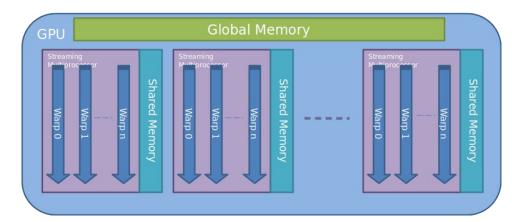
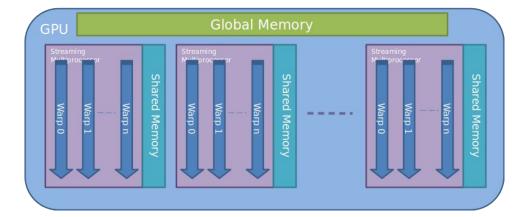
Optimizing Graph Algorithms for GPUs

By: Mayuresh Anand, Alon Albalak, Koa Sato

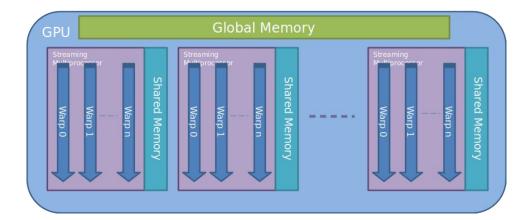
Composed of GPU cores



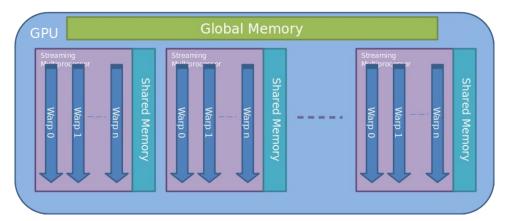
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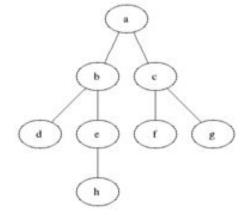


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- Threads are organized into warps, such that each warp executes an instruction in parallel
- Most GPUs utilize single-instruction, multiple-threads paradigm



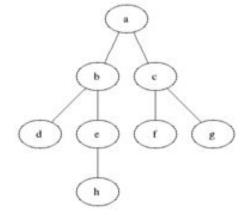
Graph Algorithms

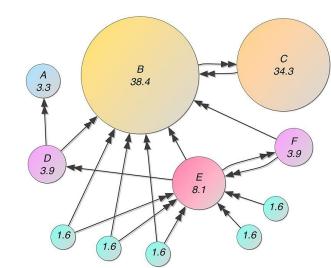
- Breadth-first search



Graph Algorithms

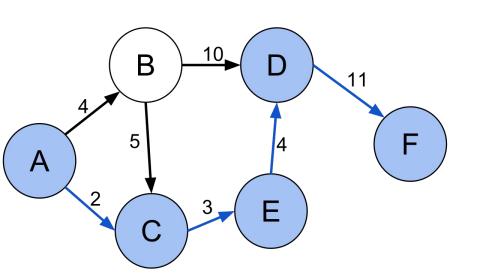
- Breadth-first search
- PageRank

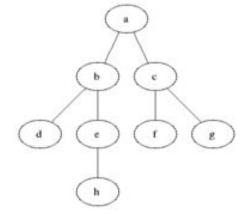


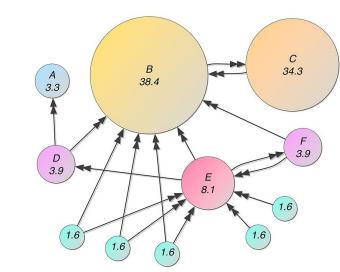


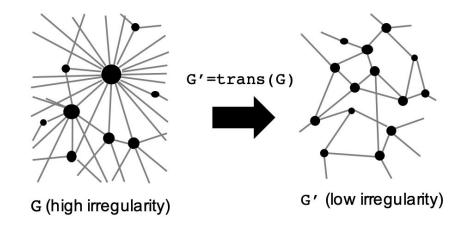
Graph Algorithms

- Breadth-first search
- PageRank
- Single-source shortest path

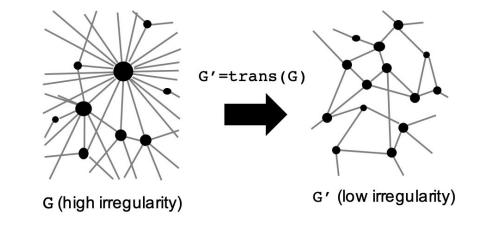


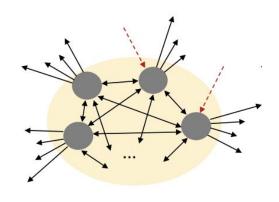






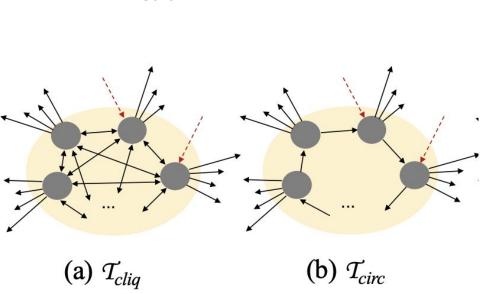
- Methods include transformations:
 - Clique

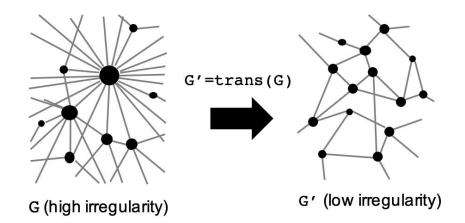




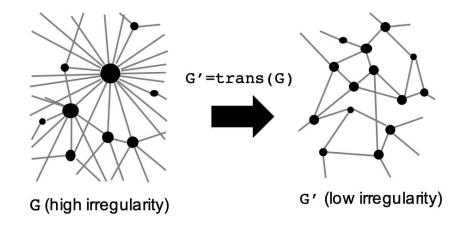
(a) \mathcal{T}_{clid}

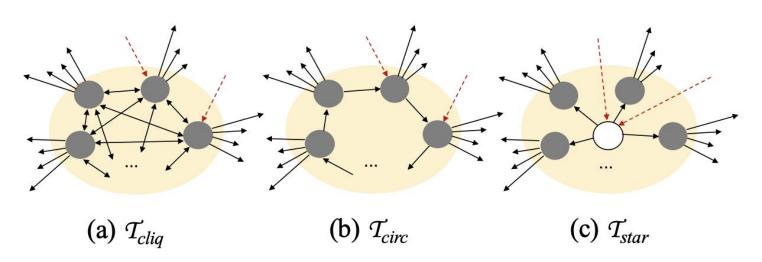
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- Methods include transformations:
 - Clique
 - Circular
 - Star





Tigr - Transforming Irregular Graphs into more Regular ones

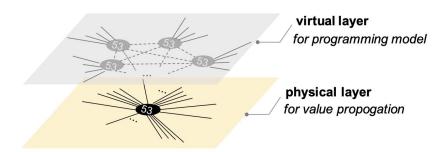
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- Previous works addressed the issue by:
 - Warp segmentation
 - Altering the graph algorithms
- Tigr targets the fundamental issue of irregularity by transforming the graph *virtually*

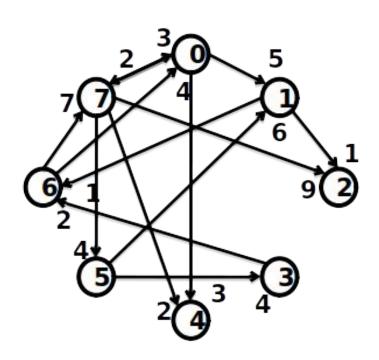


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- Shards allow contiguous placement of graph data required by a set of computation.
- G-Shards representation employs shard concept and modifies it appropriately for GPU.



Shard 0

Shard 1

SrcIndex 0 1 5 6 7 7	SrcValue X × X X X X X X X X X X X X X X X X X	Edge Valu 5	DestIndex 1
0	X	5	ĺ
1	X	1	2
5	X	6	1
5	X ₅	4	3
6	X	4	0
7	X ₇	3	0
7	X 7	9	2

O 0 1 3 6 7 7	SrcValue x o x o x 1 x 3 x 6 x 7 x 7	ule/	Destindex 4
0	X	3	4
0	X	2	7
1	X	1	6
3	X 3	2	6
6	X	7	7
7	X 7	2	4
7	X 7	4	5

- We want to make graph algorithms run faster

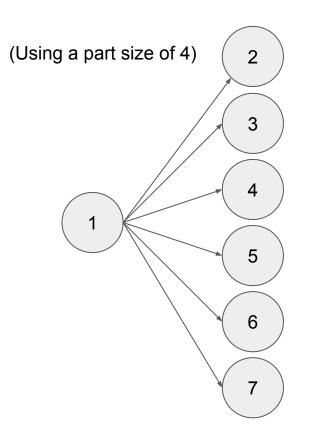
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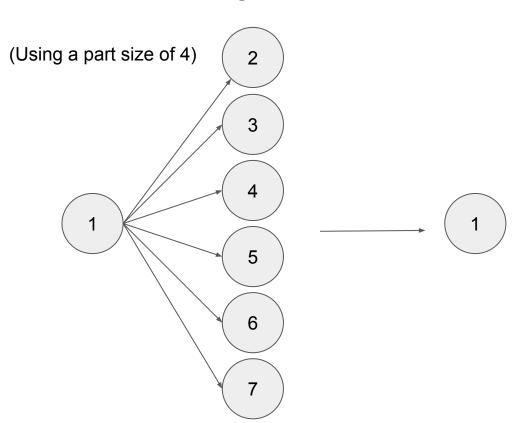
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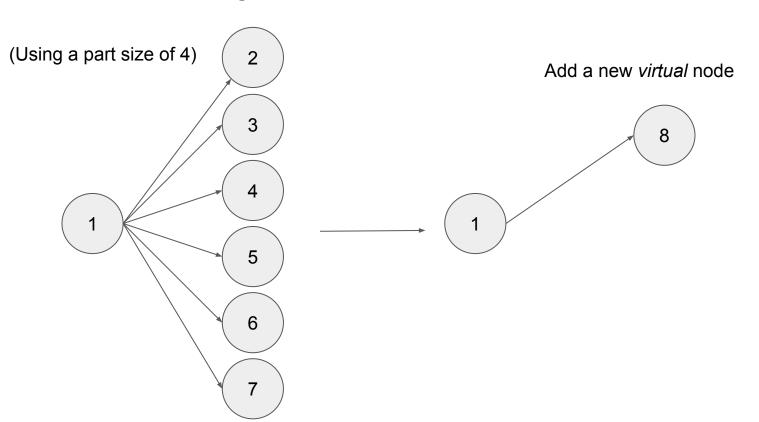
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- What if we convert graph to more regularized one using an intermediate representation and input to CUSHA
- This representation has lower out degree hence making it larger in size but regularized and efficient to process

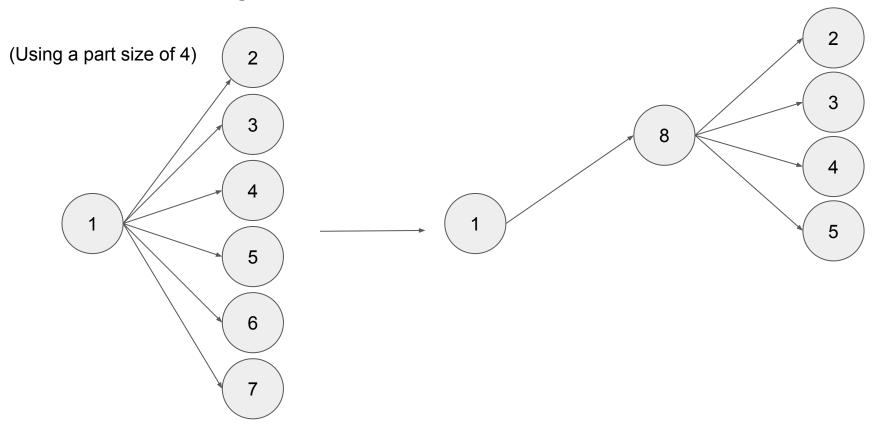
Hypothesis

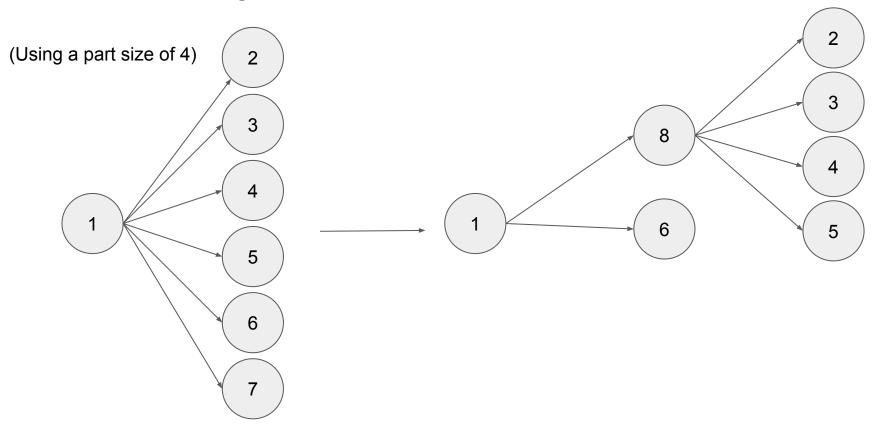
- Can we achieve better performance from CuSha if we perform a physical graph transformation (UDT) that regularizes the graph before inputting it into CuSha?

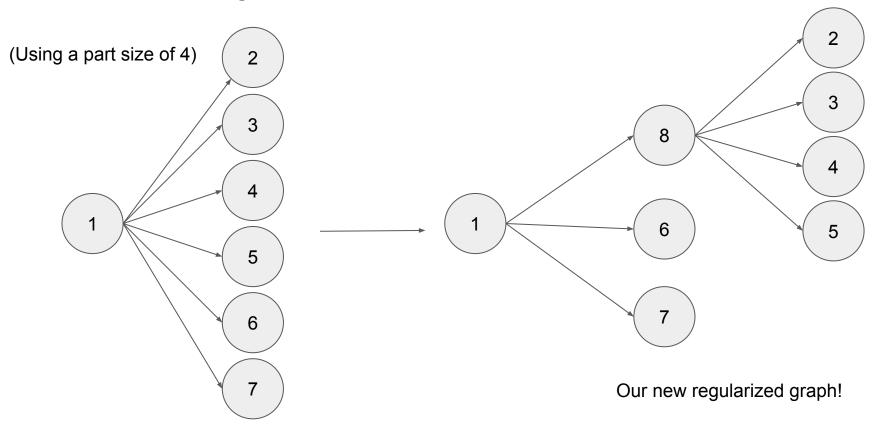












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Memory: 16 GB

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GPU: GTX 1060 6GB

Memory: 16 GB

OS: Ubuntu 18.04

Datasets

- Pokec social network¹
 - 1632803 vertices, 30622564 edges
- Higgs twitter²
 - 456627 vertices, 14855842 edges
- Amazon product co-purchasing network³
 - 403394 vertices, 3387388 edges

- 1 https://snap.stanford.edu/data/soc-Pokec.html
- 2 https://snap.stanford.edu/data/higgs-twitter.html
- 3 https://snap.stanford.edu/data/amazon0601.html

- Computation time for UDT-CuSha on BFS and SSSP

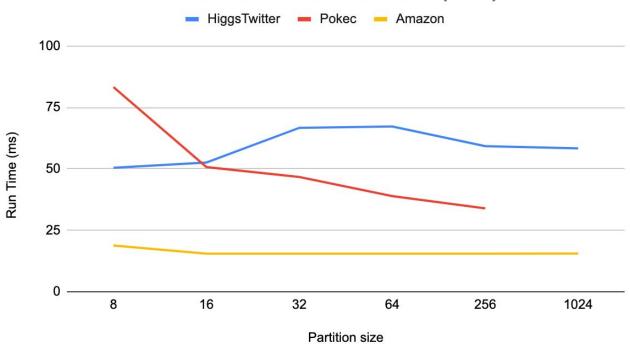
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- Comparison with baseline (Tigr-V+ and CuSha)

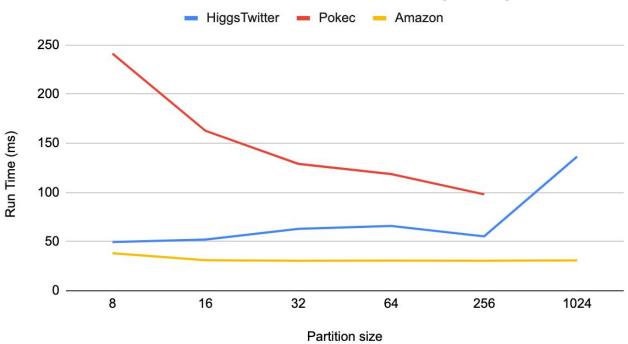
Experimentation Results





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Comparisons with Baselines

Twitter	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	CuSha	Tigr
Part Size	8	16	32	64	256	1024	N/A	8
Time (ms)	49.4730	52.0758	62.9978	65.9644	55.3284	136.479	132.789	6.7826

Amazon	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	UDT-CuSha	CuSha	Tigr
Part Size	8	16	32	64	256	1024	N/A	8
Time (ms)	38.1308	30.966	30.4466	30.5708	30.4798	30.8584	30.5586	7.182

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 - Intuitive as increasing part size means we have done less to alter the graph

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- Trade-off between increased number of nodes and regularization

Future work and things we didn't have time for

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- Try adjusting virtual warp size in CuSha algorithm to match part size

QUESTIONS?