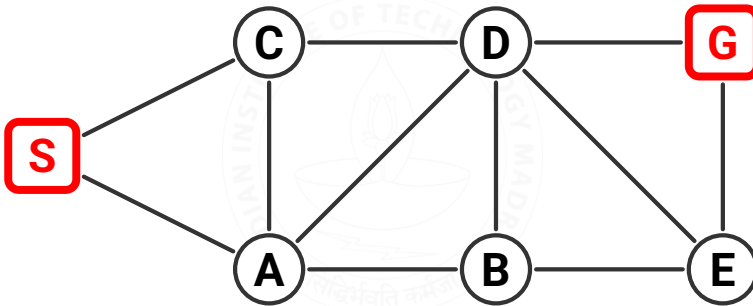


Practice Assignment: Example 1

Depth First Iterative Deepening (DFID-C)

Prepared by S. Baskaran

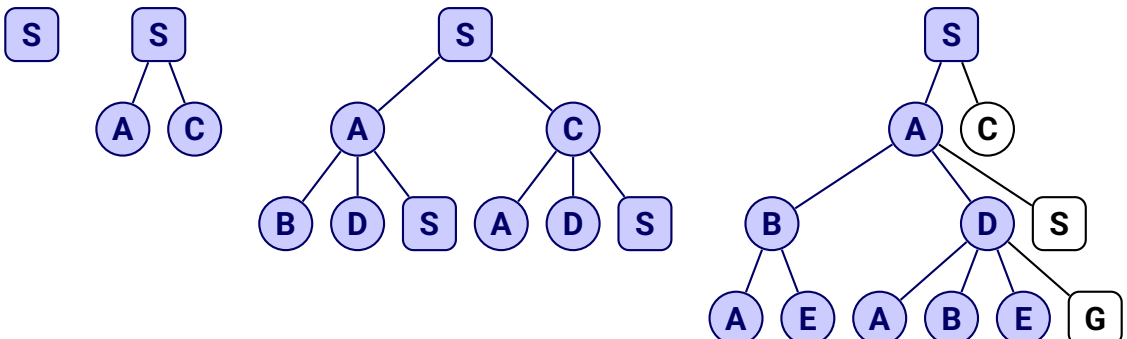
State Space



MoveGen returns nodes in ALPHABETICAL order.

S → A, C
A → B, C, D, S
B → A, D, E
C → A, D, S
D → A, B, C, E, G
E → B, D, G
G → D, E

DFID-C Search Trees (d=0,1,2,3)



DFID-C Solution

The solution provided below is based on the DFID-C algorithm published in the Week 2 Notes.

OPEN and CLOSED carry triples: (NODE,PARENT,DEPTH)

[DEPTH BOUND = 0]

OPEN (S,null,0):[]
CLOSED []

1.
NODE S
close (S,null,0)

OPEN []
CLOSED (S,null,0):[]

[DEPTH BOUND = 1]

OPEN (S,null,0):[]
CLOSED []

1.
NODE S
close (S,null,0)
moveGen A:C:[]
newNodes A:C:[]
newPairs (A,S,1):(C,S,1):[]

OPEN (A,S,1):(C,S,1):[]
CLOSED (S,null,0):[]

2.
NODE A
close (A,S,1)

OPEN (C,S,1):[]
CLOSED (A,S,1):(S,null,0):[]

3.
NODE C
close (C,S,1)

OPEN []
CLOSED (C,S,1):(A,S,1):(S,null,0):[]

[DEPTH BOUND = 2]

OPEN (S,null,0):[]
CLOSED []

1.
NODE S
close (S,null,0)
moveGen A:C:[]
newNodes A:C:[]
newPairs (A,S,1):(C,S,1):[]

OPEN (A,S,1):(C,S,1):[]
CLOSED (S,null,0):[]

2.
NODE A
close (A,S,1)
moveGen B:C:D:S:[]
newNodes B:D:S:[]
newPairs (B,A,2):(D,A,2):(S,A,2):[]

OPEN (B,A,2):(D,A,2):(S,A,2):(C,S,1):[]
CLOSED (A,S,1):(S,null,0):[]

3.
NODE B
close (B,A,2)

OPEN (D,A,2):(S,A,2):(C,S,1):[]
CLOSED (B,A,2):(A,S,1):(S,null,0):[]

4.
NODE D
close (D,A,2)

OPEN (S,A,2):(C,S,1):[]
CLOSED (D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

5.
NODE S
close (S,A,2)

OPEN (C,S,1):[]
CLOSED (S,A,2):(D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

6.
NODE C
close (C,S,1)
moveGen A:D:S:[]
newNodes A:D:S:[]
newPairs (A,C,2):(D,C,2):(S,C,2):[]

OPEN (A,C,2):(D,C,2):(S,C,2):[]
CLOSED (C,S,1):(S,A,2):(D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

7.
NODE A
close (A,C,2)

OPEN (D,C,2):(S,C,2):[]
CLOSED (A,C,2):(C,S,1):(S,A,2):(D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

8.
NODE D
close (D,C,2)

OPEN (S,C,2):[]
CLOSED (D,C,2):(A,C,2):(C,S,1):(S,A,2):(D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

9.
NODE S
close (S,C,2)

OPEN []
CLOSED (S,C,2):(D,C,2):(A,C,2):(C,S,1):(S,A,2):(D,A,2):(B,A,2):(A,S,1):(S,null,0):[]

[DEPTH BOUND = 3]

OPEN (S,null,0):[]
CLOSED []

1.
NODE S
close (S,null,0)
moveGen A:C:[]
newNodes A:C:[]
newPairs (A,S,1):(C,S,1):[]

OPEN (A,S,1):(C,S,1):[]
CLOSED (S,null,0):[]

2.
NODE A
close (A,S,1)
moveGen B:C:D:S:[]
newNodes B:D:S:[]
newPairs (B,A,2):(D,A,2):(S,A,2):[]

OPEN (B,A,2):(D,A,2):(S,A,2):(C,S,1):[]
CLOSED (A,S,1):(S,null,0):[]

3.
NODE B
close (B,A,2)
moveGen A:D:E:[]
newNodes A:E:[]
newPairs (A,B,3):(E,B,3):[]

OPEN (A,B,3):(E,B,3):(D,A,2):(S,A,2):(C,S,1):[]
CLOSED (B,A,2):(A,S,1):(S,null,0):[]

4.
NODE A
close (A,B,3)

OPEN (E,B,3):(D,A,2):(S,A,2):(C,S,1):[]
CLOSED (A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

5.
NODE E
close (E,B,3)

OPEN (D,A,2):(S,A,2):(C,S,1):[]
CLOSED (E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

6.
NODE D
close (D,A,2)
moveGen A:B:C:E:G:[]
newNodes A:B:E:G:[]
newPairs (A,D,3):(B,D,3):(E,D,3):(G,D,3):[]

OPEN (A,D,3):(B,D,3):(E,D,3):(G,D,3):(S,A,2):(C,S,1):[]
CLOSED (D,A,2):(E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

7.
NODE A
close (A,D,3)

OPEN (B,D,3):(E,D,3):(G,D,3):(S,A,2):(C,S,1):[]
CLOSED (A,D,3):(D,A,2):(E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

8.
NODE B
close (B,D,3)

OPEN (E,D,3):(G,D,3):(S,A,2):(C,S,1):[]
CLOSED (B,D,3):(A,D,3):(D,A,2):(E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

9.
NODE E
close (E,D,3)

OPEN (G,D,3):(S,A,2):(C,S,1):[]
CLOSED (E,D,3):(B,D,3):(A,D,3):(D,A,2):(E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

10.
NODE G
GOAL G

OPEN (G,D,3):(S,A,2):(C,S,1):[]
CLOSED (E,D,3):(B,D,3):(A,D,3):(D,A,2):(E,B,3):(A,B,3):(B,A,2):(A,S,1):(S,null,0):[]

PATH S:A:D:G:[]