

# May Wang

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## EDUCATION

### Cornell University, College of Engineering

*Bachelor of Science in Mechanical Engineering*

Coursework: System Dynamics, Fluid Mechanics, Dynamics, Mechanical Synthesis, Statics & Mechanics, Waves & Oscillations, Materials, Differential Equations, Linear Algebra, Thermodynamics, OOP & Data Structures

GPA: 3.53

**Ithaca, New York**

*Expected May 2026*

## PROFESSIONAL EXPERIENCE

### KM-RoBoTA

*Robotics Engineer*

**Lausanne, Switzerland**

*May 2025 - Aug 2025*

- Co-authored paper on robotic applications of the bimodal kinematics in lateral gecko jumps (under peer-review at Nature)
- Submitted 2 international patents on lotus root inspired 6-DOF stress sensor and hydrodynamic compliant robot caudal fin
- Rebuilt amphibious quadrupedal salamander robot with actuated spinal column, optimizing for environmental robustness
- Individually manufactured and quality controlled wireless motion capture devices for a ~\$10k sports performance contract

### SUMRIDGE PARTNERS AT RAYMOND JAMES

*Data Engineer / Scientist*

**Jersey City, NJ**

*May 2024 - Aug 2024*

- Developed and deployed real-time data processing framework to production that handles 2 million data points per hour
- Created in-house tooling and automated data ingest pipeline using pandas and SQL to process 800M historical data points
- Applied Iglewicz and Hoaglin outlier tests with time, spread, and source-specific tunings on multidimensional datasets
- Collaborated with traders to build tools using BeautifulSoup and Whisper for robust data parsing during live conferences

## LEADERSHIP AND SCHOOL ACTIVITIES

### ORGANIC ROBOTICS LAB

*Undergraduate Researcher*

**Ithaca, NY**

*Oct 2023 – Present*

- Published a paper on developing an ethanol histology sample dehydrator, cutting cost of equipment from \$30,000 to \$300.
- Prototyped a pneumatic-solenoid actuation system in a modular soft robotic worm to achieve agile underground movement
- Integrated force feedback and computer vision data to build accurate models that predicts soil conditions for agricultural use

### CORNELL UNIVERSITY AUTONOMOUS UNDERWATER VEHICLE

*Mechanical Engineering Subteam*

**Ithaca, NY**

*Oct 2022 - Present*

- Developed a novel hydroacoustic communication buoy; Was responsible for all mechanical, electrical, and software design
- Engaged in multiple semester-long four-stage design reviews, coordinating interdisciplinarity constraints and objectives
- Assessed and devised solutions around 50-feet of water pressure, varying outdoor lighting, and diverse aquatic environments
- Precision machined and anodized aluminum components using manual lathes and mills to team defined GD&T standards

### CORNELL MAKER CLUB

*Training & Equipment Chair*

**Ithaca, NY**

*Jan 2023 - Present*

- Mentored new members on tool and software usage with laser cutters, FDM 3D printers, PCB mills, and CNC routers
- Procured, maintained, and repaired lab equipment and materials, maximizing the effectiveness of the club's allocated budget
- Undertook commission work for Cornell's engineering department for events, managed alumni interactions and relations
- Organized Cornell Make-a-thon and actively engaged in community outreach events within the broader engineering sphere
- Assisted grad students and faculty with rapid prototyping, ran workshops to aid undergraduate students on personal projects

## COMPETITIONS AND PERSONAL PROJECTS

### CORNELL MAKE-A-THON

*First Place, Rookie Division*

**Ithaca, NY**

*Mar 2023*

- Designed and prototyped an automated nursery for an environmental hardware hackathon in 18 hours as a solo competitor
- Solved water dispensing problems with soft robotics; modified slicer settings while printing to create waterproof vessels
- Implemented PID control in C++ with 6 environmental sensors to maintain humidity, lighting, and temperature conditions

## SPECIALIZED SKILLS

**Software:** SOLIDWORKS (including FEA), Ansys, Python, JS, Java, C++, MATLAB, KiCAD, Photoshop and Illustrator

**Skills:** Manual and CNC Machining, Rapid Prototyping, PCB Design, GD&T, Mandarin (Fluent), ASL (Conversational)