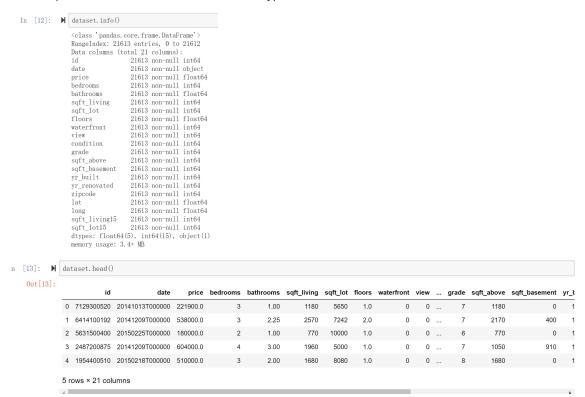
1. Linear Regression

DataSet: kc_house_data

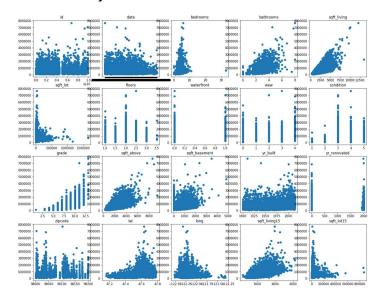
Source Code in "Linear_Regression.ipynb", use Jupyter Notebook to open.

DataSet details

Take a quick look at the dataset and its data types.



Visualize Analysis: Show the distribution of data.



Train/test split: Generally, use 90% of data for training, and 10% of data for testing. Shuffle the data first then split.

Algorithm Description

Data cleansing: I check the null values and 0 values in the dataset, the result shows there is no missing value in this dataset, so we don't need to do data cleansing.

Feature Choose: If we want to do linear regression, a linear relationship must be satisfied between the independent and dependent variables. From the pictures above, we can find some features: 'sqft_living','sqft_above','sqft_living15' Those features and 'price' can be seen to have a clear linear relationship. According to the meaning of these features, I chose 'sqft_living' as the feature to study. **Feature Scaling:** We only select one feature to do linear regression, so there is no need to do scaling, but since the data is in the million orders of magnitude, if we don't do scaling, the program will overflow, so I still use the mean-std-normalization to scale the data. Also, I store the mean and std to help denormalization after prediction.

Algorithm Details:

Since we only have one feature, suppose there is a line y = mx + b can fit data with minimal loss.

We use L2 loss.
$$Loss = \frac{1}{N} \sum_{i=1}^{N} (y_i - (mx_i + b))^2$$

To minimize the error, we let the partial derivative of each variable is zero

$$\frac{\partial Loss}{\partial m} = \frac{\frac{1}{N} \sum_{i=1}^{N} (y_i - (mx_i + b))^2}{\partial m} = -\frac{2}{N} \sum_{i=1}^{N} xi (y_i - (mx_i + b)) = 0$$

$$\frac{\partial Loss}{\partial b} = \frac{\frac{1}{N} \sum_{i=1}^{N} (y_i - (mx_i + b))^2}{\partial b} = -\frac{2}{N} \sum_{i=1}^{N} (y_i - (mx_i + b)) = 0$$

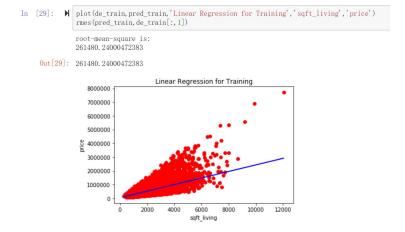
We can define a very small "step" aka "learning_rate" to update m,b.

$$b = b + step \times \frac{\partial Loss}{\partial b}$$
 $m = m + step \times \frac{\partial Loss}{\partial m}$

verge, we can get the minimum loss.

Algorithm Results

Set learning_rate = 0.001, plot the line and scatter the real data. Calculate the root-mean-square.



The model performance can vary with learning rate.

```
for i in range(3):
    b.m = LinearRegression(train_set, learning_rate=0,001*pow(10,i))
    pred_test = pred(test_set[:,0],b.m.df_mean[i:],df_std[1:])
    de_test = denormal_ization(test_set,df_mean,df_std)
    print('learning_rate = ",0,001*pow(10,i))
    rmes(pred_test,de_test[:,1])

learning_rate = 0.001
root-mean-square is:
287889.6170322912
learning_rate = 0.01
root-mean-square is:
281683.174959092
learning_rate = 0.1
root-mean-square is:
281682.99402821
```

Runtime

For each update, we need to traverse all data, calculate the gradient of every feature.

Each Iteration cost O(k*n) time. (K = feature size, n = data size)

Since we only have one feature here, so each iteration cost O(n) time

We don't know how many times the program will iterate until converge, it depends on learning rate and data itself.

Time complexity is O(iterationNumber * N).

The real wall time:

```
% witime
print("Training...")
b, m = LinearRegression(train_set)

Training...
Wall time: 36.9 s
```

2. Decision Tree

Consider the following set of training examples for the unknown target function $\langle X_1, X_2 \rangle \to Y$.

Y	X_1	X_2	Count
+	Τ	T	3
+	T	F	4
+	\mathbf{F}	\mathbf{T}	4
+	\mathbf{F}	\mathbf{F}	1
-	$\overline{\mathrm{T}}$	$_{ m T}^{ m F}$	0
-	\mathbf{T}	\mathbf{F}	1
-	\mathbf{F}	\mathbf{T}	3
1-0	\mathbf{F}	F	5

1. What is the sample entropy H(Y) for this training data (with logarithms base 2)?

$$C_{(Y='+')} = 12$$
 $C_{(Y='-')} = 9$

$$P_{(Y='+')} = \frac{12}{21} P_{(Y='-')} = \frac{9}{21}$$

$$H(Y) = -(\frac{12}{21} \times \log_2 \frac{12}{21} + \frac{9}{21} \times \log_2 \frac{9}{21}) = 0.985$$

2. What are the information gains $IG(X_1) \equiv H(Y) - H(Y|X_1)$ and $IG(X_2) \equiv H(Y) - H(Y|X_2)$ for this sample of training data?

$$H(Y|X_1) = -\frac{8}{21} \times (\frac{7}{8} \times \log_2 \frac{7}{8} + \frac{1}{8} \times \log_2 \frac{1}{8}) - \frac{13}{21} \times \left(\frac{5}{13} \times \log_2 \frac{5}{13} + \frac{8}{13} \times \log_2 \frac{8}{13}\right) = 0.802$$

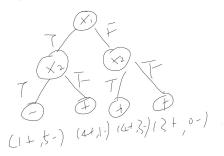
$$H(Y|X_2) = -\frac{10}{21} \times \left(\frac{7}{10} \times \log_2 \frac{7}{10} + \frac{3}{10} \times \log_2 \frac{3}{10}\right) - \frac{11}{21} \times \left(\frac{5}{11} \times \log_2 \frac{5}{11} + \frac{6}{11} \times \log_2 \frac{6}{11}\right) = 0.94$$

$$IG(X_1) = 0.183$$

$$IG(X_2) = 0.045$$

3. Draw the decision tree that would be learned by ID3 (without postpruning) from this sample of training data.

We want to maximize the IG so we choose X1 to be the first condition.



3. Perceptron

Use Jupyter Notebook to open file "Chuchu_Jin_python_HW2_Perceptron.ipynb"

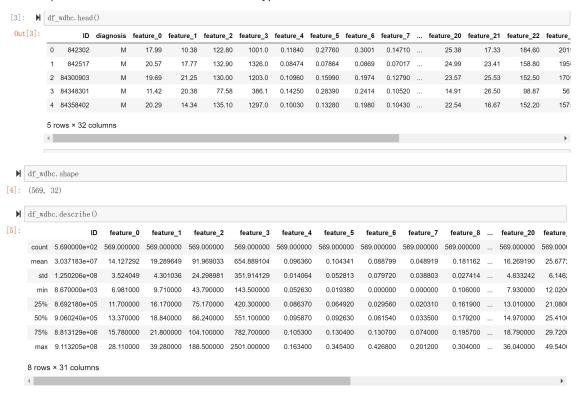
4. Support Vector Machine

DataSet: wdbc.data

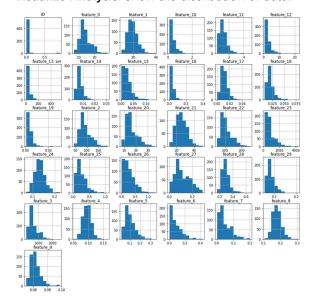
Source Code in "svm-smo.ipynb", use Jupyter Notebook to oepn

DataSet details

Take a quick look at the dataset and its data types.



Visualize Analysis: Show the distribution of data.



Train/test split: I choose 2/3 data for training, and 1/3 data for testing. Shuffle the data first then split.

Algorithm Description

Data cleansing: In file "wdbc.names" we know there is no miss value in this dataset, so we don't need to do data cleansing.

Feature Scaling: As the data have very different range of value, we need to scale the data to make it easy to train.

Algorithm Details:

I use SMO to implement SVM.

$$\vec{w} = \sum_{i=1}^{N} y_i \alpha_i \vec{x}_i, \quad b = \vec{w} \cdot \vec{x}_k - y_k \text{ for some } \alpha_k > 0$$

$$\alpha_i = 0 \Leftrightarrow y_i u_i \ge 1,$$

$$0 < \alpha_i < C \Leftrightarrow y_i u_i = 1,$$

$$\alpha_i = C \Leftrightarrow y_i u_i \le 1.$$

ai means

- 1. Choose the first a1 that obey the KKT condition, choose a random a2.
- 2. Calculate the upper and lower bound for a2

•
$$L = \max(0, \alpha_2^{old} - \alpha_1^{old}), H = \min(C, C + \alpha_2^{old} - \alpha_1^{old}), if y_1 \neq y_2$$

• $L = \max(0, \alpha_2^{old} + \alpha_1^{old} - C), H = \min(C, \alpha_2^{old} + \alpha_1^{old}), if y_1 = y_2$

3. Update a2

$$\begin{split} E_{i} &= u_{i} - y_{i} \quad \eta = K(\vec{x}_{1}, \vec{x}_{1}) + K(\vec{x}_{2}, \vec{x}_{2}) - 2K(\vec{x}_{1}, \vec{x}_{2}) \\ \alpha_{2}^{new,unc} &= \alpha_{2}^{old} + \frac{y_{2}(E_{1} - E_{2})}{\eta} \\ \alpha_{2}^{new} &= \left\{ \begin{array}{l} H, & \alpha_{2}^{new,unc} > H \\ \alpha_{2}^{new,unc}, & L \leq \alpha_{2}^{new,unc} \leq H \\ L, & \alpha_{2}^{new,unc} < L \end{array} \right. \end{split}$$

$$\alpha_1^{new} = \alpha_1^{old} + y_1 y_2 (\alpha_2^{old} - \alpha_2^{new})$$

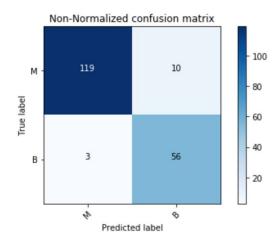
5. Update b

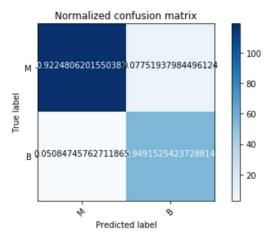
$$\begin{split} b_1^{new} &= b^{old} - E_1 - y_1(\alpha_1^{new} - \alpha_1^{old})k(x_1, x_1) - y_2(\alpha_2^{new} - \alpha_2^{old})k(x_1, x_2) \\ b_2^{new} &= b^{old} - E_2 - y_1(\alpha_1^{new} - \alpha_1^{old})k(x_1, x_2) - y_2(\alpha_2^{new} - \alpha_2^{old})k(x_2, x_2) \\ b &= \left\{ \begin{array}{ll} b_1 & \text{if } 0 < \alpha_1^{new} < C \\ b_2 & \text{if } 0 < \alpha_2^{new} < C \\ (b_1 + b_2)/2 & \text{otherwise} \end{array} \right. \end{split}$$

6. Loop Step 1-5 until alpha and b converge.

Algorithm Results

Accuracy is: 0.9308510638297872
Non-Normalized confusion matrix
[[119 10]
[3 56]]
Normalized confusion matrix
[[0.92 0.08]
[0.05 0.95]]





Runtime

In each iteration,

For each alpha, (we have n alpha)

Firstly, we calculate w base on alpha, x and y, cost O(n) time

Then we check if the alpha(i) satisfy the KKT condition, if not, choose another alpha(j),update them. So, each iteration cost $O(n^2)$ time.

We don't know how many times will it converge. Time complexity is $O(\text{iteration} \text{Number} * \text{N}^2)$.

The real wall time: