### MAYURESH SAVARGAONKAR

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An industrial engineer with a demonstrated history of working in think tanks, academia, and industry on Autonomous Vehicles (AVs), warranty analytics, and Lithium-ion batteries. My expertise lies in building solutions using machine learning, artificial intelligence, Bayesian methods, simulation tools, and engineering and physics principles for the world of automated and connected mobility.

### **Education**

Ph.D. in Industrial Engineering Thesis: Towards Connected and Autor University of Michigan, Dearborn	GPA: 4.0 nated Mobility - Artificial Intelligence for Safe Autonomous Driving	2019-2023
Master's in Industrial Engineering University of Michigan, Dearborn	GPA: 4.0	2016-2018
Bachelor's in Mechanical Engineering University of Pune (India)	GPA: 3.9	2011-2015

#### **Research Interests**

■ Autonomous Vehicles ■ Connected Mobility ■ AV simulation ■ Explainable Artificial Intelligence ■ Customized Deep Learning ■ Spatio-Temporal Modeling ■ Warranty Analytics ■ Remaining Useful Life

### **Professional Experience**

# Graduate Student Research Assistant University of Michigan- Dearborn

2019-Present

Project: Virtual Verification and Validation of Autonomous Vehicles – Ford Motor Company

- Led a project for verification and validation of AVs using Software-in-Loop testing. The project uncovered over 35 unknown unsafe scenarios, some of which were later observed in real-life testing by Waymo.
- Increased safety readiness at Ford Motor Company by employing virtual test strategies. The unsupervised learning strategies can generate over 20,000 complex scenarios using simulated agents in less than 72 hours.
- Incorporated data-driven methods for improving risky situation realization in vehicle log data by over 20%. The developed method is a random forest regressor based on NHTSA and industry-used metrics.

Project: Artificial Intelligence in Connected Autonomous Driving Technology

- Released a self-driving dataset with over 600 scenarios that promote the use of infrastructure information in trajectory or motion planning and control.
- Formulated the first trajectory prediction algorithm that integrates road level Vehicle-to-Vehicle and Vehicle-to-Infrastructure information. The use of such information increased prediction accuracy by over 50%.
- Pioneered a web-based, on-demand, scenario generation interface that generates, saves, and tags self-driving sensor information. Saved sensor information includes RGB, Radar, LiDAR, depth, and semantic segmentation.
- Integrated a statistical post-processing method that improves the performance of pre-trained perception networks by over 29% without re-training for object detection.

Project: Bayesian models for Warranty Analytics – Ford Motor Company

- Developed a Machine Learning model that predicts warranty claims for Ford Motor Company's reliability division with a 2% error over 18 months.
- Successfully provided uncertainty quantification using Bayesian optimization and unsupervised clustering.

# Project: AI-driven models for Prognostics in Lithium-ion batteries

- Researched over 6 artificial intelligence models for online and robust state-of-charge estimations in Lithium-ion batteries with over 99% accuracy.
- Leading a research group of 3 doctoral students to develop time-series models that analyze the quality of each manufactured Lithium-ion cell in a manufacturing environment. The group has over 4 publications.

# **Summer Intern – Research and Robotics Engineering Ford Motor Company**

Project: Developing Synthetic Test Capabilities for Ford Motor Company's Level 4 Highway Pilot Feature

- Deployed a simulation-based testing framework for Ford's self-driving stacks. The project is estimated to save over 10,000 hours of real-life testing.
- Setup communication bridges with average latency of 10ms for interfacing Ford's autonomous driving system with a simulator. This was done by establishing Robotic Operating System (ROS) and TCP/IP pipelines using a dedicated python library.
- Replicated vehicle CAN interface for real-time communication with driving policies in Simulink. Over 200 CAN signals were replicated using CARLA.
- Designed OpenDrive maps for simulated testing of Ford's Highway Pilot and Advanced Driver Assistance features.

# **Industrial Engineering Program Manager Production Modeling Corporation**

2017-2019

Project: Cost, Value, and Feasibility analysis for FCA, Ford, BMW, and Volvo Laser Scanning Programs.

- Reduced laser scanning and modeling defects by over 20% using lean techniques for continuous improvement.
- Organized a team of 6 for designing and developing parametric conveyor models in AutoCAD.
- Used agile methods for project liaisons between India, Mexico, and the USA, saving > 100hrs/month of redundancy.
- Created risk mitigation plans and performed root cause analysis to avoid production delays using a 5 Why's system.

# **Top Publications**

- 1. **Mayuresh Savargaonkar** and Abdallah Chehade. VTrackIt: A Synthetic Self-Driving Dataset with Infrastructure and Pooled Vehicle Information, 2022. (Under Review).
- 2. **Mayuresh Savargaonkar**, Abdallah Chehade, Ala A. Hussein. A Novel Neural Network with Gaussian Process Feedback for Modeling the State-of-Charge of Battery Cells. IEEE Transactions on Industry Applications, 2022.
- 3. Abdallah Chehade, **Mayuresh Savargaonkar**, Vasiliy Krivstov. Conditional Gaussian Mixture Model for Warranty Claims Forecasting. Reliability Engineering & System Safety, 2022.

### **Awards**

**Professional Awards** 

- Dearborn Difference Maker 2022 IISE-OCRE Best student paper 2020 Graduate Student Scholarship (\$12000)
- Ph.D. Student Fellowship

### **Profession Memberships and Associations**

■ IEEE ■ IISE ■ INFORMS ■ President IISE Dearborn Chapter ■ Treasurer Alpha Pi Mu-Dearborn Chapter

#### **Skills**

Programming Languages: Python, MATLAB, R, C++

Software: CARLA, ROS, Unreal Engine, SUMO, Simulink, Tableau, Git, CATIA V5R16, Inventor, ANSYS, MS Office, Linux

Python Libraries: TensorFlow, Keras, PyTorch, NumPy, Pandas, Matplotlib, Scikit-learn, OpenCV

Deep Learning Models: RNN, LSTM, VAE, GANs, DNN, CNN, reinforcement learning, q-learning, decision trees, random forest, Bayesian models, Gaussian mixture models, transformers

Technical Skills: Verification and Validation, Machine Learning, Artificial Intelligence, Computer Vision, Object Detection, Bayesian Learning, Text Analytics, Optimization, Design of Experiments, Statistics, ISO 21448, ISO 26262, DVP&R, PFMEA, DF&A, Software Engineering, Computer Science, Data Science, Data Analysis, Data Mining

### **Professional References**

Dr. Abdallah Chehade Assistant Professor University of Michigan - Dearborn achehade@umich.edu Dr. Onur Ulgen Professor, UM-Dearborn University of Michigan - Dearborn ulgen@umich.edu Mr. Sari Kassar Research Engineer Ford Motor Company skassar@ford.com