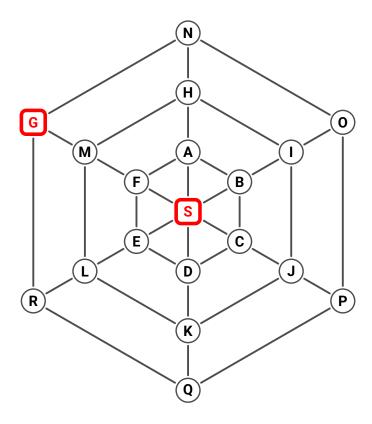
Problem 7 Breadth First Search

Prepared by S. Baskaran

State Space



MoveGen returns nodes in ALPHABETICAL order.

S -> A,B,C,D,E,F

 $A \rightarrow B, F, H, S$

B -> A,C,I,S

C -> B, D, J, S

D -> C,E,K,S

E -> D,F,L,S

F -> A,E,M,S

 $H \rightarrow A, I, M, N$

I -> B,H,J,O

 $J \rightarrow C, I, K, P$

 $K \rightarrow D, J, L, Q$

 $L \rightarrow E, K, M, R$

M -> F,G,H,L

N -> G,H,O

 $0 \rightarrow I, N, P$

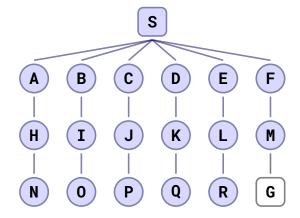
 $P \rightarrow J,0,Q$

Q -> K,P,R

 $R \rightarrow G, L, Q$

 $G \rightarrow M, N, R$

Breadth First Search - Search Tree



Breadth First Search – Solution OPEN and CLOSED carry pairs: (NODE, PARENT) (S, null):[] OPEN **CLOSED** [] 1. S NODE (S, null)close A:B:C:D:E:F:[] moveGen newNodes A:B:C:D:E:F:[] newPairs (A,S):(B,S):(C,S):(D,S):(E,S): (F,S):[] OPEN (A,S):(B,S):(C,S):(D,S):(E,S): (F,S):[] (S, null):[] CLOSED 2. NODE Α (A,S)close B:F:H:S:[] moveGen H:[] newNodes (H,A):[]newPairs (B,S):(C,S):(D,S):(E,S):(F,S): **OPEN** (H, A):[] **CLOSED** (A,S):(S,null):[] 3. NODE В (B,S)close A:C:I:S:[] moveGen newNodes I:[] (I,B):[] newPairs **OPEN** (C,S):(D,S):(E,S):(F,S):(H,A): (I,B):[] **CLOSED** (B,S):(A,S):(S,null):[] 4. NODE С (C,S)close moveGen B:D:J:S:[] J:[] newNodes newPairs (J,C):[] OPEN (D,S):(E,S):(F,S):(H,A):(I,B): (J,C):[] CLOSED (C,S):(B,S):(A,S):(S,null):[] D NODE (D,S)close moveGen C:E:K:S:[] newNodes K:[] (K,D):[] newPairs **OPEN** (E,S):(F,S):(H,A):(I,B):(J,C): (K,D):[] (D,S):(C,S):(B,S):(A,S):(S,null):[] **CLOSED** 6. NODE Ε close (E,S)D:F:L:S:[] moveGen L:[] newNodes (L,E):[] newPairs **OPEN** (F,S):(H,A):(I,B):(J,C):(K,D): (L,E):[] (E,S):(D,S):(C,S):(B,S):(A,S): **CLOSED** (S, null):[] 7. NODE F (F,S) close A:E:M:S:[] moveGen newNodes M:[](M,F):[]newPairs (H,A):(I,B):(J,C):(K,D):(L,E): OPEN (M,F):[](F,S):(E,S):(D,S):(C,S):(B,S): **CLOSED** (A,S):(S,null):[] 8. NODE Н (H, A) close A:I:M:N:[] moveGen N:[] newNodes newPairs (N, H) : []**OPEN** (I,B):(J,C):(K,D):(L,E):(M,F): (H, A):(F, S):(E, S):(D, S):(C, S): **CLOSED** (B,S):(A,S):(S,null):[] 9. NODE Ι (I,B)close B:H:J:0:[] moveGen 0:[] newNodes (0,I):[] newPairs (J,C):(K,D):(L,E):(M,F):(N,H): OPEN (0,I):[] (I,B):(H,A):(F,S):(E,S):(D,S): CLOSED (C,S):(B,S):(A,S):(S,null):[] 10. NODE J close (J,C)C:I:K:P:[] moveGen P:[] newNodes newPairs (P,J):[] **OPEN** (K,D):(L,E):(M,F):(N,H):(O,I): (P,J):[] (J,C):(I,B):(H,A):(F,S):(E,S): **CLOSED** (D,S):(C,S):(B,S):(A,S):(S,null):[] 11. NODE K close (K, D) D:J:L:Q:[] moveGen newNodes Q:[] (Q, K) : []newPairs **OPEN** (L,E):(M,F):(N,H):(O,I):(P,J): (Q, K) : []CLOSED (K,D):(J,C):(I,B):(H,A):(F,S): (E,S):(D,S):(C,S):(B,S):(A,S): (S, null):[] 12. L NODE (L,E)close E:K:M:R:[] moveGen R:[] newNodes newPairs (R,L):[] (M,F):(N,H):(O,I):(P,J):(Q,K):**OPEN** (R,L):[] CLOSED (L,E):(K,D):(J,C):(I,B):(H,A): (F,S):(E,S):(D,S):(C,S):(B,S): (A,S):(S,null):[] 13. NODE М close (M,F)F:G:H:L:[] moveGen newNodes G:[] (G, M) : []newPairs (N,H):(0,I):(P,J):(Q,K):(R,L):**OPEN** (G, M):[] (M,F):(L,E):(K,D):(J,C):(I,B): CLOSED (H,A):(F,S):(E,S):(D,S):(C,S): (B,S):(A,S):(S,null):[] 14. NODE N (N,H)close G:H:0:[] moveGen newNodes [][] newPairs **OPEN** (O, I):(P, J):(Q, K):(R, L):(G, M):[] **CLOSED** (N,H):(M,F):(L,E):(K,D):(J,C): (I,B):(H,A):(F,S):(E,S):(D,S): (C,S):(B,S):(A,S):(S,null):[] 15. NODE 0 close (0,I)I:N:P:[] moveGen newNodes [] [] newPairs OPEN (P,J):(Q,K):(R,L):(G,M):[] (O, I):(N, H):(M, F):(L, E):(K, D): CLOSED (J,C):(I,B):(H,A):(F,S):(E,S): (D,S):(C,S):(B,S):(A,S):(S,null):[] 16. P NODE (P,J)close moveGen J:0:Q:[] [] newNodes newPairs [] **OPEN** (Q,K):(R,L):(G,M):[] **CLOSED** (P,J):(0,I):(N,H):(M,F):(L,E): (K,D):(J,C):(I,B):(H,A):(F,S): (E,S):(D,S):(C,S):(B,S):(A,S): (S, null):[] 17. NODE Q close (Q,K)moveGen K:P:R:[] newNodes newPairs [] (R,L):(G,M):[] **OPEN** (Q,K):(P,J):(O,I):(N,H):(M,F):CLOSED (L,E):(K,D):(J,C):(I,B):(H,A): (F,S):(E,S):(D,S):(C,S):(B,S): (A,S):(S,null):[] 18. NODE R (R,L)close G:L:Q:[] moveGen [] newNodes [] newPairs (G, M) : []OPEN CLOSED (R,L):(Q,K):(P,J):(0,I):(N,H): (M,F):(L,E):(K,D):(J,C):(I,B): (H, A):(F, S):(E, S):(D, S):(C, S): (B,S):(A,S):(S,null):[] 19. NODE G GOAL G (G, M) : []OPEN CLOSED (R,L):(Q,K):(P,J):(O,I):(N,H):(M,F):(L,E):(K,D):(J,C):(I,B): (H, A):(F, S):(E, S):(D, S):(C, S): (B,S):(A,S):(S,null):[] S:F:M:G:[] PATH