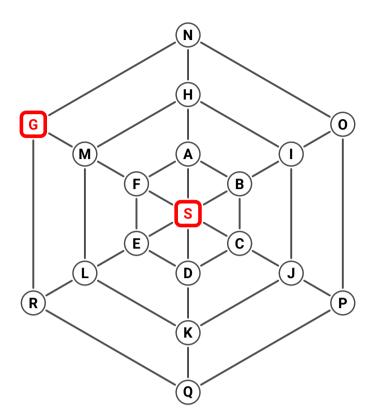
Problem 7 Depth First Search

Prepared by S. Baskaran

State Space



MoveGen returns nodes in ALPHABETICAL order.

S -> A,B,C,D,E,F

A -> B,F,H,S

B -> A,C,I,S

C -> B,D,J,S

D -> C,E,K,S

E -> D,F,L,S

F -> A, E, M, S

H -> A, I, M, N

I -> B,H,J,O

J -> C,I,K,P

K -> D,J,L,Q

L -> E,K,M,R

M -> F,G,H,L

N -> G,H,O

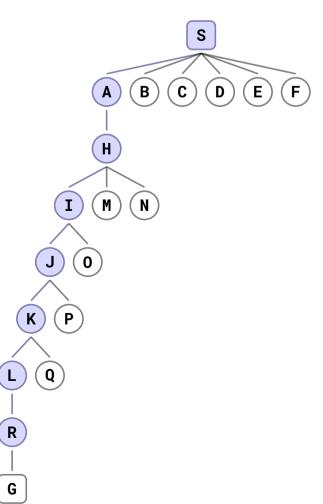
0 -> I,N,P

P -> J,0,Q Q -> K,P,R

R -> G, L, Q

 $G \rightarrow M, N, R$

Depth First Search – Search Tree



Depth First Search – Solution

```
OPEN and CLOSED carry pairs: (NODE,PARENT)
            (S, null):[]
OPEN
CLOSED
            []
1.
            S
NODE
            (S, null)
close
moveGen
            A:B:C:D:E:F:[]
newNodes
            A:B:C:D:E:F:[]
newPairs
            (A,S):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
OPEN
            (A,S):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
            (S, null):[]
CLOSED
2.
NODE
            Α
            (A,S)
close
moveGen
            B:F:H:S:[]
newNodes
            H:[]
            (H,A):[]
newPairs
            (H, A):(B, S):(C, S):(D, S):(E, S):
OPEN
            (F,S):[]
            (A,S):(S,null):[]
CLOSED
3.
NODE
            Н
            (H,A)
close
            A:I:M:N:[]
moveGen
newNodes
            I:M:N:[]
newPairs
            (I,H):(M,H):(N,H):[]
            (I,H):(M,H):(N,H):(B,S):(C,S):
OPEN
            (D,S):(E,S):(F,S):[]
            (H,A):(A,S):(S,null):[]
CLOSED
4.
NODE
            Ι
close
            (I,H)
            B:H:J:0:[]
moveGen
newNodes
            J:0:[]
newPairs
            (J,I):(0,I):[]
OPEN
            (J,I):(0,I):(M,H):(N,H):(B,S):
            (C,S):(D,S):(E,S):(F,S):[]
CLOSED
            (I,H):(H,A):(A,S):(S,null):[]
            J
NODE
            (J,I)
close
moveGen
            C:I:K:P:[]
            K:P:[]
newNodes
newPairs
            (K,J):(P,J):[]
OPEN
            (K,J):(P,J):(0,I):(M,H):(N,H):
            (B,S):(C,S):(D,S):(E,S):(F,S):[]
            (J,I):(I,H):(H,A):(A,S):(S,null):[]
CLOSED
6.
            Κ
NODE
            (K,J)
close
moveGen
            D:J:L:Q:[]
            L:Q:[]
newNodes
            (L,K):(Q,K):[]
newPairs
            (L,K):(Q,K):(P,J):(0,I):(M,H):
OPEN
            (N,H):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
            (K,J):(J,I):(I,H):(H,A):(A,S):
CLOSED
            (S, null):[]
7.
NODE
            L
            (L,K)
close
moveGen
            E:K:M:R:[]
            R:[]
newNodes
            (R,L):[]
newPairs
OPEN
            (R,L):(Q,K):(P,J):(0,I):(M,H):
            (N,H):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
            (L,K):(K,J):(J,I):(I,H):(H,A):
CLOSED
            (A,S):(S,null):[]
8.
NODE
            R
            (R, L)
close
            G:L:Q:[]
moveGen
            G:[]
newNodes
            (G,R):[]
newPairs
            (G,R):(Q,K):(P,J):(0,I):(M,H):
OPEN
            (N,H):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
            (R,L):(L,K):(K,J):(J,I):(I,H):
CLOSED
            (H,A):(A,S):(S,null):[]
9.
NODE
            G
GOAL
            G
            (G,R):(Q,K):(P,J):(O,I):(M,H):
OPEN
            (N,H):(B,S):(C,S):(D,S):(E,S):
            (F,S):[]
            (R,L):(L,K):(K,J):(J,I):(I,H):
CLOSED
            (H, A):(A, S):(S, null):[]
PATH
            S:A:H:I:J:K:L:R:G:[]
```