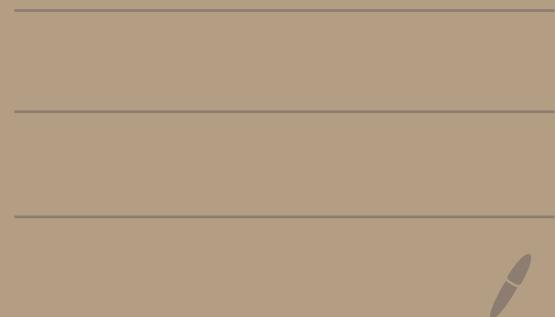


Lecture 3 Logistic Regression



$$\underline{h_{\theta}(x)} \not\in \theta^T x \notin [0, 1]$$

$$g(\theta^T x)$$

$$\underline{\theta}$$

$$P(y|x; \theta) = \begin{cases} h_{\theta}(x) & y=1 \\ 1 - h_{\theta}(x) & y=0 \end{cases}$$

$$g(z) = \frac{1}{1+e^{-z}}$$

$$g'(z) = g(z) \frac{h(\alpha) - g(z)}{1 - g(z)}$$

$$L(\theta) = y \log h(\alpha) + (1-y) \ell \log (1-h(\alpha))$$

$$\frac{\partial L(\theta)}{\partial \theta_j} = y \cdot \frac{1}{g(\alpha^T x)} \cdot \frac{\partial}{\partial \theta_j} g(\alpha^T x)$$

$$+ (1-y) \frac{1}{1-g(\alpha^T x)} \left(- \frac{\partial g(\alpha^T x)}{\partial \theta_j} \right)$$

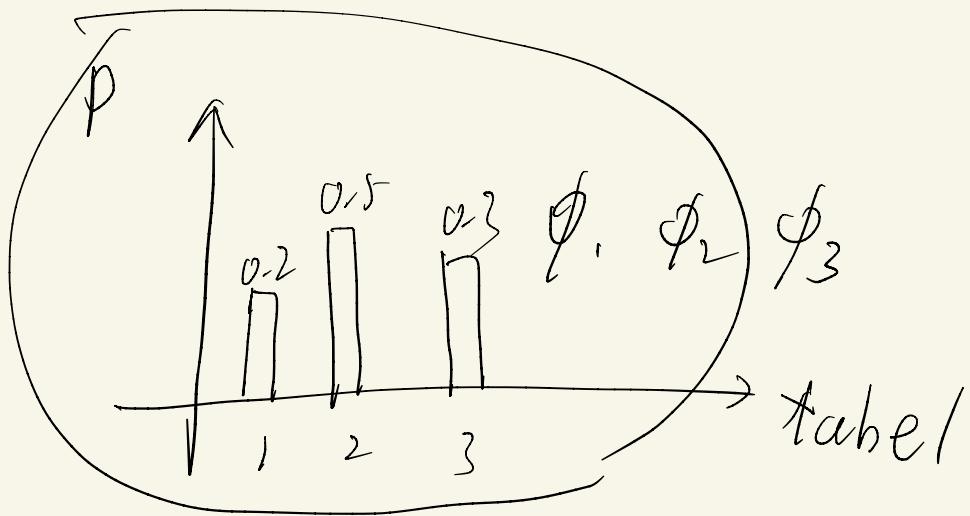
$$= \left(y \frac{1}{g(\alpha^T x)} - (1-y) \frac{1}{1-g(\alpha^T x)} \right) \frac{\partial}{\partial \theta_j} g(\alpha^T x)$$

$$= \left(y \frac{1}{g(\alpha^T x)} - (1-y) \frac{1}{1-g(\alpha^T x)} \right) g'(\alpha^T x) g(\alpha^T x)$$

$$= [y - h(\alpha^T x)] x_j$$

chain rule

$$\frac{\partial g(\theta^T x)}{\partial \theta} = \underbrace{\frac{\partial g(\theta^T x)}{\partial (\theta^T x)}}_{\equiv} \cdot \underbrace{\frac{\partial (\theta^T x)}{\partial \theta}}_{\equiv} \quad \times$$



$$0.2 + 0.5 + 0.3 = 1$$

$$\phi_i = \theta_i^T x \quad \frac{[0, 1]}{1 + e^{-x}}$$

$$\sum_{i=1}^k \frac{\exp(t_i)}{\sum_{j=1}^k \exp(t_j)} = 1 \quad \text{label}_i$$

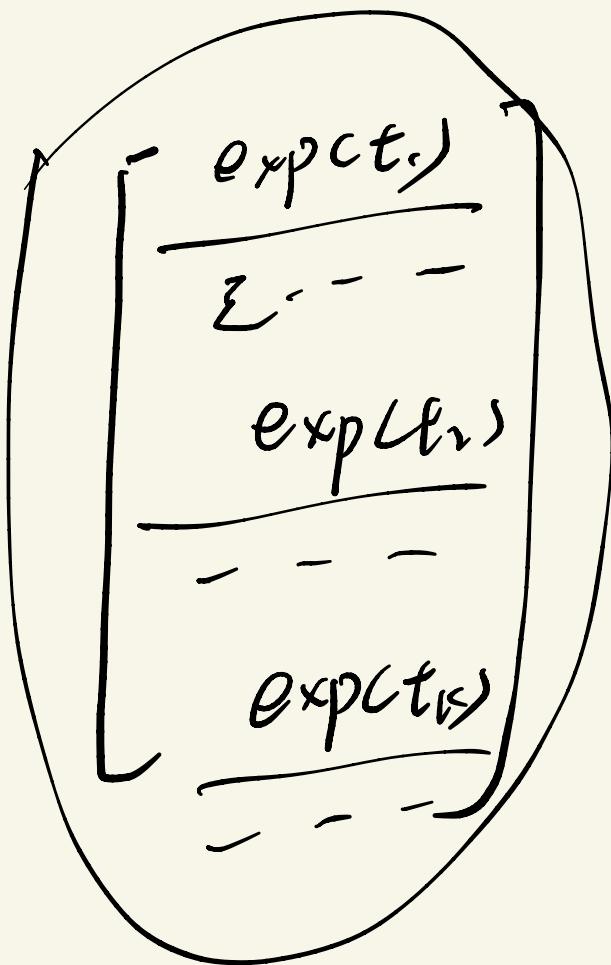
t_i larger $\exp(t_i)$

$\exp(t_i)$ larger

t_i logit

$$P(y=i) \propto \exp(t_i)$$

$$\frac{P(y=i)}{P(y=j)} = \frac{\exp(t_i)}{\exp(t_j)}$$



$$\sum_i \phi_i = 1$$

K

K-1

degree of freedom

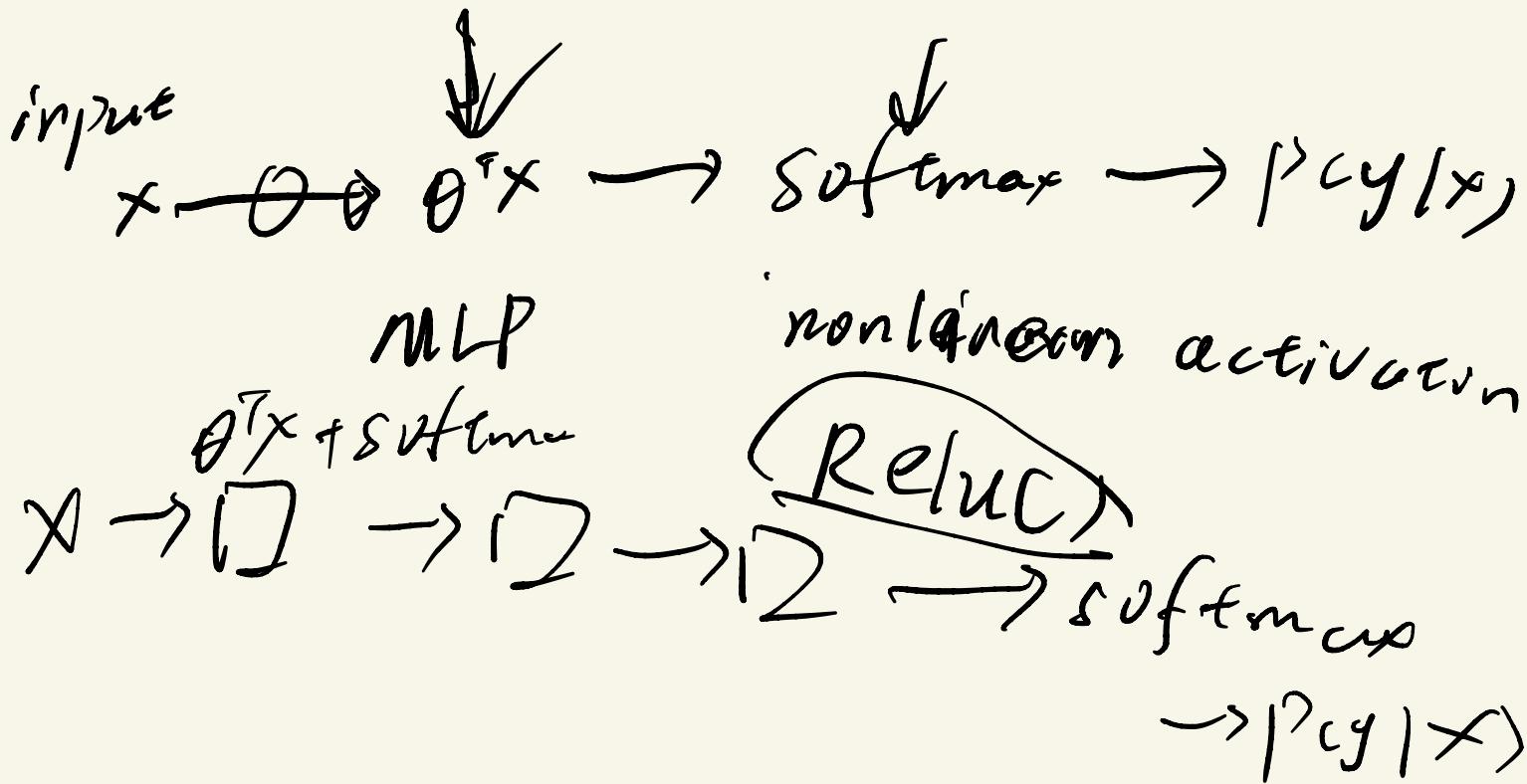
K-1

$$\begin{bmatrix} 0.1 \\ 0.2 \\ 0.7 \end{bmatrix}$$

$$1 - 0.3 = 0.7$$

$$\theta_i \in R^d \quad x \in R^d$$

$\theta_1, \theta_2, \dots, \theta_K$ $K \times d$ parameters



$$l_{ce} \stackrel{R^k \times f(t_1, \dots, t_k)}{=} \underset{y}{\underline{\underline{}} \rightarrow \underline{\underline{R_{>0}}}}$$

$$\theta^T x$$

$$l_{ce}([t_1, \dots, t_k], y) = -\log \left[\frac{\exp(t_y)}{\sum_{j=1}^k \exp(t_j)} \right]$$

$$l_{ce} = -\log \left(\frac{\exp(t_y)}{\sum_{j=1}^K \exp(t_j)} \right) \quad t = \theta^T x$$

$$\frac{\partial l_{ce}}{\partial t_i} = -\frac{1}{\phi_y}$$

$$\frac{\partial}{\partial t_i} \frac{\exp(t_y)}{\sum_{j=1}^K \exp(t_j)} = \phi_i$$

$$l_{ce} = -\log \phi_i$$

$$= -\frac{1}{\phi_y} \cdot \left[\frac{\partial}{\partial t_i} \frac{\exp(t_y)}{\sum_{j=1}^K \exp(t_j)} \right] \cdot \frac{1}{\sum_{j=1}^K \exp(t_j) + \exp(t_y) \cdot \frac{\partial}{\partial t_i} \left[\frac{1}{\sum_{j=1}^K \exp(t_j)} \right]}$$

$$= -\frac{1}{\phi_y} \left[\exp(t_y) \cdot \frac{-\exp(t_i)}{\left(\sum_{j=1}^K \exp(t_j)\right)^2} + \begin{cases} \frac{\exp(t_i)}{\sum_{j=1}^K \exp(t_j)} & i=y \\ 0 & i \neq y \end{cases} \right]$$

$$\left(-\phi_y \cdot \phi_i^* + \begin{cases} \phi_i & i=y \\ 0 & i \neq y \end{cases} \right)$$

$$\phi_i \cdot \underbrace{\mathbb{1}[y=i]^{\text{true}}}_{\text{true}}$$

$$\frac{d}{dx} f(x) \cdot g(x)$$

$$= g(x) \cdot \frac{d}{dx} f(x) + f(x) \cdot \frac{d}{dx} g(x)$$

$$\theta_i^{\text{new}} = \theta_i^{\text{old}} - [\phi_i^{\text{old}} - 1_{(y=i)}] \times \frac{x}{\|\mathbf{x}\|_2}$$

feature associated with label i

ϕ_i^{old} scalar
 negative $y \neq i$ $1_{(y \neq i)}$
 positive $y \neq i$ $1_{(y=i)}$

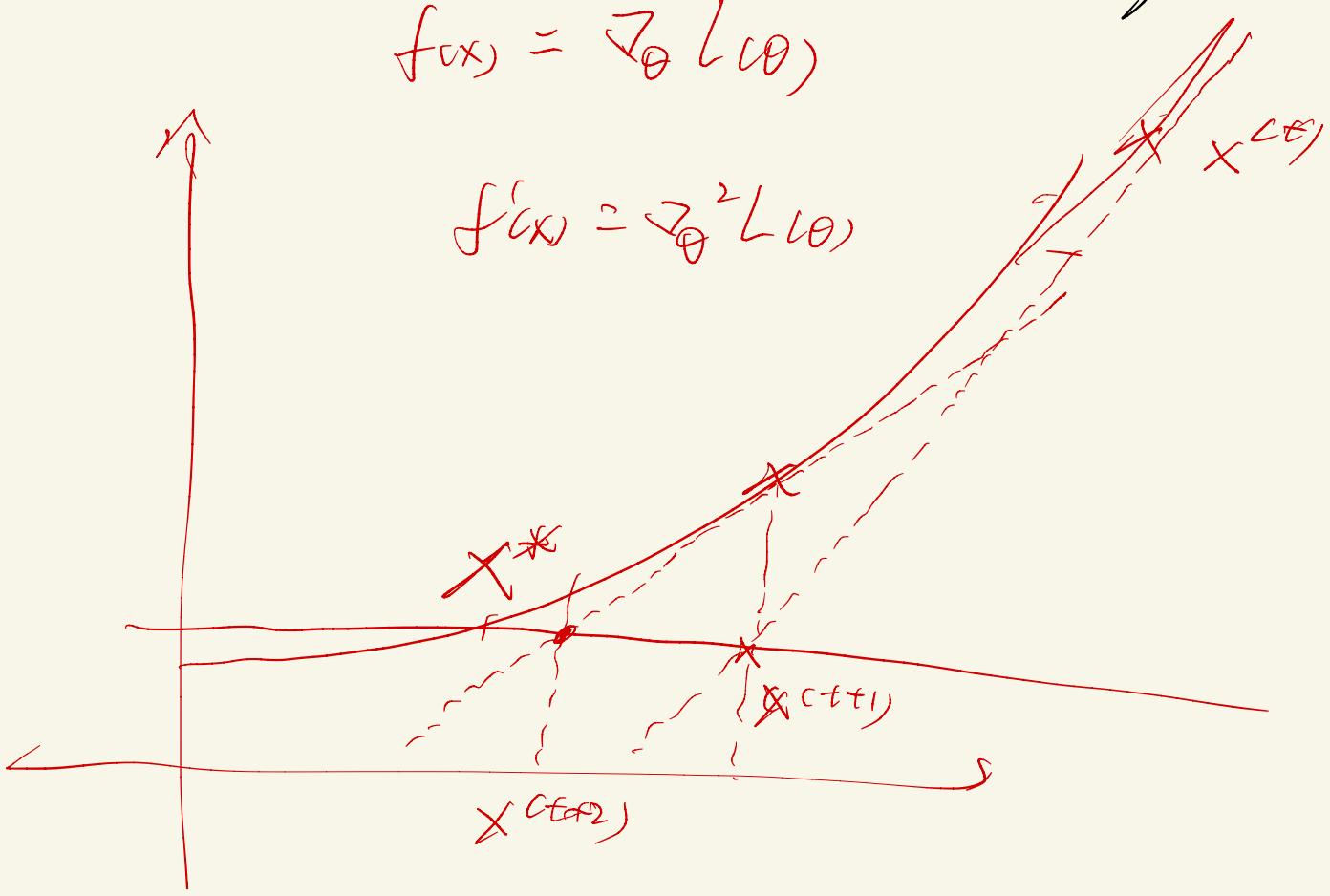
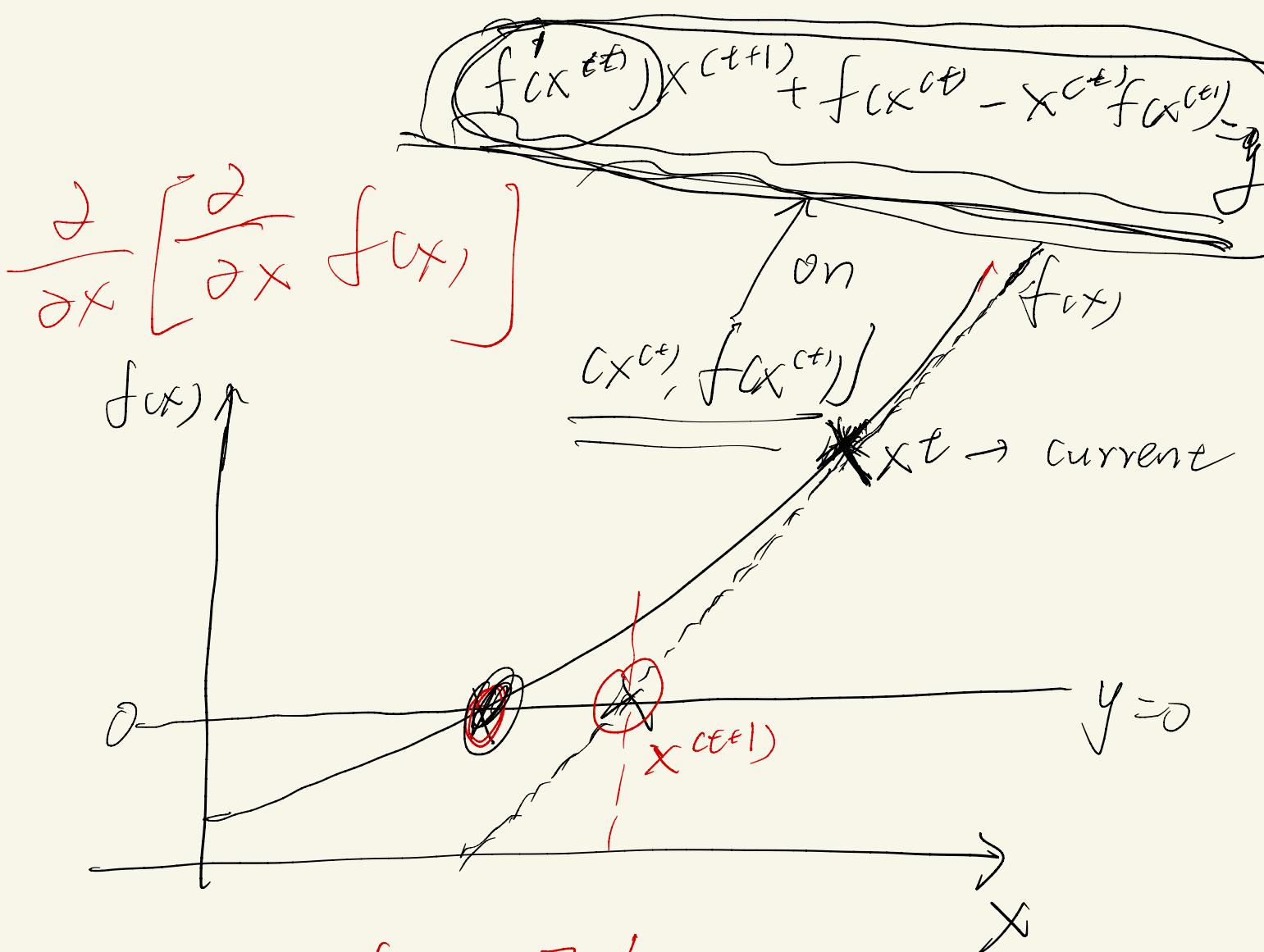
$$t_i = \theta_i^T x$$

logit label i softmax(t) = p

$$t_i^{\text{new}} = [\theta_i^{\text{old}} - [\phi_i^{\text{old}} - 1_{(y=i)}] \times \mathbf{x}]^T \mathbf{x}$$

~~$\theta_i^{\text{old}} \times$~~ ~~$[\phi_i^{\text{old}} - 1_{(y=i)}] \times \mathbf{x}^T \mathbf{x}$~~

~~old prob~~ ~~$\mathbf{x}^T \mathbf{x} = \|\mathbf{x}\|_2^2 \geq 0$~~



$$\phi = h_{\theta}(x) = g(\theta^T x)$$

$$\phi_i = \underline{\theta^T x}$$

$$\phi_i \in [0, 1] \cup$$