



Tutorial 6: Decision Trees

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Classifiers

Classifiers from previous lectures:

• Zero-Rule: class with the most instances (rule)

One-Rule: rules for one attribute

Naïve Bayes: conditional probability attribute - class

What is the difference between classification and regression?

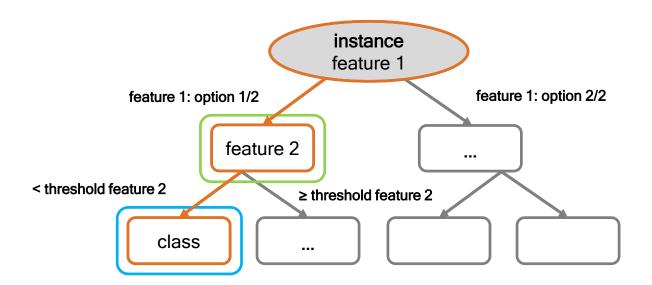
Classification	Regression
Prediction of a class label by means of the attributes	Prediction of a numerical value by means of the attributes





Classification Decision Trees

- A decision tree for n different classes is created based on some training data
- An internal node is a test on an attribute
- A branch represents an outcome of the test
- A leaf node represents a class
- A new instance is classified by following a matching path to a leaf node







Optimal Tree

For m attributes and n = 2 classes, there are 2^{2^m} possible trees already

That is equal to the number of Boolean functions

Finding the optimal tree is NP-complete

Not feasible for data mining applications

Solution: Greedy algorithm for tree construction

- Top down approach: The tree is created recursively from the root node
- Every possible split is assessed with a measure
- The best split is chosen
- Repeat until all leaf nodes are pure or all attributes have been used





Evaluating splits

Which split is better?

- Instances should be classified as easy as possible
- Good separation of classes (ideally leaf nodes contain instances of a single class only)
- In the worst case the separation does not affect the class distribution
- Possible measure: information





Information and entropy

- Let us denote c_i to be the absolute number of training examples being in class i at the current stage
- The probability (relative frequency) of class i then is $p_i = \frac{c_i}{c}$ with $C = \sum_{i=1}^n c_i$

Entropy measures information content in bits (uncertainty of a node):

entropy
$$(p_1, ..., p_n) = -\sum_{i=1}^n p_i \cdot \log_2 p_i$$
.

Information necessary to classify:

$$\inf([c_1,...,c_n]) = \operatorname{entropy}\left(\frac{c_1}{C},...,\frac{c_n}{C}\right).$$

Represents the expected amount of information that would be needed to specify the class of this node.





Information gain

The quality of a split is equal to the gained information

gain(attribute) = info(before split by attribute) - info(after split by attribute)





Formulas

Entropy:

entropy
$$(p_1, ..., p_n) = -\sum_{i=1}^n p_i \cdot \log_2 p_i$$

Information for $C = \sum c_i$:

$$info([c_1, ..., c_n]) = entropy\left(\frac{c_1}{C}, ..., \frac{c_n}{C}\right)$$

Average information for a numeric split into m branches, with $L_i = [c_{i,1}, ..., c_{i,n}]$ being the set of class counts in this split, $C_i = \sum_k c_{i,k}$ the corresponding number of instances, and $L = \sum C_i$:

$$info(L_1, ..., L_m) = \sum_{i=1}^{m} \frac{C_i}{L} \cdot info(L_i)$$

Information gain:

gain(attribute) = info(before split by attribute) - info(after split by attribute)

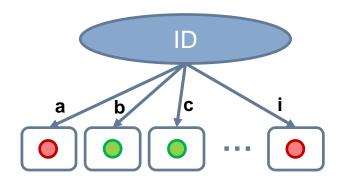




Information gain problems

Biased against attributes with a lot of edges

- For example: ID attribute
- Highest information gain because every leaf is pure
- Results in overfitting



Solution

- Take number and size of leafs into account: Intrinsic Information
- Intrinsic information: with s being the size of a leaf (number of affected instances)

$$intrinsicInfo(attribute) = info([s_1, ..., s_n])$$

New criterion: Gain ratio

$$gainRatio(attribute) = \frac{gain(attribute)}{intrinsicInfo(attribute)}$$





Numerical attributes

Considering nominal attributes

- one edge per attribute value works well
- bad in case of numerical values

Solution: Binary Splits

- values are separated into two sections: below (<) and above (≥) some chosen threshold
- the split is evaluated with the information gain: set threshold to a value, s.t.
 information gain is maximized
- common practice to place numeric thresholds halfway between the values that delimit the boundaries
- Numeric attributes may be tested several times in a tree