

WEAK SHARP MINIMA FOR CONVEX INFINITE OPTIMIZATION PROBLEMS IN NORMED LINEAR SPACES*

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Abstract. In the present paper, we study the characterization issue of the weak sharp minima properties for convex infinite optimization problems in normed linear spaces. We develop a new approach to establish several complete geometric characterizations for the global/bounded/local weak sharp minima property, which extend/improve the corresponding ones in this direction by removing/relaxing the key topological assumptions made on the index set. As by-products, some complete characterizations of the global/bounded/local weak sharp minima are obtained for a subset of the level set of a given convex function (not necessarily the level set itself) in terms of the normal cones and the subdifferentials of the involved convex subset and convex function. These characterization results are of independent interest in extending/improving the existing ones on characterizing the weak sharp minima for convex optimization problems.

Key words. weak sharp minima, convex optimization, infinite optimization problems, ε -subdifferentials

AMS subject classifications. 49J52, 46N10

DOI. 10.1137/16M1139564

1. Introduction. Let X be a normed space, Ω be a nonempty closed and convex subset of X , and Y be an arbitrary index set. Let $f : X \rightarrow \overline{\mathbb{R}} := \mathbb{R} \cup \{+\infty\}$ be a proper and lower semicontinuous (in short, lsc) function and let $\phi_{(\cdot)}(\cdot) : X \times Y \rightarrow \overline{\mathbb{R}}$ be such that the function $x \mapsto \phi_y(x)$ is lsc for each $y \in Y$. In the present paper, we consider the following infinite optimization problem:

$$(1.1) \quad \begin{array}{ll} \min & f(x) \\ \text{subject to (s.t.)} & x \in \Omega, \\ & \phi_y(x) \leq 0 \quad \forall y \in Y. \end{array}$$

*Received by the editors July 19, 2017; accepted for publication (in revised form) March 29, 2018; published electronically July 12, 2018.

<http://www.siam.org/journals/siopt/28-3/M113956.html>

Funding: Research of the first author was partially supported by the National Natural Science Foundation of China (grant 11571308) and Zhejiang Provincial Natural Science Foundation of China (grants LY18A010004 and LY17A010021). Research of the third author was partially supported by the National Natural Science Foundation of China (grant 11101363), the Youth Talent Foundations of Zhejiang Gongshang University (grant QY15-15) and the China Scholarship Council. Research of the fourth author was partially supported by the National Natural Science Foundation of China (grant 11601343), the Natural Science Foundation of Guangdong (grant 2016A030310038), the HD Video R&D Platform for Intelligent Analysis and Processing in Guangdong Engineering Technology Research Centre of Colleges and Universities (grant GCZX-A1409) and Interdisciplinary Innovation Team of Shenzhen University. Research of the fifth author was partially supported by the grant MOST 105-2115-M-039-002-MY3.

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This kind of problem arises in many practical applications, such as engineering design [31, 32], control of robots [17, 34], data envelopment analysis [24], statistics [12], and social sciences [19, 35] (see also the survey paper [20] and books [1, 4, 15, 16, 33]), and has become an active research area in mathematical programming; see [25, 26, 27, 28, 29, 30, 36, 40, 41, 42, 45] and references therein. Our interest in the present paper is focused on the convex infinite optimization problem, that is, we assume, throughout the whole paper, for problem (1.1) that

- Ω is closed and convex;
- $f : X \rightarrow \overline{\mathbb{R}}$ and $\phi_y : X \rightarrow \overline{\mathbb{R}}$ are proper, lsc, and convex for each $y \in Y$.

Let S denote the *solution set* of problem (1.1), that is,

$$(1.2) \quad S := \left\{ z \in Z \mid f(z) = \inf_{x \in Z} f(x) \right\},$$

where $Z := \{x \in \Omega \mid \phi_y(x) \leq 0 \text{ for each } y \in Y\}$. Let $\alpha > 0$ and $x_0 \in S$. Then, following [42], problem (1.1) is said to have the (global) weak sharp minima property with modulus $\alpha > 0$ if

$$\alpha d_S(x) \leq f(x) - f(x_0) + \sup_{y \in Y} [\phi_y]_+(x) + d_\Omega(x) \quad \text{for each } x \in X.$$

One important issue in the development of infinite optimization problems is to provide the geometric characterizations for the weak sharp minima property, especially in terms of the normal cones and the subdifferentials of the involved convex subsets and convex functions. Under the assumptions that

(A1) Y is a compact metric space such that $\phi_{(\cdot)}(x)$ is continuous for each $x \in X$, and

(A2) $\phi_{(\cdot)}(\cdot)$ is real valued and jointly upper semicontinuous (in short, usc) on $X \times Y$, Zheng and Yang established in [42, Theorem 3.4] the following characterization result for the weak sharp minima property for problem (1.1) in a Banach space.

THEOREM 1.1. *Problem (1.1) has the weak sharp minima property with modulus α if and only if*

$$\alpha \mathbb{B}^* \cap N_S(z) \subseteq \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_0(z)} \partial \phi_y(z)) + N_\Omega(z) \cap \mathbb{B}^* \quad \text{for each } z \in \text{bd}S,$$

where $Y_0(z) := \{y \in Y \mid \phi_y(z) = 0\}$ and $\text{bd}S$ denotes the boundary of S .

The study of the weak sharp minima property, as well as the boundedly and local weak sharp minima properties, for the infinite optimization problem seems limited, and, to the best of our knowledge, it has not been founded for the case in which the topological assumptions on the index set Y in (A1) and/or (A2) are dropped. This motivates us to investigate the geometric characterization problem of the weak sharp minima property for convex infinite optimization problem (1.1) without any topological assumptions made on Y . Using the ε -subdifferentials, instead of the subdifferentials, of the involved functions, we establish some characterization results similar to Theorem 1.1 for the weak sharp minima property (and also for the boundedly or local weak sharp minima property) for the general problem (1.1); see Theorems 4.8–4.10. In particular, as a consequence, we show that Theorem 1.1 remains true in normed linear spaces under the following weaker assumptions:

- (B1) Y is a separated compact topological space and $\phi_{(\cdot)}(x)$ is usc on Y for each $x \in X$;
- (B2) $\phi_y(\cdot)$ is continuous on S for each $y \in Y$.

(Note that the real-valuedness assumption for $\phi_{(\cdot)}(\cdot)$ in (A2) implies (B2)). The results obtained in the present paper contain not only the complete characterizations for the (global) weak sharp minima property, but also the ones for the bounded and/or local weak sharp minima property, most of which seem new.

To furnish the establishment of the proposed results, we shall first introduce and investigate the notion of weak sharp minima for a subset S_0 of the level set $L_f(\lambda) := \{x \in X | f(x) = \lambda\}$ (not necessarily the level set $L_f(\lambda)$ itself): S_0 is said to be a set of the (global) weak sharp minima for the function f with modulus $\alpha > 0$ if

$$f(z) \geq \lambda + \alpha \text{d}_{S_0}(z) \quad \text{for each } z \in X.$$

The notions of boundedly weak sharp minima and local weak sharp minima for the function f are defined similarly; see Definition 3.1 for details. In the special case in which $S_0 = \bar{S} := \text{argmin}_{x \in X} f(x)$, the notion of weak sharp minima for f is reduced to the classical one for the following optimization problem:

$$(1.3) \quad \begin{array}{ll} \min & f(x) \\ \text{s.t.} & x \in X. \end{array}$$

The notion of the classical (global) weak sharp minima for optimization problem (1.3) introduced by Ferris in [13], as well as the notions of boundedly weak sharp minima and local weak sharp minima introduced by Burke and Deng in [5], have been extensively studied and widely applied in the sensitivity and convergence analysis of many optimization algorithms; see [2, 6, 7, 8, 9, 14, 21, 22, 23, 37, 38, 41, 44] and references therein. In particular, the theory regarding the characterization of the (global) weak sharp minima for problem (1.3) is well established; see [5, 8, 39] and references therein. In fact, as presented in [39, Theorem 3.10.1] and [5, Theorem 2.3], one has the following complete characterizations for the solution set to be a set of weak sharp minima, where $J(\cdot)$ is the duality mapping, $P(\cdot|\bar{S})$ denotes the projection onto \bar{S} , and $T_{\bar{S}}(\cdot)$ denotes the tangent cone of \bar{S} ; see section 2 for details.

THEOREM 1.2. *Let $\alpha > 0$ and $\bar{S} := \text{argmin}_{x \in X} f(x)$. Consider the following statements:*

- (i) \bar{S} is a set of weak sharp minima for f with modulus α .
- (ii) For any $x \in X$ and $p \in P(x|\bar{S})$, $f'(p; x - p) \geq \alpha \text{d}_{\bar{S}}(x)$.
- (iii) For any $\bar{x} \in \bar{S}$ and $u \in J^{-1}(N_{\bar{S}}(\bar{x}))$, $f'(\bar{x}; u) \geq \|u\|$.
- (iv) For any $\bar{x} \in \bar{S}$ and $u \in J^{-1}(N_{\bar{S}}(\bar{x})) \cap \text{cone}(\text{dom} f - \bar{x})$, $f'(\bar{x}; u) \geq \|u\|$.
- (v) For any $\bar{x} \in \bar{S}$ and $u \in X$, $f'(\bar{x}; u) \geq \alpha \text{d}_{T_{\bar{S}}(\bar{x})}(u)$.
- (vi) For any $\bar{x} \in \bar{S}$, $\alpha \mathbb{B}^* \cap N_{\bar{S}}(\bar{x}) \subseteq \partial f(\bar{x})$.

Then (i) \Rightarrow (ii) \Rightarrow (iii) \Leftrightarrow (iv) and (i) \Leftrightarrow (v) \Leftrightarrow (vi). If X is a reflexive Banach space, then all above statements are equivalent.

However, to the best of our knowledge, the theory of characterizations for either bounded or local weak sharp minima for problem (1.3) is still far from being as complete as that for the global one, even in the reflexive Banach space setting; see the explanations before Theorem 3.8. As by-products, we will also establish the complete characterization results, similar to the ones presented in Theorem 1.2, for a subset $S_0 \subseteq L_f(\lambda)$ to be a set of global/boundedly/local weak sharp minima for f ; see Theorems 3.6–3.9. Our characterization results are of independent interest in the development of weak sharp minima for convex optimization problem (1.3) and play a key role in the following study of the weak sharp minima property for the infinite convex optimization problem (1.1). In particular, these results not only extend Theorem 1.2 for the weak sharp minima from the special case in which $S_0 = \bar{S}$ to the

general case in which S_0 is a subset of a level set, but also provide complete characterizations for the boundedly and/or local weak sharp minima, which particularly improve the existing corresponding results even in the special case in which $S_0 = \bar{S}$; see the explanations before Theorems 3.6 and 3.8 for details. The approaches used here for treating the weak sharp minima property for f or problem (1.1) deviate from that used in [5, 8, 39]: for the function f , we establish the relationships between the equivalent characterizations of weak sharp minima for a subset S_0 of the level set and the ones for the minima set \bar{S} (see Proposition 3.4); for problem (1.1), we introduce an auxiliary function to develop a bridge connecting the weak sharp minima property for problem (1.1) and the weak sharp minima for the auxiliary function over the set S defined as in (1.2) (see Proposition 4.2).

The present paper is organized as follows. In section 2, we present some basic notation and preliminary results used in what follows, mostly for convex functions and sets in normed spaces. Section 3 is devoted to the completed theory of geometric characterizations for a subset of a level set to be a set of global/boundedly/local weak sharp minima for a given function. In section 4, we apply the results obtained in section 3 to investigate the characterization problem of the weak sharp minima property for infinite convex optimization problem (1.1).

2. Notation and preliminary results. Let X be a normed space with norm $\|\cdot\|$ and let X^* be its dual. We use $\langle \cdot, \cdot \rangle$ to denote the canonical pairing between X^* and X , that is, $\langle x^*, x \rangle := x^*(x)$ for each pair $(x^*, x) \in X^* \times X$. The closed ball with radius $r > 0$ and center x in X or X^* is denoted by $\mathbb{B}(x, r)$; in particular, $\mathbb{B} := \mathbb{B}(0, 1)$ stands for the closed unit ball in X or X^* . The duality mappings $J : X \rightarrow X^*$ and $J^* : X^* \rightarrow X$ are the set-valued mappings defined respectively by

$$J(x) := \{x^* \in X^* | \langle x^*, x \rangle = \|x^*\|^2 = \|x\|^2\} \quad \text{for each } x \in X$$

and

$$J^*(x^*) := \{x \in X | \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\} \quad \text{for each } x^* \in X^*.$$

Clearly, X is reflexive if and only if J is surjective, and in particular, when X is a Hilbert space, then one has that $J = J^* = \mathbf{I}$, the identity on X ; see, for example, [3, 11, 39].

For a nonempty set A in X or X^* , the closure (resp., interior, weak*-closure, convex hull, convex conical hull, polar) of A is denoted by $\text{cl}A$ (resp., $\text{int}A$, cl^*A , $\text{co}A$, $\text{con}A$, A°). As usual, we use $N_A(\cdot)$ and $T_A(\cdot)$ to stand for the norm cone mapping and the tangent cone mapping of A (assuming that A is closed and convex), defined by

$$N_A(x) := \{x^* \in X^* | \langle x^*, y - x \rangle \leq 0 \ \forall y \in A\} \quad \text{for each } x \in A$$

and

$$T_A(x) := (N_A(x))^\circ = \text{cl con}(A - x) \quad \text{for each } x \in A,$$

respectively. Associated with A , the distance function and the metric projection operator are denoted by $d_A(\cdot)$ and $P(\cdot|A)$, and are defined by

$$d_A(x) := \inf_{z \in A} \|z - x\| \quad \text{for each } x \in X$$

and

$$P(x|A) := \{y \in A | \|x - y\| = d_A(x)\} \quad \text{for each } x \in X,$$

respectively. Obviously, d_A is Lipschitz continuous on X with modulus 1, and it is also well known (see, for example, [39]) that, in the case in which A is nonempty

closed and convex, A is proximal (i.e., $P(x|A) \neq \emptyset$ for each $x \in X$) if X is a reflexive space, and $P(\cdot|A)$ is Lipschitz continuous with modulus 1 if X is a Hilbert space. Some other useful properties are described in the following lemma; see [39, Theorem 3.8.4 and Corollary 3.8.5] for (i) and (ii), and [5, Theorem A.1] for (iii).

LEMMA 2.1. *Let $A \subseteq X$ be a nonempty closed and convex set and let $\bar{x} \in A$. Then the following assertions hold:*

- (i) *For any $x \in X$, $\bar{x} \in P(x|A)$ if and only if $J(x - \bar{x}) \cap N_A(\bar{x}) \neq \emptyset$.*
- (ii) *For any $v \in J^*N_A(\bar{x})$ and $t > 0$, $\bar{x} \in P(\bar{x} + tv|A)$.*
- (iii) *For any $x \in X$, $d_A(x) = \sup_{y \in A} d_{y+T_A(y)}(x)$.*

For $A \subseteq X$, the indicator function and the support function of A are defined by

$$\delta_A(x) := \begin{cases} 0, & x \in A, \\ +\infty, & x \in X \setminus A, \end{cases}$$

and

$$\delta_A^*(x^*) := \sup\{\langle x^*, x \rangle | x \in A\} \quad \text{for each } x^* \in X^*,$$

respectively. The following lemma is taken from [5, Theorem A.1], which will be used frequently in what follows.

LEMMA 2.2. *Let E and F be two nonempty convex subsets of X^* and let C be a nonempty closed and convex cone in X . Then we have that*

$$(2.1) \quad d_C(x) = \delta_{C^\circ \cap \mathbb{B}}^*(x) \quad \text{for each } x \in X$$

and

$$(2.2) \quad [\delta_E^*(x) \leq \delta_F^*(x) \quad \forall x \in C] \Leftrightarrow [\delta_E^*(x) \leq \delta_{F+C^\circ}^*(x) \quad \forall x \in X] \Leftrightarrow E \subseteq \text{cl}^*(F + C^\circ).$$

Another useful lemma regarding the distance function and metric projection is as follows.

LEMMA 2.3. *Let $0 < r \leq +\infty$ and S_0 be a nonempty closed set. Let $x_0 \in S_0$ and $x \in \mathbb{B}(x_0, r)$. Then we have that*

$$(2.3) \quad d_{S_0}(x) = d_{S_0 \cap \mathbb{B}(x_0, 2r)}(x) \quad \text{and} \quad P(x|S_0) \subseteq \mathbb{B}(x_0, 2r).$$

Proof. Let $y \in S_0 \setminus \mathbb{B}(x_0, 2r)$. Then one has that $2\|x - x_0\| < \|y - x_0\|$ (noting that $\|x - x_0\| \leq r$ and $\|y - x_0\| > 2r$), and so

$$d_{S_0 \cap \mathbb{B}(x_0, 2r)}(x) \leq \|x_0 - x\| < \|y - x_0\| - \|x_0 - x\| \leq \|y - x\|.$$

Hence (2.3) holds, and the proof is complete. \square

Let $f : X \rightarrow \overline{\mathbb{R}}$ be a proper and convex function. As usual, the effective domain and the epigraph of f are denoted by $\text{dom} f$ and $\text{epi} f$, and defined by

$$\text{dom} f := \{x \in X | f(x) < +\infty\}$$

and

$$\text{epi} f := \{(x, r) | f(x) \leq r\},$$

respectively. Recall that f is lsc on X if and only if its epigraph $\text{epi} f$ is closed in $X \times \overline{\mathbb{R}}$, and its lsc hull (or its closure) is the function $\text{cl} f : X \rightarrow \overline{\mathbb{R}}$ satisfying

$$\text{epi}(\text{cl} f) = \text{cl}(\text{epi} f),$$

which is the greatest lsc function not exceeding f . We recall in the following definition the notions of the subdifferential and the ε -subdifferential for a proper and convex function.

DEFINITION 2.4. Let $f : X \rightarrow \overline{\mathbb{R}}$ be a proper and convex function, and let $\varepsilon \geq 0$ and $\bar{x} \in \text{dom} f$. The ε -subdifferential of f at \bar{x} is defined by

$$\partial_\varepsilon f(\bar{x}) := \{x^* \in X^* \mid \langle x^*, x - \bar{x} \rangle \leq f(x) - f(\bar{x}) + \varepsilon \ \forall x \in X\}.$$

In particular, $\partial f(\bar{x}) := \partial_0 f(\bar{x})$ is called the subdifferential of f at \bar{x} .

Remark 2.5. (a) Recall that the directional derivative $f'(\bar{x}; \cdot) : X \rightarrow \overline{\mathbb{R}}$ of f at \bar{x} is defined by

$$f'(\bar{x}; w) = \lim_{t \downarrow 0} \frac{f(\bar{x} + tw) - f(\bar{x})}{t} = \inf_{t > 0} \frac{f(\bar{x} + tw) - f(\bar{x})}{t} \quad \text{for each } w \in X.$$

Then, by [39, Corollary 2.4.15], one has the following relationship between $f'(\bar{x}; \cdot)$ and $\partial f(\bar{x})$:

$$(2.4) \quad \text{cl} f'(\bar{x}; \cdot) = \delta_{\partial f(\bar{x})}^*(\cdot).$$

(b) In particular, $J(x) = \partial(\frac{1}{2}\|\cdot\|^2)(x)$ for each $x \in X$, and

$$(2.5) \quad \partial d_A(x) = N_A(x) \cap \mathbb{B} \quad \text{and} \quad \partial \delta_A(x) = N_A(x) \quad \text{for each } x \in A,$$

where $A \subseteq X$ is a nonempty closed and convex set.

The sum rules for subdifferentials and ε -subdifferentials are given in the following lemma, which are known in [39, Corollary 2.6.7 and Theorem 2.8.7] and will be used in section 4.

LEMMA 2.6. Let $f_1, f_2 : X \rightarrow \overline{\mathbb{R}}$ be two proper lsc and convex functions. Let $z \in \text{dom} f_1 \cap \text{dom} f_2$ and $\varepsilon \geq 0$. Then the following equalities are true:

(i) $\partial_\varepsilon(f_1 + f_2)(z) = \cap_{\eta > 0} \text{cl}^*(\cup_{\varepsilon_i \geq 0, \varepsilon_i + \eta = \varepsilon_1 + \varepsilon_2} (\partial_{\varepsilon_1} f_1(z) + \partial_{\varepsilon_2} f_2(z)))$.

(ii) $\partial(f_1 + f_2)(z) = \cap_{\eta > 0} \text{cl}^*(\partial_\eta f_1(z) + \partial_\eta f_2(z))$.

Further, suppose that f_1 is continuous at some point $\bar{x} \in \text{dom} f_2$. Then the following equalities are true:

(iii) $\partial_\varepsilon(f_1 + f_2)(z) = \cup_{\varepsilon_i \geq 0, \varepsilon_i = \varepsilon_1 + \varepsilon_2} (\partial_{\varepsilon_1} f_1(z) + \partial_{\varepsilon_2} f_2(z))$.

(iv) $\partial(f_1 + f_2)(z) = \partial f_1(z) + \partial f_2(z)$.

3. Weak sharp minima for convex optimization problems. Let X be a normed space and $f : X \rightarrow \overline{\mathbb{R}}$ be a proper lsc and convex function. In this section, we consider the convex optimization problem

$$(3.1) \quad \begin{array}{ll} \min & f(x) \\ \text{s.t.} & x \in X, \end{array}$$

denoting its solution set by \bar{S} , i.e., $\bar{S} = \text{argmin}_{x \in X} f(x)$. Throughout the section, we define the set-valued mapping $L_f : \mathbb{R} \rightarrow 2^X$ by

$$L_f(\lambda) := \{x \in X \mid f(x) = \lambda\} \quad \text{for each } \lambda \in \mathbb{R},$$

and make the following assumption:

- $\lambda \in \mathbb{R}$ and $S_0 \subseteq L_f(\lambda)$ is a nonempty closed and convex set.

The notions of weak sharp minima in the following definition are the extensions of the corresponding ones in [5] for the special case in which $S_0 = \bar{S}$.

DEFINITION 3.1. Let $\alpha > 0$ and $x_0 \in S_0$.

- (a) x_0 is called a local weak sharp minimum over S_0 for f with modulus α if there exists $r > 0$ such that

$$(3.2) \quad \alpha d_{S_0}(x) \leq f(x) - f(x_0) \quad \text{for each } x \in \mathbb{B}(x_0, r).$$

- (b) S_0 is called a set of boundedly weak sharp minima for f if, for each $r > 0$, there exists $\alpha(= \alpha_r) > 0$ such that (3.2) holds with 0 in place of x_0 .
 (c) S_0 is called a set of (global) weak sharp minima for f with modulus α if (3.2) holds for $r = +\infty$.

Let $0 < r \leq +\infty$. Then the following implications are clear by definition:

$$(3.3) \quad (3.2) \Rightarrow [L_f(\lambda) \cap \mathbb{B}(x_0, r) = S_0 \cap \mathbb{B}(x_0, r) = \bar{S} \cap \mathbb{B}(x_0, r)];$$

consequently

$$(3.4) \quad [(c) \text{ in Definition 3.1}] \Rightarrow [(b) \text{ in Definition 3.1}] \Rightarrow [S_0 = L_f(\lambda) = \bar{S}].$$

Remark 3.2. Let $S \subseteq X$ be a nonempty closed and convex set. Associated with the following constrained optimization problem

$$(3.5) \quad \begin{array}{ll} \min & f(x) \\ \text{s.t.} & x \in S, \end{array}$$

we define

$$f_S(x) := (f + \delta_S)(x) = \begin{cases} f(x), & x \in S, \\ +\infty & \text{otherwise.} \end{cases}$$

Then the constrained optimization problem (3.5) is equivalent to problem (3.1) with f_S in place of f , and $L_{f_S}(\lambda) = S \cap L_f(\lambda)$ for each $\lambda \in \mathbb{R}$. Moreover, letting $S_0 \subseteq L_{f_S}(\lambda)$, one has that S_0 is a set of global (or boundedly) weak sharp minima for f over the set S (see [5] for the special case in which $S_0 = \operatorname{argmin}_{x \in S} f$) if and only if S_0 is a set of global (or boundedly) weak sharp minima for f_S . A similar result holds for the local weak sharp minima.

In the special case in which $S_0 = \bar{S}$, the assertions in the following proposition on the characterizations for the weak sharp minima are known from [5, Theorems 2.3, 5.2, and 6.3], and will also be used for our study in what follows.

PROPOSITION 3.3. Let $\alpha > 0$ and $x_0 \in \bar{S}$. Then we have the following assertions:

- (i) If x_0 is a local weak sharp minimum for f (over \bar{S}) with modulus α , then there exists $r > 0$ such that

$$(3.6) \quad \alpha \mathbb{B} \cap N_{\bar{S}}(z) \subseteq \partial f(z) \quad \text{for each } z \in \bar{S} \cap \mathbb{B}(x_0, r).$$

- (ii) If \bar{S} is a set of boundedly weak sharp minima for f , then, for each $r > 0$, there exists $\alpha(= \alpha_r) > 0$ such that (3.6) holds (with 0 in place of x_0).
 (iii) \bar{S} is a set of weak sharp minima for f with modulus α if and only if (3.6) holds for $r = +\infty$.

The following two propositions are the key tools for our study in this section.

PROPOSITION 3.4. *Let $S_0 \subseteq \text{dom} f$ be nonempty closed and convex, and let $\alpha > 0$ and $z \in S_0$. Consider the following statements:*

$$(3.7) \quad f'(z; \nu) \geq \alpha d_{T_{S_0}(z)}(\nu) \quad \text{for each } \nu \in X,$$

$$(3.8) \quad \alpha \mathbb{B} \cap N_{S_0}(z) \subseteq \partial f(z),$$

$$(3.9) \quad \alpha \mathbb{B} \cap N_{S_0}(z) \subseteq \partial f(z) + [J^* N_{S_0}(z)]^\circ,$$

$$(3.10) \quad f'(z; \nu) \geq \alpha \|\nu\| \quad \text{for each } \nu \in J^* N_{S_0}(z),$$

$$(3.11) \quad \alpha \mathbb{B} \subseteq \text{cl}^*(\partial f(z) + [J^* N_{S_0}(z)]^\circ).$$

Then one has that

$$(3.12) \quad (3.7) \Leftrightarrow (3.8) \Rightarrow (3.9) \Rightarrow (3.10),$$

and, if X is a Hilbert space,

$$(3.13) \quad (3.9) \Rightarrow (3.11) \Rightarrow (3.10).$$

Proof. We first note by (2.1) in Lemma 2.2 (applied to $T_{S_0}(z)$ in place of C) that

$$\alpha d_{T_{S_0}(z)}(\nu) = \alpha \delta_{\mathbb{B} \cap [T_{S_0}(z)]^\circ}^*(\nu) = \delta_{\alpha \mathbb{B} \cap N_{S_0}(z)}^*(\nu) \quad \text{for each } \nu \in X.$$

It follows from (2.4) and (2.2) (applied to $\alpha \mathbb{B} \cap N_{S_0}(z)$, $\partial f(z)$, X in place of E , F , C) that

$$\begin{aligned} (3.7) & \Leftrightarrow \text{cl} f'(z; \nu) \geq \alpha d_{T_{S_0}(z)}(\nu) \quad \text{for each } \nu \in X \\ & \Leftrightarrow \delta_{\partial f(z)}^*(\nu) \geq \delta_{\alpha \mathbb{B} \cap N_{S_0}(z)}^*(\nu) \quad \text{for each } \nu \in X \\ & \Leftrightarrow (3.8), \end{aligned}$$

where the first equivalence holds because the function $d_{T_{S_0}(z)}(\cdot)$ is continuous, and $(3.7) \Leftrightarrow (3.8)$ is shown. Hence, to complete the proof of (3.12), it suffices to verify the implication $(3.9) \Rightarrow (3.10)$ because the implication $(3.8) \Rightarrow (3.9)$ is trivial. Consider the following statement:

$$(3.14) \quad \text{cl} f'(z; \cdot)(\nu) \geq \alpha \|\nu\| \quad \text{for each } \nu \in J^* N_{S_0}(z).$$

Clearly, to show the implication $(3.9) \Rightarrow (3.10)$, we only need to check the following implication:

$$(3.15) \quad (3.9) \Rightarrow (3.14).$$

To do this, we note that

$$(3.16) \quad \delta_{\alpha \mathbb{B}}^*(\nu) = \delta_{\alpha \mathbb{B}^* \cap N_{S_0}(z)}^*(\nu) = \alpha \|\nu\| \quad \text{for each } \nu \in J^* N_{S_0}(z)$$

because, for each $\nu \in J^* N_{S_0}(z)$, one has that

$$\|\nu\| = \delta_{\mathbb{B}}^*(\nu) \geq \delta_{\mathbb{B}^* \cap N_{S_0}(z)}^*(\nu) \geq \left\langle \frac{u^*}{\|u^*\|}, \nu \right\rangle = \|\nu\|,$$

where $u^* \in N_{S_0}(z)$ is such that $\nu \in J^*(u^*)$. To proceed, suppose that (3.9) holds. Then one has by definition that

$$\delta_{\alpha \mathbb{B}^* \cap N_{S_0}(z)}^*(\nu) \leq \delta_{\partial f(z) + [J^* N_{S_0}(z)]^\circ}^*(\nu) \quad \text{for each } \nu \in X,$$

and, in particular,

$$(3.17) \quad \delta_{\alpha\mathbb{B}^* \cap N_{S_0}(z)}^*(\nu) \leq \delta_{\partial f(z)}^*(\nu) \quad \text{for each } \nu \in J^*N_{S_0}(z).$$

Thus, combining (3.16) and (3.17), we apply (2.4) to conclude that

$$\text{cl}f'(z; \cdot)(\nu) = \delta_{\partial f(z)}^*(\nu) \geq \alpha\|\nu\| \quad \text{for each } \nu \in J^*N_{S_0}(z).$$

Hence, the implication (3.15) is checked, and the proof for (3.12) is complete.

Finally, assume that X is a Hilbert space. Then $J^* = \mathbf{I}$ and so $J^*N_{S_0}(z) = N_{S_0}(z)$ is a convex cone. Thus, one applies (2.2) (to $\alpha\mathbb{B}$, $\partial f(z)$, $N_{S_0}(z)$ in place of E , F , C) again to get that

$$(3.11) \quad \Leftrightarrow \quad [\delta_{\alpha\mathbb{B}}^*(\nu) \leq \delta_{\partial f(z)}^*(\nu) \quad \forall \nu \in N_{S_0}(z)].$$

This, together with (3.16) and (2.4), implies that (3.11) \Leftrightarrow (3.14). Noting clearly that (3.14) \Rightarrow (3.10), we see that (3.13) holds by (3.15). The proof is complete. \square

PROPOSITION 3.5. *Let $\alpha > 0$, $0 < r \leq +\infty$, and $x_0 \in S_0$. Then we have the following assertions:*

- (i) *If (3.10) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$, then, for each $x \in \mathbb{B}(x_0, r)$, one has*

$$(3.18) \quad f'(z; x - z) \geq \alpha d_{S_0}(x) \quad \text{for each } z \in P(x|S_0).$$

- (ii) *If (3.10) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$ and S_0 is proximal, then (3.2) holds.*

- (iii) *If (3.8) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$, then (3.2) holds but with $\frac{\alpha}{2}$ in place of α in the case in which $r < +\infty$.*

Proof. (i) Let $x \in \mathbb{B}(x_0, r)$ and $z \in P(x|S_0)$. Then one has by Lemma 2.3 that $z \in \mathbb{B}(x_0, 2r)$, and so $z \in S_0 \cap \mathbb{B}(x_0, 2r)$. Furthermore, by Lemma 2.1(i), one sees that $J(x - z) \cap N_{S_0}(z) \neq \emptyset$, and can take $z^* \in J(x - z) \cap N_{S_0}(z)$. Thus $x - z \in J^*(z^*)$ by definition and so $x - z \in J^*N_{S_0}(z)$. Consequently, (3.10) is applicable and then

$$f'(z; x - z) \geq \alpha\|x - z\| = \alpha d_{S_0}(x)$$

(noting $z \in P(x|S_0)$). Hence (3.18) is proved.

(ii) Assume that (3.10) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$ and S_0 is proximal. Then, for each $x \in \mathbb{B}(x_0, r)$, one can choose $z \in P(x|S_0)$ and so (3.18) holds by the established assertion (i). Furthermore, we note by the convexity of f that

$$(3.19) \quad f(x) - f(x_0) = f(x) - f(z) \geq f'(z; x - z) \quad \text{for each } x \in X.$$

This, together with (3.18), implies that (3.2) holds, and the proof for (ii) is complete.

(iii) Assume that (3.8) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$ and let $x \in \mathbb{B}(x_0, r)$. Then, by Proposition 3.4, (3.7) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$. This, together with (3.19), entails that

$$(3.20) \quad f(x) - f(x_0) \geq \alpha d_{T_{S_0}(z)}(x - z) \quad \text{for each } z \in S_0 \cap \mathbb{B}(x_0, 2r).$$

Thus, if $r = +\infty$, then (3.2) follows from Lemma 2.1(iii) (applied to S_0 in place of A). It remains to consider the case in which $r < +\infty$. By (3.20), it suffices to prove that

$$d_{S_0}(x) \leq 2 \sup_{z \in S_0 \cap \mathbb{B}(x_0, 2r)} d_{T_{S_0}(z)}(x - z).$$

For this purpose, we below verify that

$$(3.21) \quad \mathbb{B}^* \cap N_{S_0 \cap \mathbb{B}(x_0, 2r)}(z) \subseteq 2\mathbb{B}^* \cap N_{S_0}(z) + N_{\mathbb{B}(x_0, 2r)}(z) \quad \text{for each } z \in S_0 \cap \mathbb{B}(x_0, 2r).$$

Granting this, one has by (3.8) that, for each $z \in \tilde{S}_0$,

$$\frac{\alpha}{2} \mathbb{B}^* \cap N_{S_0 \cap \mathbb{B}(x_0, 2r)}(z) \subseteq \partial f(z) + N_{\mathbb{B}(x_0, 2r)}(z) = \partial \tilde{f}(z),$$

where $\tilde{f} : X \rightarrow \overline{\mathbb{R}}$ is the function defined by $\tilde{f} := f + \delta_{\mathbb{B}(x_0, 2r)}$ and $\tilde{S}_0 := S_0 \cap \mathbb{B}(x_0, 2r) \subseteq L_{\tilde{f}}(\lambda)$; hence (3.8) holds for each $z \in \tilde{S}_0$ with $\frac{\alpha}{2}$, \tilde{f} , \tilde{S}_0 in place of α , f , S_0 . Thus, applying the conclusion (to \tilde{f} , \tilde{S}_0 in place of f , S_0) just established for the case in which $r = +\infty$, we have that

$$f(x) - f(x_0) = \tilde{f}(x) - \tilde{f}(x_0) \geq \frac{\alpha}{2} d_{\tilde{S}_0}(x) = \frac{\alpha}{2} d_{S_0}(x),$$

where the last equality is because of (2.3), and so (3.2) holds with $\frac{\alpha}{2}$ in place of α .

To proceed, we note by the equivalence in Proposition 3.3(iii) (when applied to \tilde{S}_0 , $2d_{S_0}(\cdot) + \delta_{\mathbb{B}(x_0, 2r)}(\cdot)$ in place of S_0 , $f(\cdot)$) that, thanks to (2.5), equation (3.21) is equivalent to

$$(3.22) \quad d_{\tilde{S}_0}(x) \leq 2d_{S_0}(x) \quad \text{for each } x \in \mathbb{B}(x_0, 2r).$$

Therefore, to complete the proof, we have to show (3.22). To do this, let $x \in \mathbb{B}(x_0, 2r)$. Without loss of generality, we assume that $x_0 = 0$. Set $z := \frac{2rP(x|S_0)}{d_{S_0}(x) + 2r}$. Then

$$\|z\| = \frac{2r\|P(x|S_0) - x\| + 2r\|x\|}{d_{S_0}(x) + 2r} \leq \frac{2rd_{S_0}(x) + 4r^2}{d_{S_0}(x) + 2r} = 2r,$$

and so $z \in S_0 \cap 2r\mathbb{B} = \tilde{S}_0$ (as $z \in S_0$ is clear). Thus,

$$d_{\tilde{S}_0}(x) \leq \|x - z\| = \frac{\|d_{S_0}(x)x + 2r(x - P(x|S_0))\|}{d_{S_0}(x) + 2r} \leq \frac{4rd_{S_0}(x)}{d_{S_0}(x) + 2r} \leq 2d_{S_0}(x),$$

as desired, and the proof is complete. \square

Our first theorem in this section, which extends/improves the corresponding ones in [5, 39] for the special case in which $S_0 = \bar{S}$ (noting the equivalence between the constrained optimization problem (3.5) and the unconstrained optimization problem (3.1) explained in Remark 3.2), is as follows. In particular, in the special case in which $S_0 = \bar{S}$, the equivalence between statements (i)–(iii) were established in [5, Theorem 2.3]; the implications (i) \Rightarrow (vi) \Rightarrow (v) were provided in [39, Theorem 3.10.1], where the equivalence between statements (i)–(vi) was also established for the case in which X is reflexive; while the equivalence between statements (i)–(iii) and statements (v)–(vii) was proved in [5, Theorem 2.3] for the case in which X is a Hilbert space.

THEOREM 3.6. *Let $\alpha > 0$. Then we have the following assertions.*

- (I) *The following statements are equivalent.*
- (i) *S_0 is a set of (global) weak sharp minima for f with modulus α .*
 - (ii) *For each $z \in S_0$, (3.7) holds:*

$$f'(z; \nu) \geq \alpha d_{T_{S_0}(z)}(\nu) \quad \text{for each } \nu \in X.$$

(iii) For each $z \in S_0$, (3.8) holds:

$$\alpha\mathbb{B} \cap N_{S_0}(z) \subseteq \partial f(z).$$

(II) If S_0 is proximal (e.g., X is reflexive), then each of (i)–(iii) is equivalent to each of the following statements.

(iv) For each $z \in S_0$, (3.9) holds:

$$\alpha\mathbb{B} \cap N_{S_0}(z) \subseteq \partial f(z) + [J^*N_{S_0}(z)]^\circ.$$

(v) For each $z \in S_0$, (3.10) holds:

$$f'(z; \nu) \geq \alpha \|\nu\| \quad \text{for each } \nu \in J^*N_{S_0}(z).$$

(vi) For any $x \in X$ and $z \in P(x|S_0)$,

$$(3.23) \quad f'(z; x - z) \geq \alpha d_{S_0}(x).$$

(III) If X is a Hilbert space, then each of (i)–(vi) is equivalent to each of the following statements.

(vii) For each $z \in S_0$, (3.11) holds:

$$(3.24) \quad \alpha\mathbb{B} \subseteq \text{cl}(\partial f(z) + [N_{S_0}(z)]^\circ).$$

(viii) For each $z \in S_0$,

$$(3.25) \quad \hat{\alpha}\mathbb{B} \subseteq \partial f(z) + [N_{S_0}(z)]^\circ \quad \text{for each } \hat{\alpha} \in (0, \alpha).$$

Proof. We first prove that

$$(3.26) \quad (i) \Leftrightarrow (ii) \Leftrightarrow (iii) \Rightarrow (iv) \Rightarrow (v) \Leftrightarrow (vi).$$

Granting this, one completes the proof for assertion (I).

To verify (3.26), we note that the implications $(ii) \Leftrightarrow (iii) \Rightarrow (iv) \Rightarrow (v)$ follow from Proposition 3.4 and $(v) \Rightarrow (vi)$ from Proposition 3.5(i) (by taking $r = +\infty$). Thus it suffices to show that $(i) \Leftrightarrow (iii)$ and $(vi) \Rightarrow (v)$. To do this, we note by Proposition 3.5(iii) (by taking $r = +\infty$) that $(iii) \Rightarrow (i)$. Hence by (3.4) if either (i) or (iii) holds, then $S_0 = L_f(\lambda) = \bar{S}$. Thus the equivalence $(i) \Leftrightarrow (iii)$ follows immediately from Proposition 3.3(iii).

To show $(vi) \Rightarrow (v)$, suppose that (vi) holds, and let $z \in S_0$. Fix $\nu \in J^*N_{S_0}(z)$ and write $x := z + \nu$. Then, by Lemma 2.1(ii), one has that $z \in P(x|S_0)$, and so $d_{S_0}(x) = \|x - z\| = \|\nu\|$. Thus, from (vi), it follows that

$$f'(z; \nu) = f'(z; x - z) \geq \alpha d_{S_0}(x) = \alpha \|\nu\|.$$

This shows (3.10) as $\nu \in J^*N_{S_0}(z)$ is arbitrary, and so (v) is seen to hold. Therefore, the proof for (3.26) is complete.

To verify assertion (II), assume that S_0 is proximal. By (3.26), we only need to show the implication $(v) \Rightarrow (i)$. To do this, assume (v), that is, (3.10) holds for each $z \in S_0$. Thus Proposition 3.5(ii) is applicable and we conclude that (3.2) holds for $r = +\infty$, that is, (i) holds, and assertion (II) is proved.

Finally, we show assertion (III). For this purpose, suppose that X is a Hilbert space. We only need to verify that $(iv) \Rightarrow (vii) \Leftrightarrow (viii) \Rightarrow (v)$. We will complete the

proof by showing that $(3.9) \Rightarrow (3.24) \Leftrightarrow (3.25) \Rightarrow (3.10)$ holds for each $z \in S_0$. To do this, let $z \in S_0$. Note that (3.24) coincides with (3.11), and so $(3.9) \Rightarrow (3.24) \Rightarrow (3.10)$ by (3.13) in Proposition 3.4. To show $(3.24) \Leftrightarrow (3.25)$, one notes that

$$\text{int}(\text{cl}(\partial f(z) + [N_{S_0}(z)]^\circ)) = \text{int}(\partial f(z) + [N_{S_0}(z)]^\circ).$$

It follows that

$$(3.24) \Leftrightarrow [\text{int}(\alpha \mathbb{B}) \subseteq \text{int}(\partial f(z) + [N_{S_0}(z)]^\circ)] \Leftrightarrow (3.25).$$

The proof is complete. \square

Remark 3.7. As argued in the proof, the following equivalences/implications for statements (i)–(vi) given in Theorem 3.6 hold in general normed linear spaces (see (3.26)):

$$(i) \Leftrightarrow (ii) \Leftrightarrow (iii) \Rightarrow (iv) \Rightarrow (v) \Leftrightarrow (vi).$$

Theorems 3.8 and 3.9 below provide the analogues of Theorem 3.6 for the local weak sharp minima over S_0 and the boundedly weak sharp minima, respectively. As described in Proposition 3.3, for the special case in which $S_0 = \bar{S}$, the implication $(i) \Rightarrow (ii)$ (for statements (i) and (ii) given in Theorem 3.8 or Theorem 3.9) was showed in [5, Theorems 5.2 and 6.3], where the converse implication was proved only for the case in which X is a Hilbert space or a finite-dimensional space. Moreover, in the case in which S_0 is complete, the implication $(ii) \Rightarrow (i)$ was also known as a direct consequence of [43, Proposition 4.2]. However, the implication $(ii) \Rightarrow (i)$ for general linear normed spaces and other equivalent characterizations for the local weak sharp minima or the boundedly weak sharp minima seem new, even for the case in which $S_0 = \bar{S}$ and/or when X is a reflexive space or a Hilbert space.

THEOREM 3.8. *Let $x_0 \in S_0$ and $\alpha > 0$. Then we have the following assertions.*

(I) *The following statements are equivalent but $(iii) \Rightarrow (i)$ for possible different values of $\alpha > 0$:*

- (i) x_0 is a local weak sharp minima over S_0 for f with modulus α .
- (ii) There exists $r > 0$ such that (3.7) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.
- (iii) There exists $r > 0$ such that (3.8) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.

(II) *If S_0 is proximal, then each of (i)–(iii) is equivalent to each of the following statements:*

- (iv) There exists $r > 0$ such that (3.9) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.
- (v) There exists $r > 0$ such that (3.10) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.
- (vi) There exists $r > 0$ such that (3.23) holds for each $x \in \mathbb{B}(x_0, r)$ and each $z \in P(x|S_0)$.

(III) *If X is a Hilbert space, then each of (i)–(vi) is equivalent to each of the following statements:*

- (vii) There exists $r > 0$ such that (3.24) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.
- (viii) There exists $r > 0$ such that (3.25) holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$.

Proof. The proofs for $(ii) \Leftrightarrow (iii) \Rightarrow (iv) \Rightarrow (v) \Rightarrow (vi)$, and for assertions (II) and (III) are similar to those for the corresponding ones in Theorem 3.6 (by choosing an appropriate r), and so we omit them here.

To complete the proof, we only need to verify $(vi) \Rightarrow (v)$ and $(i) \Leftrightarrow (iii)$. We first show the implication $(vi) \Rightarrow (v)$. To do this, assume that (vi) holds and let $r > 0$ be such that (3.23) holds for any $x \in \mathbb{B}(x_0, r)$ and $z \in P(x|S_0)$. It suffices to prove that (3.10) holds for each $z \in S_0 \cap \mathbb{B}(x_0, \frac{r}{2})$. To do this, let $z \in S_0 \cap \mathbb{B}(x_0, \frac{r}{2})$ and fix

$\nu \in J^*N_{S_0}(z)$. Write $x := z + \frac{r\nu}{2\|\nu\|}$. Then, by Lemma 2.1(ii), one has that $z \in P(x|S_0)$, and so $d_{S_0}(x) = \|x - z\| = \frac{r}{2}$. Since $\|x - x_0\| \leq \|z - x_0\| + \frac{r}{2} < r$, (3.23) is applicable, and so

$$f'\left(z; \frac{r\nu}{2\|\nu\|}\right) = f'(z; x - z) \geq \alpha d_{S_0}(x) = \frac{\alpha r}{2}.$$

Hence, $f'(z; \nu) \geq \alpha\|\nu\|$ because $f'(z; \cdot)$ is positively homogeneous. Thus, (3.10) is checked as $\nu \in J^*N_{S_0}(z)$ is arbitrary, and (v) is obtained, as desired.

Below, we verify the equivalence (i) \Leftrightarrow (iii). To this end, assume first that (i) holds. Then there exists $r' > 0$ such that (3.2) holds with r' in place of r . This, together with (3.3), implies that

$$(3.27) \quad S_0 \cap \mathbb{B}(x_0, r') = \bar{S} \cap \mathbb{B}(x_0, r').$$

Furthermore, since $S_0 \subseteq \bar{S}$, it follows from (3.2) (applied to r' in place of r) that

$$\alpha d_{\bar{S}}(x) \leq f(x) - f(x_0) \quad \text{for each } x \in \mathbb{B}(x_0, r').$$

This means that x_0 is a local weak sharp minima (over \bar{S}) for f with modulus α . Thus, one applies Proposition 3.3(i) to conclude that there exists $r > 0$ such that (3.6) holds. Without loss of generality, assume that $r < r'$. Then, by (3.27),

$$N_{\bar{S}}(z) = N_{\bar{S} \cap \mathbb{B}(x_0, r')}(z) = N_{S_0 \cap \mathbb{B}(x_0, r')}(z) = N_{S_0}(z)$$

holds for each $z \in S_0 \cap \mathbb{B}(x_0, r)$, and so it follows from (3.6) that

$$\alpha \mathbb{B} \cap N_{S_0}(z) \subseteq \partial f(z) \quad \text{for each } z \in S_0 \cap \mathbb{B}(x_0, r).$$

Thus (iii) is checked.

Conversely, assume that (iii) holds, that is, there exists $r > 0$ such that (3.8) holds for each $z \in S_0 \cap \mathbb{B}(x_0, 2r)$. Then, (3.2) holds by Proposition 3.5(iii) with $\frac{\alpha}{2}$ in place of α . This means that (i) holds with $\frac{\alpha}{2}$ in place of α , and the proof is complete. \square

THEOREM 3.9. *The following assertions are true.*

(I) *The following statements are equivalent:*

(i) *S_0 is a set of boundedly weak sharp minima for f .*

(ii) *For each $r > 0$, there exists $\alpha > 0$ such that (3.7) holds for each $z \in S_0 \cap r\mathbb{B}$.*

(iii) *For each $r > 0$, there exists $\alpha > 0$ such that (3.8) holds for each $z \in S_0 \cap r\mathbb{B}$.*

(II) *If S_0 is proximal, then each of (i)–(iii) is equivalent to each of the following statements:*

(iv) *For each $r > 0$, there exists $\alpha > 0$ such that (3.9) holds for each $z \in S_0 \cap r\mathbb{B}$.*

(v) *For each $r > 0$, there exists $\alpha > 0$ such that (3.10) holds for each $z \in S_0 \cap r\mathbb{B}$.*

(vi) *For each $r > 0$, there exists $\alpha > 0$ such that (3.23) holds for each $x \in r\mathbb{B}$ and each $z \in P(x|S_0)$.*

(III) *If X is a Hilbert space, then each of (i)–(vi) is equivalent to the following statement:*

(vii) *For each $r > 0$, there exists $\alpha > 0$ such that*

$$\alpha \mathbb{B} \subseteq \partial f(z) + [N_{S_0}(z)]^\circ \quad \text{for each } z \in S_0 \cap r\mathbb{B}.$$

Proof. The proof is similar to that of Theorem 3.8. \square

Remark 3.10. As remarked for Theorem 3.6, for statements (i)–(vi) given in Theorems 3.8 or 3.9, the implications/equivalences (3.26) hold in general normed linear spaces.

4. Weak sharp minima for convex infinite optimization problems. As in the preceding sections, we assume that X is a normed space, and $f : X \rightarrow \overline{\mathbb{R}}$ is a proper lsc and convex function. This section is devoted to investigating the characterization problem of weak sharp minima for the convex infinite optimization problem

$$(4.1) \quad \begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & x \in \Omega, \\ & \phi_y(x) \leq 0 \quad \forall y \in Y, \end{aligned}$$

where Y is an index set, $\Omega \subseteq X$ is a nonempty closed and convex set, and $\phi_{(\cdot)}(\cdot) : X \times Y \rightarrow \overline{\mathbb{R}}$ is such that, for each $y \in Y$, $\phi_y(\cdot)$ is lsc and convex on X . Let Z denote the set of all feasible points for optimization problem (4.1), that is,

$$Z := \{x \in \Omega \mid \phi_y(x) \leq 0 \quad \forall y \in Y\}.$$

In order to avoid triviality, we assume, throughout this section, that

$$Z \cap \text{dom} f \neq \emptyset.$$

As in [42], we write

$$\lambda := \inf_{x \in Z} f(x) \quad \text{and} \quad S := \{x \in Z \mid f(x) = \lambda\} = Z \cap L_f(\lambda).$$

Then S is closed and convex. For a function $\phi : X \rightarrow \overline{\mathbb{R}}$, its positive part is defined by

$$\phi_+(x) := \max\{\phi(x), 0\} \quad \text{for each } x \in X.$$

We recall in the following definition the notion of the weak sharp minima property for problem (4.1). In particular, items (a) and (c) are taken from [42].

DEFINITION 4.1. Let $\alpha > 0$ and $x_0 \in S$. Problem (4.1) is said to have

(a) a local weak sharp minimum property at x_0 in S (with modulus α) if there exists $r > 0$ such that

$$(4.2) \quad \alpha d_S(x) \leq f(x) - f(x_0) + \sup_{y \in Y} [\phi_y]_+(x) + d_\Omega(x) \quad \text{for each } x \in \mathbb{B}(x_0, r);$$

(b) a boundedly weak sharp minima property in S if, for each $r > 0$, there exists $\alpha := \alpha_r > 0$ such that (4.2) holds with 0 in place of x_0 ;

(c) a global weak sharp minima property in S (with modulus α) if (4.2) holds for $r = +\infty$.

Associated with problem (4.1), we define $\hat{f} : X \rightarrow \overline{\mathbb{R}}$ by

$$(4.3) \quad \hat{f}(x) := f(x) + \sup_{y \in Y} [\phi_y]_+(x) + d_\Omega(x) \quad \text{for each } x \in X.$$

Then, \hat{f} is lsc and convex, and $\hat{f} = f$ on S because $\sup_{y \in Y} [\phi_y]_+(x) = 0$ and $d_\Omega(x) = 0$ hold for each $x \in S$. Hence, the relationship between problem (4.1) has a global (resp., local, boundedly) weak sharp minima property in S and S is a set of global (resp., local, boundedly) weak sharp minima for \hat{f} is stated as follows.

PROPOSITION 4.2. Problem (4.1) has a global (resp., local, boundedly) weak sharp minima property in S if and only if S is a set of global (resp., local, boundedly) weak sharp minima for \hat{f} .

To apply the characterization theorems established in the previous section, we need to calculate the subdifferential of \hat{f} , which will be done in the following subsection.

4.1. Subdifferential of the associated function. For the remainder of the paper, we use Φ to denote the sup-function of the family of proper lsc and convex functions $\{\phi_y|y \in Y\}$, and define it as

$$(4.4) \quad \Phi(x) := \sup_{y \in Y} \phi_y(x) \quad \text{for each } x \in X.$$

Let $\varepsilon \geq 0$ and $x \in X$. We use $Y^\varepsilon(x)$ to denote the ε -active set at x for the family $\{\phi_y|y \in Y\}$, defined by

$$Y^\varepsilon(x) := \{y \in Y | \phi_y(x) \geq \Phi(x) - \varepsilon\}.$$

The active set at x is denoted by $Y(x)$, that is,

$$Y(x) := Y^0(x) = \{y \in Y | \phi_y(x) = \Phi(x)\}.$$

We first recall in the following proposition some subdifferential formulas for the sup-function Φ , known from [18, Corollary 8] and [39, Theorem 2.4.18].

PROPOSITION 4.3. *Let $z \in \text{dom}\Phi$. Then the following assertions hold.*

(i) *We have that*

$$\partial\Phi(z) \supseteq \text{cl}^* \text{co}(\cup_{y \in Y(z)} \partial\phi_y(z)).$$

(ii) *If $\text{ri}(\text{dom}\Phi) \neq \emptyset$, then*

$$(4.5) \quad \partial\Phi(z) = \cap_{\varepsilon > 0} \text{cl}^* (\text{co}(\cup_{y \in Y^\varepsilon(z)} \partial_{\tau\varepsilon}\phi_y(z)) + N_{\text{dom}\Phi}(z)) \quad \text{for each } \tau > 0.$$

(iii) *If assumption (B1) holds, and each function $\phi_y(\cdot)$ is continuous at z , then*

$$(4.6) \quad \partial\Phi(z) = \text{cl}^* \text{co}(\cup_{y \in Y(z)} \partial\phi_y(z)).$$

PROPOSITION 4.4. *Suppose that $\text{ri}(\text{dom}f \cap \text{dom}\Phi) \neq \emptyset$ and let $z \in \text{dom}f \cap S$. Then*

$$(4.7) \quad \partial(f + \Phi)(z) = \cap_{\varepsilon > 0} \text{cl}^* [\text{co}(\cup_{y \in Y^\varepsilon(z)} (\partial_\varepsilon f(z) + \partial_\varepsilon \phi_y(z))) + N_{\text{dom}(f+\Phi)}(z)].$$

Proof. Consider the family of proper and convex functions $\{f + \phi_y|y \in Y\}$ on X . Then one sees that

$$(4.8) \quad f + \Phi = \sup_{y \in Y} (f + \phi_y),$$

and, for each $\varepsilon \geq 0$, the ε -active set at z for the family $\{f + \phi_y|y \in Y\}$ is equal to the one for the family $\{\phi_y|y \in Y\}$, that is,

$$(4.9) \quad \{y \in Y | (f + \phi_y)(z) \geq (f + \Phi)(z) - \varepsilon\} = Y^\varepsilon(z).$$

To apply Proposition 4.3(ii), we use Lemma 2.6(i) to estimate the ε -subdifferential of $(f + \phi_y)(z)$ for each $y \in Y$ and have that

$$\begin{aligned} \partial_\varepsilon(f + \phi_y)(z) &= \cap_{\eta > 0} \text{cl}^* (\cup_{\varepsilon_i \geq 0, \varepsilon + \eta = \varepsilon_1 + \varepsilon_2} (\partial_{\varepsilon_1} f(z) + \partial_{\varepsilon_2} \phi_y(z))) \\ &\subseteq \cap_{\eta > 0} \text{cl}^* (\partial_{\varepsilon + \eta} f(z) + \partial_{\varepsilon + \eta} \phi_y(z)). \end{aligned}$$

Thus, by Proposition 4.3(ii), one has that

$$\begin{aligned} (4.10) \quad \partial(f + \Phi)(z) &= \cap_{\varepsilon > 0} \text{cl}^* [\text{co}(\cup_{y \in Y^\varepsilon(z)} \partial_\varepsilon(f + \phi_y)(z)) + N_{\text{dom}(f+\Phi)}(z)] \\ &\subseteq \cap_{\varepsilon > 0} \text{cl}^* [\text{co}(\cup_{y \in Y^\varepsilon(z)} \cap_{\eta > 0} \text{cl}^* (\partial_{\varepsilon + \eta} f(z) + \partial_{\varepsilon + \eta} \phi_y(z))) + N_{\text{dom}(f+\Phi)}(z)]. \end{aligned}$$

To proceed, we note the clear inclusions

$$(4.11) \quad \cup_{y \in T} \text{cl}^* A(y) \subseteq \text{cl}^* \text{co}(\cup_{y \in T} A(y))$$

for a family of sets $\{A(y)|y \in T\}$ in X^* and

$$(4.12) \quad \text{cl}^* A + B \subseteq \text{cl}^*(A + B)$$

for two sets A and B in X^* . Thus, one concludes by (4.11) (applied to $\{\partial_{\varepsilon+\eta} f(z) + \partial_{\varepsilon+\eta} \phi_y(z)|y \in Y^\varepsilon(z)\}$ in place of $\{A(y)|y \in T\}$) that the following inclusion holds for each $\eta > 0$ and $\varepsilon > 0$:

$$\begin{aligned} \text{co}(\cup_{y \in Y^\varepsilon(z)} \cap_{\eta > 0} \text{cl}^*(\partial_{\varepsilon+\eta} f(z) + \partial_{\varepsilon+\eta} \phi_y(z))) \\ \subseteq \text{cl}^*[\text{co}(\cup_{y \in Y^\varepsilon(z)} (\partial_{\varepsilon+\eta} f(z) + \partial_{\varepsilon+\eta} \phi_y(z)))]. \end{aligned}$$

Combining this and (4.10), and thanks to (4.12) (applied to

$$\text{co}(\cup_{y \in Y^\varepsilon(z)} (\partial_{\varepsilon+\eta} f(z) + \partial_{\varepsilon+\eta} \phi_y(z))), \quad N_{\text{dom}(f+\Phi)}(z)$$

in place of A, B), we obtain that

$$\partial(f + \Phi)(z) \subseteq \cap_{\varepsilon > 0} \cap_{\eta > 0} \text{cl}^*[\text{co}(\cup_{y \in Y^\varepsilon(z)} (\partial_{\varepsilon+\eta} f(z) + \partial_{\varepsilon+\eta} \phi_y(z))) + N_{\text{dom}(f+\Phi)}(z)].$$

Since $Y^\varepsilon(z) \subseteq Y^{\varepsilon+\eta}(z)$ and $\partial_\varepsilon f(z) + \partial_\varepsilon \phi_y(z) \subseteq \partial_{2\varepsilon}(f + \phi_y)(z)$, it follows that

$$\begin{aligned} \partial(f + \Phi)(z) &\subseteq \cap_{\varepsilon > 0} \text{cl}^*[\text{co}(\cup_{y \in Y^\varepsilon(z)} (\partial_\varepsilon(f(z) + \phi_y(z)))) + N_{\text{dom}(f+\Phi)}(z)] \\ &\subseteq \cap_{\varepsilon > 0} \text{cl}^*[\text{co}(\cup_{y \in Y^\varepsilon(z)} \partial_{2\varepsilon}(f + \phi_y)(z)) + N_{\text{dom}(f+\Phi)}(z)] \\ &= \partial(f + \Phi)(z), \end{aligned}$$

where the equality is because of (4.5) (applied to 2, $\{f + \phi_y|y \in Y\}$ in place of τ , $\{\phi_y|y \in Y\}$, and thanks to (4.8) and (4.9)). Therefore, (4.7) is proved and the proof is complete. \square

For the sake of simplicity, we introduce the notation $E(\varepsilon, z)$ for any $z \in X$ and $\varepsilon > 0$ defined by

$$(4.13) \quad E(\varepsilon, z) := \text{cl}^* \left(\text{co}[\cup_{y \in Y_+^\varepsilon(z)} (\partial_\varepsilon f(z) + \partial_\varepsilon \phi_y(z)) \cup \partial_\varepsilon f(z)] + N_{\text{dom}f \cap \text{dom}\Phi}(z) \right),$$

where

$$Y_+^\varepsilon(z) := \{y \in Y | \phi_y(z) \geq -\varepsilon\} \quad \text{for any } z \in X \text{ and } \varepsilon \geq 0.$$

In particular, we write $Y_+(z)$ for $Y_+^0(z)$, that is,

$$Y_+(z) := Y_+^0(z) = \{y \in Y | \phi_y(z) = 0\}.$$

The following theorem plays a crucial role in characterizing the weak sharp minima property for convex infinite optimization problem (4.1) in the next subsection. Recall that \hat{f} is defined by (4.3).

THEOREM 4.5. *Let $z \in \text{dom}f \cap Z$. Then we have the following assertions.*

(i) *The following inclusion holds:*

$$(4.14) \quad \partial \hat{f}(z) \supseteq \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + N_\Omega(z) \cap \mathbb{B}.$$

(ii) Assume that $\text{ri}(\text{dom} f \cap \text{dom} \Phi) \neq \emptyset$. Then

$$(4.15) \quad \partial \hat{f}(z) = \cap_{\varepsilon > 0} E(\varepsilon, z) + N_{\Omega}(z) \cap \mathbb{B}.$$

(iii) Assume that either f or Φ is continuous at some point $x_0 \in \text{dom} f \cap \text{dom} \Phi$. Then

(4.16)

$$\partial \hat{f}(z) = \partial f(z) + [0, 1] \cap_{\varepsilon > 0} \text{cl}^* \left(\text{co}(\cup_{y \in Y_{\varepsilon}^+(z)} \partial_{\varepsilon} \phi_y(z)) + N_{\text{dom} \Phi}(z) \right) + N_{\Omega}(z) \cap \mathbb{B}$$

if $\text{ri}(\text{dom} \Phi) \neq \emptyset$, and

$$(4.17) \quad \partial \hat{f}(z) = \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + N_{\Omega}(z) \cap \mathbb{B}$$

if assumption (B1) holds and each function $\phi_y(\cdot)$ is continuous at z .

Proof. (i) Let Φ_+ denote the sup-function of the family $\{[\phi_y]_+ | y \in Y\}$, that is,

$$\Phi_+(x) := \sup_{y \in Y} [\phi_y]_+(x) \quad \text{for each } x \in X.$$

Then $\Phi_+(z) = 0$ (as $z \in Z$), and

$$\{y \in Y : \phi_y(z) = \Phi_+(z)\} = Y_+(z).$$

Note that

$$\partial[\phi_y]_+(z) = \begin{cases} [0, 1] \partial \phi_y(z), & \text{if } y \in Y_+(z), \\ \{0\} & \text{otherwise} \end{cases}$$

(see [39, Corollary 2.8.11 and Example 2.8.1]). Hence, applying Proposition 4.3(i) (to the family $\{[\phi_y]_+ | y \in Y\}$ in place of $\{\phi_y | y \in Y\}$), we have that

$$(4.18) \quad [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) = \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial[\phi_y]_+(z)) \subseteq \partial \Phi_+(z).$$

Note further by (2.5) that

$$(4.19) \quad \partial d_{\Omega}(z) = N_{\Omega}(z) \cap \mathbb{B}.$$

Since $\partial \hat{f}(z) \supseteq \partial f(z) + \partial \Phi_+(z) + \partial d_{\Omega}(z)$, inclusion (4.14) follows from (4.18) and (4.19), and thus assertion (i) is proved.

(ii) By Lemma 2.6(iv), one has that

$$\partial \hat{f}(z) = \partial(f + \Phi_+)(z) + \partial d_{\Omega}(z).$$

Therefore, to show (4.15), it suffices to verify that

$$(4.20) \quad \partial(f + \Phi_+)(z) = \cap_{\varepsilon > 0} E(\varepsilon, z).$$

To do this, consider the family $\{\phi_y | y \in \tilde{Y}\}$, where $\tilde{Y} := Y \cup \{y_{\infty}\}$ with $\phi_{y_{\infty}} := 0$. Then, one checks that

$$(4.21) \quad \Phi_+(\cdot) = \sup_{y \in \tilde{Y}} \phi_y(\cdot), \quad \text{dom} \Phi_+ = \text{dom} \Phi,$$

and

$$(4.22) \quad \tilde{Y}^{\varepsilon}(z) = \{y \in \tilde{Y} | \phi_y(z) \geq \Phi_+(z) - \varepsilon\} = Y_+^{\varepsilon}(z) \cup \{y_{\infty}\} \quad \text{for each } \varepsilon > 0.$$

By assumption, Proposition 4.4 can be applied (to the family $\{\phi_y|y \in \tilde{Y}\}$ in place of $\{\phi_y|y \in Y\}$), and so we have from (4.21) and (4.22) that

$$\partial(f + \Phi_+)(z) = \cap_{\varepsilon>0} \text{cl}^*[\text{co}(\cup_{y \in \tilde{Y}^\varepsilon(z)} (\partial_\varepsilon f(z) + \partial_\varepsilon \phi_y(z))) + N_{\text{dom}(f + \Phi_+)}(z)].$$

In terms of (4.13), this shows (4.20) as $\partial_\varepsilon \phi_{y_\infty}(z) = 0$, and the proof of assertion (ii) is complete.

(iii) By assumption, it follows from Lemma 2.6(iv) that

$$(4.23) \quad \partial \hat{f}(z) = \partial f(z) + \partial \Phi_+(z) + \partial d_\Omega(z).$$

Clearly, $\Phi_+(\cdot) = \max\{\Phi(\cdot), 0\}$ and $\Phi_+(z) = 0$. Hence, we have that

$$(4.24) \quad \partial \Phi_+(z) = [0, 1] \partial \Phi(z) \quad \text{and} \quad Y^\varepsilon(z) = Y_+^\varepsilon(z) \quad \text{for each } \varepsilon \geq 0.$$

Thus, thanks to (4.23), (4.24), and (4.19), equations (4.16) and (4.17) follow immediately from (4.5) and (4.6), respectively. The proof is complete. \square

Remark 4.6. Let Φ be sup-function of the family $\{\phi_y|y \in Y\}$ defined by (4.4). Some subdifferential rules for the function $f + \Phi$ were established in [10]. Noting that f and ϕ_y involved here are lsc for each $y \in Y$, the assumption in [10, Theorem 4] is satisfied. Thus the corresponding results there regarding the subdifferentials are applicable when establishing the counterparts of Theorem 4.5. To this end, let $z \in \text{dom} f \cap Z$ and let $\mathcal{F}(z)$ denote the family of finite-dimensional subspaces containing z . Then, using similar arguments to those we used for proving (ii) in Theorem 4.5, one can apply [10, Theorem 4] and [10, Corollary 8], together with Lemma 2.6(iv), to obtain the following subdifferential formulas for \hat{f} at z .

(i) The following equality holds:

$$(4.25) \quad \begin{aligned} \partial \hat{f}(z) = & \cap_{\varepsilon>0, L \in \mathcal{F}(z)} \text{cl}^* \text{co} \left\{ \cup_{y \in Y_+^\varepsilon(z)} (\partial_\varepsilon \phi_y(z) \cup \{0\}) + \partial(f + \delta_{L \cap \text{dom} \Phi})(z) \right\} \\ & + N_\Omega(z) \cap \mathbb{B}. \end{aligned}$$

(ii) Assume that $\text{ri}(\text{dom} f \cap \text{dom} \Phi) \neq \emptyset$ and $f|_{\text{aff}(\text{dom} f \cap \text{dom} \Phi)}$ is continuous on $\text{ri}(\text{dom} f \cap \text{dom} \Phi)$. Then

$$\partial \hat{f}(z) = \cap_{\varepsilon>0} \text{cl}^* \text{co} \left\{ \cup_{y \in Y_+^\varepsilon(z)} (\partial_\varepsilon \phi_y(z) \cup \{0\}) + \partial(f + \delta_{\text{dom} \Phi})(z) \right\} + N_\Omega(z) \cap \mathbb{B}$$

and

$$\begin{aligned} \partial \hat{f}(z) = & \cap_{\varepsilon>0} \text{cl}^* \text{co} \left\{ \cup_{y \in Y_+^\varepsilon(z)} (\partial_\varepsilon \phi_y(z) \cup \{0\}) + \partial f(z) + N_{\text{dom} \Phi}(z) \right\} \\ & + N_\Omega(z) \cap \mathbb{B} \end{aligned}$$

if f is continuous at some point of $\text{dom} \Phi$.

4.2. Characterizations for the weak sharp minima. By virtue of Proposition 4.2 and Theorem 4.5(i), the following corollary is a direct consequence of Theorems 3.6, 3.8, and 3.9, in which (i) and (ii) were respectively proved in [42, Theorems 3.2 and 3.1] for the case in which X is a Banach space.

COROLLARY 4.7. *Let $\alpha > 0$ and $x_0 \in S$. Consider the following inclusion:*

$$(4.26) \quad \alpha \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + N_\Omega(z) \cap \mathbb{B}.$$

Then we have that

- (i) if (4.26) holds for each $z \in S$, then problem (4.1) has a global weak sharp minima property in S with modulus α ;
- (ii) if there exists $r > 0$ such that (4.26) holds for each $z \in S \cap \mathbb{B}(x_0, r)$, then problem (4.1) has a local weak sharp minimum property at x_0 in S with modulus α ;
- (iii) if for each $r > 0$ there exists $\alpha(= \alpha_r) > 0$ such that (4.26) holds for each $z \in S \cap r\mathbb{B}$, then problem (4.1) has a boundedly weak sharp minima property in S .

Similarly, based on Theorem 4.5 and Proposition 4.2, and noting the equality

$$\text{cl}^*(A + B) = \text{cl}^*A + B$$

whenever $A \subseteq X^*$ is an arbitrary set and $B \subseteq X^*$ is a weak*-compact set, one can apply Theorem 3.6 to conclude directly in the following theorem the equivalent characterizations for the global weak sharp minima property of the convex infinite optimization problem (4.1). Theorem 4.8 not only extends [42, Theorem 3.4] under the weaker assumptions, in which only the equivalence between (i) and (4.35) was shown under the assumptions (A1) and (A2) in Banach spaces (noting in section 1 that (B1) and (B2) are strictly weaker than (A1) and (A2)), but also presents more complete characterizations of the global weak sharp minima property in normed spaces, e.g., (ii)–(v) and (4.36)–(4.38) seem new to the best of our knowledge.

THEOREM 4.8. *Let $\alpha > 0$. Suppose that $\text{ri}(\text{dom}f \cap \text{dom}\Phi) \neq \emptyset$. Then we have the following assertions.*

(I) *The following statements are equivalent:*

- (i) *Problem (4.1) has a global weak sharp minima property in S with modulus α .*
- (ii) *For each $z \in S$,*

$$(4.27) \quad \alpha\mathbb{B} \cap N_S(z) \subseteq \cap_{\varepsilon>0} E(\varepsilon, z) + N_\Omega(z) \cap \mathbb{B}.$$

(II) *If S is proximal, then (i) and (ii) are equivalent to the following statement:*

- (iii) *For each $z \in S$,*

$$(4.28) \quad \alpha\mathbb{B} \cap N_S(z) \subseteq \cap_{\varepsilon>0} E(\varepsilon, z) + [J^*N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B}.$$

(III) *If X is a Hilbert space, then (i)–(iii) are equivalent to the following statements:*

- (iv) *For each $z \in S$,*

$$(4.29) \quad \alpha\mathbb{B} \subseteq \text{cl}\{\cap_{\varepsilon>0} E(\varepsilon, z) + [N_S(z)]^\circ\} + N_\Omega(z) \cap \mathbb{B}.$$

- (v) *For any $z \in S$ and $\hat{\alpha} \in (0, \alpha)$,*

$$(4.30) \quad \hat{\alpha}\mathbb{B} \subseteq \cap_{\varepsilon>0} E(\varepsilon, z) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B}.$$

Further, assume that either f or Φ is continuous at some point $x_0 \in \text{dom}f \cap \text{dom}\Phi$.

Then (4.27)–(4.30) above can be replaced by

$$(4.31) \quad \alpha \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \cap_{\varepsilon > 0} \text{cl}^* \left(\text{co}(\cup_{y \in Y_+^\varepsilon(z)} \partial_\varepsilon \phi_y(z)) + N_{\text{dom}\Phi}(z) \right) + N_\Omega(z) \cap \mathbb{B},$$

$$(4.32) \quad \alpha \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \cap_{\varepsilon > 0} \text{cl}^* \left(\text{co}(\cup_{y \in Y_+^\varepsilon(z)} \partial_\varepsilon \phi_y(z)) + N_{\text{dom}\Phi}(z) \right) + N_\Omega(z) \cap \mathbb{B} + [J^* N_S(z)]^\circ,$$

$$(4.33) \quad \alpha \mathbb{B} \subseteq \text{cl}[\partial f(z) + [0, 1] \cap_{\varepsilon > 0} \text{cl}(\text{co}(\cup_{y \in Y_+^\varepsilon(z)} \partial_\varepsilon \phi_y(z)) + N_{\text{dom}\Phi}(z)) + [N_S(z)]^\circ] + N_\Omega(z) \cap \mathbb{B},$$

$$(4.34) \quad \hat{\alpha} \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \cap_{\varepsilon > 0} \text{cl}(\text{co}(\cup_{y \in Y_+^\varepsilon(z)} \partial_\varepsilon \phi_y(z)) + N_{\text{dom}\Phi}(z)) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B},$$

respectively, if $\text{ri}(\text{dom}\Phi) \neq \emptyset$, and by

$$(4.35) \quad \alpha \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + N_\Omega(z) \cap \mathbb{B},$$

$$(4.36) \quad \alpha \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \text{cl}^* \text{co}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + N_\Omega(z) \cap \mathbb{B} + [J^* N_S(z)]^\circ,$$

$$(4.37) \quad \alpha \mathbb{B} \subseteq \text{cl}[\partial f(z) + [0, 1] \text{clco}(\cup_{y \in Y_+(z)} \partial \phi_y(z))] + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B},$$

$$(4.38) \quad \hat{\alpha} \mathbb{B} \cap N_S(z) \subseteq \partial f(z) + [0, 1] \text{clco}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B},$$

respectively, if assumptions (B1) and (B2) hold.

Analogously to Theorem 4.8, we can further apply Theorems 3.8 and 3.9 to obtain in the following theorems the equivalent characterizations for the local or boundedly weak sharp minima property of the convex infinite optimization problem (4.1), respectively. Most of characterizations provided in Theorems 4.9 and 4.10 seem new in the literature, even in the case in which the assumptions (A1) and (A2) hold.

THEOREM 4.9. *Let $\alpha > 0$ and $x_0 \in S$. Suppose that $\text{ri}(\text{dom}f \cap \text{dom}\Phi) \neq \emptyset$. Then we have the following assertions.*

(I) *The following statements are equivalent but (ii) \Rightarrow (i) for possible different values of $\alpha > 0$:*

(i) *Problem (4.1) has a local weak sharp minimum property at x_0 in S with modulus α .*

(ii) *There exists $r > 0$ such that (4.27) holds for each $z \in S \cap \mathbb{B}(x_0, r)$.*

(II) *If S is proximal, then (i) and (ii) are equivalent to the following statement:*

(iii) *There exists $r > 0$ such that (4.28) holds for each $z \in S \cap \mathbb{B}(x_0, r)$.*

(III) *If X is a Hilbert space, (i)–(iii) are equivalent to the following statements:*

(iv) *There exists $r > 0$ such that (4.29) holds for each $z \in S \cap \mathbb{B}(x_0, r)$.*

(v) *There exists $r > 0$ such that (4.30) holds for any $z \in S \cap \mathbb{B}(x_0, r)$ and $\hat{\alpha} \in (0, \alpha)$.*

Further, assume that either f or Φ is continuous at some point $x_0 \in \text{dom}f \cap \text{dom}\Phi$. Then (4.27)–(4.30) can be replaced by (4.31)–(4.34), respectively, if $\text{ri}(\text{dom}\Phi) \neq \emptyset$, and by (4.35)–(4.38), respectively, if assumptions (B1) and (B2) hold.

THEOREM 4.10. Suppose that $\text{ri}(\text{dom} f \cap \text{dom} \Phi) \neq \emptyset$. Then we have the following assertions.

(I) The following statements are equivalent:

(i) Problem (4.1) has a boundedly weak sharp minima property in S .

(ii) For each $r > 0$, there exists $\alpha > 0$ such that (4.27) holds for each $z \in S \cap r\mathbb{B}$.

(II) If S is proximal, then (i) and (ii) are equivalent to the following statement:

(iii) For each $r > 0$, there exists $\alpha > 0$ such that (4.28) holds for each $z \in S \cap r\mathbb{B}$.

(III) If X is a Hilbert space, then (i)–(iii) are equivalent to the following statement:

(iv) For each $r > 0$, there exists $\alpha > 0$ such that

$$(4.39) \quad \alpha\mathbb{B} \subseteq \cap_{\varepsilon>0} E(\varepsilon, z) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B}$$

holds for each $z \in S \cap r\mathbb{B}$.

Furthermore, assume that either f or Φ is continuous at some point $x_0 \in \text{dom} f \cap \text{dom} \Phi$. Then (4.27), (4.28), and (4.39) can be replaced by (4.31), (4.32), and

$$\alpha\mathbb{B} \subseteq \partial f(z) + [0, 1] \cap_{\varepsilon>0} \text{cl}(\text{co}(\cup_{y \in Y_\varepsilon^\varepsilon(z)} \partial_\varepsilon \phi_y(z)) + N_{\text{dom} \Phi}(z)) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B},$$

respectively, if $\text{ri}(\text{dom} \Phi) \neq \emptyset$, and by (4.35), (4.36), and

$$\alpha\mathbb{B} \subseteq \partial f(z) + [0, 1] \text{clco}(\cup_{y \in Y_+(z)} \partial \phi_y(z)) + [N_S(z)]^\circ + N_\Omega(z) \cap \mathbb{B},$$

respectively, if assumptions (B1) and (B2) hold.

Remark 4.11. Involving the subdifferential formulas for \hat{f} presented in Remark 4.6 into the considerations of characterizing the global/local/boundedly weak sharp minima property of the convex infinite optimization problem (4.1), one can establish similarly the counterparts of Theorems 4.8–4.10, which provide some other characterizations for the corresponding weak sharp minima properties. In particular, the characterization results based on the subdifferential formula (4.25) do not require the blanket assumption $\text{ri}(\text{dom} f \cap \text{dom} \Phi) \neq \emptyset$ made in Theorems 4.8–4.10.

Acknowledgment. The authors are grateful to two anonymous reviewers for their valuable suggestions and remarks, which allowed us to improve the original presentation of the paper.

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