Control of Multi-agent Systems with Python

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Program: 10:00∼17:00

1. Introduction to multi-agent systems and applications (**M. Nagahara**)
2. Linear algebra and graph theory (**M. Nagahara**)
3. Consensus control (**S. Azuma**)
4. Coverage control (**S. Azuma**)

Requirement: Python environment

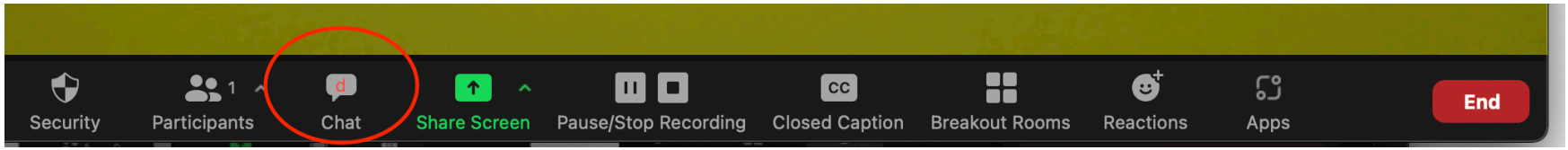
- We use Python as a programming language for numerical computation in multi-agent systems control.
- We strongly recommend to use Google Colaboratory (Colab in short), a web browser-based programming environment of Jupyter notebook for Python. You don't need to install any softwares. Just use your web browser, and access

  `https://colab.research.google.com/`

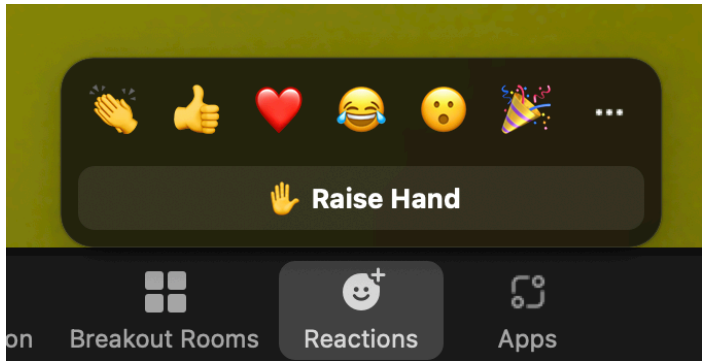
- We will explain how to use it later.

Questions?

- If you have any questions during the presentation, please use Chat.



- In the Q & A sections, please use Raise Hand in Reactions if you want to ask questions using your microphone. You can also use Chat in Q & A.



Python programs and lecture slides

https://drive.google.com/drive/folders/1YOFu2b3tDSOXsP_YV5NpaGGPeujIrkf1

Are you ready?

Let's get started!