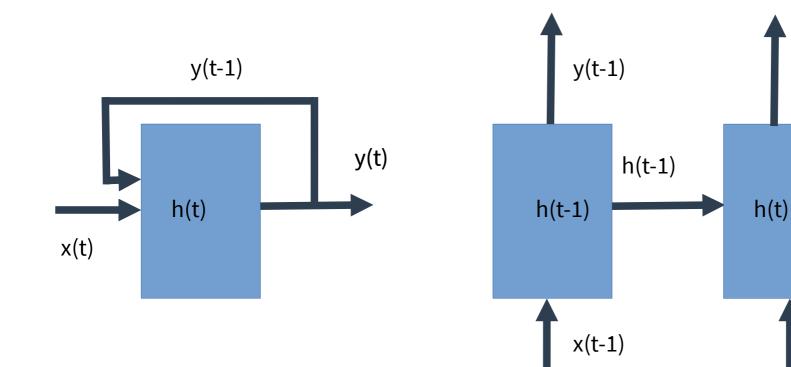


Рекурентные сети RNN



y(t)

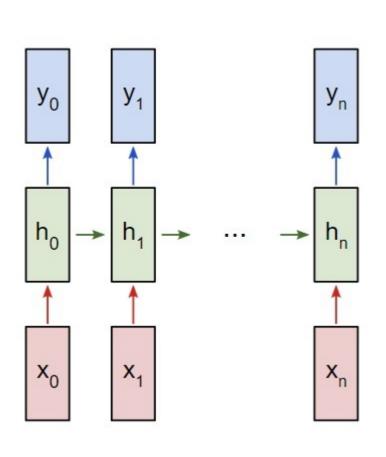
x(t)

h(t

https://python-scripts.com/recurrent-neural-network

https://habr.com/ru/company/wunderfund/blog/331310/

Вычисление RNN



Зачем?

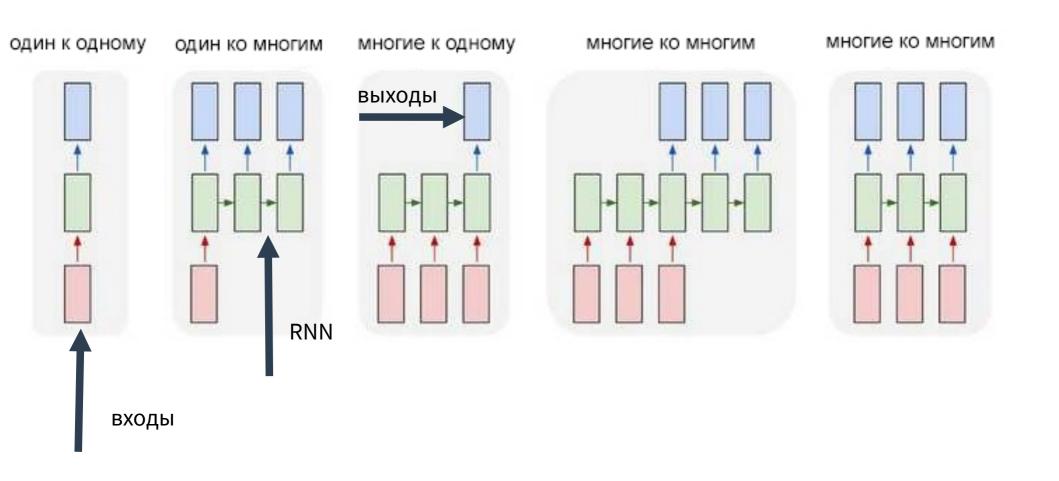
Птица пьет из ключа



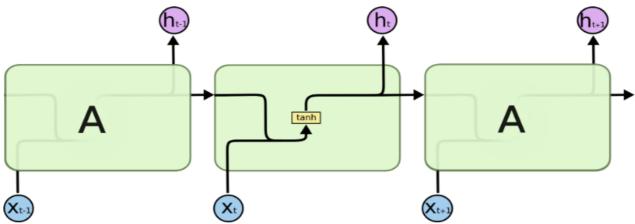


$$h_t = anh(W_{xh}x_t + W_{hh}h_{t-1} + b_h)$$
 $y_t = W_{hy}h_t + b_y$

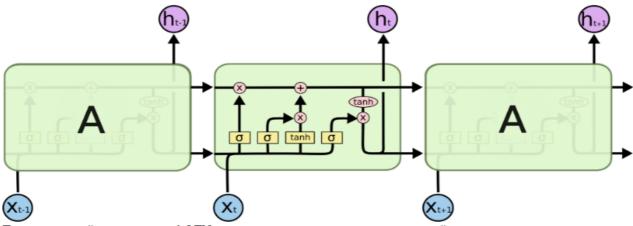
Варианты рекурентных сетей



RNN vs LSTM

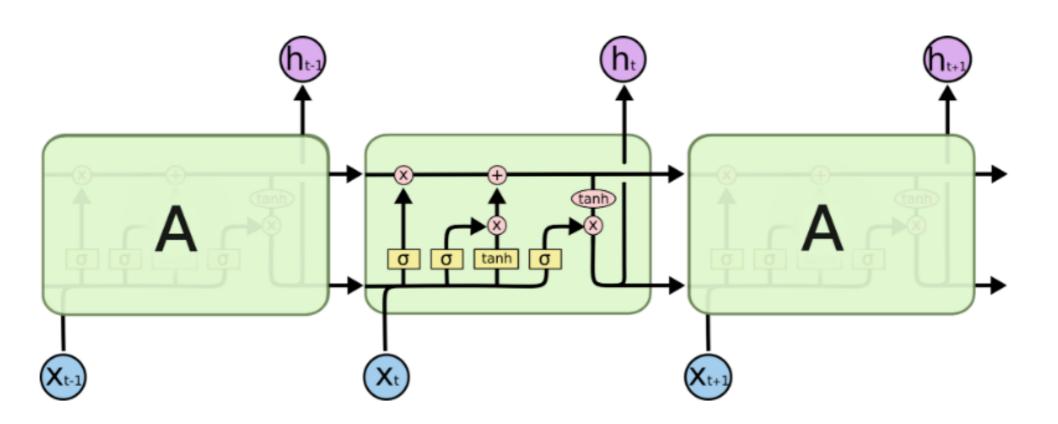


Повторяющийся модуль в стандартной RNN состоит из одного слоя.

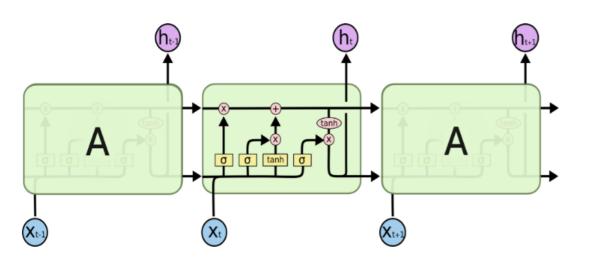


Повторяющийся модель в LSTM сети состоит из четырех взаимодействующих слоев.

RNN vs LSTM



LSTM + BPTT



$$egin{aligned} g(t) &= \phi(W_{gx}x(t) + W_{gh}h(t-1) + b_g) \ i(t) &= \sigma(W_{ix}x(t) + W_{ih}h(t-1) + b_i) \ f(t) &= \sigma(W_{fx}x(t) + W_{fh}h(t-1) + b_f) \ o(t) &= \sigma(W_{ox}x(t) + W_{oh}h(t-1) + b_o) \ s(t) &= g(t) * i(t) + s(t-1) * f(t) \ h(t) &= s(t) * o(t) \end{aligned}$$

$$l(t) = f(h(t), y(t)) = \|h(t) - y(t)\|^2$$

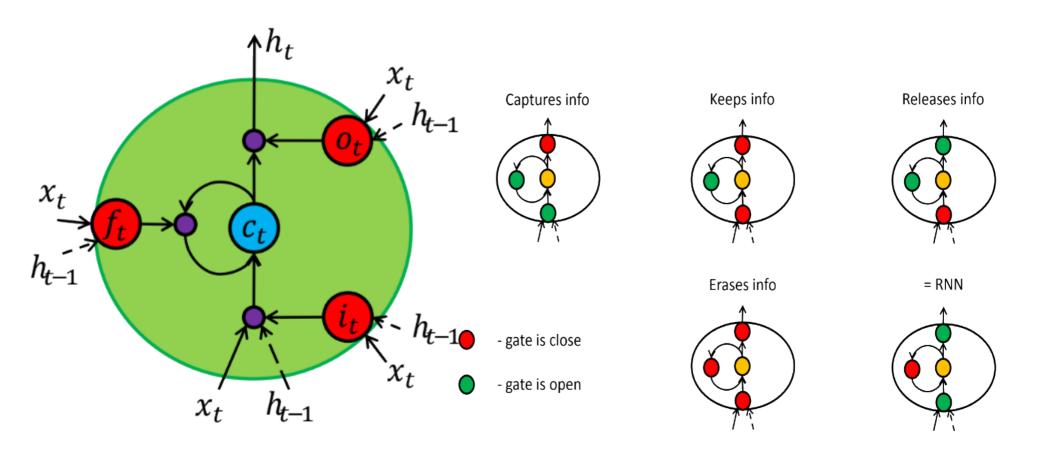
$$L = \sum_{t=1}^T l(t)$$
 $L(t) = egin{cases} l(t) + L(t+1) & ext{if } t < T \ l(t) & ext{if } t = T \end{cases}$

$$rac{dL(t)}{dh(t)} = rac{dl(t)}{dh(t)} + rac{dL(t+1)}{dh(t)}$$

$$\frac{dL(T)}{dh(T)} = \frac{dl(T)}{dh(T)}$$

$$rac{dL}{dw} = \sum_{t=1}^T \sum_{i=1}^M rac{dL(t)}{dh_i(t)} rac{dh_i(t)}{dw}$$

RNN vs LSTM



SimpleRNN

LSTM

GRU RNN Gated Recurrent Unit (GRU)

```
LSTM(units, activation="tanh",
recurrent_activation="sigmoid",
 use_bias=True, kernel_initializer="glorot_uniform",
 recurrent_initializer="orthogonal",
bias initializer="zeros",
 unit_forget_bias=True,
 Dropout=0.0, recurrent_dropout=0.0,
 return_sequences=False, return_state=False)
```

CallBacks

```
my_callbacks = [
    tf.keras.callbacks.EarlyStopping(patience=2),
    tf.keras.callbacks.ModelCheckpoint(filepath='model.
{epoch:02d}-{val_loss:.2f}.h5'),
    tf.keras.callbacks.TensorBoard(log_dir='./logs'),
]
model.fit(dataset, epochs=10, callbacks=my_callbacks)
```

https://keras.io/api/callbacks/

Embeding
tf.keras.layers.Embedding(
 input_dim,
 output_dim
)

