

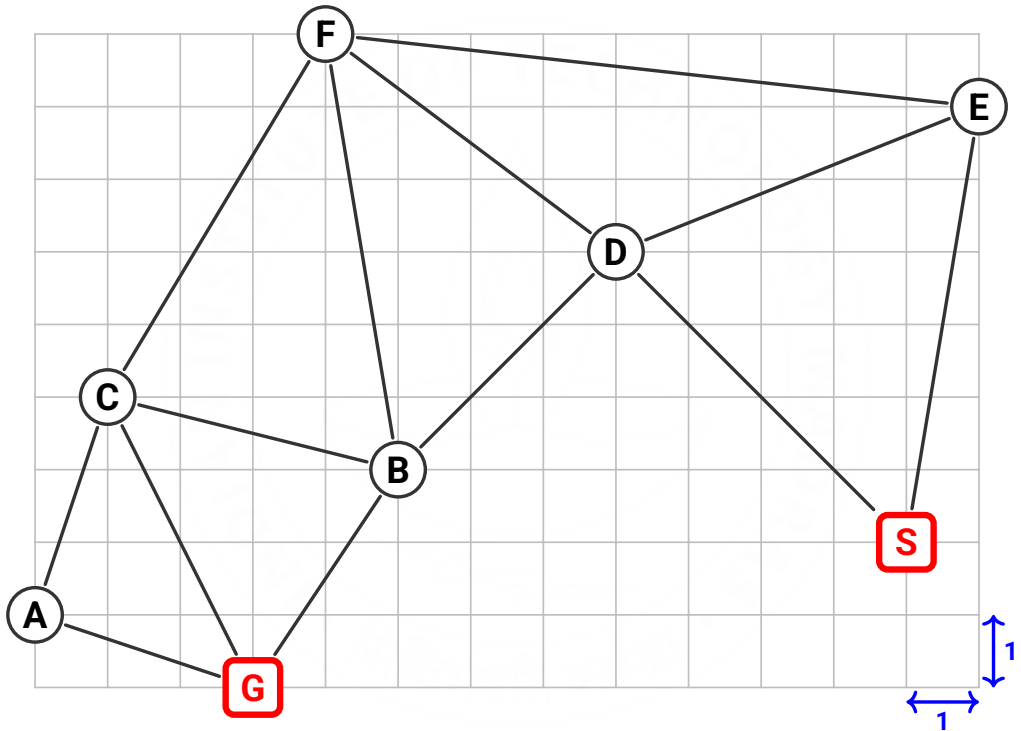
Practice Assignment: City Map Example 2

Breadth First Search

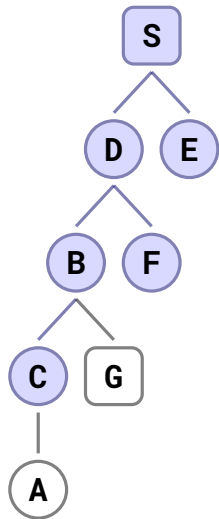
Prepared by S. Baskaran

State Space

MoveGen returns nodes in ALPHABETICAL ORDER.



Search Tree



Solution

OPEN and CLOSED carry pairs: (NODE,PARENT)

OPEN (S,null):[]
CLOSED []

1.
NODE S
close (S,null)
moveGen D:E:[]
newNodes D:E:[]
newPairs (D,S):(E,S):[]

OPEN (D,S):(E,S):[]

CLOSED (S,null):[]

2.
NODE D
close (D,S)
moveGen B:E:F:S:[]
newNodes B:F:[]
newPairs (B,D):(F,D):[]

OPEN (E,S):(B,D):(F,D):[]

CLOSED (D,S):(S,null):[]

3.
NODE E
close (E,S)
moveGen D:F:S:[]
newNodes []
newPairs []

OPEN (B,D):(F,D):[]

CLOSED (E,S):(D,S):(S,null):[]

4.
NODE B
close (B,D)
moveGen C:D:F:G:[]
newNodes C:G:[]
newPairs (C,B):(G,B):[]

OPEN (F,D):(C,B):(G,B):[]

CLOSED (B,D):(E,S):(D,S):(S,null):[]

5.
NODE F
close (F,D)
moveGen B:C:D:E:[]
newNodes []
newPairs []

OPEN (C,B):(G,B):[]

CLOSED (F,D):(B,D):(E,S):(D,S):(S,null):[]

6.
NODE C
close (C,B)
moveGen A:B:F:G:[]
newNodes A:[]
newPairs (A,C):[]

OPEN (G,B):(A,C):[]

CLOSED (C,B):(F,D):(B,D):(E,S):(D,S):(S,null):[]

7.
NODE G
GOAL G

OPEN (G,B):(A,C):[]

CLOSED (C,B):(F,D):(B,D):(E,S):(D,S):(S,null):[]

PATH S:D:B:G:[]