24s/it]
Epoch: [182/200] Time: 0.0min:1.2000627517700195sec Loss: 615.2912
     | 184/200 [03:51<00:19, 1.25s/it]
Epoch: [183/200] Time: 0.0min:1.274472951889038sec Loss: 609.5386
92%| | 185/200 [03:52<00:18, 1.26s/it]
Epoch: [184/200] Time: 0.0min:1.2741096019744873sec Loss: 612.5787
93%| | | 186/200 [03:53<00:17, 1.24s/it]
Epoch: [185/200] Time: 0.0min:1.1945104598999023sec Loss: 609.6553
94%| | 187/200 [03:55<00:16, 1.25s/it]
Epoch: [186/200] Time: 0.0min:1.2710340023040771sec Loss: 615.0568
```

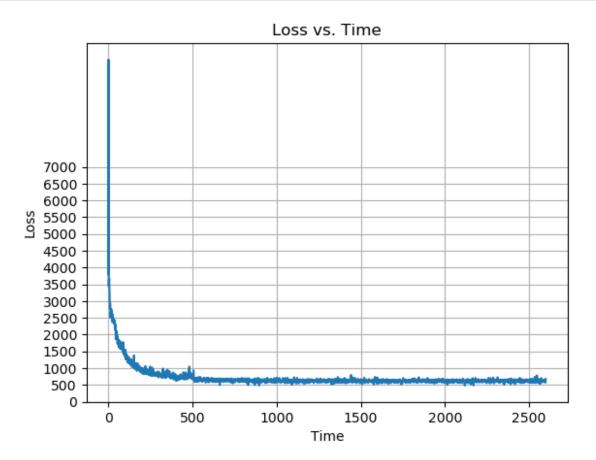
```
94%| | 188/200 [03:56<00:15, 1.26s/it]
Epoch: [187/200] Time: 0.0min:1.3022384643554688sec Loss: 612.7276
94%| | 189/200 [03:57<00:13, 1.26s/it]
Epoch: [188/200] Time: 0.0min:1.2380948066711426sec Loss: 618.1464
95%| | 190/200 [03:58<00:12, 1.26s/it]
Epoch: [189/200] Time: 0.0min:1.2701866626739502sec Loss: 616.8546
96% | 191/200 [04:00<00:11, 1.26s/it]
Epoch: [190/200] Time: 0.0min:1.2644097805023193sec Loss: 616.1155
            | 192/200 [04:01<00:10, 1.25s/it]
Epoch: [191/200] Time: 0.0min:1.228109359741211sec Loss: 614.6650
96% | 193/200 [04:02<00:08, 1.26s/it]
Epoch: [192/200] Time: 0.0min:1.2798347473144531sec Loss: 611.7037
97%| | 194/200 [04:03<00:07, 1.25s/it]
Epoch: [193/200] Time: 0.0min:1.2216136455535889sec Loss: 615.1479
     | 195/200 [04:05<00:06, 1.25s/it]
98%1
Epoch: [194/200] Time: 0.0min:1.2583420276641846sec Loss: 622.1304
98%| | 196/200 [04:06<00:05, 1.26s/it]
Epoch: [195/200] Time: 0.0min:1.269775629043579sec Loss: 624.3564
98%| | 197/200 [04:07<00:03, 1.24s/it]
Epoch: [196/200] Time: 0.0min:1.201889991760254sec Loss: 614.1582
     | 198/200 [04:08<00:02, 1.25s/it]
Epoch: [197/200] Time: 0.0min:1.2705137729644775sec Loss: 619.8682
100%| 199/200 [04:10<00:01, 1.24s/it]
Epoch: [198/200] Time: 0.0min:1.1991171836853027sec Loss: 615.3322
100% | 200/200 [04:11<00:00, 1.26s/it]
Epoch: [199/200] Time: 0.0min:1.2618074417114258sec Loss: 618.4857
```

del net

Question 4: Plot loss over time (20 points)

For this part, plot your loss from training the model.

```
### TODO: make plot of reconstruction loss (y-axis) over training time
(x-axis)
time intervals = list(range(len(losses)))
# plt.figure(figsize=(10, 6))
plt.plot(time intervals, losses)
plt.title('Loss vs. Time')
plt.xlabel('Time')
plt.ylabel('Loss')
# plt.ylim(0, 7000) # Adjust the values as needed
# plt.grid(True)
# plt.show()
custom_y_ticks = [0, 500, 1000, 1500, 2000, 2500, 3000, 3500, 4000,
4500, 5000, 5500, 6000, 6500, 7000] # Define your custom y-axis tick
values
plt.yticks(custom_y_ticks)
plt.grid(True)
plt.show()
```



Evaluation

Question 5: Reconstruct whole image (20 points)

For this part, reconstruct the image using your model's outputs, at each coordinate. You can use our scaffolding code, or write your own. For this part, we are just grading the image plot, where you should plot the original image side-by-side with the reconstruction, as shown in this example.

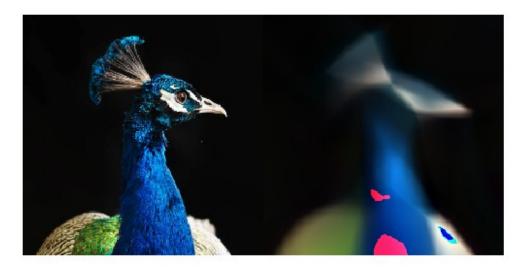


```
### TODO: ~12 lines of code to assemble gt image, build pred image
###
          from model
#evaluation
# load dataset
dataset = SingleImageDataset('/home/mayank/828i/HW2/mypeacock.jpg')
dataloader = DataLoader(dataset, batch size=1024,shuffle=False)
ground truth image =
torch.zeros((dataset.h,dataset.w,3),dtype=torch.uint8)
predicted image = torch.zeros like(ground truth image)
net.eval()
for batch in dataloader:
    position x, positiony, intensity = batch["x"], batch["y"],
batch["intensity"]
    x = position x.to(device)
    y = positiony.to(device)
    #normalize 0 to 1
    x = x / dataset.w
    y = y / dataset.h
    coord = torch.vstack([x,y]).T
```

```
pred = net(coord)
#detach torch to numpy
x = position_x.detach().numpy()
y = positiony.detach().numpy()
intensity = intensity.detach()
pred_intensity = pred.type(torch.uint8).cpu().detach()
#assign intensity to x,y positionsi., x,y to rgb
for idx, (y1, x1) in enumerate(zip(y,x)):
    ground_truth_image[y1,x1,:] = intensity[idx]
    predicted_image[y1,x1,:] = pred_intensity[idx]

concat_image = torch.cat([ground_truth_image, predicted_image], dim=1)
plt.imshow(concat_image)
plt.axis('off')

(-0.5, 447.5, 223.5, -0.5)
```



Question 6: Compute PSNR (10 points)

For this part, print the PSNR for your reconstruction vs. the original image. Feel free to use any libraries, or implement it from scratch.

```
### TODO: compute and print PSNR between reconstructed (predicted) and
ground truth images
import numpy as np

def psnr(ground_truth_image, pred_image):
    # Ensure the input images have the same shape and data type
    if ground_truth_image.shape != pred_image.shape:
        raise ValueError("Input images must have the same shape")

# Calculate the mean squared error (MSE)
    # mse = np.mean((ground_truth_image - pred_image) ** 2)
```

```
mse red channel = np.mean((ground truth image[:, :, 0] -
pred image[:, :, 0])**2)
    mse green channel = np.mean((ground truth image[:, :, 1] -
pred image[:, :, 1])**2)
    mse_blue_channel = np.mean((ground_truth image[:, :, 2] -
pred image[:, :, 2])**2)
    # Maximum possible pixel value (assumes pixel values are in the
range [0, 255])
    max pixel value = 255.0
    mse=mse red channel+mse green channel+mse blue channel
    # Calculate PSNR
    if mse == 0:
        return float('inf')
    psnr value = 20 * np.log10(max pixel value / np.sqrt(mse))
    return psnr_value
ground truth = ground truth image.numpy()
predict = predicted image.numpy()
psnr value = psnr(ground truth, predict)
print("PSNR value: ", psnr_value)
PSNR value: 27.742275863610462
```

Question 7: Outpainting (10 points)

INR is a continuous image representation. What happens if your input coordinates don't correspond to real pixels? Try it out and show the result!

For this part, have your model predict 20 pixels in all directions that are outside the boundaries of the original image, and show the resulting image below. Also plot a box around the region corresponding to the original image, for clarity.

We show an example below.



```
import matplotlib.patches as patches

### TODO: 6-10 lines of code to generate outpainted image

height, width = dataset.h, dataset.w
outpaint_pix = 20
outpainted_image = np.pad(np.zeros((height, width, 3),
dtype=np.uint8), ((outpaint_pix, outpaint_pix), (outpaint_pix,
outpaint_pix), (0, 0)), mode="constant")

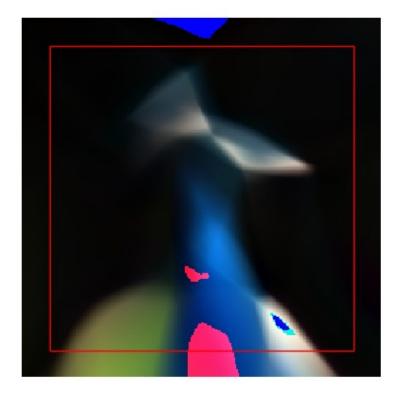
net.eval()
with torch.no_grad():
    for i in range(-outpaint_pix, height + outpaint_pix):
        coords = []
    for j in range(-outpaint_pix, width + outpaint_pix):
        y = torch.tensor(i / height).to(device)
        x = torch.tensor(j / width).to(device)
        coords.append([x, y])
```

```
cat = torch.tensor(coords).float().to(device)
    pred = net(cat).type(torch.uint8).cpu().detach().numpy()

for k in range(pred.shape[0]):
    outpainted_image[i + outpaint_pix, k] = pred[k]

fig, ax = plt.subplots()
ax.imshow(outpainted_image)

rect = patches.Rectangle((20, 20), dataset.w, dataset.h,
linewidth=1,edgecolor='r', facecolor='none')
ax.add_patch(rect)
plt.axis('off')
plt.show()
```



Bonus

The main idea of the bonus is to do something to make your model better than the one we walk you through in the assignment. Be creative! You can receive a maximum of 20 points for this portion.

Question 8: Improve the Reconstruction Quality of the System (20 points, optional)

For this question, you must do two things:

- Make a non-trivial change from what we guided you through in the assignment.
- 2. Prove that the change improves reconstruction quality. Compare your new output/PSNR to the old output/PSNR (plot the images, print the PSNR).

If you can't think of your own idea, revisit some of the literature from Shishira's guest lectures. For example, instead of taking raw coordinate inputs, you could try using positional encodings.

```
### TODO: bonus
import math
def pose encod(B, x):
        #postional feature mapping of input
        X_proj= 2 * torch.pi * torch.matmul(x, B.T)
        cos = torch.cos(X proj)
        sin = torch.sin(X proj)
        out=torch.cat([cos, sin], dim=-1)
        return out
dataset = SingleImageDataset('/home/mayank/828i/HW2/mypeacock.jpg')
dataloader = DataLoader(dataset, batch size=4096,shuffle=False)
m = 100
B = 10*torch.randn(m, 2).to(device)
new network=FFN(number input=m * 2)
new network=new network.to(device)
criterion = torch.nn.MSELoss()
### TODO: 2 lines of code for optimizer, number of epochs
optimizer = torch.optim.Adam(new network.parameters(), lr=1e-3)
#Reduce learning rate when a metric has stopped improving
scheduler = ReduceLROnPlateau(optimizer, factor=0.1, patience=5,
verbose=True)
NUM EPOCHS = 200
losses=[]
### TODO: set up mechanism for storing loss values
for epoch in tqdm(range(NUM EPOCHS)):
      starting time = time.time()
      list losses = []
      running_corrects=0
      n \text{ sample} = 0
      for batch in dataloader:
            x, y, actual = batch["x"], batch["y"], batch["intensity"]
            #USIng GPU so moving data to device
            x = x.to(device)
            y = y.to(device)
            actual = actual.float().to(device)
            #normalize from 0 to 1
            x = x / dataset.w
            y = y / dataset.h
            ### TODO: 3 lines of code to assemble coord from x and y,
pass to net,
                      compute loss
```

```
coord =torch.vstack([x, y]).T
            positional coord=pose encod(B,coord)
           pred = new network(positional coord)
            loss =criterion(pred, actual)
            list losses.append(loss.item())
           optimizer.zero grad()
            loss.backward()
           optimizer.step()
           ### TODO: track loss
           losses.append(loss.item())
     # data.set description(f'Epoch [{epoch}/{NUM EPOCHS}]')
     # data.set postfix(acc=(running corrects/n sample).item())
      average loss = sum(list losses)/len(list losses)
      scheduler.step(average loss)
      time_diff = time.time() - starting_time
      print("Epoch: [{}/{}] Time: {}min:{}sec Loss:
{:.4f}".format(epoch, NUM EPOCHS, time diff//60, time diff%60,
average loss))
  0% | 0/200 [00:00<?, ?it/s]
        | 1/200 [00:01<05:46, 1.74s/it]
  0%|
Epoch: [0/200] Time: 0.0min:1.7427978515625sec Loss: 2974.4811
              | 2/200 [00:03<05:16, 1.60s/it]
  1%|
Epoch: [1/200] Time: 0.0min:1.4982709884643555sec Loss: 3275.1451
       | 3/200 [00:04<04:58, 1.51s/it]
Epoch: [2/200] Time: 0.0min:1.4089415073394775sec Loss: 3150.8341
  2%||
        | 4/200 [00:06<04:57, 1.52s/it]
Epoch: [3/200] Time: 0.0min:1.5246145725250244sec Loss: 2635.3795
  2%|
               | 5/200 [00:07<04:55, 1.52s/it]
Epoch: [4/200] Time: 0.0min:1.5162413120269775sec Loss: 2682.4155
  3%||
               | 6/200 [00:08<04:38, 1.43s/it]
Epoch: [5/200] Time: 0.0min:1.269592046737671sec Loss: 2348.7221
 4%||
              | 7/200 [00:10<04:29, 1.39s/it]
Epoch: [6/200] Time: 0.0min:1.3126013278961182sec Loss: 2303.3206
               | 8/200 [00:11<04:17, 1.34s/it]
  4%|
```

```
Epoch: [7/200] Time: 0.0min:1.2222528457641602sec Loss: 2160.1987
 4%| | 9/200 [00:12<04:13, 1.33s/it]
Epoch: [8/200] Time: 0.0min:1.3060693740844727sec Loss: 2071.4505
 5%| | 10/200 [00:14<04:13, 1.33s/it]
Epoch: [9/200] Time: 0.0min:1.3406195640563965sec Loss: 1956.5598
 6%| | 11/200 [00:15<04:04, 1.30s/it]
Epoch: [10/200] Time: 0.0min:1.209822177886963sec Loss: 1826.1366
 6%| | 12/200 [00:16<04:03, 1.30s/it]
Epoch: [11/200] Time: 0.0min:1.3009254932403564sec Loss: 1662.6300
 6%| | 13/200 [00:17<04:02, 1.30s/it]
Epoch: [12/200] Time: 0.0min:1.2903878688812256sec Loss: 1448.4232
 7%| | 14/200 [00:19<03:58, 1.28s/it]
Epoch: [13/200] Time: 0.0min:1.246321678161621sec Loss: 1191.3132
 8%| | | 15/200 [00:20<03:58, 1.29s/it]
Epoch: [14/200] Time: 0.0min:1.31614089012146sec Loss: 925.5438
 8%| | 16/200 [00:21<03:54, 1.27s/it]
Epoch: [15/200] Time: 0.0min:1.2319741249084473sec Loss: 765.7896
 8%| | 17/200 [00:23<03:54, 1.28s/it]
Epoch: [16/200] Time: 0.0min:1.299997329711914sec Loss: 740.4243
 9%| | 18/200 [00:24<03:55, 1.29s/it]
Epoch: [17/200] Time: 0.0min:1.3227298259735107sec Loss: 891.2215
10%| | 19/200 [00:25<03:51, 1.28s/it]
Epoch: [18/200] Time: 0.0min:1.2356178760528564sec Loss: 919.8187
10%| | 20/200 [00:26<03:51, 1.29s/it]
Epoch: [19/200] Time: 0.0min:1.3053998947143555sec Loss: 2099.5597
10% | 21/200 [00:28<03:47, 1.27s/it]
Epoch: [20/200] Time: 0.0min:1.2342610359191895sec Loss: 1208.6805
11%| | 22/200 [00:29<03:49, 1.29s/it]
```

```
Epoch: [21/200] Time: 0.0min:1.3338801860809326sec Loss: 1600.8677
12%| | 23/200 [00:30<03:48, 1.29s/it]
Epoch 00023: reducing learning rate of group 0 to 1.0000e-04.
Epoch: [22/200] Time: 0.0min:1.2978122234344482sec Loss: 803.4293
12%| | 24/200 [00:31<03:42, 1.27s/it]
Epoch: [23/200] Time: 0.0min:1.2030253410339355sec Loss: 700.4204
12%| | 25/200 [00:33<03:43, 1.28s/it]
Epoch: [24/200] Time: 0.0min:1.2987799644470215sec Loss: 674.5855
13%| | 26/200 [00:34<03:38, 1.25s/it]
Epoch: [25/200] Time: 0.0min:1.1992027759552002sec Loss: 655.6775
              | 27/200 [00:35<03:39, 1.27s/it]
14%|
Epoch: [26/200] Time: 0.0min:1.30946683883667sec Loss: 647.0213
             | 28/200 [00:37<03:39, 1.27s/it]
14%|
Epoch: [27/200] Time: 0.0min:1.2801744937896729sec Loss: 640.5992
14%| | 29/200 [00:38<03:35, 1.26s/it]
Epoch: [28/200] Time: 0.0min:1.2325730323791504sec Loss: 634.7182
             | 30/200 [00:39<03:37, 1.28s/it]
 15%||
Epoch: [29/200] Time: 0.0min:1.316725492477417sec Loss: 629.5478
16% | 31/200 [00:40<03:37, 1.29s/it]
Epoch: [30/200] Time: 0.0min:1.3098535537719727sec Loss: 624.9704
16%| | 32/200 [00:42<03:33, 1.27s/it]
Epoch: [31/200] Time: 0.0min:1.2290334701538086sec Loss: 620.8535
              | 33/200 [00:43<03:33, 1.28s/it]
16%|
Epoch: [32/200] Time: 0.0min:1.298947811126709sec Loss: 617.1147
17%|
              | 34/200 [00:44<03:29, 1.26s/it]
Epoch: [33/200] Time: 0.0min:1.2183387279510498sec Loss: 613.6894
18%| | 35/200 [00:46<03:31, 1.28s/it]
Epoch: [34/200] Time: 0.0min:1.3245604038238525sec Loss: 610.5249
```

```
Epoch: [35/200] Time: 0.0min:1.286987543106079sec Loss: 607.5801
18%| | 37/200 [00:48<03:26, 1.27s/it]
Epoch: [36/200] Time: 0.0min:1.2354052066802979sec Loss: 604.8224
19%| | 38/200 [00:49<03:27, 1.28s/it]
Epoch: [37/200] Time: 0.0min:1.3098139762878418sec Loss: 602.2205
20%| | 39/200 [00:51<03:28, 1.29s/it]
Epoch: [38/200] Time: 0.0min:1.3237278461456299sec Loss: 599.7540
     | 40/200 [00:52<03:24, 1.28s/it]
Epoch: [39/200] Time: 0.0min:1.2301316261291504sec Loss: 597.4043
20% | 41/200 [00:53<03:23, 1.28s/it]
Epoch: [40/200] Time: 0.0min:1.2861499786376953sec Loss: 595.1591
21% | 42/200 [00:54<03:19, 1.26s/it]
Epoch: [41/200] Time: 0.0min:1.2208385467529297sec Loss: 593.0094
22%| | 43/200 [00:56<03:19, 1.27s/it]
Epoch: [42/200] Time: 0.0min:1.292262077331543sec Loss: 590.9369
             | 44/200 [00:57<03:19, 1.28s/it]
22%||
Epoch: [43/200] Time: 0.0min:1.2922043800354004sec Loss: 588.9257
22%| 45/200 [00:58<03:15, 1.26s/it]
Epoch: [44/200] Time: 0.0min:1.2132360935211182sec Loss: 586.9665
    | 46/200 [01:00<03:16, 1.27s/it]
23%|
Epoch: [45/200] Time: 0.0min:1.3101844787597656sec Loss: 585.0463
24% | 47/200 [01:01<03:12, 1.26s/it]
Epoch: [46/200] Time: 0.0min:1.2220079898834229sec Loss: 583.1513
24% | 48/200 [01:02<03:14, 1.28s/it]
Epoch: [47/200] Time: 0.0min:1.3253684043884277sec Loss: 581.2780
24%| 49/200 [01:03<03:15, 1.29s/it]
Epoch: [48/200] Time: 0.0min:1.3240361213684082sec Loss: 579.4236
```

```
Epoch: [49/200] Time: 0.0min:1.2304840087890625sec Loss: 577.5861
26% | 51/200 [01:06<03:10, 1.28s/it]
Epoch: [50/200] Time: 0.0min:1.2955341339111328sec Loss: 575.7548
            | 52/200 [01:07<03:06, 1.26s/it]
26%|
Epoch: [51/200] Time: 0.0min:1.2179217338562012sec Loss: 573.9266
Epoch: [52/200] Time: 0.0min:1.3382611274719238sec Loss: 572.0996
    | 54/200 [01:10<03:08, 1.29s/it]
Epoch: [53/200] Time: 0.0min:1.3149540424346924sec Loss: 570.2718
28% | 55/200 [01:11<03:05, 1.28s/it]
Epoch: [54/200] Time: 0.0min:1.2326421737670898sec Loss: 568.4394
Epoch: [55/200] Time: 0.0min:1.3083839416503906sec Loss: 566.5980
28%| | 57/200 [01:14<03:04, 1.29s/it]
Epoch: [56/200] Time: 0.0min:1.3020331859588623sec Loss: 564.7445
            | 58/200 [01:15<03:00, 1.27s/it]
29%|
Epoch: [57/200] Time: 0.0min:1.2339701652526855sec Loss: 562.8739
30%| 59/200 [01:16<03:00, 1.28s/it]
Epoch: [58/200] Time: 0.0min:1.2904515266418457sec Loss: 560.9832
30% | 60/200 [01:17<02:58, 1.27s/it]
Epoch: [59/200] Time: 0.0min:1.2544572353363037sec Loss: 559.0688
30% | 61/200 [01:19<02:58, 1.28s/it]
Epoch: [60/200] Time: 0.0min:1.3080344200134277sec Loss: 557.1261
31% | 62/200 [01:20<02:57, 1.29s/it]
Epoch: [61/200] Time: 0.0min:1.303426742553711sec Loss: 555.1502
32%| | 63/200 [01:21<02:54, 1.27s/it]
Epoch: [62/200] Time: 0.0min:1.2301275730133057sec Loss: 553.1372
```

```
32%| 64/200 [01:23<02:54, 1.28s/it]
Epoch: [63/200] Time: 0.0min:1.3126389980316162sec Loss: 551.0828
     | 65/200 [01:24<02:54, 1.29s/it]
32%||
Epoch: [64/200] Time: 0.0min:1.3059072494506836sec Loss: 548.9819
Epoch: [65/200] Time: 0.0min:1.2102551460266113sec Loss: 546.8299
34%| | 67/200 [01:26<02:49, 1.27s/it]
Epoch: [66/200] Time: 0.0min:1.2883317470550537sec Loss: 544.6213
     | 68/200 [01:28<02:46, 1.26s/it]
Epoch: [67/200] Time: 0.0min:1.221069097518921sec Loss: 542.3493
34% | 69/200 [01:29<02:46, 1.27s/it]
Epoch: [68/200] Time: 0.0min:1.2906253337860107sec Loss: 540.0037
35%| 70/200 [01:30<02:46, 1.28s/it]
Epoch: [69/200] Time: 0.0min:1.301523208618164sec Loss: 537.5840
36%| 71/200 [01:31<02:42, 1.26s/it]
Epoch: [70/200] Time: 0.0min:1.2139546871185303sec Loss: 535.0850
             | 72/200 [01:33<02:42, 1.27s/it]
36%|
Epoch: [71/200] Time: 0.0min:1.297961950302124sec Loss: 532.5001
36%| 73/200 [01:34<02:39, 1.25s/it]
Epoch: [72/200] Time: 0.0min:1.2153141498565674sec Loss: 529.8231
37%| | 74/200 [01:35<02:41, 1.28s/it]
Epoch: [73/200] Time: 0.0min:1.3392670154571533sec Loss: 527.0457
38%| | 75/200 [01:37<02:40, 1.28s/it]
Epoch: [74/200] Time: 0.0min:1.2885029315948486sec Loss: 524.1603
38%| 76/200 [01:38<02:36, 1.26s/it]
Epoch: [75/200] Time: 0.0min:1.213299036026001sec Loss: 521.1585
38%| | 77/200 [01:39<02:36, 1.27s/it]
Epoch: [76/200] Time: 0.0min:1.2874870300292969sec Loss: 518.0323
```

```
39%| | 78/200 [01:40<02:33, 1.26s/it]
Epoch: [77/200] Time: 0.0min:1.2262697219848633sec Loss: 514.7722
40%| | 79/200 [01:42<02:35, 1.28s/it]
Epoch: [78/200] Time: 0.0min:1.3421630859375sec Loss: 511.3680
40%| 80/200 [01:43<02:33, 1.28s/it]
Epoch: [79/200] Time: 0.0min:1.275651216506958sec Loss: 507.8085
40% | 81/200 [01:44<02:29, 1.26s/it]
Epoch: [80/200] Time: 0.0min:1.2079830169677734sec Loss: 504.0798
     | 82/200 [01:45<02:29, 1.27s/it]
Epoch: [81/200] Time: 0.0min:1.2913694381713867sec Loss: 500.1639
42%| 83/200 [01:47<02:29, 1.28s/it]
Epoch: [82/200] Time: 0.0min:1.302267074584961sec Loss: 496.0573
42%| 84/200 [01:48<02:26, 1.26s/it]
Epoch: [83/200] Time: 0.0min:1.218324899673462sec Loss: 491.7439
42%| 85/200 [01:49<02:26, 1.27s/it]
Epoch: [84/200] Time: 0.0min:1.288139820098877sec Loss: 487.2058
43%| 86/200 [01:50<02:22, 1.25s/it]
Epoch: [85/200] Time: 0.0min:1.2076430320739746sec Loss: 482.4234
44%| 87/200 [01:52<02:22, 1.26s/it]
Epoch: [86/200] Time: 0.0min:1.2709119319915771sec Loss: 477.3794
44%| 88/200 [01:53<02:21, 1.27s/it]
Epoch: [87/200] Time: 0.0min:1.290390968322754sec Loss: 472.0588
44%| 89/200 [01:54<02:18, 1.25s/it]
Epoch: [88/200] Time: 0.0min:1.210803747177124sec Loss: 466.4487
45%| 90/200 [01:56<02:19, 1.27s/it]
Epoch: [89/200] Time: 0.0min:1.3170347213745117sec Loss: 460.5393
46% | 91/200 [01:57<02:19, 1.28s/it]
Epoch: [90/200] Time: 0.0min:1.2973730564117432sec Loss: 454.3201
```

```
46%| 92/200 [01:58<02:16, 1.26s/it]
Epoch: [91/200] Time: 0.0min:1.2177796363830566sec Loss: 447.7756
46%| 93/200 [01:59<02:15, 1.26s/it]
Epoch: [92/200] Time: 0.0min:1.264754056930542sec Loss: 440.8761
47% | 94/200 [02:01<02:11, 1.24s/it]
Epoch: [93/200] Time: 0.0min:1.1998379230499268sec Loss: 433.1580
48%| 95/200 [02:02<02:11, 1.26s/it]
Epoch: [94/200] Time: 0.0min:1.2827372550964355sec Loss: 424.3900
     | 96/200 [02:03<02:12, 1.27s/it]
Epoch: [95/200] Time: 0.0min:1.3066127300262451sec Loss: 415.3480
48%| 97/200 [02:04<02:09, 1.26s/it]
Epoch: [96/200] Time: 0.0min:1.2191822528839111sec Loss: 406.2955
49% | 98/200 [02:06<02:08, 1.26s/it]
Epoch: [97/200] Time: 0.0min:1.2744534015655518sec Loss: 396.4900
50% | 99/200 [02:07<02:06, 1.25s/it]
Epoch: [98/200] Time: 0.0min:1.2282438278198242sec Loss: 385.6978
50% | 100/200 [02:08<02:11, 1.31s/it]
Epoch: [99/200] Time: 0.0min:1.4474236965179443sec Loss: 374.2854
50% | 101/200 [02:10<02:09, 1.31s/it]
Epoch: [100/200] Time: 0.0min:1.2903926372528076sec Loss: 363.0812
51% | 102/200 [02:11<02:04, 1.27s/it]
Epoch: [101/200] Time: 0.0min:1.2009873390197754sec Loss: 352.1802
52%| | 103/200 [02:12<02:03, 1.28s/it]
Epoch: [102/200] Time: 0.0min:1.282956600189209sec Loss: 341.0694
52%| | 104/200 [02:13<02:00, 1.25s/it]
Epoch: [103/200] Time: 0.0min:1.1934986114501953sec Loss: 330.1079
52%| | 105/200 [02:15<01:59, 1.26s/it]
Epoch: [104/200] Time: 0.0min:1.2709932327270508sec Loss: 319.3910
```

```
53%| | 106/200 [02:16<01:59, 1.27s/it]
Epoch: [105/200] Time: 0.0min:1.3101913928985596sec Loss: 308.6783
 54%| | 107/200 [02:17<01:56, 1.25s/it]
Epoch: [106/200] Time: 0.0min:1.205622673034668sec Loss: 298.7600
54% | 108/200 [02:18<01:57, 1.28s/it]
Epoch: [107/200] Time: 0.0min:1.3337504863739014sec Loss: 289.7524
55% | 109/200 [02:20<01:56, 1.28s/it]
Epoch: [108/200] Time: 0.0min:1.2871501445770264sec Loss: 281.5399
     | 110/200 [02:21<01:53, 1.26s/it]
Epoch: [109/200] Time: 0.0min:1.2137336730957031sec Loss: 273.9535
 56%| | 111/200 [02:22<01:52, 1.26s/it]
Epoch: [110/200] Time: 0.0min:1.2632184028625488sec Loss: 267.0121
56% | 112/200 [02:23<01:49, 1.24s/it]
Epoch: [111/200] Time: 0.0min:1.1973202228546143sec Loss: 260.7129
56% | 113/200 [02:25<01:49, 1.26s/it]
Epoch: [112/200] Time: 0.0min:1.2861385345458984sec Loss: 255.0085
57% | 114/200 [02:26<01:48, 1.26s/it]
Epoch: [113/200] Time: 0.0min:1.2689950466156006sec Loss: 249.8469
57% | 115/200 [02:27<01:45, 1.24s/it]
Epoch: [114/200] Time: 0.0min:1.18387770652771sec Loss: 245.1734
     | 116/200 [02:28<01:44, 1.25s/it]
Epoch: [115/200] Time: 0.0min:1.2724099159240723sec Loss: 240.9404
58% | 117/200 [02:30<01:44, 1.26s/it]
Epoch: [116/200] Time: 0.0min:1.27262544631958sec Loss: 237.0801
 59%| | | 118/200 [02:31<01:41, 1.24s/it]
Epoch: [117/200] Time: 0.0min:1.2056198120117188sec Loss: 233.5669
60% | 119/200 [02:32<01:44, 1.30s/it]
Epoch: [118/200] Time: 0.0min:1.4205844402313232sec Loss: 230.3337
```

```
60%| | 120/200 [02:34<01:42, 1.28s/it]
Epoch: [119/200] Time: 0.0min:1.2375364303588867sec Loss: 227.3694
60% | 121/200 [02:35<01:40, 1.28s/it]
Epoch: [120/200] Time: 0.0min:1.273167371749878sec Loss: 224.6187
61% | 122/200 [02:36<01:39, 1.28s/it]
Epoch: [121/200] Time: 0.0min:1.2741751670837402sec Loss: 222.0650
62%| | 123/200 [02:37<01:36, 1.26s/it]
Epoch: [122/200] Time: 0.0min:1.2145836353302002sec Loss: 219.6846
     | 124/200 [02:39<01:36, 1.27s/it]
Epoch: [123/200] Time: 0.0min:1.2964820861816406sec Loss: 217.4476
62%| | 125/200 [02:40<01:33, 1.25s/it]
Epoch: [124/200] Time: 0.0min:1.2019431591033936sec Loss: 215.3519
63%| | 126/200 [02:41<01:35, 1.29s/it]
Epoch: [125/200] Time: 0.0min:1.3886723518371582sec Loss: 213.3714
     | 127/200 [02:42<01:34, 1.29s/it]
64%1
Epoch: [126/200] Time: 0.0min:1.2843408584594727sec Loss: 211.5021
64% | 128/200 [02:44<01:30, 1.26s/it]
Epoch: [127/200] Time: 0.0min:1.1940488815307617sec Loss: 209.7258
64% | 129/200 [02:45<01:29, 1.27s/it]
Epoch: [128/200] Time: 0.0min:1.2729334831237793sec Loss: 208.0366
     | 130/200 [02:46<01:27, 1.25s/it]
Epoch: [129/200] Time: 0.0min:1.2024734020233154sec Loss: 206.4273
66% | 131/200 [02:48<01:28, 1.29s/it]
Epoch: [130/200] Time: 0.0min:1.3891565799713135sec Loss: 204.8873
66% | 132/200 [02:49<01:27, 1.29s/it]
Epoch: [131/200] Time: 0.0min:1.2866888046264648sec Loss: 203.4128
66% | 133/200 [02:50<01:24, 1.26s/it]
Epoch: [132/200] Time: 0.0min:1.1945040225982666sec Loss: 201.9953
```

```
67%| | 134/200 [02:51<01:25, 1.30s/it]
Epoch: [133/200] Time: 0.0min:1.382659673690796sec Loss: 200.6312
68% | 135/200 [02:53<01:23, 1.29s/it]
Epoch: [134/200] Time: 0.0min:1.2713241577148438sec Loss: 199.3131
68%| | 136/200 [02:54<01:20, 1.26s/it]
Epoch: [135/200] Time: 0.0min:1.2042100429534912sec Loss: 198.0384
68%| | 137/200 [02:55<01:20, 1.27s/it]
Epoch: [136/200] Time: 0.0min:1.2846307754516602sec Loss: 196.8030
         | 138/200 [02:56<01:17, 1.25s/it]
Epoch: [137/200] Time: 0.0min:1.2096130847930908sec Loss: 195.6030
70% | 139/200 [02:58<01:16, 1.26s/it]
Epoch: [138/200] Time: 0.0min:1.274320125579834sec Loss: 194.4368
70% | 140/200 [02:59<01:17, 1.29s/it]
Epoch: [139/200] Time: 0.0min:1.3674194812774658sec Loss: 193.3013
70%| | 141/200 [03:00<01:14, 1.26s/it]
Epoch: [140/200] Time: 0.0min:1.1901648044586182sec Loss: 192.1931
71% | 142/200 [03:01<01:13, 1.26s/it]
Epoch: [141/200] Time: 0.0min:1.2646498680114746sec Loss: 191.1095
72%| | 143/200 [03:03<01:12, 1.28s/it]
Epoch: [142/200] Time: 0.0min:1.316335678100586sec Loss: 190.0491
     | 144/200 [03:04<01:10, 1.26s/it]
Epoch: [143/200] Time: 0.0min:1.2043042182922363sec Loss: 189.0089
72%| | 145/200 [03:05<01:09, 1.26s/it]
Epoch: [144/200] Time: 0.0min:1.2726287841796875sec Loss: 187.9878
73%| | 146/200 [03:06<01:07, 1.25s/it]
Epoch: [145/200] Time: 0.0min:1.2291591167449951sec Loss: 186.9837
74%| | 147/200 [03:08<01:06, 1.26s/it]
Epoch: [146/200] Time: 0.0min:1.271831750869751sec Loss: 185.9943
```

```
74%| | 148/200 [03:09<01:07, 1.29s/it]
Epoch: [147/200] Time: 0.0min:1.3762750625610352sec Loss: 185.0184
74% | 149/200 [03:10<01:05, 1.28s/it]
Epoch: [148/200] Time: 0.0min:1.2451417446136475sec Loss: 184.0554
Epoch: [149/200] Time: 0.0min:1.3312408924102783sec Loss: 183.1060
76%| | 151/200 [03:13<01:01, 1.26s/it]
Epoch: [150/200] Time: 0.0min:1.1869323253631592sec Loss: 182.1707
          | 152/200 [03:14<01:01, 1.28s/it]
Epoch: [151/200] Time: 0.0min:1.306957721710205sec Loss: 181.2493
76% | 153/200 [03:15<01:00, 1.28s/it]
Epoch: [152/200] Time: 0.0min:1.2893788814544678sec Loss: 180.3398
77% | 154/200 [03:17<00:57, 1.25s/it]
Epoch: [153/200] Time: 0.0min:1.1904728412628174sec Loss: 179.4437
78% | 155/200 [03:18<00:56, 1.26s/it]
Epoch: [154/200] Time: 0.0min:1.2740991115570068sec Loss: 178.5616
78%| | 156/200 [03:19<00:54, 1.25s/it]
Epoch: [155/200] Time: 0.0min:1.2131531238555908sec Loss: 177.6906
78%| | 157/200 [03:20<00:54, 1.26s/it]
Epoch: [156/200] Time: 0.0min:1.2793021202087402sec Loss: 176.8317
     | 158/200 [03:22<00:52, 1.26s/it]
Epoch: [157/200] Time: 0.0min:1.268425703048706sec Loss: 175.9839
80%| | 159/200 [03:23<00:50, 1.24s/it]
Epoch: [158/200] Time: 0.0min:1.1913971900939941sec Loss: 175.1469
80%| | 160/200 [03:24<00:50, 1.25s/it]
Epoch: [159/200] Time: 0.0min:1.275521993637085sec Loss: 174.3188
80% | 161/200 [03:25<00:49, 1.26s/it]
Epoch: [160/200] Time: 0.0min:1.2937901020050049sec Loss: 173.4981
```

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81%| | 162/200 [03:27<00:47, 1.25s/it]
Epoch: [161/200] Time: 0.0min:1.2046983242034912sec Loss: 172.6852
82% | 163/200 [03:28<00:46, 1.26s/it]
Epoch: [162/200] Time: 0.0min:1.2876191139221191sec Loss: 171.8804
82%| | 164/200 [03:29<00:44, 1.24s/it]
Epoch: [163/200] Time: 0.0min:1.195620059967041sec Loss: 171.0831
82%| | 165/200 [03:30<00:43, 1.25s/it]
Epoch: [164/200] Time: 0.0min:1.2684600353240967sec Loss: 170.2937
           | 166/200 [03:32<00:42, 1.26s/it]
Epoch: [165/200] Time: 0.0min:1.2742340564727783sec Loss: 169.5099
84%| | | 167/200 [03:33<00:41, 1.24s/it]
Epoch: [166/200] Time: 0.0min:1.2153241634368896sec Loss: 168.7339
84%| | 168/200 [03:34<00:40, 1.26s/it]
Epoch: [167/200] Time: 0.0min:1.2858643531799316sec Loss: 167.9618
84%| | 169/200 [03:36<00:39, 1.26s/it]
Epoch: [168/200] Time: 0.0min:1.2677109241485596sec Loss: 167.1965
85% | 170/200 [03:37<00:37, 1.24s/it]
Epoch: [169/200] Time: 0.0min:1.202204704284668sec Loss: 166.4321
86% | 171/200 [03:38<00:36, 1.25s/it]
Epoch: [170/200] Time: 0.0min:1.2692067623138428sec Loss: 165.6753
     | 172/200 [03:39<00:34, 1.23s/it]
Epoch: [171/200] Time: 0.0min:1.191143274307251sec Loss: 164.9169
86%| | 173/200 [03:40<00:33, 1.24s/it]
Epoch: [172/200] Time: 0.0min:1.2661230564117432sec Loss: 164.1681
87%| | | 174/200 [03:42<00:32, 1.26s/it]
Epoch: [173/200] Time: 0.0min:1.2980389595031738sec Loss: 163.4138
88%| | 175/200 [03:43<00:31, 1.25s/it]
Epoch: [174/200] Time: 0.0min:1.2218079566955566sec Loss: 162.6757
```

```
88%| | 176/200 [03:44<00:30, 1.26s/it]
Epoch: [175/200] Time: 0.0min:1.2843384742736816sec Loss: 161.9247
     | 177/200 [03:45<00:28, 1.24s/it]
Epoch: [176/200] Time: 0.0min:1.2018487453460693sec Loss: 161.2050
89%| | 178/200 [03:47<00:27, 1.26s/it]
Epoch: [177/200] Time: 0.0min:1.2947509288787842sec Loss: 160.4596
90% | 179/200 [03:48<00:26, 1.27s/it]
Epoch: [178/200] Time: 0.0min:1.2956128120422363sec Loss: 159.7813
           | 180/200 [03:49<00:25, 1.25s/it]
Epoch: [179/200] Time: 0.0min:1.217066764831543sec Loss: 159.0601
90%| | | 181/200 [03:51<00:24, 1.27s/it]
Epoch: [180/200] Time: 0.0min:1.2924582958221436sec Loss: 158.5062
91% | 182/200 [03:52<00:22, 1.25s/it]
Epoch: [181/200] Time: 0.0min:1.2136938571929932sec Loss: 157.9112
     | 183/200 [03:53<00:21, 1.28s/it]
92%1
Epoch: [182/200] Time: 0.0min:1.3438160419464111sec Loss: 157.7935
92%| | 184/200 [03:54<00:20, 1.28s/it]
Epoch: [183/200] Time: 0.0min:1.290787696838379sec Loss: 157.8097
92%| | 185/200 [03:56<00:18, 1.26s/it]
Epoch: [184/200] Time: 0.0min:1.2104368209838867sec Loss: 159.3953
     | 186/200 [03:57<00:17, 1.27s/it]
Epoch: [185/200] Time: 0.0min:1.2847487926483154sec Loss: 162.0350
94%| | 187/200 [03:58<00:16, 1.27s/it]
Epoch: [186/200] Time: 0.0min:1.2786133289337158sec Loss: 170.1410
94%| | | 188/200 [03:59<00:15, 1.25s/it]
Epoch: [187/200] Time: 0.0min:1.2129898071289062sec Loss: 180.9247
94%| | 189/200 [04:01<00:13, 1.27s/it]
```

```
Epoch 00189: reducing learning rate of group 0 to 1.0000e-05.
Epoch: [188/200] Time: 0.0min:1.3106403350830078sec Loss: 207.3050
95% | 190/200 [04:02<00:12, 1.25s/it]
Epoch: [189/200] Time: 0.0min:1.2084012031555176sec Loss: 203.3927
     | 191/200 [04:03<00:11, 1.26s/it]
Epoch: [190/200] Time: 0.0min:1.2781314849853516sec Loss: 173.9050
     | 192/200 [04:04<00:10, 1.27s/it]
Epoch: [191/200] Time: 0.0min:1.2816367149353027sec Loss: 157.3306
96% | 193/200 [04:06<00:08, 1.25s/it]
Epoch: [192/200] Time: 0.0min:1.2107973098754883sec Loss: 153.3532
97%| | 194/200 [04:07<00:07, 1.28s/it]
Epoch: [193/200] Time: 0.0min:1.3276481628417969sec Loss: 152.8113
98% | 195/200 [04:08<00:06, 1.28s/it]
Epoch: [194/200] Time: 0.0min:1.2829699516296387sec Loss: 152.6839
     | 196/200 [04:10<00:05, 1.26s/it]
Epoch: [195/200] Time: 0.0min:1.2070226669311523sec Loss: 152.5651
     | 197/200 [04:11<00:03, 1.27s/it]
Epoch: [196/200] Time: 0.0min:1.2985317707061768sec Loss: 152.4630
99%| 198/200 [04:12<00:02, 1.25s/it]
Epoch: [197/200] Time: 0.0min:1.2053260803222656sec Loss: 152.3773
     | 199/200 [04:13<00:01, 1.26s/it]
100%
Epoch: [198/200] Time: 0.0min:1.2893006801605225sec Loss: 152.2988
100%| 200/200 [04:15<00:00, 1.28s/it]
Epoch: [199/200] Time: 0.0min:1.2843544483184814sec Loss: 152.2233
del new network
NameError
                                      Traceback (most recent call
last)
```

```
/home/mayank/828i/HW2/Copy of cmsc828I fall 2023 HW2.ipynb Cell 32
line 1
----> <a
href='vscode-notebook-cell:/home/mayank/828i/HW2/Copy of cmsc828I fall
2023 HW2.ipynb#X50sZmlsZQ%3D%3D?line=0'>1</a> del new network
NameError: name 'new network' is not defined
#BONUS
#EValuation
dataset = SingleImageDataset('/home/mayank/828i/HW2/mypeacock.jpg')
dataloader = DataLoader(dataset, batch size=4096, shuffle=False)
ground truth image1 =
torch.zeros((dataset.h,dataset.w,3),dtype=torch.uint8)
predicted image1 = torch.zeros like(ground truth image1)
new network.eval()
for batch in dataloader:
    position x, positiony, intensity = batch["x"], batch["y"],
batch["intensity"]
    x = position x.to(device)
    y = positiony.to(device)
    #normalize 0 to 1
    x = x / dataset.w
    y = y / dataset.h
    coord = torch.vstack([x,y]).T
    positional coord=pose encod(B,coord)
    pred = new network(positional coord)
    #detach torch to numpy
    x = position x.detach().numpy()
    y = positiony.detach().numpy()
    intensity = intensity.detach()
    pred intensity = pred.type(torch.uint8).cpu().detach()
    #assign intensity to x,y positionsi., x,y to rgb
    for idx, (y1, x1) in enumerate(zip(y,x)):
        ground truth image1[y1,x1,:] = intensity[idx]
        predicted image1[y1,x1,:] = pred intensity[idx]
concat image1 = torch.cat([ground truth image1, predicted image1],
dim=1)
fig, (ax1, ax2)=plt.subplots(nrows=1, ncols=2)
plt.figure(figsize=(20,20))
ax1.set title('Initial Model')
ax1.imshow(concat image)
ax1.axis('off')
ax2.imshow(concat image1)
ax2.set_title('Improved Model')
ax2.axis('off')
plt.show()
ground truth1 = ground truth image1.numpy()
```

```
predict1 = predicted_image1.numpy()
psnr_value1 = round(psnr(ground_truth1, predict1),2)
psnr_value=round(psnr(ground_truth, predict),2)
print("PSNR value for improved model: ", psnr_value1)
print("PSNR value for initialmodel",psnr_value)
```

Initial Model



Improved Model



<Figure size 2000x2000 with 0 Axes>

PSNR value for improved model: 29.2 PSNR value for initialmodel 27.74