Title: "Quantified Self Movement Prediction Assignment"

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Background

Using devices such as JawboneUp, NikeFuelBand, and Fitbitit is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it.

In this assignment, the goal is to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants and develop a machine learning algorithm. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website: http://groupware.les.inf.puc-rio.br/har (see the section on the Weight Lifting Exercise Dataset).

Data and R packages

Load packages, set caching

```
## Loading required package: caret
## Warning: package 'caret' was built under R version 3.2.5
## Loading required package: lattice
## Loading required package: ggplot2
## Warning: package 'ggplot2' was built under R version 3.2.5
## Loading required package: corrplot
## Warning: package 'corrplot' was built under R version 3.2.5
## Loading required package: Rtsne
## Warning in library(package, lib.loc = lib.loc, character.only = TRUE,
## logical.return = TRUE, : there is no package called 'Rtsne'
## Loading required package: knitr
```

Getting Data

Set the variables for the URL of training and testing data

```
train.link <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
training.csv"
test.link <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
testing.csv"</pre>
```

Set the variables for the file names

```
train.fname <- "pml-training.csv"</pre>
test.fname <- "pml-testing.csv"</pre>
# if files does not exist, download the files
if (!file.exists(train.fname)) {
  download.file(train.link, destfile=train.fname, method="curl")
if (!file.exists(test.fname)) {
  download.file(test.link, destfile=test.fname, method="curl")
}
# load the CSV files as data.frame
train.data = read.csv("pml-training.csv")
test.data = read.csv("pml-testing.csv")
names(train.data)
     [1] "X"
##
                                     "user name"
##
     [3] "raw timestamp part 1"
                                     "raw_timestamp_part_2"
##
     [5] "cvtd_timestamp"
                                     "new window"
     [7] "num_window"
                                     "roll_belt"
##
     [9] "pitch belt"
##
                                     "yaw belt"
    [11] "total_accel_belt"
                                     "kurtosis_roll_belt"
    [13] "kurtosis_picth_belt"
##
                                     "kurtosis_yaw_belt"
##
    [15] "skewness roll belt"
                                     "skewness roll belt.1"
    [17] "skewness_yaw_belt"
##
                                     "max_roll_belt"
## [19] "max_picth_belt"
                                     "max_yaw_belt"
## [21] "min_roll_belt"
                                     "min_pitch_belt"
## [23] "min_yaw_belt"
                                     "amplitude_roll_belt"
## [25] "amplitude_pitch_belt"
                                     "amplitude_yaw_belt"
## [27] "var_total_accel_belt"
                                     "avg roll belt"
## [29] "stddev_roll_belt"
                                     "var_roll_belt"
## [31] "avg_pitch_belt"
                                     "stddev_pitch_belt"
## [33] "var_pitch_belt"
                                     "avg_yaw_belt"
    [35] "stddev_yaw_belt"
                                     "var_yaw_belt"
##
                                     "gyros_belt_y"
## [37] "gyros_belt_x"
## [39] "gyros_belt_z"
                                     "accel_belt_x"
## [41] "accel belt_y"
                                     "accel_belt_z"
## [43] "magnet_belt_x"
                                     "magnet_belt_y"
## [45] "magnet_belt_z"
                                     "roll arm"
## [47] "pitch_arm"
                                     "yaw_arm"
## [49] "total_accel_arm"
                                     "var_accel_arm"
## [51] "avg_roll_arm"
                                     "stddev_roll_arm"
## [53] "var_roll_arm"
                                     "avg pitch arm"
```

```
[55] "stddev pitch arm"
                                      "var pitch arm"
                                     "stddev_yaw_arm"
##
    [57] "avg_yaw_arm"
    [59] "var_yaw_arm"
##
                                     "gyros arm x"
    [61] "gyros_arm_y"
##
                                     "gyros_arm_z"
##
    [63] "accel arm x"
                                     "accel_arm_y"
##
    [65] "accel_arm_z"
                                     "magnet_arm_x"
    [67] "magnet_arm_y"
                                     "magnet_arm_z"
    [69] "kurtosis_roll_arm"
##
                                     "kurtosis_picth_arm"
    [71] "kurtosis_yaw_arm"
                                     "skewness_roll_arm"
##
    [73] "skewness_pitch_arm"
                                     "skewness_yaw_arm"
##
    [75] "max_roll_arm"
                                     "max picth arm"
    [77] "max_yaw_arm"
                                     "min_roll_arm"
##
##
    [79] "min_pitch_arm"
                                     "min_yaw_arm"
##
    [81] "amplitude_roll_arm"
                                     "amplitude_pitch_arm"
##
    [83] "amplitude yaw arm"
                                     "roll_dumbbell"
    [85] "pitch_dumbbell"
                                     "yaw_dumbbell"
##
    [87] "kurtosis_roll_dumbbell"
                                     "kurtosis_picth_dumbbell"
    [89] "kurtosis_yaw_dumbbell"
##
                                     "skewness roll dumbbell"
##
    [91] "skewness_pitch_dumbbell"
                                     "skewness_yaw_dumbbell"
    [93] "max_roll_dumbbell"
##
                                     "max_picth_dumbbell"
##
    [95] "max_yaw_dumbbell"
                                     "min_roll_dumbbell"
    [97] "min pitch dumbbell"
##
                                     "min_yaw_dumbbell"
    [99] "amplitude_roll_dumbbell"
                                     "amplitude_pitch_dumbbell"
## [101] "amplitude_yaw_dumbbell"
                                     "total accel dumbbell"
## [103] "var_accel_dumbbell"
                                     "avg_roll_dumbbell"
## [105] "stddev_roll_dumbbell"
                                     "var_roll_dumbbell"
## [107] "avg_pitch_dumbbell"
                                     "stddev_pitch_dumbbell"
## [109] "var_pitch_dumbbell"
                                     "avg_yaw_dumbbell"
## [111] "stddev_yaw_dumbbell"
                                     "var_yaw_dumbbell"
## [113] "gyros_dumbbell_x"
                                     "gyros_dumbbell_y"
## [115] "gyros_dumbbell_z"
                                     "accel_dumbbell_x"
## [117] "accel_dumbbell_y"
                                     "accel_dumbbell_z"
## [119] "magnet_dumbbell_x"
                                     "magnet dumbbell y"
## [121] "magnet_dumbbell_z"
                                     "roll forearm"
## [123] "pitch_forearm"
                                     "yaw_forearm"
## [125] "kurtosis roll forearm"
                                     "kurtosis_picth_forearm"
## [127] "kurtosis_yaw_forearm"
                                     "skewness_roll_forearm"
## [129] "skewness_pitch_forearm"
                                     "skewness_yaw_forearm"
## [131] "max_roll_forearm"
                                     "max_picth_forearm"
## [133] "max_yaw_forearm"
                                     "min_roll_forearm"
## [135] "min_pitch_forearm"
                                     "min_yaw_forearm"
## [137] "amplitude_roll_forearm"
                                     "amplitude_pitch_forearm"
## [139] "amplitude_yaw_forearm"
                                     "total_accel_forearm"
## [141] "var_accel_forearm"
                                     "avg_roll_forearm"
## [143] "stddev_roll_forearm"
                                     "var_roll_forearm"
## [145] "avg_pitch_forearm"
                                     "stddev_pitch_forearm"
## [147] "var_pitch_forearm"
                                     "avg_yaw_forearm"
## [149] "stddev_yaw_forearm"
                                     "var_yaw_forearm"
## [151] "gyros_forearm_x"
                                     "gyros_forearm_y"
## [153] "gyros_forearm_z"
                                     "accel_forearm_x"
```

Data Preparation

The assignment needs us to use data from accelerometers on the belt, forearm, arm, and dumbell, so the features are extracted based on these keywords along with the classe feature.

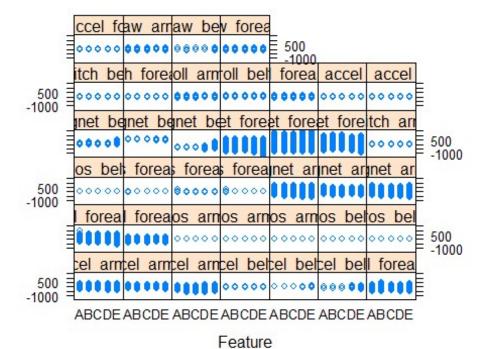
```
## [1] "A" "B" "C" "D" "E"

## [1] 1 1 1 1 1 1

## Levels: 1 2 3 4 5
```

Plot the relationship between features and outcome.

```
featurePlot(train, outcome.tmp, "strip")
```



From the above plot, we can see that each feature has relatively the same distribution among the 5 outcome levels (A, B, C, D, E).

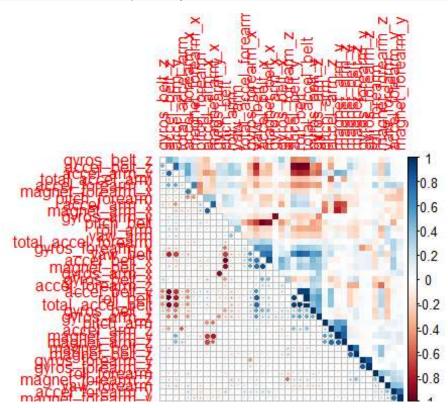
Check for features's variance

Based on the principal component analysis (PCA), it is necessary that features have maximum variance for maximum uniqueness, so that each feature is as distant as possible from other features.

```
# check for zero variance
zvar = nearZeroVar(train, saveMetrics=TRUE)
zvar
##
                        fregRatio percentUnique zeroVar
## roll belt
                         1.101904
                                      6.7781062
                                                   FALSE FALSE
## pitch belt
                                      9.3772296
                         1.036082
                                                   FALSE FALSE
## yaw belt
                                      9.9734991
                                                   FALSE FALSE
                         1.058480
## total accel belt
                         1.063160
                                      0.1477933
                                                   FALSE FALSE
## gyros belt x
                                      0.7134849
                                                   FALSE FALSE
                         1.058651
## gyros_belt_y
                         1.144000
                                      0.3516461
                                                   FALSE FALSE
## gyros_belt_z
                         1.066214
                                      0.8612782
                                                   FALSE FALSE
## accel belt x
                         1.055412
                                      0.8357966
                                                   FALSE FALSE
## accel_belt_y
                         1.113725
                                      0.7287738
                                                   FALSE FALSE
## accel belt z
                                                   FALSE FALSE
                         1.078767
                                      1.5237998
## magnet belt x
                                                   FALSE FALSE
                         1.090141
                                      1.6664968
## magnet belt y
                                                   FALSE FALSE
                         1.099688
                                      1.5187035
## magnet belt z
                                                   FALSE FALSE
                         1.006369
                                      2.3290184
## roll arm
                        52.338462
                                     13.5256345
                                                   FALSE FALSE
## pitch_arm
                        87.256410
                                     15.7323412
                                                   FALSE FALSE
## yaw arm
                        33.029126
                                     14.6570176
                                                   FALSE FALSE
## total accel arm
                         1.024526
                                      0.3363572
                                                   FALSE FALSE
## gyros arm x
                         1.015504
                                      3.2769341
                                                   FALSE FALSE
## gyros arm y
                                                   FALSE FALSE
                         1.454369
                                      1.9162165
## gyros arm z
                                      1.2638875
                                                   FALSE FALSE
                         1.110687
                                                   FALSE FALSE
## accel arm x
                         1.017341
                                      3.9598410
## accel arm y
                         1.140187
                                      2.7367241
                                                   FALSE FALSE
## accel arm z
                         1.128000
                                      4.0362858
                                                   FALSE FALSE
## magnet arm x
                         1.000000
                                      6.8239731
                                                   FALSE FALSE
## magnet_arm_y
                         1.056818
                                      4.4439914
                                                   FALSE FALSE
## magnet arm z
                         1.036364
                                      6.4468454
                                                   FALSE FALSE
## roll_forearm
                                                   FALSE FALSE
                        11.589286
                                     11.0895933
## pitch_forearm
                                                   FALSE FALSE
                        65.983051
                                     14.8557741
## yaw forearm
                        15.322835
                                     10.1467740
                                                   FALSE FALSE
## total accel forearm
                        1.128928
                                      0.3567424
                                                   FALSE FALSE
## gyros_forearm_x
                         1.059273
                                      1.5187035
                                                   FALSE FALSE
## gyros forearm y
                         1.036554
                                      3.7763735
                                                   FALSE FALSE
## gyros forearm z
                         1.122917
                                      1.5645704
                                                   FALSE FALSE
## accel forearm x
                                                   FALSE FALSE
                         1.126437
                                      4.0464784
## accel forearm v
                                                   FALSE FALSE
                         1.059406
                                      5.1116094
## accel forearm z
                         1.006250
                                      2.9558659
                                                   FALSE FALSE
## magnet forearm x
                                      7.7667924
                                                   FALSE FALSE
                         1.012346
## magnet forearm y
                                                   FALSE FALSE
                         1.246914
                                      9.5403119
## magnet_forearm_z
                         1.000000
                                      8.5771073
                                                   FALSE FALSE
```

It appears that there are no features without variability (all has enough variance). So there is no feature to be removed further.

Let's plot a correlation matrix between features.



A good set of features are visibile when they are highly uncorrelated with each other. The plot above shows average correlation which is not too high, so no further PCA preprocessing is needed.

Modeling

Ran into trouble using Random Forest as my laptop couldn't complete the train function. Switched to XGBOOST instead. It just ran fine in few minutes

```
require(xgboost)
## Loading required package: xgboost
```

```
## Warning: package 'xgboost' was built under R version 3.2.5
train.matrix = as.matrix(train)
mode(train.matrix) = "numeric"
test.matrix = as.matrix(test)
mode(test.matrix) = "numeric"
# convert outcome from factor to numeric matrix
   xgboost takes multi-labels in [0, numOfClass)
y = as.matrix(as.integer(outcome)-1)
param <- list("objective" = "multi:softprob", # multiclass classification</pre>
              "num_class" = num.class, # number of classes
              "eval_metric" = "merror",
                                         # evaluation metric
              "nthread" = 8, # number of threads to be used
              "max depth" = 16, # maximum depth of tree
              "eta" = 0.3,  # step size shrinkage
"gamma" = 0,  # minimum loss reduction
              "subsample" = 1,  # part of data instances to grow tree
              "colsample bytree" = 1, # subsample ratio of columns when
constructing each tree
              "min_child_weight" = 12 # minimum sum of instance weight
needed in a child
set.seed(1234)
system.time( bst.cv <- xgb.cv(param=param, data=train.matrix, label=y,</pre>
              nfold=4, nrounds=200, prediction=TRUE, verbose=FALSE) )
##
      user system elapsed
## 489.08 23.67 171.89
pred.cv = matrix(bst.cv$pred, nrow=length(bst.cv$pred)/num.class,
ncol=num.class)
pred.cv = max.col(pred.cv, "last")
min.merror.idx = which.min(bst.cv$dt[, test.merror.mean])
min.merror.idx
## [1] 187
# minimum merror
bst.cv$dt[min.merror.idx,]
      train.merror.mean train.merror.std test.merror.mean test.merror.std
##
## 1:
                                          0.005402
```

Model training

Fit the XGBoost gradient boosting model on all of the training data.

```
## user system elapsed
## 146.59 6.58 43.53
```

Predict test data using the trained model

```
pred <- predict(bst, test.matrix)
head(pred, 10)
## [1] 2.722199e-04 9.982042e-01 1.132105e-03 1.515472e-04 2.398420e-04
## [6] 9.991074e-01 6.353945e-04 2.402208e-04 3.893657e-06 1.299460e-05</pre>
```

Decoding prediction

```
pred = matrix(pred, nrow=num.class, ncol=length(pred)/num.class)
pred = t(pred)
pred = max.col(pred, "last")
pred.char = toupper(letters[pred])
```

confusion matrix

```
confusionMatrix(factor(y+1), factor(pred.cv))
## Confusion Matrix and Statistics
##
##
             Reference
                            3
                                      5
## Prediction
                 1
                      2
                                 4
            1 5566
                     10
                            2
                                 2
##
                                      0
                12 3772
                           12
##
            2
                                 0
                                      1
##
            3
                 0
                     24 3384
                                14
                                      0
##
            4
                 0
                      0
                           19 3194
                                      3
            5
##
                      1
                            1
                                 8 3597
##
## Overall Statistics
##
##
                  Accuracy : 0.9944
##
                    95% CI: (0.9933, 0.9954)
##
       No Information Rate: 0.2843
##
       P-Value [Acc > NIR] : < 2.2e-16
##
##
                     Kappa: 0.993
   Mcnemar's Test P-Value : NA
##
##
## Statistics by Class:
##
##
                        Class: 1 Class: 2 Class: 3 Class: 4 Class: 5
## Sensitivity
                           0.9978
                                    0.9908
                                             0.9901
                                                       0.9925
                                                                0.9989
## Specificity
                           0.9990
                                    0.9984
                                             0.9977
                                                       0.9987
                                                                0.9994
## Pos Pred Value
                           0.9975
                                    0.9934
                                             0.9889
                                                       0.9932
                                                                0.9972
## Neg Pred Value
                           0.9991
                                    0.9978
                                             0.9979
                                                       0.9985
                                                                0.9998
## Prevalence
                           0.2843
                                    0.1940
                                             0.1742
                                                       0.1640
                                                                0.1835
```

## Detection Rate	0.2837	0.1922	0.1725	0.1628	0.1833
## Detection Prevalence	0.2844	0.1935	0.1744	0.1639	0.1838
## Balanced Accuracy	0.9984	0.9946	0.9939	0.9956	0.9991

You can see the confusion matrix shows concentration of correct predictions as expected. Hence the average accuracy is 99.44%.

Estimation of the out-of-sample error rate

The testing subset data gives an unbiased estimate of the xgboost algorithm's prediction Accuracy (99.44% as calculated above). The out-of-sample error rate is derived by the formula 100% - Accuracy = 0.66%.

Hence the out-of-sample error rate is 0.66%.

Creating submission files

path <-"" pml_write_files <- function(x) { n <- length(x) for(i in 1: n) { filename <paste0("problem_id_", i, ".txt") write.table(x[i], file=file.path(path, filename), quote=FALSE,
row.names=FALSE, col.names=FALSE) } } pml_write_files(pred.char)</pre>