

# Algebra Linear Computacional - Lista 4

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## Exercício 1)

$$f(x) = \log(\cosh(x\sqrt{gk})) - 50$$

$$g = 9.806, k = 0.00341$$

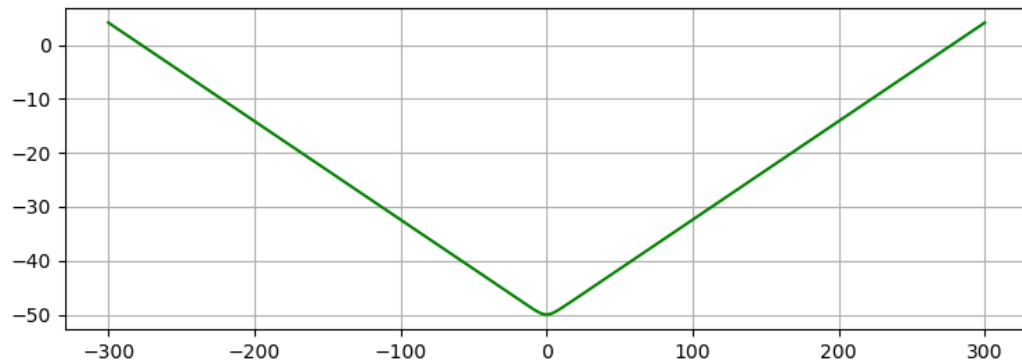
Plotando o gráfico da função utilizando a biblioteca matplotlib do python, para verificar intervalo de raízes:

```
In [1]: %matplotlib notebook
import matplotlib.pyplot as plt
import numpy as np
```

Definindo a função:

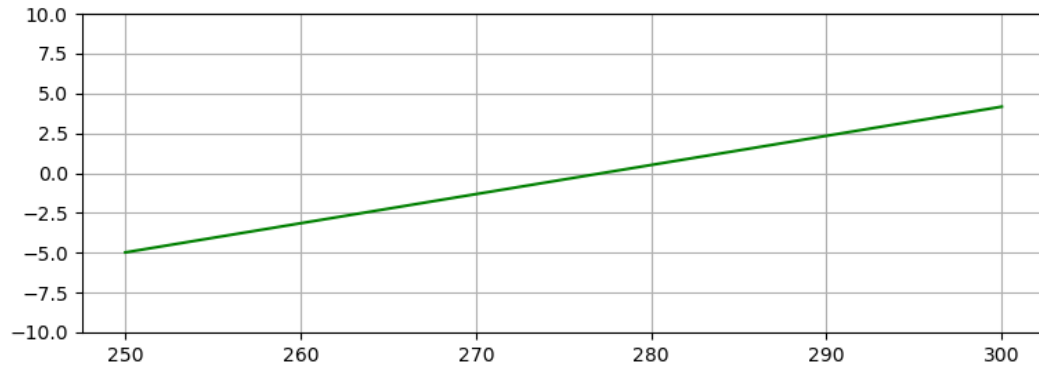
```
In [2]: def f(x):
        g = 9.806
        k = 0.00341
        y = np.log(np.cosh(x * np.sqrt(g*k))) - 50
        return y
```

```
In [3]: X = np.linspace(-300, 300, 1000)
F = np.vectorize(f)
plt.rcParams['figure.figsize'] = (9,3)
plt.plot(X, F(X), 'g-')
plt.grid()
plt.show()
```



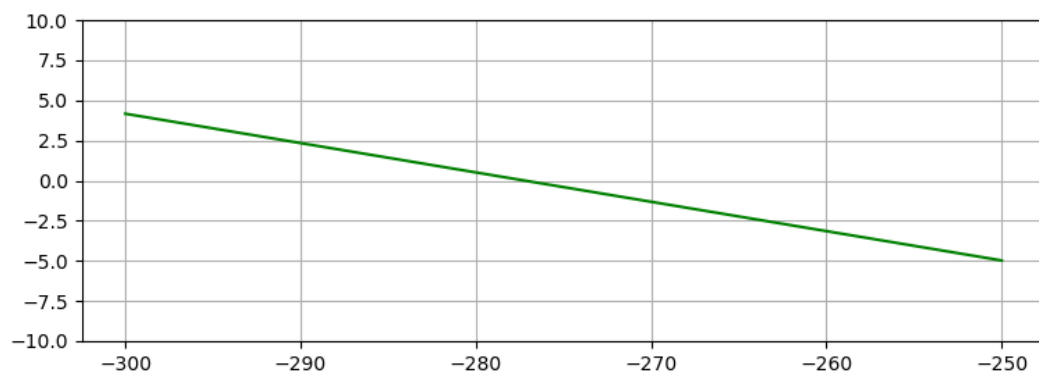
Mais aproximadamente entre os pontos  $x = 250$  e  $x = 300$

```
In [4]: X = np.linspace(250, 300, 100)
F = np.vectorize(f)
plt.rcParams['figure.figsize'] = (9,3)
plt.plot(X, F(X), 'g-')
plt.ylim(-10, 10)
plt.grid()
plt.show()
```



A função é simétrica em relação ao eixo  $y$ , portando, plotando o gráfico da função para  $x = -300$  e  $x = -250$ :

```
In [5]: X = np.linspace(-300, -250, 100)
F = np.vectorize(f)
plt.plot(X, F(X), 'g-')
plt.ylim(-10, 10)
plt.grid()
plt.show()
```



### Método da Bisseção:

Definindo a tolerância:

```
In [6]: tol = 0.0001
```

```
In [7]: def ordena(a, b):
        if a < b:
            return a, b
        return b, a
```

```
In [8]: def bissecao(a, b, tol):
        a, b = ordena(a, b)
        err = abs(b-a)
        aux = a
        it = 0
        while err >= tol:
            x = (a+b)/2.0
            print(' ', it, ' {:>8,.5f} '.format(a), ' {:>8,.5f} '.format(b), ' {:>8,.5f} '.format(f(x)), ' {:>8,.5f} '.format(err))
            if f(x)*f(a) < 0:
                b = x
            elif f(x)*f(a) > 0:
                a = x
            else:
                return x
            err = abs(x-aux)
            aux = x
            it += 1
        print(' ', it, ' {:>8,.5f} '.format(a), ' {:>8,.5f} '.format(b), ' {:>8,.5f} '.format(f(x)), ' {:>8,.5f} '.format(err))
        return x
```

```
In [9]: a = 250
        b = 300
        print('ITER      a              b              x              f(x)              Err')
        x = bissecao(a, b, tol)
        print("\nA raiz exata é x= %.5f" % x)
```

ITER	a	b	x	f(x)	Err
0	250.00000	300.00000	275.00000	-0.40614	50.00000
1	275.00000	300.00000	287.50000	1.87964	25.00000
2	275.00000	287.50000	281.25000	0.73675	12.50000
3	275.00000	281.25000	278.12500	0.16531	6.25000
4	275.00000	278.12500	276.56250	-0.12041	3.12500
5	276.56250	278.12500	277.34375	0.02245	1.56250
6	276.56250	277.34375	276.95312	-0.04898	0.78125
7	276.95312	277.34375	277.14844	-0.01327	0.39062
8	277.14844	277.34375	277.24609	0.00459	0.19531
9	277.14844	277.24609	277.19727	-0.00434	0.09766
10	277.19727	277.24609	277.22168	0.00012	0.04883
11	277.19727	277.22168	277.20947	-0.00211	0.02441
12	277.20947	277.22168	277.21558	-0.00099	0.01221
13	277.21558	277.22168	277.21863	-0.00043	0.00610
14	277.21863	277.22168	277.22015	-0.00015	0.00305
15	277.22015	277.22168	277.22092	-0.00001	0.00153
16	277.22092	277.22168	277.22130	0.00006	0.00076
17	277.22092	277.22130	277.22111	0.00002	0.00038
18	277.22092	277.22111	277.22101	0.00000	0.00019
19	277.22092	277.22101	277.22101	0.00000	0.00010

A raiz exata é x= 277.22101

Para raiz negativa:

```
In [10]: a = -250
b = -300
print('ITER      a              b              x              f(x)              Err')
x = bissecao(a, b, tol)
print("\nA raiz exata é x= %.5f" % x)
```

ITER	a	b	x	f(x)	Err
0	-300.00000	-250.00000	-275.00000	-0.40614	50.00000
1	-300.00000	-275.00000	-287.50000	1.87964	25.00000
2	-287.50000	-275.00000	-281.25000	0.73675	12.50000
3	-281.25000	-275.00000	-278.12500	0.16531	6.25000
4	-278.12500	-275.00000	-276.56250	-0.12041	3.12500
5	-278.12500	-276.56250	-277.34375	0.02245	1.56250
6	-277.34375	-276.56250	-276.95312	-0.04898	0.78125
7	-277.34375	-276.95312	-277.14844	-0.01327	0.39062
8	-277.34375	-277.14844	-277.24609	0.00459	0.19531
9	-277.24609	-277.14844	-277.19727	-0.00434	0.09766
10	-277.24609	-277.19727	-277.22168	0.00012	0.04883
11	-277.22168	-277.19727	-277.20947	-0.00211	0.02441
12	-277.22168	-277.20947	-277.21558	-0.00099	0.01221
13	-277.22168	-277.21558	-277.21863	-0.00043	0.00610
14	-277.22168	-277.21863	-277.22015	-0.00015	0.00305
15	-277.22168	-277.22015	-277.22092	-0.00001	0.00153
16	-277.22168	-277.22092	-277.22130	0.00006	0.00076
17	-277.22130	-277.22092	-277.22111	0.00002	0.00038
18	-277.22111	-277.22092	-277.22101	0.00000	0.00019
19	-277.22101	-277.22092	-277.22101	0.00000	0.00010

A raiz exata é x= -277.22101

### Método de Newton original:

Definindo a derivada  $f'(x)$

```
In [11]: def fder(x):
cte = (9.806*0.00341)**0.5
return (cte*np.sinh(x * cte)/np.cosh(x * cte))
```

```
In [12]: def newton(x0, tol, it_max):
it = 0
err = 10
while (err >= tol) and (it < it_max):
x = x0 - f(x0)/fder(x0)
err = abs(x-x0)
print(' ', it, '      {:>8,.4f} '.format(x0), ' {:>8,.4f} '.format(f(x0)),
      ' {:>8,.4f} '.format(fder(x0)), ' {:>8,.5f} '.format(err))
x0 = x
it += 1
return (x, it)
```

Definindo  $x_0 = 10$  para encontrar raíz positiva:

```
In [13]: x0 = 10
it_max = 100
tol = 0.0001
```

```
In [14]: print("ITER      x0      f(x)      f'(x)      Err")
x, i = newton(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x0	f(x)	f'(x)	Err
0	10.0000	-48.8391	0.1737	281.23015
1	291.2302	2.5617	0.1829	14.00916
2	277.2210	0.0000	0.1829	0.00000

Raiz encontrada x= 277.22100

Para raiz negativa, iniciando com  $x_0 = -10$ :

```
In [15]: x0 = -10
print("ITER      x0      f(x)      f'(x)      Err")
x, i = newton(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x0	f(x)	f'(x)	Err
0	-10.0000	-48.8391	-0.1737	281.23015
1	-291.2302	2.5617	-0.1829	14.00916
2	-277.2210	0.0000	-0.1829	0.00000

Raiz encontrada x= -277.22100

### Método da Secante:

```
In [16]: def secante(x0, tol, it_max):
    delta = 0.001
    x1 = x0 + delta
    fa = f(x0)
    it = 0
    err = 10
    while (err >= tol) and (it < it_max):
        fi = f(x1)
        x2 = x1 - (fi*(x1-x0)/(fi-fa))
        err = abs(x2-x1)
        print(' ', it, '    {:>8,.4f} '.format(x0), '    {:>8,.4f} '.format(x1),
              '    {:>8,.4f} '.format(x2), '    {:>8,.5f} '.format(err))
        x0 = x1
        x1 = x2
        fa = fi
        it += 1
    return (x1, it)
```

Iniciando com  $x_0 = 10$  para encontrar raiz positiva:

```
In [17]: x0 = 10
print("ITER      x_k-1      x_k      x_k+1      Err")
x, i = secante(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x_k-1	x_k	x_k+1	Err
0	10.0000	10.0010	291.2275	281.22650
1	10.0010	291.2275	277.2141	14.01344
2	291.2275	277.2141	277.2210	0.00694
3	277.2141	277.2210	277.2210	0.00000

Raiz encontrada x= 277.22100

Para raiz negativa, iniciando com  $x_0 = -10$ :

```
In [18]: x0 = -10
print("ITER      x_k-1      x_k      x_k+1      Err")
x, i = secante(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x_k-1	x_k	x_k+1	Err
0	-10.0000	-9.9990	-291.2328	281.23381
1	-9.9990	-291.2328	-277.2140	14.01876
2	-291.2328	-277.2140	-277.2210	0.00695
3	-277.2140	-277.2210	-277.2210	0.00000

Raiz encontrada x= -277.22100

**Método da Interpolação inversa:**

```
In [19]: def maior_indice(y):
    if y[0] > y[1]:
        maior = 0
    else:
        maior = 1
    if y[maior] > y[2]:
        return maior
    return 2
```

```
In [20]: def interpolacao_inversa(x):
it = 0
err = 10
x = sorted(x)
x0 = 10**10
y = [0, 0, 0]
y[0] = f(x[0])
y[1] = f(x[1])
y[2] = f(x[2])
while (err >= tol) and (it < it_max):
    phi0 = ((y[1]*y[2])/((y[0]-y[1])*(y[0]-y[2])))
    phi1 = ((y[0]*y[2])/((y[1]-y[0])*(y[1]-y[2])))
    phi2 = ((y[0]*y[1])/((y[2]-y[0])*(y[2]-y[1])))
    aux = phi0*x[0] + phi1*x[1] + phi2*x[2]

    err = abs(aux - x0)

    print(' ', it, ' {:>8,.4f} '.format(x[0]), ' {:>8,.4f} '.format(x[1]),
          ' {:>8,.4f} '.format(x[2]), ' {:>8,.4f} '.format(y[0]), ' {:>8,.4f} '.format(y[1]),
          ' {:>8,.4f} '.format(y[2]), ' {:>8,.4f} '.format(aux), ' {:>8,.5f} '.format(err))

    i = maior_indice(y)
    x[i] = aux
    y[i] = f(aux)
    x = sorted(x)
    y = sorted(y)
    x0 = aux
    it += 1

return (aux, it)
```

Definindo um vetor inicial  $x_0$  para entrada, buscando a raiz positiva:

```
In [21]: x = [200, 250, 300]
```

```
In [22]: print("ITER      x1          x2          x3          y1          y2          y3")
aux, i = interpolacao_inversa(x)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % aux)
```

ITER	x1	x2	x3	y1	y2	y3	
x*		Err					
0	200.0000	250.0000	300.0000	-14.1208	-4.9777	4.1654	27
7.2210		9,999,999,722.77900					
1	200.0000	250.0000	277.2210	-14.1208	-4.9777	0.0000	27
7.2210		0.00000					

Raiz encontrada x= 277.22100

Para raiz negativa:

```
In [23]: x = [-300, -285, -260]
```

```
In [24]: print("ITER      x1      x2      x3      y1      y2      y3")
aux, i = interpolacao_inversa(x)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % aux)
```

ITER	x1	x2	x3	y1	y2	y3
x*		Err				
0	-300.0000	-285.0000	-260.0000	4.1654	1.4225	-3.1491
	-277.2210	10,000,000,277.22100				
1	-285.0000	-277.2210	-260.0000	-3.1491	0.0000	1.4225
	-277.2210	0.00000				

Raiz encontrada x= -277.22100

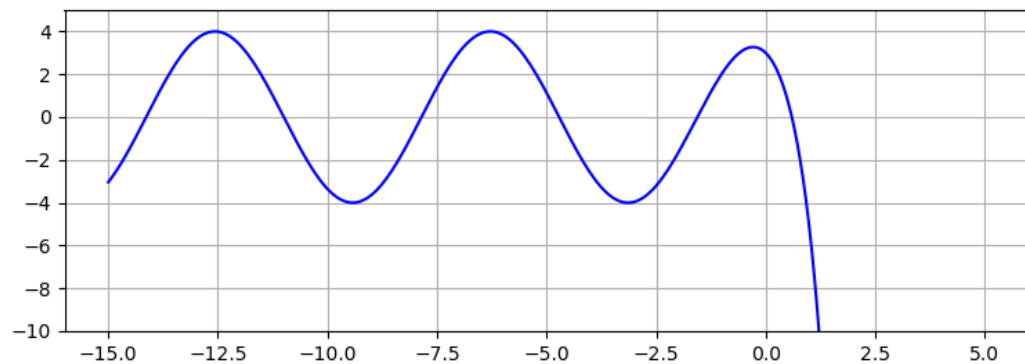
## Exercício 2)

$$f(x) = 4\cos(x) - e^{2x}$$

Gráfico da função entre os pontos  $x = -15$  e  $x = 5$

```
In [25]: def f(x): return 4*np.cos(x) - np.exp(2*x)
```

```
In [26]: X = np.linspace(-15, 5, 300)
F = np.vectorize(f)
plt.plot(X, F(X), 'b-')
plt.ylim(-10, 5)
plt.grid()
plt.show()
```



### Método da Bisseção:

Para  $x > 0$ , a função possui apenas uma raiz e para  $x < 0$  a função tem comportamento oscilante. Definindo condições iniciais para  $x > 0$



```
In [27]: print('ITER      a          b          x          f(x)          Err')
x = bissecao(0, 2, tol)
print("\nA raiz exata é x= %.5f" % x)
```

ITER	a	b	x	f(x)	Err
0	0.00000	2.00000	1.00000	-5.22785	2.00000
1	0.00000	1.00000	0.50000	0.79205	1.00000
2	0.50000	1.00000	0.75000	-1.55493	0.50000
3	0.50000	0.75000	0.62500	-0.24649	0.25000
4	0.50000	0.62500	0.56250	0.30348	0.12500
5	0.56250	0.62500	0.59375	0.03652	0.06250
6	0.59375	0.62500	0.60938	-0.10293	0.03125
7	0.59375	0.60938	0.60156	-0.03270	0.01562
8	0.59375	0.60156	0.59766	0.00204	0.00781
9	0.59766	0.60156	0.59961	-0.01530	0.00391
10	0.59766	0.59961	0.59863	-0.00662	0.00195
11	0.59766	0.59863	0.59814	-0.00229	0.00098
12	0.59766	0.59814	0.59790	-0.00013	0.00049
13	0.59766	0.59790	0.59778	0.00095	0.00024
14	0.59778	0.59790	0.59784	0.00041	0.00012
15	0.59784	0.59790	0.59784	0.00041	0.00006

A raiz exata é x= 0.59784

Definindo condições iniciais para  $x < 0$

```
In [28]: print('ITER      a          b          x          f(x)          Err')
x = bissecao(-2, 0, tol)
print("\nA raiz exata é x= %.5f" % x)
```

ITER	a	b	x	f(x)	Err
0	-2.00000	0.00000	-1.00000	2.02587	2.00000
1	-2.00000	-1.00000	-1.50000	0.23316	1.00000
2	-2.00000	-1.50000	-1.75000	-0.74318	0.50000
3	-1.75000	-1.50000	-1.62500	-0.25548	0.25000
4	-1.62500	-1.50000	-1.56250	-0.01075	0.12500
5	-1.56250	-1.50000	-1.53125	0.11137	0.06250
6	-1.56250	-1.53125	-1.54688	0.05034	0.03125
7	-1.56250	-1.54688	-1.55469	0.01980	0.01562
8	-1.56250	-1.55469	-1.55859	0.00453	0.00781
9	-1.56250	-1.55859	-1.56055	-0.00311	0.00391
10	-1.56055	-1.55859	-1.55957	0.00071	0.00195
11	-1.56055	-1.55957	-1.56006	-0.00120	0.00098
12	-1.56006	-1.55957	-1.55981	-0.00025	0.00049
13	-1.55981	-1.55957	-1.55969	0.00023	0.00024
14	-1.55981	-1.55969	-1.55975	-0.00001	0.00012
15	-1.55975	-1.55969	-1.55975	-0.00001	0.00006

A raiz exata é x= -1.55975

**Método de Newton original:**

Definindo a derivada da função  $f(x)$

```
In [29]: def fder(x): return (-4*np.sin(x) - np.exp(2*x)*2)
```

Para  $x_0 = 1$ , buscando a raiz positiva:

```
In [30]: x0 = 1
print("ITER      x0      f(x)      f'(x)      Err")
x, i = newton(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x0	f(x)	f'(x)	Err
0	1.0000	-5.2278	-18.1440	0.28813
1	0.7119	-1.1240	-10.9182	0.10295
2	0.6089	-0.0988	-9.0476	0.01092
3	0.5980	-0.0010	-8.8657	0.00011
4	0.5979	-0.0000	-8.8638	0.00000

Raiz encontrada x= 0.59789

Comprovando característica oscilatória da função para  $x < 0$

```
In [31]: print("ITER      x0      f(x)      f'(x)      Err")
x, i = newton(-2, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x0	f(x)	f'(x)	Err
0	-2.0000	-1.6829	3.6006	0.46740
1	-1.5326	0.1061	3.9038	0.02718
2	-1.5598	-0.0001	3.9114	0.00003

Raiz encontrada x= -1.55975

```
In [32]: print("ITER      x0      f(x)      f'(x)      Err")
x, i = newton(-4, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x0	f(x)	f'(x)	Err
0	-4.0000	-2.6149	-3.0279	0.86361
1	-4.8636	0.6025	-3.9545	0.15237
2	-4.7112	-0.0047	-4.0002	0.00116
3	-4.7124	0.0000	-4.0002	0.00000

Raiz encontrada x= -4.71241

### Método da Secante:

Buscando raiz positiva, iniciando com  $x_0 = 1$

```
In [33]: print("ITER      x_k-1      x_k      x_k+1      Err")
x, i = secante(x0, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\n Raiz encontrada x= %.5f" % x)
```

ITER	x_k-1	x_k	x_k+1	Err
0	1.0000	1.0010	0.7121	0.28888
1	1.0010	0.7121	0.6331	0.07902
2	0.7121	0.6331	0.6014	0.03169
3	0.6331	0.6014	0.5980	0.00341
4	0.6014	0.5980	0.5979	0.00011
5	0.5980	0.5979	0.5979	0.00000

Raiz encontrada x= 0.59789

Para  $x_0 = -2$ , para raiz negativa:

```
In [34]: print("ITER      x_k-1      x_k      x_k+1      Err")
x, i = secante(-2, tol, it_max)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % x)
```

ITER	x_k-1	x_k	x_k+1	Err
0	-2.0000	-1.9990	-1.5327	0.46630
1	-1.9990	-1.5327	-1.5603	0.02761
2	-1.5327	-1.5603	-1.5598	0.00056
3	-1.5603	-1.5598	-1.5598	0.00000

Raiz encontrada x= -1.55975

**Método da Interpolação inversa:**

```
In [35]: x = [0.1, 0.4, 0.6]
```

```
In [36]: print("ITER      x1      x2      x3      y1      y2      y3")
aux, i = interpolacao_inversa(x)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % aux)
```

ITER	x1	x2	x3	y1	y2	y3
x*	Err					
0	0.1000	0.4000	0.6000	2.7586	1.4587	-0.0188
0.5984	9,999,999	999.40160				
1	0.4000	0.5984	0.6000	-0.0188	-0.0046	1.4587
0.6611	0.06271					
2	0.4000	0.5984	0.6611	-0.5945	-0.0188	-0.0046
0.6818	0.02066					
3	0.4000	0.5984	0.6818	-0.8042	-0.5945	-0.0188
0.6731	0.00867					
4	0.4000	0.5984	0.6731	-0.8042	-0.7152	-0.5945
2.2290	2.90207					-
5	-2.2290	0.4000	0.5984	-2.4583	-0.8042	-0.7152
2.4060	4.63498					
6	-2.2290	0.4000	2.4060	-125.9469	-2.4583	-0.8042
3.4001	0.99407					
7	-2.2290	0.4000	3.4001	-901.8668	-125.9469	-2.4583
3.4670	0.06692					
8	-2.2290	0.4000	3.4670	-1,030.3902	-901.8668	-125.9469
1.8923	1.57467					
9	-2.2290	0.4000	1.8923	-1,030.3902	-901.8668	-45.2847
1.1954	0.69691					
10	-2.2290	0.4000	1.1954	-1,030.3902	-901.8668	-9.4561
1.0404	0.15499					
11	-2.2290	0.4000	1.0404	-1,030.3902	-901.8668	-5.9878
0.9406	0.09978					
12	-2.2290	0.4000	0.9406	-1,030.3902	-901.8668	-4.2048
0.8698	0.07083					
13	-2.2290	0.4000	0.8698	-1,030.3902	-901.8668	-3.1153
0.8169	0.05289					
14	-2.2290	0.4000	0.8169	-1,030.3902	-901.8668	-2.3857
0.7762	0.04074					
15	-2.2290	0.4000	0.7762	-1,030.3902	-901.8668	-1.8683
0.7441	0.03204					
16	-2.2290	0.4000	0.7441	-1,030.3902	-901.8668	-1.4868
0.7186	0.02559					
17	-2.2290	0.4000	0.7186	-1,030.3902	-901.8668	-1.1974
0.6979	0.02067					
18	-2.2290	0.4000	0.6979	-1,030.3902	-901.8668	-0.9732
0.6810	0.01684					
19	-2.2290	0.4000	0.6810	-1,030.3902	-901.8668	-0.7967
0.6672	0.01381					
20	-2.2290	0.4000	0.6672	-1,030.3902	-901.8668	-0.6558
0.6559	0.01138					
21	-2.2290	0.4000	0.6559	-1,030.3902	-901.8668	-0.5424
0.6464	0.00943					
22	-2.2290	0.4000	0.6464	-1,030.3902	-901.8668	-0.4502
0.6386	0.00783					
23	-2.2290	0.4000	0.6386	-1,030.3902	-901.8668	-0.3748
0.6321	0.00653					
24	-2.2290	0.4000	0.6321	-1,030.3902	-901.8668	-0.3128
0.6266	0.00545					
25	-2.2290	0.4000	0.6266	-1,030.3902	-901.8668	-0.2616
0.6221	0.00456					
26	-2.2290	0.4000	0.6221	-1,030.3902	-901.8668	-0.2191

0.6182	0.00382					
27	-2.2290	0.4000	0.6182	-1,030.3902	-901.8668	-0.1838
0.6150	0.00321					
28	-2.2290	0.4000	0.6150	-1,030.3902	-901.8668	-0.1544
0.6123	0.00269					
29	-2.2290	0.4000	0.6123	-1,030.3902	-901.8668	-0.1298
0.6101	0.00227					
30	-2.2290	0.4000	0.6101	-1,030.3902	-901.8668	-0.1092
0.6082	0.00191					
31	-2.2290	0.4000	0.6082	-1,030.3902	-901.8668	-0.0919
0.6066	0.00161					
32	-2.2290	0.4000	0.6066	-1,030.3902	-901.8668	-0.0774
0.6052	0.00135					
33	-2.2290	0.4000	0.6052	-1,030.3902	-901.8668	-0.0652
0.6041	0.00114					
34	-2.2290	0.4000	0.6041	-1,030.3902	-901.8668	-0.0550
0.6031	0.00096					
35	-2.2290	0.4000	0.6031	-1,030.3902	-901.8668	-0.0464
0.6023	0.00081					
36	-2.2290	0.4000	0.6023	-1,030.3902	-901.8668	-0.0391
0.6016	0.00068					
37	-2.2290	0.4000	0.6016	-1,030.3902	-901.8668	-0.0330
0.6010	0.00058					
38	-2.2290	0.4000	0.6010	-1,030.3902	-901.8668	-0.0279
0.6005	0.00049					
39	-2.2290	0.4000	0.6005	-1,030.3902	-901.8668	-0.0235
0.6001	0.00041					
40	-2.2290	0.4000	0.6001	-1,030.3902	-901.8668	-0.0199
0.5998	0.00035					
41	-2.2290	0.4000	0.5998	-1,030.3902	-901.8668	-0.0168
0.5995	0.00029					
42	-2.2290	0.4000	0.5995	-1,030.3902	-901.8668	-0.0142
0.5992	0.00025					
43	-2.2290	0.4000	0.5992	-1,030.3902	-901.8668	-0.0120
0.5990	0.00021					
44	-2.2290	0.4000	0.5990	-1,030.3902	-901.8668	-0.0101
0.5988	0.00018					
45	-2.2290	0.4000	0.5988	-1,030.3902	-901.8668	-0.0085
0.5987	0.00015					
46	-2.2290	0.4000	0.5987	-1,030.3902	-901.8668	-0.0072
0.5986	0.00013					
47	-2.2290	0.4000	0.5986	-1,030.3902	-901.8668	-0.0061
0.5985	0.00011					
48	-2.2290	0.4000	0.5985	-1,030.3902	-901.8668	-0.0051
0.5984	0.00009					

Raiz encontrada x= 0.59838

Testando o método para raiz negativa:

In [37]: `x = [-3, -2, 0.5]`

```
In [38]: print("ITER      x1      x2      x3      y1      y2      y3")
aux, i = interpolacao_inversa(x)
if i == it_max:
    print("O método não convergiu")
print("\nRaiz encontrada x= %.5f" % aux)
```

ITER	x1	x2	x3	y1	y2	y3	
x*	Err						
0	-3.0000	-2.0000	0.5000	-3.9624	-1.6829	0.7920	-
0.4603	10,000,000,000.46027						
1	-3.0000	-2.0000	-0.4603	-3.9624	-1.6829	3.1854	-
1.3759	0.91567						
2	-3.0000	-2.0000	-1.3759	-3.9624	-1.6829	0.7107	-
1.5157	0.13975						
3	-3.0000	-2.0000	-1.5157	-3.9624	-1.6829	0.1721	-
1.5482	0.03249						
4	-3.0000	-2.0000	-1.5482	-3.9624	-1.6829	0.0453	-
1.5566	0.00847						
5	-3.0000	-2.0000	-1.5566	-3.9624	-1.6829	0.0122	-
1.5589	0.00227						
6	-3.0000	-2.0000	-1.5589	-3.9624	-1.6829	0.0033	-
1.5595	0.00061						
7	-3.0000	-2.0000	-1.5595	-3.9624	-1.6829	0.0009	-
1.5597	0.00017						
8	-3.0000	-2.0000	-1.5597	-3.9624	-1.6829	0.0002	-
1.5597	0.00004						

Raiz encontrada x= -1.55973

O resultado para raiz positiva, precisou de alguns chutes iniciais para o vetor de entrada, após algumas tentativas de vetor inicial, foi possível alcançar os mesmos resultados.

### Exercício 3)

$$16x^4 + 16y^4 + z^4 = 16$$

$$x^2 + y^2 + z^2 = 3$$

$$x^3 - y + z = 1$$

**Método de Newton:**

```
In [39]: def f(V):
x, y, z = V
S = np.array([16*x**4+16*y**4+z**4-16,
              x**2+y**2+z**2-3,
              x**3-y+z-1])
return S
```

```
In [40]: def j(V):
          x, y, z = V
          J = np.array([[64*x**3, 64*y**3, 4*z**3],
                        [2*x, 2*y, 2*z],
                        [3*x**2, -1, 1]])
          return J
```

```
In [41]: def newton(V, tol, it_max):
          it = 0
          err = 10

          while (err >= tol) and (it < it_max):
              J = j(V)
              F = f(V)
              inv_J = np.linalg.inv(J)

              delta = - inv_J.dot(F)
              V = V + delta
              err = np.linalg.norm(delta)/np.linalg.norm(V)

              X = np.round(V, 3)
              print("ITER ", it, "|X = ", X, " | Err = %.5f" % err)

              it += 1

          return (V, it)
```

Definindo as condições iniciais e vetor inicial:

```
In [42]: V = np.array([1, 1, 1])
          tol = 0.0001
          it_max = 100
```

```
In [43]: X, i = newton(V, tol, it_max)
          X = np.round(X, 3)
          if i == it_max:
              print("O método não convergiu")
          print("\nSolução X = ", X)
```

```
ITER  0 |X = [0.858 0.858 1.283] | Err = 0.19644
ITER  1 |X = [0.8   0.811 1.307] | Err = 0.04551
ITER  2 |X = [0.791 0.807 1.313] | Err = 0.00678
ITER  3 |X = [0.79  0.807 1.313] | Err = 0.00012
ITER  4 |X = [0.79  0.807 1.313] | Err = 0.00000
```

Solução X = [0.79 0.807 1.313]

**Método de Broyden:**

```
In [44]: def broyden(X, B):
it = 0
err = 10
while (err >= tol) and (it < it_max):
    J = np.copy(B)

    F = f(X)
    F = np.reshape(F, (-1, 1))

    delta = np.linalg.solve(J, -F)

    X = np.reshape(X, (-1, 1)) + delta
    X = X + delta

    Y = f(X)
    Y = np.reshape(Y, (-1, 1))
    Y = Y - F
    err = np.linalg.norm(delta)/np.linalg.norm(X)
    print("ITER ", it, "|X = ", np.reshape(np.round(X, 3), (1, -1)), " | Err = %.5f" % err)

    aux = (Y - np.dot(B, delta))
    numerador = np.dot(aux, np.transpose(delta))
    denominador = np.dot(np.transpose(delta), delta)
    B = B + np.divide(numerador, denominador)
    it += 1

    return (X, it)
```

Para matriz  $B$  inicial sendo o jacobiano do vetor  $X$ :

```
In [45]: X = np.array([1, 1, 1])
B = j(X)
```

```
In [46]: print(B)

[[64 64  4]
 [ 2  2  2]
 [ 3 -1  1]]
```

```
In [47]: X, i = broyden(X, B)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", np.reshape(np.round(X, 3), (1, -1)))
```

```
ITER 0 |X = [[0.717 0.717 1.567]] | Err = 0.18597
ITER 1 |X = [[0.748 0.734 1.237]] | Err = 0.10227
ITER 2 |X = [[0.753 0.808 1.356]] | Err = 0.04008
ITER 3 |X = [[0.784 0.803 1.332]] | Err = 0.01149
ITER 4 |X = [[0.788 0.81 1.314]] | Err = 0.00550
ITER 5 |X = [[0.791 0.806 1.312]] | Err = 0.00157
ITER 6 |X = [[0.79 0.807 1.313]] | Err = 0.00050
ITER 7 |X = [[0.79 0.807 1.313]] | Err = 0.00002
```

```
Solução X = [[0.79 0.807 1.313]]
```

Para matriz  $B$  identidade:



```
In [48]: X = np.array([1, 1, 1])
        B = np.eye(3)
```

```
In [49]: X, i = broyden(X, B)
        if i == it_max:
            print("O método não convergiu")
        print("\nSolução X = ", np.reshape(np.round(X, 3), (1, -1)))
```

```
ITER 0 |X = [[-33.  1.  1.]] | Err = 0.51468
ITER 1 |X = [[1.  1.002 0.936]] | Err = 10.01856
ITER 2 |X = [[1.  1.245 1.004]] | Err = 0.06699
ITER 3 |X = [[1.  1.017 1.072]] | Err = 0.06666
ITER 4 |X = [[1.  1.014 0.855]] | Err = 0.06530
ITER 5 |X = [[1.  1.014 0.98 ]] | Err = 0.03607
ITER 6 |X = [[1.  1.017 0.983]] | Err = 0.00127
ITER 7 |X = [[1.  1.017 0.983]] | Err = 0.00012
ITER 8 |X = [[1.  1.017 0.983]] | Err = 0.00003
```

Solução X = [[1. 1.017 0.983]]

Percebemos que são soluções diferentes, contudo, ambas são soluções do sistema de equações definido.

## Exercício 4)

$$2c_3^2 + c_2^2 + 6c_4^2 = 1$$

$$8c_3^3 + 6c_3c_2^2 + 36c_3c_2c_4 + 108c_3c_4^2 = \theta_1$$

$$60c_3^4 + 60c_3^2c_2^2 + 576c_3^2c_2c_4 + 2232c_3^2c_4^2 + 252c_4^2c_2^2 + 1296c_4^3c_2 + 3348c_4^4 + 24c_2^3c_4 + 3c_2 = \theta_2$$

```
In [50]: def f(V):
        x, y, z = V
        S = np.array([2*(y**2) + x**2 + 6*(z**2) - 1,
                        8*(y**3) + 6*y*(x**2) + 36*y*x*z + 108*y*(z**2) - theta1,
                        60*y**4 + 60*(y**2)*(x**2) + 576*(y**2)*x*z + 2232*(y**2)*(z**2) +
                        252*(z**2)*(x**2) + 1296*(z**3)*x + 3348*(z**4) + 24*(x**3)*z +
                        theta2])
        return S
```

```
In [51]: def j(V):
        x, y, z = V
        S = np.array([2*x, 4*y, 12*z],
                        [12*y*x + 36*y*z, 24*y**2+6*x**2+36*x*z+108*z**2, 36*y*x+216*y*z],
                        [120*y**2*x+576*y**2*z+504*z**2*x+1296*z**3+72*x**2*z+3,
                        240*y**3+120*y*x**2+2*576*y*x*z+4464*y*z**2,
                        576*y**2*x+4464*y**2*z+504*z*x**2+3*1296*z**2*x+4*3348*z**3+2*
                        theta2])
        return S
```

a)

$$\theta_1 = 0$$

$$\theta_2 = 3$$

```
In [52]: theta1 = 0
theta2 = 3
```

### Método de Newton

```
In [53]: V = np.array([1, 1, 1])
tol = 0.0001
it_max = 100
```

```
In [54]: X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

ITER	0	X =	[-5.71	1.558	1.265]		Err = 1.11331
ITER	1	X =	[-2.49	1.401	0.718]		Err = 1.11018
ITER	2	X =	[-0.902	0.956	0.507]		Err = 1.18030
ITER	3	X =	[-0.539	0.274	0.52 ]		Err = 0.96960
ITER	4	X =	[-0.377	0.12	0.405]		Err = 0.44372
ITER	5	X =	[-0.612	0.065	0.342]		Err = 0.35452
ITER	6	X =	[-0.712	0.027	0.294]		Err = 0.15188
ITER	7	X =	[-0.756	0.006	0.269]		Err = 0.06862
ITER	8	X =	[-0.765	0.	0.263]		Err = 0.01524
ITER	9	X =	[-0.766	0.	0.262]		Err = 0.00078
ITER	10	X =	[-0.766	0.	0.262]		Err = 0.00000

Solução X = [-0.766 0. 0.262]

Buscando outra solução para o sistema:

```
In [55]: V = np.array([1,0.5, 2])
```

```
In [56]: X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

ITER	0	X =	[26.964	-0.711	-1.084]		Err = 0.96960
ITER	1	X =	[12.983	-1.043	-2.538]		Err = 1.05957
ITER	2	X =	[ 6.388	-1.031	-1.321]		Err = 1.01565
ITER	3	X =	[ 3.042	-0.98	-0.725]		Err = 1.03691
ITER	4	X =	[ 1.359	-0.803	-0.45 ]		Err = 1.04523
ITER	5	X =	[ 0.719	-0.418	-0.38 ]		Err = 0.81973
ITER	6	X =	[ 0.644	-0.143	-0.344]		Err = 0.38670
ITER	7	X =	[ 0.735	-0.068	-0.286]		Err = 0.16573
ITER	8	X =	[ 0.822	-0.027	-0.24 ]		Err = 0.12413
ITER	9	X =	[ 0.867	-0.006	-0.207]		Err = 0.06740
ITER	10	X =	[ 0.887	-0.	-0.19 ]		Err = 0.02949
ITER	11	X =	[ 0.891	-0.	-0.186]		Err = 0.00648
ITER	12	X =	[ 0.891	-0.	-0.185]		Err = 0.00031
ITER	13	X =	[ 0.891	-0.	-0.185]		Err = 0.00000

Solução X = [ 0.891 -0. -0.185]

### Método de Broden:

```
In [57]: X, i = broyden(X, B)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", np.reshape(np.round(X, 3), (1, -1)))
```

```
ITER 0 |X = [[ 0.893 -0.    -0.164]] | Err = 0.01140
ITER 1 |X = [[ 0.89  0.    -0.186]] | Err = 0.01168
ITER 2 |X = [[ 0.892  0.    -0.186]] | Err = 0.00110
ITER 3 |X = [[ 0.891  0.    -0.185]] | Err = 0.00080
ITER 4 |X = [[ 0.891  0.    -0.185]] | Err = 0.00002
```

Solução X = [[ 0.891 0. -0.185]]

**b)**

$$\theta_1 = 0.75$$

$$\theta_2 = 6.5$$

```
In [58]: theta1 = 0.75
theta2 = 6.5
```

### Método de Newton

```
In [59]: V = np.array([1,1,1])
X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

```
ITER 0 |X = [-5.725  1.568  1.265] | Err = 1.11288
ITER 1 |X = [-2.495  1.417  0.714] | Err = 1.10913
ITER 2 |X = [-0.888  0.993  0.494] | Err = 1.17928
ITER 3 |X = [-0.507  0.349  0.496] | Err = 0.94762
ITER 4 |X = [-0.375  0.186  0.393] | Err = 0.40711
ITER 5 |X = [-0.6    0.158  0.333] | Err = 0.33361
ITER 6 |X = [-0.683  0.163  0.288] | Err = 0.12433
ITER 7 |X = [-0.712  0.179  0.268] | Err = 0.04946
ITER 8 |X = [-0.716  0.183  0.265] | Err = 0.00834
ITER 9 |X = [-0.716  0.183  0.265] | Err = 0.00024
ITER 10 |X = [-0.716  0.183  0.265] | Err = 0.00000
```

Solução X = [-0.716 0.183 0.265]

Buscando outra solução para o sistema:

```
In [60]: V = np.array([1,0,0])
X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

```
ITER 0 |X = [1.    0.125 0.146] | Err = 0.18863
ITER 1 |X = [0.97  0.089 0.099] | Err = 0.06733
ITER 2 |X = [0.98  0.086 0.071] | Err = 0.03070
ITER 3 |X = [0.98  0.088 0.063] | Err = 0.00763
ITER 4 |X = [0.98  0.088 0.063] | Err = 0.00051
ITER 5 |X = [0.98  0.088 0.063] | Err = 0.00000
```

Solução X = [0.98 0.088 0.063]

### Método de Broyden

```
In [61]: X = np.array([1, 0, 0])
B = j(X)
X, i = broyden(V, B)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", np.reshape(np.round(X, 3), (1, -1)))
```

```
ITER 0 |X = [[1.    0.25  0.292]] | Err = 0.17930
ITER 1 |X = [[ 0.971  0.162 -0.115]] | Err = 0.21065
ITER 2 |X = [[ 0.876  0.169 -0.104]] | Err = 0.05356
ITER 3 |X = [[ 0.923  0.184 -0.109]] | Err = 0.02622
ITER 4 |X = [[ 0.92  0.187 -0.095]] | Err = 0.00727
ITER 5 |X = [[ 0.895  0.215 -0.163]] | Err = 0.04144
ITER 6 |X = [[ 0.642  0.365 -0.384]] | Err = 0.22098
ITER 7 |X = [[ 0.862  0.219 -0.154]] | Err = 0.19386
ITER 8 |X = [[ 0.855  0.23  -0.158]] | Err = 0.00758
ITER 9 |X = [[ 0.675  0.341 -0.254]] | Err = 0.14565
ITER 10 |X = [[ 0.809  0.242 -0.184]] | Err = 0.10472
ITER 11 |X = [[ 0.793  0.252 -0.198]] | Err = 0.01386
ITER 12 |X = [[ 0.778  0.255 -0.21  ]] | Err = 0.01142
ITER 13 |X = [[ 0.783  0.252 -0.208]] | Err = 0.00326
ITER 14 |X = [[ 0.783  0.251 -0.208]] | Err = 0.00066
ITER 15 |X = [[ 0.784  0.25  -0.208]] | Err = 0.00066
ITER 16 |X = [[ 0.784  0.25  -0.208]] | Err = 0.00012
ITER 17 |X = [[ 0.784  0.25  -0.208]] | Err = 0.00000
```

Solução X = [[ 0.784 0.25 -0.208]]

c)

$$\theta_1 = 0$$

$$\theta_2 = 11.667$$

```
In [62]: theta1 = 0
theta2 = 11.667
```

### Método de Newton

Com vetor inicial  $[1, 0, 0]$ .

```
In [63]: V = np.array([1, 0, 0])
X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

ITER	0	X =	[1. 0. 0.361]	Err = 0.33966
ITER	1	X =	[0.802 0. 0.272]	Err = 0.25605
ITER	2	X =	[0.933 0. 0.181]	Err = 0.16759
ITER	3	X =	[0.949 0. 0.136]	Err = 0.04905
ITER	4	X =	[0.955 0. 0.122]	Err = 0.01602
ITER	5	X =	[0.955 0. 0.121]	Err = 0.00137
ITER	6	X =	[0.955 0. 0.121]	Err = 0.00001

Solução X =  $[0.955 \ 0. \ 0.121]$

Buscando outra solução para o sistema, com vetor inicial  $[1, 1, 1]$

```
In [64]: V = np.array([1, 1, 1])
X, i = newton(V, tol, it_max)
X = np.round(X, 3)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", X)
```

ITER	0	X =	[-5.717 1.559 1.267]	Err = 1.11319
ITER	1	X =	[-2.493 1.402 0.719]	Err = 1.11041
ITER	2	X =	[-0.902 0.953 0.511]	Err = 1.18350
ITER	3	X =	[-0.54 0.251 0.533]	Err = 0.98964
ITER	4	X =	[-0.34 0.104 0.414]	Err = 0.50312
ITER	5	X =	[-0.549 0.05 0.357]	Err = 0.34055
ITER	6	X =	[-0.63 0.015 0.321]	Err = 0.13489
ITER	7	X =	[-0.653 0.002 0.31 ]	Err = 0.03988
ITER	8	X =	[-0.655 0. 0.309]	Err = 0.00359
ITER	9	X =	[-0.655 0. 0.309]	Err = 0.00003

Solução X =  $[-0.655 \ 0. \ 0.309]$

### Método de Broyden

```
In [65]: B = j(V)
X, i = broyden(V, B)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", np.reshape(np.round(X, 3), (1, -1)))
```

```
ITER 0 |X = [[-12.435  2.118  1.533]] | Err = 0.53089
ITER 1 |X = [[1.174 0.066 0.536]] | Err = 5.34060
ITER 2 |X = [[1.339 0.322 0.393]] | Err = 0.11741
ITER 3 |X = [[1.507 0.297 0.34 ]] | Err = 0.05656
ITER 4 |X = [[0.674 0.232 0.605]] | Err = 0.46882
ITER 5 |X = [[-5.109  0.029  1.995]] | Err = 0.54253
ITER 6 |X = [[0.812 0.111 0.585]] | Err = 3.02273
ITER 7 |X = [[0.991 0.048 0.554]] | Err = 0.08446
ITER 8 |X = [[-0.951  0.379  0.851]] | Err = 0.74831
ITER 9 |X = [[ 2.499 -0.08  0.288]] | Err = 0.70038
ITER 10 |X = [[-9.025  0.869  1.976]] | Err = 0.62964
ITER 11 |X = [[3.23  0.069 0.151]] | Err = 1.91929
ITER 12 |X = [[ 4.521  0.123 -0.011]] | Err = 0.14390
ITER 13 |X = [[1.951 0.086 0.26 ]] | Err = 0.65564
ITER 14 |X = [[1.446 0.075 0.296]] | Err = 0.17162
ITER 15 |X = [[0.942 0.058 0.324]] | Err = 0.25299
ITER 16 |X = [[0.713 0.046 0.33 ]] | Err = 0.14544
ITER 17 |X = [[0.619 0.039 0.326]] | Err = 0.06782
ITER 18 |X = [[0.613 0.036 0.321]] | Err = 0.00628
ITER 19 |X = [[0.621 0.035 0.318]] | Err = 0.00637
ITER 20 |X = [[ 1.642 -0.045 -0.007]] | Err = 0.32703
ITER 21 |X = [[0.652 0.027 0.292]] | Err = 0.72570
ITER 22 |X = [[0.703 0.019 0.265]] | Err = 0.03871
ITER 23 |X = [[-0.07  0.103  0.609]] | Err = 0.68373
ITER 24 |X = [[0.605 0.023 0.287]] | Err = 0.56178
ITER 25 |X = [[0.479 0.028 0.317]] | Err = 0.11251
ITER 26 |X = [[ 1.218 -0.003  0.142]] | Err = 0.30986
ITER 27 |X = [[0.672 0.017 0.261]] | Err = 0.38728
ITER 28 |X = [[0.79  0.011 0.228]] | Err = 0.07439
ITER 29 |X = [[0.902 0.005 0.194]] | Err = 0.06376
ITER 30 |X = [[0.873 0.006 0.198]] | Err = 0.01680
ITER 31 |X = [[0.882 0.005 0.193]] | Err = 0.00580
ITER 32 |X = [[0.901 0.003 0.178]] | Err = 0.01311
ITER 33 |X = [[0.922 0.001 0.16 ]] | Err = 0.01483
ITER 34 |X = [[0.924 0.001 0.156]] | Err = 0.00237
ITER 35 |X = [[0.919 0.001 0.161]] | Err = 0.00331
ITER 36 |X = [[ 0.94 -0.    0.14]] | Err = 0.01534
ITER 37 |X = [[ 0.94 -0.    0.139]] | Err = 0.00046
ITER 38 |X = [[0.937 0.    0.142]] | Err = 0.00179
ITER 39 |X = [[ 0.953 -0.001  0.124]] | Err = 0.01227
ITER 40 |X = [[ 0.953 -0.    0.123]] | Err = 0.00071
ITER 41 |X = [[ 0.948 -0.001  0.13 ]] | Err = 0.00478
ITER 42 |X = [[ 0.955 -0.    0.121]] | Err = 0.00593
ITER 43 |X = [[ 0.955 -0.    0.121]] | Err = 0.00007
```

Solução X = [[ 0.955 -0. 0.121]]

## Exercício 5)

$$f(x) = b_0 + b_1 x^{b_2}$$

$$x = [1, 2, 3]$$

$$y = [1, 2, 9]$$

### Mínimos quadrados

Rotina para definir a função  $f(x)$  e definir o jacobiano  $j(x)$  de  $f$ .

```
In [66]: def f(B):
    X = np.array([1, 2, 3])
    Y = np.array([1, 2, 9])
    b0, b1, b2 = B

    S = np.array([b0 + b1*(X[0]**b2) - Y[0],
                  b0 + b1*(X[1]**b2) - Y[1],
                  b0 + b1*(X[2]**b2) - Y[2]])

    return S
```

```
In [67]: def j(B):
    b0, b1, b2 = B
    J = np.array([[1, 1, 0],
                  [1, 2**b2, b1*(2**b2)*np.log(2)],
                  [1, 3**b2, b1*(3**b2)*np.log(3)]])

    return J
```

```
In [68]: def minimos(B, tol, it_max):
    it = 0
    err = 10

    while (err >= tol) and (it < it_max):
        J = j(B)
        F = f(B)
        delta = np.linalg.solve(
            np.dot(np.transpose(J), J), np.dot(np.transpose(J), -F))
        B = B + delta
        err = np.linalg.norm(delta)/np.linalg.norm(B)
        x = np.round(B, 3)
        print("ITER ", it, "|X = ", x, " | Err = %.5f" % err)
        it += 1

    return (B, it)
```

Definindo valores iniciais:

```
In [69]: B = np.array([0, 1, 2])
    tol = 0.0001
    it_max = 100
```

```
In [70]: V, i = minimos(B, tol, it_max)
V = np.round(V, 4)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", V)
```

```
ITER 0 |X = [ 2.643 -1.643  4.139] | Err = 0.83165
ITER 1 |X = [0.99  0.01  4.097] | Err = 0.55480
ITER 2 |X = [9.920e-01 8.000e-03 1.133e+01] | Err = 0.63594
ITER 3 |X = [9.9900e-01 1.0000e-03 1.1214e+01] | Err = 0.01030
ITER 4 |X = [9.9900e-01 1.0000e-03 1.0263e+01] | Err = 0.09224
ITER 5 |X = [9.980e-01 2.000e-03 8.634e+00] | Err = 0.18748
ITER 6 |X = [9.940e-01 6.000e-03 6.303e+00] | Err = 0.36530
ITER 7 |X = [0.978 0.022 4.163] | Err = 0.50031
ITER 8 |X = [0.988 0.012 7.159] | Err = 0.41454
ITER 9 |X = [0.986 0.014 6.31 ] | Err = 0.13301
ITER 10 |X = [0.978 0.022 5.418] | Err = 0.16194
ITER 11 |X = [0.97  0.03  5.051] | Err = 0.07150
ITER 12 |X = [0.969 0.031 5.064] | Err = 0.00260
ITER 13 |X = [0.969 0.031 5.063] | Err = 0.00014
ITER 14 |X = [0.969 0.031 5.063] | Err = 0.00000
```

Solução X = [0.9692 0.0308 5.0631]

Definindo novos valores iniciais:

```
In [71]: B = np.array([1, 0.5, 2])
tol = 0.0001
it_max = 100
```

```
In [72]: V, i = minimos(B, tol, it_max)
V = np.round(V, 4)
if i == it_max:
    print("O método não convergiu")
print("\nSolução X = ", V)
```

```
ITER 0 |X = [ 2.643 -1.643  6.277] | Err = 0.72196
ITER 1 |X = [0.978 0.022 6.285] | Err = 0.37019
ITER 2 |X = [0.978 0.022 5.713] | Err = 0.09859
ITER 3 |X = [0.973 0.027 5.204] | Err = 0.09620
ITER 4 |X = [0.969 0.031 5.064] | Err = 0.02715
ITER 5 |X = [0.969 0.031 5.063] | Err = 0.00018
ITER 6 |X = [0.969 0.031 5.063] | Err = 0.00000
```

Solução X = [0.9692 0.0308 5.0631]