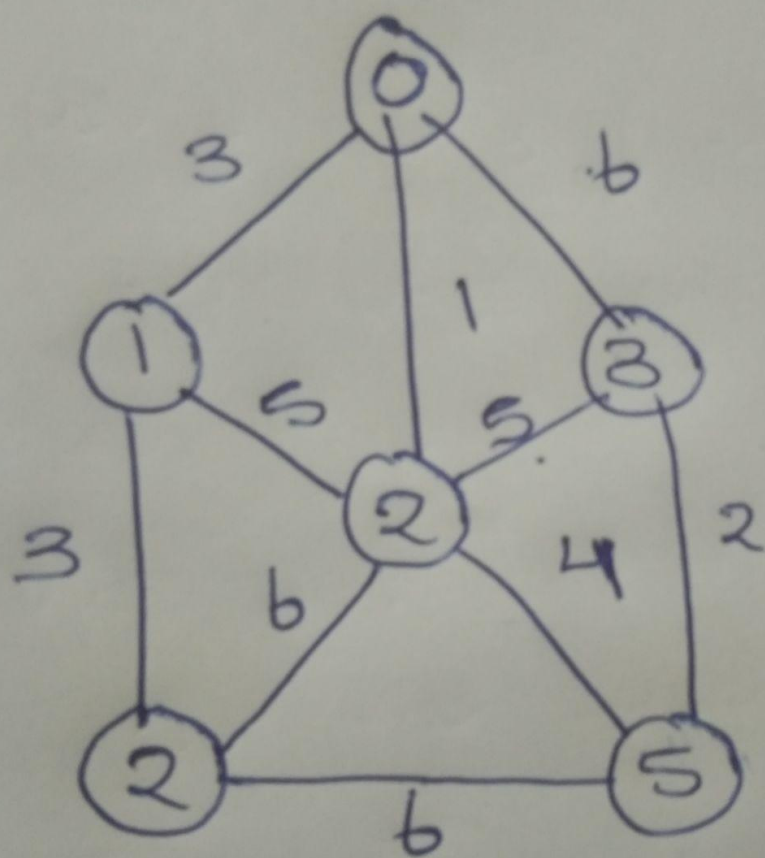


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DATA STRUCTURE LAB

GITHUB LINK:<https://github.com/mayurim20/DSLAb.git>

**1.DEVELOP A PROGRAM TO GENERATE MINIMUM SPANNING TREE
USING KRUSKAL'S ALGORITHM OF THE GIVEN GRAPH AND COMPUTE
THE TOTAL COST**



ALGORITHM:

KRUSKAL(G):

$A = \emptyset$

For each vertex $v \in G$.

V: MAKE-SET(v)

For each edge $(u, v) \in G$.

E ordered by increasing order by weight(u, v):

if FIND-SET(u) \neq FIND-SET(v):

$A = A \cup \{(u, v)\}$

UNION(u, v)

return A

* KRUSKAL (G):

1) $A = \emptyset$

2) For each vertex $x, v \in G$.

3) V : MAKE-SET (v)

4) For each edge $(u, v) \in G$

5) E ordered by increasing order by weight (u, v) :

6) IF FIND-SET (u) \neq FIND-SET (v):

7) $A = A \cup \{(u, v)\}$

8) UNION (u, v)

9) ~~return~~ (u, v)

~~return~~ A .

PROGRAM CODE:

```
#include<stdio.h>
#include<stdlib.h>
int i,j,k,a,b,u,v,n,ne=1;
int min,mincost=0,cost[9][9],parent[9];
int find(int);
int uni(int,int);
void main()
{
printf("\n\t Implementation of Kruskal's algorithm\n");
printf("\nEnter the no. of vertices:");
scanf("%d",&n);
printf("\nEnter the cost adjacency matrix:\n");
for(i=1;i<=n;i++)
{
for(j=1;j<=n;j++)
{
scanf("%d",& cost[i][j]);
if(cost[i][j]==0)
cost[i][j]=999;
}
}
printf("The edges of Minimum Cost Spanning Tree are\n");
while(ne < n)
{
for(i=1,min=999;i<=n;i++)
{
for(j=1;j <= n;j++)
{
if(cost[i][j] < min)
{
min=cost[i][j];
a=u=i;
b=v=j;
}
}
}
u=find(u);
v=find(v);
if(uni(u,v))
{
printf("%d edge (%d,%d) =%d\n",ne++,a,b,min);
mincost +=min;
}
```

```

    }
    cost[a][b]=cost[b][a]=999;
}
printf("\n\tMinimum cost = %d\n",mincost);

}
int find(int i)
{
    while(parent[i])
        i=parent[i];
    return i;
}
int uni(int i,int j)
{
    if(i!=j)
    {
        parent[j]=i;
        return 1;
    }
    return 0;
}

```

OUTPUT:

```

mayurim@mayurim-VirtualBox:~/Desktop/Dslab/Dslab/lab$ gcc -o kru kru.c
mayurim@mayurim-VirtualBox:~/Desktop/Dslab/Dslab/lab$ ./kru

    Implementation of Kruskal's algorithm

Enter the no. of vertices:6

Enter the cost adjacency matrix:
0 3 1 6 0 0
3 0 5 0 3 0
1 5 0 5 6 4
6 0 5 0 0 2
0 3 6 0 0 6
0 0 4 2 6 0
The edges of Minimum Cost Spanning Tree are
1 edge (1,3) =1
2 edge (4,6) =2
3 edge (1,2) =3
4 edge (2,5) =3
5 edge (3,6) =4

    Minimum cost = 13

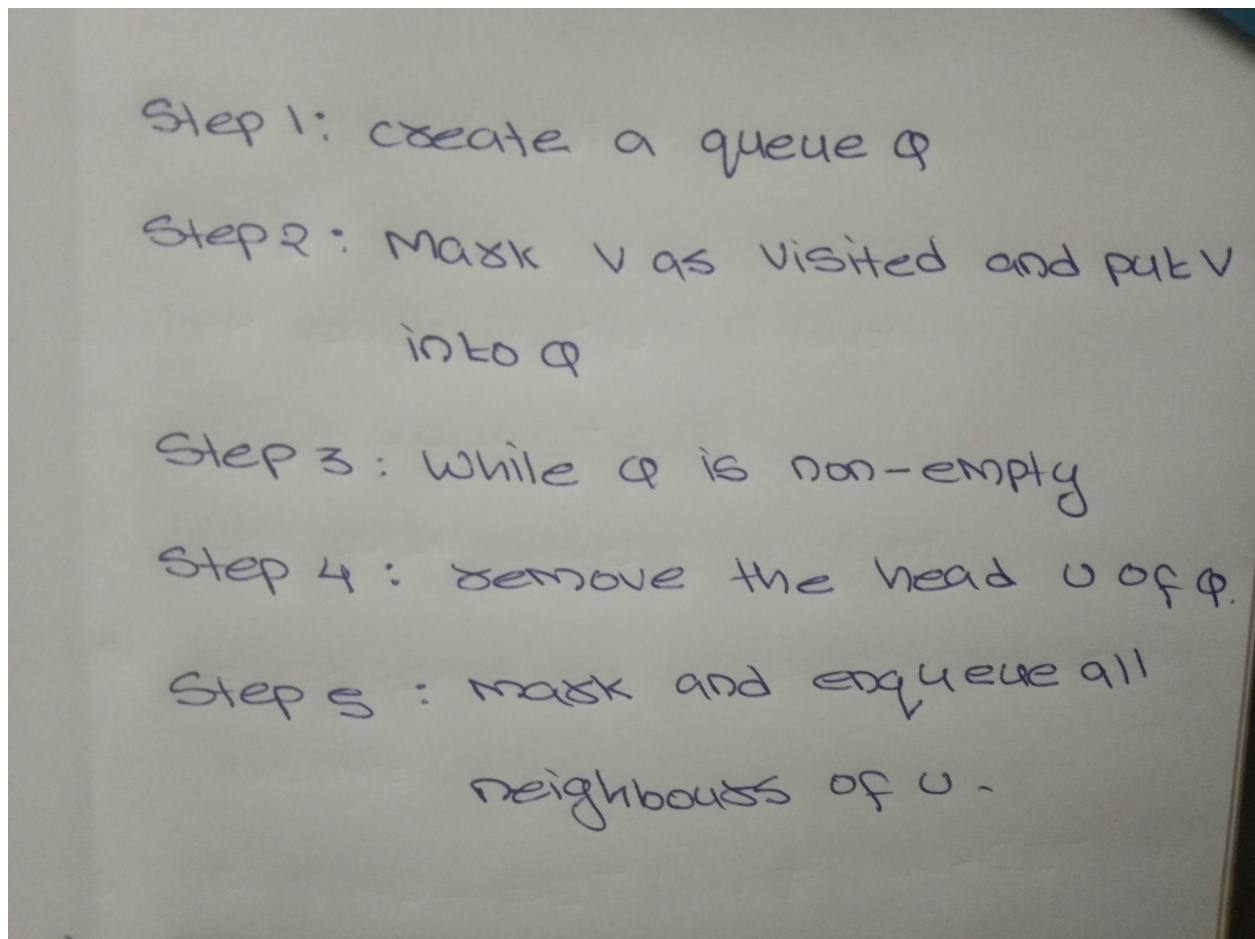
```

2.DEVELOP A PROGRAM TO IMPLEMENT DFS AND BFS

a)BFS

ALGORITHM

1. Create a queue Q
2. Mark v as visited and put v into Q
3. while Q is non-empty
4. remove the head u of Q
5. mark and enqueue all (unvisited) neighbours of u



PROGRAM CODE

```
#include<stdio.h>
int a[20][20], q[20], visited[20], n, i, j, f = 0, r = -1;
```



```

void bfs(int v)
{
    for(i = 1; i <= n; i++)
        if(a[v][i] && !visited[i])
            q[++r] = i;
    if(f <= r) {
        visited[q[f]] = 1;
        bfs(q[f++]);
    }
}

int main()
{
    int v;
    printf("\n Enter the number of vertices:");
    scanf("%d", &n);
    for(i=1; i <= n; i++)
    {
        q[i] = 0;
        visited[i] = 0;
    }
    printf("\n Enter graph data in matrix form:\n");
    for(i=1; i<=n; i++)
    {
        for(j=1;j<=n;j++)
        {
            scanf("%d", &a[i][j]);
        }
    }
    printf("\n Enter the starting vertex:");
    scanf("%d", &v);
    bfs(v);
    printf("\n The node which are reachable are:\n");
    for(i=1; i <= n; i++)
    {
        if(visited[i])
            printf("%d\t", i);
        else
        {
            printf("\n Bfs is not possible. Not all nodes are reachable");
            break;
        }
    }
}

```

OUTPUT:

```
mayurim@mayurim-VirtualBox:~/Desktop/Dslab/Dslab/lab$ ./bfs

Enter the number of vertices:3

Enter graph data in matrix form:
1 4 2
5 7 0
6 3 8

Enter the starting vertex:1

The node which are reachable are:
1      2      3      mayurim@mayurim-VirtualBox:~/Desktop/Dslab/Dslab/lab$
```

(b)DFS:

ALGORITHM

```
DFS(G, u) u.
visited = true
for each v  $\in$  G.Adj[u]
if v.visited == false
DFS(G,v)
init()
{
For each u  $\in$  G u.
visited = false For each u  $\in$  G
DFS(G, u) }
```

- 1) DFS(G, U) U.
- 2) visited = true
- 3) for each $v \in G$. Adj[U]
- 4) if v .visited == false
- 5) DFS(G, v)
- 6) init()
- 7) for each $U \in G$.
- 8) visited = false for each $U \in G$
- 9) DFS(G, U) }

PROGRAM CODE:

```
#include<stdio.h>
int a[20][20],reach[20],n;
int dfs(int v)
{
    int i;
    reach[v]=1;
    for (i=1;i<=n;i++)
        if(a[v][i] && !reach[i])
        {

printf("\n %d->%d",v,i);
        dfs(i);
        }
}
```

```

int main()
{
    int i,j,count=0;
    printf("\n Enter number of vertices:");
    scanf("%d",&n);
    for (i=1;i<=n;i++)
    {
        reach[i]=0;
        for (j=1;j<=n;j++)
            a[i][j]=0;
    }
    printf("\n Enter the adjacency matrix:\n");
    for (i=1;i<=n;i++)
        for (j=1;j<=n;j++)
            scanf("%d",&a[i][j]);
    dfs(1);
    printf("\n");
    for (i=1;i<=n;i++)
    {
        if(reach[i])
            count++;
    }
    if(count==n)
        printf("\n Graph is connected"); else
        printf("\n Graph is not connected");
    return 0;
}

```

OUTPUT:

```
Enter the number of vertices:3

Enter graph data in matrix form:
1 0 0
0 1 0
1 1 1

Enter the starting vertex:1

The node which are reachable are:
1
Bfs is not possible. Not all nodes are reachablemayurin@mayurin-VirtualBox:~/Desktop/Dslab/Dslab/lab$ ./bfs

Enter the number of vertices:4

Enter graph data in matrix form:
1 1 1 1
0 1 0 1
1 0 0 1
1 1 0 1

Enter the starting vertex:1

The node which are reachable are:
1      2      3      4      mayurin@mayurin-VirtualBox:~/Desktop/Dslab/Dslab/lab$
```

Activate Windows
Go to Settings to activate Windows