



COMPONENT DESING
FOOTBALL LAUNCHER



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1.0 Introduction

The purpose of this report is to present the comprehensive design and analysis of a ball launcher driven by a single motor. The ball launcher is equipped with two wheels rotating in opposite directions to propel the ball forward. The design incorporates a speed conversion box utilizing spur gears to achieve the desired rotation speed for both launcher wheels. Additionally, an alternative design using V-Belts for speed conversion is explored. The report aims to provide detailed insights into the product design, motor selection, speed conversion box design, and alternative belt-driven system.

1.1 Problem Statement

The problem statement revolves around developing a product design specification for this ball launcher, focusing on selecting the most appropriate motor available in the market and designing a speed conversion box using spur gear. The critical challenge is to achieve an optimal balance between the motor's performance and the launcher mechanism's efficiency, ensuring smooth and effective operation.

2.0 Product Design Specification

2.1 Introduction:

The product design specification for the ball launcher project is a comprehensive document outlining the key parameters and criteria for the development of an efficient and reliable ball launcher system. This specification serves as a roadmap for the design and engineering teams, providing a clear understanding of project goals and constraints.

2.2 Purpose

The primary purpose of the ball launcher is to propel a standard-sized ball with precision and consistency. The design should accommodate a single motor that drives two launcher wheels in

opposite directions, ensuring a synchronized and effective launch mechanism. The ball launcher targets applications in recreational settings, training scenarios, or automated retrieval systems.

2.3 Functional Requirements

- Propel a standard-sized ball with sufficient force for desired distances.
- Ensure synchronized rotation of the left and right launcher wheels.
- Accommodate a single motor for driving both launcher wheels.
- Feature a user-friendly interface for operation.
- Provide a consistent and accurate launch trajectory.

2.4 Materials and Components

Gears: Constructed from AISI 4320 steel (HB 293) for durability and wear resistance.

Shaft Material: Martensitic 410 CW with a safety factor to withstand bending and torsional stresses.

Bearings: Selected based on thrust load considerations and detailed specifications.

Motor: Selected motor must provide required torque and speed for the application.

2.5 Design the speed conversion box using spur gear

The speed conversion box uses spur gear. Due to the possibility that the center point of the ball does not coincide with the mid-point of the opening of the launcher, 50% of the torque of the wheel will be assumed to contribute as thrust load to the shaft. The bearing E and G shown in Figure 1 will withstand the thrust load to be transferred to the speed conversion box.

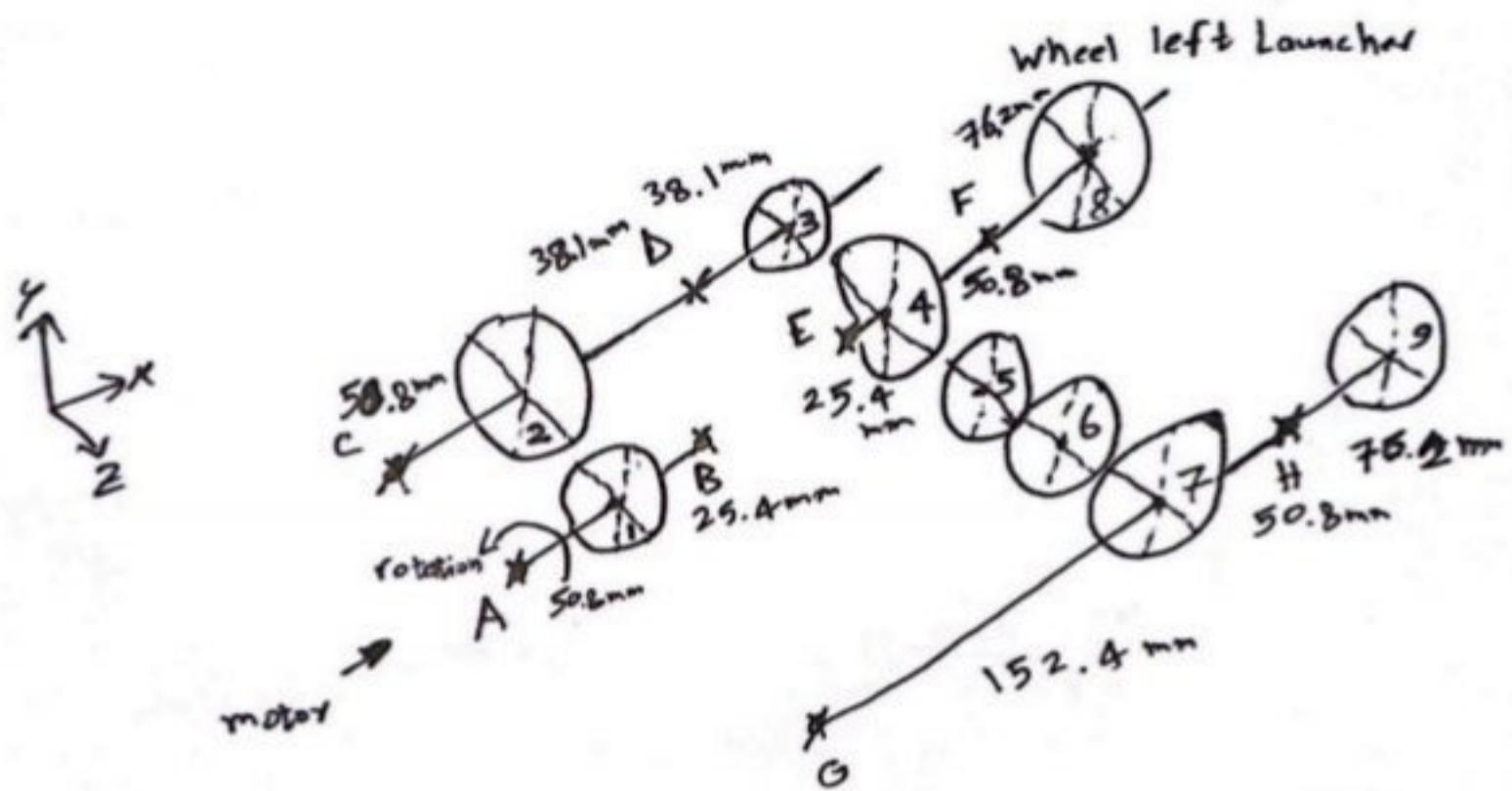


Figure 1: Design of speed conversion using spur gear

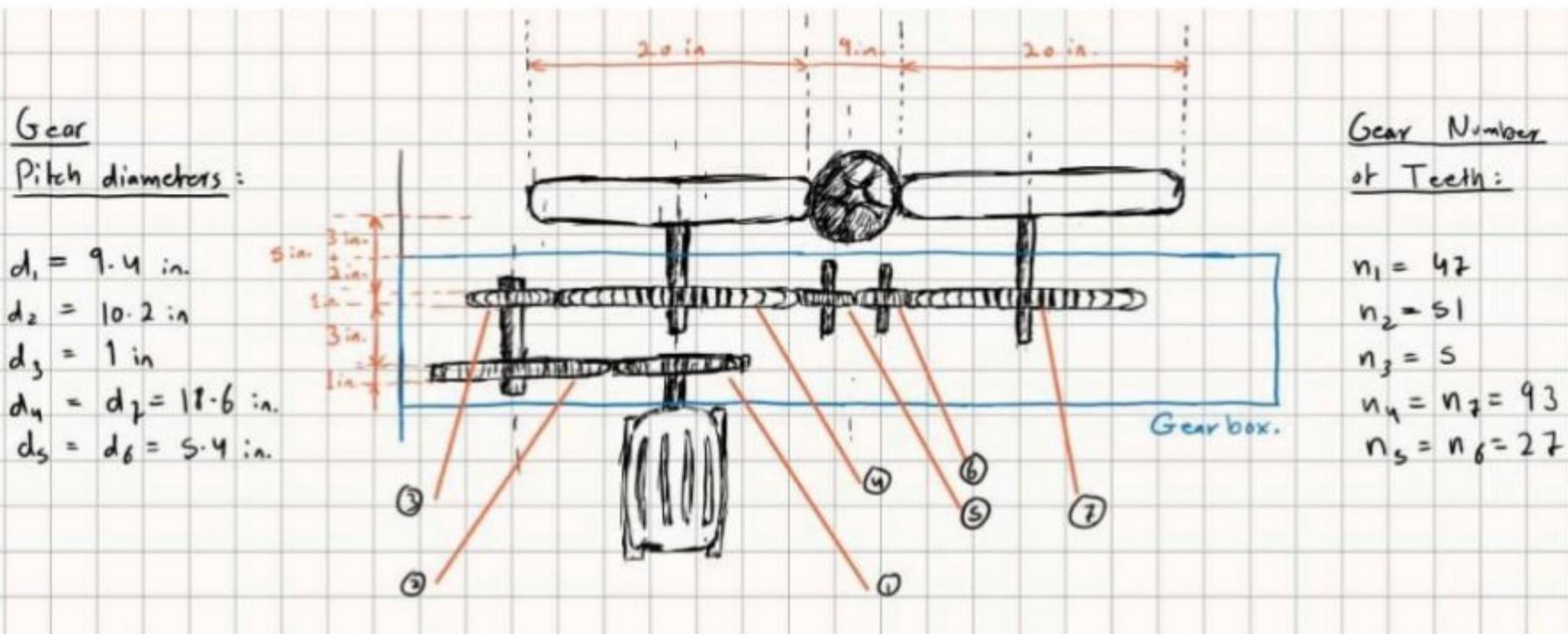


Figure 2: Schematic diagram of the overall gearing system .

2.7 Alternative design with belt

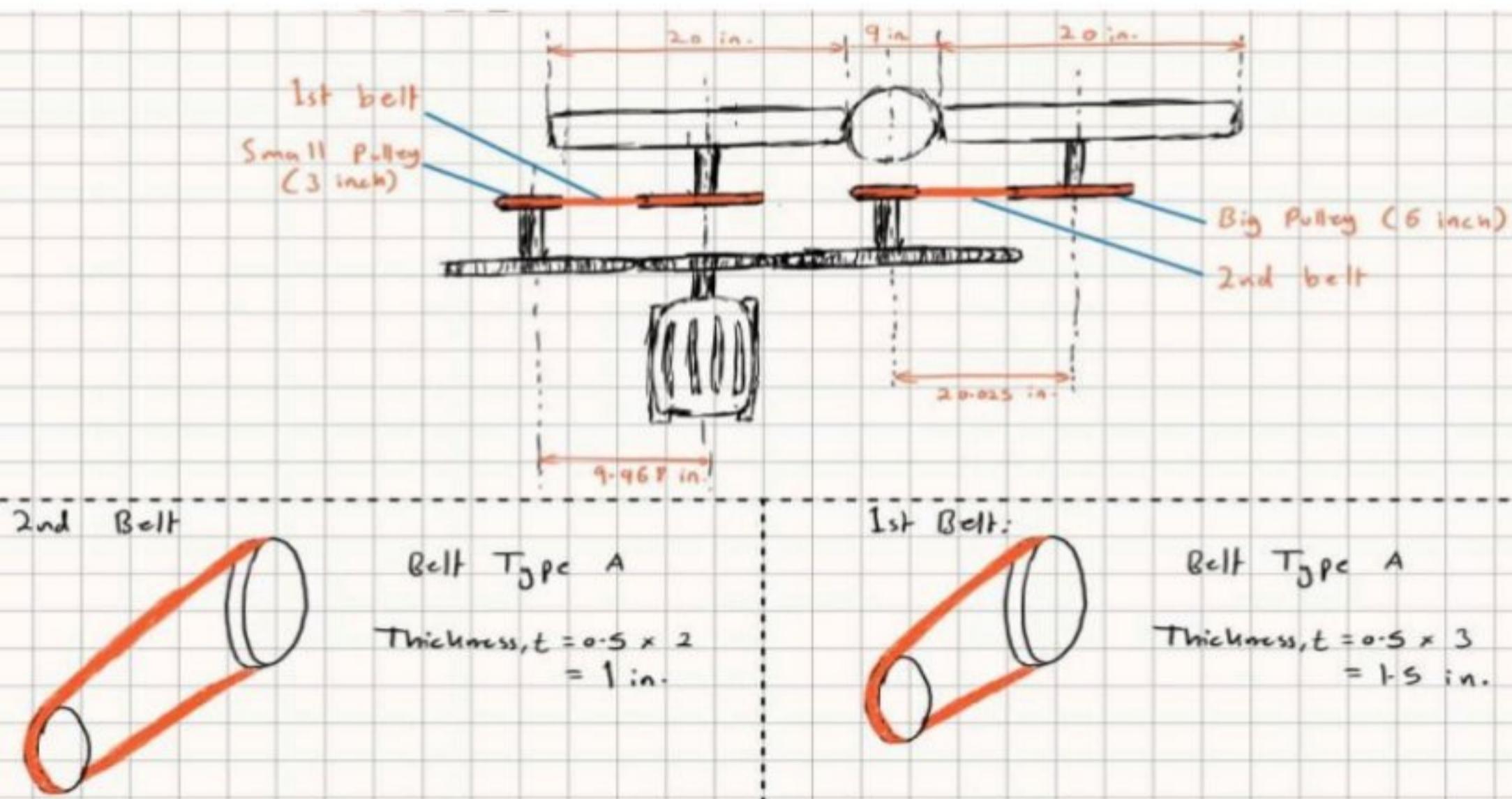


Figure 3: Design of speed conversion using belt

3.0 Results

3.1 Overall speed conversion box (schematic drawing)

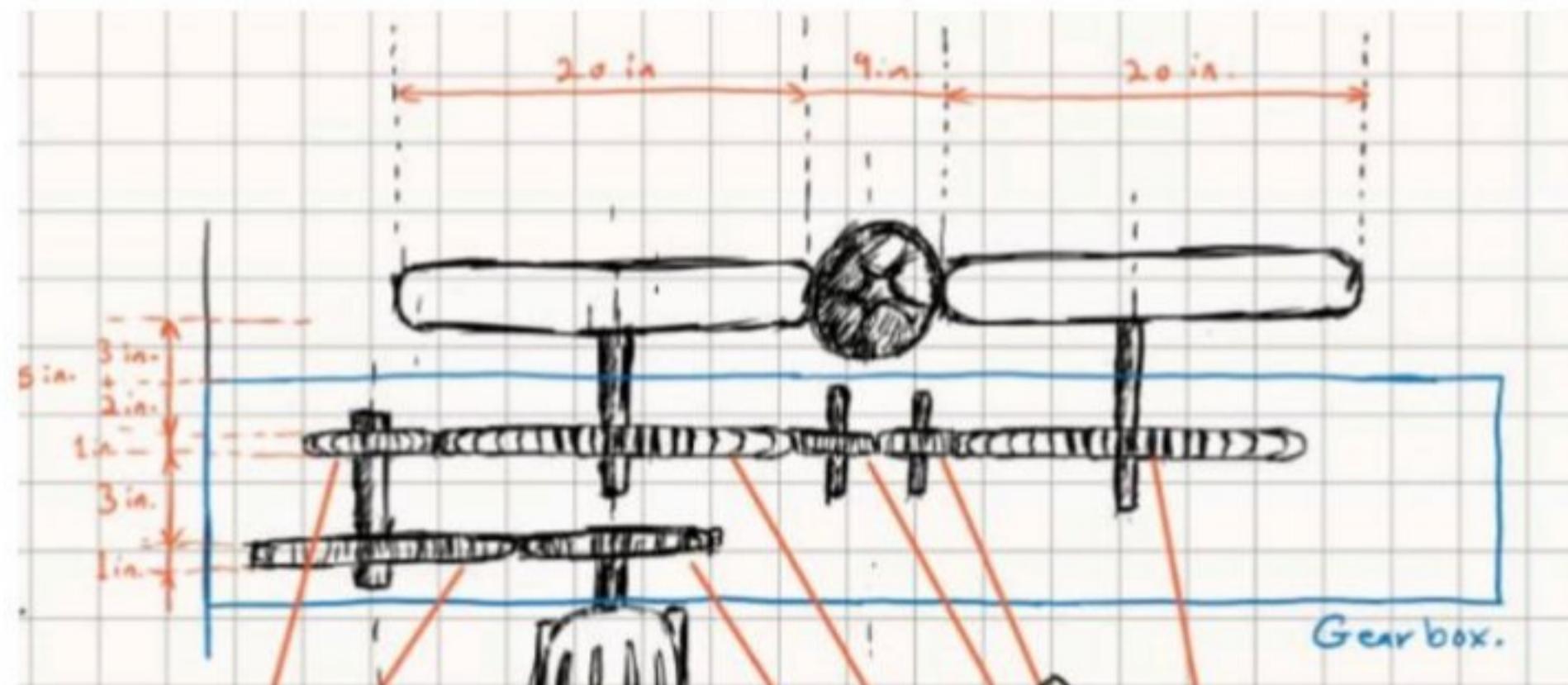


Figure 4: Overall Speed Conversion Box (schematic drawing)



Figure 5: Overall Speed Conversion Box (**solidworks**)

3.2 Gear: State the final module for the gear box, discuss characteristics of the module from input to output, etc

In our gear system for the ball launcher, we have incorporated seven gears to create an effective reduction system, ensuring synchronized and controlled rotation of the launcher wheels. The gear module has been meticulously designed, considering the material properties, gear specifications, and the critical role of idler gears. The reduction system is designed to handle varying rotational speeds, ensuring optimal performance.

The gear system is defined by the following rotational speeds:

Input Speed (n_1): 2990 rpm (from the motor)

Intermediate Speeds (n_2, n_3): 2726 rpm

Intermediate Speeds (n_4, n_7, n_8, n_9): 1450 rpm (gear 9 and 8 are the wheels)

Material Selection:

Gear material: AISI 4320 steel.

Hardness: HB 293.

These material properties ensure durability and strength under varying loads and rotational speeds.

Gear Specifications:

Gear 1: 47 teeth

Gear 2: 50 teeth

Gear 3: 6 teeth

Gear 4: 93 teeth

Gear 5: 27 teeth (idler)

Gear 6: 27 teeth (idler)

Gear 7: 93 teeth

Pitch and Diameter:

Diametral pitch (P): 5

Gear module (d): 1

Gear diameter (d): Calculated based on the diametral pitch.

d₁=9.4 in

d₂=10in

d₃=1in

d₄=18.6in

d₅=5.4in

d₆=5.4in

d₇=18.6in

d₈ and d₉=20in [wheels]

Critical Gear Considerations:

Gears 5 and 6, identified as idlers, underwent rigorous analysis to prevent critical failures.

Factors such as k_v , k_o , k_m , and c_s were thoroughly considered in the design process and all these factors have been listed clearly in the appendix.

Endurance Limit and Stress Analysis:

Endurance limit (S_i): 35.11 ksi

Stress (σ): 157.66 ft-lbf

Force (F_\square): 111.34 lbf

Reduction System Summary:

The gear module, designed with the specific material and rotational speed requirements in mind, forms a reliable reduction system. The reduction ratios from the input to the output speeds ensure the desired operational characteristics of the ball launcher. The calculated forces, stress limits, and safety factors, detailed in the analysis, attest to the robustness and efficiency of the gear system within the broader ball launcher assembly. The seven-gear reduction system effectively and efficiently reduces the motor's RPM to the desired values for the launch wheels. By meticulously choosing gear ratios and meticulously analyzing critical components, we've ensured a robust and reliable gear train that delivers optimal performance for the ball launcher.

3.3 Bearing: state the final selection of the bearing, discuss the characteristic of the bearing from input to output

The motor connected to shaft AB, which holds by the bearing A, and bearing B and connected to the shafts CD to reduce the speed ratio using 2 gears reduction, next connected to EF Shaft and on the other side interlocks their teeths with gear 5, and 6, interlocks with shaft GH.

The below table shows the characteristics of each bearings on the shafts

Kr=0.2 for 99% reliability, while theta for angular ball bearing is 20 degrees, and Life span as working 20 hours a day, 7 days, 52 weeks in a year with rpm variation from 2900 to 1450 rpm depends on the shaft we are calculating.

Table of characteristics of Bearings in the design for radial bearing $\alpha=0$ degrees

Bearing Name	Creq (kN)	Bore for Extra Light Series (mm)	Bearing Basic Number	Bore for Light Series (mm)	Bearing Basic Number	Bore for Medium Series (mm)	Bearing Basic Number
A	0.384	10	L00	10	200	10	300
B	0.768	10	L00	10	200	10	300
C	5.32	45	L09	30	206	25	305
D	15.98	90	L18	65	213	55	311
E	2.37	25	L05	17	203	12	301
F	3.27	30	L06	20	204	17	303
G	1.42	20	L04	15	202	10	300
H	2.64	30	L06	17	203	15	302

As shown from the above table and relating with shaft analysis we can decide from the first shaft that have bearing A, and B to the last shaft with bearing G, and H, will have the following specifications:

Bearing A: Extra light series with Bore 10 mm, L00.

Bearing B: Extra light series with Bore 10 mm, L00.

Bearing C: Extra light series with Bore 45 mm, L09.

Bearing D: Extra light series with Bore 90 mm, L18.

Bearing E: Extra light series with Bore 25 mm, L05.

Bearing F: Extra light series with Bore 30 mm, L06.

Bearing G: Extra light series with Bore 20 mm, L04.

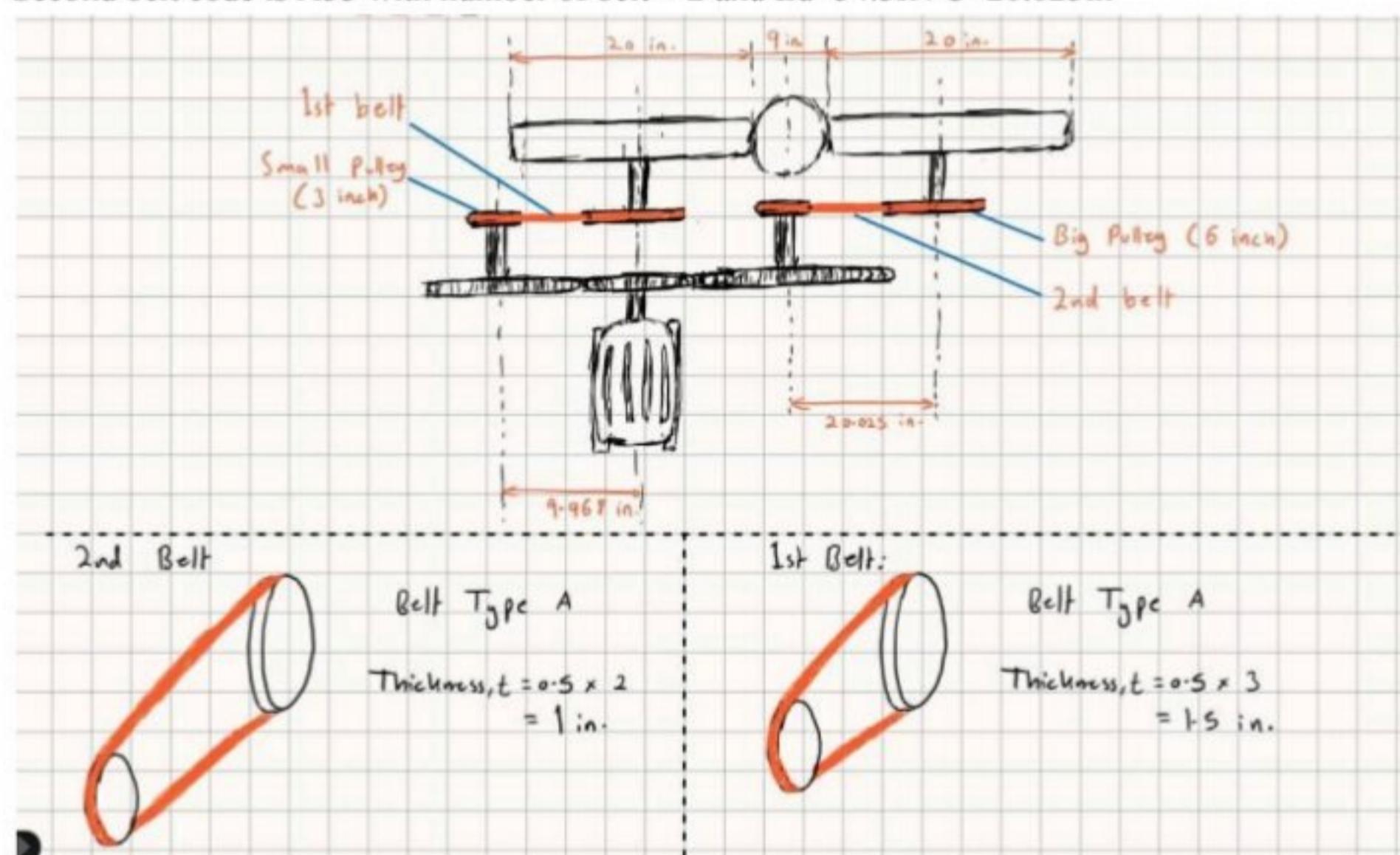
Bearing H: Extra light series with Bore 30 mm, L06.

3.4 Belt: State the final configuration of the V-Belt

When deliberating on belt selection for a ball launcher, meticulous attention to detail is paramount to ensure optimal performance and longevity. Among the options, two belts emerge as contenders: the A33 and A53. The A33 belt, characterized by a quantity of three and a length of 34.3 inches, boasts a circumference of 9.968 inches, prioritizing reliability and balance. Conversely, the A53 belt, numbering two with a length of 54.3 inches, offers a circumference of 20.025 inches, promising enhanced durability and robustness. The decision between these belts hinges on a careful assessment of the launcher's specific requirements, ensuring seamless operation and maximum efficiency.

First belt code is A33 with the a number of belt = 3 and a Ld= 34.3in C=9.968in

Second belt code is A53 with number of belt = 2 and Ld=54.3IN C=20.025in



3.5 Shaft: calculate the diameter.

The design and analysis of the shafts (A-B), (C-D), (E-F), and (G-H) play a crucial role in ensuring the structural integrity and reliable operation of the ball launcher system. Shaft design involves considerations of both bending due to bearing loads and torsion induced by the gears. The meticulous analysis conducted for each shaft has led to the determination of the appropriate shaft diameters.

The design of the four shafts (A-B, C-D, E-F, G-H) considered several crucial factors:

- Load conditions: Each shaft experiences a combination of bending moments from bearing reactions and torsional moments from gear engagements. These loads were meticulously calculated with detailed considerations in the appendix.
- Material selection: Martensitic 410 CW steel with a yield strength (s_u) of 105 ksi was chosen for its excellent strength, fatigue resistance, and machinability.
- Fatigue analysis: Applying the endurance limit (s_n) of 35.11 ksi derived from the gear analysis and employing relevant fatigue stress concentration factors (k_f) based on standard charts, a comprehensive fatigue analysis was conducted for each shaft.

Shaft Configuration:

Shaft (A-B):

Connects the motor to the first gear.

Rotates counterclockwise.

Undergoes bending due to bearing loads and torsion from gear engagement.

Shaft (C-D):

Connects gears 2 and 3

Rotates clockwise.

Subjected to bending forces from bearing loads and torsional stresses from gear interaction

Shaft (E-F):

Connects gear 4 and the wheel.

Experiences bending forces and torsional stresses.

Critical for the transfer of power from gear 3 to the wheel.

Shaft (G-H):

Positioned between gear 6 and the wheel.

Rotates clockwise.

Bending and torsional stresses are significant considerations in its design.

Shaft Diameter Calculations:

Results and Optimization:

Through rigorous calculations, optimized diameters were determined for each shaft:

Shaft A-B: 10 mm (increased from 9 mm for added safety)

Shaft C-D: 25 mm

Shaft E-F: 20 mm (increased from 15 mm for added safety)

Shaft G-H: 19 mm (increased from 15 mm for added safety)

Material and Safety Factors:

Material Used: Martensitic 410 CW ($su=105$ ksi).

Endurance Limit (S_i): 35.11 ksi (from gear analysis).

Fatigue Stress Concentration Factor (K_f): 1.6.

Safety factors incorporated for each shaft diameter.

The appendix contains a comprehensive breakdown of the equations, factors, and considerations used in the shaft design analysis. Detailed calculations for bending and torsional stresses, along with safety factors, are provided for each shaft.

In conclusion, the careful analysis and design of the shafts are integral to the overall success of the ball launcher project. The chosen materials and safety factors contribute to the system's resilience and longevity, ensuring smooth operation and minimal risk of failure. The appendix serves as a valuable resource for those seeking a deeper understanding of the intricacies involved in the shaft design process.

4.0 Discussion & Conclusion

4.1 State the final sizing of the gearbox using spur gear and V-Belt

The sizing of the gearbox at its final stages whether using spur gears or V-Belt structures is an integral part to incorporate in any form engineering design due not only technical performance but also aesthetic purpose. First, the gearbox is designed at 50 inches wide and deep with a height of nine inches. On the other hand, in search for better visuals and a more detailed design changes are done increasing dimensions to 53 inches wide by 22 deep. It is important to note that these dimensions remain constant for both the spur gear and V-Belt configurations, thus leading us into a fair comparative study.

Despite the uniformity in dimensions, a noteworthy advantage emerges with the V-Belt configuration. Through utilizing the belt system, the gearbox can be effectively downsized, reducing its width to 42.6 inches and its depth to 11 inches, while maintaining the same height. This reduction in size is a testament to the inherent efficiency and compactness of the belt system, highlighting its superiority over the spur gear alternative.

The decision to prefer the V-Belt configuration is not solely based on its ability to achieve a smaller gearbox size but also considers its other advantages. V-Belts offer smoother operation, reduced noise levels, and greater flexibility, which can be advantageous in various applications. Additionally, the compactness of the belt system contributes to easier installation and maintenance, further enhancing its appeal.

Furthermore, the downsizing of the gearbox aligns with contemporary design trends that prioritize sleekness and efficiency. A smaller gearbox not only enhances the overall aesthetic of the machinery but also allows for more streamlined integration into existing systems or machinery layouts.

Both spur gear and V-Belt configurations are viable choices in the design of a gearbox; however, it is arguably correct to favor the latter since with minimal tradeoffs its configuration allows for smaller size without compromising functionality. This choice highlights the significance of balancing technical and empirical components in engineering design, ideal embodied solutions that are not only productive but pleasant to behold.

4.2 Discuss the method to reduce the size of the gearbox

One of the most important factors in maximizing the ball launcher system's overall effectiveness and performance is the decrease of gearbox size. In addition to improving the device's mobility, a small and well-designed gearbox also helps to save manufacturing costs, weight, and energy usage. A number of techniques have been used to reduce the gearbox size without sacrificing dependability or usefulness.

4.2.1 Gear Arrangement and Configuration

Optimizing the arrangement and layout of gears is a crucial tactic for minimizing the size of the gearbox. The entire size of the gearbox can be greatly impacted by the proper selection of gear types, such as helical, bevel, or planetary gears. For example, helical gears can enable more compact designs and offer smoother operation because of their superior power transmission efficiency.

In addition, exploring alternative gear configurations, such as planetary gear systems, allows for a more compact and lightweight design by distributing the load across multiple gears. The planetary arrangement, where gears share the load, enhances the power-to-weight ratio and reduces the overall size of the gearbox.

4.2.2 Material Selection

Size reduction is mostly dependent on the materials used in gearbox manufacturing. Smaller, more reliable gear systems may be designed by utilizing high-strength materials with advantageous mechanical qualities. Improvements in strength-to-weight ratios and composite materials offer shrinking possibilities without sacrificing structural integrity.

Additionally, the use of materials with low coefficients of friction can contribute to the reduction of gear sizes by minimizing the need for extensive lubrication systems. This not only simplifies the design but also allows for more compact arrangements of gears within the gearbox.

4.2.3 Advanced Manufacturing Techniques

Utilizing advanced manufacturing techniques can significantly contribute to size reduction. Precision machining, computer numerical control (CNC) technology, and additive manufacturing processes enable the production of gears with intricate designs and tight tolerances. This precision allows for the creation of more compact gear arrangements and the incorporation of features that enhance efficiency.

Moreover, the implementation of lightweight and high-strength materials through additive manufacturing, such as 3D printing, offers new possibilities for intricate and optimized gear designs. This not only reduces the weight of the gearbox but also facilitates innovative geometries that can lead to a more compact overall size.

In general ,a comprehensive system approach, new material developments, manufacturing processes, and creative design methods all play a part in the complex process of reducing gearbox size. Through meticulous evaluation of gear configurations, materials, production procedures, system integration, computational tools, customisation, and ongoing enhancement, engineers can produce a gearbox that is not only highly efficient and compact, but also precisely customized to meet the unique needs of the ball launcher system. This all-encompassing and iterative method makes sure that overall system performance, durability, or dependability are not compromised in the name of size reduction initiatives. Realizing future breakthroughs in gearbox design and size reduction will depend on embracing new approaches and being at the forefront of innovation as technology continues to change.

5.0 Appendices

5.1 Force analysis and motor selection

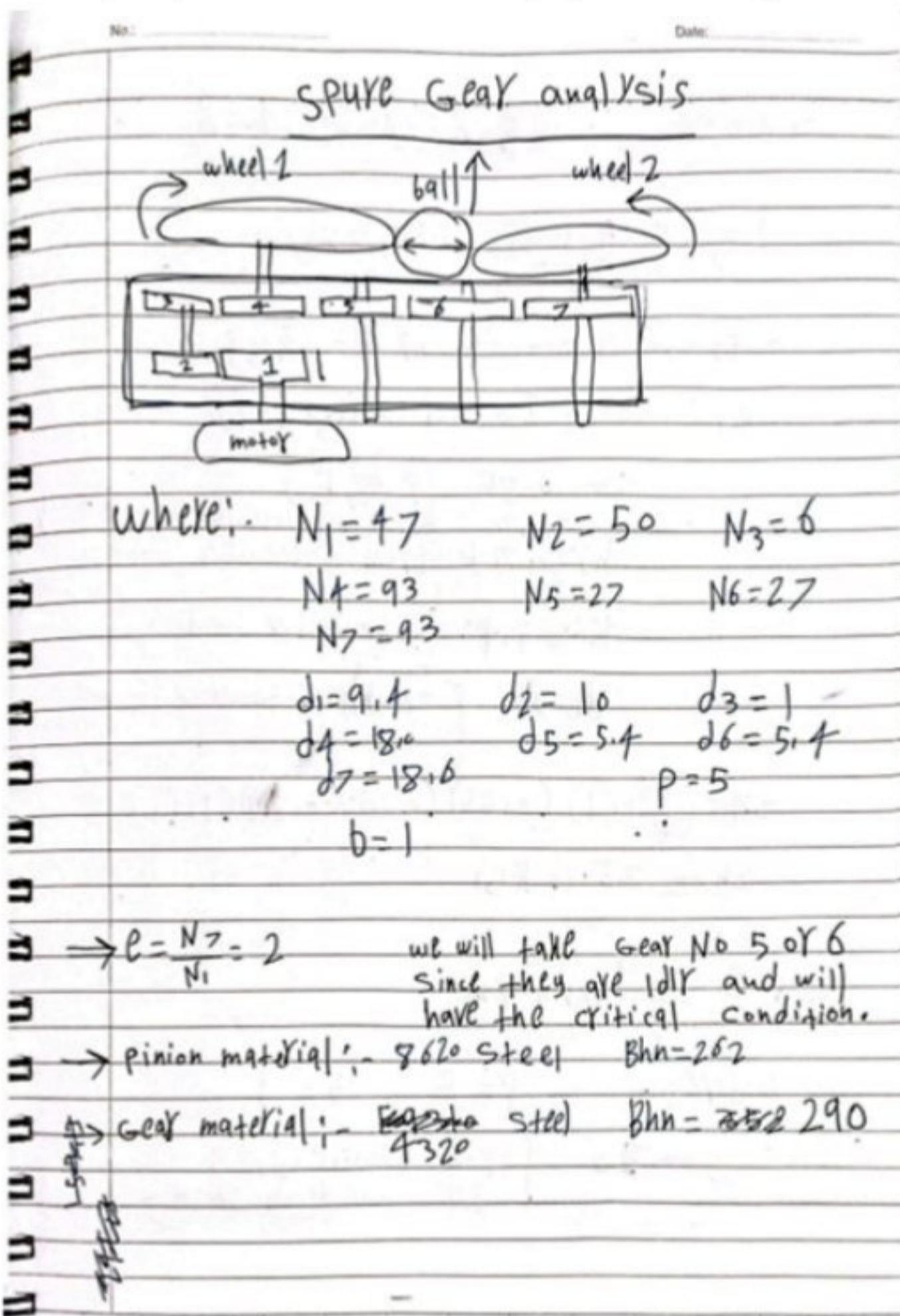
Motor selection

Aluminium; 400 V; 50 Hz; Class IE2

2-pole

P _n [kW]	n _n [rpm]	Frame size Type code ALAA..	Nominal current I _n [A]	Locked rotor current (multiple of nominal current) I ₁ /I _n	Efficiency at load points				Power factor at load points				Nominal torque T _n [Nm]	Locked rotor torque (multiple of nominal torque) T/T _n	Pull up torque (multiple of nominal torque) T _z /T _n	Break down torque (multiple of nominal torque) T _z /T _n	Moment of inertia J kgm ²	Total mass (B3 version, approx.) m [kg]	Sound pressure, Noise level dB (A)
					[%]				cos φ										
Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load
0,18	2775	0063M0	0,49	4,41	67,4	67,4	60,4	48,0	0,79	0,69	0,55	0,38	0,62	1,90	1,70	2,00	0,17 x 10 ⁻³	5,0	53
0,25	2785	0063M1	0,65	4,50	69,9	70,0	65,7	49,0	0,79	0,70	0,56	0,39	0,86	1,95	1,70	2,05	0,21 x 10 ⁻³	6,0	53
0,37	2790	0071M0	0,93	4,86	71,0	71,0	66,7	52,5	0,81	0,71	0,55	0,36	1,27	1,90	1,70	2,20	0,17 x 10 ⁻³	8,0	55
0,55	2780	0071M1	1,27	5,32	75,5	76,2	73,3	59,0	0,83	0,75	0,59	0,39	1,89	1,90	1,70	2,20	0,33 x 10 ⁻³	9,0	56
0,75	2815	0080M0	1,63	5,85	77,4	78,6	77,4	66,2	0,86	0,79	0,67	0,44	2,54	3,10	2,70	3,00	0,46 x 10 ⁻³	12,0	57
1,1	2820	0080M1	2,32	6,90	79,6	80,8	80,0	73,1	0,86	0,80	0,68	0,46	3,72	3,35	2,95	3,25	0,75 x 10 ⁻³	14,0	57
1,5	2865	0090S0	3,11	7,71	81,3	82,0	80,9	73,9	0,86	0,80	0,69	0,46	5,00	3,10	2,90	3,30	1,0 x 10 ⁻³	17,0	56
2,2	2860	0090L0	4,39	7,45	83,2	84,0	83,2	77,1	0,87	0,82	0,72	0,51	7,34	3,05	2,75	3,20	1,5 x 10 ⁻³	20,0	57
3	2880	0100L0	6,06	7,45	84,6	85,5	84,8	78,3	0,85	0,79	0,66	0,45	9,94	3,05	2,55	3,35	4,0 x 10 ⁻³	27,0	59
4	2905	0112M0	7,78	7,75	85,8	86,3	85,3	78,9	0,87	0,83	0,75	0,55	13,1	1,95	1,80	2,85	8,25 x 10 ⁻³	35,0	64
5,5	2930	0132S0	11,3	7,05	87,0	87,0	85,6	79,4	0,81	0,75	0,64	0,42	17,9	2,65	2,45	3,05	13,5 x 10 ⁻³	51,0	69
7,5	2920	0132S1	15,7	7,00	88,1	88,4	87,5	80,9	0,79	0,73	0,62	0,41	24,5	2,80	2,50	3,00	16 x 10 ⁻³	56,0	69
11	2950	0160M0	19,9	8,28	89,5	90,5	90,0	85,5	0,89	0,86	0,77	0,57	35,6	2,30	1,80	3,05	38 x 10 ⁻³	87,0	74
15	2950	0160M1	26,6	8,46	90,5	91,5	91,0	87,5	0,90	0,86	0,78	0,58	48,5	2,45	1,95	3,15	48 x 10 ⁻³	98,0	74
18,5	2945	0160L0	32,2	9,00	91,0	92,0	92,0	88,5	0,91	0,91	0,86	0,71	60,0	2,60	1,85	3,10	59 x 10 ⁻³	109	73

Gear analysis (MOHAMMED KHALIL)&(Mazen Omar)



$$\Rightarrow \rho = \frac{n_1}{n_2} \rightarrow n_2 = (2) (2900) = 1450$$

$$V_F = \frac{\pi d_F \times n_2}{12} = 2049.8 \text{ ft/min}$$

$$\Rightarrow S_n = S_n' C_L C_G C_S K_Y K_T K_m S$$

where:- $C_L = 1.0$ for bending load

$$C_G = 0.85 \quad [P \leq 5]$$

$$C_S = 0.70 \quad [\text{machined figure 8.13}]$$

$$K_Y = 0.814 \quad [\text{From Table 15.3, 99% reli}]$$

$$K_m S = 1.4 \quad [\text{one idler gear}]$$

$$K_T = 1 \quad [\text{Temperature should be} \leq 160^\circ F]$$

$$S_n = \left(\frac{2900}{4} \right) (1) (0.85) (0.70) (0.814) (1) (1)$$

$$S_n = 35.11 \text{ ksi}$$

$$\Rightarrow G = \frac{F_t P}{b j} K_Y K_T K_m$$

where:- $P = 5 \quad b = 1$

$$j = 2.6 \quad [\text{From Figure 15.23 } 20^\circ \text{ full depth teeth}]$$

$$KV = \frac{600 + \sqrt{1450}}{600} = 3,416 \quad [\text{Figure 15,24}]$$

$$H_0 = 1.50 \quad [\text{Table 15.1}]$$

$$K_m = 1.6 \quad [\text{TaBL 15,2}]$$

$$f = \frac{f_L(5)}{(0.125)(1)} \quad (3.416) \quad (1, 50) \quad (1, 6)$$

$$\delta = 157.66 \text{ ft psi}$$

∴ our safety factor is 2.

$$\Rightarrow Sf = \frac{Sh}{\theta} \rightarrow (Sf)(6) = Sh$$

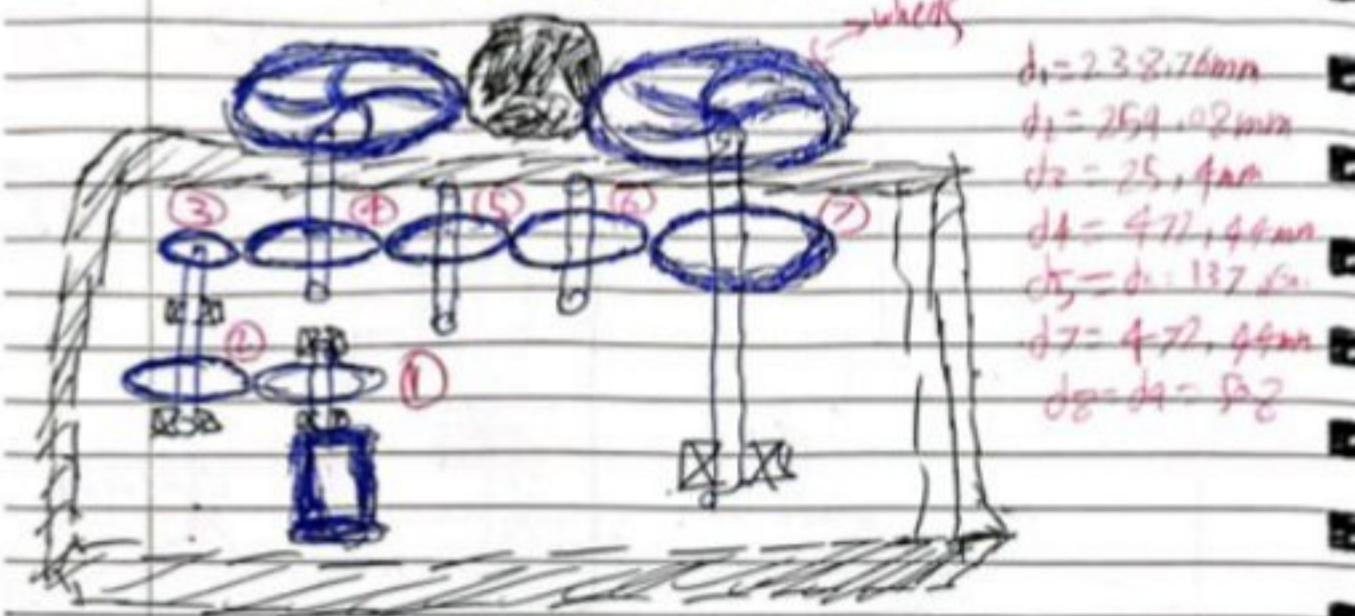
$$(2 \times 157.66) \text{ ft} = 35.11 \times 10^3$$

$$ft = 111.34 \text{ lb} //$$

$$HP = FT \times V_5 - 4.89 \text{ HP} \quad \cancel{\#}$$

Gear analysis continue

- There are 8 gear at the attached to the motor and the wheel as the following



Gear 1°:

$$F_W = \frac{T_1}{9549} = T_1 = 12,02 \text{ Nm}$$

$$f_{T1} = \frac{T_1 \times r_1}{d_1} = 100.69 \text{ N}$$

$$f_{F1} = 100.69 \tan 20 = 36.65 \text{ N}$$

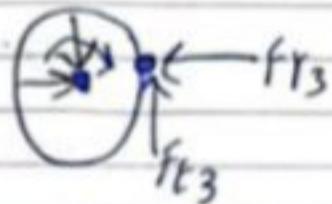
Gear 2

$$T_2 = T_1 = \frac{100.69 \times 259.08}{2 \times 100} = 13.04 \text{ Nm}$$

$$f_{T2} = 100.69$$

$$f_{F2} = 36.65 \text{ N}$$

$$\omega_2 = 272.6 \text{ rpm}$$

Gear 3

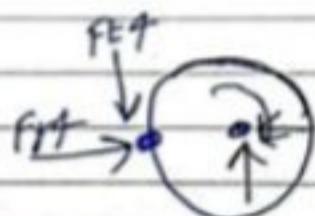
$$n_3 = 2726 \text{ rpm}$$

$$T_3 = 13104 \text{ N.m}$$

$$f_{T3} = 1027.04 \text{ N}$$

$$\begin{aligned} f_{R3} &= 1027 + 4420 \\ &= 3731.8 \text{ N} \end{aligned}$$

Gear 4:



$$T_4 = 24104 \text{ N.m}$$

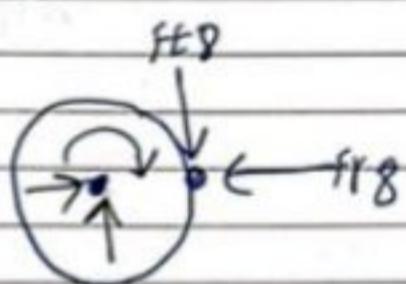
$$f_{T3} = f_{T4} = 1027.04 \text{ N}$$

$$n_4 = 1450 \text{ rpm} = n_8 = n$$

$$F_{R3} = F_{R4} = 3731.8 \text{ N}$$

$$\phi = 20 \quad \psi = 28$$

Gear 8: [wheel]



$$f_{E8} = 94105 \text{ N}$$

$$F_{R8} = 34145 \text{ N}$$

$$n_8 = 1450$$

$$T_8 = 24104 \text{ N.m}$$

Gear 7:

$$T_7 = 24,09 \text{ N}$$

$$F_{t7} = 495,26 \text{ N} = f_{t5}$$

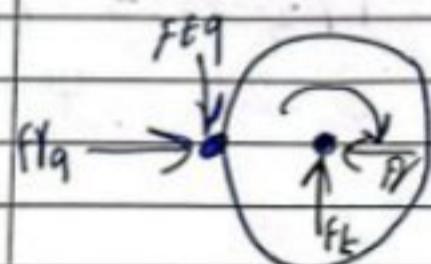
$$f_{r7} = 180,12^6 = f_{r5}$$

$$n_7 = 1450 \text{ rpm}$$

Gear 5 and 6 are idler and we have taken the f_t from it to avoid any failure.

Gear 8: [wheel]

$$F_{Eq} = \frac{24,09(21,100)}{508} = 97,05$$



$$f_{r8} = 34,45 \text{ N}$$

$$T_8 = 24,09 \text{ Nm}$$

$$n_8 = 1450 \text{ rpm}$$

Appendix C-7 Mechanical Properties of Some Carburizing Steels

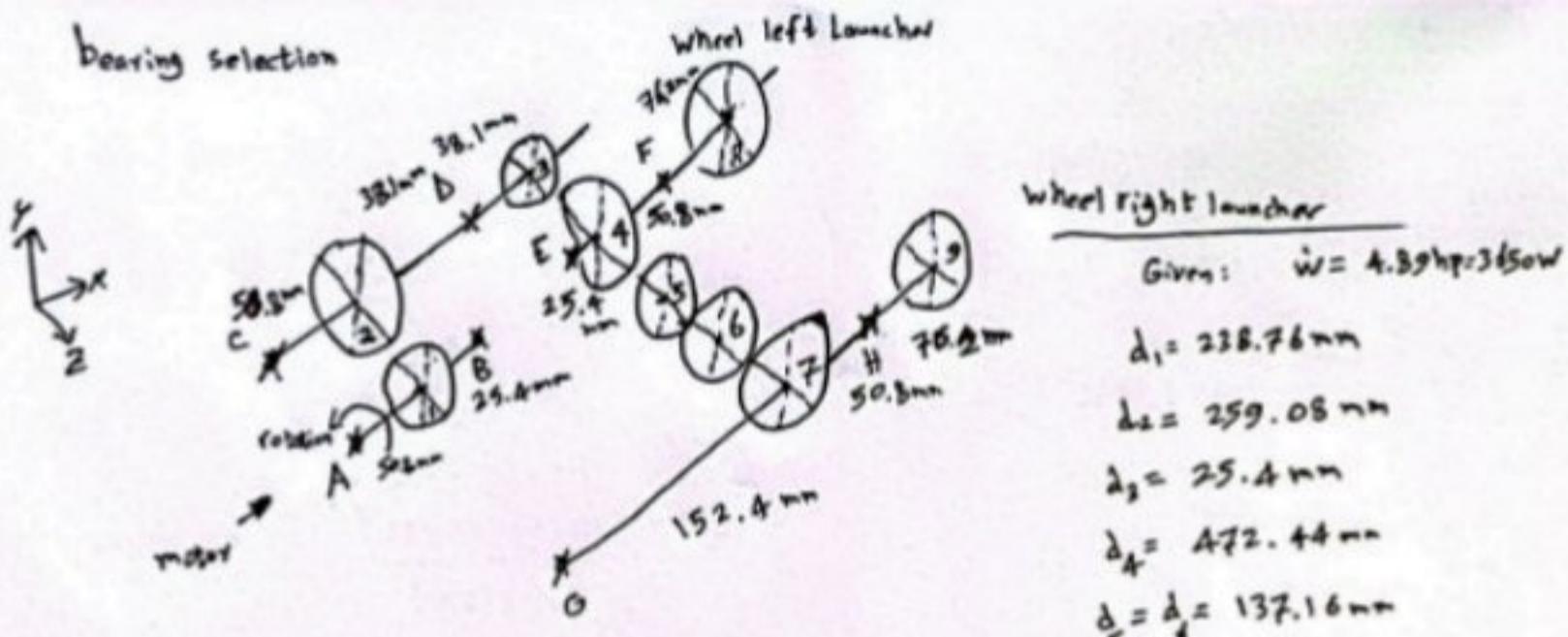
Steel AISI	Hardness, H_B	Core								Case		
		Tensile Strength				Ductility		Impact Strength Izod		Hardness, R_C	Thickness	
		Ultimate, S_u ksi	Ultimate, S_u MPa	Yield, S_y ksi	Yield, S_y MPa	Elongation in 2 in. (%)	Reduction of Area (%)	ft-lb	J		in.	mm
1015 ^a	149	73	503	46	317	32	71	91	123	62	0.048	1.22
1022 ^a	163	82	565	47	324	27	66	81	110	62	0.046	1.17
1117 ^a	192	96	662	59	407	23	53	33	45	65	0.045	1.14
1118 ^a	229	113	779	76	524	17	45	16	22	61	0.065	1.65
4320 ^b	293	146	1006	94	648	22	56	48	65	59	0.075	1.91
4620 ^b	235	115	793	77	531	22	62	78	106	59	0.060	1.52
8620 ^b	262	130	896	77	531	22	52	66	89	61	0.070	1.78
E9310 ^b	352	169	1165	138	952	15	62	63	85	58	0.055	1.40

^a1-in. round section treated; 0.505-in. round section tested. Single quench in water, tempered 350°F (177°C).^b0.565-in. round section treated; 0.505-in. round section tested. Double quench in oil, tempered 450°F (232°C). (Tempering at 300°F gives greater case hardness but less core toughness.)

Note: Values tabulated are approximate median expectations.

Source: *Modern Steels and Their Properties*, Bethlehem Steel Corporation, Bethlehem, Pa., 4th ed., 1958, and 7th ed., 1972.

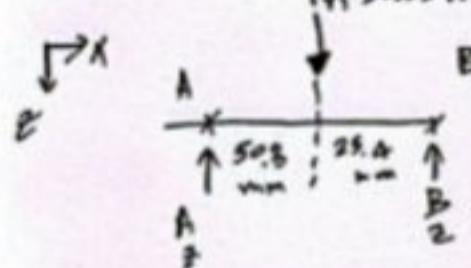
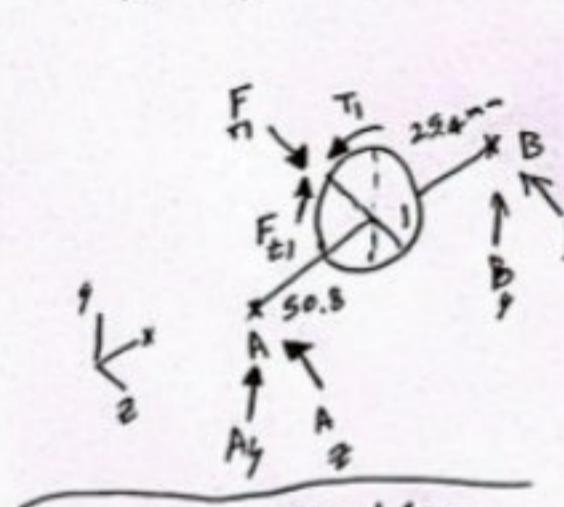
Bearing analysis selection (AMMAR MOHAMMED)&(Mazen Omar)



$$\dot{W} = 365 \text{ kW} \quad \dot{W} = \frac{T \cdot n}{9549} \Rightarrow T = \frac{9549(3650)}{2900} = 12,02 \text{ N.m}$$

$$T_1 = F_{t1} d_1 \Rightarrow F_{t1} = \frac{T_1 \times z_1 \times 1000}{d_1} = \frac{(12,02)(2)(1000)}{238.76} = 100.69 \text{ N}$$

$$F_{r1} = F_{t1} \tan \phi = 100.69 \tan 20^\circ = 36.65 \text{ N}$$

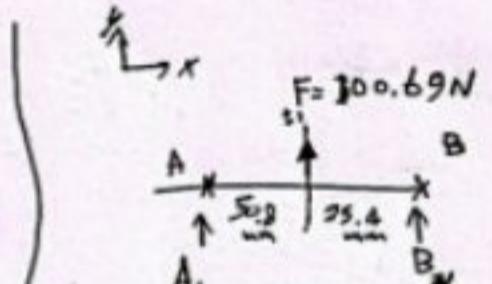


$$(+) \sum M_A = 0 \\ -36.65(50.8) + B_z(76.2) = 0$$

$$B_z = 24.43 \text{ N}$$

$$(+) \sum F_z = 0 \\ A_z + B_z - 36.65 = 0$$

$$A_z = 12.22 \text{ N}$$



$$(+) \sum M_A = 0 \\ 100.69(50.8) + B_z(76.2) = 0$$

$$B_z = -67.13 \text{ N} \quad (\text{-ve } \downarrow)$$

$$(+) \sum F_y = 0$$

$$A_y + 100.69 + B_z = 0$$

$$A_y = -33.56 \text{ N} \quad (\text{-ve } \downarrow)$$

$$F_{r1} A = \sqrt{A_x^2 + A_y^2} = 39.72 \text{ N} \quad (\text{radial})$$

No thrust

$$F_{r1} B = \sqrt{B_x^2 + B_z^2} = 71.45 \text{ N} \quad (\text{radial})$$

No thrust

wheel right launcher

Given: $\dot{W} = 4.39 \text{ kW} : 3650 \text{ N.m}$

$d_1 = 238.76 \text{ mm}$
 $d_2 = 259.06 \text{ mm}$
 $d_3 = 25.4 \text{ mm}$
 $d_4 = 472.44 \text{ mm}$
 $d_5 = d_6 = 137.16 \text{ mm}$
 $d_7 = 472.44 \text{ mm}$
 $d_8 = d_9 = 50.8 \text{ mm}$

$n_1 = 2700 \text{ rpm}$
 $n_2 = n_3 = 272.6 \text{ rpm}$
 $n_4 = n_B = 1450 \text{ rpm}$
 $n_7 = n_9 = 1450 \text{ rpm}$

using radial ball with $\phi = 0^\circ$

Heavy impact (highest value)
 $k_a = 3$
 $K_r = 0.2 \rightarrow 99\%$

$$\frac{L}{R} = 90 \times 10^6$$

$$0 < \frac{F_r}{F_t} < 0.5, F_r = F_t$$

$$0.75 < \frac{F_r}{F_t} < 1.0, F_r = F_t \left[1 + 1.15 \left(\frac{F_r}{F_t} - 0.75 \right) \right]$$

$$\frac{F_r}{F_t} > 1.0, F_r = 1.176 F_t$$

$$C_{eq} = K_r F_r \left[\frac{L}{K_r R} \right]^{0.5}$$

①

For Point A

$$F_e = F_{r,A} = 35.72 N$$

$$C_{req} = K_A \frac{F}{e} \left[\frac{L}{K_A} \right]^{0.3}$$

$$= (3)(35.72) \left[\frac{(2900 \times 60 \times 20 \times 7 \times 52)}{(0.2)(90 \times 10)} \right]^{0.3}$$

$$C_{req} = 383.93 N$$

using table 14.2 nearest value is

$$xit \rightarrow Bore = 10 mm \rightarrow L_{00}$$

$$it \rightarrow Bore = 10 mm \rightarrow 200$$

$$med \rightarrow Bore = 10 mm \rightarrow 300$$

For Point B

$$F_e = F_{r,B} = 71.45 N$$

$$C_{req} = (3)(71.45) \left[\frac{2900 \times 60 \times 20 \times 7 \times 52}{0.2 \times 90 \times 10} \right]^{0.3}$$

$$= 767.97 N$$

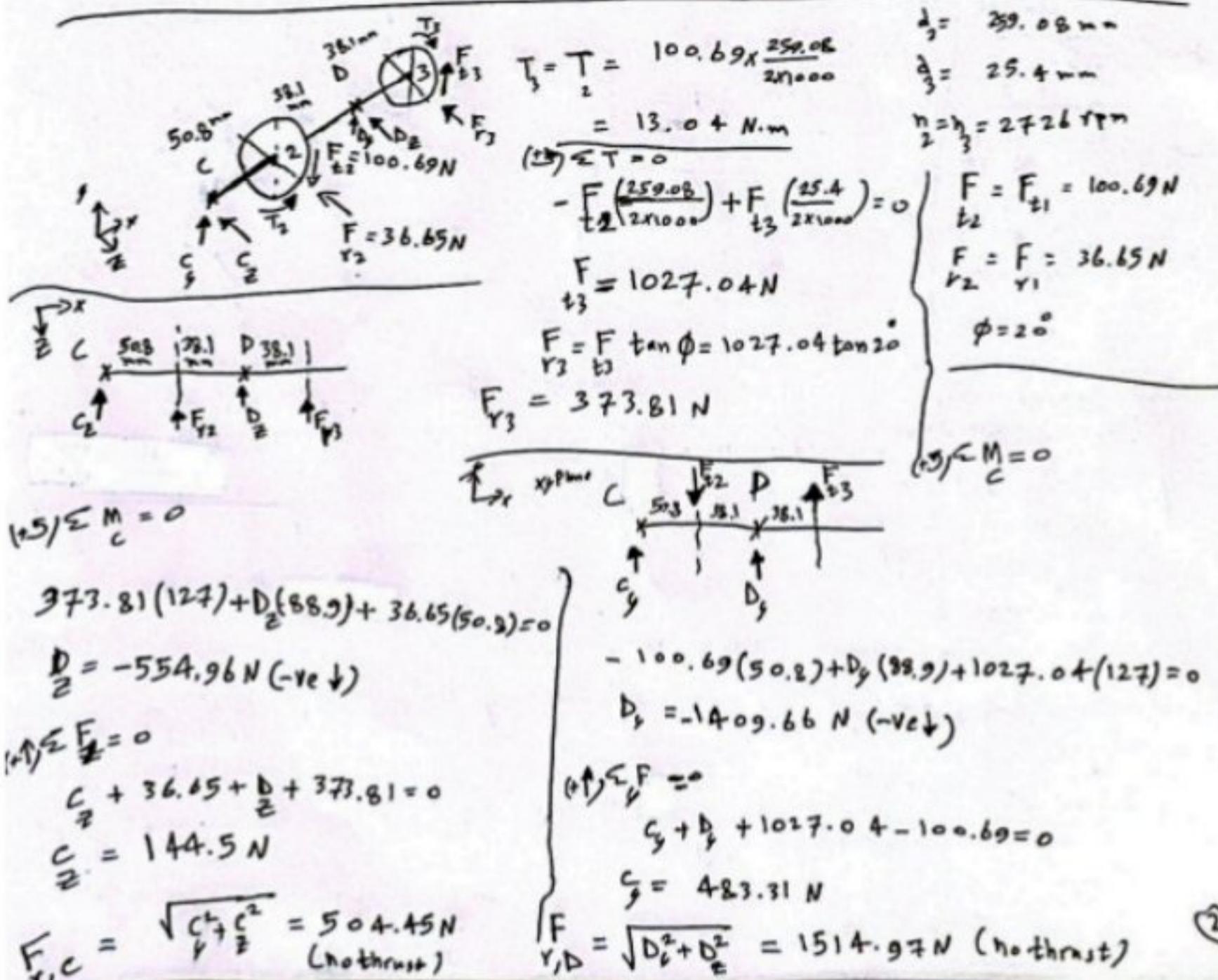
table 14.2

table 14.1

$$xit \rightarrow Bore = 10 mm \rightarrow L_{00}$$

$$it \rightarrow Bore = 10 mm \rightarrow 200$$

$$med \rightarrow Bore = 10 mm \rightarrow 300$$



For Point C

$$F_{e,C} = F_{r,C} = 504.45 \text{ N}$$

$$\begin{aligned} C_{req} &= (3)(504.45) \left[\frac{(2726)(60)(20)(7 \times 52)}{0.2(90 \times 10^6)} \right]^{0.3} \\ &= 5322.51 \text{ N} \end{aligned}$$

using table 14.2

$$\begin{aligned} \text{xt} \rightarrow B_{are} &= 45 \rightarrow L_09 \\ \text{lt} \rightarrow B_{are} &= 30 \rightarrow 206 \\ \text{med} \rightarrow B_{are} &= 25 \rightarrow 305 \end{aligned}$$

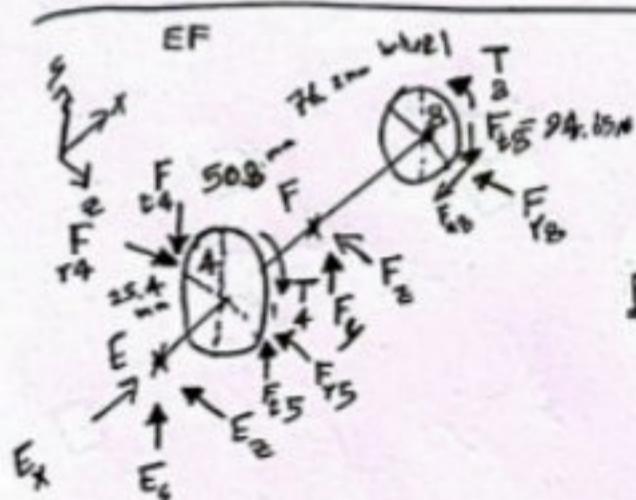
for Point D

$$F_{e,D} = F_{r,D} = 1514.97 \text{ N} \quad \eta = \eta = 2726$$

$$\begin{aligned} C_{req} &= (3)(1514.97) \left[\frac{(2726)(60)(20)(7 \times 52)}{0.2(90 \times 10^6)} \right]^{0.3} \\ &= 15934.02 \text{ N} \end{aligned}$$

table 14.1

$$\begin{aligned} \text{xt} \rightarrow B &= 90 \rightarrow L18 \\ \text{lt} \rightarrow B &= 65 \rightarrow 213 \\ \text{med} \rightarrow B &= 55 \rightarrow 311 \end{aligned}$$



$$\text{Given } F_{t5} = 111.3 + 16 \\ = 495.26 \text{ N}$$

$$T = T_B = 24.04 \text{ N-mm}$$

$$F_{tB} = \frac{24.04(2 \times 1000)}{508} = 94.65 \text{ N}$$

$$\begin{aligned} F_{tB} &= E = F_{tB} - \tan \psi (0.5) \\ &= [94.65 - \tan 28] 0.5 \\ &= (25.17) \text{ N} \end{aligned}$$

$$d_A = 472.44 \text{ mm}$$

$$d_B = 20 \text{ mm}$$

wharf

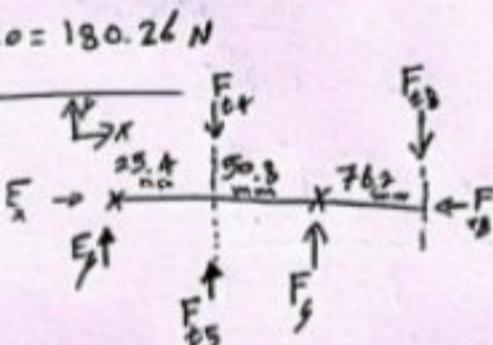
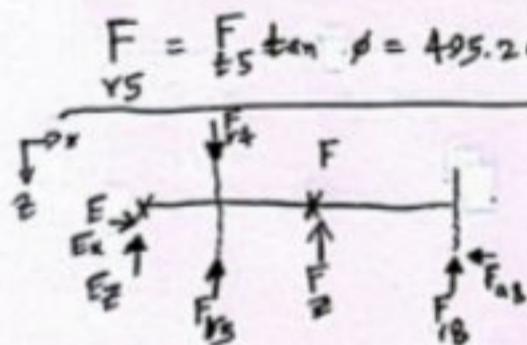
$$\frac{\eta}{4} = \frac{1450}{8}$$

$$F_{t3} = F_{t4} = 1027.04 \text{ N}$$

$$F_{t3} = F_{t4} = 373.81 \text{ N}$$

$$\phi = 20^\circ$$

$$\psi = 28^\circ$$



$$(13) \sum M = 0$$

$$-323.81(25.4) + 180.26(25.4) + F_t(76.2) + 34.45(152.4) = 0 \quad \left\{ -(1027.04)(25.4) + (495.26)(25.4) + F(76.2) - 25.17(5.03) \right. \\ \left. - (94.65)(152.4) = 0 \right.$$

$$F = 79.52 \text{ N}$$

$$(14) \sum F_z = 0$$

$$E_z = 79.52 \text{ N}$$

$$\begin{cases} F_{r,E} = 271.78 \text{ N} & (F = E = 25.17 \text{ N}) \\ F_{r,P} = 375.08 \text{ N} & (\text{no thrust}) \end{cases}$$

$$(15) \sum M_E = 0$$

$$-(1027.04)(25.4) + (495.26)(25.4) + F(76.2) - 25.17(5.03) - (94.65)(152.4) = 0$$

$$F_g = 766.56 \text{ N}$$

$$(16) \sum F_g = 0$$

$$E_g = 259.82 \text{ N}$$

③

for Point E

$$\frac{F_t}{F_y} = 0.1 < 0.35 \quad F_e = F_{r,E} = 271.78 N$$

$$C_{eq} = (3) \left(\frac{271.78}{\frac{(1450)(1.60 \times 2.0 \times 2152)}{0.2 \times 90 \times 10^4}} \right)^{0.3}$$

$$= 2272.8 N$$

$$1t \rightarrow B = 25 mm \rightarrow 105$$

$$1t \rightarrow B = 17 mm \rightarrow 203$$

$$med \rightarrow B = 12 mm \rightarrow 301$$

for Point F

$$F_r F = 375.08 N$$

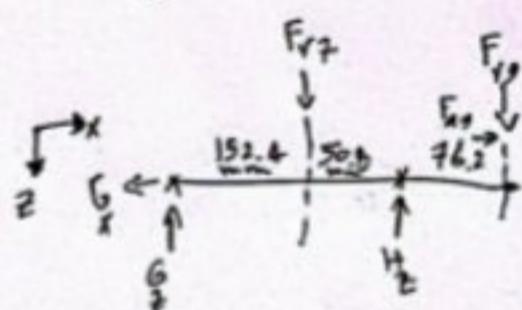
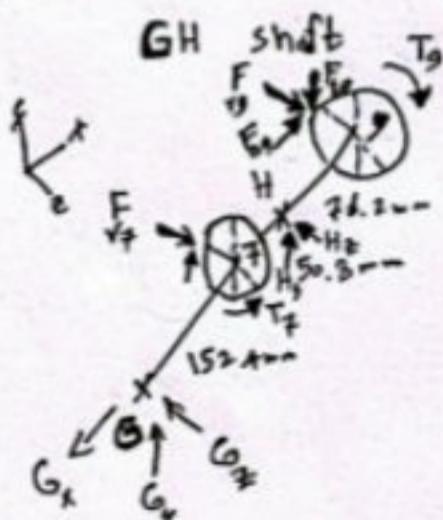
$$= (2) \left(\frac{375.08}{\frac{1450 \times 1.60 \times 2.0 \times 2152}{0.2 \times 90 \times 10^4}} \right)^{0.3}$$

$$= 3274.6 N$$

$$1t \rightarrow B = 30 mm \rightarrow 106$$

$$1t \rightarrow B = 20 mm \rightarrow 204$$

$$med \rightarrow B = 17 mm \rightarrow 303$$



$$T_7 = T_9 = 24.04 N-m$$

$$F_{t9} = \frac{24.04(2 \times 1000)}{508} = 94.65 N$$

$$F_{ag} = \frac{G}{x} = \frac{F}{t9} \tan 4^\circ (0.5)$$

$$= [94.65 \tan 28] 0.5$$

$$= 25.17 N$$

$$F_{v9} = 94.65 \tan 28^\circ$$

$$= 34.45 N$$

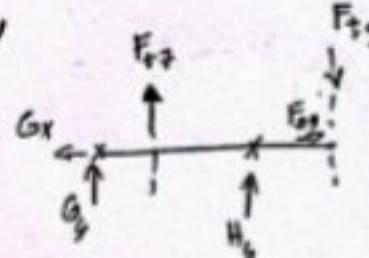
$$d_7 = 472.44 mm$$

$$d_9 = 508 mm$$

$$n_7 = n_9 = 1450 rpm$$

$$F_{t7} = F_{t9} = 495.26 N$$

$$F_{v7} = F_{v9} = 180.26 N$$



$$(+) \sum M_B = 0$$

$$- F_{r7}(152.4) + H_2(203.2) - F_{t9}(279.4) = 0$$

$$H_2 = 182.56 N$$

$$\begin{cases} (+) \sum M_B = 0 \\ F_{r7}(152.4) + H_1(203.2) - F_{t9}(279.4) = 0 \\ H_1 = -241.3 N (-ve \downarrow) \end{cases}$$

$$(+) \sum F_z = 0$$

$$G_x = 32.12 N$$

$$\frac{F_{r,G}}{F_{r,H}} = 1.6252 N \quad (\text{thrust})$$

$$(+) \sum F_y = 0$$

$$G_y = -159.11 N (-ve \downarrow)$$

$$F_{r,H} = 302.58 N$$

(no thrust)

②

for Point G

$$\frac{F}{F_r} = 0.15 < 0.35 \quad F_r = F = 162.52 N$$
$$C_{rg} = (3)(162.52) \left[\frac{(1450)(60)20 \times 7.152}{0.2 \times 9.81 \times 1.6} \right]^{0.3}$$
$$= 1418.9 N$$
$$\left. \begin{array}{l} F_r = F = 302.58 N \\ C_{rh} = (3)(302.58) \left[\frac{1450 \times 60 \times 20 \times 7.152}{0.2 \times 9.81 \times 1.6} \right]^{0.3} \\ = 2641.6 N \end{array} \right\}$$

$$1t \rightarrow B = 20 \text{ mn} \rightarrow 10^{\circ}$$

$$1t \rightarrow B = 15 \text{ mn} \rightarrow 20^{\circ}$$

$$\text{med} \rightarrow B = 10 \text{ mn} \rightarrow 30^{\circ}$$

for Point H

$$F_r = 302.58 N$$

$$C_{rh} = (3)(302.58) \left[\frac{1450 \times 60 \times 20 \times 7.152}{0.2 \times 9.81 \times 1.6} \right]^{0.3}$$
$$= 2641.6 N$$

$$1t \Rightarrow B = 30 \text{ mn} \rightarrow 10^{\circ}$$

$$1t \rightarrow B = 17 \text{ mn} \rightarrow 20^{\circ}$$

$$\text{med} \rightarrow B = 15 \text{ mn} \rightarrow 30^{\circ}$$

(5)

Shaft analysis (MOHAMMED KHALIL)&(Mazen Omar)

No.: _____

Date: _____

Shaft analysis

∴ we will have 4 shafts, (A-B), (C-D)
(E-F) & (G-H).

∴ in order to know the diameter of each one we will do shaft analysis and the equation that we will use are:-

$$d = \left[\frac{6n}{\pi} \times \left(\frac{A}{S_{UH}} + \frac{B}{S_{UT}} \right) \right]^{1/3}$$

where: A = 2 k_f m_d

B = $\sqrt{3}$ k_{fs} T_m

n = 2

~~But~~ in the k_f and k_{fs} is from figure [17.9] where the material bhn is over 200. therefore, k_f = 1.6 n_f = 1.6

∴ the material is [martenitic + l_o c_w]

S_U = 105 ksi

= 723.94 MPa

S_U = 35.11 ksi

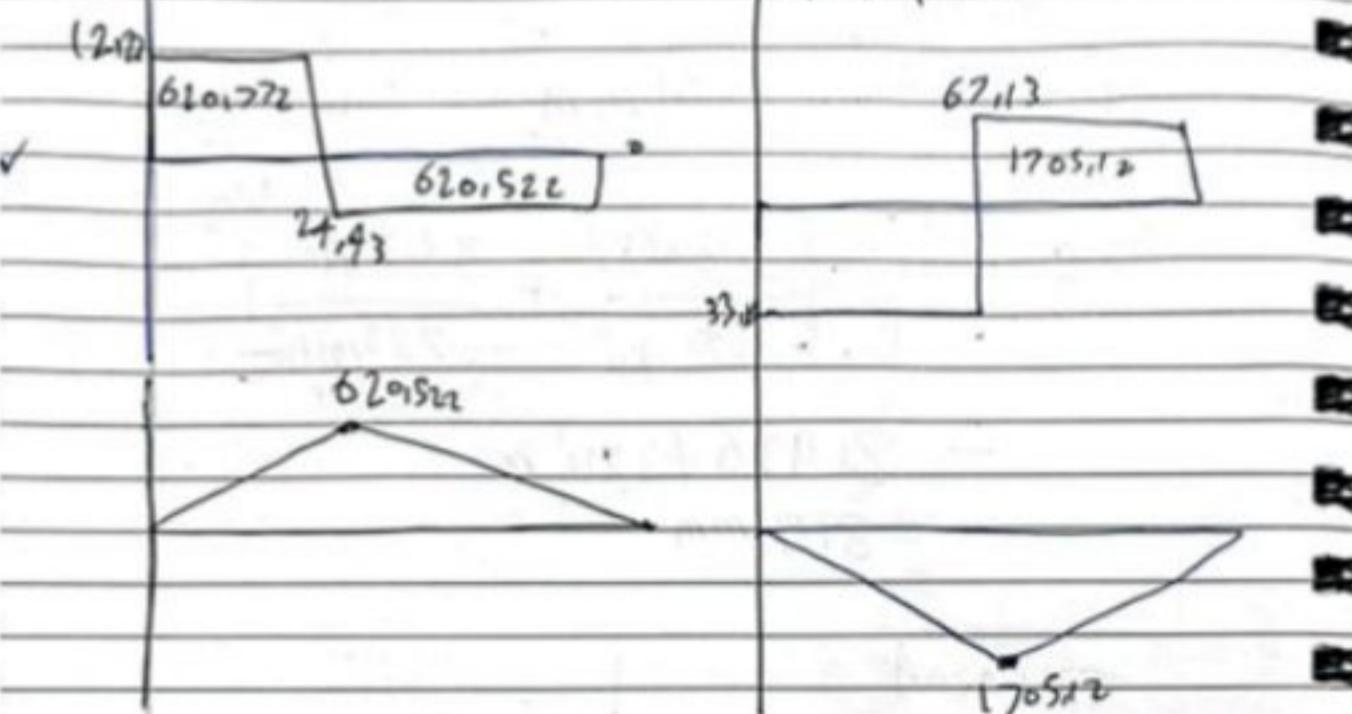
= 248.0 MPa

∴ All the value that are used here from bearing and gear analysis.

FIRST SHAFT: All the values are from bearing and gear analysis.

AB-Shaft
X-Z plane

$$K_F = 1.6 \\ n = 2 \\ X-Y PLT$$



$$\rightarrow M_a = \sqrt{620,522^2 + 1705,13^2} = 1814,5 \text{ N.m.m.}$$

$$\rightarrow T = 12,102 \text{ N.m}$$

$$A = 2 K_F m_a = 5806,4 \text{ N.m.m}$$

$$B = \sqrt{3} K_F T = 33310,8 \text{ N.m.m}$$

$$d = \left[\frac{16n}{\pi} \left(\frac{A}{S_C} + \frac{B}{S_{UT}} \right) \right]^{\frac{1}{3}} \quad \text{where: } S_{UT} =$$

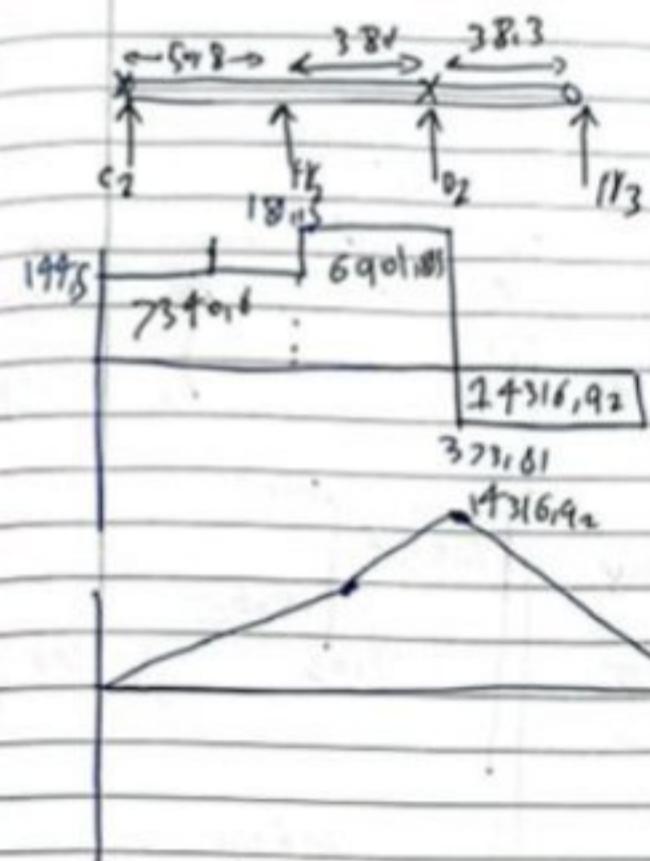
$$d = \left[\frac{16,12}{\pi} \left(\frac{5806,4}{272 \times 10^6} + \frac{33310,8}{72349 \times 10^6} \right) \right]^{\frac{1}{3}} = 8,93 \approx 9 \text{ mm}$$

for safety = 10 mm

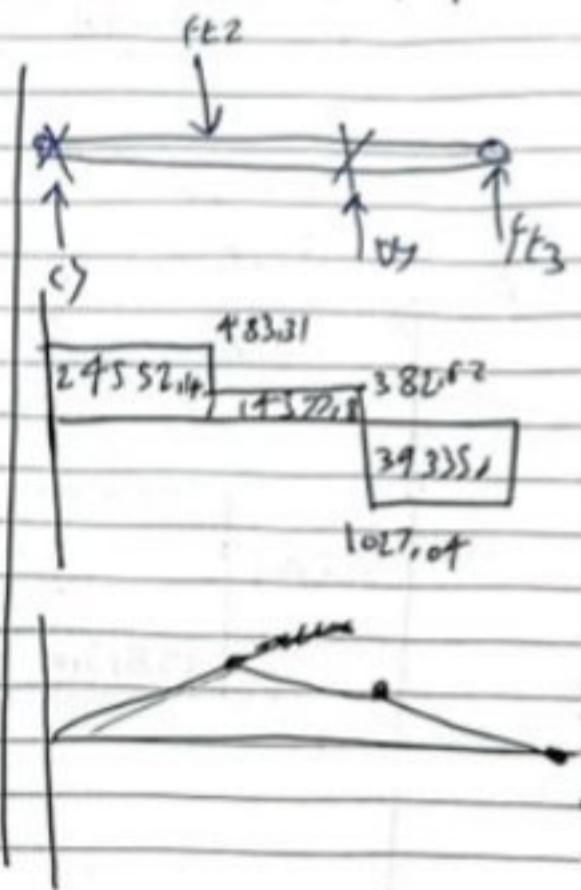
No.:

Date:

Shaft cd $x=2 \text{ plaq.}$



$x=5 \text{ plaq.}$



$$M_{max} = \sqrt{14316.9_2^2 + 39335_1^2} = 41869.75 \text{ Nmm}$$

$$\therefore T = 13104 \text{ Nm}$$

$$A = 2\pi f M_2 = 133983.2 \text{ Nmm}$$

$$B = \sqrt{3} K_f T = 36137.5 \text{ Nmm}$$

$$D = \left[\frac{16.2}{\pi} \times \left(\frac{A}{s_c} + \frac{B}{s_{out}} \right)^3 \right]^{1/3} = 18.13 \text{ mm}$$

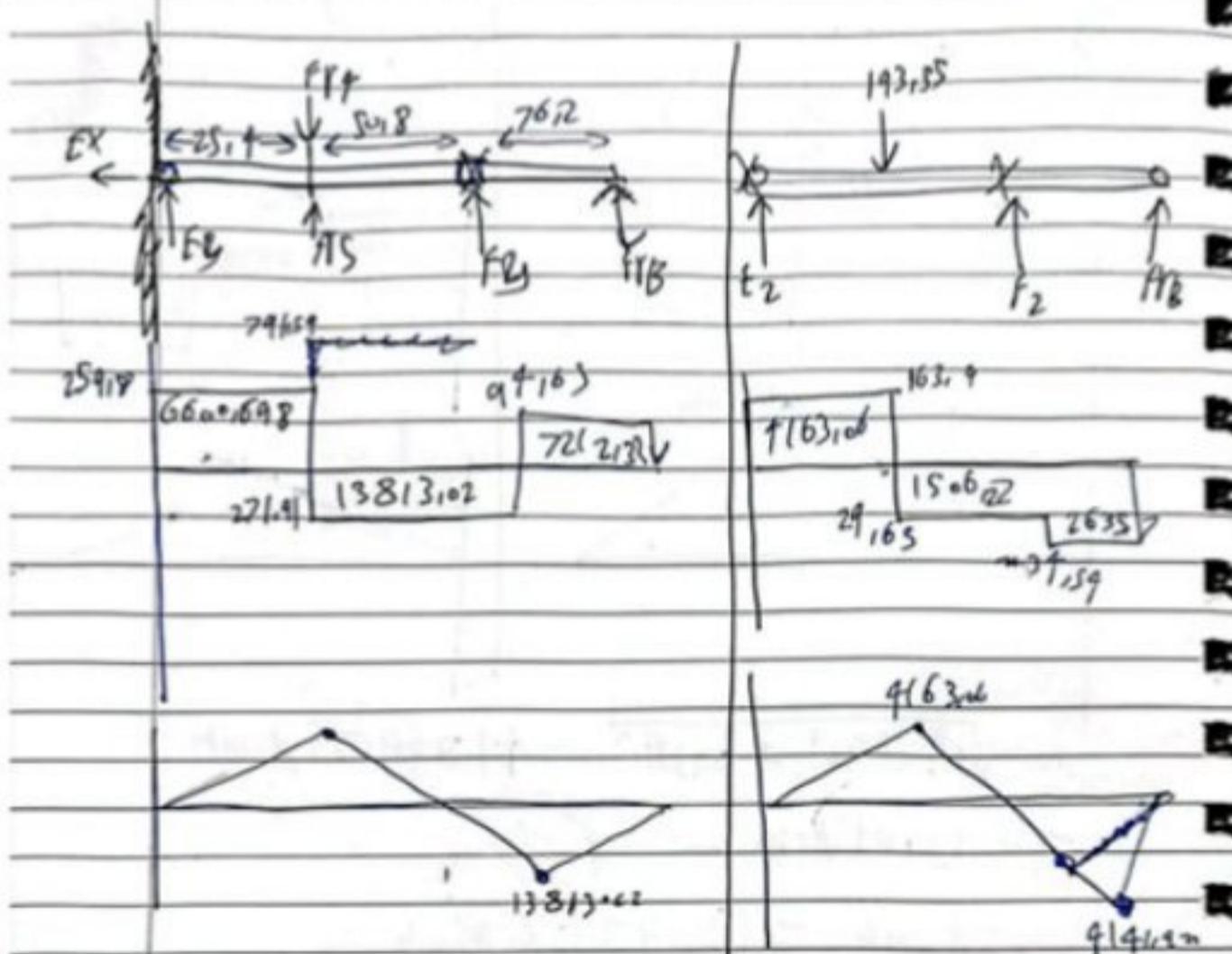
for the safety it will be 25 mm ~~✓~~

No.:

Date:

EF Shaft

X-Y plane



$$m = \sqrt{13813.62^2 + 19385.1978^2} = 19421.23 \text{ Nmm}$$

$$T = 48.08 \text{ Nm}$$

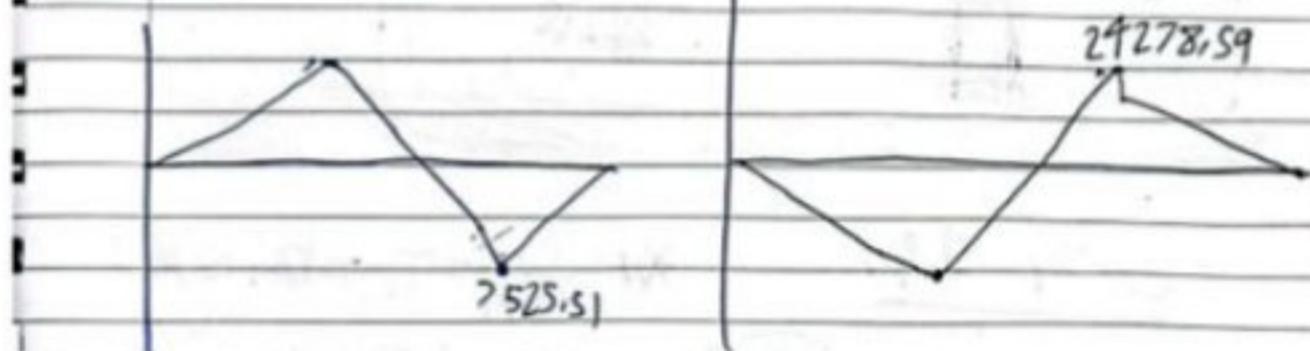
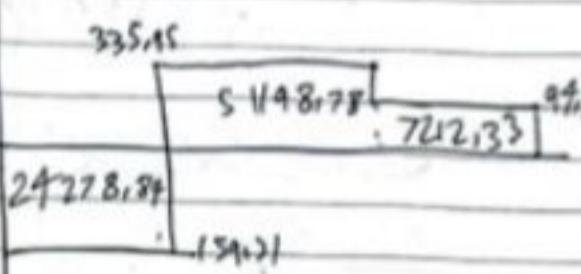
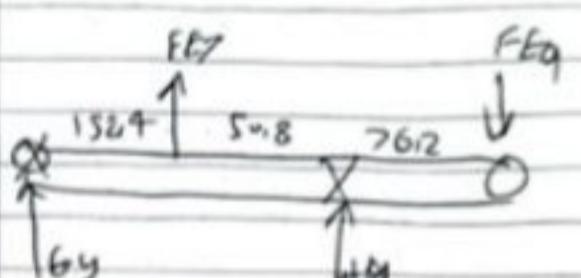
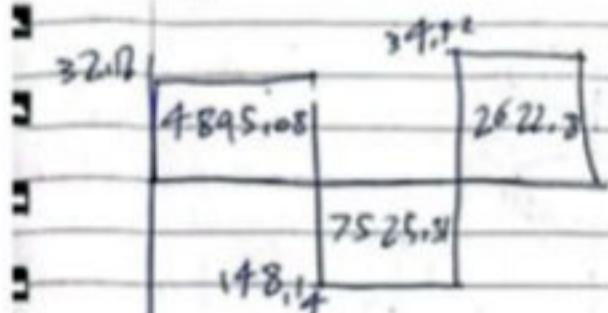
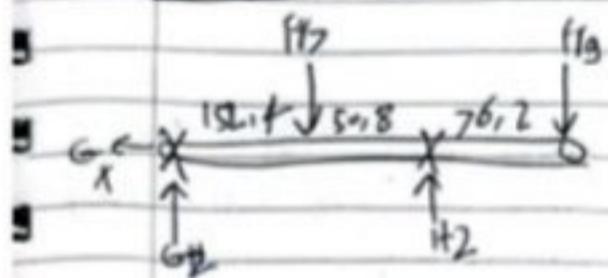
$$A = 2 \times F_m g = 46147.930 \text{ Nmm}$$

$$B = \sqrt{3} F_m g = 133243.2045 \mu\text{Nm}$$

$$d = \left[\frac{B}{T} \left(\frac{A}{S_1} + \frac{B}{S_2} \right) \right]^{\frac{1}{3}} = 15.62 \text{ mm}$$

for safety = 20 mm

G H shaft



$$m = \sqrt{7525.31^2 + 24278.59^2} = 25418.16 \text{ N-mm}$$

$$T = 241.09 \text{ N-m}$$

$$A = 2 \text{ KF ma} = 81338.122 \text{ N-mm}$$

$$B = \sqrt{KFT} = 66621.6 \text{ N-mm}$$

$$d = \left[\frac{64}{T} \left(\frac{A}{se} + \frac{B}{sm} \right) \right]^{1/3} = 16.13 \text{ mm}$$

For safety it will be 20 mm ~~ff~~

Relevant tables used in the calculations

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Appendix C ■ Material Properties and Uses

Appendix C-2 Tensile Properties of Some Metals

Material	Ultimate Strength, S_u		Yield Strength, S_y		σ_0^2		m^2	e_b
	ksi	MPa	ksi	MPa	ksi	MPa		
Carbon and alloy steels								
1002 A ^b	42	290	19	131	78	538	0.27	1.25
1010 A	44	303	29	200	82	565	0.23	1.29
1018 A	49.5	341	32	225	90	621	0.25	1.05
1020 HR ^c	66	455	42	290	115	793	0.22	0.91
1045 HR	92.5	638	60	414	140	965	0.14	0.58
1212 HR	61.5	424	28	193	110	758	0.24	0.85
4340 HR	151	1041	132	910	210	1448	0.09	0.45
52100 A	167	1151	131	903	210	1448	0.07	0.40
Stainless steels								
302 A	92	634	34	234	210	1448	0.48	1.29
303 A	87	600	35	241	205	1413	0.51	1.16
304 A	83	572	40	276	185	1276	0.45	1.07
440C A	117	807	67	462	180	1241	0.14	0.12
Aluminum alloys								
1100-O	12	83	4.5	31	22	152	0.25	2.30
2024-T4	65	448	43	296	100	690	0.15	0.18
7075-O	34	234	14.3	99	61	421	0.22	0.53
7075-T6	86	593	78	538	128	883	0.13	0.18
Magnesium alloys								
HK31XA-O	25.5	176	19	131	49.5	341	0.22	0.33
HK31XA-H24	36.2	250	31	214	48	331	0.08	0.20
Copper alloys								
90-10 Brass A	36.4	251	8.4	58	83	572	0.46	—
80-20 Brass A	35.8	247	7.2	50	84	579	0.48	—
70-30 Brass A	44	303	10.5	72	105	724	0.52	1.55
Naval Brass A	54.5	376	17	117	125	862	0.48	1.00

^aDefined in Section 3.4.

^bA = annealed, HR = hot-rolled.

Note: Values are from single tests and believed typical. Actual values may vary through small differences in composition and processing; hence, some values here do not agree with values in other Appendix C tables.

Source: J. Datsko, *Materials in Design and Manufacturing*, Mallory, Inc., Ann Arbor, Mich. 1977.

Appendix C-8 Mechanical Properties of Some Wrought Stainless Steels (Approximate Median Expectations)

AISI Type	Ultimate Strength, S_u (ksi)			Yield Strength S_y (ksi)			Elongation (%)			Izod Impact (ft-lb)			Drawability	Machinability	Weldability	Typical Uses
	An.	CW	H&T	An.	CW	H&T	An.	CW	H&T	An.	CW	H&T				
Austenitic																
302	85	110		35	75		60	35		110	90		VG	P	G	General purpose; springs
303	90	110		35	80		50	22		85	35		G	G	P	Bolts, nuts, rivets, aircraft fittings
304	85	110		35	75		60	55		110	90		VG	P	G	General purpose; welded construction
310, 310S	95			45			50			110			G	P	G	Turbine, furnace, heat exchanger parts
347, 348	90	110		35	65		50	40		110			VG	P	G	Jet engine, nuclear energy parts
384 (wire)	75			35			55						E			Severely cold-worked parts; fasteners
Martensitic																
410	75	105	115	40	85	85	35	17	23	90	75	80	F	F-	F	Machine parts, shafts, bolts, cutlery
414	115	130 ^a	160	90	110 ^a	125	20	15 ^b	17	50	45		F	F		Machine parts, springs, bolts, cutlery
416, 416Se	75	100 ^b	110	40	85 ^b	85	30	13 ^b	18	70	20 ^b	25	P	G	P	Cutlery, fasteners, tools, screw machine parts
431	125	130 ^b	165	95	110 ^b	125	20	15 ^b	17	50	40		P-	F		High-strength bolts, aircraft fittings
440 A,B,C	105	115 ^a	260	60	90 ^a	240	14	7 ^a	3	2	2 ^a	2	VP	P		Balls, bearing parts, nozzles, cutlery (highest H&T hardness of any stainless)
Ferritic																
430, 430F	75	83		43	63		27	20					G	F-G	F	Decorative trim, mufflers, screw machine parts
446	83	85		53	70		23	20		2			P	F	F	Parts subjected to high-temperature corrosion

^aAnnealed and cold-drawn.^bTempered and cold-drawn.

Note: An., CW, H&T mean annealed, cold-worked, and hardened and tempered, respectively.

E, VG, G, F, P, VP mean excellent, very good, good, fair, poor, very poor, respectively.

Sources: *Metals Progress Databook 1980*, American Society for Metals, Metals Park, Ohio, Vol. 118, No. 1 (mid-June 1980); *ASME Handbook Metal Properties*, McGraw-Hill, New York, 1954; *Materials Engineering*, 1981 Materials Selector Issue, Penton/IPC, Cleveland, Vol. 92, No. 6 (Dec. 1980); *Machine Design*, 1981 Materials Reference Issue, Penton/IPC, Cleveland, Vol. 53, No. 6 (March 19, 1981).**TABLE 14.1** Bearing Dimensions

Bearing Basic Number	Bore (mm)	Ball Bearings						Roller Bearings					
		OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)	OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)		
L00	10	26	8	0.30	12.7	23.4							
200	10	30	9	0.64	13.8	26.7							
300	10	35	11	0.64	14.8	31.2							
L01	12	28	8	0.30	14.5	25.4							
201	12	32	10	0.64	16.2	28.4							
301	12	37	12	1.02	17.7	32.0							
L02	15	32	9	0.30	17.5	29.2							
202	15	35	11	0.64	19.0	31.2							
302	15	42	13	1.02	21.2	36.6							

Extra Light Series

Light Series

Medium Series

(continued)

TABLE 14.1 Bearing Dimensions (*continued*)

Bearing Basic Number	Ball Bearings						Roller Bearings					
	Bore (mm)	OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)	OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)	
L03	17	35	10	0.30	19.8	32.3	35	10	0.64	20.8	32.0	
203	17	40	12	0.64	22.4	34.8	40	12	0.64	20.8	36.3	
303	17	47	14	1.02	23.6	41.1	47	14	1.02	22.9	41.4	
L04	20	42	12	0.64	23.9	38.1	42	12	0.64	24.4	36.8	
204	20	47	14	1.02	25.9	41.7	47	14	1.02	25.9	42.7	
304	20	52	15	1.02	27.7	45.2	52	15	1.02	25.9	46.2	
L05	25	47	12	0.64	29.0	42.9	47	12	0.64	29.2	43.4	
205	25	52	15	1.02	30.5	46.7	52	15	1.02	30.5	47.0	
305	25	62	17	1.02	33.0	54.9	62	17	1.02	31.5	55.9	
L06	30	55	13	1.02	34.8	49.3	47	9	0.38	33.3	43.9	
206	30	62	16	1.02	36.8	55.4	62	16	1.02	36.1	56.4	
306	30	72	19	1.02	38.4	64.8	72	19	1.52	37.8	64.0	
L07	35	62	14	1.02	40.1	56.1	55	10	0.64	39.4	50.8	
207	35	72	17	1.02	42.4	65.0	72	17	1.02	41.7	65.3	
307	35	80	21	1.52	45.2	70.4	80	21	1.52	43.7	71.4	

TABLE 14.1 Bearing Dimensions (*continued*)

Bearing Basic Number	Ball Bearings						Roller Bearings					
	Bore (mm)	OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)	OD (mm)	w (mm)	r^a (mm)	d_S (mm)	d_H (mm)	
L08	40	68	15	1.02	45.2	62.0	68	15	1.02	45.7	62.7	
208	40	80	18	1.02	48.0	72.4	80	18	1.52	47.2	72.9	
308	40	90	23	1.52	50.8	80.0	90	23	1.52	49.0	81.3	
L09	45	75	16	1.02	50.8	68.6	75	16	1.02	50.8	69.3	
209	45	85	19	1.02	52.8	77.5	85	19	1.52	52.8	78.2	
309	45	100	25	1.52	57.2	88.9	100	25	2.03	55.9	90.4	
L10	50	80	16	1.02	55.6	73.7	72	12	0.64	54.1	68.1	
210	50	90	20	1.02	57.7	82.3	90	20	1.52	57.7	82.8	
310	50	110	27	2.03	64.3	96.5	110	27	2.03	61.0	99.1	
L11	55	90	18	1.02	61.7	83.1	90	18	1.52	62.0	83.6	
211	55	100	21	1.52	65.0	90.2	100	21	2.03	64.0	91.4	
311	55	120	29	2.03	69.8	106.2	120	29	2.03	66.5	108.7	

TABLE 14.1 Bearing Dimensions (*continued*)

Bearing Basic Number	Ball Bearings						Roller Bearings					
	Bore (mm)	OD (mm)	w (mm)	r ^a (mm)	d _S (mm)	d _H (mm)	OD (mm)	w (mm)	r ^a (mm)	d _S (mm)	d _H (mm)	
L12	60	95	18	1.02	66.8	87.9	95	18	1.52	67.1	88.6	
212	60	110	22	1.52	70.6	99.3	110	22	2.03	69.3	101.3	
312	60	130	31	2.03	75.4	115.6	130	31	2.54	72.9	117.9	
L13	65	100	18	1.02	71.9	92.7	100	18	1.52	72.1	93.7	
213	65	120	23	1.52	76.5	108.7	120	23	2.54	77.0	110.0	
313	65	140	33	2.03	81.3	125.0	140	33	2.54	78.7	127.0	
L14	70	110	20	1.02	77.7	102.1	110	20	Not Available			
214	70	125	24	1.52	81.0	114.0	125	24	2.54	81.8	115.6	
314	70	150	35	2.03	86.9	134.4	150	35	3.18	84.3	135.6	
L15	75	115	20	1.02	82.3	107.2	115	20	Not Available			
215	75	130	25	1.52	86.1	118.9	130	25	2.54	85.6	120.1	
315	75	160	37	2.03	92.7	143.8	160	37	3.18	90.4	145.8	

TABLE 14.1 Bearing Dimensions (*continued*)

Bearing Basic Number	Ball Bearings						Roller Bearings					
	Bore (mm)	OD (mm)	w (mm)	r ^a (mm)	d _S (mm)	d _H (mm)	OD (mm)	w (mm)	r ^a (mm)	d _S (mm)	d _H (mm)	
L16	80	125	22	1.02	88.1	116.3	125	22	2.03	88.4	117.6	
216	80	140	26	2.03	93.2	126.7	140	26	2.54	91.2	129.3	
316	80	170	39	2.03	98.6	152.9	170	39	3.18	96.0	154.4	
L17	85	130	22	1.02	93.2	121.4	130	22	2.03	93.5	122.7	
217	85	150	28	2.03	99.1	135.6	150	28	3.18	98.0	139.2	
317	85	180	41	2.54	105.7	160.8	180	41	3.96	102.9	164.3	
L18	90	140	24	1.52	99.6	129.0	140	24	Not Available			
218	90	160	30	2.03	104.4	145.5	160	30	3.18	103.1	147.6	
318	90	190	43	2.54	111.3	170.2	190	43	3.96	108.2	172.7	
L19	95	145	24	1.52	104.4	134.1	145	24	Not Available			
219	95	170	32	2.03	110.2	154.9	170	32	3.18	109.0	157.0	
319	95	200	45	2.54	117.3	179.3	200	45	3.96	115.1	181.9	
L20	100	150	24	1.52	109.5	139.2	150	24	2.54	109.5	141.7	
220	100	180	34	2.03	116.1	164.1	180	34	3.96	116.1	167.1	
320	100	215	47	2.54	122.9	194.1	215	47	4.75	122.4	194.6	

TABLE 14.2 Bearing Rated Capacities, C , for $L_R = 90 \times 10^6$
Revolution Life with 90 Percent Reliability

Bore (mm)	Radial Ball, $\alpha = 0^\circ$			Angular Ball, $\alpha = 25^\circ$			Roller		
	L00 Xlt (kN)	200 lt (kN)	300 med (kN)	L00 Xlt (kN)	200 lt (kN)	300 med (kN)	1000 Xlt (kN)	1200 lt (kN)	1300 med (kN)
10	1.02	1.42	1.90	1.02	1.10	1.88			
12	1.12	1.42	2.46	1.10	1.54	2.05			
15	1.22	1.56	3.05	1.28	1.66	2.85			
17	1.32	2.70	3.75	1.36	2.20	3.55	2.12	3.80	4.90
20	2.25	3.35	5.30	2.20	3.05	5.80	3.30	4.40	6.20
25	2.45	3.65	5.90	2.65	3.25	7.20	3.70	5.50	8.50
30	3.35	5.40	8.80	3.60	6.00	8.80	2.40 ^a	8.30	10.0
35	4.20	8.50	10.6	4.75	8.20	11.0	3.10 ^a	9.30	13.1
40	4.50	9.40	12.6	4.95	9.90	13.2	7.20	11.1	16.5
45	5.80	9.10	14.8	6.30	10.4	16.4	7.40	12.2	20.9
50	6.10	9.70	15.8	6.60	11.0	19.2	5.10 ^a	12.5	24.5
55	8.20	12.0	18.0	9.00	13.6	21.5	11.3	14.9	27.1

TABLE 14.2 Bearing Rated Capacities, C , for $L_R = 90 \times 10^6$
Revolution Life with 90 Percent Reliability

Bore (mm)	Radial Ball, $\alpha = 0^\circ$			Angular Ball, $\alpha = 25^\circ$			Roller		
	L00 Xlt (kN)	200 lt (kN)	300 med (kN)	L00 Xlt (kN)	200 lt (kN)	300 med (kN)	1000 Xlt (kN)	1200 lt (kN)	1300 med (kN)
60	8.70	13.6	20.0	9.70	16.4	24.0	12.0	18.9	32.5
65	9.10	16.0	22.0	10.2	19.2	26.5	12.2	21.1	38.3
70	11.6	17.0	24.5	13.4	19.2	29.5		23.6	44.0
75	12.2	17.0	25.5	13.8	20.0	32.5		23.6	45.4
80	14.2	18.4	28.0	16.6	22.5	35.5	17.3	26.2	51.6
85	15.0	22.5	30.0	17.2	26.5	38.5	18.0	30.7	55.2
90	17.2	25.0	32.5	20.0	28.0	41.5		37.4	65.8
95	18.0	27.5	38.0	21.0	31.0	45.5		44.0	65.8
100	18.0	30.5	40.5	21.5	34.5		20.9	48.0	72.9
105	21.0	32.0	43.5	24.5	37.5			49.8	84.5
110	23.5	35.0	46.0	27.5	41.0	55.0	29.4	54.3	85.4
120	24.5	37.5		28.5	44.5			61.4	100.1

The diagram illustrates two types of keyways:

- Sled-runner keyway:** Shows a rectangular slot with rounded ends. A gear is shown meshing with a sprocket, which is mounted on a shaft with a sled-runner keyway.
- Profiled keyway:** Shows a slot with a semi-circular profile. A gear is shown meshing with a sprocket, which is mounted on a shaft with a profiled keyway.

Steel	Fatigue stress concentration factor, K_f			
	Bending	Torsion	Bending	Torsion
Annealed (less than 200 Bhn)	1.3	1.3	1.6	1.3
Quenched and drawn (over 200 Bhn)	1.6	1.6	2.0	1.6

FIGURE 17.9

Keyway types and corresponding fatigue stress concentration factors K_f . (Base nominal stress on total shaft section.)

Belt analysis

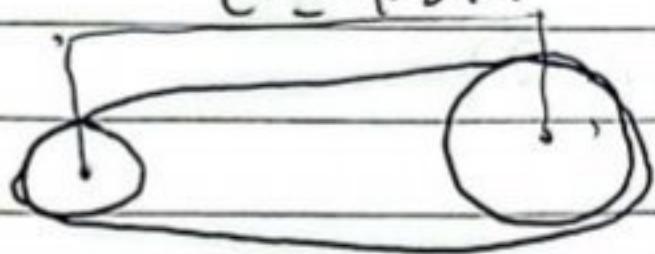
No. _____

Date _____

Mazen Omar

First belt

$$C' = 9.8 \text{ in}$$



SR=2 assume

$$H_T = 4.023$$

Power coming

from the motor

assuming the

same power will

be transmit if

the power is from

the table we choose

our motor from

C' = 9.8 in } so we secure that
it is in the center

$$H_d = H_T + k_s$$

$$k_s = k_0 + k_i + k_e$$

K₀ = light duty Ac motor with 4 hr/day

$$k_0 = 1$$

$$k_i = 0 \text{ no idler}$$

$$k_e = \text{dusty environment} = 0.2$$

$$k_s = 1.2$$

$$H_d = 4.023 \times 1.2 = 4.83 \text{ hp}$$

RPM of the pulley = 2672

table 1-1 $H_d = 4.83$ with small pulley = 2672 rpm

Type A

Pully size = 3 in diameter diameter dd

$$D_B d = SR \times dd = 2 \times 3 = 6 \text{ in}$$

$$l_d' = 2C' + 1.57(D_d + dd) = 2(9.8) + 1.57(6+3) = 33.73 \text{ in}$$

$$l_d = 33.73 \text{ in from table 1-9}$$

$$l_d = 34.3 \text{ in Belt code 33}$$

A 33

$$b = 2l_d - \pi (D_2 + d_2) = 2(34.3) - \pi (6+3) = 40.325$$

$$C = \frac{b + \sqrt{b^2 - 8(D_2 - d_2)^2}}{8}$$

$$C = \frac{40.326 + \sqrt{40.326^2 - 8(6-3)^2}}{8}$$

$$C = 9.968 \text{ in}$$

$$n_b = \frac{H_d}{H_C} \quad H_C = (H_S + H_a) \times k_C$$

$$k_C = k_0 \times k_f$$

table 1-15

f

$$H_S = 2.06 \quad H_a = 0.745 \quad k_0 = 0.96 \quad \text{table 1-6}$$

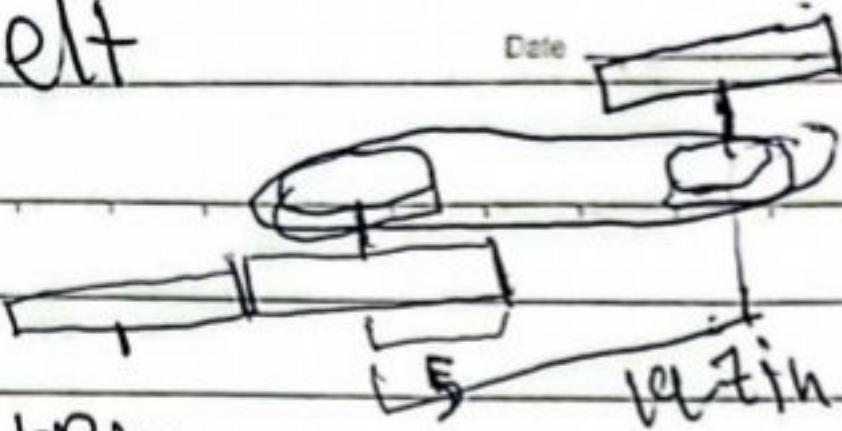
$$\frac{D_2 - d_2}{C} = \frac{6-3}{9.968} = 0.3$$

$$k_f = 0.85 \text{ table 1-7}$$

$$H_C = (2.06 + 0.745)(0.85 \times 0.96) = 2.288$$

$$n_b = \frac{4.83}{2.288} = 2.11 \approx 3 \text{ belts or } \boxed{A 33}$$

for the second belt



$$C = 19.7 \text{ in}$$

Small pulley speed = 2672 rpm

$H_2 = 4.83 \text{ hp}$ same as the first belt

Type A due to same H_2 and speed

with the first belt as well as same D_2, d_2

$$l_d' = 2C' + 1.57(D_2 + d_2) = 2 \times 19.7 + 1.57(6 + 3)$$

$$l_d' = 53.53 \text{ in}$$

$$l_d = 54.3 \quad \text{belt code A53}$$

$$b = 2 \times 54.3 - 11(6 + 3) = 80.32$$

$$C = \frac{80.32 + \sqrt{80.32^2 - 8(6+3)^2}}{8} = 20.025 \text{ in}$$

$$n_b = \frac{l+d}{4C} \quad H_s = 2.06 \quad H_a = 0.745$$

$$\frac{6+3}{20.025} = 0.149$$

$$k_B = 0.97 \quad k_f = 0.94$$

$$H_C = (2.06 + 0.745)(0.97 \times 0.94)$$

$$n_b = \frac{4.83}{2.58} \quad H_C = 2.56$$

$$n_b = 1.88 \approx 2 \text{ belt or A53}$$

Gear ratio from input to output

Gear

Pitch diameters:

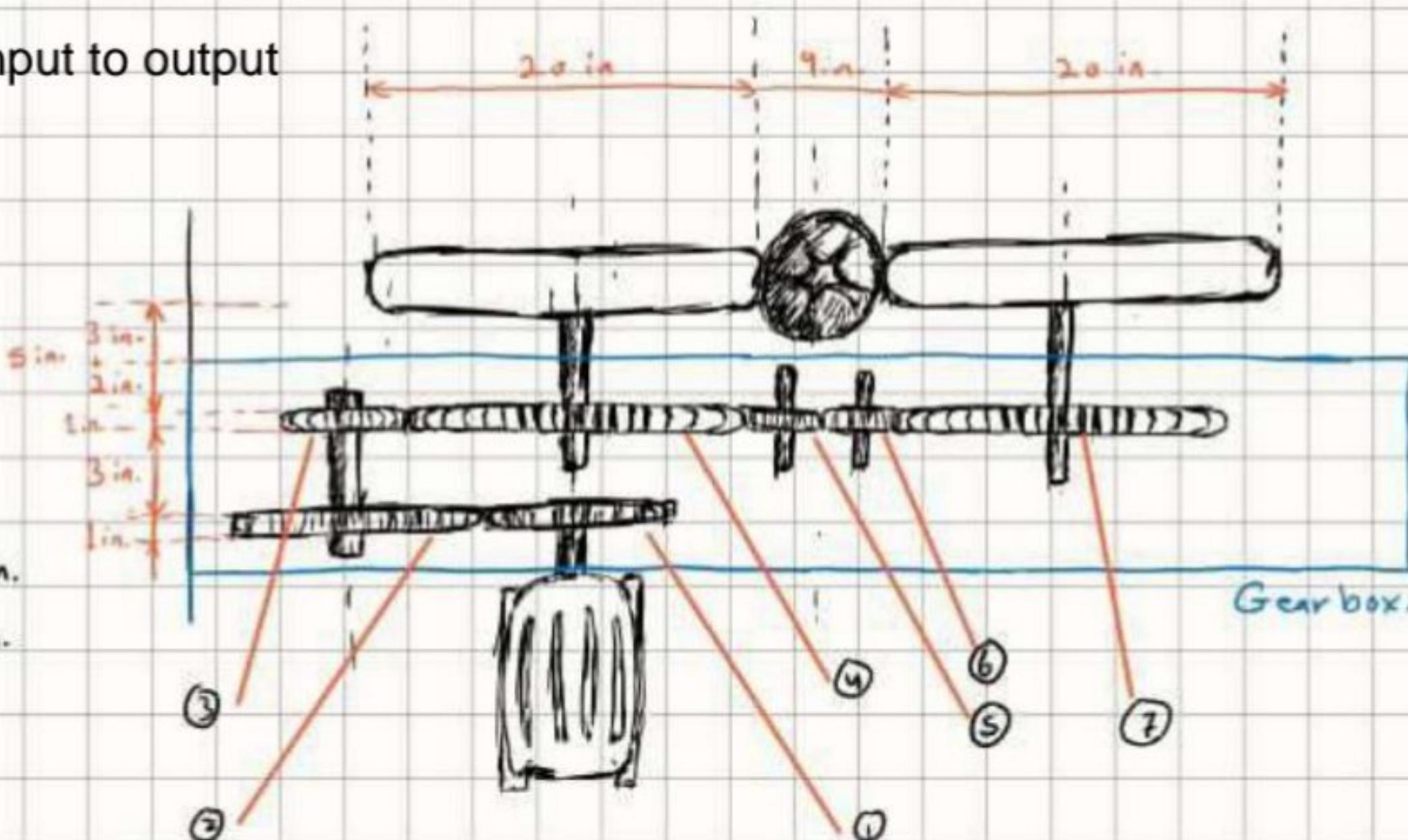
$$d_1 = 9.4 \text{ in.}$$

$$d_2 = 10.2 \text{ in.}$$

$$d_3 = 1 \text{ in.}$$

$$d_4 = d_7 = 18.6 \text{ in.}$$

$$d_5 = d_6 = 5.4 \text{ in.}$$



Gear Number

or Teeth:

$$n_1 = 47$$

$$n_2 = 51$$

$$n_3 = 5$$

$$n_4 = n_7 = 93$$

$$n_5 = n_6 = 27$$

Gear ratio:

$$\frac{n_1}{n_2} \times \frac{n_3}{n_4} \times \frac{D_4}{n_5} \times \frac{n_5}{n_6} \times \frac{n_6}{n_7}$$

$$n_2 = n_3 \\ n_5 \text{ and } n_6 \text{ idler}$$

$$= \frac{n_1}{n_7} = \frac{2900}{1465} = 1.9722$$

Schematic drawing to show the final configuration of the gear box

Gear

Pitch diameters :

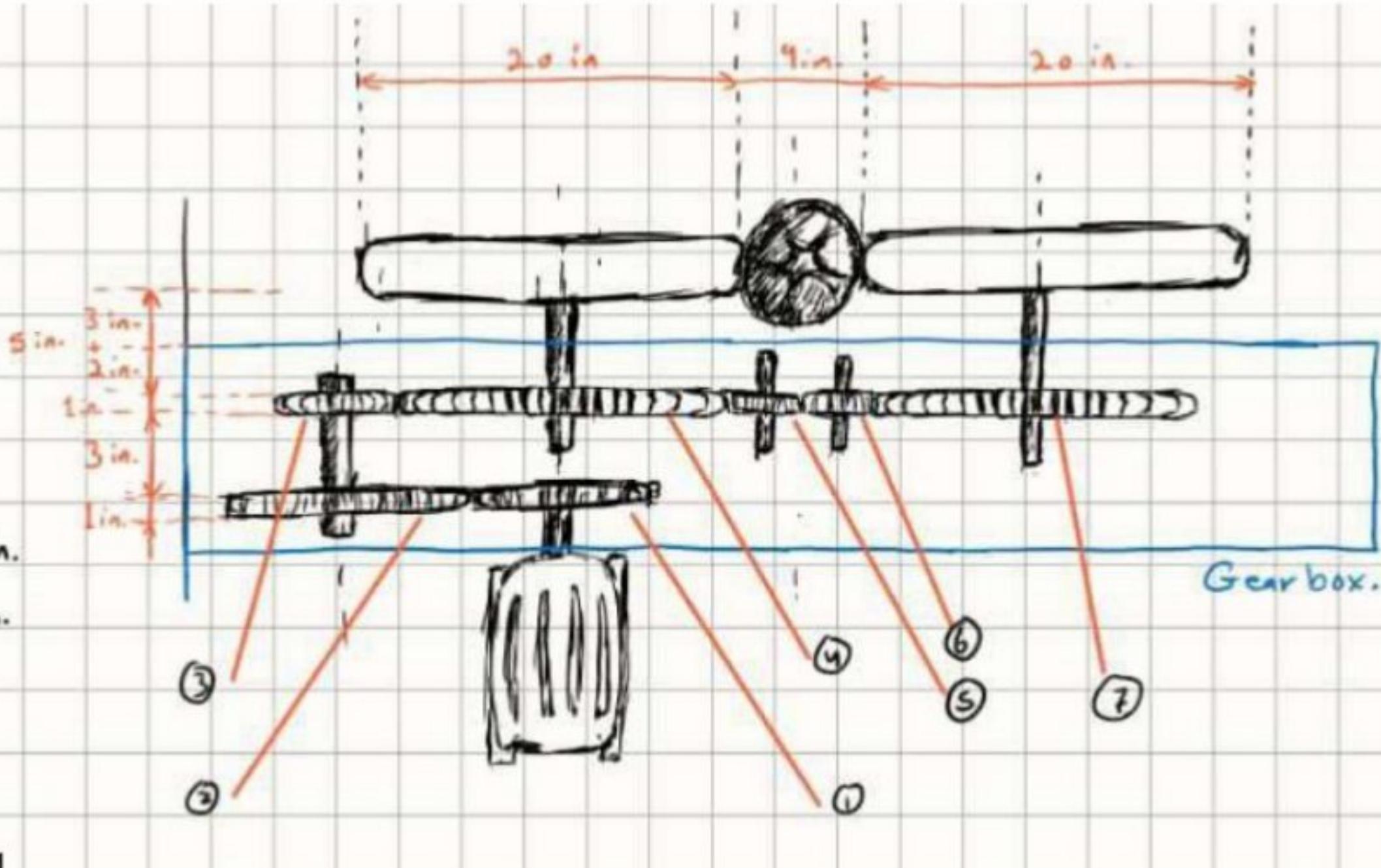
$$d_1 = 9.4 \text{ in.}$$

$$d_2 = 10.2 \text{ in.}$$

$$d_3 = 1 \text{ in.}$$

$$d_4 = d_7 = 18.6 \text{ in.}$$

$$d_5 = d_6 = 5.4 \text{ in.}$$



Gear Number

of Teeth :

$$n_1 = 47$$

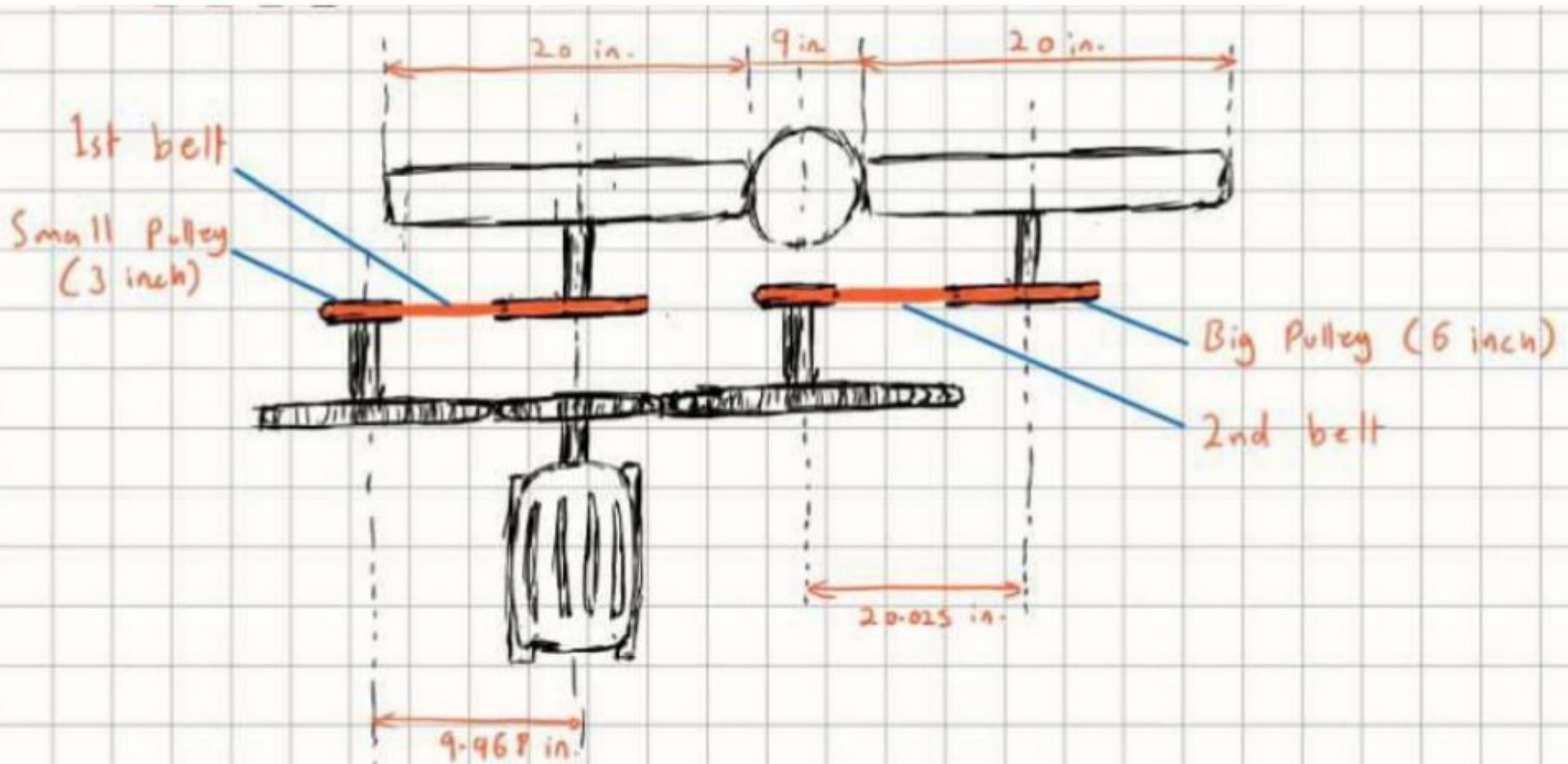
$$n_2 = 51$$

$$n_3 = 5$$

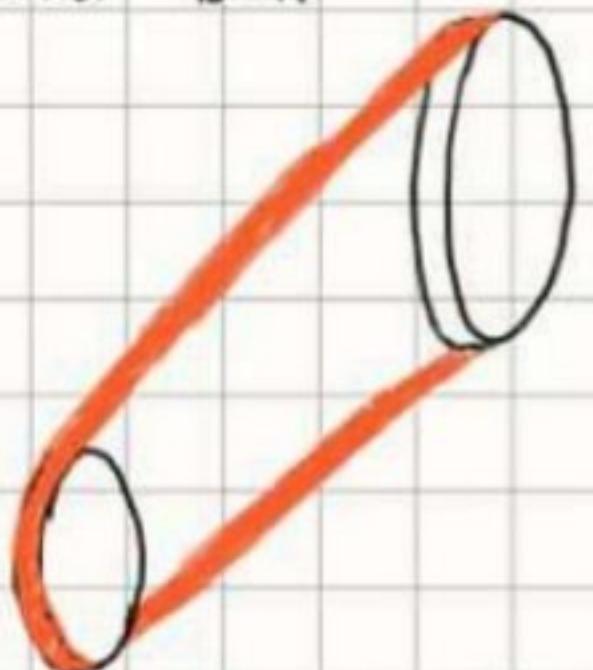
$$n_4 = n_7 = 93$$

$$n_5 = n_6 = 27$$

Mazen drawing



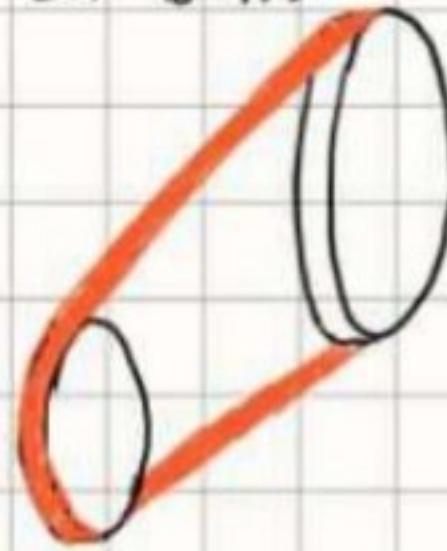
2nd Belt



Belt Type A

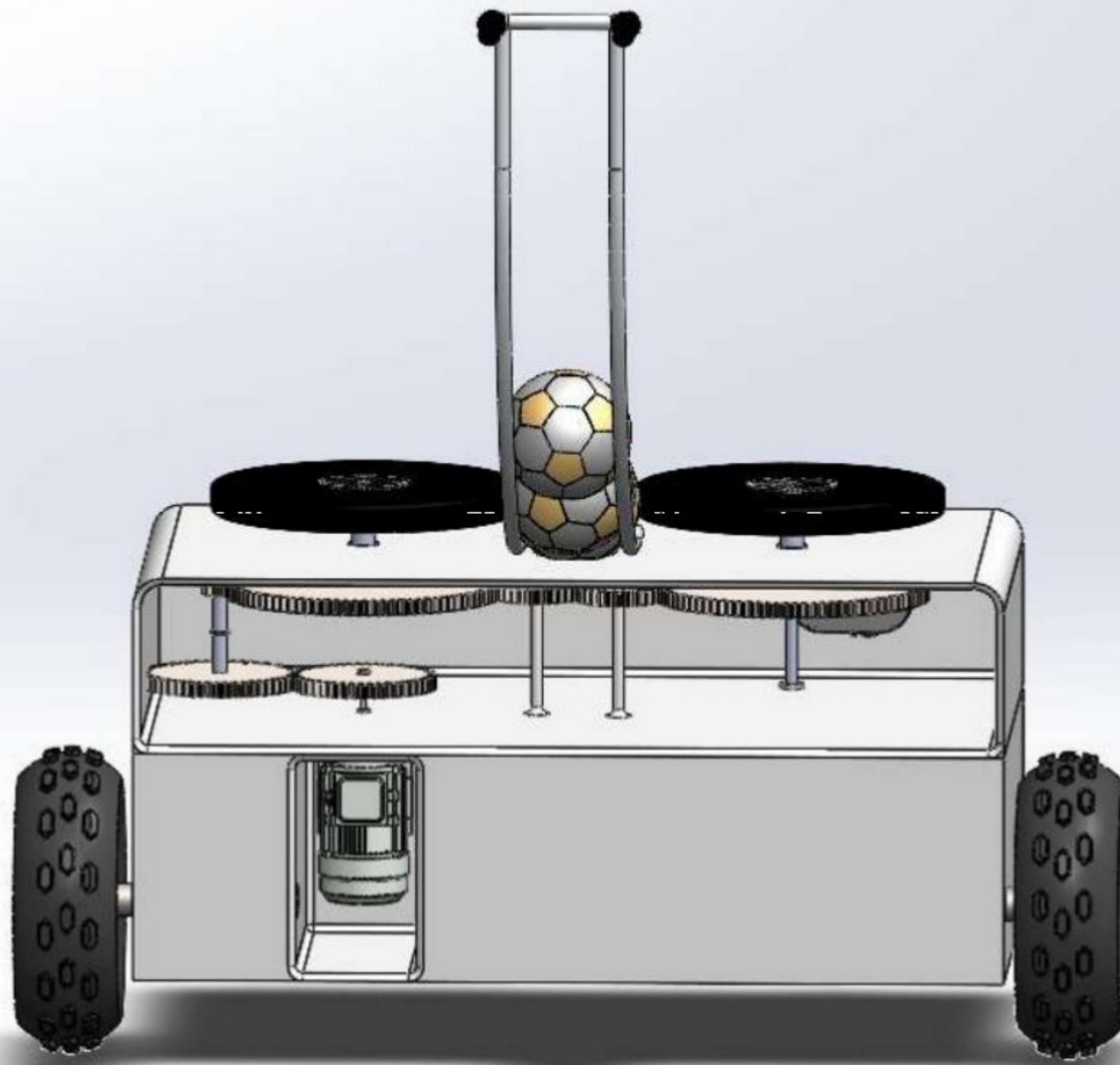
$$\text{Thickness, } t = 0.5 \times 2 \\ = 1 \text{ in.}$$

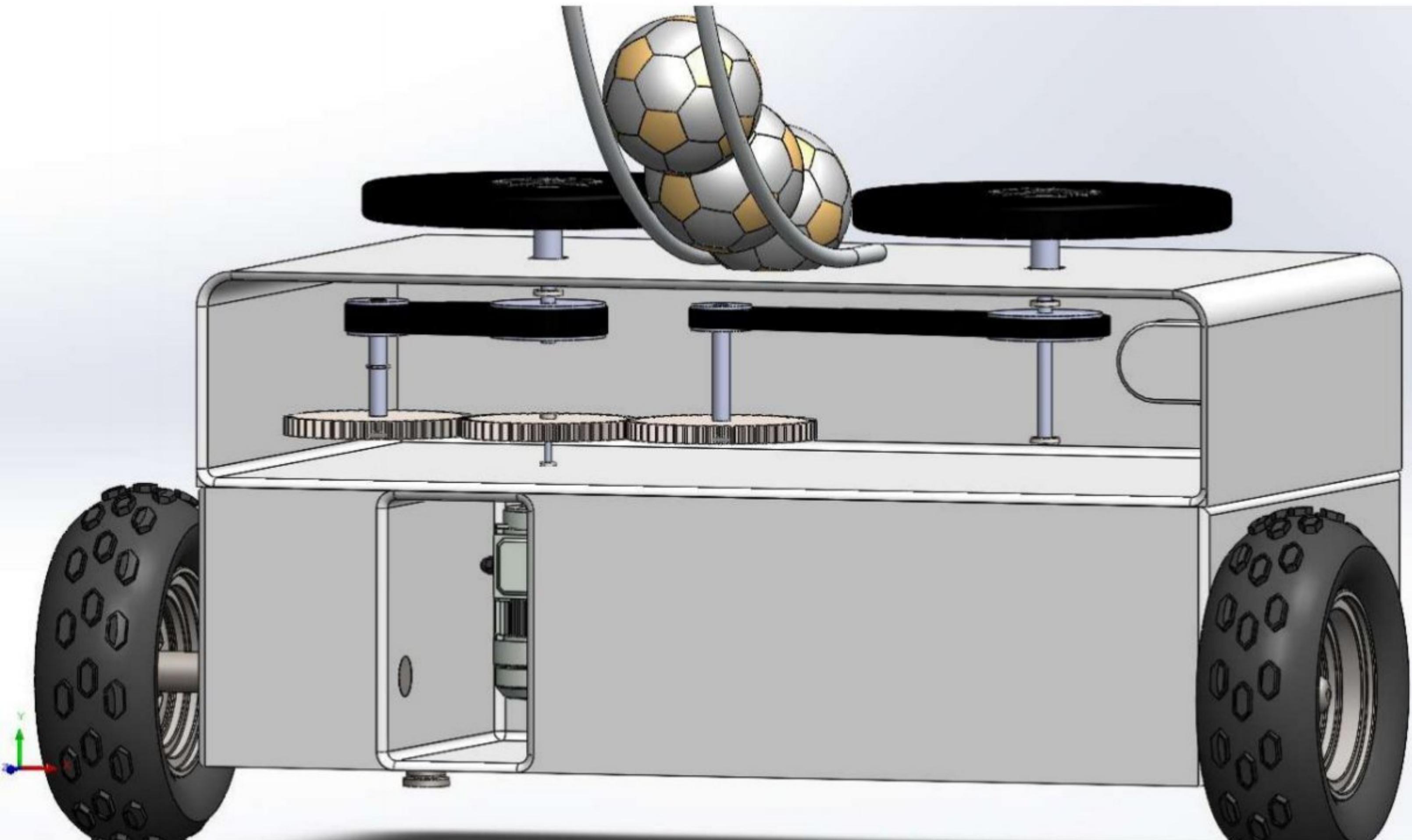
1st Belt:

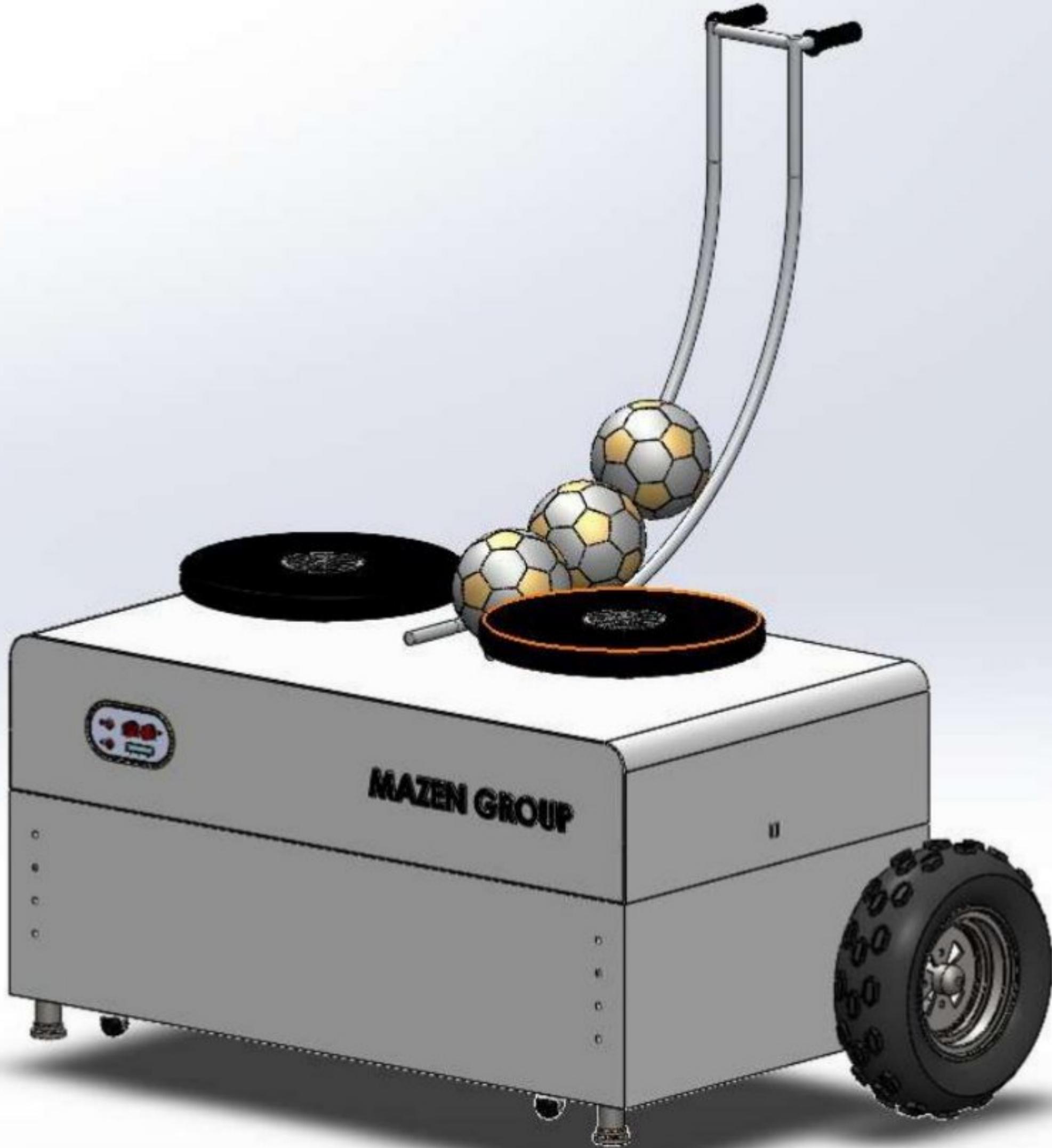


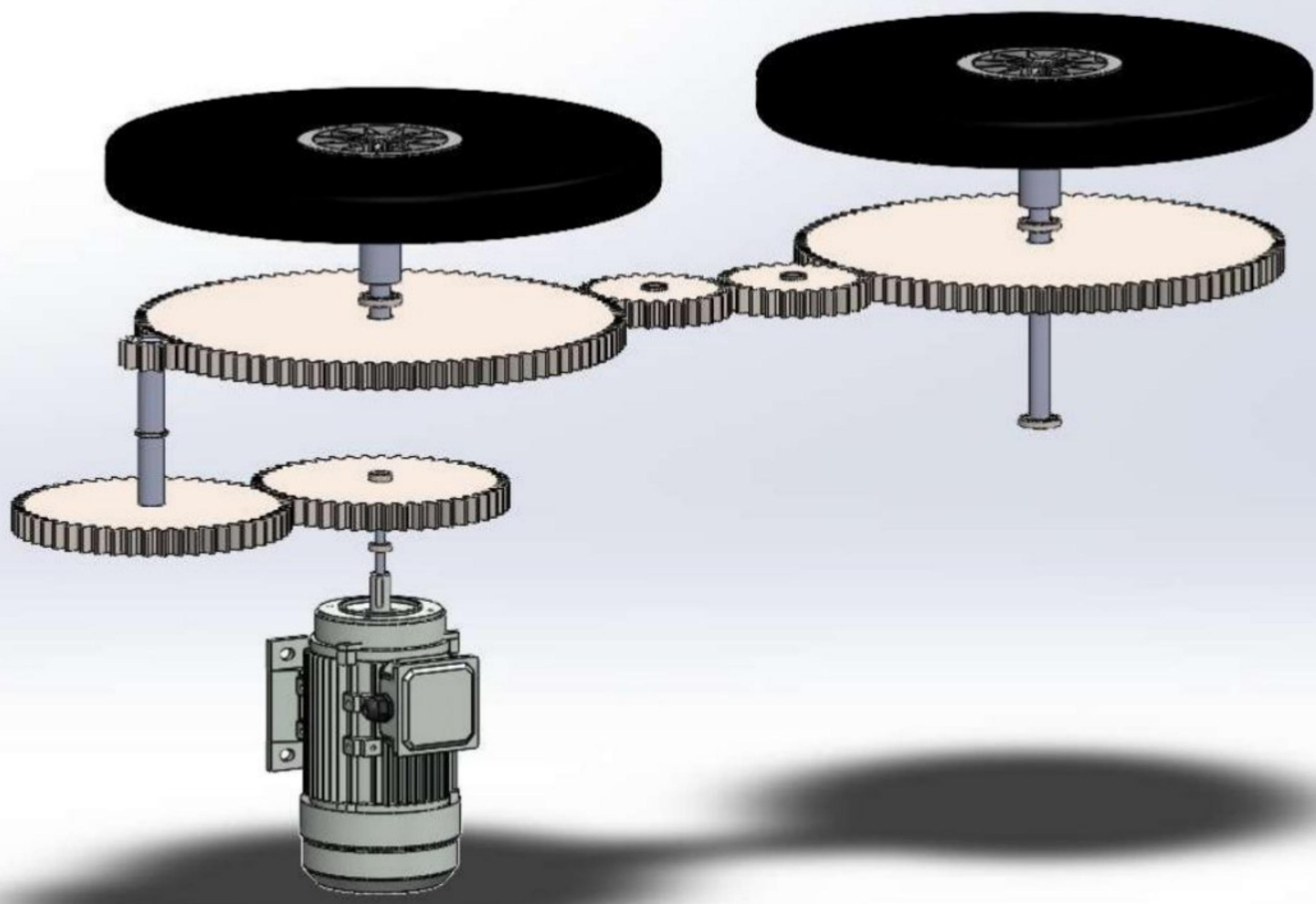
Belt Type A

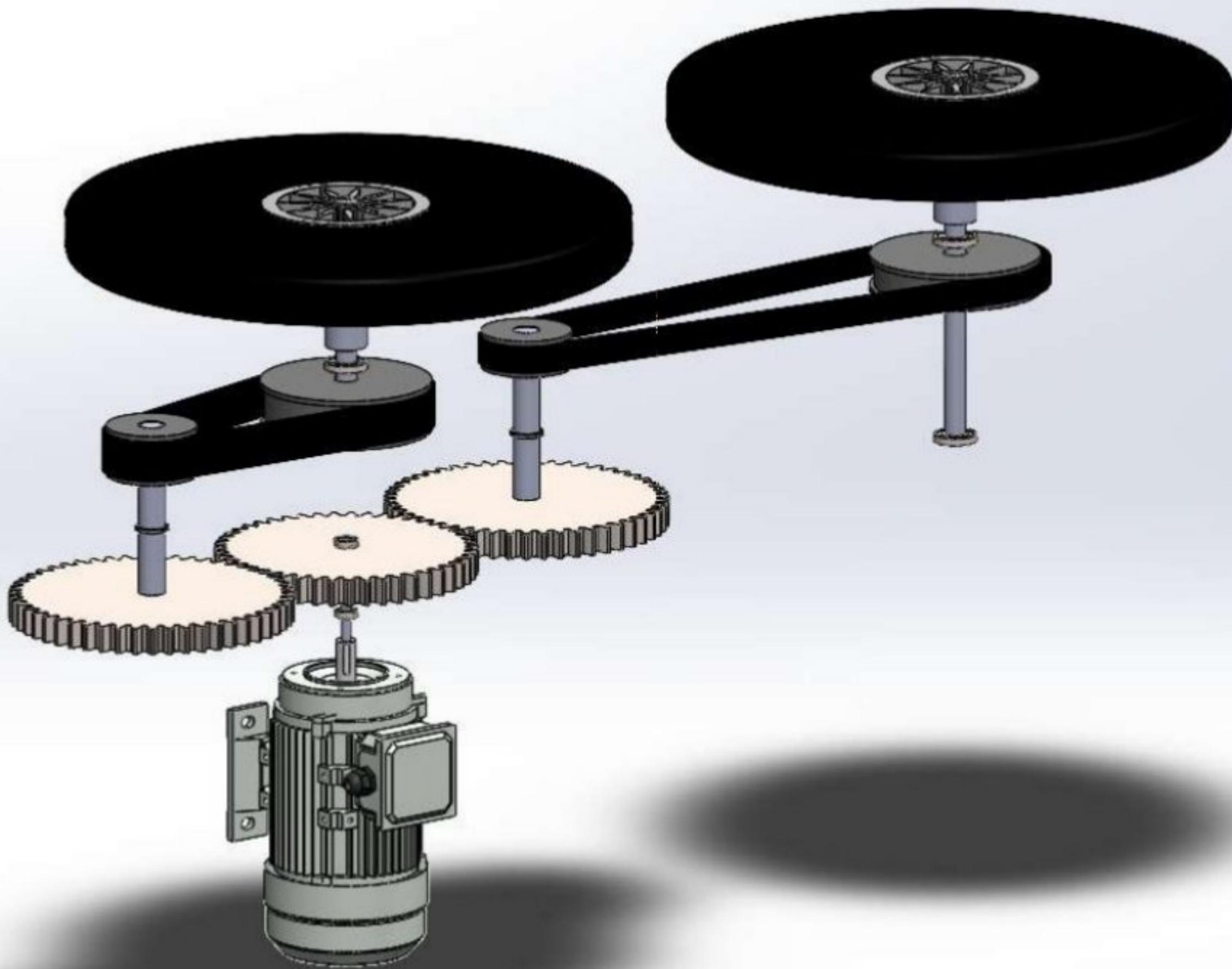
$$\text{Thickness, } t = 0.5 \times 3 \\ = 1.5 \text{ in.}$$

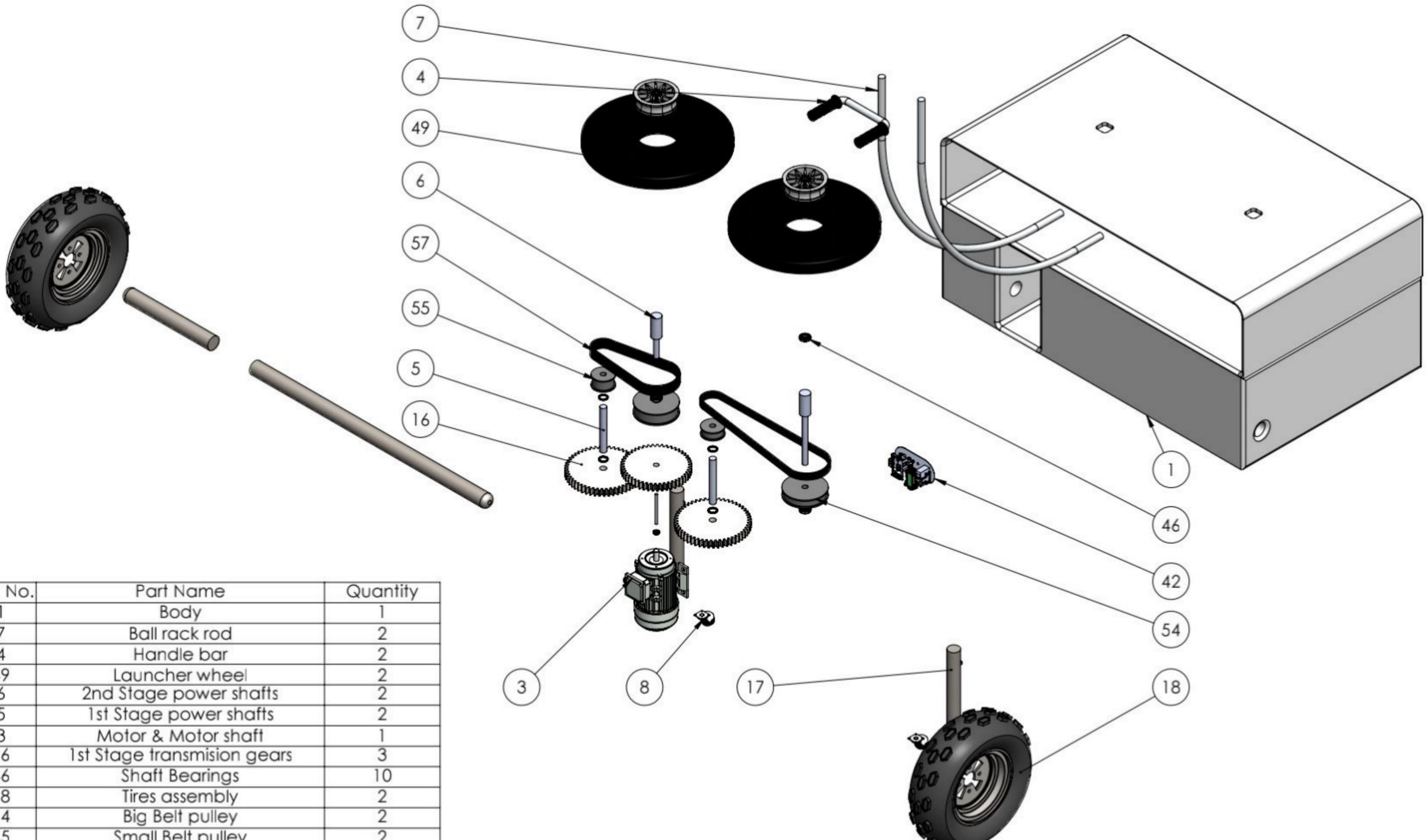












Part No.	Part Name	Quantity
1	Body	1
7	Ball rack rod	2
4	Handle bar	2
49	Launcher wheel	2
6	2nd Stage power shafts	2
5	1st Stage power shafts	2
3	Motor & Motor shaft	1
16	1st Stage transmission gears	3
46	Shaft Bearings	10
18	Tires assembly	2
54	Big Belt pulley	2
55	Small Belt pulley	2
42	Controller Unit	1
8	Front 360 rollers	2
17	Recliner Shafts	2
57	Belts	2



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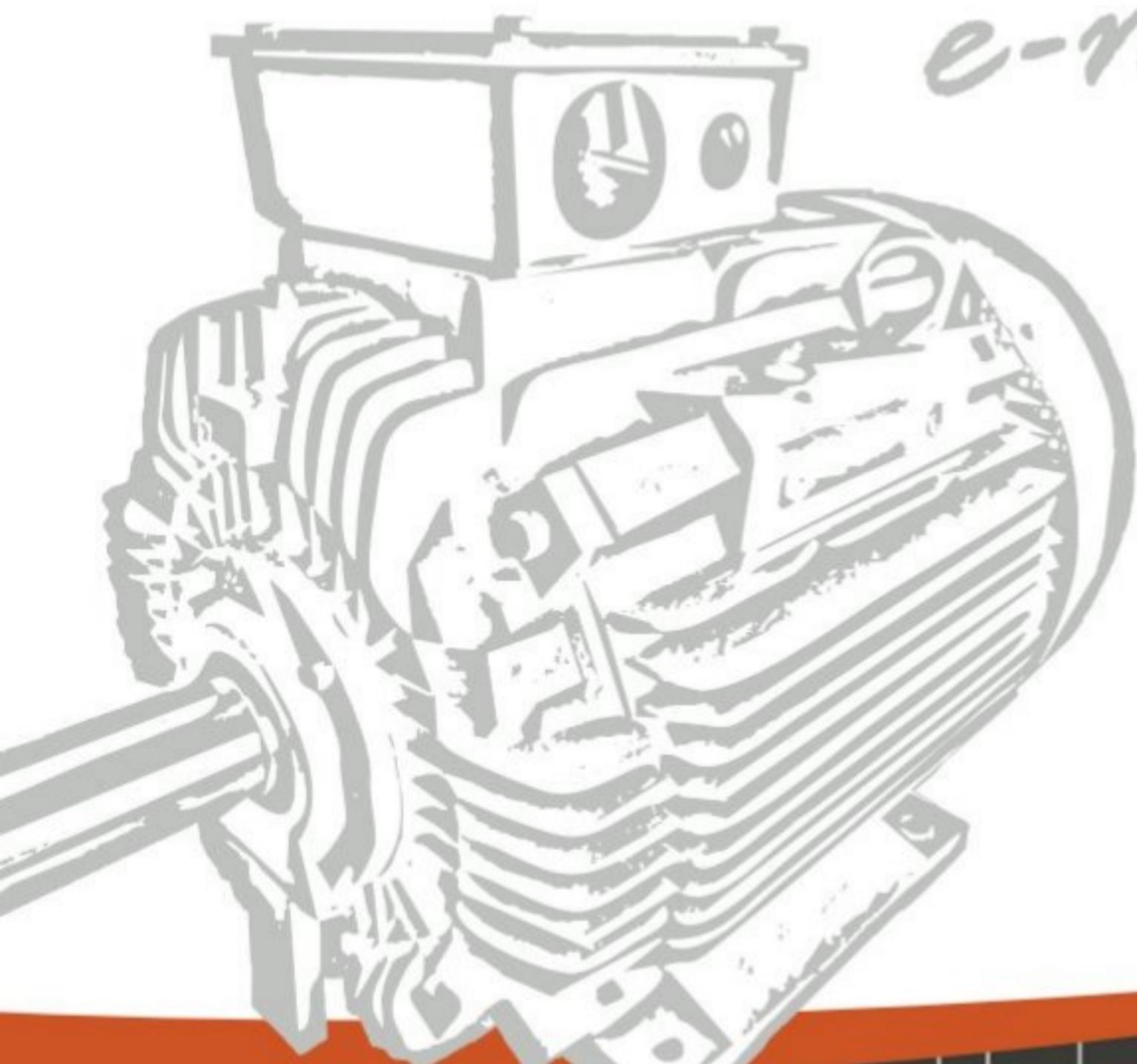
TITLE: EXPLODED VIEW

NAME: MAZEN OMAR MOHAMED
SECTION: 51

DATE: 29-JAN-2024
SCALE: 1:3

TECO

e-motion



Technical Catalogue

2014

Whilst every care has been taken to ensure the accuracy of the information contained in this publication, due to a policy of continuous product development and improvement we reserve the right to supply products which may differ slightly from those drawn or described in this publication.

For critical applications please refer to your local TECO Office.

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TECO History

- 1956 Company foundation and start of production in the first TECO factory in San-Chung, TAIWAN
1965 Production capacity increased by opening new factory in Shin-Chuan, TAIWAN
1966 Start of close technical co-operation with Hitachi, Yaskawa and Taiyo
1979 Increased production capacity by opening factory in Chung Li, TAIWAN Plant I (Heavy Motor Plant)
1987 Opened Chung Li Plant II for serial motor production (Small Motor Plant), TAIWAN
1987 Started Joint Venture with Westinghouse Motor Company, USA, one of the leading motor manufacturers in North America
1991 Founded TECO Perai, Penang Provence, MALAYSIA, low voltage motors for local market
1993 Established TECO Electric Europe in Manchester, UNITED KINGDOM to start presence in Europe
1995 100% take over of Westinghouse motor business by TECO. Established TECO-Westinghouse Motor Company, USA
2000 Opened TECO factory for low voltage motors in Suzhou, Jiangsu Provence, CHINA
2003 Opened TECO factory for low and medium voltage motors in Wuxi, CHINA
2005 Opened third TECO factory in Nanchang, Jiangxi Provence, CHINA
2006 Opened factory in Huyen Long Thanh, Tinh Dong Nai Provence, VIETNAM
2008 Opened TECO repair plant in Dammam, KINGDOM OF SAUDI ARABIA, on joint venture basis
2009 Established TECO Fuan in Fujian Provence, CHINA
2010 Starting the production of aluminium motors and semi finished aluminium parts at TECO Fuan factory in Fujian Provence, CHINA
2012 Established India branch office
2013 Established Turkey branch office

TECO General

In 2013 TECO operates in 45 countries worldwide and affiliates gained a turnover of 1.9 Billion EURO, with approximately 20.000 employees worldwide. More than 50% of the turnover was generated by the Electric Motor business. TECO is listed in the stock exchange in Taipei, TAIWAN. Detailed financial data can be downloaded from the TECO website http://www.teco.com.tw/en_version, under "Investor Relations".

TECO is mainly focused on

- Sustainable development with new competitive advantages
- Enhancing service quality
- Development and education of experienced employees
- Creating outstanding products

TECO has

- Significant Experience in the Motor Industry
- Experienced Engineering and Manufacturing Staff
- State of the art factories in the most important manufacturing markets
- State of the art Testing Facilities for the full power and voltage range of its motors

TECO Europe

TECO Europe currently has direct local presences in Germany, UK, the Netherlands, and Spain. TECO Europe also networks with competent sales and services partners in most of the markets within the European Union to provide local professional technical and sales supports. TECO Europe also has major warehouses located in the Netherlands and UK to support various logistic needs.

In Europe, along with well-known TECO-Westinghouse **Medium Voltage Motors**, TECO manufactures full range **Low Voltage Stock Motors** to IE2 & IE3 standard, with both cast iron and aluminium cases. With the recently released 510 Series, TECO offers high performance and cost effective wide range of **Variable Speed Drives** that fit virtually all applications. So whatever your motor and drive requirement our experienced engineering team can help and advise on the correct products to suit your applications.

References in this catalogue:

- *TECO Manual "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS FOR TECO LOW VOLTAGE MOTORS Type ALAA and ALCA"*
- *TECO short form safety instructions*

TECO Scope of Supply:

Low Voltage 0,12 to 1000 kW	Three Phase Asynchronous Motors	Cast Iron Aluminium Open Drip Proof
	High Efficiency Motors	IE2 Cast Iron IE3 Cast Iron IE2 Aluminium IE3 Aluminium NEMA Premium Efficiency
	Single Phase Motors	Capacitor-Start Capacitor-Start, Capacitor Run Split Phase Start
	Explosion Proof Motors	Non Sparking Flameproof Increased Safety Dust Ignition Proof
	Vertical Motors	Solid Shaft High Thrust Hollow Shaft High Thrust
	Special Purpose Motors	Inverter Duty Pole Changing Smoke Extraction Brake Motor Marine Duty Extended Shaft End Double Shaft End Hollow Shaft Crusher Duty Submersible Crane Duty Wind Generator Cooling Fan Design Pump jack (Oil Well) Design
	3 Phase Drives	0.4–1000kW 200, 400, 690V Constant/Variable Torque models IP00, IP20, IP54, IP65 V/F and Flux Vector
	Single Phase Drives	0.18–2.2kW IP20 and IP65 V/F and Flux Vector
	3 Phase Motors	Asynchronous Synchronous Slip ring
	Explosion Proof Motors	Non Sparking Flameproof Increased Safety Dust Ignition Proof
High Voltage 0,315 to 45 MW	Vertical Motors	Solid Shaft High Thrust Hollow Shaft High Thrust
	Special Purpose	Inverter Duty Pole Changing Marine Duty Extended Shaft End Double Shaft End Crusher Duty Wind Generator
	Wound Rotor Induction Motors	
	Permanent Magnet Motors	
	DC Motors	Series Type Shunt Type Compound Type
Special Design		

1 General

1.1 Standards and regulations

There are different international standards for electrical machines, e.g.

- the international "IEC" standard or
- the North American "NEMA"-standard and others.

The motors covered by this catalogue are designed and manufactured according to the latest IEC standards. Furthermore they fulfil the relevant regulations of the European Community ("EC Regulations").

List of national and international standards and regulations applied:

Title	International IEC	Europe EN/Directive	Germany DIN/VDE
Rotating electrical machines – Part 1: Rating and performance	60 034-1	60 034-1	DIN EN 60 034-1 VDE 0530 Part 1
Rotating electrical machines – Part 2-1: Standard methods for determining losses and efficiency from tests	60 034-2-1: 2007	60 034-2-1: 2007	DIN EN 60 034-2 VDE 0530 Part 2
Rotating electrical machines – Part 5: Degrees of protection provided by the integral design of rotating electrical machines (IP code) – Classification	60 034-5	60 034-5	DIN EN 60 034-5 VDE 0530 Part 5
Rotating electrical machines – Part 6: Methods of cooling (IC Code)	60 034-6	60 034-6	DIN EN 60 034-6 VDE 0530 Part 6
Rotating electrical machines – Part 7: Classification of types of construction, mounting arrangements and terminal box position (IM Code)	60 034-7	60 034-7	DIN EN 60 034-7 VDE 0530 Part 7
Rotating electrical machines – Part 8: Terminal markings and direction of rotation	60 034-8	60 034-8	DIN EN 60 034-8 VDE 0530 Part 8
Rotating electrical machines – Part 9: Noise limits	60 034-9	60 034-9	DIN EN 60 034-9 VDE 0530 Part 9
Rotating electrical machines – Part 11: Thermal protection	60 034-11	60 034-11	
Thermistors, PTC			DIN 44081:1980-6
Rotating electrical machines – Part 12: Starting performance of single-speed three-phase cage induction motors	60 034-12	60 034-12	DIN EN 60 034-12 VDE 0530 Part 12
Rotating electrical machines – Part 14: Mechanical vibration of certain machines with shaft heights 56 mm and higher – Measurement, evaluation and limits of vibration severity	60 034-14	60 034-14	DIN EN 60 034-14 VDE 0530 Part 14
Rotating electrical machines – Part 17: ³⁾			
Cage induction motors when fed from converters-Application guide	TS 60034-17		
Mechanical vibration; balancing shaft and fitment key convention			DIN ISO 8821
Mechanical vibration – Balance quality requirements for rotors in a constant (rigid) state – Part 1: Specification and verification of balance tolerances			DIN ISO 1940-1: 2004-04

Title	International IEC	Europe EN/Directive	Germany DIN/VDE
Rotating electrical machines – Part 30: Efficiency classes of single-speed, three-phase, cage-induction motors (IE-code)	60 034-30		
IEC standard voltages	60 038	—	DIN IEC 60 038
Dimensions and output series for rotating electrical machines – Part 1: Frame numbers 56 to 400 and flange numbers 55 to 1080	60 072-1 ¹⁾	50 347	DIN EN 50 347 ²⁾
Electrical insulation – Thermal evaluation and designation	60 085	—	DIN IEC 60 085
Safety of electrical Machines – Electrical equipment of Machines Part 1: Common Requirements	60 204-1	60 204-1	DIN EN 60 204-1 VDE 0113-1
Electro technical graphical symbols	60 617-2	60 617-2	DIN EN 60 617-2
Drive Type Fastenings without Taper Action; Parallel Keys, Keyways, Deep Pattern			DIN 6885-1
Hexagonal screws			DIN EN ISO 4014
Hexagonal nuts			DIN EN ISO 4032
Lubricating nipples; button head			DIN 3404
Protection of steel structures from corrosion by organic and metallic coatings			DIN 55 928
Low Voltage Directive 2006/95/EC		2006/95/EC	
EMC Directive 2004/108/EC		2004/108/EC	
Machinery Directive 2006/42/EC ⁴⁾		2006/42/EC	

¹⁾ Applicable for dimensions and frame sizes only

²⁾ Applicable for single speed motors up to frame size 315M only

³⁾ As far as applicable

⁴⁾ Not directly applicable for low voltage motors

Table 1-1: Standards and regulations applied

Remarkable latest innovations in above mentioned standards are:

- IEC 60034-2-1 (...standard methods for determining losses and efficiency from tests) and
- IEC 60034-30 (...efficiency classes of single-speed, three-phase cage-induction motors; IE-code).

By IEC 60034-2-1 an improved procedure for testing of the efficiency is described. In general the nominal efficiency evaluated by this method is slightly lower than the value based on the formerly used procedure. IEC 60034-30 defines classes of efficiency for standard motors ("International Efficiency"):

- "IE1" (Standard Efficiency),
- "IE2" (High Efficiency),
- "IE3" (Premium Efficiency) and
- "IE4" (Super Premium efficiency).

These efficiency class definitions demand a minimum efficiency value depending on power rating and pole number of the motor. (This classification replaces the formerly used efficiency class definitions like e.g. "eff1".) The motors in this catalogue (category IE2 and IE3) fulfil or override these minimum levels.

Depending on local regulations the current and future use of these advanced motors is mandatory. The current regulation within the European Community is EG 640/2009, as a part of the EU's eco-design project. It covers 2-, 4-, 6- and 8-pole three phase low voltage induction motors with power rating from 0,75 kW up to 375 kW (excepted of special motors like explosion proof motors and others). Schedule for mandatory use of these motors:

- June 2011: efficiency class IE2 for all motors covered by this regulation
- January 2015: efficiency class IE3 for motors from 7,5 kW up to 375 kW (or IE2 if inverter operated)
- January 2017: efficiency class IE3 for all motors from 0,75 kW up to 375 kW (or IE2 if inverter operated).

A sample for efficiency requirements is given in the figure below (4-pole motors, classification "IE2" and "IE3"):

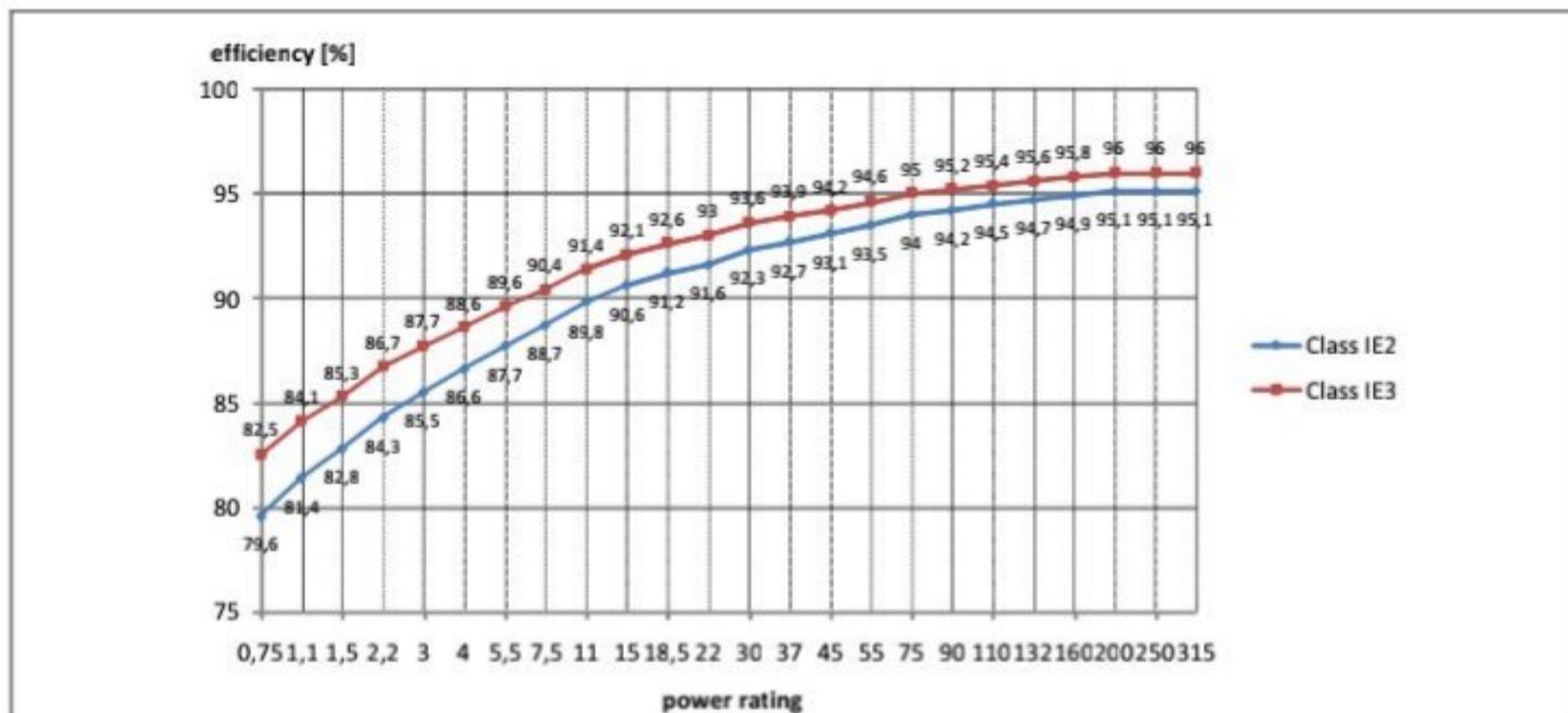


Figure 1-1: Minimum nominal efficiency for 4-pole motors acc. class IE2 and IE3 (IEC 60034-30)

1.2 Basics, terms and definitions

Induction machines are the commonly most used motor type for general drive applications. They are extremely durable and robust and provide an economic drive solution, even under severe environmental conditions. They can be used for direct line operation (fixed speed) or in combination with a frequency inverter (variable speed drive system). They are available in a lot of varieties. Some typical characteristics are listed below:

1.2.1 Power rating

The power rating of electrical motors refers to the mechanical shaft output power (in opposite: for electrical generators the rating refers to the electrical power at the terminals). Within the IEC standard range (up to 315 kW) standardized values for the rating are defined (e.g. 37 kW, 45 kW etc.).

1.2.2 Frame size

The frame size is defined as the distance [mm] between the mounting level and the centre of the shaft (in case of floor mounted arrangement; accordingly a definition is stated for flange mounted arrangement). Standard values for the frame sizes are defined for the IEC standard range (e.g. frame size 200, 225 etc.). In addition a fixed coordination between power rating and frame size is defined in IEC 60072-1. Within a defined frame size several types can be designed with different lengths.

1.2.3 Mounting arrangement

Rotating electrical machines can be delivered in a large variety of possible physical arrangements. In IEC 60034-7 the construction and arrangement is classified, (IM code as e.g. "IM B3"). Mechanical interface dimensions and their tolerances are standardized for each frame size. Table of some typical arrangements:

Mounting	Code acc. IEC 60034-7		Description	
Diagram	Code I	Code II	Feet	Flange
Horizontal use:				
	IM B3	IM 1001	with feet	—
	IM B5	IM 3001	—	with flange (clearance fixing holes)
	IM B14	IM 3601	—	with flange (tapped fixing holes)
	IM B34	IM 2101	with feet	with flange (tapped fixing holes)

Mounting	Code acc. IEC 60034-7		Description	
Diagram	Code I	Code II	Feet	Flange
	IM B35	IM 2001	with feet	with flange (clearance fixing holes)
Vertical use:				
	IM V1	IM 3011	—	with flange (clearance fixing holes) shaft up
	IM V3	IM 3031	—	with flange (clearance fixing holes) shaft down
	IM V5	IM 1011	with feet shaft down	—
	IM V6	IM 1031	with feet shaft up	—

Table 1-2: Relevant IM arrangements (selection)

1.2.4 Construction and construction material

The relevant components are:

- Stator housing with active stator parts inside (magnetic core, stator winding),
- End shields with bearings,
- Shaft with active rotor parts (magnetic core, squirrel cage),
- Cooling system,
- Terminal box.

Housing, end shields and terminal box can be manufactured in aluminium (preferable at small machines), cast iron (medium size machines) or welded steel (large machines).

1.2.5 Cooling

Cooling can be carried out either with ambient air or with cooling water with a large variety of detailed constructions. Principle arrangements of the cooling are defined in IEC 60034-6 (IC code). In the range of IEC standard motors as presented in this catalogue the cooling system in general is "IC 411": Totally Enclosed Surface Fan cooled ("TEFC") as shown in the sample picture above.

1.2.6 Degrees of protection

The level of protection against environmental conditions like water, dust, etc. is defined in 60034-5 (IP code as e.g. "IP55"). The user has to choose a sufficient degree of protection according to his environmental conditions.

1.2.7 Performance characteristics: Speed, torque

(Only induction motors with a rotor in "squirrel cage" design regarded here; no "wound rotor" types). If operated at a grid with fixed voltage and frequency the nominal speed ("full load speed") is near to the "no-load speed" (also called "synchronous speed"): this is defined by the grid frequency and the "pole number" of the motor (also called "2p" with "p" as the number of pole pairs):

Motor design	2-pole	4-pole	6-pole	8-pole
No load speed at 50 Hz grid	3000 rpm	1500 rpm	1000 rpm	750 rpm
No load speed at 60 Hz grid	3600 rpm	1800 rpm	1200 rpm	900 rpm

Table 1-3: No load speed

The starting performance is standardized by IEC 60034-12 ("Starting performance of single-speed three-phase cage induction motors"). The motors covered by this catalogue comply with "IEC 60034-12, Design N". The typical characteristic of the torque versus speed is shown in the diagram below:

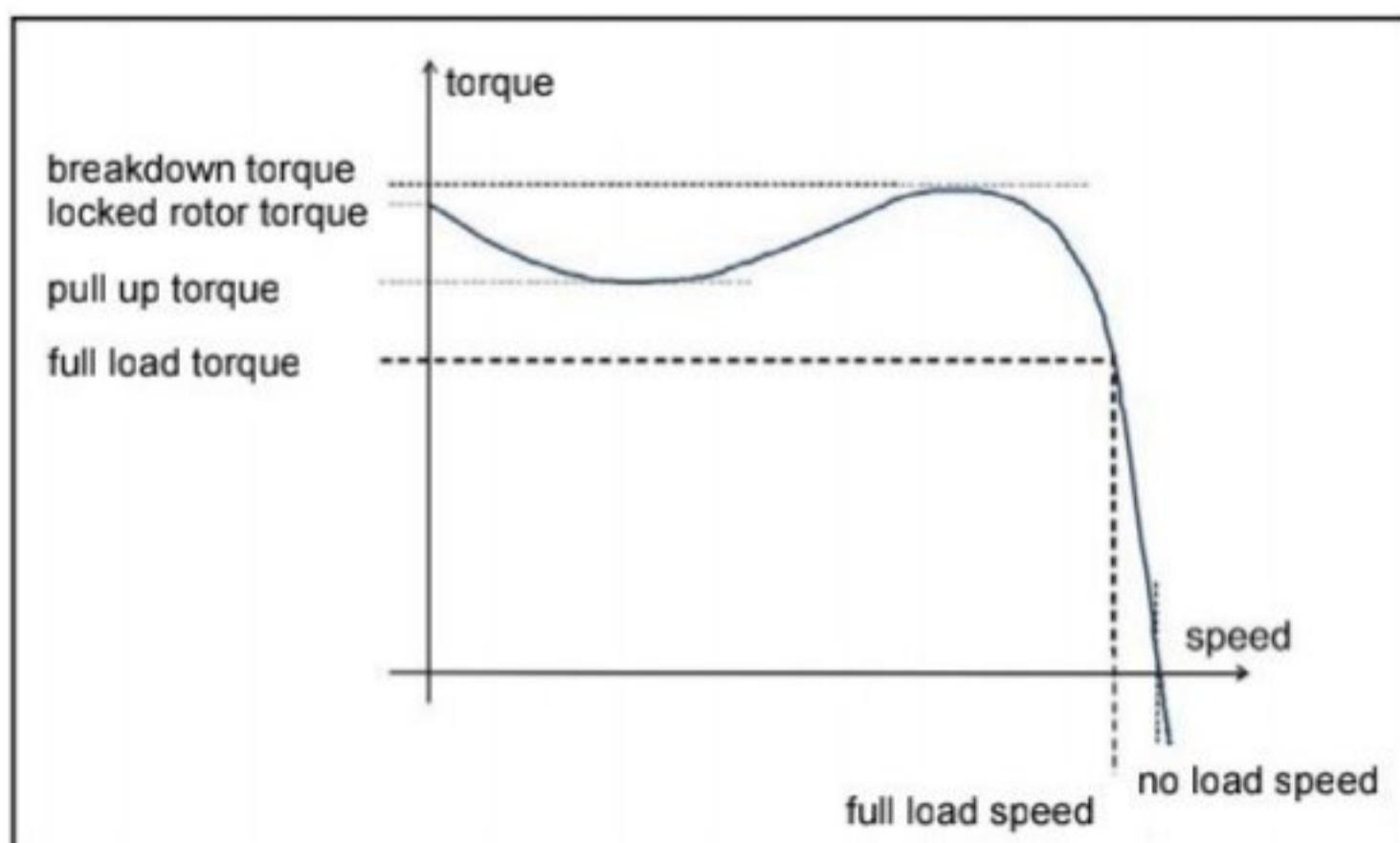


Figure 1-2: Typical characteristic for induction motors: Torque versus speed

Characteristic points which are content of the type data:

- Full load speed ("nominal speed")
- Full load torque ("nominal torque")
- Locked rotor torque ("starting torque"); as a multiple of nominal
- Pull up torque; as a multiple of nominal
- Breakdown torque; as a multiple of nominal.

1.2.8 Electrical performance characteristics

According to 1.2.7 Performance characteristics: Speed, torque the typical characteristic of current and power factor is shown in the diagram below:

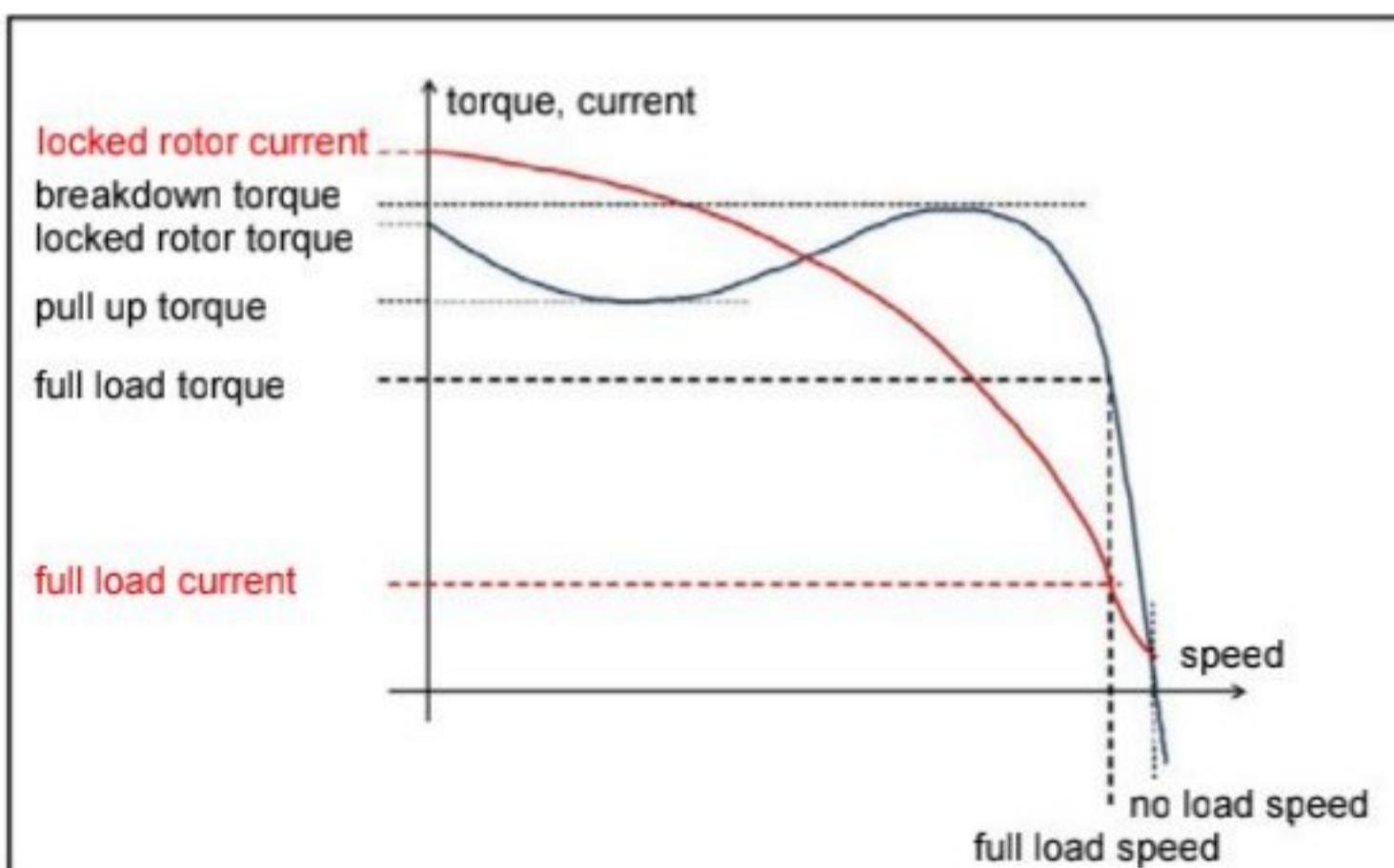


Figure 1-3: Typical characteristic for induction motors: Torque and current versus speed

Characteristic points which are content of the type data (see 6 Technical data, starting page 58):

- Full load current ("nominal current")
- Full load power factor
- Locked rotor current; as a multiple of nominal.

At different load points (partial load, overload) the values for current, power factor and efficiency are varying; a typical characteristic is shown in diagram below. The values of power factor and efficiency for each motor type are listed in section 6 for the load points 1/4; 2/4 and 3/4 partial load.

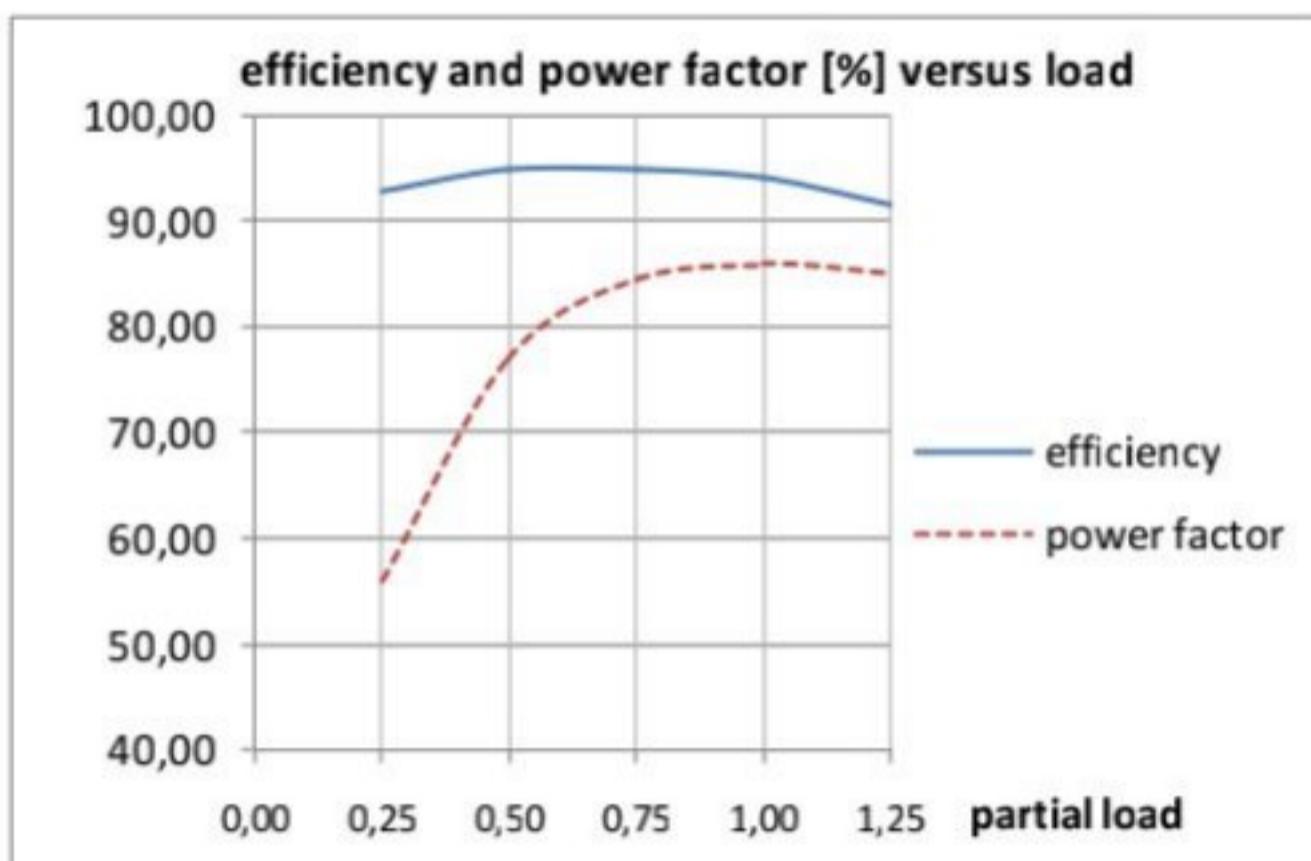


Figure 1-4: Typical characteristic for a TECO motor (30 kW): power factor and efficiency at partial load

2 AC Motors, European Design

2.1 Range of motors covered by this catalogue; variety of characteristics

Common characteristics	Three phase low voltage motors according to IEC standard, single speed, totally enclosed, for <i>Standard Safe Area</i>
Power rating	0,18 kW–315 kW
Frame size	63–315
Pole number	2-pole; 4-pole; 6-pole; 8-pole
Line Frequency	50 Hz; 60 Hz
Type of mounting	Feet version, flange version and combinations
Construction material	Aluminium or Cast Iron
Efficiency class acc. IEC	Cast iron motors: IE2 and IE3 (identical dimensions) Aluminium motors: IE 2
Accessories	Standard or with options (e. g. forced ventilation)
Standards	IEC standards, European directives (CE marking). Compliance with additional regulations for applications non essential service: "GL Rules and guidelines 2011" "BV Rules and guidelines 2011" "LR Rules and Regulations for the classification of ships, 2011" "DNV Rules for Ships/High Speed, Light Craft and Naval Surface Craft, January 2011"

Table 2-1: Motors covered by this catalogue

2.2 TECO type code (“Motor Identification Code”)

The type code is covering the overall range of TECO induction motors. It is explained for a sample motor type "ALCA-0160MC-30004-IZ": A low voltage 3 phase AC motor for application in "Safe Area", with aluminium housing; frame size 100; 4-pole; according IEC standards; optional version with accessories.

Remarks for digits 13 to 17: "31284" e.g. is defined as "3 speed, with 12 pole, 8 pole and 4 pole winding".

Table 2-2: TECO type code

3 Mechanical design

3.1 Housing, mounting arrangement

All construction components are shown for a sample motor in the figure below.

01	Shaft cover	16	Washer	31	External Earth terminal assy
02	Oil Seal	17	Eye bolt	32	Inner bearing cover
03	Outer bearing cover	18	Name plate carrier	33	Bearing stop ring
04	Grease drain cover	19	Name plate	34	Bearing
05	End shield DE	20	Terminal box plate	35	Pre-load spring
06	Grease nipple	21	Blind plug	36	End shield NDE
07	Bearing	22	Terminal box housing	37	Grease nipple
08	Bearing stop ring	23	Fixed seat	38	Grease drain cover
09	Inner bearing cover	24	Power connecting assy	39	Outer bearing cover
10	Shaft	25	Internal Earth terminal assy	40	Oil seal
11	Key	26	Power terminals	41	External fan
12	Rotor	27	Hex nut	42	Fan cowl
13	Stator	28	Star-Delta jumpers	43	Detachable gland plate Gasket
14	Frame	29	Terminal box gasket	44	Detachable gland plate
15	Feet	30	Terminal box cover		

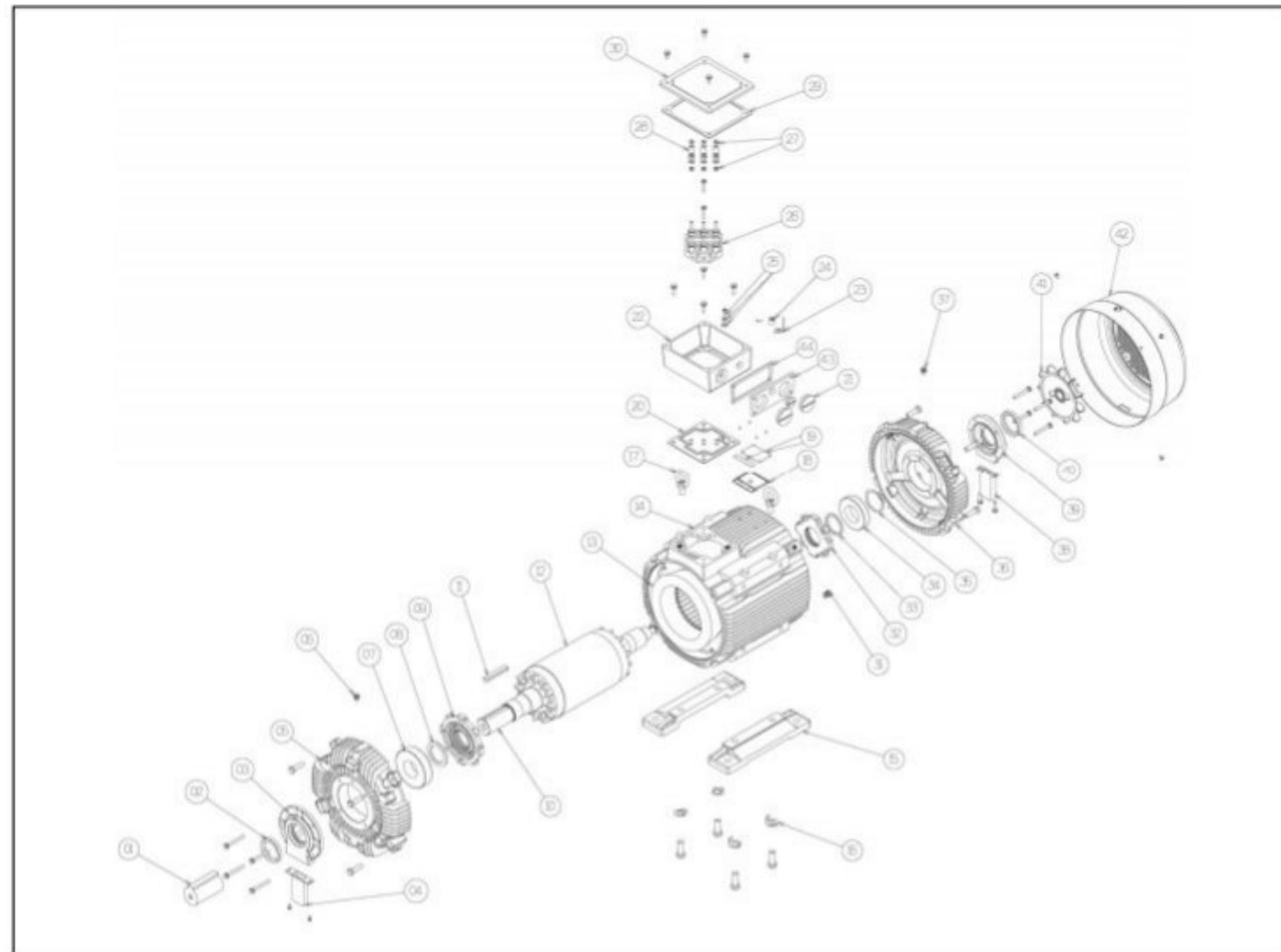


Figure 3-1: "Exploded" drawing of a sample TECO motor

The motors are available in the versions:

- Aluminium housing (type code e.g. "ALAA-.....) or
- Cast iron housing (type code e.g. "ALCA-.....).

Power ratings	Depending on pole number, see 6 Technical data, starting page 58.													
Frame size	63	71	80	90	100	112	132	160	180	200	225	250	280	315
Aluminium	X	X	X	X	X	X	X	X						
Cast iron			X	X	X	X	X	X	X	X	X	X	X	

Table 3-1: Motor versions available

The motors can be delivered for many types of mounting:

- Feet version (IM code B3, suitable for arrangements B6, B7, B8, V5, V6); with top mounted terminal box (standard configuration)
- Flange version with clearance fixing holes (IM code B5, suitable for arrangements V1 and V3) or
- Flange version with tapped fixing holes (IM code B14, suitable for arrangements V18 and V19) or
- Version with feet and flange with clearance fixing holes (IM code B35, suitable for V15 and V36 or
- Version with feet and flange with tapped fixing holes (IM code B34).

To be regarded only for motors with frame size 315; 2-pole: Vertical use (V-mountings) is only admissible in a special design; this has to be defined in the order.



Figure 3-2: Sample of a TECO motor (feet version)



Figure 3-3: Sample of a TECO motor (flange version)

Dimensions:

All external dimensions of the motor (shaft height, length) for a defined motor rating are identical for the IE2- and the IE3-version. This allows variability for the user depending on the application. The dimensions and tolerances for the mechanical interface (e. g. positions of feet holes) are defined by IEC 60072-1.

Multi-mount symmetric design – Axial direction:

The motor housing is designed to allow for a large variety of mounting arrangements. It is symmetric in axial direction (DE – NDE), except of the asymmetric position of the terminal box. Therefore the user can change the axial position of the terminal box according to the individual spatial conditions at his construction (front or back) by changing the position of the rotor including DE and NDE end shield. Due to a special design of the DE end shield this modification can be carried out without dismantling the NDE assembly. (To be regarded when carrying out this modification: the rotational direction of the motor is no longer acc. to IEC 60034-8 then. Precautions shall be made to prevent disturbances. Modification of mounting arrangement shall only be carried out by qualified personnel; regard the guidelines in the TECO manual "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS....".)



Figure 3-4: Multi-mount design (in axial direction); terminal box "Drive End"



Figure 3-5: Multi-mount design (in axial direction); terminal box "Non drive end"

SDF

As a standard the "feet" – in SDF version (B3; B34; B35) are delivered with a top mounted terminal box. In the "Standard Detachable Feet" (SDF) version; the feet can be detached if required.

ADF

In the optional version "Advanced Detachable Feet"; (ADF) the housing is machined to be able to move the feet in 3 x 90° positions. Therefore the feet can easily be mounted in each of the 3 rotational positions and the 2 axial positions. All surfaces and all fixing holes for mounting the feet are machined, drilled, tapped and plugged. The holes (as well as others e.g. for lifting lugs, etc.) are designed as blind holes. If using the original feet a change of the feet position is possible without new alignment of the motor when feet are fixed in the new position.



Figure 3-6: Multi-mount design (top mounted terminal box)



Figure 3-7: Multi-mount design (terminal box in left hand side position)



Figure 3-8: Multi-mount design (terminal box in right hand side position)

Details for flange version

Possible mounting arrangements according to IEC 60034-7: B5, V1, V3. All customer interface dimensions (hole circle diameter, centring diameter, etc.) and their tolerances are defined by IEC 60072-1. For a number of motor frame sizes as an option flanges with external dimensions equivalent to larger or smaller frame sizes are available on request; see tables:

Available FF(A) – Flanges (clearance fixing holes)														
Frame size	FF [mm]	100	115	130	165	215	265	300	350	400	500	600	740	940
	A [mm]	120	140	160	200	250	300	350	400	450	550	660	800	1000
63			X	X										
71				X	X									
80					X	X								
90					X	X								
100						X	X							
112						X	X							
132							X	X						
160								X	X					
180								X						

Available FF(A) – Flanges (clearance fixing holes)														
Frame size	FF [mm]	100	115	130	165	215	265	300	350	400	500	600	740	940
	A [mm]	120	140	160	200	250	300	350	400	450	550	660	800	1000
200									X					
225										X				
250											X			
280											X			
315												X		

FF = hole circle

X = standard

A = diameter

X = available on request

Table 3-2: Flange sizes available (B5; clearance fixing holes)

Available FT(C) – Flanges (tapped fixing holes)														
Frame size	FT [mm]	65	75	85	100	115	130	165	215					
	C [mm]	80	90	105	120	140	160	200	250					
63		X	X	X										
71			X	X	X									
80				X	X	X								
90					X	X	X							
100						X	X	X						
112						X	X	X						
132							X	X	X					
160								X	X					
180								X						

FT = hole circle

X = standard

C = diameter

X = available on request

Table 3-3: Flange sizes available (B14; tapped fixing holes)

3.2 Terminal box and cable entry

As a standard the motors are delivered with a top mounted terminal box; located at the drive end, with cable entry to the right hand side. As described in 3.1 Housing, mounting arrangement, the position of the terminal box can easily be varied (left, right, front or back). Furthermore the terminal box itself is able to be rotated by steps of 90° to every direction to enable power cable entry from 4 directions (front, rear, left, right). (Guidelines for proper modification of the terminal box position: see TECO manual "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS....")



Figure 3-9: Cable entry front



Figure 3-10: Cable entry back



Figure 3-11: Cable entry left



Figure 3-12: Cable entry right

There are two cable entry holes for the power supply cable(s) and one entry hole for the cable for auxiliary devices, e. g. for thermistor connection. They are drilled, tapped and properly sealed; with threads according to table below. (The applicable cable outer diameter is dependent on the customer's cable gland type.)

All six winding lead ends from the windings are brought out and connected to a terminal block with metric threaded bolts for smaller motors or to metric duct connection bolts for bigger motors. Screws and nuts are hexagonal with metric thread and with ISO wrench sizes acc. to DIN EN ISO 4014 (screws) and DIN EN ISO 4032 (nuts). Three jumpers are attached to enable the customer a simple star or delta connection (see 4 Electrical design, starting page 37).

The lead ends of the standard thermistors (as well as optional accessories like space heaters) are connected to terminals (luster terminals or spring loaded serial terminals, see table below).

The terminals are marked and directed according to IEC 60034-8. A connection diagram sticker with the wiring diagram is fitted on the inside of the terminal box lid.

ALAA, cable entries for power and thermistors:

Frame size	Power Supply		Thermistor	
	Threads	Power connector bolts	Threads	Type of Connector
63	2 x M16 x 1.5	U-clamp		Luster terminal
71	2 x M16 x 1.5	U-clamp		Luster terminal
80	2 x M16 x 1.5	U-clamp		Luster terminal
90	2 x M25 x 1.5	U-clamp		Luster terminal
100	2 x M25 x 1.5	U-clamp		Luster terminal
112	1 x M32 x 1.5	U-clamp	1 x M25 x 1.5	Luster terminal
132	1 x M32 x 1.5	U-clamp	1 x M25 x 1.5	Luster terminal
160	2 x M40 x 1.5	Bolts	1 x M20 x 1.5	Serial terminal

ALCA, cable entries for power and thermistors:

Frame size	Power Supply		Thermistor	
	Threads	Power connector bolts	Threads	Type of Connector
63	1 x M20 x 1.5	U-clamp	M16 x 1.5	Luster terminal
71	1 x M20 x 1.5	U-clamp	M16 x 1.5	Luster terminal
80	2 x M25 x 1.5	U-clamp	M20 x 1.5	Luster terminal
90	2 x M25 x 1.5	U-clamp	M20 x 1.5	Luster terminal
100	2 x M32 x 1.5	U-clamp	M20 x 1.5	Luster terminal
112	2 x M32 x 1.5	U-clamp	M20 x 1.5	Luster terminal
132	2 x M32 x 1.5	U-clamp	M20 x 1.5	Luster terminal
160	2 x M40 x 1.5	Bolts	M20 x 1.5	Serial terminal
180	2 x M40 x 1.5	Bolts	M20 x 1.5	Serial terminal
200	2 x M50 x 1.5	Bolts	M20 x 1.5	Serial terminal
225	2 x M50 x 1.5	Bolts	M20 x 1.5	Serial terminal
250	2 x M63 x 1.5	Bolts	M20 x 1.5	Serial terminal
280	2 x M63 x 1.5	Bolts	M20 x 1.5	Serial terminal
315	2 x M63 x 1.5	Bolts	M20 x 1.5	Serial terminal

Table 3-4: Cable entries and connectors

Detailed mechanical dimensions depending on motor type: see 7 Outline drawings, starting page 82.

Options, on request:

From frame size 160 to 250 an optional attachment of one and from frame size 280 to 400 of two separate accessory terminal boxes is available (e.g.: different terminal boxes for different voltage levels may be demanded by customer specifications).

The motors can also be delivered without a terminal box on request. In this case we provide a blind plate with bushing for direct entry of customer specified cable(s).

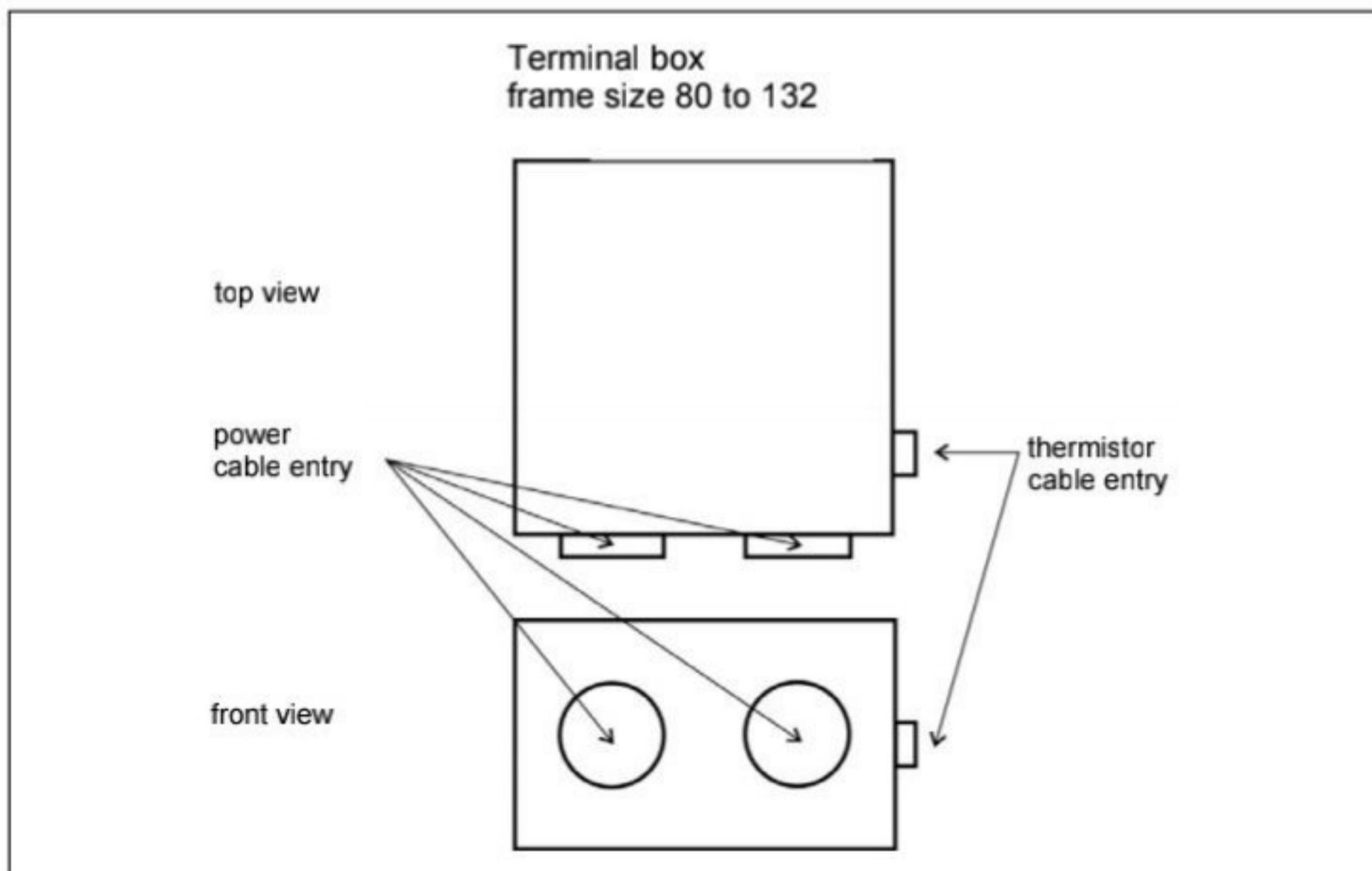


Figure 3-13: Position of cable entries (up to frame size 132)

Frame size 160 and above are equipped with a detachable steel plate on one side of the terminal box (cable entry plate). This is to enable customers an easy power supply connection and simple replacement of the motors with bulky cables as well as for later flexibility if customer asks for special amount of cable entry holes with special threads (special cable size or number of cables).

In these cases TECO can manufacture customized entry plates or blank plates on demand. Customer's cable glands:
Insure the cable glands used are rated to an equal or better protection class than the motor.

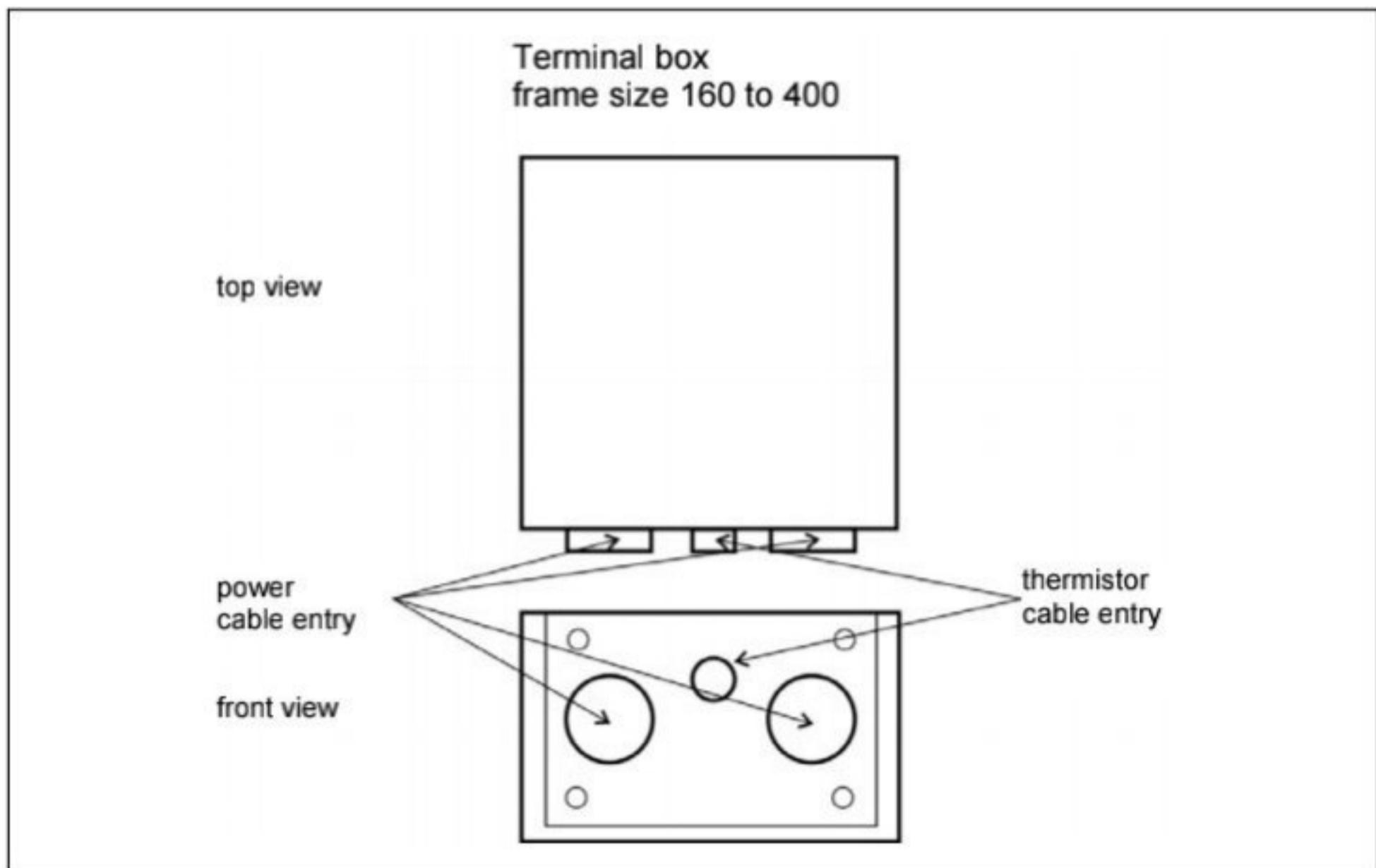


Figure 3-14: Position of cable entries (ALCA, frame size 160 to 315)



Figure 3-15: Detached entry plate

3.3 Cooling

As a standard the motors covered by this catalogue are "Totally Enclosed Surface Fan Cooled" ("TEFC") acc. to the IEC code "IC 411". This design provides cooling fins on the surface of the motor housing and a fan (and fan cowl) at NDE to generate a cooling air flow over these fins from NDE to DE. Even though acoustic noise is optimized, the fan is suitable for application in both directions of rotation ("bidirectional design"). The fan cowl is manufactured in steel sheet.



Figure 3-16: Cooling principle ("TEFC")

In accordance with IEC standards the degree of protection for the cooling system is IP20 (even though the motor is classified in a much higher degree of protection, in this case IP55). The cooling system allows operation in any mounting position in principle. When mounted in a "shaft down position" precautions are required to prevent foreign bodies or excessive amount of water falling into the openings of fan. An accessory kit "Protection cover for shaft down motors" is available on request; it can be added easily in site.

The user has to take care that the air flow is not hindered or a high back pressure is generated when integrating the motor into his machine. As a general rule e.g. the distance between air inlet of motor and obstruction should be at least $\frac{1}{4}$ of the air inlet diameter of the fan cowl.

Options:

- A special design with "uni-directional" fan for acoustic noise reduction is available on request. In this case a sticker is mounted at the top of the front end shield which clearly indicates the direction of rotation. (acoustic noise level: see 5.3 Mechanical performance, starting page 42).
- Especially for frequency inverter operation (high speed or low speed range) a "Forced Ventilation" can be installed as an option. The fan then is operated by an additional motor to provide constant cooling independent from the main motor's speed.

For special applications the motors can be delivered without ventilation. Power rating and duty type then have to be calculated by TECO acc. to customer's request.

3.4 Rotor assembly (active part, shaft, bearings)

3.4.1 General

The active rotor part of a squirrel cage motor is a rugged arrangement only consisting of the magnetic lamination and the short circuit "winding" made of cast aluminium. It is mounted on the shaft manufactured from high tensile strength carbon steel. The bearings (including sealing) are supported in the end shields (aluminium or cast iron, according to motor type).

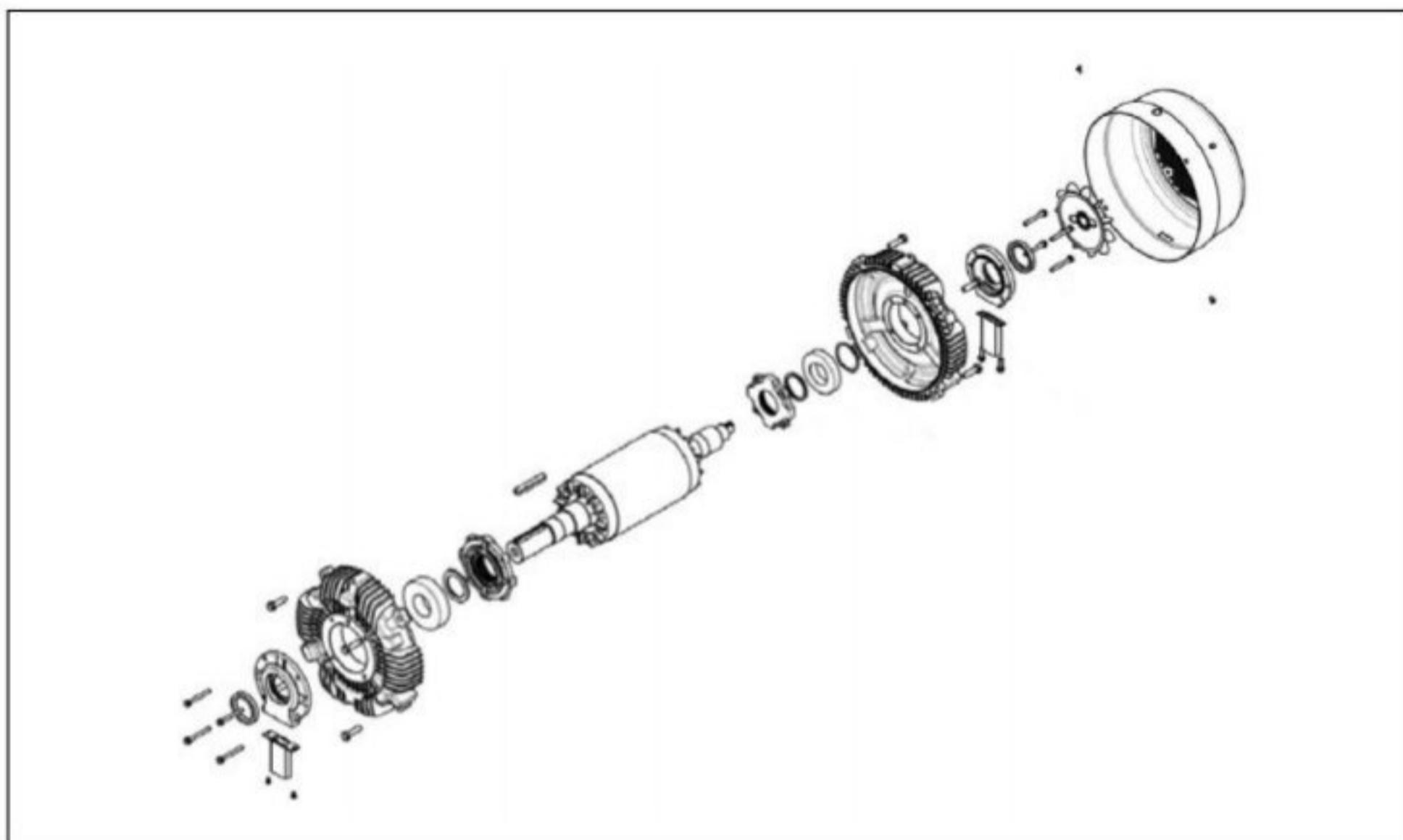


Figure 3-17: Rotor assembly (active part, shaft, bearings, end shields, fan)

The rotor is dynamically balanced with half key. The balance quality meets DIN ISO 1940, Q2,5. The mechanical vibrations of the motors meet level A according to EN 60034-14 at synchronous speed. Mechanical vibrations; permissible axial and radial forces at DE and maximum mechanical speed: See 5.3 Mechanical performance, starting page 42.

3.4.2 Shaft

The dimensions of the DE shaft end (including the keyway) and their tolerances are standardized by IEC 60027-1 (DIN EN 50347). The DE shaft face has a threaded centre hole for mounting of customer's shaft fitments. The key is press fit into key way. The NDE shaft end is carrying the fan; on larger machines (see dimensional diagrams). Depending on frame size its face is equipped with a threaded centre hole for later mounting of accessories (like speed sensor, etc.). The fan is manufactured from conductive polypropylene (non-sparking material).

3.4.3 Bearings

As a standard both DE bearing and NDE bearing are ball bearings, suitable both for horizontal and vertical mounting of the motor (except for frame size 315, 2-pole; where a special bearing is provided for operation at vertical mounting, see tables below). As an option reinforced bearing types can be provided according to customer's load specifications.

The DE bearing is fixed; it absorbs axial and radial forces transmitted from the driven machine. The floating bearing is installed at the non drive end (NDE) to allow thermal expansion of the shaft and to absorb radial forces. The bearings are preloaded in axial direction by an undular washer at NDE. Even though the DE bearing is fixed due to a special design of the DE end shield it is easy to fit a flange end shield without removing the rotor. Disassembling of the rotor (e.g. for changing the terminal box position) can be carried out without disassembling the NDE).

Motors up to frame size 160 are equipped with double shielded bearings (suffix "zz" on bearing type). Those motors bearings are lubricated for life. They are maintenance-free and cannot be regreased.

Motors from frame size 180 up to frame size 315 are equipped with grease nipples both at DE and NDE for manual greasing. These motors are already greased during manufacture. Grease nipples are of "flat button head" design according to DIN 3404 with thread M10 x 1. DE and NDE nipple are easily accessible (NDE nipple outside of the fan cowl).

Baugrubel Frame Size/ Hauteur d'Arbre/ Grandezza Motore/ Carcasas/ Размер агрегата	160	Polzahl Poles Poles Poli Polos полюсов	Lagergröße Bearing Size Type de Roulement Grandezza Cuscinetti Tamaño Rodamiento Размер подшипника	Nachschmierfrist [h] Lubrication Interval [h] Intervalle de Lubrification [h] Intervallo Lubrificazione [h] Intervalo Lubricación [h] Периодичность смазки смазки в подшипниках [ч]	Fettmenge [g] Grease Quantity [g] Quantité de Graisse [g] Quantità di Grasso [g] Cantidad de Grasa [g] Количество смазки [г]			
		Standard	DE	NDE	DE	NDE	DE	NDE
2	6309 C3	6307 C3	3500	4200	25	13		
4	6309 C3	6307 C3	8500	10500	25	13		
6	6309 C3	6307 C3	14000	16000	25	13		
8	6309 C3	6307 C3	17500	21000	25	13		
Verstärkt/ Reinforced/ Renforcé/ Rinforzati/ Reforzados/ Усиленный								
4	NU309C3	6307 C3	3300	10500	25	13		
6	NU309C3	6307 C3	5100	16000	25	13		
8	NU309C3	6307 C3	7100	21000	25	13		
DE = Antriebsseitig/ Drive End/ Coté Arbre/ Anteriore/ Lado Acoplamiento/ Приводная сторона двигателя								
NDE = Lüfters seitig/ Non Drive End/ Coté Opposé à l'Arbre/ Posteriore/ Lado Op. Асопламенто/ Неприводная сторона двигателя								
32045A0100005								

Figure 3-18: Regreasing sticker

A shaft lock is fitted on frame size 280 and 315 to prevent bearing damage during transportation.

Tables with the types of standard bearings and reinforced bearings (optional):

Frame size	Poles	Drive end	Non drive end	Remarks
63	2	6201 ZZC3	6201 ZZC3	Sealed bearings
	4	6201 ZZC3	6201 ZZC3	Sealed bearings
71	2	6202 ZZC3	6202 ZZC3	Sealed bearings
	4	6202 ZZC3	6202 ZZC3	Sealed bearings
	6	6202 ZZC3	6202 ZZC3	Sealed bearings
80	2	6204 ZZC3	6204 ZZC3	Sealed bearings
	4	6204 ZZC3	6204 ZZC3	Sealed bearings
	6, 8	6204 ZZC3	6204 ZZC3	Sealed bearings
90	2	6205 ZZC3	6205 ZZC3	Sealed bearings
	4	6205 ZZC3	6205 ZZC3	Sealed bearings
	6, 8	6205 ZZC3	6205 ZZC3	Sealed bearings
100	2	6206 ZZC3	6305 ZZC3	Sealed bearings
	4	6206 ZZC3	6305 ZZC3	Sealed bearings
	6, 8	6206 ZZC3	6305 ZZC3	Sealed bearings
112	2	6306 ZZC3	6306 ZZC3	Sealed bearings
	4	6306 ZZC3	6306 ZZC3	Sealed bearings
	6, 8	6306 ZZC3	6306 ZZC3	Sealed bearings
132	2	6308 ZZC3	6308 ZZC3	Sealed bearings
	4	6308 ZZC3	6308 ZZC3	Sealed bearings
	6, 8	6308 ZZC3	6308 ZZC3	Sealed bearings
160	2	6309 ZZC3	6309 ZZC3	Sealed bearings
	4	6309 ZZC3	6309 ZZC3	Sealed bearings
	6, 8	6309 ZZC3	6309 ZZC3	Sealed bearings

Table 3-5: Standard bearings used in aluminium motors (type code: ALAA....)

Frame size	Poles	Drive end					Non drive end	
		Sealed		Regreasable			Sealed	Regreasable
		Standard	Standard	Standard	Reinforced	Standard	Standard	Standard
		All mountings	B-mountings	V-mountings	All mountings	All mountings	All mountings	All mountings
80	2	6204 ZZC3	nA	nA	nA	6204 ZZC3	nA	nA
	4	6204 ZZC3	nA	nA	nA	6204 ZZC3	nA	nA
	6, 8	6204 ZZC3	nA	nA	nA	6204 ZZC3	nA	nA
90	2	6205 ZZC3	nA	nA	nA	6205 ZZC3	nA	nA
	4	6205 ZZC3	nA	nA	nA	6205 ZZC3	nA	nA
	6, 8	6205 ZZC3	nA	nA	nA	6205 ZZC3	nA	nA
100	2	6206 ZZC3	nA	nA	nA	6206 ZZC3	nA	nA
	4	6206 ZZC3	nA	nA	nA	6206 ZZC3	nA	nA
	6, 8	6206 ZZC3	nA	nA	nA	6206 ZZC3	nA	nA

Frame size	Poles	Drive end				Non drive end	
		Sealed	Regreasable			Sealed	Regreasable
		Standard	Standard	Standard	Reinforced	Standard	Standard
		All mountings	B-mountings	V-mountings	All mountings	All mountings	All mountings
112	2	6306 ZZC3	nA	nA	nA	6306 ZZC3	nA
	4	6306 ZZC3	nA	nA	nA	6306 ZZC3	nA
	6, 8	6306 ZZC3	nA	nA	nA	6306 ZZC3	nA
132	2	6308 ZZC3	nA	nA	nA	6306 ZZC3	nA
	4	6308 ZZC3	nA	nA	nA	6306 ZZC3	nA
	6, 8	6308 ZZC3	nA	nA	nA	6306 ZZC3	nA
160	2	6309 ZZC3	nA	nA	nA	6307 ZZC3	nA
	4	6309 ZZC3	nA	nA	nA	6307 ZZC3	nA
	6, 8	6309 ZZC3	nA	nA	nA	6307 ZZC3	nA

Table 3-6: Standard bearings used in cast iron motors (type code: ALCA....), frame size up to 160

Frame size	Poles	Drive end				Non drive end	
		Sealed	Regreasable			Sealed	Regreasable
		Standard	Standard	Standard	Reinforced	Standard	Standard
		All mountings	B-mountings	V-mountings	All mountings	All mountings	All mountings
180	2	nA	6311C3	6311C3	NU311	nA	6310C3
	4	nA	6311C3	6311C3	NU311	nA	6310C3
	6, 8	nA	6311C3	6311C3	NU311	nA	6310C3
200	2	nA	6312 C3	6312 C3	NU312	nA	6212 C3
	4	nA	6312 C3	6312 C3	NU312	nA	6212 C3
	6, 8	nA	6312 C3	6312 C3	NU312	nA	6212 C3
225	2	nA	6312 C3	6312 C3	NU312	nA	6212 C3
	4	nA	6313 C3	6313 C3	NU313	nA	6213 C3
	6, 8	nA	6313 C3	6313 C3	NU313	nA	6213 C3
250	2	nA	6313 C3	6313 C3	NU313	nA	6313 C3
	4	nA	6315 C3	6315 C3	NU315	nA	6313 C3
	6, 8	nA	6315 C3	6315 C3	NU315	nA	6313 C3
280	2	nA	6316 C3	6316 C3	NU316	nA	6314 C3
	4	nA	6318 C3	6318 C3	NU318	nA	6316 C3
	6, 8	nA	6318 C3	6318 C3	NU318	nA	6316 C3
315	2	nA	6316 C3	7316 C3	NU316	nA	6314 C3
	4	nA	6320 C3	6320 C3	NU320	nA	6316 C3
	6, 8	nA	6320 C3	6320 C3	NU320	nA	6316 C3
315D	2	nA	6316 C3	7316 C3	NU316	nA	6316 C3
	4	nA	6322 C3	6322 C3	NU322	nA	6322 C3
	6, 8	nA	6322 C3	6322 C3	NU322	nA	6322 C3

Table 3-7: Bearings used in cast iron motors (type code: ALCA....), frame size 180 up to 315

Bearing lifetime:

The calculated operating life L10 of the bearings is at least 20000 hours, provided:

- operation in horizontal position
- operation at nominal max temperature and nominal speed
- radial and axial forces are within the limits stated in the catalogue, refer to 5.3 "Mechanical performance", page 42.

In case of operation with a coupling (no additional axial or radial forces from the driven machine) a lifetime of 50000 h is calculated. Lifetime is reduced when operated at increased ambient temperature higher speed than nominal or under severe vibration conditions.

Tables for calculated operating lifetime:

Frame size	Lifetime at nominal operational conditions			
	2-pole	4-pole	6-pole	8-pole
	[h]	[h]	[h]	[h]
63	20000	40000	40000	40000
71	20000	40000	40000	40000
80	20000	40000	40000	40000
90	20000	40000	40000	40000
100	20000	40000	40000	40000
112	20000	40000	40000	40000
132	20000	40000	40000	40000
160	20000	40000	40000	40000

Table 3-8: Calculated lifetime for sealed standard bearings (operating life L10)

Sealing:

The sealing of DE and NDE bearing is provided by a radial seal ring with dust protection lip to fulfil the requirements of degree of protection "IP55". IP56 or IP65 protection options (dust tight; protection against powerful water jets) can be realized by reinforced sealing (see 3.4.3 Bearings, starting page 28). For applications with direct gearbox mounting an option "Oil Sealed Design" is available.

Bearing insulation:

If the motor is line operated (sinusoidal voltage supply) motors covered by this catalogue usually do not need a bearing insulation, because the shaft voltage (caused by small magnetic unbalance within the machine) does not exceed the level of 500 mV. This level is agreed as a save limit in the standard IEC 60034-17.

If the motor is inverter operated, increased bearing stress by high frequent bearing currents might occur. As an option TECO recommends using insulated bearing on NDE for frame size 280 and above in this case (see 5.5 Motor performance (inverter operated), starting page 51).

3.4.4 Regreasing

(relevant for cast iron motors, frame size 160–315)

Frame size	Regreasing intervals at nominal operational conditions [h], grease quantity per bearing [g]							
	2-pole		4-pole		6-pole		8-pole	
	DE	NDE	DE	NDE	DE	NDE	DE	NDE
160	4300 h	5800 h	1100 h	13000 h	16000 h	19000 h	2000 h	25000 h
	25 g	13 g	25 g	13 g	25 g	13 g	25 g	13 g
180	3500 h	3700 h	9000 h	9800 h	14000 h	15000 h	18000 h	19000 h
	40 g	30 g	40 g	30 g	40 g	30 g	40 g	30 g
200	3100 h	3700 h	8000 h	9000 h	12000 h	14000 h	17000 h	19000 h
	50 g	50 g	50 g	50 g	50 g	50 g	50 g	50 g
225	3100 h	3700	7200	8500	11000	13000	16000	17500
	65 g	30 g	65 g	30 g	65 g	30 g	65 g	30 g
250	2600 h	2600 h	6500 h	7200 h	10000 h	11000 h	15000 h	16000 h
	90 g	65 g	90 g	65 g	90 g	65 g	90 g	65 g
280	1800 h	2500 h	4700 h	6000 h	8500 h	9300 h	11800 h	12100 h
	100 g	80 g	120 g	100 g	120 g	100 g	120 g	100 g
315 S/M/L	1800 h	2500 h	4200 h	5500 h	7700 h	9300 h	11000 h	12100 h
	100 g	80 g	160 g	100 g	160 g	100 g	160 g	100 g
315 D	1800 h	1800 h	3600 h	3600 h	7000 h	7000 h	9500 h	9500 h
	100 g	100 g	220 g	220 g	220 g	220 g	220 g	220 g

Table 3-9: Regreasing intervals and grease quantity for motors with standard bearings; for nominal operation conditions at 50 Hz (data for motors operated at 60 Hz are available on request).

Frame size	Regreasing intervals at nominal operational conditions [h], grease quantity per bearing [g]							
	2-pole		4-pole		6-pole		8-pole	
	DE	NDE	DE	NDE	DE	NDE	DE	NDE
160	n.a.	n.a.	3300 h	10500 h	5100 h	16000 h	7100 h	21000 h
	n.a.	n.a.	25 g	13 g	25 g	13 g	25 g	13 g
180	n.a.	n.a.	3700 h	9800 h	6500 h	15000 h	1900 h	17000 h
	n.a.	n.a.	40 g	30 g	40 g	30 g	40 g	30 g
200	n.a.	n.a.	3600 h	9000 h	6200 h	14000 h	8200 h	19000 h
	n.a.	n.a.	50 g	50 g	50 g	50 g	50 g	50 g
225	n.a.	n.a.	3300 h	8500 h	5800 h	13000 h	7600 h	17500 h
	n.a.	n.a.	65 g	30 g	65 g	30 g	65 g	30 g
250	n.a.	n.a.	2800 h	7200 h	4600 h	11000 h	7000 h	16000 h
	n.a.	n.a.	90 g	65 g	90 g	65 g	90 g	65 g
280	n.a.	n.a.	2250 h	6000 h	3800 h	9300 h	5500 h	12100 h
	n.a.	n.a.	120 g	100 g	120 g	100 g	120 g	100 g
315 S/M/L	n.a.	n.a.	1900 h	5500 h	3400 h	9300 h	4500 h	12100 h
	n.a.	n.a.	160 g	100 g	160 g	100 g	160 g	100 g
315 D	n.a.	n.a.	1800 h	3600 h	3200 h	7000 h	4500 h	9500 h
	n.a.	n.a.	220 g	220 g	220 g	220 g	220 g	220 g

Table 3-10: Regreasing intervals and grease quantity for motors with reinforced bearings; for nominal operation conditions at 50 Hz (data for motors operated at 60 Hz are available on request).

The grease must be replaced at regular intervals depending on the motor size and its usage. The used grease exits through a grease drain. Regreasing intervals and grease quantity: see tables Table 3-9 and Table 3-10 and regreasing labels on the motor.

Regard that greasing intervals are given for operation at rated speed, nominal operation conditions and for horizontal mounting position. In case of vertical use the intervals shall be reduced to 50 %. In case of ambient temperature higher than 40 °C or when operated with higher speed than nominal the intervals have to be reduced according table below:

Ambient temperature	+40 °C	+50 °C	+60 °C
Recommended reduction of regreasing intervals	1	0,6	0,4
Continuous speed	nominal	1,5 x nominal	2 x nominal
Recommended reduction of regreasing intervals	1	0,6	0,5

Table 3-11: Rule of thumb for reduction of regreasing intervals

Details (grease type, recommendations for greasing procedure) can be seen on additional regreasing nameplates (close to the regreasing nipples) and the TECO manual "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS".

3.5 Degree of protection

The IEC classification system IEC 60034-5 defines the protection against external influence, e.g. degree "IP55". The first numeral describes the protection of people against contact with live parts and rotating parts and the protection against ingress of dust. The second numeral defines the protection against ingress of water.

As a standard the motors comply with degree IP55; this describes:

- The machine is completely protected against contact with live or rotating parts. Ingress of dust is not totally prevented, but dust does not enter in sufficient quantity to interfere with satisfactory operation of the machine.
- The machine is protected against water jets. Water projected by a nozzle against the machine from any direction has no harmful effect. (Remark: Restrictions concerning fan, degree IP20, and the shaft end are covered by standards).

This allows the operation of the motor in a rough environment.

In outdoor application the motor shall be protected against excessive solar radiation.

The motors are intended for use in a "Safe Area". Operation in "Hazardous Area" is not permitted.

Optionally IP56 or IP66 (dust tight; protection against powerful water jets) can be realized by reinforced sealing (see 3.4.3 Bearings, starting page 28).

3.6 Others

3.6.1 Grounding terminals

The grounding terminals are directly screwed into the motor frame and have no other function except of grounding, they comply with EN 60 204-1. Screws, washers and U-clamps are made of electro-zinc plated steel. They are labelled with the ground symbol defined in DIN EN 60 617-2: One terminal is located inside of the terminal box. The stator housing provides 4 external access points for grounding to allow easy access in every possible mounting position. The assembled grounding access point shall be free of primer or paint and shall be metallic blank. Only 1 access points is finally assembled ex factory (right hand side).

Design examples for grounding terminals:

- a) for motors frame size 80...250
- b) for motors frame size 280 and larger

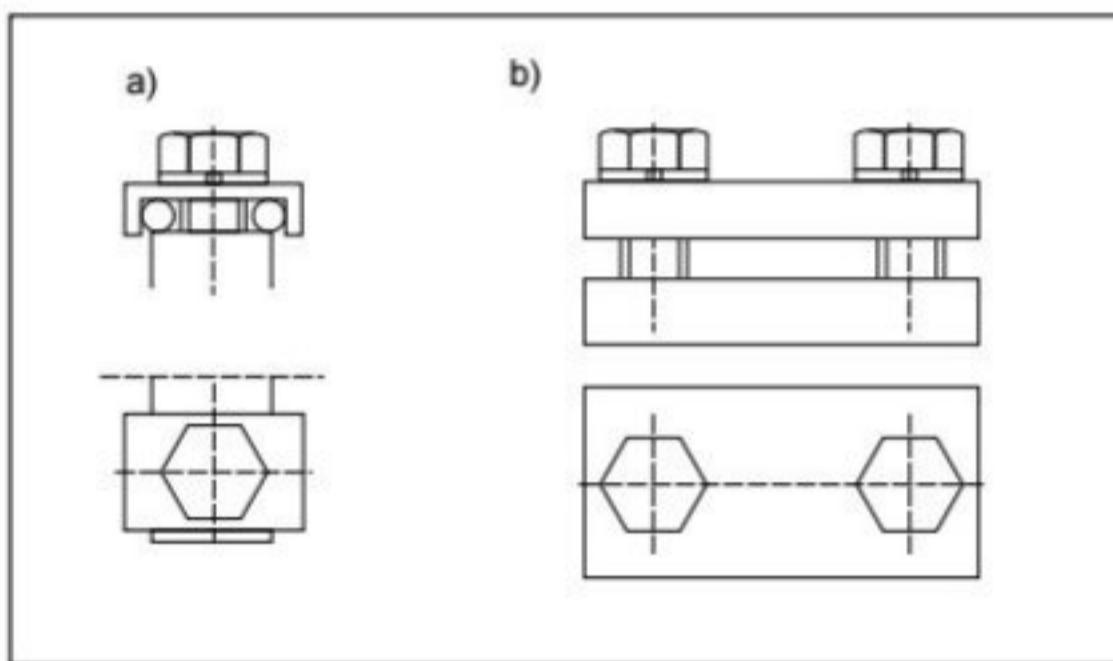


Figure 3-19: Design examples for grounding terminals

3.6.2 Lifting eyes

Using the lifting eye(s) is obligatory when transporting and lifting the motor; details see TECO manual "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS". The position of the lifting eye(s) can be seen in the sample figure below and in section 7 Outline drawings, starting page 82. In case of 2 lifting eyes (frame size 132 and larger) both of the 2 lifting eyes have to be used. They are located in a way that there is no collision with already installed power cables installed in axial direction.



Figure 3-20: Position of lifting eyes

3.6.3 Drain holes

As a standard no drain holes are provided. Drain holes can be drilled on customer's request for frame size 132 and larger. They will be located in the brackets or flanges and not in the housing to allow later modifications of the mounting arrangement.

3.6.4 SPM provision

Drilled, tapped and plugged holes with conical M8 thread for later shock pulse measurement nipple mounting on DE and NDE are provided for frame size 280 and above.

3.6.5 Painting, corrosion protection

Concerning corrosion the top coat is resistant to water, steam and salt water. Concerning chemical surrounding the top coat is resistant to hydraulic liquids, cleaning agents, synthetic coolants, solvents and chemicals. The coating is appropriate for a temperature range from -40 °C to +130 °C; it stays nonabrasive, elastic, scratch resistant and impact resistant through the whole temperature range. The motors are suitable for use in paint shops and are 100 % free of paint adhesion detrimental substances as for example silicone. Layer thickness see figure below.

	Cast iron, frame size ≤ 132 Aluminium motors ≤ 160	Cast iron, frame size ≥ 160
Primer for cast iron parts	min. 20 µm	min. 25 µm
Primer for aluminium parts	min. 20 µm	—
Primer for steel parts	min. 20 µm	min. 25 µm
Base prior to top coat	min. 20 µm	min. 50 µm
Top coat *	min. 20 µm	min. 25 µm
Total thickness of coating	min. 60 µm	min. 100 µm

*) The inner surface of the fan cowl is treated with primer only.

Table 3-12: Layer thickness of painting

As a standard the motor frame and fan cowl colour is grey (RAL 7032, pebble grey). For later customizing of the motor it is possible to spray a second layer of top coat (same thickness as standard coating) without influence to the thermal design of the motor.

All machined and metallic blank surfaces (feet, flange, 1 external grounding surface, shaft end) are protected against corrosion. The antirust agent can stay at the parts without influence to customer assembling (coupling) or mounting the motor to machine (max. layer thickness 5 µm).

3.6.6 Rating plate and labelling

The material of the rating plate is stainless steel and the data indicated are irremovable and clearly engraved or laserered. It is irremovably fixed (riveted) at the motor frame.

Rating plate data comply with IEC 60 034-1 and contain e.g. (see sample below):

- name of manufacturer
- serial number (a unique individual identification number) and year of construction
- reference to IEC standard
- efficiency level (efficiency class IE-code according to IEC 60 034-30)
- the CE marking
- technical data according to IEC 60 034-1.

The Rating plate is split into 2 sections, mounted on a common plastic base plate. The plastic base plate and the main section (bottom) of the rating plate are riveted to the motor frame. The upper section is solely wearing the manufacturer's brand and is clipped into the plastic base plate. As a standard it will carry the TECO-Brand; optionally with customer's brand instead. For original equipment manufacturers it is possible to remove the original brand plate easily and to clip an individual brand plate into the plastic base plate in site.



Figure 3-21: Sample of a TECO rating plate

Additional nameplates and markings:

- Connection diagram sticker with the wiring diagram, fitted on the inside of the terminal box lid
- In case of optional accessories: connection diagram sticker inside terminal box
- Grounding symbols according to DIN EN 60617-2
- Incase of regreasable bearings: regreasing nameplates (close to the regreasing nipples)

4 Electrical design

Squirrel cage motors as covered by this catalogue provide electrical active parts:

- **Rotor**
The active part is a rugged arrangement only consisting of the magnetic lamination and the short circuit "winding" made of cast aluminium embedded in slots.
- **Stator**
Contains the magnetic stator lamination, the three phase winding embedded in slots; including its insulation system and integrated temperature sensors.
- **Terminals**

4.1 Stator winding

The stator winding is carried out as a wire wound winding ("random winding"). High quality enamelled wires are used. Insulating sheets provide proper performance for

- insulation phase to ground,
- insulation phase to phase and
- interturn insulation.

An appropriate phase separation and a proper bandage of the winding overhang ensure high electric and mechanical strength. The stator winding is rotating dip impregnated with varnish or resin according to "thermal class F" requirements. According to the classification EN 60085 thermal class F allows a maximum hot spot temperature of 155 °C.

TECO motors covered by this catalogue are utilized (under nominal conditions) according to class "B":

- average temperature rise (by resistance method) is 80 °K;
- maximum spot temperature is 130 °C.

This ensures a high lifetime of the insulation system. (Insulation does not suddenly fail if the maximum temperature of the thermal class is reached, but useful operating life declines rapidly. A rule of thumb is a halving of life time for every increase of 10 °C.) As an option an additional finish for tropical protection (against fungus) can be provided (option "Tropical Climate Proof").



Figure 4-1: Stator core with winding



Figure 4-2: Stator core with slot liners

The winding features 3 phases which produce the rotating magnetic flux. All 6 winding ends are connected to the terminal box. The 3-phase line can be connected to the winding either in star connection (written as "Y") or delta connection (written as "D" or Δ), see figure below:

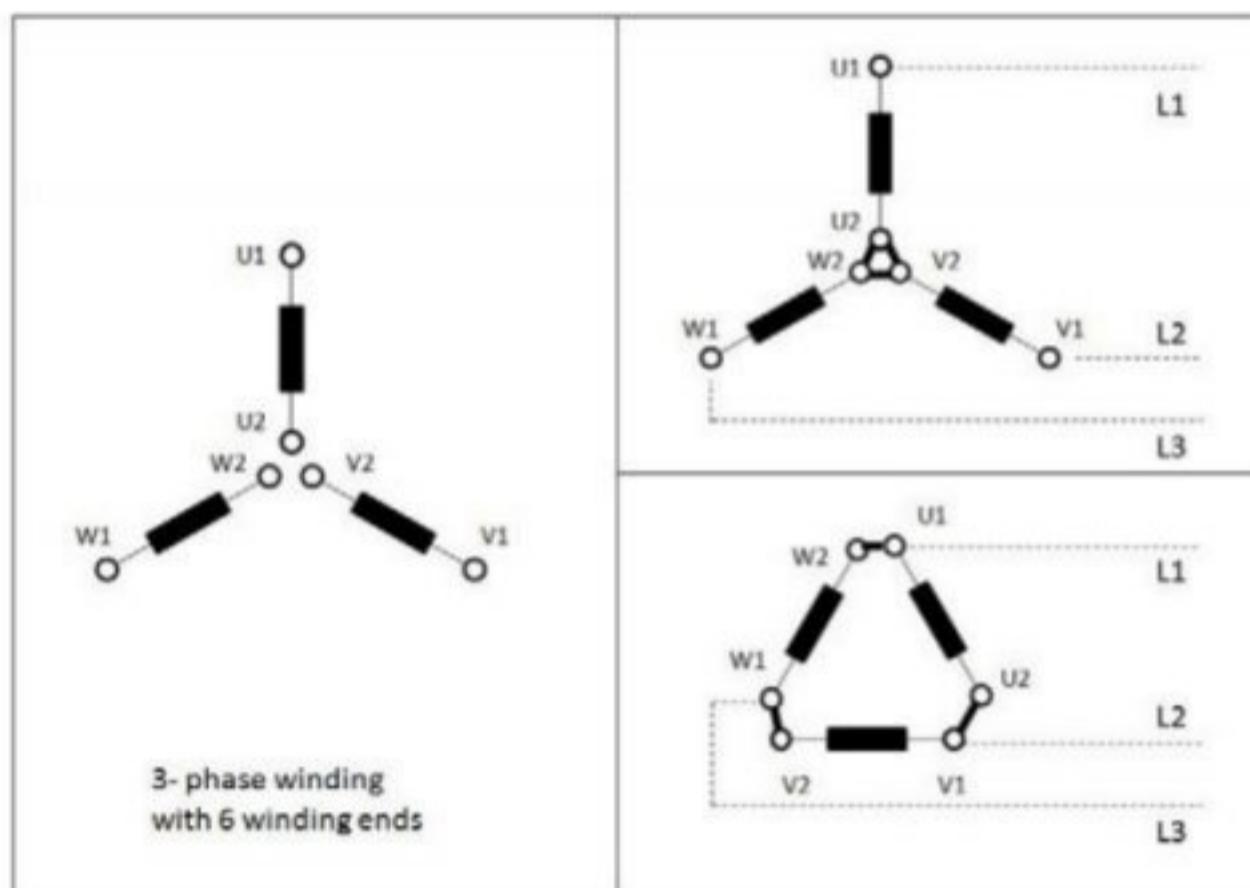


Figure 4-3: Three phase stator winding (star and delta connection)

These configurations allow operation of a certain motor at a higher line voltage level (e.g. 690 V with "star" connection) or at a lower line voltage (e.g. 400 V with "delta" connection). In case of dual rating: The rating plate is providing data for both applications (e.g.: "400 V/690 V D/Y; 129,4 A/75 A").

If the standard configuration of the motor for nominal voltage is designed as "delta" (preferred at higher power rating) the motor might be switched to "star" during starting by an external switchgear. This allows reduction of starting current (factor $\sqrt{3}$) and starting torque (factor 3).

The TECO standard configuration is shown in the table below:

Power rating [kW]	Line frequency [Hz]	Nominal voltage [V]; connection
≤ 2.2	50	230 V Δ / 400 V Y
	60	265 V Δ / 460 V Y
≥ 3.0	50	400 V Δ / 690 V Y
	60	460 V Δ

Table 4-1: TECO standard winding configuration and nominal voltage(s)

The configuration can be carried out by the user by inserting the jumpers of the terminal box; the spatial arrangement is shown in the figure below (standard sticker inside of the terminal box):

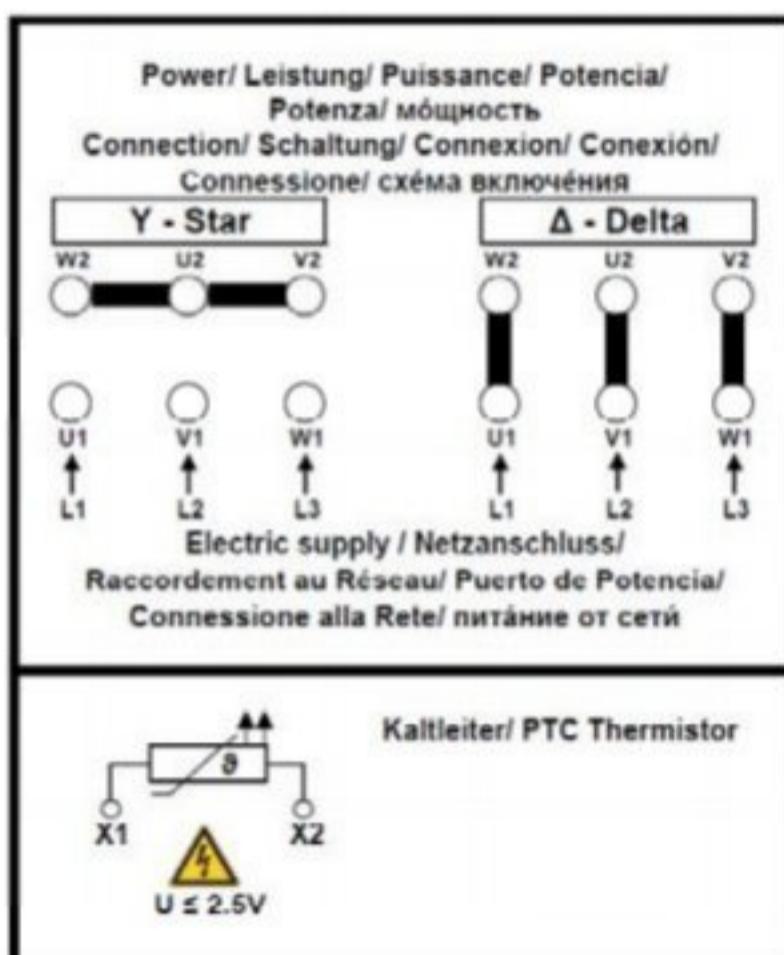


Figure 4-4: Arrangement of connection bolts and jumpers for star/delta connection

Phase sequence:

If the terminals are connected to an electrically clockwise supply system the motor is designed for clockwise mechanical rotation (when viewing from driving shaft end; according to IEC 60 034-8). For change of rotational direction a change of 2 supply line phases has to be carried out by customer.

4.2 Thermal protection

For thermal protection of the winding as a standard 3 temperature PTC thermistors are embedded in the winding; one for each phase (acc to standards IEC 60 034-11 and DIN 44081). Their nominal temperature level is 150 °C; when reaching this temperature their resistance suddenly escalates to a high level. They are connected in series and lead to terminals in the terminal box. A suitable monitoring device according to standard DIN 44081 shall be connected by customer and shall be used for tripping the system.

At inverter operation the use of this method of thermal protection is mandatory; protection measures based on operating current are not suitable in this case. A warning on the sticker inside the terminal box shows that no voltage higher than 2,5 V must be applied on these terminals.

5 Performance data

5.1 Duty type

The motors are designed for continuous operation at full load under nominal ambient conditions (duty type "S1" according to IEC 60034-1). Type data for differing duty types (S2...S8, periodic variation of load, influence of frequent starting stress, etc.) and S9 (non-periodic load and speed variation, e.g. at inverter operation) can be evaluated on request.

5.2 Environmental conditions, performance

All environmental conditions in site as listed in standard IEC 60721-3 (temperature, altitude, exposition to water, biological, chemical and mechanical active substances, vibrations, etc. have to be in accordance with the design of the motor (e.g. degree of protection).

5.2.1 Operation at high ambient temperature/high altitude

As a standard the motors are designed for

- ambient temperature (cooling air temperature): -20 °C up to +40 °C
- maximum altitude 1000 m above sea level

The motors can also be operated at higher ambient temperatures or at higher altitude if the continuous output power is reduced, see figures below. In this case the winding temperature rise is approximately identical to nominal operation. It has to be regarded that the bearing stress at higher temperature is increased and regreasing intervals shall be shortened accordingly then (see 3.4.3 Bearings, starting page 28).

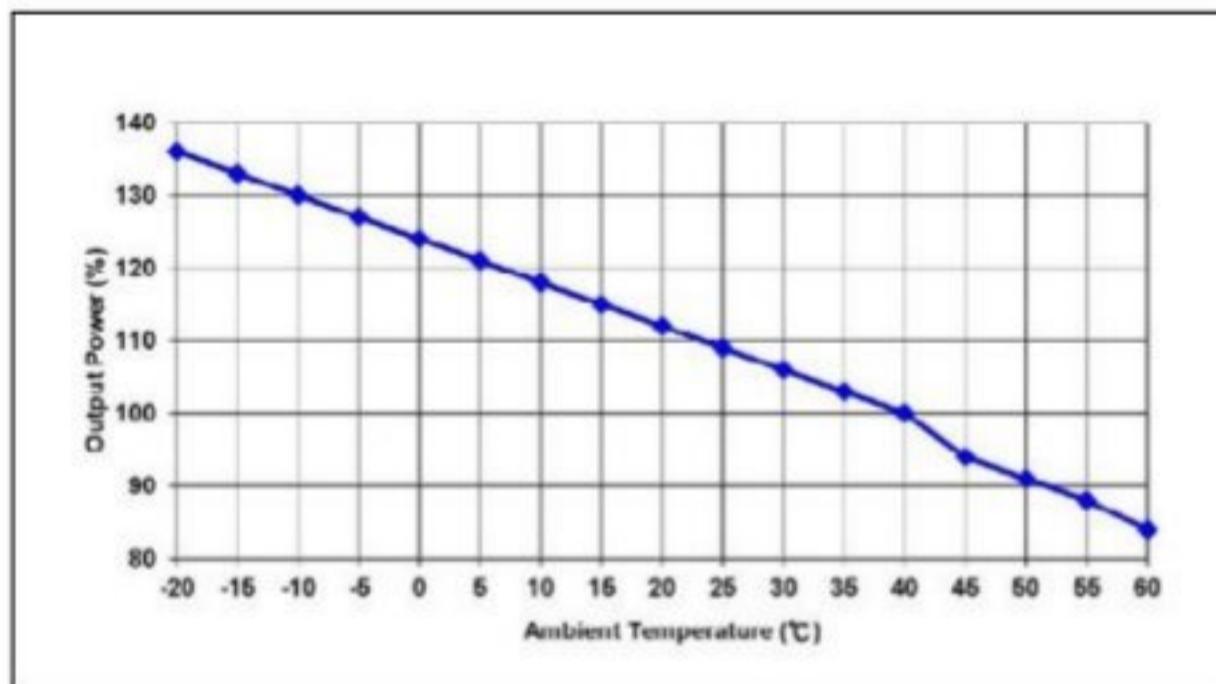


Figure 5-1: Reduction of output power versus ambient temperature

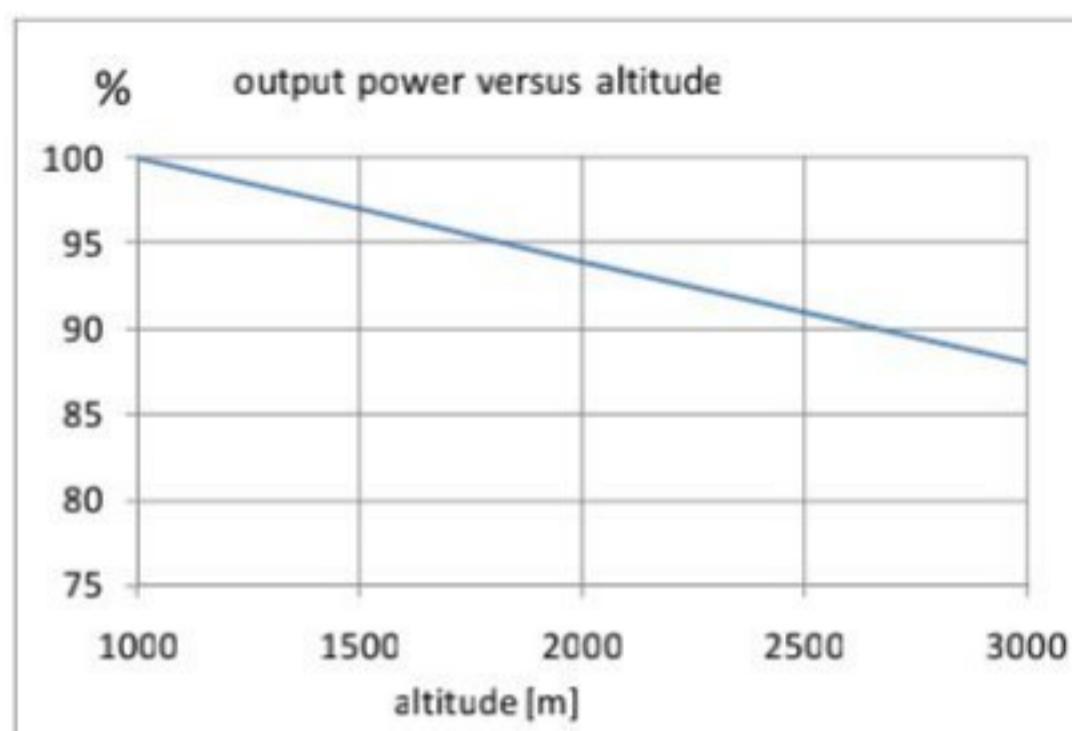


Figure 5-2: Reduction of output power versus altitude

Output with nominal power rating is permissible at high altitude, if accordingly the ambient temperature is reduced, see figure below:

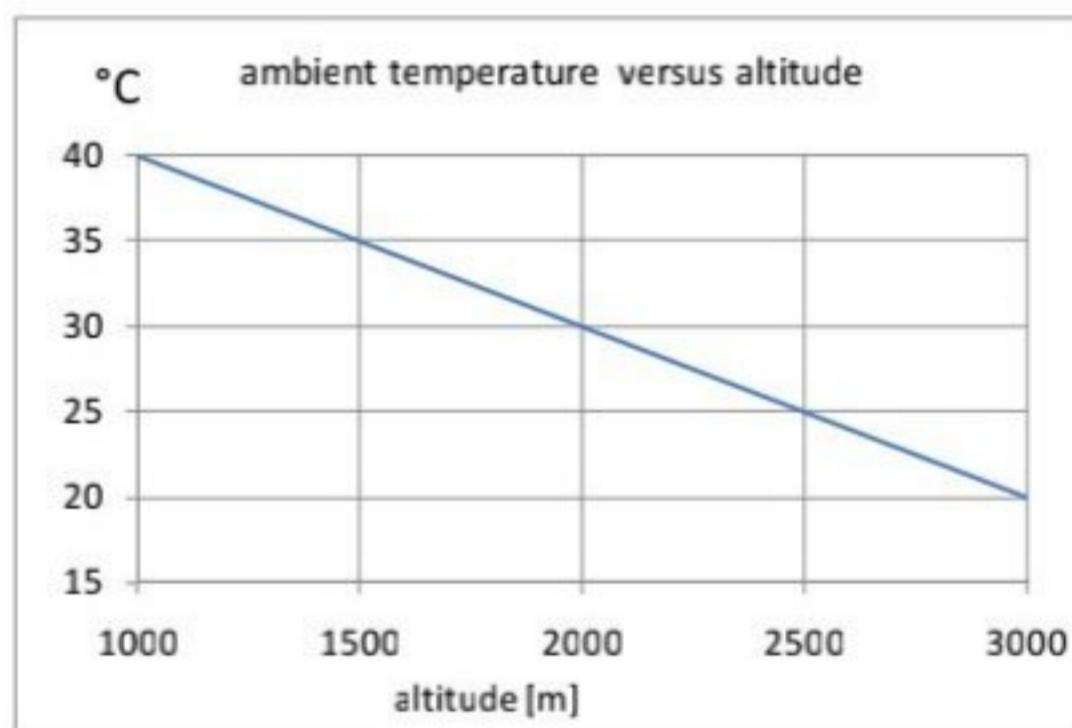


Figure 5-3: Reduction of ambient temperature versus altitude for nominal output rating

5.2.2 Operation at low temperature/high humidity

For operation at ambient temperature range -20°C to $+40^{\circ}\text{C}$ a heater for the motor winding is necessary at standstill. The same precaution is requested for operation in sites with normal temperature level, but high humidity (typically above 90 %) to prevent condensation inside the motor.

Heating can be carried out:

- By accessory "Heating via strip heater"
In this case additional terminals for the heater are provided within the terminal box. Heater terminals are marked with a voltage flash and a short note "Heater may be energized even if motor is isolated!" A special connection diagram sticker with the wiring diagram of the accessory is fitted inside terminal box lid.
Approx. heater power see Table 5-1, page 42.
- By heating the motor via stator winding. An auxiliary single phase AC voltage supply is to be connected to 2 power connectors. The appropriate voltage level and VA-rating depending on the motor size: On request. The safety precautions as mentioned above have to be regarded by the user.

Frame size	To prevent condensation			For ambient temperature -20 °C to -40 °C		
	Heater output [W]	Heater nominal voltage single phase AC [V]		Heater output [W]	Heater nominal voltage single phase AC [V]	
		230	400		230	400
63	10	10	10	10	10	10
71	10	10	10	10	10	10
80	20	20	20	20	20	20
90	20	20	20	20	20	20
100	30	30	30	30	30	30
112	30	30	30	30	30	30
132	40	40	40	40	40	40
160	40	40	40	40	40	40
180	50	50	50	50	50	50
200	50	50	50	50	50	50
225	60	60	60	60	60	60
250	60	60	60	60	60	60
280	150	150	150	150	150	150
315	200	200	200	200	200	200

Table 5-1: Availability and output power of option "Heating via Strip Heater"

5.2.3 Operation at severe mechanical conditions

For operation at extraordinary mechanical conditions (permanent exposure to vibration and shock higher than class 3M3 acc. to IEC 60721-3) we recommend a special request.

5.3 Mechanical performance

5.3.1 Torque characteristic; starting performance

The power rating (nominal power P_N) and the nominal torque (T_N) of each type is listed in 6 Technical data, starting page 58. The torque can be calculated in general as:

$$T = \frac{9550 \times P}{n}$$

where T = torque [Nm]
 P = power [kW] and
 n = speed [rpm].

The motors are equipped with a squirrel cage rotor (cast aluminium); they are suitable for direct starting. Direction of rotation is clockwise (view onto shaft end) if a clockwise supply system is connected according to the wiring diagram. Technical data of the standard motors are valid for both directions of rotation (bidirectional design). In IEC 600034-12 the starting performance is standardized.

During starting the motor creates a torque according to its individual characteristic (locked rotor torque, pull up torque and break down torque as generally described in 1.2.7 Performance characteristics: Speed, torque, starting page 11). Depending on the type an individual value for the torques is listed in 6 Technical data, starting page 58. A sample of a

TECO type test see figure below. In steady operation at full load torque the individual nominal speed (close to no load speed) is reached. It has to be regarded that this speed is only valid for thermal equilibrium conditions. If the motor is not heated up this speed will be significant closer to the no load speed. Limits and tolerances according to IEC standard: see 6.1 General data; tolerances (acc. to IEC 60034-1), starting page 58.

According to requirements of IEC 60034 the break down torque (including -10 % tolerance) has to be 160 % at least. The torque values are quadratic depending on a variation of line voltage. (Correspondingly the complete torque characteristic e.g. is reduced by a factor of 3 when starting the motor in star-delta).

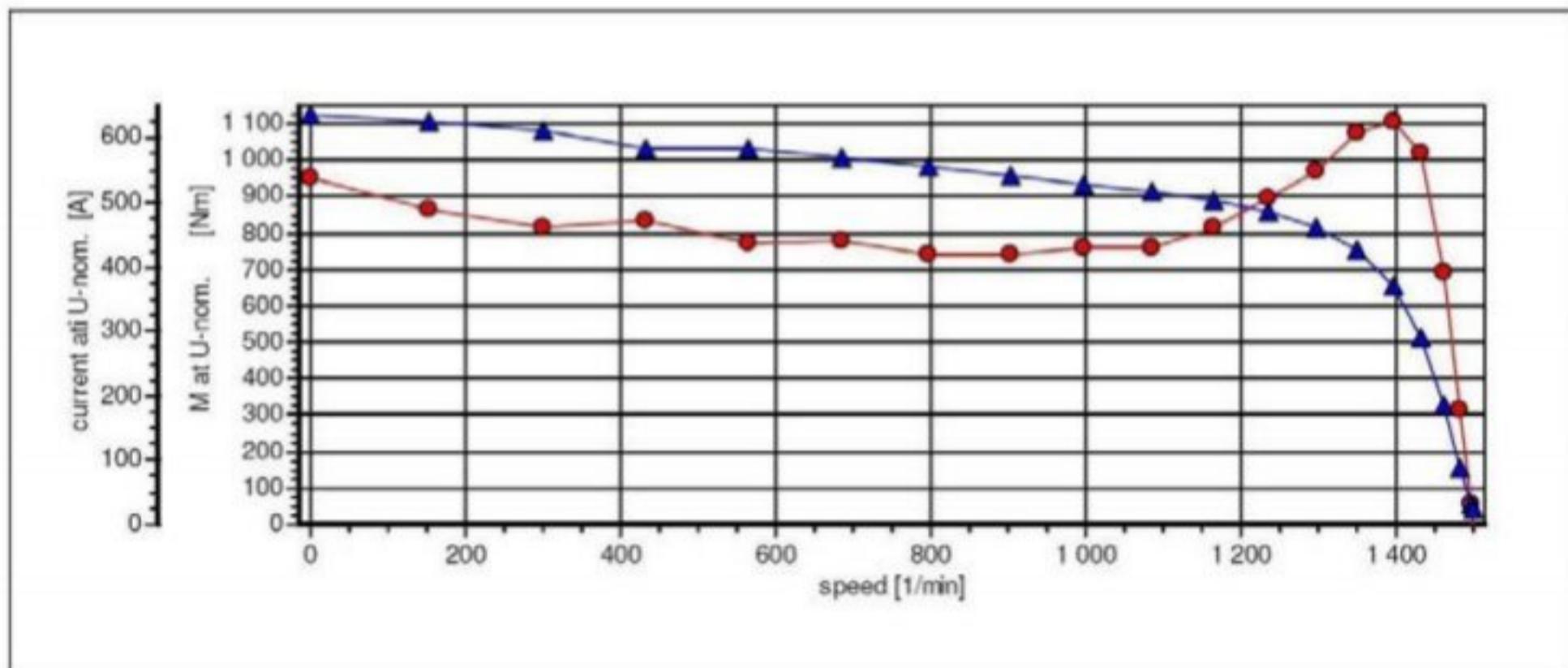


Figure 5-4: Sample of TECO type test data sheet: Torque and current vs. speed

5.3.2 Maximum operational speed

It is possible to increase the speed e.g. by feeding the motor from a frequency inverter with increased frequency. In general it shall be regarded at increased speed (also see 5.5 Motor performance (inverter operated), starting page 51):

- increase of acoustic noise level (especially contribution of fan noise)
- increase of vibration
- regreasing intervals shall be shortened accordingly then (see 3.4.3 Bearings, starting page 28)
- bearing life may be reduced
- maximal mechanically permissible operational speed limit,
see table below, following the requirements of IEC 60034-1; both for horizontal and vertical mounting:

Frame size	2-pole		4-pole		6-pole		8-pole	
	[min ⁻¹]	[Hz]						
63	5200	87	3600	120	2400	120	1600	106
71	5200	87	3600	120	2400	120	1600	106
80	5200	87	3600	120	2400	120	1600	106
90	5200	87	3600	120	2400	120	1600	106
100	5200	87	3600	120	2400	120	1600	106
112	5200	87	3600	120	2400	120	1600	106
132	4500	75	2700	90	2400	120	1600	106
160	4500	75	2700	90	2400	120	1600	106
180	4500	75	2700	90	2400	120	1600	106
200	4500	75	2300	77	1800	90	1200	80
225	3600	60	2300	77	1800	90	1200	80
250	3600	60	2300	77	1800	90	1200	80
280	—	—	—	—	—	—	—	—
315	—	—	—	—	—	—	—	—

Table 5-2: Maximal permissible operational speed

5.3.3 Permissible radial shaft forces

At operation with belt drive (or caused by other influences of the driven equipment) radial forces will impact on shaft end and bearings. For belt drives a rough estimation of the radial force can be carried out:

$$F_r \approx \frac{5000 \times P}{D \times n}$$

where F_r = radial force [N]
 P = power rating [kW]
 D = diameter of pulley [m] and
 n = speed [rpm].

The permissible radial force depends on the axial point of application of the external force, see figure below:

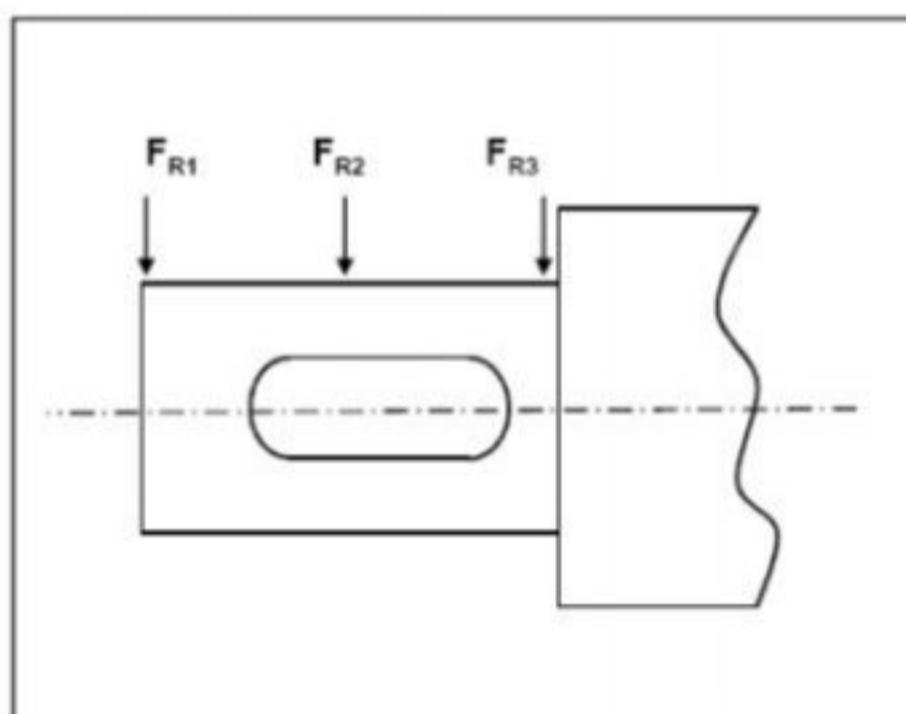


Figure 5-5: Axial point of application of the external radial force

The permissible radial thrust is given in the table below:

- for standard ball bearings and
- for optional version with cylinder roller bearings.

It has to be regarded that cylinder roller bearings demand a minimum radial force for proper operation.

Radial bearing load F_R [N]													
Frame size	poles	Load F_R for standard ball bearings						Load F_R for cylinder roller bearings					
		Aluminium motors			Cast iron motors			Cast iron motors					
		Max.	F_{R1}	F_{R2}	Max.	F_{R1}	F_{R2}	F_{R1}	F_{R2}	F_{R3}	Max.	Min.	
63	2				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	8				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
71	2				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
	8				n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	
80	2				558	620	682	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				699	777	855	n.a.	n.a.	n.a.	n.a.	n.a.	
	6							n.a.	n.a.	n.a.	n.a.	n.a.	
	8							n.a.	n.a.	n.a.	n.a.	n.a.	
90	2				583	659	736	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				741	838	936	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				849	961	1073	n.a.	n.a.	n.a.	n.a.	n.a.	
	8							n.a.	n.a.	n.a.	n.a.	n.a.	
100	2				830	932	1034	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				1039	1168	1296	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				1186	1333	1479	n.a.	n.a.	n.a.	n.a.	n.a.	
	8							n.a.	n.a.	n.a.	n.a.	n.a.	
112	2				1157	1293	1429	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				1465	1637	1809	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				1699	1898	2098	n.a.	n.a.	n.a.	n.a.	n.a.	
	8							n.a.	n.a.	n.a.	n.a.	n.a.	
132	2				1734	1970	2207	n.a.	n.a.	n.a.	n.a.	n.a.	
	4				2185	2428	2780	n.a.	n.a.	n.a.	n.a.	n.a.	
	6				2530	2834	3139	n.a.	n.a.	n.a.	n.a.	n.a.	
	8							n.a.	n.a.	n.a.	n.a.	n.a.	
160	2				2198	2507	2816						
	4				2740	3125	3511						
	6				3143	3541	3938						
	8												
180	2	n.a.	n.a.	n.a.	3141	3529	3917	6669	7407	8327	919		
	4	n.a.	n.a.	n.a.	3835	4316	4796	8027	8920	10036	804		
	6	n.a.	n.a.	n.a.	4398	4902	5405	9186	10135	11302	766		
	8	n.a.	n.a.	n.a.				n.a.	n.a.	n.a.	n.a.		
200	2	n.a.	n.a.	n.a.	3434	3793	4152	7350	8119	8888	1108		
	4	n.a.	n.a.	n.a.	4368	4825	5282	9075	10024	10973	960		
	6	n.a.	n.a.	n.a.	4965	5485	6004	10203	11271	12338	911		
	8	n.a.	n.a.	n.a.									
225	2	n.a.	n.a.	n.a.	4010	4401	4792	8233	9036	9839	1316		
	4	n.a.	n.a.	n.a.	4731	5346	5962	9503	10739	11976	1131		
	6	n.a.	n.a.	n.a.	5436	6112	6788	10817	12161	13506	1069		
	8	n.a.	n.a.	n.a.									
250	2	n.a.	n.a.	n.a.	4902	5441	5981	11585	12860	14135	1807		
	4	n.a.	n.a.	n.a.	6026	6685	7343	14149	15695	17240	1525		
	6	n.a.	n.a.	n.a.	7130	7909	8688	16194	17963	19732	1431		
	8	n.a.	n.a.	n.a.									
280	2	n.a.	n.a.	n.a.	5231	5685	6224	11638	12656	13856	2092		
	4	n.a.	n.a.	n.a.	7482	8255	9210	17635	19451	21692	2241		
	6	n.a.	n.a.	n.a.	8353	9210	10275	19671	21705	24216	2082		
	8	n.a.	n.a.	n.a.									
315 L	2	n.a.	n.a.	n.a.	5208	5514	5871	12114	12827	13642	2094		
	4	n.a.	n.a.	n.a.	8895	9786	10894	22106	24348	27100	2910		
	6	n.a.	n.a.	n.a.				24996	27531	30640	2679		
	8	n.a.	n.a.	n.a.									

Table 5-3: Permissible radial shaft forces

5.3.4 Permissible axial shaft forces

The permissible external forces in axial direction (direction towards DE or towards NDE) is depending on the mounting position of the motor:

- horizontal shaft,
- shaft up or
- shaft down.

The figures refer to standard bearing design (reinforced version on request) and operation at nominal speed or horizontal mounting; e. g. mounting B3, B5, B6, B7, B8, B14, B34, B35:

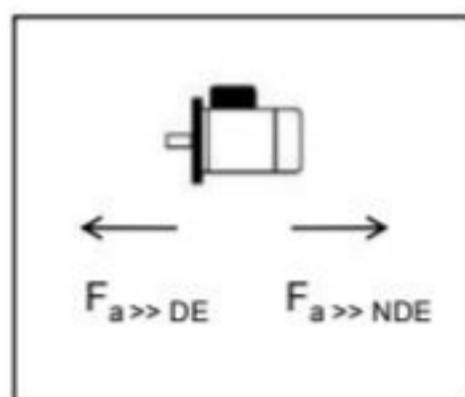


Figure 5-6: Mounting position "horizontal" and directions of axial force

Frame size	Maximal axial bearing load F_a [N]							
	2-pole		4-pole		6-pole		8-pole	
	$F_a >> NDE$	$F_a >> DE$	$F_a >> NDE$	$F_a >> DE$	$F_a >> NDE$	$F_a >> DE$	$F_a >> NDE$	$F_a >> DE$
	←	→	←	→	←	→	←	→
63								
71								
80	490	490	617	617				
90	470	470	676	676	774	774		
100	657	657	931	931	1068	1068		
112	911	911	1294	1294	1490	1490		
132	1401	1401	1960	1960	2254	2254		
160	1793	1793	2528	2528	2881	2881		
180	2470	2470	3440	3440	3920	3920		
200	2734	2734	3459	3459	4449	4449		
225	3165	3165	3920	3920	5018	5018		
250	3900	3900	4753	4753	6233	6233		
280	4106	4106	6085	6085	6860	6860		
315 S/M	3775	3775	6694	6694	7577	7577		
315 L	3645	3645	6713	6713	7693	7693		

Table 5-4: Maximal permissible axial bearing load for mounting position "horizontal"

5.3.5 Vibration

The motors are dynamically balanced with half key and the shaft end face is marked according to standard DIN ISO 8821 (marking "H" = half key). The balance quality meets DIN ISO 1940, Q2.5.

The mechanical vibrations of the motors meet level A according to EN 60034-14 at synchronous speed; standardized limits see table below (special design like full-key-balancing, no-key-balancing or vibration grade B on request.)

Frame size		56 to 132		160 to 280		> 280	
		Displac.	Veloc.	Displac.	Veloc.	Displac.	Veloc.
	Mounting	[µm]	[mm/s] RMS	[µm]	[mm/s] RMS	[µm]	[mm/s] RMS
Vibration Grade A	Free suspension	25	1.6	35	2.2	45	2.8
	Rigid mounting	21	1.3	29	1.8	37	2.3
Vibration Grade B	Free suspension	11	0.7	18	1.1	29	1.8
	Rigid mounting	n.a.	n.a.	14	0.9	24	1.5
Grade "A" applies to machines with no special vibration requirements; Grade "B" applies to machines with special vibration requirements.							

Table 5-5: Vibration limits according to IEC 60034-14

5.4 Motor performance (line operated)

The motors covered by this catalogue are low voltage asynchronous motors; designed for operation at a three phase AC voltage system (depending on the type; availability see 4.1 Stator winding, starting page 37):

- 230 V, 3 AC, 50 Hz,
- 400 V, 3 AC, 50 Hz,
- 690 V, 3 AC, 50 Hz, according to IEC 60038 and DIN IEC 60 038
- 265 V, 3 AC, 60 Hz,
- 460 V, 3 AC, 60 Hz.

The motors are designed for efficiency class IE2 (aluminium motors) and for both IE2 and IE3 (cast iron motors).

5.4.1 Requirements for supply voltage and frequency

Permissible tolerances of voltage and frequency at operation IEC 60034-1 defines 2 ranges of permissible variation of voltage and frequency, "Zone A" and "Zone B", see figure below:

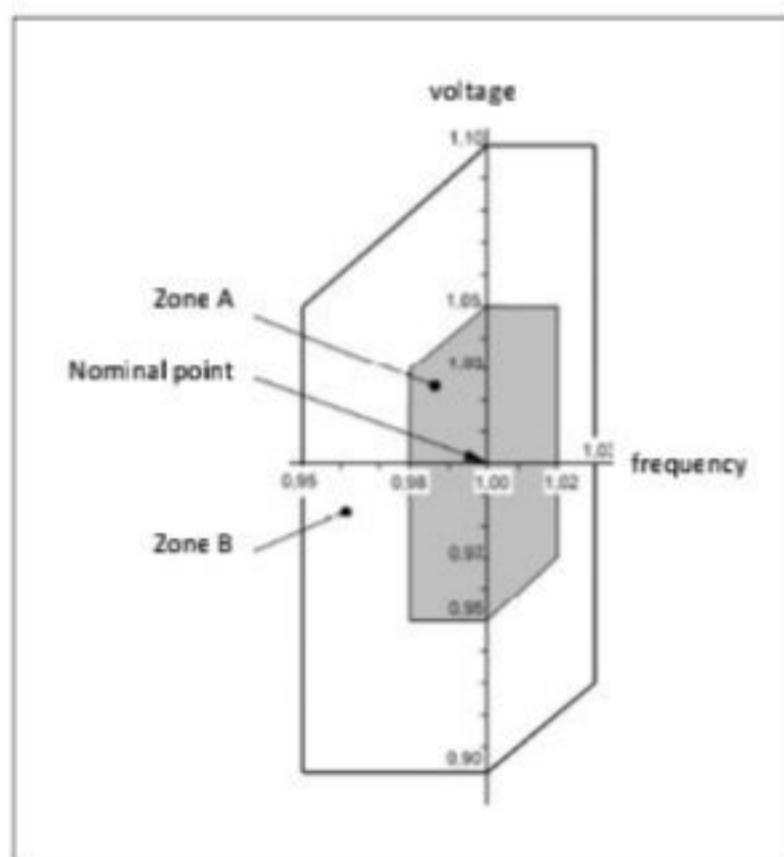


Figure 5-7: Permissible tolerance of voltage and frequency acc. to IEC 60034-1

"Zone A":

According to IEC 60034-1 the motor is suitable to perform its nominal torque continuously. The performance characteristics may have deviations from the nominal values and the temperature rise is higher than nominal.

"Zone B":

(continuous operation is explicitly not recommended by IEC 60034-1): The motor is suitable to perform its nominal torque continuously. The performance characteristics may have greater deviations from the nominal values; the temperature rise is higher than within "Zone A".

Requirements for waveform and unbalance of the supply voltage: Distortion of the sinusoidal waveform (caused by neighbouring power electronics) and unbalance of the voltage system (e.g. caused by single-phase loads) is permissible within the limits given in IEC 60034-1 section 7.2.1.1 (distortion factor HVF < 3 % and negative sequence component < 1 %).

Special requirements (voltage peaks) have to be observed at inverter operation: see 5.5 Motor performance (inverter operated), starting page 51.

5.4.2 Current, power factor and efficiency at partial load

The general characteristic is shown in section 1 (e.g. Figure 1-4, page 13).

Type specific data for TECO motors:

- Values for the nominal point can be seen on the rating plate and in 6 Technical data, starting page 58.
- Values for partial load (power factor and efficiency) can be seen in 6 Technical data, starting page 58, columns 1/4, 2/4 and 3/4 partial load.

Overload capability according to IEC 60034-1 section 9:

- 150 % of nominal current during 2 min. at least;
- Min. 160 % of full load torque for 15 sec.

5.4.3 Current during starting, limitations

General characteristic: see 1.2 Basics, terms and definitions, starting page 9 (sample for a TECO type test protocol: see Figure 5-4, page 43). Type specific data for TECO motors are evaluated during type test and are available on request.

Overload capability:

A minimum of overload capability is defined in IEC 60034-1 section 9:

- Min. 2 min. at 150 % of nominal current (for motors with power rating up to 315 kW);
- Min. 160 % of full load torque for 15 sec.

Locked rotor:

The motors are suitable for direct starting; however the high current during starting causes a high thermal load for the stator winding and especially for the rotor.

A maximum locked rotor time has to be regarded, depending on the type. The table below shows the max. duration when starting at cold machine and at nominal operation temperature:

Nominal power [kW]	Maximum locked rotor time [s]: 50 Hz; cast iron; IE2 version (n.a. = not available)							
	2-pole		4-pole		6-pole		8-pole	
	Cold	Hot	Cold	Hot	Cold	Hot	Cold	Hot
0.18	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	102.9	51.4
0.25	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	95.2	47.6
0.37	n.a.	n.a.	n.a.	n.a.	53.3	26.7	116.9	58.4
0.55	n.a.	n.a.	39.2	19.6	73.0	36.5	82.0	41.0
0.75	17.3	8.6	37.4	18.7	61.9	30.9	57.0	28.5
1.1	11.1	5.6	30.4	15.2	47.4	23.7	52.8	26.4
1.5	10.8	5.4	25.9	13.0	45.9	23.0	41.5	20.8
2.2	10.2	5.1	23.3	11.7	29.5	14.7	23.1	11.6
3	10.1	5.0	20.9	10.5	28.9	14.5	20.8	10.4
4	16.6	8.3	14.4	7.2	25.2	12.6	40.2	20.1
5.5	10.5	5.3	17.8	8.9	22.9	11.5	32.0	16.0
7.5	10.2	5.1	11.4	5.7	19.3	9.7	32.7	16.4
11	18.5	9.2	15.9	7.9	17.4	8.7	25.4	12.7
15	14.1	7.0	12.3	6.2	24.1	12.1	31.2	15.6
18.5	15	7.5	37.1	18.5	31.9	15.9	51.8	25.9
22	18.8	9.4	29.9	14.9	31.7	15.8	53.4	26.7
30	22.0	11.0	17.2	8.6	34.3	17.1	41.6	20.8
37	18.9	9.5	26.3	13.1	38.6	19.3	30.9	22.1
45	20.4	10.2	21.3	10.7	19.7	14.1	27.7	19.8
55	24.9	12.4	19.9	9.9	19.9	14.2	20.6	14.7
75	13.4	9.6	10.4	7.4	18.2	13.0	19.0	13.6
90	11.9	8.5	8.5	6.1	15.5	11.1	18.3	13.1
110	14.0	10.0	10.5	7.5	16.2	11.6	17.9	12.8
132	12.9	9.2	9.1	6.5	16.1	11.5	14.1	10.1

Performance data



Nominal power [kW]	Maximum locked rotor time [s]: 50 Hz; cast iron; IE2 version (n.a. = not available)							
	2-pole		4-pole		6-pole		8-pole	
	Cold	Hot	Cold	Hot	Cold	Hot	Cold	Hot
160	10.2	7.3	9.7	6.9	12.3	8.8	13.9	9.9
200	9.4	6.7	8.5	6.1	12.2	8.7	13.2	9.4
250	9.9	7.1	9.9	7.1	10.8	7.7	12.2	8.7
315	9.1	6.5	8.1	5.8	14.6	10.4	n.a.	n.a.

Nominal power [kW]	Maximum locked rotor time [s]: 60 Hz; cast iron; IE2 version (n.a. = not available)							
	2-pole		4-pole		6-pole		8-pole	
	Cold	Hot	Cold	Hot	Cold	Hot	Cold	Hot
0.18	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	102.9	51.4
0.25	n.a.	n.a.	n.a.	n.a.	n.a.	n.a.	95.2	47.6
0.37	n.a.	n.a.	n.a.	n.a.	53.0	26.5	116.9	58.4
0.55	n.a.	n.a.	38.2	19.1	66.7	33.4	82.0	41.0
0.75	14.4	7.2	34.8	17.4	58.4	29.2	57.0	28.5
1.1	10.8	5.4	27.7	13.8	44.8	22.4	52.8	26.4
1.5	10.0	5.0	23.7	11.8	39.6	19.8	41.5	20.8
2.2	10.4	5.2	20.5	10.3	23.7	11.9	23.1	11.6
3	10.1	5.0	16.8	8.4	23.0	11.5	20.8	10.4
4	13.7	6.8	15.5	7.7	20.0	10.0	42.5	21.3
5.5	11.2	5.6	23.9	12.0	17.1	8.6	33.0	16.5
7.5	10.1	5.1	10.5	5.3	18.4	9.2	34.4	17.2
11	17.8	8.9	16.5	8.2	16.4	8.2	24.5	12.2
15	14.5	7.2	16.2	8.1	22.7	11.4	24.8	12.4
18.5	16.4	8.2	25.7	12.9	24.9	12.4	47.8	23.9
22	16.6	8.3	22.8	11.4	24.6	12.3	50.2	25.1
30	16.7	8.4	16.4	8.2	30.3	15.1	29.2	14.6
37	16.5	8.2	22.9	11.5	27.4	13.7	33.9	24.2
45	16.4	8.2	16.7	8.4	26.2	18.7	33.2	23.7
55	21.8	10.9	16.8	8.4	24.5	17.5	24.5	17.5
75	16.7	11.9	15.5	11.1	20.3	14.5	23.9	17.1
90	14.1	10.1	12.7	9.1	17.4	12.4	15.5	11.1
110	17.9	12.8	11.8	8.4	16.8	12.0	15.1	10.8
132	13.7	9.8	10.5	7.5	24.5	17.5	23.9	17.1
160	11.6	8.3	8.4	6.0	17.8	12.7	15.5	11.1
200	11.5	8.2	8.4	6.0	13.2	9.4	15.1	10.8
250	10.8	7.7	8.3	5.9	12.3	8.8	n.a.	n.a.
315	8.4	6.0	7.4	5.3	15.5	11.1	n.a.	n.a.

5.5 Motor performance (inverter operated)

5.5.1 General

When line operated, asynchronous motors provide an almost fixed rotational speed depending on line frequency and pole number. When feeding the motor by an electronic frequency inverter with variable frequency and voltage a "Variable Speed Drive System" is generated. It shows remarkable benefits for energy efficiency and enables a low-cost and maintenance-free solution for flexible control of processes. (Control system which only are varying the voltage are not covered here; they are only permissible for short-term use like soft starters).

Technical details can be seen in IEC 60034-17 (for general purpose motors) and IEC 60034-25 (for motors especially designed for inverter operation). The motors covered by this catalogue are general purpose motors; they are suitable for operation with a frequency inverter. Several items have to be observed when the motors are inverter operated (details following sections):

General:	see section ...
additional losses due to non-sinusoidal supply voltage	5.5.3
increased winding insulation stress	5.5.4
increased acoustic noise level due to non- sinusoidal supply voltage	5.5.7
additional bearing currents	5.5.5
EMC considerations	5.5.6
Depending on operational range:	
decreased cooling of self-ventilated motors at low speed	5.5.3
increased acoustic noise level of self-ventilated motors at high speed	5.5.7
shortening of regreasing intervals when permanently operated at high speed	3.4.4
max speed due to decrease of breakdown torque in the field weakening range	6 (breakdown torque)
Maximum operational speed	5.3.2

5.5.2 Operational range; principle

At inverter operation (variable frequency and voltage) the speed-torque-characteristic curve of the motor (see Figure 1-2, page 11) can be shifted along the speed axis in any position. It allows permanent operation at any speed and torque at both directions of rotation. Depending on the design of the inverter operation in the generator range is possible as well:

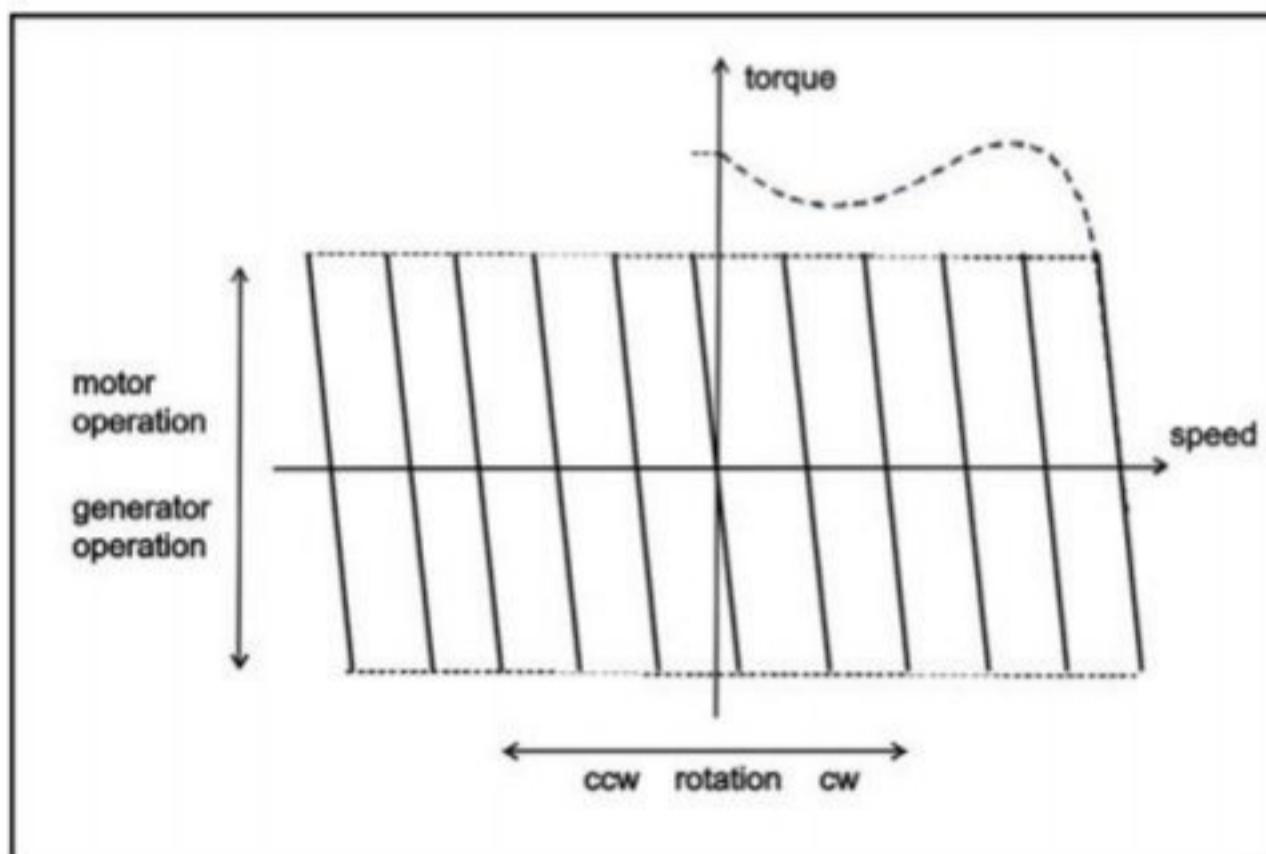


Figure 5-8: Operational range of inverter operated induction motors (range with constant flux)

In addition the frequency can also be adjusted be higher than the nominal frequency while the voltage is kept constant (field weakening operation). The operational range then is defined by two sections, see figure below:

- constant flux range: frequency and voltage are almost proportional; the achievable torque is constant
- field weakening range: frequency is increased at constant voltage: the achievable power is constant.

Remark: In the field weakening range a quadratic decrease of breakdown torque has to be regarded. Thus the max speed may be restricted depending on the motor data.

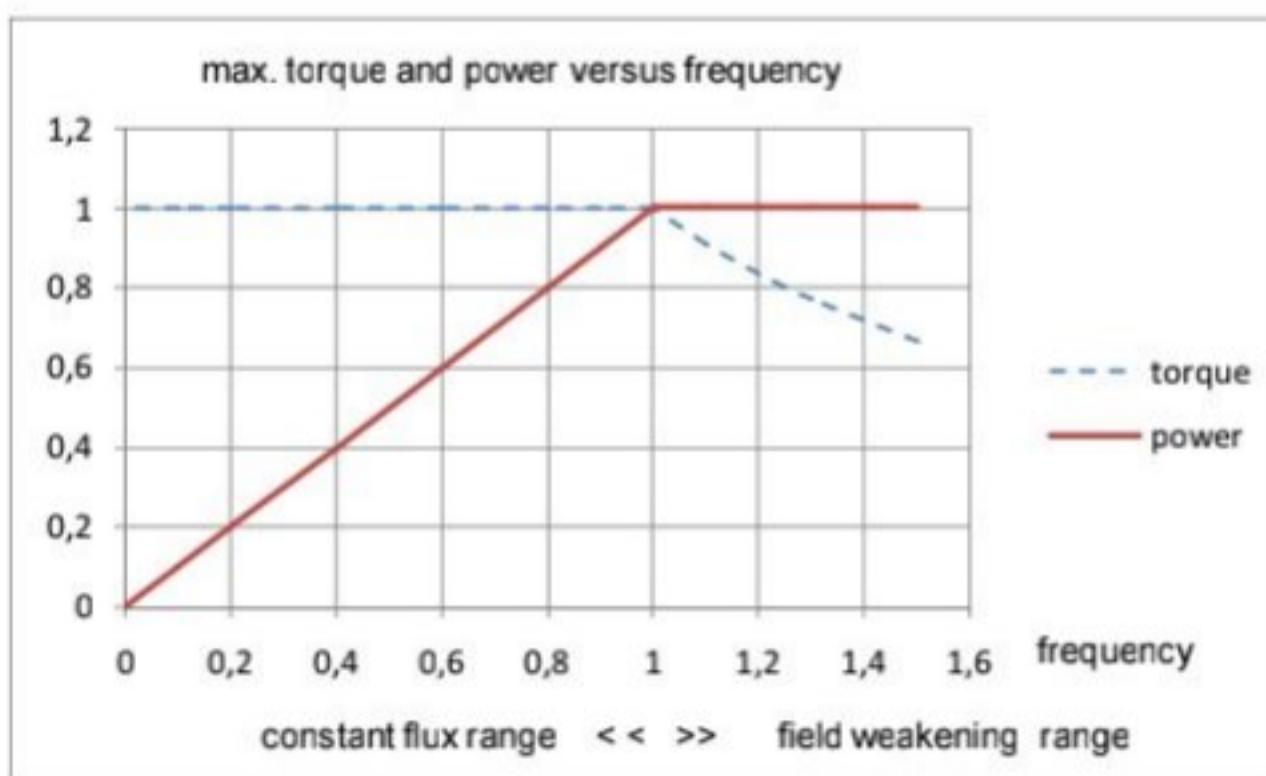


Figure 5-9: Max. torque and power versus frequency

5.5.3 Operational range for continuous operation

In general the inverter provides a non-sinusoidal supply voltage for the motor. As a consequence additional harmonic currents and additional losses are generated, especially in the rotor. The amount of additional losses is depending on the design of the inverter. In case of a PMW inverter (voltage source inverter with pulse shaped output voltage) the losses are significantly depending on the pulse frequency. As a rough figure the pulse frequency shall be 3 kHz–5 kHz at least under this aspect. Motors covered by this catalogue in general are suitable for continuous operation with nominal output under this precondition.

Configuration for 87 Hz:

If a motor is designed for 50 Hz in star connection of the winding, it can be operated up to 87 Hz in constant flux operation, if the winding connection is changed to delta connection. The theoretically achievable maximal power then is $\sqrt{3}$ of nominal at $\sqrt{3}$ of nominal speed. However, as the core losses are increased at higher frequency, the output power for continuous operation at 87 Hz is only approximately in the range of 1,5 of nominal (small motors) and 1,2 of nominal (large motors), see figure below. The exact value for a specific motor type and type of inverter can be evaluated on request. (Max. mechanical speed for the motor type has to be regarded.)

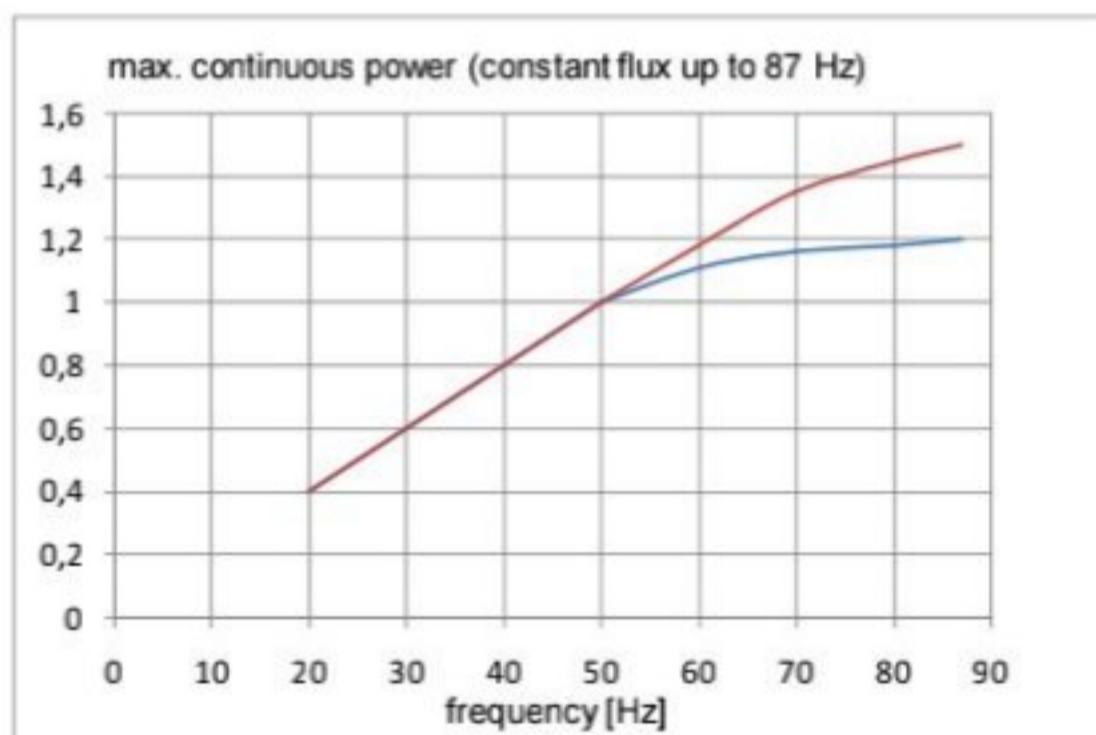


Figure 5-10: Typical characteristics for max. continuous power in "87 Hz-configuration"

Maximum permissible torque and power for continuous operation within the speed range: In 5.5.2 Operational range; principle the achievable characteristics are shown. For continuous operation it has to be regarded that the losses of the motor and (in case of self ventilated design) the heat transfer is depending on the operation point. As a consequence the typical characteristics for maximum permissible torque versus speed (and power versus speed) is given; see figures below. (speed 0...1 = operation with nominal flux; speed > 1 = field weakening operation). The exact value for a concrete motor type and type of inverter can be evaluated on request.

Remark: In the field weakening range a quadratic decrease of breakdown torque has to be regarded. Thus the max speed may be restricted depending on the motor data.

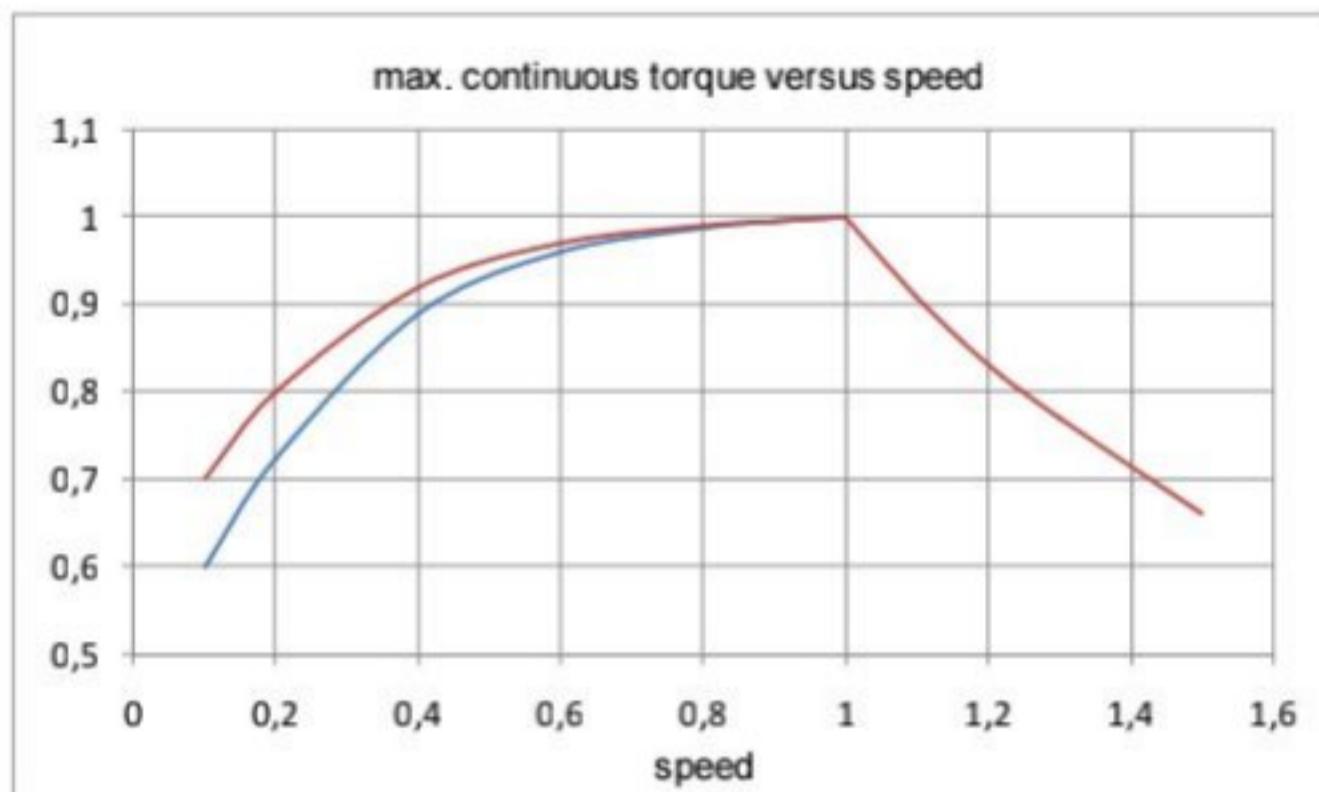


Figure 5-11: Typical max. continuous torque (self ventilated motors)



Figure 5-12: Typical max. continuous power (self ventilated motors)

For drive application with quadratic torque characteristic this restriction is not relevant. Drives with constant torque demand either a motor with accordingly higher rating or the use of forced ventilation. If forced ventilation is used (cooling method "IC 416" according to IEC 60034-6) the cooling is independent from the motor speed. Continuous operation is permissible according to figure below:

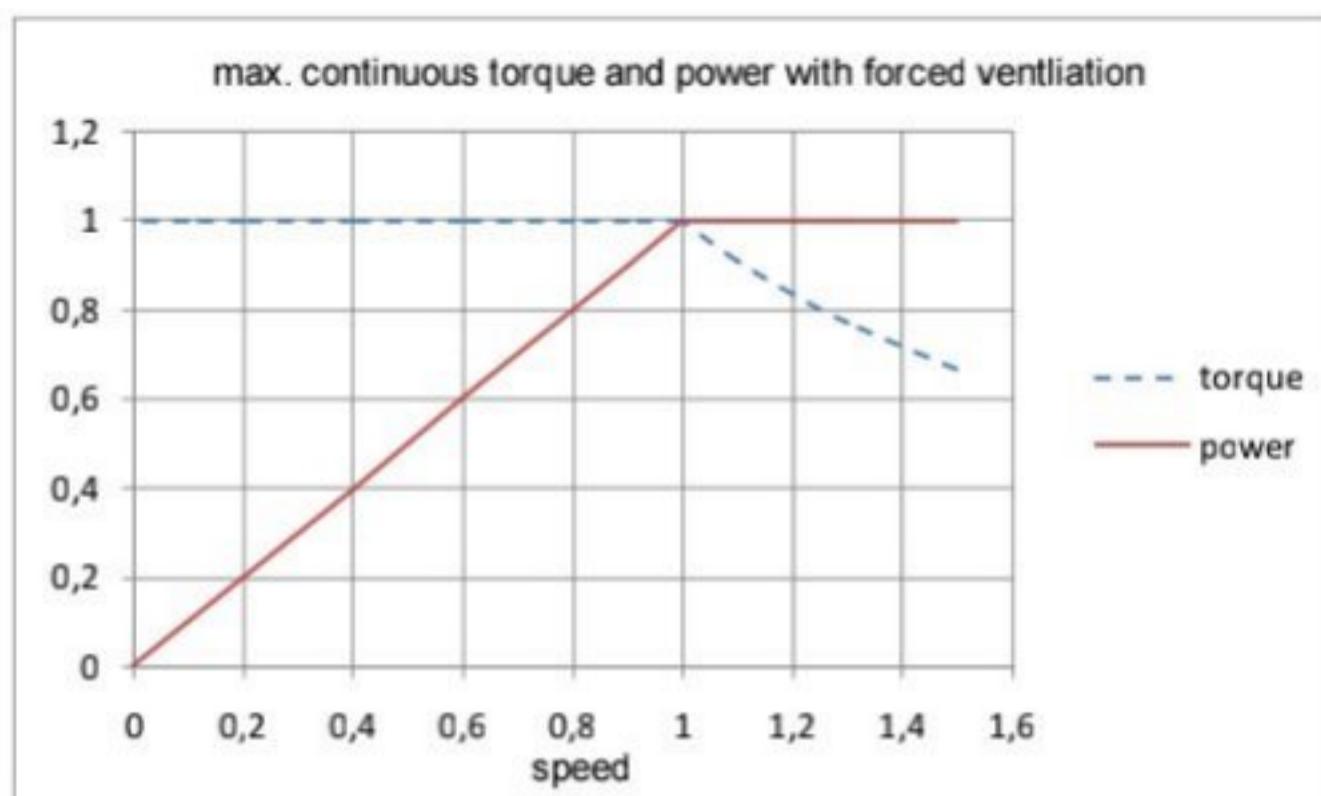


Figure 5-13: Max. continuous torque and power (motors with forced ventilation)

5.5.4 Winding insulation stress

In case of using PWM inverters a pulse shaped voltage is applied to the motor winding. The height of the voltage pulses is depending on the DC link voltage. In addition the voltage pulses show a voltage overshoot. Waveform and peak voltage are a function of both motor cable length and inverter specific pulse shape.

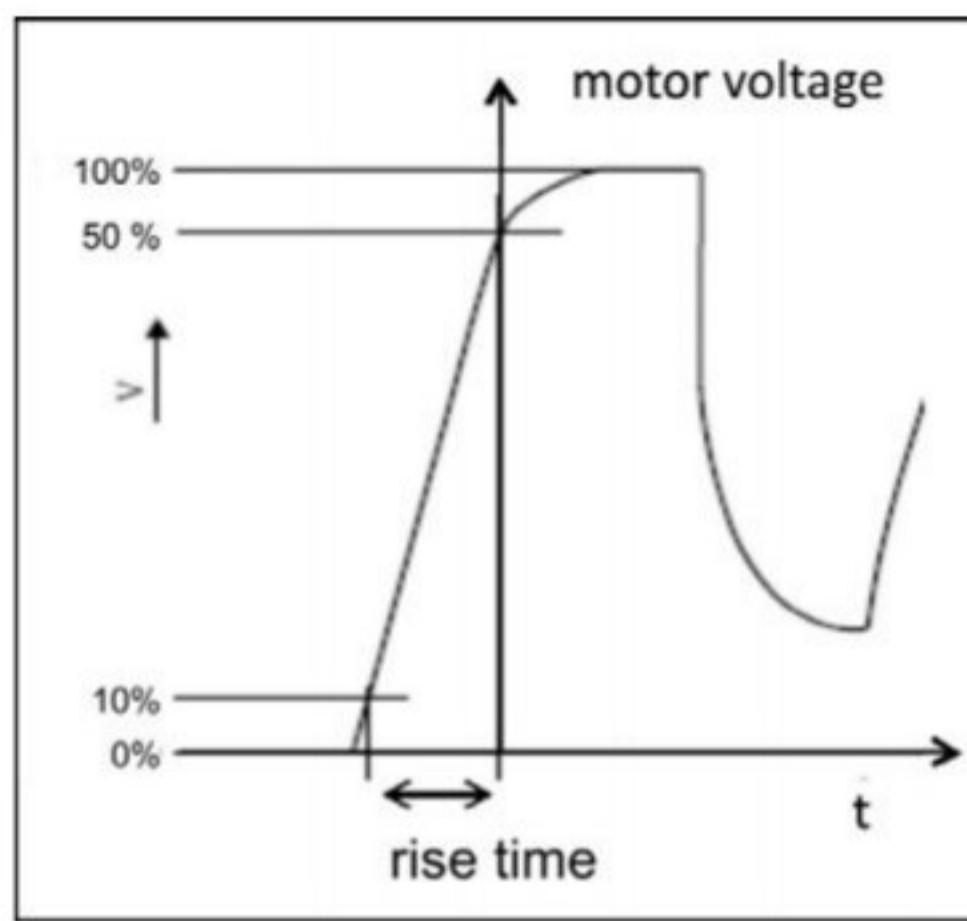


Figure 5-14: Typical pulse waveform and definition of rise time according to IEC 60034-17

Short rise time of the voltage pulses effects an unbalanced voltage contribution within the winding and therefore increases the dielectric stress. The winding stress is defined as a combination of both peak voltage and voltage rise time. A characteristic describes limits for admissible peak voltage versus voltage versus rise time. In IEC Technical Specification "TS 60034-17" (Cage induction motors when fed from converters- Application guide; edition 2006-05) a limit curve is defined for general purpose motors. Motors covered by this catalogue comply with the curve in this standard, shown in the diagram below:

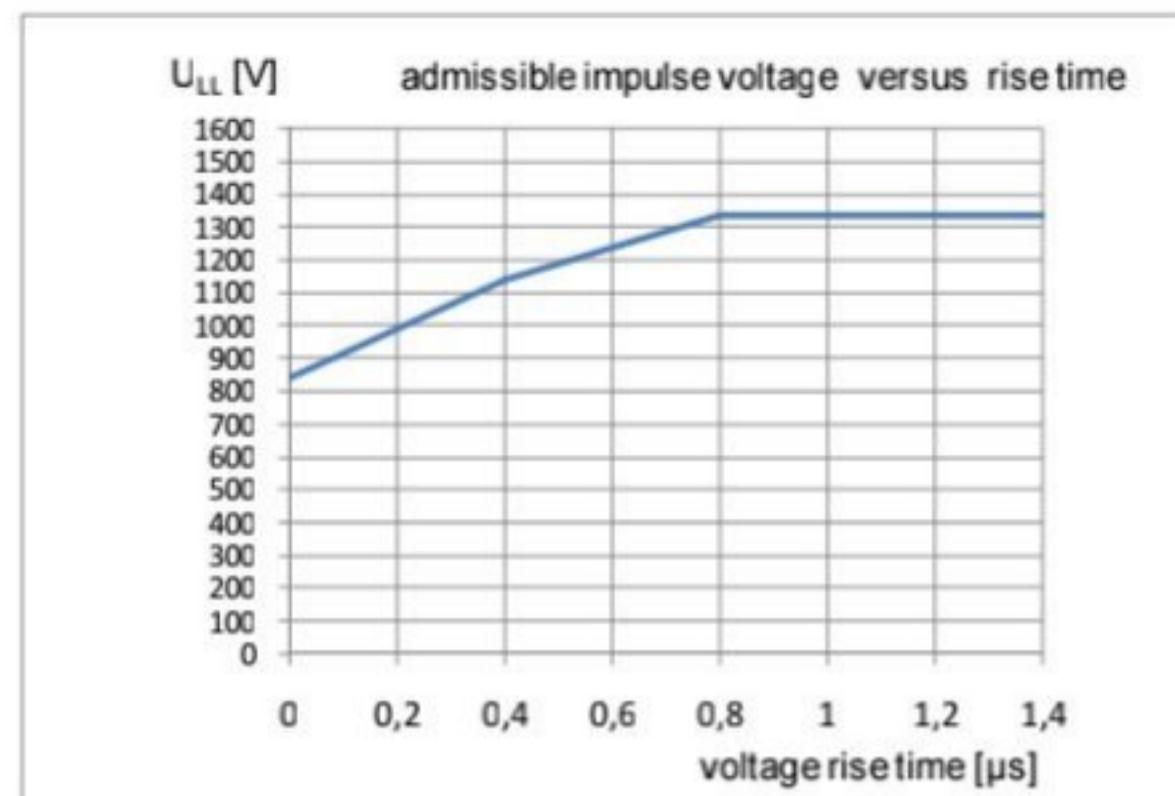


Figure 5-15: Admissible peak voltage versus rise time according to IEC TS 60034-17 (2006)

At high nominal voltage level (e.g. 690 V) and especially in case of long motor cables these requirements can only be fulfilled by using "dV/dt filters" which are increasing the voltage rise time and decrease the amount of voltage overshoot. In some cases even expensive "sine wave filters" may be required.

5.5.5 Inverter caused bearing currents

PWM inverters in general are generating a high frequency "common mode voltage". There are several mechanisms which can produce harmful high frequency current through the bearings. A listing of possible counter measures can be seen below:

Counter measure	Remarks
Insulation of NDE bearing	Recommended by TECO for frame size 280 and higher
Inverter filters (dV/dt filter; common mode filter)	
Choice of a low inverter switching frequency	
Use of non-conductive coupling	
Symmetric power cabling and effective motor grounding	

As a simplified rule to avoid problems both with bearing current and winding insulation TECO recommends general precautions according table below (voltage limits according to the insulation system chosen has to be regarded):

TECO general recommendations		
Rated voltage	Frame size < 250	Frame size ≥ 280
≤ 460 V	Standard motor (Motor cable lengths < 20 m)	Standard motor + Insulated NDE bearing
≤ 600V	Standard motor + dV/dt-filter (reactor) or Reinforced insulation	Standard motor + dV/dt-filter (reactor) + Insulated NDE bearing or Reinforced insulation + Insulated NDE bearing
≤ 690V	Reinforced insulation + dV/dt-filter (reactor)	Reinforced insulation + dV/dt-filter (reactor) + Insulated NDE bearing

Table 5-6: TECO recommendations for general precautions at inverter operation

5.5.6 Electromagnetic compatibility

If squirrel cage motors are line operated, the electromagnetic emissions are regarded as negligible (see IEC 60034-1, section 13). The motors meet the limit values of Class B of EN 55011 and therefore can be used both in industrial and residential environment.

If inverter operated the EMC performance can only be considered for the complete drive system (inverter, filters, cabling, motor) as an entity, according to the relevant product standard EN 61800-3 ("Adjustable speed electrical power drive systems; EMC requirements and specific test methods...").

For this purpose TECO motors e.g. are equipped with a metallic terminal box with cable entries suitable for the use of EMC-compliant cable glands.

5.5.7 Additional acoustic noise

Due to the non-sinusoidal motor voltage the acoustic noise level in general is increased at inverter operation. The increase is depending on the type and technical data of the inverter (at PWM inverters especially the pulse frequency and the pulse generation method) and cannot be stated generally.

Increase at nominal speed:

As a rule of thumb an increase at nominal speed can be expected when fed from inverter:

- approx. 1–3 dB(A) in case of a current source inverter or a PWM inverter with high pulse frequency
- approx. 1–10 dB(A) in case of a customary PWM inverter.

If acoustic noise is a relevant feature in the application, the cast iron version shall be preferred instead of aluminium design.

Speeds higher than nominal speed:

Self ventilated motors are generating an increased fan noise at higher speed. A rough estimation for the increase of overall sound level is shown in the table below (the increase can be minimized by using the option "Forced ventilation").

	Increase of sound pressure level [dB(A)]			
	50 Hz	60 Hz	75 Hz	100 Hz
2-pole motor	0	4	10	16
4-pole motor	0	3	7	12
6 and 8 pole motor	0	3	6	8

Table 5-7: Acoustic sound increase to be expected at high speed (self ventilated motors)

6 Technical data

6.1 General data; tolerances (acc. to IEC 60034-1)

Rating, Performance	
Product Group, Design standard	Low Voltage Squirrel Cage Induction Motor, IEC 60034
Nominal voltages	3 AC; 230 V–690 V; tolerance see Figure 5-7, page 48
Winding configuration	Star/Delta, 6 winding ends
Winding temperature rise	Less than 80 K acc. Utilization B (by resistance method)
Method of starting	Full Voltage Direct On Line or Star/Delta starting
Nominal frequency	50 Hz or 60 Hz; tolerance according to IEC 60034-1
Inverter Operation	Suitable for inverter operation according to IEC 60034-17
Output range	0,12 kW–315 kW
Duty type	Continuous (S1); SF 1.0 (data for other duty types on request)
Efficiency	IE2 or IE3 according to IEC 60034-30
Range of frame size	From 63 up to 315
Pole numbers	2-pole; 4-pole; 6-pole and 8-pole
Rotational speed (synchronous)	750 rpm–3000 rpm (50 Hz); 900 rpm–3600 rpm (60 Hz)
Operational speed limit	See 5.3.2 Maximum operational speed, starting page 43
Rotational direction	Clockwise acc. IEC definition; suitable for bidirectional operation
Locked rotor torque	Tolerance: -15 %; +25 %
Pull up torque	Tolerance: -15 % (Minimum: 30 % of FLT)
Breakdown torque	>160 % of full load torque; tolerance – 10 % included
Slip	Tolerance: ±30 % for rating < 1 kW; ±20 % for rating ≥ 1 kW
Efficiency η	Tolerance: -0,15 (1- η) for rating < 150 kW; -0,1 (1- η) for rating ≥ 150 kW
Power factor cos ϕ	Tolerance: (1-cos ϕ)/6 (min. 0,02; max 0,07)
Locked rotor current	Tolerance: +20 %
Acoustic noise level	Tolerance +3dB(A) acc. to IEC 60034-1
Vibration Level	Level A according to IEC 60034-14

Application, Construction	
Site condition	Shadow, Non-hazardous
Ambient Temperature	-20 °C to +40 °C
Site Altitude	Less than 1000 m
Relative Humidity	Less than 90 % RH (Non-Condensation)
Enclosure	Totally Enclosed (IP55 acc. to IEC)
Cooling Method	Self Ventilated, Surface Cooled, "TEFC" (IC 411 acc. to IEC code)
Mounting	Foot Mounting (B3), Flange Mounting (B5 and B14) and derivatives
Stator Winding	Random Wound, Copper wire, Thermal class F insulation
Rotor Winding	Squirrel cage, Aluminium Conductor
Power Connectors	See section 3.2 Terminal box and cable entry, starting page 21
Bearings, Lubrication	See section 3.4 Rotor assembly (active part, shaft, bearings), starting page 27
Material (housing, end shields)	Die-Casting Aluminium ("ALAA...") or Cast Iron ("ALCA...")
Painting	Pebble Grey (RAL 7032)

General tolerances of dimensions (nomenclature acc. dimensional diagram)		
Motor mass	m	-5 %...+10 %
Rotor inertia	J	±10 %
Radial spacing of feet fixing holes	A	±1 mm
Axial spacing of feet fixing holes	B	±1 mm
Shaft height	H	frame ≤ 250: -0,5 mm; frame > 250: -1mm
Pitch circle diameter of flange	M	±0,8 mm
Shaft end diameter	D	see dimensional diagram

6.2 Type data for aluminium version

Remarks (valid for all following tables with performance data):

1. The typical values above are based on test according to IEC 60034, especially IEC 60034-2-1.
2. All tolerances are according to IEC 60034-1.
3. Design and operation at other nominal voltages: The full load current has to be calculated inversely with the voltage; all other data are the same.
4. Rating 0.55 kW and below and 8-pole motors an D* marked values: Efficiency per TECO performance standard.

6.2.1 Aluminium; 400 V; 50 Hz; Class IE2

2-pole

Power rating P_N	Nominal speed n_N	Frame size Type code ALAA... [kW]	Nominal current I_N [A]	Locked rotor current (multiple of nominal current) [A]	Efficiency at load points					Power factor at load points					Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) [Nm]	Pull up torque (multiple of nominal torque) [Nm]	Break down torque (multiple of nominal torque) [Nm]	Moment of inertia J [kgm ²]	Total mass (B3 version; approx.) [kg]	Sound pressure; Noise level dB (A)
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load	cos φ								
[r/min]					[%]																
0,18	2775	0063M0	0,49	4,41	67,4	67,4	60,4	48,0	0,79	0,69	0,55	0,38	0,62	1,90	1,70	2,00	$0,17 \times 10^{-3}$	5,0	53		
0,25	2785	0063M1	0,65	4,50	69,9	70,0	65,7	49,0	0,79	0,70	0,56	0,39	0,86	1,95	1,70	2,05	$0,21 \times 10^{-3}$	6,0	53		
0,37	2790	0071M0	0,93	4,86	71,0	71,0	66,7	52,5	0,81	0,71	0,55	0,36	1,27	1,90	1,70	2,20	$0,17 \times 10^{-3}$	8,0	55		
0,55	2780	0071M1	1,27	5,32	75,5	76,2	73,3	59,0	0,83	0,75	0,59	0,39	1,89	1,90	1,70	2,20	$0,33 \times 10^{-3}$	9,0	56		
0,75	2815	0080M0	1,63	5,85	77,4	78,6	77,4	66,2	0,86	0,79	0,67	0,44	2,54	3,10	2,70	3,00	$0,46 \times 10^{-3}$	12,0	57		
1,1	2820	0080M1	2,32	6,90	79,6	80,8	80,0	73,1	0,86	0,80	0,68	0,46	3,72	3,35	2,95	3,25	$0,75 \times 10^{-3}$	14,0	57		
1,5	2865	0090S0	3,11	7,71	81,3	82,0	80,9	73,9	0,86	0,80	0,69	0,46	5,00	3,10	2,90	3,30	$1,0 \times 10^{-3}$	17,0	56		
2,2	2860	0090L0	4,39	7,45	83,2	84,0	83,2	77,1	0,87	0,82	0,72	0,51	7,34	3,05	2,75	3,20	$1,5 \times 10^{-3}$	20,0	57		
3	2880	0100L0	6,06	7,45	84,6	85,5	84,8	78,3	0,85	0,79	0,66	0,45	9,94	3,05	2,55	3,35	$4,0 \times 10^{-3}$	27,0	59		
4	2905	0112M0	7,78	7,75	85,8	86,3	85,3	78,9	0,87	0,83	0,75	0,55	13,1	1,95	1,80	2,85	$8,25 \times 10^{-3}$	35,0	64		
5,5	2930	0132S0	11,3	7,05	87,0	87,0	85,6	79,4	0,81	0,75	0,64	0,42	17,9	2,65	2,45	3,05	$13,5 \times 10^{-3}$	51,0	69		
7,5	2920	0132S1	15,7	7,00	88,1	88,4	87,5	80,9	0,79	0,73	0,62	0,41	24,5	2,80	2,50	3,00	16×10^{-3}	56,0	69		
11	2950	0160M0	19,9	8,28	89,5	90,5	90,0	85,5	0,89	0,86	0,77	0,57	35,6	2,30	1,80	3,05	38×10^{-3}	87,0	74		
15	2950	0160M1	26,6	8,46	90,5	91,5	91,0	87,5	0,90	0,86	0,78	0,58	48,5	2,45	1,95	3,15	48×10^{-3}	98,0	74		
18,5	2945	0160L0	32,2	9,00	91,0	92,0	92,0	88,5	0,91	0,91	0,86	0,71	60,0	2,60	1,85	3,10	59×10^{-3}	109	73		

4-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code A1AA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull up torque (multiple of nominal torque) T_p/T_N	Break down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J	Total mass (B3 version; approx.) [kg]	Sound pressure; Noise level dB (A)
					%	cos φ			[%]	[Nm]	T_p/T_N	T_b/T_N							
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.18	1375	0063M1	0.54	3.90	65,0	63,8	58,2	43,6	0,75	0,64	0,50	0,35	1,25	2,00	1,80	2,00	$0,43 \times 10^{-3}$	6,0	42
0.25	1380	0071M0	0.67	4.20	69,5	70,1	66,2	51,8	0,77	0,67	0,52	0,35	1,73	2,00	1,75	2,00	$0,67 \times 10^{-3}$	8,0	46
0.37	1385	0071M1	1.02	4.20	69,5	69,9	66,3	52,2	0,75	0,65	0,50	0,33	2,55	2,05	1,80	2,05	$0,8 \times 10^{-3}$	9,0	46
0.55	1435	0080M0	1.34	6,60	78,1	78,1	75,2	63,6	0,76	0,69	0,56	0,37	3,66	2,55	2,20	2,80	$2,6 \times 10^{-3}$	13,0	48
0.75	1430	0080M1	1.75	6,15	79,6	79,6	76,1	67,1	0,78	0,71	0,59	0,38	5,01	2,45	2,15	2,70	$3,0 \times 10^{-3}$	14,0	52
1,1	1435	0090S0	2,44	6,95	81,4	81,4	79,2	71,4	0,80	0,72	0,58	0,37	7,32	2,65	2,30	3,05	$3,5 \times 10^{-3}$	15,0	50
1,5	1430	0090L0	3,27	7,05	82,8	83,2	81,9	74,6	0,80	0,72	0,59	0,40	10,0	2,75	2,35	3,15	$4,5 \times 10^{-3}$	19,0	50
2,2	1435	0100L0	4,62	6,95	84,3	86,3	86,5	81,0	0,82	0,77	0,64	0,43	14,6	2,80	2,55	2,85	$9,8 \times 10^{-3}$	26,0	53
3	1430	0100L1	6,45	6,50	85,5	86,5	86,7	80,8	0,79	0,73	0,60	0,42	20,0	2,70	2,50	2,75	11×10^{-3}	28,0	53
4	1440	0112M0	7,98	7,85	86,6	87,0	87,0	81,4	0,84	0,79	0,68	0,47	26,5	2,85	2,30	2,85	$16,3 \times 10^{-3}$	35,0	58
5,5	1450	0132S0	10,8	7,40	87,7	88,2	86,9	81,0	0,84	0,79	0,67	0,46	36,2	2,55	2,15	2,95	36×10^{-3}	55,0	60
7,5	1455	0132M0	14,5	7,50	88,7	88,8	88,0	83,1	0,84	0,79	0,68	0,47	49,2	2,65	2,15	3,00	44×10^{-3}	59,0	61
11	1465	0160M0	20,5	7,80	90,0	90,5	90,0	86,0	0,86	0,82	0,73	0,52	71,7	2,00	1,50	2,40	74×10^{-3}	80,0	65
15	1465	0160L0	27,5	8,00	91,0	91,5	91,0	88,0	0,87	0,83	0,74	0,54	97,7	2,20	1,55	2,55	107×10^{-3}	108	65

6-pole

Power rating P_n	Nominal speed n_n	Frame size Type code ALAA..	Nominal current I_n	Locked rotor current (multiple of nominal current) I_1/I_n	Efficiency at load points					Power factor at load points					Nominal torque T_n	Locked rotor torque (multiple of nominal torque) T_1/T_n	Pull up torque (multiple of nominal torque) T_p/T_n	Break down torque (multiple of nominal torque) T_d/T_n	Moment of inertia J	Total mass (B3 version; approx.) [kg]	Sound pressure; noise level dB (A)
					[%]					cos φ				[Nm]							
					Full load	3/4 load	2/4 load	1/4 load		Full load	3/4 load	2/4 load	1/4 load								
0,18	935	0071M0	0,63	3,70	62,5	60,0	52,4	38,5	0,66	0,56	0,45	0,32	1,84	1,80	1,65	2,05	$1,41 \times 10^{-3}$	9,0	43		
0,25	935	0071M1	0,85	3,70	65,0	63,0	55,5	38,5	0,67	0,56	0,44	0,31	2,55	2,00	1,80	2,20	$1,67 \times 10^{-3}$	10,0	44		
0,37	920	0080M0	1,24	3,65	65,5	64,5	59,0	42,3	0,66	0,57	0,46	0,30	3,84	1,75	1,55	2,00	$1,64 \times 10^{-3}$	12,0	46		
0,55	920	0080M1	1,64	5,70	74,0	74,6	72,2	61,1	0,66	0,57	0,46	0,30	5,71	1,85	1,65	2,10	$3,15 \times 10^{-3}$	13,0	46		
0,75	935	0090S0	2,08	5,05	75,9	76,4	74,3	62,5	0,69	0,60	0,47	0,30	7,66	2,25	2,25	2,40	$4,25 \times 10^{-3}$	20,0	50		
1,1	935	0090L0	3,03	5,25	78,1	78,6	76,4	64,8	0,67	0,59	0,46	0,29	11,2	2,30	2,25	2,50	$5,75 \times 10^{-3}$	22,0	50		
1,5	945	0100L0	3,64	5,85	79,8	81,4	80,9	71,0	0,75	0,68	0,55	0,37	15,2	2,20	1,90	2,25	$11,5 \times 10^{-3}$	33,0	52		
2,2	955	0112M0	5,21	5,90	81,8	81,9	79,8	70,8	0,75	0,68	0,56	0,36	22,0	2,00	1,85	2,60	22×10^{-3}	38,0	53		
3	965	0132S0	6,42	6,90	83,3	83,4	81,6	73,6	0,81	0,75	0,62	0,41	29,7	2,35	2,05	3,00	43×10^{-3}	49,0	55		
4	965	0132M0	8,48	7,15	84,6	84,7	83,2	75,6	0,81	0,74	0,62	0,41	39,6	2,35	2,05	3,00	54×10^{-3}	56,0	57		
5,5	970	0132M1	11,5	7,30	86,0	86,1	84,5	77,8	0,81	0,74	0,61	0,40	54,1	2,30	2,05	3,00	68×10^{-3}	68,0	57		
7,5	980	0160M0	15,9	6,60	88,0	89,5	89,5	85,0	0,78	0,71	0,59	0,38	74,6	2,45	1,95	2,50	91×10^{-3}	100	60		
11	985	0160L0	22,9	7,42	90,0	91,0	90,5	87,5	0,77	0,71	0,59	0,39	109	2,70	2,05	2,70	140×10^{-3}	121	60		

8-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code ALAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull-up torque (multiple of nominal torque) T_p/T_N	Break-down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; Noise level dB (A)
					%	cos φ			[%]	[Nm]	T_p/T_N	T_b/T_N							
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.18	690	0080M0	0.86	3.95	55,0	51,5	43,5	29,5	0,55	0,47	0,39	0,28	0,28	1,65	4,55	2,00	$1,9 \times 10^{-3}$	13,0	
0.25	690	0080M1	1.13	3.00	58,0	54,5	47,0	29,5	0,55	0,47	0,39	0,28	3,46	1,65	1,55	2,00	$2,5 \times 10^{-3}$	14,0	
0.37	695	0090S0	1.38	3.50	62,0	59,5	53,0	35,0	0,63	0,55	0,44	0,31	5,08	1,65	1,55	2,00	$4,1 \times 10^{-3}$	20,0	
0.55	690	0090L0	2.07	3.50	63,0	60,5	54,0	36,5	0,61	0,53	0,43	0,30	7,61	1,70	1,60	2,05	$4,9 \times 10^{-3}$	22,0	
0.75	695	0100L0	2.32	3.90	71,8	73,0	69,5	56,0	0,65	0,56	0,45	0,29	10,3	1,90	1,70	2,00	$8,5 \times 10^{-3}$	27,0	
1,1	695	0100L1	3.22	4.10	74,7	76,0	73,5	61,0	0,66	0,58	0,46	0,28	15,1	1,90	1,70	2,00	$12,3 \times 10^{-3}$	33,0	
1,5	700	0112M0	4,24	4,25	76,8	77,5	75,0	62,0	0,67	0,57	0,44	0,27	20,5	1,85	1,80	2,20	$14,6 \times 10^{-3}$	38,0	
2,2	715	0132S0	5,55	5,15	79,4	80,0	79,5	70,0	0,72	0,63	0,50	0,31	29,4	1,75	1,45	2,25	34×10^{-3}	53,0	
3	715	0132M0	7,40	5,15	81,3	82,0	81,0	73,0	0,72	0,64	0,50	0,31	40,0	1,75	1,45	2,30	45×10^{-3}	64,0	
4	715	0160M0	9,73	5,65	83,0	84,0	82,0	73,5	0,72	0,63	0,51	0,31	53,4	1,70	1,60	2,45	86×10^{-3}	90,0	
5,5	715	0160M1	13,2	5,30	84,5	84,0	82,5	74,0	0,71	0,63	0,51	0,31	73,4	1,65	1,60	2,40	86×10^{-3}	107	
7,5	720	0160L0	18,0	5,85	86,0	86,0	84,0	76,0	0,70	0,61	0,49	0,30	99,4	1,90	1,80	2,70	147×10^{-3}	122	

6.2.2 Aluminium; 460 V; 60 Hz; Class IE2

2-pole

Power rating P_N	Nominal speed n_N	Frame size Type code ALAA... [kW]	Nominal current I_N [A]	Locked rotor current (multiple of nominal current) [A]	Efficiency at load points					Power factor at load points					Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) [Nm]	Pull up torque (multiple of nominal torque) [Nm]	Break down torque (multiple of nominal torque) [Nm]	Moment of inertia J [kgm ²]	Total mass (B3 version; approx.) [kg]	Sound pressure; Noise level dB (A)
					η	cos φ				T/T_N	cos φ										
						Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load								
0,18	3390	0063M0	0,45	5,40	69,0	67,3	61,3	49,2	0,73	0,64	0,51	0,36	0,51	2,40	2,00	2,40	$0,25 \times 10^{-3}$	5,0	57		
0,25	3400	0063M1	0,59	5,35	70,0	69,0	63,8	49,2	0,76	0,67	0,54	0,37	0,70	2,35	1,95	2,35	$0,25 \times 10^{-3}$	6,0	57		
0,37	3440	0071M0	0,82	5,90	75,0	73,7	68,7	55,2	0,76	0,65	0,51	0,34	1,03	2,25	2,20	3,40	$0,25 \times 10^{-3}$	8,0	59		
0,55	3440	0071M1	1,05	6,60	79,0	78,8	75,4	63,6	0,84	0,74	0,60	0,39	1,53	2,20	2,15	3,35	$0,5 \times 10^{-3}$	9,0	60		
0,75	3465	0080M0	1,42	8,45	80,7	80,3	77,5	68,0	0,82	0,75	0,63	0,43	2,07	3,30	3,10	3,55	$0,75 \times 10^{-3}$	12,0	61		
1,1	3465	0080M1	1,99	9,05	82,5	82,5	80,4	72,0	0,84	0,78	0,66	0,45	3,03	3,50	3,30	3,75	$1,0 \times 10^{-3}$	14,0	61		
1,5	3490	0090S0	2,67	9,40	84,0	83,8	81,6	73,0	0,84	0,78	0,67	0,46	4,10	3,10	2,95	3,40	$1,5 \times 10^{-3}$	17,0	60		
2,2	3480	0090L0	3,69	9,50	85,5	85,5	84,2	78,0	0,88	0,83	0,74	0,52	6,03	3,00	2,85	3,30	$2,0 \times 10^{-3}$	20,0	61		
3	3495	0100L0	5,12	9,45	87,5	87,5	86,0	79,0	0,84	0,78	0,67	0,45	8,19	2,90	2,50	3,30	$4,0 \times 10^{-3}$	27,0	63		
4	3515	0112M0	6,63	9,40	87,5	87,5	85,8	79,0	0,87	0,83	0,74	0,55	10,9	2,45	2,10	3,45	$8,25 \times 10^{-3}$	35,0	68		
5,5	3535	0132S0	10,2	7,75	88,5	88,0	85,5	77,0	0,77	0,71	0,60	0,40	14,9	3,00	2,45	3,10	$13,5 \times 10^{-3}$	51,0	73		
7,5	3550	0132S1	13,8	7,95	89,5	89,2	87,5	79,3	0,76	0,70	0,60	0,36	20,3	3,00	2,45	3,10	16×10^{-3}	56,0	73		
11	3550	0160M0	17,2	9,60	90,2	90,5	89,0	82,0	0,89	0,86	0,78	0,60	29,6	2,95	2,20	3,65	38×10^{-3}	87,0	78		
15	3555	0160M1	23,3	9,65	90,2	90,5	89,5	84,0	0,90	0,87	0,79	0,60	40,3	3,10	2,20	3,5	48×10^{-3}	98,0	78		
18,5	3545	0160L0	27,8	9,70	91,7	92,0	91,5	87,5	0,91	0,90	0,86	0,71	49,8	2,75	1,85	3,05	59×10^{-3}	109	77		

4-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code A1AA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T_L/T_N	Pull up torque (multiple of nominal torque) T_p/T_N	Break down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; Noise level dB (A)		
					η		$\cos \varphi$		Full load		3/4 load	2/4 load	1/4 load		$\cos \varphi$		Full load				
[A]		[%]																			
0.18	1700	0063M1	0.49	4.50	69,0	66,3	60,2	45,7	0,67	0,56	0,44	0,30	1,01	2,3	2,2	2,55	$0,50 \times 10^{-3}$	6,0	46		
0.25	1705	0071M0	0.62	4.90	72,5	71,2	66,5	52,6	0,70	0,60	0,47	0,31	1,40	2,15	2,05	2,50	$0,75 \times 10^{-3}$	8,0	50		
0.37	1705	0071M1	0.92	4.95	74,0	72,8	68,4s	54,7	0,69	0,59	0,46	0,30	2,07	2,20	2,15	2,60	$0,75 \times 10^{-3}$	9,0	50		
0.55	1745	0080M0	1.18	7,60	81,2	80,2	76,8	65,6	0,72	0,64	0,52	0,34	3,01	3,1	2,85	3,4	$2,5 \times 10^{-3}$	13,0	52		
0.75	1745	0080M1	1.55	7,15	82,5	81,7	78,6	67,8	0,74	0,66	0,54	0,35	4,10	2,95	2,70	3,25	$3,0 \times 10^{-3}$	14,0	56		
1,1	1745	0090S0	2,11	8,55	84,0	83,8	81,7	73,0	0,78	0,70	0,56	0,35	6,02	3,30	2,70	3,85	$3,5 \times 10^{-3}$	15,0	54		
1,5	1745	0090L0	2,80	8,55	84,0	84,0	82,2	75,0	0,80	0,72	0,59	0,37	8,20	3,30	2,70	3,85	$4,5 \times 10^{-3}$	19,0	54		
2,2	1745	0100L0	3,92	8,95	87,5	88,0	87,0	80,6	0,81	0,75	0,64	0,41	12,0	3,15	2,65	3,20	$9,75 \times 10^{-3}$	26,0	57		
3	1740	0100L1	5,45	8,10	87,5	88,2	87,3	81,2	0,79	0,74	0,63	0,40	16,5	3,10	2,60	3,15	$11,0 \times 10^{-3}$	28,0	57		
4	1750	0112M0	7,04	9,20	87,5	88,2	87,3	82,0	0,82	0,76	0,64	0,43	21,8	3,20	2,70	3,40	$16,3 \times 10^{-3}$	35,0	62		
5,5	1760	0132S0	9,35	8,60	89,5	89,3	87,5	80,5	0,83	0,77	0,65	0,43	29,8	2,90	2,40	3,40	$36,3 \times 10^{-3}$	55,0	64		
7,5	1760	0132M0	12,8	8,50	89,5	89,5	87,8	81,7	0,83	0,77	0,66	0,44	40,7	3,00	2,50	3,60	44×10^{-3}	59,0	65		
11	1770	0160M0	17,9	8,95	91,0	91,0	90,5	86,0	0,85	0,81	0,71	0,49	59,3	2,25	1,60	2,75	74×10^{-3}	80,0	69		
15	1770	0160L0	24,1	9,35	91,5	92,0	92,0	88,0	0,86	0,81	0,71	0,49	80,9	2,50	1,75	2,95	107×10^{-3}	108	69		

6-pole

Power rating P_n	Nominal speed n_n	Frame size Type code ALAA..	Nominal current I_n	Locked rotor current (multiple of nominal current) I_1/I_n	Efficiency at load points					Power factor at load points					Nominal torque T_n	Locked rotor torque (multiple of nominal torque) T_1/T_n	Pull up torque (multiple of nominal torque) T_p/T_n	Break down torque (multiple of nominal torque) T_d/T_n	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; noise level dB (A)
					%	$\cos \varphi$				[Nm]											
[kW]	[rpm]	[A]	[%]																		
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load									
0,18	1145	0071M0	0,60	4,05	63,5	59,9	54,1	40,5	0,60	0,50	0,40	0,28	1,50	2,20	2,10	2,65	$1,5 \times 10^{-3}$	9,0	47		
0,25	1145	0071M1	0,80	4,05	65,0	61,4	56,1	40,4	0,60	0,50	0,40	0,28	2,08	2,30	2,20	2,72	$1,75 \times 10^{-3}$	10,0	48		
0,37	1135	0080M0	1,22	3,95	67,5	65,0	58,6	42,0	0,57	0,48	0,38	0,27	3,11	2,20	2,10	2,45	$1,75 \times 10^{-3}$	12,0	50		
0,55	1135	0080M1	1,44	4,75	78,7	78,5	75,3	63,6	0,61	0,53	0,41	0,26	4,63	2,10	2,00	2,35	$3,25 \times 10^{-3}$	13,0	50		
0,75	1145	0090S0	1,77	5,50	80,0	79,7	76,5	64,6	0,67	0,58	0,45	0,28	6,25	2,40	2,40	2,90	$4,25 \times 10^{-3}$	20,0	54		
1,1	1145	0090L0	2,66	5,55	82,5 (*)	82,5	80,2	71,0	0,63	0,54	0,42	0,26	9,17	2,55	2,55	3,00	$5,75 \times 10^{-3}$	22,0	54		
1,5	1155	0100L0	3,24	6,20	82,5 (*)	83,0	81,5	72,0	0,71	0,63	0,51	0,32	12,4	2,65	2,25	2,65	$11,5 \times 10^{-3}$	33,0	56		
2,2	1160	0112M0	4,42	7,70	85,5 (*)	84,8	81,8	71,6	0,73	0,65	0,52	0,33	18,1	2,45	2,10	3,30	$21,5 \times 10^{-3}$	38,0	57		
3	1175	0132S0	5,63	8,6	87,5	87,0	84,5	75,8	0,77	0,69	0,56	0,36	24,4	2,50	2,20	3,20	43×10^{-3}	49,0	59		
4	1175	0132M0	7,45	8,75	87,5	87,0	84,7	76,7	0,77	0,70	0,57	0,37	32,5	2,50	2,20	3,20	$53,5 \times 10^{-3}$	56,0	61		
5,5	1175	0132M1	10,0	8,95	89,5	89,0	86,8	79,0	0,77	0,70	0,57	0,36	44,7	2,50	2,20	3,20	68×10^{-3}	68,0	61		
7,5	1165	0160M0	13,7	7,65	90,2	91,0	90,5	86,0	0,76	0,69	0,57	0,35	61,4	2,85	2,50	2,90	91×10^{-3}	100	64		
11	1170	0160L0	20,3	8,10	90,5	91,5	90,5	86,0	0,75	0,69	0,56	0,51	89,7	3,15	2,50	3,15	140×10^{-3}	121	64		

8-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code AIAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull-up torque (multiple of nominal torque) T_p/T_N	Break-down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J kgm ²	Total mass (B3 version; approx.) m	Sound pressure; Noise level dB (A)
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.18	850	0080M0	0.84	3.10	56,5	53,0	44,5	27,0	0,48	0,41	0,33	0,24	2,02	2,00	2,00	2,45	$2,0 \times 10^{-3}$	13,0	
0.25	850	0080M1	1,11	3.10	59,5	56,0	48,0	30,0	0,48	0,41	0,33	0,24	2,81	2,00	2,00	2,45	$2,5 \times 10^{-3}$	14,0	
0.37	855	0090S0	1,17	4.20	68,5	66,0	59,0	42,0	0,58	0,50	0,40	0,28	4,13	2,00	2,00	2,55	$4,0 \times 10^{-3}$	20,0	
0.55	855	0090L0	1,79	4.05	69,0	67,5	61,0	43,5	0,56	0,48	0,38	0,26	6,14	2,05	2,00	2,50	$4,75 \times 10^{-3}$	22,0	
0.75	860	0100L0	2,23	4.55	74,0	73,5	70,5	56,0	0,57	0,49	0,38	0,24	8,32	2,30	2,00	2,30	$8,5 \times 10^{-3}$	27,0	
1,1	860	0100L1	3,06	4,75	77,0	77,0	74,0	61,0	0,59	0,50	0,39	0,24	12,2	2,30	2,00	2,30	$12,3 \times 10^{-3}$	33,0	
1,5	855	0112M0	3,80	4,75	80,0	80,0	76,0	64,0	0,62	0,53	0,40	0,25	16,8	2,10	1,95	2,60	$14,5 \times 10^{-3}$	38,0	
2,2	880	0132S0	4,78	7,30	82,5	82,5	80,0	69,5	0,70	0,61	0,48	0,30	23,9	2,25	1,85	3,30	34×10^{-3}	53,0	
3	885	0132M0	6,44	7,20	83,5	83,5	81,0	71,5	0,70	0,62	0,49	0,30	32,4	2,25	1,85	3,30	45×10^{-3}	64,0	
4	870	0160M0	8,56	6,45	85,0	84,5	82,0	72,5	0,69	0,60	0,47	0,30	43,9	1,90	1,80	2,65	86×10^{-3}	90,0	
5,5	870	0160M1	12,2	5,75	84,5	84,5	82,0	72,0	0,67	0,58	0,45	0,29	60,3	1,95	1,85	2,60	68×10^{-3}	107	
7,5	870	0160L1	16,4	6,10	86,5	86,0	83,5	74,5	0,67	0,58	0,44	0,29	82,3	2,20	2,10	2,90	147×10^{-3}	122	

6.3 Type data for cast iron version

6.3.1 Cast iron; 400 V; 50 Hz; Class IE2

2-pole

Power rating P_N	Nominal speed n_N	Frame size Type code ALAA- ...	Nominal current I_N	Locked rotor current (multiple of nominal current) I_1/I_N	Efficiency at load points					Power factor at load points					Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T_1/T_N	Pull up torque (multiple of nominal torque) T_p/T_N	Break down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J	Total mass (IE3 version; approx.) m	Sound pressure; noise level dB (A)
					[%]		η			$\cos \varphi$			T_N	T/T_N	T_p/T_N	T_b/T_N	$k\text{gm}^2$	[kg]			
					Full load	3/4 load	2/4 load	1/4 load		Full load	3/4 load	2/4 load	1/4 load								
0,75	2850	0080M0	1,64	5,50	77,4	78,0	76,3	64,3	0,86	0,79	0,66	0,45	2,51	2,15	1,80	2,55	$1,25 \times 10^{-3}$	17	56		
1,1	2875	0080M2	2,33	7,30	79,6	80,0	78,3	68,5	0,86	0,79	0,67	0,45	3,65	2,55	2,00	3,05	$1,75 \times 10^{-3}$	19,5	56		
1,5	2880	0090S0	3,08	7,80	81,3	81,8	80,3	73,5	0,87	0,81	0,69	0,48	4,97	2,60	2,45	3,25	$2,75 \times 10^{-3}$	24,5	59		
2,2	2875	0090L0	4,36	8,05	83,2	84,3	83,4	77,9	0,88	0,82	0,71	0,49	7,30	2,85	2,40	3,35	$3,5 \times 10^{-3}$	28	59		
3	2895	0100L0	5,82	8,40	84,6	85,9	85,7	80,4	0,88	0,83	0,73	0,50	5,70	2,45	2,25	3,10	$5,5 \times 10^{-3}$	37,6	60		
4	2880	0112M0	7,39	8,50	85,8	86,9	86,6	81,4	0,91	0,88	0,81	0,62	13,3	2,35	2,40	3,35	$10,5 \times 10^{-3}$	49	70		
5,5	2925	0132S0	10,6	7,75	87,0	87,2	86,2	81,0	0,86	0,83	0,75	0,56	18,0	2,40	1,80	2,80	$15,8 \times 10^{-3}$	68	66		
7,5	2920	0132S2	14,9	6,60	88,1	88,3	87,8	83,3	0,83	0,78	0,68	0,47	24,5	2,50	2,30	2,50	19×10^{-3}	72,5	66		
11	2950	0160M0	19,6	8,80	89,4	89,3	88,1	82,5	0,91	0,88	0,81	0,62	35,6	2,30	1,80	3,05	38×10^{-3}	110	74		
15	2930	0160M2	25,6	8,80	90,3	91,0	91,2	88,1	0,94	0,93	0,89	0,74	48,9	2,45	1,65	2,55	48×10^{-3}	120	74		
18,5	2925	0160L0	31,6	9,20	90,9	91,5	91,7	88,6	0,93	0,92	0,88	0,73	60,4	2,60	1,85	3,10	59×10^{-3}	137	74		
22	2930	0180M0	38,0	7,75	91,3	91,2	90,5	85,8	0,92	0,90	0,86	0,71	71,6	2,15	1,65	2,60	71×10^{-3}	178	80		
30	2945	0200L0	52,0	8,45	92,0	92,2	91,3	86,3	0,91	0,90	0,86	0,72	97,2	2,05	1,50	3,00	130×10^{-3}	270	75		
37	2945	0200L2	63,1	9,25	92,5	92,9	92,7	89,1	0,92	0,91	0,88	0,75	120	1,60	1,30	2,35	165×10^{-3}	308	75		
45	2965	0225M0	76,8	9,25	92,9	92,5	91,3	85,9	0,91	0,89	0,83	0,65	145	1,70	1,40	3,35	265×10^{-3}	333	81		
55	2970	0250M0	92,1	7,90	93,2	93,2	92,6	88,6	0,93	0,92	0,88	0,74	177	1,45	1,20	3,05	335×10^{-3}	456	81		
75	2965	0280S0	127	7,15	93,8	93,8	92,8	88,8	0,91	0,90	0,86	0,69	242	2,10	1,90	3,15	0,50	602	82		
90	2965	0280M0	152	7,25	94,1	94,1	93,5	90,2	0,91	0,91	0,87	0,73	290	2,25	2,05	3,10	0,60	640	82		
110	2965	0315S0	188	7,10	94,3	94,3	93,1	89,5	0,90	0,88	0,85	0,68	355	2,05	1,85	3,20	1,10	850	88		
132	2965	0315M0	223	6,75	94,6	94,6	93,5	90,5	0,91	0,90	0,86	0,72	425	2,20	2,00	3,20	1,20	920	88		
160	2970	0315M2	272	6,95	94,8	94,8	94,2	91,0	0,90	0,89	0,85	0,70	515	2,25	2,05	3,30	1,30	1000	90		
200	2970	0315L0	334	6,95	95,0	95,0	94,2	91,3	0,91	0,91	0,88	0,75	645	2,30	2,15	3,15	1,60	1200	90		
250	2970	0315D0	417	6,85	95,0	95,0	94,0	91,5	0,91	0,91	0,89	0,76	805	1,80	1,60	3,00	2,80	1690	90		
315	2970	0315D2	520	6,80	95,0	95,0	94,3	91,7	0,92	0,92	0,89	0,74	1015	1,70	1,50	2,90	3,00	1830	92		

4-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code ALAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull-up torque (multiple of nominal torque) T_p/T_N	Break-down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J kgm ²	Total mass (B3 version; approx.) m	Sound pressure; Noise level dB (A)
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.55	1425	0080M0	1.40	5.70	78,1	78,0	75,1	64,1	0,73	0,62	0,48	0,30	3,69	2,90	2,60	3,05	$2,5 \times 10^{-3}$	17,5	52
0.75	1415	0080M2	1.85	5.95	79,6	79,5	76,9	66,3	0,74	0,64	0,50	0,31	5,06	3,00	3,30	3,25	$3,25 \times 10^{-3}$	20,5	52
1,1	1445	0090S0	2,57	7,40	81,4	81,4	78,9	69,8	0,76	0,67	0,53	0,34	7,26	2,70	2,65	3,25	$4,25 \times 10^{-3}$	25	52
1,5	1435	0090L0	3,23	7,10	82,8	83,7	82,6	75,7	0,81	0,73	0,60	0,38	9,97	2,50	1,80	2,90	$5,5 \times 10^{-3}$	28	52
2,2	1450	0100L0	4,62	7,15	84,3	85,0	84,1	76,1	0,82	0,74	0,61	0,39	14,5	1,95	1,55	2,65	$10,2 \times 10^{-3}$	37	51
3	1445	0100L2	6,18	7,10	85,5	85,9	84,8	77,3	0,82	0,75	0,63	0,40	19,8	1,95	1,55	2,80	$12,5 \times 10^{-3}$	40	51
4	1450	0112M0	7,84	7,40	86,6	87,6	87,5	83,2	0,85	0,81	0,71	0,48	26,3	2,20	2,00	2,70	21×10^{-3}	54	51
5,5	1455	0132S0	10,6	7,65	87,7	88,7	88,6	84,5	0,86	0,81	0,70	0,47	36,1	2,55	2,10	3,05	31×10^{-3}	72	60
7,5	1460	0132M0	14,5	7,70	88,7	89,6	89,5	85,3	0,84	0,79	0,67	0,45	49,1	2,75	2,00	3,05	36×10^{-3}	79	60
11	1465	0160M0	20,4	7,85	89,8	90,6	90,7	87,1	0,87	0,83	0,75	0,53	71,6	2,00	1,50	2,40	74×10^{-3}	121	62
15	1470	0160L0	27,6	7,95	90,6	91,3	91,2	88,1	0,87	0,83	0,74	0,52	97,3	2,20	1,55	2,55	107×10^{-3}	138	62
18,5	1475	0180M0	34,2	6,75	91,2	91,7	91,6	88,7	0,86	0,83	0,77	0,57	120	1,90	1,45	2,20	164×10^{-3}	180	70
22	1470	0180L0	40,5	6,65	91,6	92,4	92,2	89,3	0,86	0,84	0,78	0,58	143	1,85	1,45	2,10	193×10^{-3}	199	70
30	1470	0200L0	53,6	7,85	92,3	92,9	92,9	90,6	0,88	0,85	0,77	0,56	195	2,30	1,80	2,75	304×10^{-3}	266	72
37	1475	0225S0	65,8	6,55	92,7	93,3	93,3	90,3	0,88	0,86	0,80	0,62	239	1,85	1,50	2,60	410×10^{-3}	333	75
45	1480	0225M0	81,1	7,15	93,1	93,3	92,9	89,8	0,86	0,83	0,75	0,54	290	1,95	1,70	2,75	0,50	368	75
55	1485	0250M0	97,0	8,05	93,5	93,7	93,3	90,0	0,88	0,85	0,79	0,60	354	2,45	1,80	2,65	0,90	492	80
75	1480	0280S0	129	7,80	94,0	94,0	93,5	91,5	0,89	0,87	0,81	0,61	483	2,00	1,80	2,80	1,40	684	71
90	1480	0280M0	156	7,90	94,2	94,2	93,7	91,7	0,89	0,87	0,79	0,59	580	2,00	1,80	2,80	1,60	716	71
110	1482	0315S0	190	6,60	94,5	94,5	94,0	91,4	0,89	0,88	0,83	0,66	709	2,05	1,85	2,80	2,50	1020	75
132	1482	0315M0	227	6,30	94,7	94,7	94,3	91,7	0,89	0,88	0,83	0,65	850	2,05	1,85	2,90	2,70	1070	79
160	1481	0315M2	275	6,75	94,9	94,9	94,5	92,2	0,89	0,88	0,83	0,65	1030	2,00	1,80	2,85	2,90	1100	79
200	1482	0315L0	343	6,55	95,1	95,1	94,7	92,5	0,89	0,87	0,83	0,66	1290	2,00	1,80	2,85	3,60	1280	83
250	1485	0315D0	424	6,85	95,1	95,1	94,7	92,6	0,90	0,88	0,84	0,69	1610	2,10	1,85	2,80	6,30	1750	85
315	1485	0315D2	534	6,80	95,1	95,1	94,7	92,6	0,90	0,88	0,85	0,71	2025	2,10	1,90	2,60	7,80	1920	85

6-pole

Power rating P _s	Nominal speed n _n	Frame size Type code ALAA..	Nominal current I _n	Locked rotor current (multiple of nominal current) I _r /I _n	Efficiency at load points					Power factor at load points					Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T _r /T _n	Pull up torque (multiple of nominal torque) T _p /T _n	Break down torque (multiple of nominal torque) T _b /T _n	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; noise level dB (A)
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load	cos φ	T _n	T _r /T _n	T _p /T _n	T _b /T _n				
0,37	915	0080M0	1,25	4,00	65,5	63,8	57,9	40,5	0,65	0,56	0,44	0,31	3,85	2,30	2,15	2,35	2,3 x 10 ⁻³	17,5	52		
0,55	915	0080M2	1,73	4,05	68,5	68,8	64,9	50,2	0,67	0,57	0,44	0,29	5,83	2,25	2,20	2,25	3,0 x 10 ⁻³	19,5	52		
0,75	935	0090S0	2,05	4,90	75,9	76,4	73,9	63,8	0,70	0,60	0,47	0,30	7,65	2,10	1,85	2,35	4,8 x 10 ⁻³	25	56		
1,1	930	0090L0	2,84	4,95	78,1	78,8	76,9	68,2	0,72	0,62	0,49	0,31	11,3	2,15	1,90	2,40	6,5 x 10 ⁻³	30	56		
1,5	950	0100L0	3,85	4,95	79,8	80,5	78,8	68,5	0,71	0,62	0,49	0,30	15,1	1,60	1,30	2,20	12 x 10 ⁻³	39	51		
2,2	950	0112M0	5,18	6,55	81,8	82,4	81,1	72,6	0,75	0,67	0,53	0,34	22,1	2,80	2,55	2,90	18 x 10 ⁻³	49	60		
3	960	0132S0	6,66	5,55	83,3	84,1	83,2	76,8	0,78	0,71	0,58	0,37	29,8	1,70	1,65	2,75	26 x 10 ⁻³	61	55		
4	960	0132M0	8,64	6,15	84,6	85,6	85,1	79,3	0,79	0,73	0,60	0,39	39,7	1,90	1,80	2,80	33 x 10 ⁻³	69	57		
5,5	960	0132M2	11,6	6,70	86,0	86,9	86,5	81,2	0,80	0,73	0,61	0,39	54,6	2,30	1,95	2,75	47 x 10 ⁻³	81	57		
7,5	960	0160M0	15,1	6,95	87,2	88,2	87,7	82,4	0,82	0,77	0,67	0,45	74,6	2,10	1,95	2,35	91 x 10 ⁻³	110	64		
11	965	0160L0	22,0	7,75	88,7	89,2	88,6	83,2	0,82	0,76	0,65	0,43	109	2,45	2,05	2,70	140 x 10 ⁻³	138	64		
15	975	0180L0	29,3	7,50	89,7	90,4	90,2	86,7	0,83	0,78	0,68	0,46	147	2,10	1,95	2,50	335 x 10 ⁻³	205	60		
18,5	980	0200L0	37,2	7,00	90,4	91,0	90,9	87,7	0,80	0,75	0,66	0,44	180	2,15	1,70	2,15	0,40	263	66		
22	980	0200L2	43,1	7,00	90,9	91,4	91,8	88,0	0,81	0,78	0,69	0,44	214	2,10	1,65	2,10	0,48	283	66		
30	980	0225M0	54,9	6,65	91,7	92,4	92,2	88,9	0,86	0,83	0,76	0,56	292	2,10	1,60	2,15	0,61	343	67		
37	980	0250M0	67,0	6,80	92,2	92,3	91,7	87,2	0,87	0,83	0,74	0,51	360	2,05	1,85	2,45	0,84	436	72		
45	980	0280S0	83,2	6,35	92,9	92,7	91,0	89,0	0,84	0,81	0,74	0,52	439	2,05	1,85	2,95	1,60	630	68		
55	985	0280M0	101	6,35	93,4	93,4	93,0	90,0	0,84	0,82	0,74	0,52	534	2,10	1,85	2,75	1,90	674	68		
75	985	0315S0	138	6,30	93,7	93,7	92,9	88,5	0,84	0,81	0,71	0,48	727	2,00	1,80	2,60	3,10	870	69		
90	985	0315M0	164	6,30	94,0	94,0	93,5	91,0	0,85	0,82	0,74	0,53	870	2,00	1,80	2,60	3,50	960	70		
110	985	0315M2	197	6,45	94,5	94,4	94,2	91,5	0,86	0,83	0,75	0,53	1063	2,05	1,85	2,70	4,70	1080	70		
132	985	0315L0	236	6,10	94,6	94,6	94,3	92,2	0,86	0,84	0,77	0,56	1276	2,05	1,85	2,75	5,10	1270	75		
160	985	0315L2	288	6,40	94,8	94,8	94,5	92,5	0,85	0,82	0,74	0,50	1550	2,10	1,90	2,75	5,80	1330	75		
200	985	0315D0	355	6,50	95,0	95,0	94,3	91,6	0,86	0,84	0,78	0,59	1938	2,10	1,90	2,80	9,70	1800	76		
250	985	0315D2	444	6,50	95,0	95,0	94,5	92,0	0,86	0,84	0,79	0,59	2425	2,00	1,80	2,70	11,6	1900	79		

8-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code ALAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull up torque (multiple of nominal torque) T_p/T_N	Break down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J kgm ²	Total mass (B3 version; approx.) m [kg]	Sound pressure; Noise level dB (A)
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.18		0080M0																	
0.25		0080M2																	
0.37		0090S0																	
0.55		0090L0																	
0.75	695	0100L0	2.32	4.30	71,8	71,0	68,0	54,0	0,65	0,56	0,44	0,28	10,3	2,00	1,75	2,15	$11,5 \times 10^{-3}$	37,5	
1,1	690	0100L2	3,15	4,45	74,7	75,0	73,0	61,5	0,68	0,59	0,46	0,28	15,2	1,95	1,75	2,05	$14,8 \times 10^{-3}$	44,5	
1,5	700	0112M0	4,27	4,20	76,8	77,0	75,5	63,0	0,66	0,57	0,45	0,28	20,4	1,80	1,50	2,05	$17,8 \times 10^{-3}$	49,5	
2,2	710	0132S0	6,20	5,00	79,4	82,0	79,5	69,0	0,65	0,55	0,42	0,25	29,5	2,40	2,45	2,75	$34,5 \times 10^{-3}$	65,5	
3	700	0132M0	7,72	4,80	81,3	83,0	81,5	72,0	0,69	0,60	0,46	0,28	40,9	2,15	2,10	2,45	40×10^{-3}	71	
4	715	0160M0	9,73	5,65	83,0	84,0	82,0	73,5	0,72	0,63	0,51	0,31	53,3	1,70	1,60	2,45	86×10^{-3}	110	
5,5	715	0160M2	13,2	5,30	84,5	84,0	82,5	74,0	0,71	0,63	0,51	0,31	73,4	1,65	1,60	2,40	86×10^{-3}	111	
7,5	720	0160L0	18,0	5,85	86,0	86,0	84,0	76,0	0,70	0,61	0,49	0,30	99,4	1,90	1,80	2,70	147×10^{-3}	146	
11	720	0180L0	25,9	5,40	87,7	87,5	87,0	80,0	0,70	0,62	0,56	0,34	146	1,90	1,60	2,05	255×10^{-3}	182	
15	720	0200L0	31,6	5,20	89,0	90,0	91,0	87,0	0,77	0,72	0,65	0,41	199	1,65	1,40	1,85	440×10^{-3}	275	
18,5	735	0225S0	40,5	5,45	91,5	92,0	91,0	86,0	0,72	0,66	0,58	0,36	240	2,05	1,85	2,15	0,67	345	
22	735	0225M0	46,3	5,20	92,0	92,0	92,0	88,0	0,75	0,69	0,63	0,40	286	1,85	1,70	1,95	0,76	367	
30	735	0250M0	63,2	5,55	92,0	92,0	92,0	88,0	0,75	0,68	0,58	0,36	390	2,00	1,70	2,25	1,14	475	
37	735	0280S0	71,8	6,20	92,2	92,3	91,5	88,0	0,81	0,77	0,67	0,46	480	1,50	1,30	2,70	2,10	694	
45	735	0280M0	87,1	6,10	92,6	92,6	92,0	89,0	0,81	0,78	0,69	0,46	585	1,50	1,30	2,70	2,40	734	
55	738	0315S0	106	6,05	93,0	93,0	92,3	89,4	0,81	0,77	0,68	0,46	710	1,70	1,50	2,50	4,00	970	
75	738	0315M0	144	6,05	93,7	93,8	93,5	90,2	0,81	0,78	0,69	0,48	970	1,70	1,50	2,50	5,30	1080	
90	740	0315L0	172	6,00	94,0	94,0	93,7	90,7	0,81	0,78	0,69	0,48	1160	1,70	1,50	2,50	6,10	1180	
110	740	0315L2	209	6,10	94,5	94,5	94,1	91,0	0,81	0,79	0,70	0,48	1420	1,80	1,60	2,60	7,70	1320	
132	740	0315D0	250	6,40	94,6	94,6	94,2	91,2	0,81	0,76	0,66	0,43	1700	1,40	1,20	2,70	8,70	1700	
160	740	0315D2	302	6,75	94,8	94,8	94,3	91,7	0,81	0,76	0,65	0,43	2065	1,40	1,20	2,75	10,2	1800	
200	740	0315D4	377	6,50	95,0	95,0	94,5	92,5	0,81	0,76	0,66	0,43	2580	1,40	1,20	2,70	11,8	1950	

6-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code ALAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_R/I_N	Efficiency at load points				Power factor at load points				Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T_R/T_N	Pull-up torque (multiple of nominal torque) T_p/T_N	Break-down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; Noise level dB (A)
					%	cos φ			[%]	[Nm]	T_p/T_N	T_b/T_N							
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0.43	1115	0080M0	1.28	3.90	67,5	66,2	60,4	44,3	0,63	0,53	0,42	0,28	3.683	2,30	2,15	2,60	$2,3 \times 10^{-3}$	17,5	56
0.63	1110	0080M2	1.62	4,32	72,5	72,5	68,5	54,5	0,68	0,58	0,43	0,29	5.420	2,30	2,25	2,65	$3,0 \times 10^{-3}$	19,5	56
0.86	1140	0090S0	1.93	5,18	80,0	78,9	75,9	64,5	0,70	0,60	0,48	0,30	7,20	2,05	1,85	2,70	$4,8 \times 10^{-3}$	25	60
1.27	1140	0090L0	2,77	5,41	81,0	80,5	78,0	67,5	0,71	0,62	0,49	0,31	10,64	2,05	1,85	2,70	$6,5 \times 10^{-3}$	30	60
1.73	1155	0100L0	3,71	5,39	82,5	82,6	80,5	70,5	0,71	0,63	0,51	0,32	14,30	1,80	1,60	2,60	12×10^{-3}	39	55
2.53	1155	0112M0	5,12	6,83	85,0	85,5	84,3	76,2	0,73	0,65	0,52	0,31	20,92	2,95	2,85	3,10	18×10^{-3}	49	64
3.45	1165	0132S0	6,34	5,99	87,5	87,2	85,9	78,7	0,78	0,72	0,60	0,38	28,28	1,80	1,55	2,85	26×10^{-3}	61	59
4,6	1165	0132M0	8,32	6,25	89,0	88	87,9	81,7	0,78	0,72	0,60	0,38	37,71	2,00	1,55	2,90	33×10^{-3}	69	61
6,33	1165	0132M2	11,2	6,42	89,5	89,4	88,5	82,5	0,80	0,74	0,62	0,40	51,89	2,00	1,65	3,00	47×10^{-3}	81	61
8,6	1165	0160M0	14,6	5,68	89,5	89,7	89,0	83,6	0,83	0,79	0,70	0,47	70,80	2,15	1,80	2,55	91×10^{-3}	110	68
12,7	1170	0160L0	21,6	6,99	90,2	90,5	89,8	84,7	0,82	0,79	0,66	0,44	104,1	2,60	2,15	2,75	140×10^{-3}	138	68
17,3	1175	0180L0	28,4	6,76	91,7	91,3	91,4	87,1	0,83	0,81	0,73	0,50	140,6	2,45	2,15	2,95	335×10^{-3}	205	64
21,3	1175	0200L0	36,2	6,04	91,7	92,4	92,2	88,7	0,81	0,78	0,69	0,47	173,1	2,40	2,20	3,00	0,40	263	70
25,3	1175	0200L2	38,6	7,65	91,7	92,0	92,0	88,0	0,78	0,74	0,63	0,42	178	2,30	2,10	2,50	0,48	283	71
34,5	1180	0225M0	54,1	5,6	93,0	93,5	93,2	89,6	0,86	0,84	0,77	0,56	279	2,00	1,60	2,45	0,61	343	72
42,6	1185	0250M0	66	5,68	93,6	93,2	92,3	87,7	0,87	0,84	0,77	0,53	343	1,90	1,45	2,60	0,84	436	76
52	1186	0280S0	81,9	6,71	93,8	93,6	92,7	89,5	0,85	0,82	0,73	0,50	418,7	1,85	1,70	2,80	1,60	630	72
63	1186	0280M0	98,0	6,93	93,8	93,8	93,5	90,5	0,86	0,83	0,75	0,52	507,3	1,90	1,65	2,80	1,90	674	72
86	1185	0315S0	119	6,95	94,1	93,8	93,0	89,0	0,84	0,80	0,71	0,48	604	1,70	1,40	2,50	3,10	870	73
104	1185	0315M0	163	6,31	94,3	94,4	94	91,8	0,85	0,82	0,75	0,53	838,1	1,90	1,70	2,40	3,50	960	73
127	1185	0315M2	195	6,56	95,0	94,8	94,2	91,5	0,86	0,84	0,77	0,56	1024	2,00	1,75	2,40	4,70	1080	73
152	1185	0315L0	234	6,79	95,0	95	94,3	92,4	0,86	0,84	0,76	0,55	1225	2,10	1,85	2,40	5,10	1270	78
184	1186	0315L2	283	6,57	95,0	95,0	94,5	92,5	0,86	0,84	0,78	0,57	1482	2,20	1,95	2,55	5,80	1330	78
230	1185	0315D0	351	6,98	95,1	95	94,2	91,5	0,87	0,85	0,8	0,64	1854	2,00	1,75	2,50	9,70	1800	80
288	1185	0315D2	436	7,04	95,2	95,2	94,4	92,0	0,87	0,86	0,80	0,64	2321	2,05	1,80	2,50	11,6	1900	83

8-pole

Power rating P_n	Nominal speed n_n	Frame size Type code ALAA..	Nominal current I_n	Locked rotor current (multiple of nominal current) I_1/I_n	Efficiency at load points				Power factor at load points				Nominal torque T_n	Locked rotor torque (multiple of nominal torque) T_1/T_n	Pull up torque (multiple of nominal torque) T_p/T_n	Break down torque (multiple of nominal torque) T_d/T_n	Moment of inertia J	Total mass (B3 version; approx.) m	Sound pressure; noise level dB (A)
					η		$\cos \varphi$		[%]	[Nm]	[kgm ²]	[kg]							
[kW]	[rpm]	[A]			Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load							
0,18	0080M0																		
0,25	0080M2																		
0,37	0090S0																		
0,55	0090L0																		
0,86	850	0100L0	2,23	4,93	75,0	75,5	73,0	61,0	0,65	0,65	0,43	0,27	9,66	2,00	1,65	2,50	$11,5 \times 10^{-3}$	37,5	
1,27	845	0100L2	3,07	4,56	77,5	79,0	78,0	67,0	0,67	0,59	0,46	0,28	14,35	2,00	1,60	2,35	$14,8 \times 10^{-3}$	44,5	
1,73	850	0112M0	4,40	4,77	76,5	77,0	76,0	64,5	0,65	0,56	0,44	0,27	19,44	1,90	1,10	2,40	$17,8 \times 10^{-3}$	49,5	
2,53	855	0132S0	5,97	5,36	82,5	82,0	79,0	68,5	0,65	0,56	0,42	0,26	28,26	2,30	2,15	2,90	$34,5 \times 10^{-3}$	65,5	
3,45	850	0132M0	7,56	4,89	83,0	83,5	82,0	73,0	0,69	0,60	0,47	0,29	38,76	2,05	1,90	2,50	40×10^{-3}	71	
4,6	865	0160M0	9,20	5,76	86,0	86,5	86,5	80,0	0,73	0,64	0,51	0,31	50,79	2,00	1,70	2,80	86×10^{-3}	110	
6,33	865	0160M2	12,9	69,89	86,5	87,0	87,0	80,5	0,71	0,63	0,49	0,29	68,89	2,00	1,75	2,70	86×10^{-3}	111	
8,6	870	0160L0	16,6	6,32	88,0	88,5	87,0	80,0	0,74	0,66	0,53	0,32	94,4	2,10	2,05	3,50	147×10^{-3}	146	
12,7	870	0180L0	24,8	5,72	88,0	88,5	88,5	88,3	0,73	0,67	0,56	0,33	139,4	2,00	1,70	2,40	255×10^{-3}	182	
17,3	870	0200L0	30,0	5,46	89,5	91,0	91,0	87,5	0,81	0,78	0,69	0,48	189	1,90	1,80	2,65	440×10^{-3}	275	
21,3	880	0225S0	38,0	5,15	92,0	92,5	92,0	87,5	0,77	0,72	0,62	0,40	231	2,00	1,40	2,35	0,67	345	
25,3	880	0225M0	44,3	4,69	92,0	92,5	92,0	88,0	0,78	0,75	0,66	0,45	274	1,80	1,50	2,50	0,76	367	
34,5	885	0250M0	58,9	5,00	93,0	93,0	93,0	89,0	0,79	0,75	0,65	0,41	372	1,80	1,30	2,25	1,14	475	
42,6	885	0280S0	70,7	6,43	92,8	92,8	92,0	88,0	0,82	0,79	0,70	0,48	459	1,25	1,05	2,40	2,10	694	
52	885	0280M0	85,6	6,54	93,0	92,8	92,2	88,1	0,82	0,79	0,71	0,49	561	1,20	1,00	2,30	2,40	734	
63	885	0315S0	104	4,98	93,1	93,0	92,5	89,0	0,82	0,79	0,71	0,50	678	1,30	1,10	2,20	4,00	970	
86	885	0315M0	141	5,31	93,7	93,7	92,8	89,5	0,82	0,80	0,70	0,51	928	1,30	1,10	2,20	5,30	1080	
104	888	0315L0	170	5,41	94,2	94,1	93,2	90,1	0,82	0,80	0,72	0,51	1121	1,35	1,15	2,20	6,10	1180	
127	888	0315L2	207	6,03	94,5	94,4	93,6	90,8	0,82	0,8	0,72	0,51	1366	1,40	1,20	2,20	7,70	1320	
152	888	0315D0	247	6,23	94,8	94,8	94,0	91,0	0,82	0,79	0,70	0,48	1635	0,95	0,75	2,40	8,70	1700	
184	888	0315D2	298	4,48	95,0	94,9	94,5	91,0	0,82	0,79	0,70	0,46	1979	0,95	0,75	2,50	10,2	1800	
230	890	0315D4	370	6,24	95,1	95,1	94,5	91,5	0,82	0,79	0,72	0,48	2474	1,00	0,80	2,40	11,8	1950	

6.3.4 Cast iron; 460 V; 60 Hz; Class IE3

2-pole

Power rating P_N [kW]	Nominal speed n_n [rpm]	Frame size Type code ALAA... [A]	Nominal current I_n	Locked rotor current (multiple of nominal current) I / I_n	Efficiency at load points				Power factor at load points				Nominal torque [Nm]	Locked rotor torque (multiple of nominal torque) T / T_n	Pull up torque (multiple of nominal torque) T_p / T_n	Break down torque (multiple of nominal torque) T_b / T_n	Moment of inertia J kgm ²	Total mass (B3 version; approx.) [kg]						
					η [%]				$\cos \varphi$															
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load												
0.86	3480	0080M1	1,57	8,9	81,6	80,5	76,7	65,1	0,84	0,78	0,67	0,48	2,360	2,95	2,85	3,70	$1,5 \times 10^{-3}$	17,5						
1,27	3470	0080M3	2,22	8,63	84	83,9	81,6	72,9	0,86	0,80	0,68	0,47	3,495	3,20	3,10	3,65	$1,75 \times 10^{-3}$	19,5						
1,73	3455	0090S1	2,82	8,15	85,5	86,7	86,5	81,5	0,90	0,86	0,77	0,58	4,782	2,95	2,10	3,00	$3,0 \times 10^{-3}$	25						
2,53	3460	0090L1	4,1	9,26	86,5	87,4	87	82,3	0,90	0,86	0,77	0,55	6,983	3,2	2,35	3,15	$3,5 \times 10^{-3}$	28						
3,45	3450	0100L1	5,44	8,63	88,5	89,4	89,2	84,6	0,90	0,88	0,80	0,52	9,55	2,95	2,85	3,35	$6,3 \times 10^{-3}$	38						
4,6	3470	0112M1	7,05	9,65	89,5	90,2	89,9	85,7	0,92	0,86	0,82	0,63	12,66	2,55	2,50	3,25	$11,5 \times 10^{-3}$	50						
6,33	3530	0132S1	10,1	7,82	89,5	89,7	88,9	84,2	0,88	0,85	0,79	0,60	17,13	2,10	2,05	3,00	$18,8 \times 10^{-3}$	70,5						
8,6	3520	0132S3	13,7	7,29	90,2	90,7	90,2	86,8	0,88	0,86	0,79	0,62	23,33	2,10	2,00	3,00	20×10^{-3}	75						
12,7	3525	0160M1	19,0	8,15	91	91	90,1	85	0,92	0,91	0,88	0,75	34,41	2,15	1,90	3,00	46×10^{-3}	110						
17,3	3535	0160M3	26	8,65	91,7	92	91,5	87,3	0,91	0,89	0,84	0,66	46,74	3,05	2,55	3,40	50×10^{-3}	120						
21,3	3525	0160L1	31,3	8,46	91,7	92,4	92,3	89,0	0,93	0,90	0,87	0,72	57,71	2,55	2,10	3,00	59×10^{-3}	137						
25,3	3540	0180M1	38,3	8,12	91,7	92,0	91,3	87,7	0,91	0,86	0,79	0,60	68,25	2,50	2,00	3,00	71×10^{-3}	178						
34,5	3545	0200L1	51,2	7,81	93	92,9	92	87,5	0,91	0,9	0,88	0,78	92,94	2,00	1,60	2,20	150×10^{-3}	276						
42,6	3550	0200L3	62,8	8,12	93,6	93,8	93,6	90,2	0,91	0,91	0,88	0,78	114,6	2,05	1,50	2,55	185×10^{-3}	302						
51,8	3560	0225M1	74,7	8,29	93,6	93,6	92,8	88,4	0,93	0,93	0,93	0,80	139	1,80	1,75	3,00	295×10^{-3}	333						
63	3565	0250M1	91,3	8,1	93,6	93,9	93,3	90,8	0,93	0,92	0,89	0,76	168	2,10	1,60	3,00	385×10^{-3}	456						
86	3570	0280S1	125,5	6,93	94,5	94,5	93,8	90,8	0,91	0,90	0,86	0,69	230	1,20	1,00	3,00	0,60	705						
104	3570	0280M1	151	7,48	95,0	95,0	94,4	91,0	0,91	0,90	0,85	0,68	278,2	1,40	1,15	3,10	0,70	740						
127	3575	0315S1	184	7,28	95,2	95,2	94,5	91	0,91	0,90	0,85	0,69	339	1,30	1,05	3,00	1,20	970						
152	3575	0315M1	218	6,83	95,6	95,5	94,8	91,5	0,92	0,91	0,88	0,74	406	1,30	1,05	2,80	1,30	1025						
184	3577	0315M3	262	7,00	95,8	95,6	94,5	91,5	0,92	0,92	0,89	0,75	491	1,10	1,15	2,70	1,30	1075						
230	3578	0315L1	325	7,84	95,8	95,6	94,5	91,5	0,93	0,92	0,90	0,80	613	1,10	1,15	2,50	1,70	1270						
288	3578	0315D1	407	7,24	95,8	95,6	94,5	91,5	0,93	0,92	0,91	0,81	768	1,10	1,15	2,60	2,60	1765						
362	3578	0315D3	508	7,36	96,0	95,8	94,6	91,5	0,93	0,93	0,92	0,82	966	1,10	1,15	2,60	2,90	1885						

4-pole

Power rating P _N	Nominal speed n _N	Frame size Type code ALAA	Nominal current I _N	Locked rotor current (multiple of nominal current)	Efficiency at load points				Power factor at load points				Nominal torque T _N	Locked rotor torque (multiple of nominal torque)	Pull up torque (multiple of nominal torque)	Break down torque (multiple of nominal torque)	Moment of inertia J	Total mass (B3 version; approx.) m
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load						
[kW]	[rpm]		[A]		[%]				[Nm]									
0,63	1725	0080M1	1,41	6,38	80,0	78,8	74,3	61,3	0,70	0,63	0,48	0,31	3,48	3,25	2,95	3,55	2,5 x 10 ⁻³	17,5
0,86	1710	0080M3	1,74	6,89	84,0	83,6	81,4	73,6	0,74	0,65	0,51	0,32	4,80	3,70	3,40	3,55	3,25 x 10 ⁻³	20,5
1,27	1730	0090S1	2,39	7,12	85,5	86,1	84,6	78,0	0,78	0,70	0,58	0,38	7,01	2,50	1,95	3,00	4,75 x 10 ⁻³	26
1,73	1735	0090L1	3,36	7,44	85,5	85,7	83,9	76,9	0,76	0,67	0,53	0,33	9,52	2,80	2,20	3,30	5,5 x 10 ⁻³	28
2,53	1760	0100L1	4,82	8,50	88,5	88,1	86,9	79,2	0,75	0,66	0,52	0,32	13,73	2,45	1,95	3,50	11 x 10 ⁻³	38
3,45	1750	0100L3	6,15	8,13	88,5	88,5	87,1	80,7	0,79	0,72	0,60	0,39	18,83	2,25	2,20	3,40	13 x 10 ⁻³	40,5
4,6	1740	0112M1	7,96	7,16	88,5	89,2	88,8	84,3	0,82	0,78	0,67	0,45	25,25	2,20	1,75	3,00	21 x 10 ⁻³	54
6,33	1755	0132S1	10,1	7,72	91,7	92,1	91,9	88,0	0,86	0,81	0,71	0,48	34,45	2,55	2,05	3,30	33 x 10 ⁻³	74,5
8,6	1760	0132M1	13,8	8,18	91,7	92,2	91,9	88,7	0,86	0,81	0,71	0,49	46,66	2,85	2,35	3,50	43 x 10 ⁻³	85
12,7	1760	0160M1	19,8	8,33	92,4	93,0	92,9	90,1	0,87	0,84	0,76	0,55	68,91	2,55	2,40	3,55	92 x 10 ⁻³	133
17,3	1755	0160L1	26,8	9,51	93,0	93,5	93,4	90,9	0,87	0,84	0,76	0,55	94,14	2,85	2,80	3,85	115 x 10 ⁻³	138
21,3	1770	0180M1	34,6	7,65	93,6	94	93,5	90,1	0,83	0,79	0,71	0,50	114,9	2,30	2,25	3,55	175 x 10 ⁻³	183
25,3	1770	0180L1	41,4	7,48	93,6	94,0	93,5	90,3	0,82	0,79	0,71	0,49	136,5	2,35	2,30	3,55	198 x 10 ⁻³	199
34,5	1770	0200L1	51,7	7,93	94,1	94,5	94,3	92,3	0,89	0,87	0,82	0,65	186	2,10	1,95	3,00	363 x 10 ⁻³	266
42,6	1780	0225S1	65,8	7,75	94,5	94,7	94,1	90,4	0,86	0,83	0,76	0,54	228	2,10	1,90	3,10	470 x 10 ⁻³	333
51,8	1775	0225M1	80	7,75	94,5	94,5	94,1	90,9	0,86	0,84	0,77	0,55	278,7	2,35	2,00	2,95	0,50	368
63	1780	0250M1	94,6	7,98	95	95	94,2	90,6	0,88	0,86	0,79	0,57	338	2,40	2,05	3,00	0,98	492
86	1780	0280S1	126	6,88	95,4	95,4	94,2	91,0	0,90	0,89	0,84	0,67	461	1,70	1,45	2,60	1,60	710
104	1780	0280M1	152	7,23	95,4	95,4	94,5	91,5	0,90	0,89	0,84	0,67	558	1,80	1,55	2,60	1,80	755
127	1785	0315S1	185,9	7,47	95,8	95,7	94,5	91,5	0,90	0,89	0,83	0,65	679	1,80	1,55	2,80	2,90	1080
152	1783	0315M1	222	6,23	95,8	95,5	94,5	91,5	0,90	0,89	0,86	0,72	814	1,50	1,25	2,30	3,10	1100
184	1785	0315M3	265	6,94	96,2	96,0	94,6	92,0	0,91	0,90	0,86	0,70	984	1,10	1,15	2,40	3,00	1220
230	1788	0315L1	329	6,71	96,2	96,0	94,8	92,0	0,91	0,90	0,87	0,72	1228	1,10	1,15	2,30	3,80	1400
288	1788	0315D1	410	7,46	96,2	96,0	95,0	92,2	0,92	0,91	0,89	0,75	1538	1,10	1,15	2,40	7,30	1990
362	1788	0315D3	514	7,46	96,0	95,8	95,0	92,2	0,92	0,92	0,90	0,77	1934	1,10	1,15	2,50	8,50	2110

6-pole

Power rating P_N [kW]	Nominal speed n_N [rpm]	Frame size Type code ALAA..	Nominal current I_N	Locked rotor current (multiple of nominal current) I_L/I_N	Efficiency at load points				Power factor at load points				Nominal torque T_N [Nm]	Locked rotor torque (multiple of nominal torque) T_L/T_N	Pull up torque (multiple of nominal torque) T_p/T_N	Break down torque (multiple of nominal torque) T_b/T_N	Moment of inertia J kgm ²	Total mass (B3 version; approx.) [kg]
					Full load	3/4 load	2/4 load	1/4 load	Full load	3/4 load	2/4 load	1/4 load						
0,43	1120	0080M1	1,10	4,54	76,0	76,4	73,1	59,5	0,65	0,55	0,43	0,27	3,67	2,25	2,20	2,55	$2,5 \times 10^{-3}$	18
0,63	1110	0080M3	1,56	4,48	76,0	76,4	73,5	60,2	0,67	0,57	0,44	0,28	5,42	2,10	2,05	2,40	$3,0 \times 10^{-3}$	19
0,86	1140	0090S1	1,86	5,37	82,5	83,8	82,7	73,0	0,71	0,62	0,49	0,30	7,204	1,95	1,70	2,50	$5,5 \times 10^{-3}$	27,5
1,27	1130	0090L1	2,68	4,80	82,5 (*)	83,3	82,6	77,3	0,72	0,62	0,51	0,32	10,73	1,85	1,65	2,35	$6,5 \times 10^{-3}$	30
1,73	1150	0100L1	3,54	5,08	84,0 (*)	84,2	82,7	75,5	0,73	0,66	0,53	0,34	14,37	2,00	1,55	2,40	14×10^{-3}	41
2,53	1155	0112M1	5,44	5,14	86,5 (*)	86,5	84,7	77,5	0,68	0,60	0,48	0,30	20,92	1,65	1,60	2,70	21×10^{-3}	52,5
3,45	1165	0132S1	6,28	6,52	89,5	89,5	88,1	82,7	0,77	0,70	0,57	0,37	28,28	1,9	1,65	3,00	38×10^{-3}	74
4,6	1170	0132M1	8,26	7,38	90,2	90,4	88,9	83,8	0,76	0,71	0,58	0,37	37,55	2,1-0	1,70	3,00	51×10^{-3}	84
6,33	1170	0132M3	11,8	7,37	90,2	90,0	88,6	82,6	0,75	0,67	0,54	0,33	51,67	2,10	1,85	3,30	54×10^{-3}	87
8,6	1170	0160M1	14,8	7,43	91,0	91,5	91,0	86,4	0,80	0,75	0,65	0,43	70,2	2,35	2,10	3,00	120×10^{-3}	110
12,7	1170	0160L1	21,5	7,95	91,7	92,0	91,7	87,4	0,81	0,76	0,65	0,42	103,7	2,45	2,20	3,00	157×10^{-3}	138
17,3	1165	0180L1	28,4	7,21	91,7	92,3	92,6	89,7	0,83	0,81	0,73	0,51	141	2,25	2,00	2,80	335×10^{-3}	205
21,3	1175	0200L1	35,1	7,69	93,0	93,4	93,3	90,0	0,82	0,78	0,70	0,48	173	2,55	1,95	2,60	0,46	263
25,3	1175	0200L3	41,6	7,69	93	93,5	93,5	90,5	0,82	0,79	0,71	0,49	205	2,45	1,90	2,50	0,52	283
34,5	1175	0225M1	53,5	6,35	93,0	93,7	93,7	90,6	0,87	0,86	0,81	0,61	280	1,75	1,20	2,10	0,76	343
42,6	1180	0250M1	64,9	7,70	94,1	94,3	94,0	90,7	0,88	0,86	0,80	0,59	344	2,20	1,95	2,50	1,05	458
51,8	1185	0280S1	80,9	6,18	94,5	94,5	93,5	90,5	0,85	0,83	0,76	0,55	417	1,50	1,25	2,60	1,90	675
63	1185	0280M1	98,1	6,44	94,5	94,5	93,5	90,6	0,85	0,83	0,76	0,55	507,7	1,60	1,35	2,70	2,40	745
86	1185	0315S1	132	6,81	95,0	95,0	93,6	90,8	0,86	0,83	0,77	0,55	693	1,80	1,55	2,60	3,70	985
104	1185	0315M1	160	6,87	95,2	95,0	94,0	91,0	0,86	0,84	0,78	0,57	838	1,80	1,55	2,40	4,20	1065
127	1188	0315M3	194	7,16	95,8	95,8	94,2	91,5	0,86	0,83	0,76	0,54	1021	2,10	1,85	2,70	5,10	1170
152	1188	0315L1	227	6,51	95,8	95,8	94,5	91,5	0,88	0,86	0,80	0,61	1222	1,10	1,15	2,30	5,30	1345
184	1188	0315L3	275	6,56	95,9	96,0	94,6	92,0	0,88	0,86	0,80	0,61	1479	1,10	1,15	2,30	5,80	1435
230	1188	0315D1	341	7,14	96,0	96,0	94,8	92,0	0,88	0,87	0,81	0,61	1849	1,30	1,38	2,40	10,9	1930
288	1188	0315D3	427	7,16	96,0	96,0	95,0	92,2	0,88	0,87	0,82	0,62	2315	1,20	1,26	2,30	11,5	2010

7 Outline drawings

7.1 Aluminium design

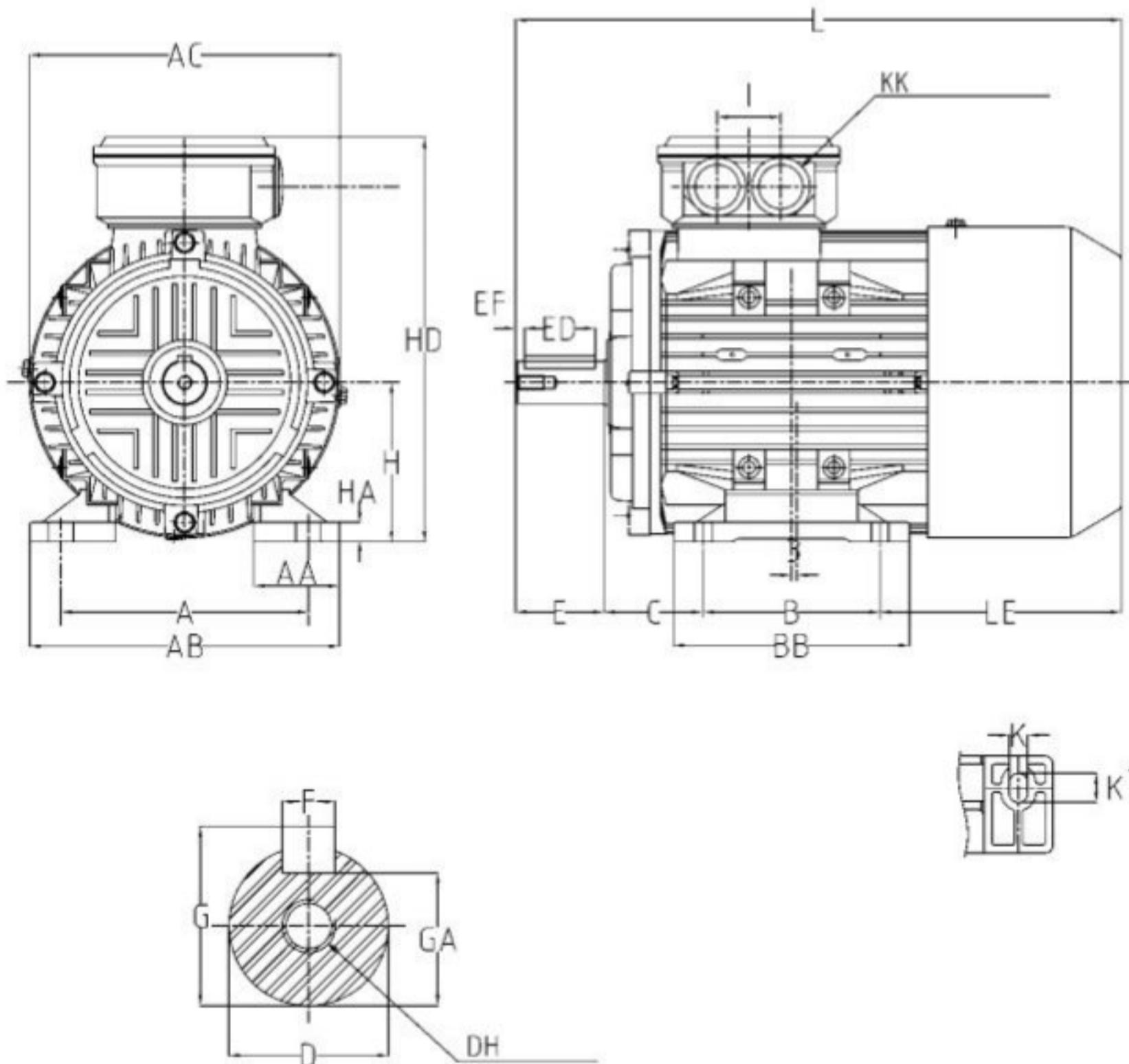


Figure 7-1: Outline drawing of aluminium design, feet version, mounting B3, frame size 63 – 160 (sample)

Frame size		Outline dimensions of aluminium design, feet version (mounting B3), dimensions in [mm]														
		A	AA	AB	AC	B	BB	C	H	HA	HD	K	K'	KK	I	L
63	S													2 M16 x1,5		
	M	100	35,5	125	120	80	105	40	63	9	171	10	14		28	220,5
	L															
71	S													2 M16 x1,5		
	M	112	36,5	136	136	90	116	45	71	9	187	10	14		28	245
	L															
80	S													2 M25 x1,5		
	M	125	42,5	158	159	100	126	50	80	9	208	10	14		28	314
	L															
90	S	140	49	175	176	100	133	56	90	11	228	10	14	38	343	
	M															
	L	140	49	175	176	125	155	56	90	11	228	10	14		38	368
100	S													2 M25 x1,5 + M32 x1,5		
	M														38	404
	L	160	52	196	198	140	174	63	100	12	248	12	16			
112	S													M25 x1,5 + M32 x1,5		
	M	190	59	225	220	140	177	70	112	14	277	12	16		40	415
	L															
132	S	216	63,5	254	258	140	180	89	132	16	317	12	16	40	462	
	M	216	63,5	254	258	178	224	89	132	16	317	12	16		40	500
	L															
160	S													2 M40 x1,5+ 1 M20 x1,5		
	M	254	54	290	314	210	294	108	160	16	392	15	19		56	643
	L	254	54	290	314	254	294	108	160	16	392	15	19		56	643

Frame size	Shaft extension									Bearings			
	LE	D	E	ED	EF	F	G	GA	DH	at DE	at NDE	Figure	
63	S									M4 x 8			
	M	77,5	11 j6	23	16	4	4	8,5	12,5		6201ZZC3	6201ZZC3	7-1
	L												
71	S									M5 x 10			
	M	80	14 j6	30	22	4	5	11	16		6202ZZC3	6202ZZC3	7-1
	L												
80	S									M6 x 12			
	M	124	19 j6	40	32	4	6	15,5	21,5		6204ZZC3	6204ZZC3	7-1
	L												
90	S	137	24 j6	50	40	5	8	20	27	M8 x 16	6205ZZC3	6205ZZC3	7-1
	M												
	L	137	24 j6	50	40	5	8	20	27		6205ZZC3	6205ZZC3	7-1
100	S									M10 x 20			
	M												
	L	141	28 j6	60	50	5	8	24	31		6206ZZC3	6305ZZC3	7-1
112	S									M10 x 20			
	M	145	28 j6	60	50	5	8	24	31		6306ZZC3	6306ZZC3	7-1
	L												
132	S	153	38 k6	80	70	5	10	33	41	M12 x 24	6308ZZC3	6308ZZC3	7-1
	M	153	38 k6	80	70	5	10	33	41		6308ZZC3	6308ZZC3	7-1
	L												
160	S									M16 x 32			
	M	171	42 k6	110	100	5	12	37	45		6309ZZC3	6309ZZC3	7-1
	L	171	42 k6	110	100	5	12	37	45		6309ZZC3	6309ZZC3	7-1

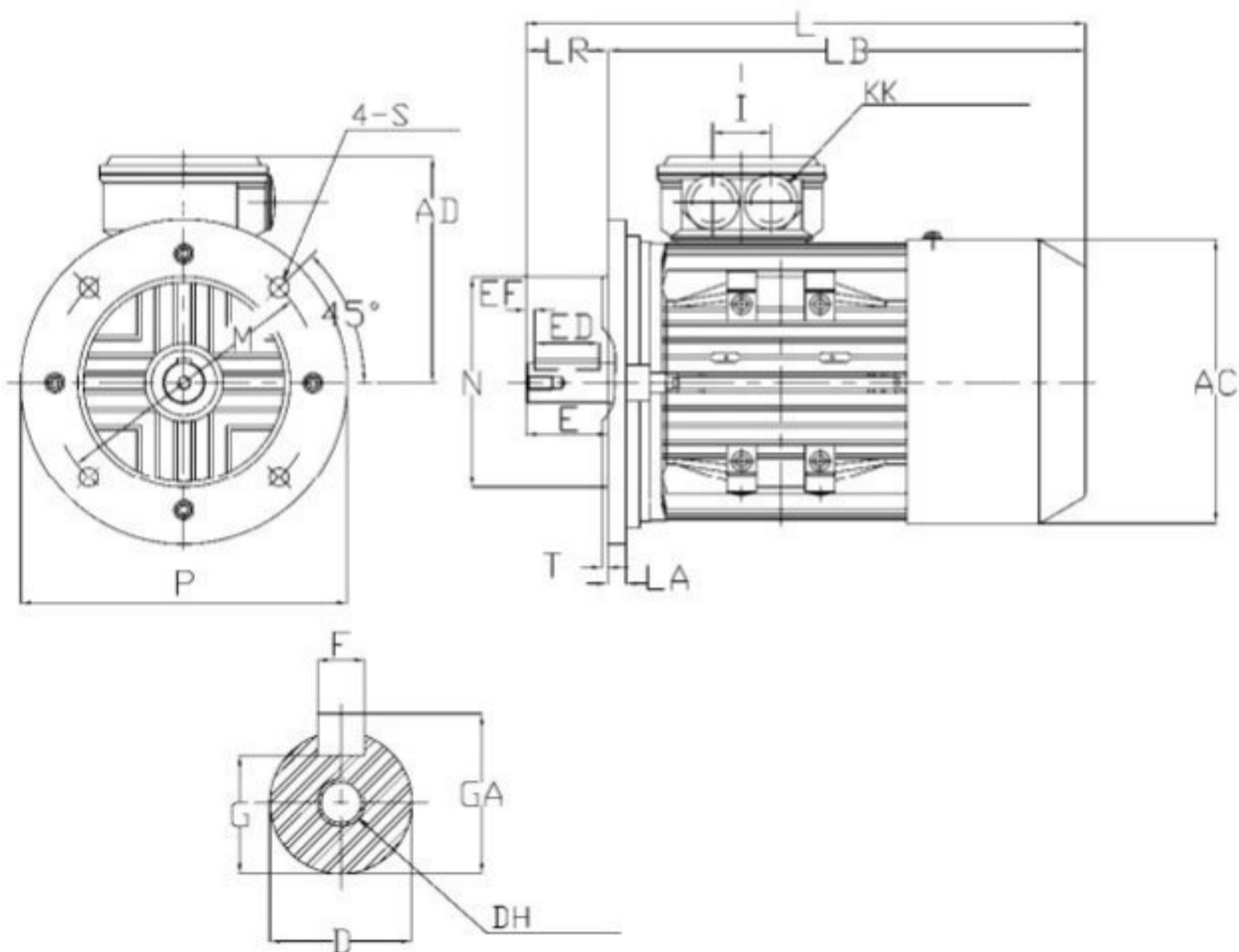


Figure 7-2: Outline drawing of aluminium design, flange version, mounting B5, frame size 63 – 160 (sample)

Frame size		Outline drawing of aluminium design, flange version, mounting B5, frame size 63 – 160, dimensions in [mm]												
		AC	AD	KK	LA	LB	LR	M	N	P	S	T	I	L
63	S			2 M16 x1,5										
	M	120	108		9	197,5	23	115	95	140	Ø 10	3	28	220,5
	L													
71	S			2 M25 x1,5										
	M	136	116		10	215	30	130	110	160	Ø 10	3,5	28	245
	L													
80	S			2 M25 x1,5										
	M	159	129		10	274	40	165	130	200	Ø 12	3,5	28	314
	L													
90	S	176	139	2 M25 x1,5	11	293	50	165	130	200	Ø 12	3,5	38	343
	M													
	L	176	139		11	318	50	165	130	200	Ø 12	3,5	38	368
100	S			2 M25 x1,5										
	M													
	L	198	149		14	344	60	215	180	250	Ø 14,5	4	38	404
112	S			M25 x1,5 + M32 x1,5										
	M	220	167		14	355	60	215	180	250	Ø 14,5	4	40	415
	L													
132	S	258	186	2 M40 x1,5+ M20 x1,5	15,5	382	80	265	230	300	Ø 14,5	4	40	462
	M	258	186		15,5	420	80	265	230	300	Ø 14,5	4	40	500
	L													
160	S			2 M40 x1,5+ M20 x1,5										
	M	314	232		16	533	110	300	250	350	Ø 18,5	5	56	643
	L	314	232		16	533	110	300	250	350	Ø 18,5	5	56	643

Frame size		Shaft extension							Bearings				
		D	E	ED	EF	F	G	GA	DH	at DE	at NDE	Figure	
63	S								M4 x 8				
	M	11 j6	23	16	4	4	8,5	12,5		6201ZZC3	6201ZZC3	7-2	
	L												
71	S								M5 x 10				
	M	14 j6	30	22	4	5	11	16		6202ZZC3	6202ZZC3	7-2	
	L												
80	S								M6 x 12				
	M	19 j6	40	32	4	6	15,5	21,5		6204ZZC3	6204ZZC3	7-2	
	L												
90	S	24 j6	50	40	5	8	20	27	M8 x 16	6205ZZC3	6205ZZC3	7-2	
	M												
	L	24 j6	50	40	5	8	20	27		6205ZZC3	6205ZZC3	7-2	
100	S								M10 x 20				
	M									6206ZZC3	6305ZZC3	7-2	
	L	28 j6	60	50	5	8	24	31					
112	S								M10 x 20				
	M	28 j6	60	50	5	8	24	31		6306ZZC3	6306ZZC3	7-2	
	L												
132	S	38 k6	80	70	5	10	33	41	M12 x 24	6308ZZC3	6308ZZC3	7-2	
	M	38 k6	80	70	5	10	33	41		6308ZZC3	6308ZZC3	7-2	
	L												
160	S								M16 x 32				
	M	42 k6	110	100	5	12	37	45		6309ZZC3	6309ZZC3	7-2	
	L	42 k6	110	100	5	12	37	45		6309ZZC3	6309ZZC3	7-2	

Outline drawings

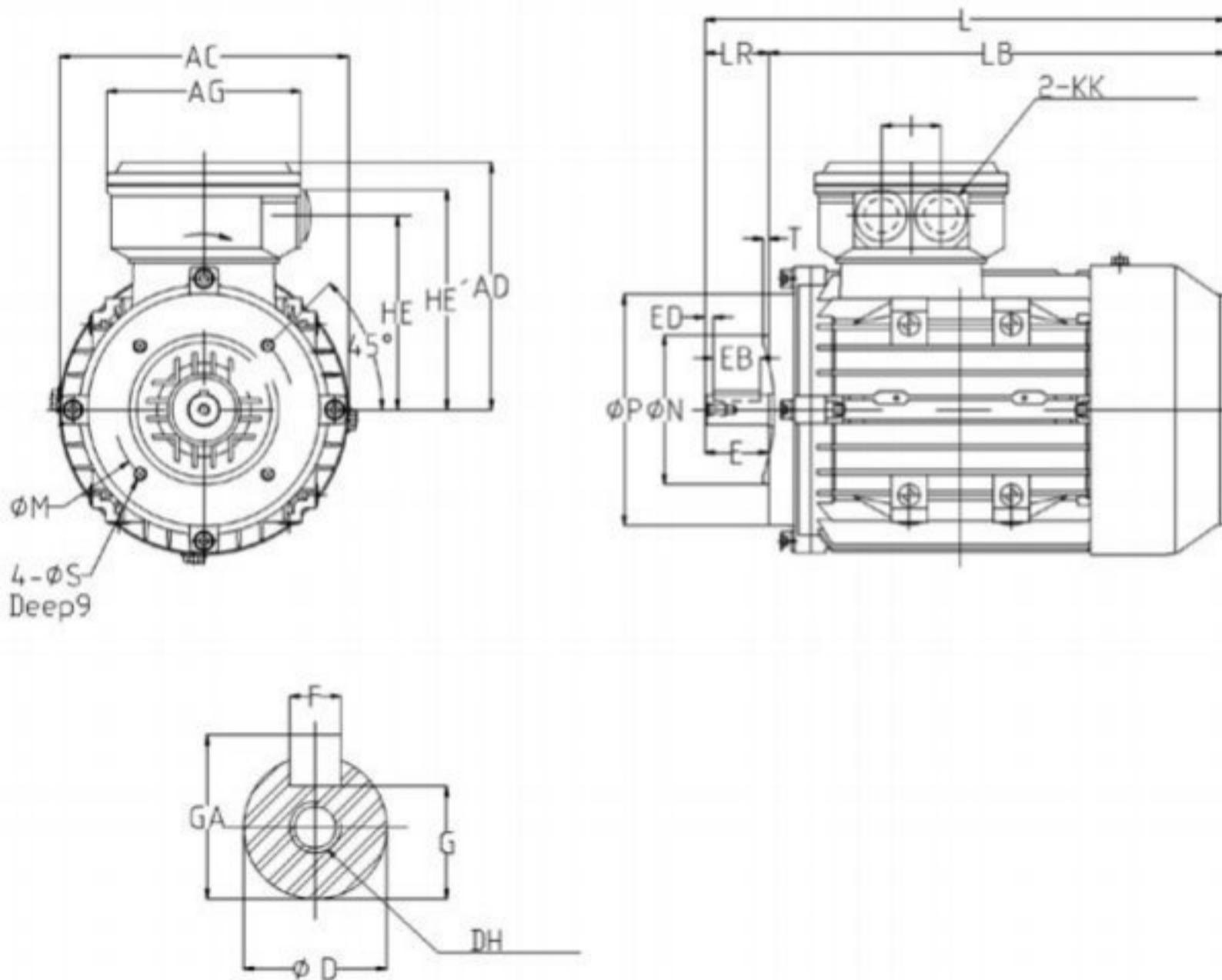


Figure 7-3: Outline drawing of aluminium design, face version, mounting B14, frame size 63 – 160 (sample)

Frame size		Outline drawing of aluminium design, face version, mounting B14, frame size 63 – 160, dimensions in [mm]												
		AC	AD	KK	LA	LB	LR	M	N	P	S	T	I	L
63	S			1 M20 x 1.5 + 1										
	M	120	108		9	197,5	23	75	60	90	M5	3	28	220,5
	L													
71	S			M16 x 1.5										
	M	136	116		10	215	30	85	70	105	M6	3,5	28	245
	L													
80	S			2 M25 x 1.5 + 1										
	M	159	129		10	274	40	100	80	120	M6	3,5	28	314
	L													
90	S	176	139	M20 x 1.5	11	293	50	115	95	140	M8	3,5	38	343
	M													
	L	176	139		11	318	50	115	95	140	M8	3,5	38	368
100	S			2 M32 x 1.5 + 1										
	M				14	344	60	130	110	160	M8	4	38	404
	L	198	149											
112	S			M20 x 1.5	14	355	60	130	110	160	M8	4	40	415
	M	220	167											
	L													
132	S	258	186	2 x M40 x 1.5 + 1 x M20 x 1.5	15,5	382	80	165	130	200	M10	4	40	462
	M	258	186		15,5	420	80	165	130	200	M10	4	40	500
	L													
160	S			16										
	M	314	232		16	533	110	210	180	250	M12	5	56	643
	L	314	232		16	533	110	210	180	250	M12	5	56	643

Frame size	Shaft extension								Bearings				
	D	E	ED	EF	F	G	GA	DH	at DE	at NDE	Figure		
63	S							M4 x 8					
	M	11 j6	23	16	4	4	8,5		6201ZZC3	6201ZZC3	7-3		
	L												
71	S							M5 x 10					
	M	14 j6	30	22	4	5	11		6202ZZC3	6202ZZC3	7-3		
	L												
80	S							M6 x 12					
	M	19 j6	40	32	4	6	15,5		6204ZZC3	6204ZZC3	7-3		
	L												
90	S	24 j6	50	40	5	8	20	27	M8 x 16	6205ZZC3	6205ZZC3	7-3	
	M												
	L	24 j6	50	40	5	8	20	27	6205ZZC3	6205ZZC3	7-3		
100	S							M10 x 20					
	M												
	L	28 j6	60	50	5	8	24	31	6206ZZC3	6305ZZC3	7-3		
112	S							M10 x 20					
	M	28 j6	60	50	5	8	24		6306ZZC3	6306ZZC3	7-3		
	L												
132	S	38 k6	80	70	5	10	33	41	M12 x 24	6308ZZC3	6308ZZC3	7-3	
	M	38 k6	80	70	5	10	33	41		6308ZZC3	6308ZZC3	7-3	
	L												
160	S							M16 x 32					
	M	42 k6	110	100	5	12	37	45	6309ZZC3	6309ZZC3	7-3		
	L	42 k6	110	100	5	12	37	45	6309ZZC3	6309ZZC3	7-3		

7.2 Cast iron design

7.2.1 Cast iron design; feet version (B3)

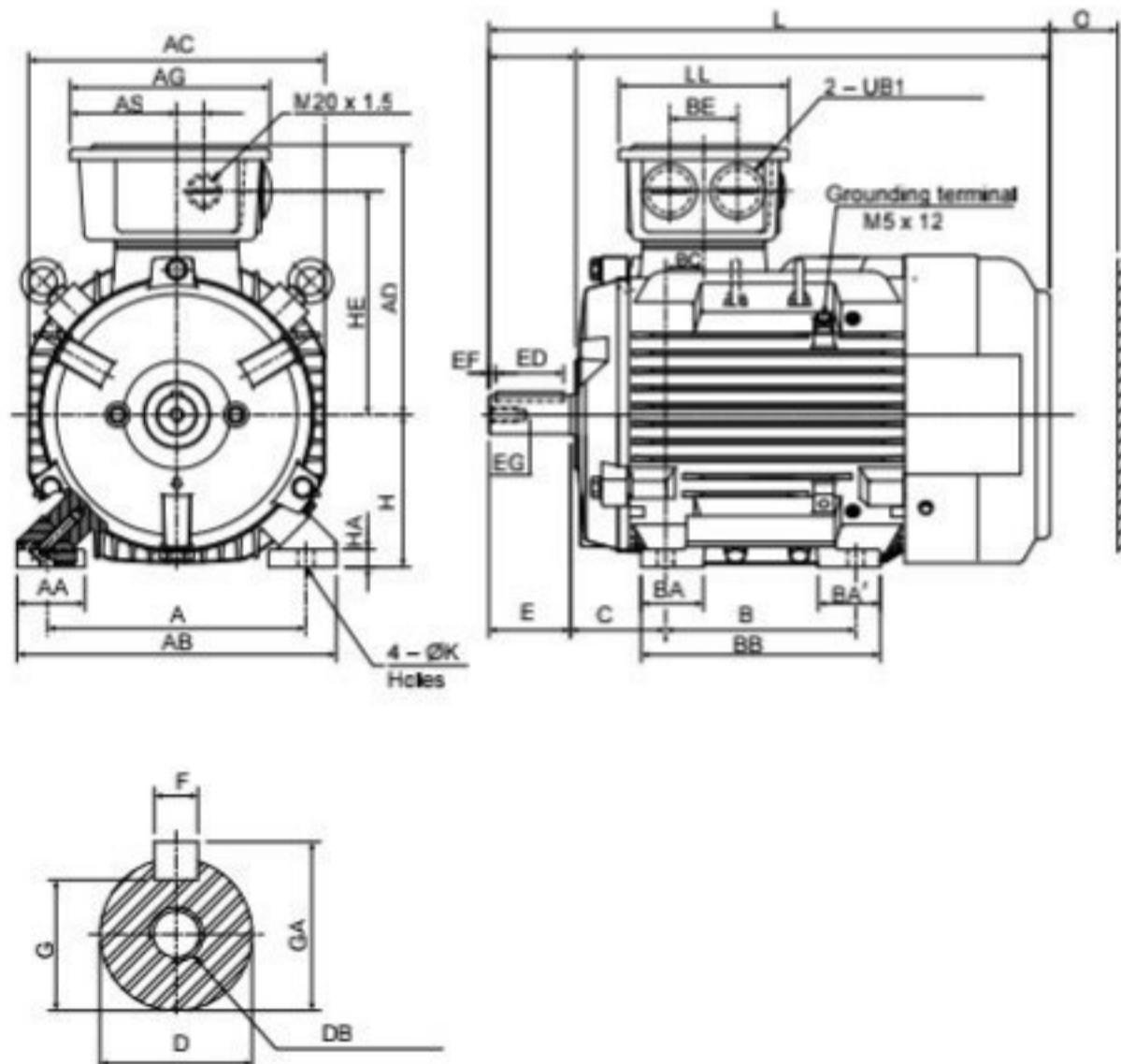


Figure 7-4: Outline drawing of cast iron design, feet version, mounting B3; frame size 80 – 112

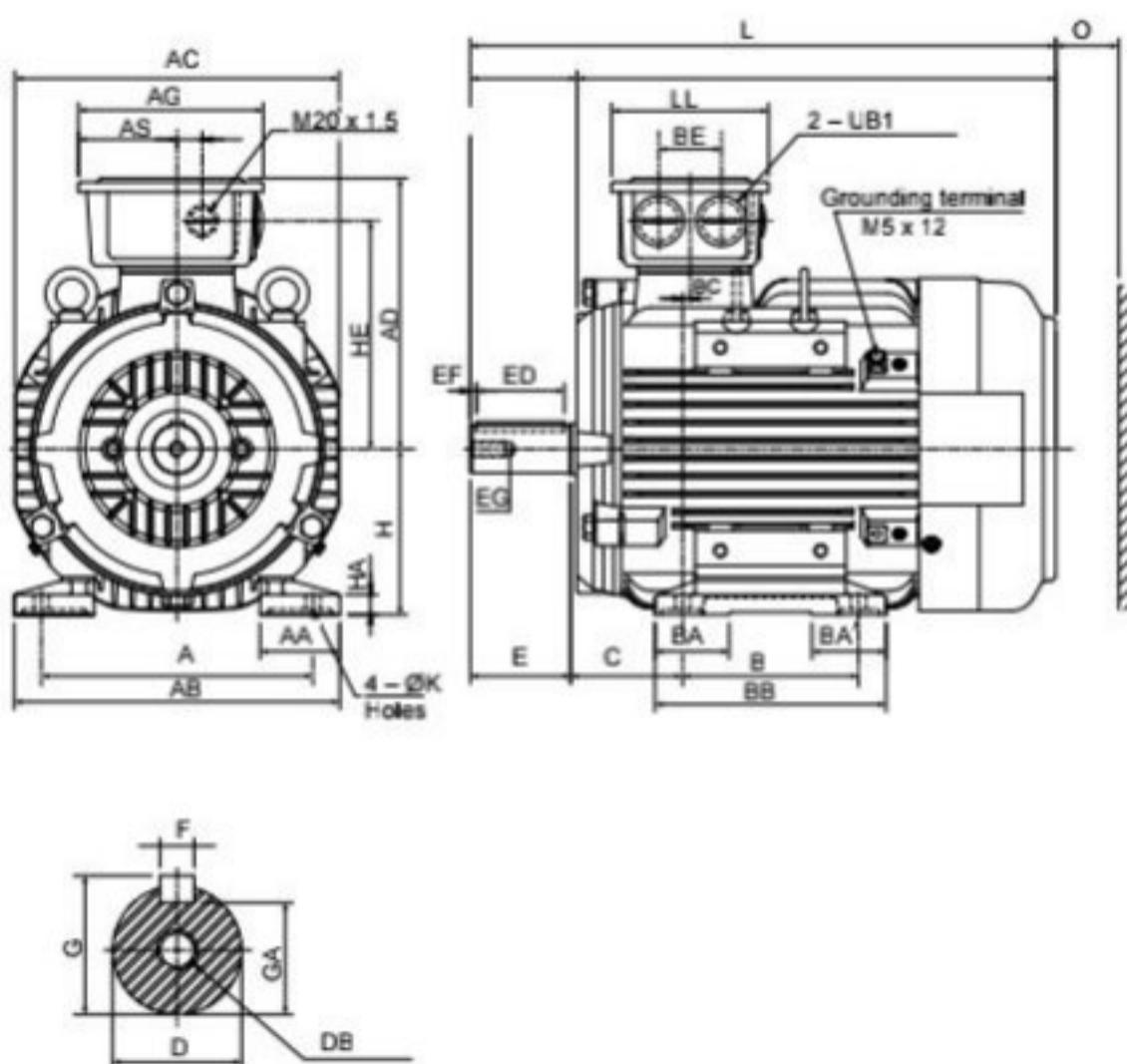


Figure 7-5: Outline drawing of cast iron design, feet version, mounting B3; frame size 132

Frame size		Outline drawing of cast iron design, feet version, mounting B3; frame size 80M – 112M, dimensions in [mm]																		
		A	AA	AB	AC	AD	AG	AS	B	B'	BA	BA'	BB	BE	BC	C	H	HA	HE	HE'
80	S																			
	M	125	35	161	156	161	115	57.5	100		35.5	35.5	130	40	18.5	50	80	10	123.5	—
	L																			—
90	S	140	40	180	176	171	115	57.5	100		33.0	33.0	125	40	36	56	90	10	133.5	
	M																			—
	L	140	40	180	176	171	115	57.5					150	40	36	56	90	10	133.5	—
100	S																			
	M																			
	L	160	40	200	196	191	147	68.5	140		43.5	43.5	176	46	21	63	100	12	157	—
112	S																			—
	M	190	50	235	218	198.5	147	68.5	140		45.5	45.5	176	46	28	70	112	13	164.5	—
	L																			
132	S	216	63.5	259	258	216	147	68.5	140		59	59	184	46	6	89	132	16	182	
	M	216	63.5	259	258	216	147	68.5	178		59	97	222	46	6	89	132	16	182	
	L																			

*) = 4-, 6- and 8-pole version

Frame size		Shaft extension															Bearings		
		K	L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
80	S																		
	M	10	293.0	115	40	M25 x1.5		19	40		32	16	6	15.5	21.5	M6	6204ZZC3	6204ZZC3	7-4
	L																		
90	S	10	344.5	115	40	M25 x1.5		24	50		40	19	8	20.0	27.0	M8	6205ZZC3	6205ZZC3	7-4
	M																		
	L	10	369.5	115	40	M25 x1.5		24	50		40	19	8	20.0	27.0	M8	6205ZZC3	6205ZZC3	7-4
100	S																		
	M																		
	L	12	392.0	125	50	M32 x1.5		28	60		50	22	8	24.0	31.0	M10	6206ZZC3	6206ZZC3	7-4
112	S																		
	M	12	412.5	125	50	M32 x1.5		28	60		50	22	8	24.0	31.0	M10	6306ZZC3	6306ZZC3	7-4
	L																		
132	S	12	466.0	125	50	M32 x1.5		38	80		70	28	10	33	41	M12	6308ZZ3	6306ZZC3	7-5
	M	12	504	125	50	M32 x1.5		38	80		70	28	10	33	41	M12	6308ZZ3	6306ZZC3	7-5
	L																		

*) = 4-, 6- and 8-pole version

Outline drawings

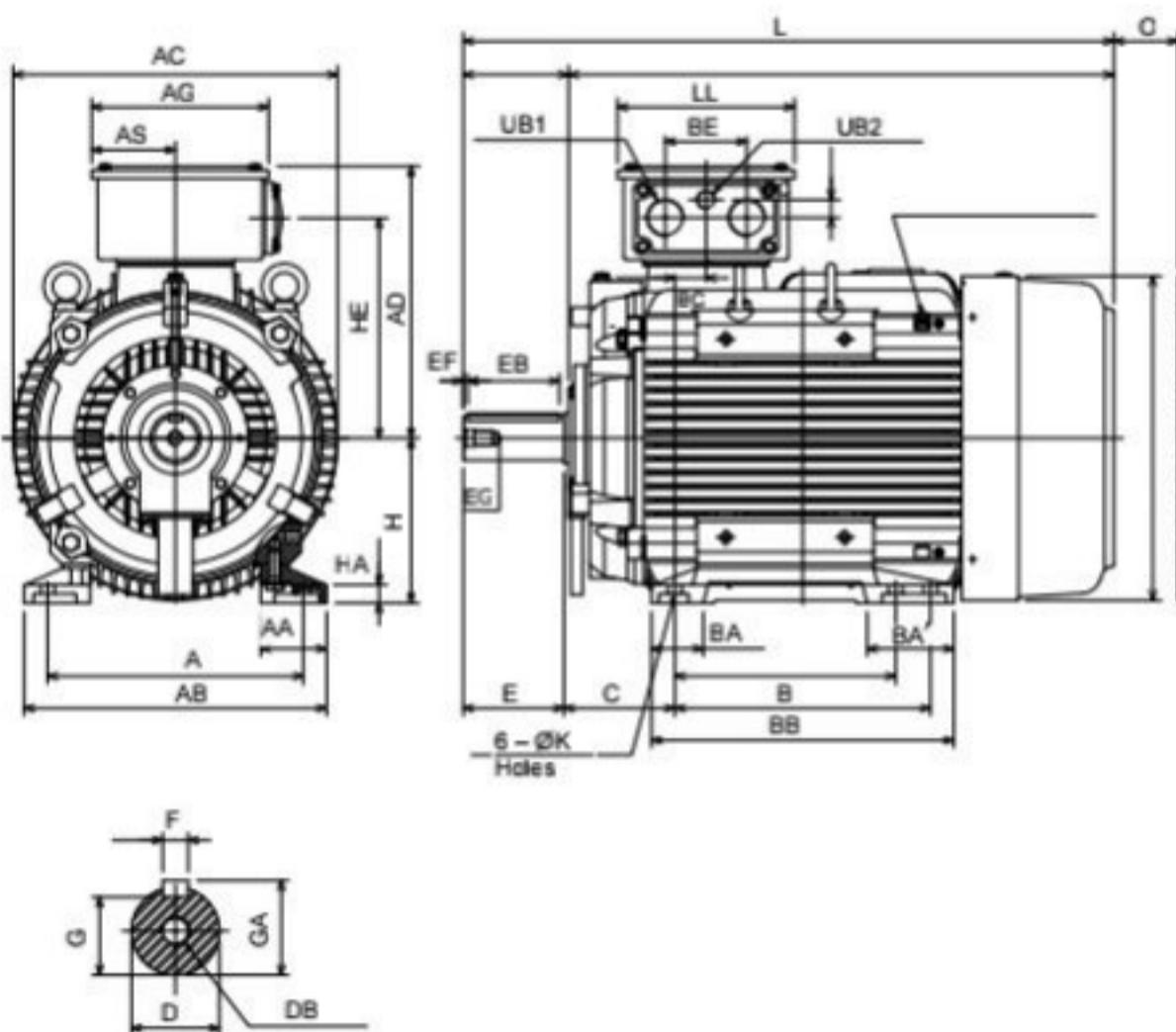


Figure 7-6: Outline drawing of cast iron design, feet version, mounting B3; frame size 160 – 180

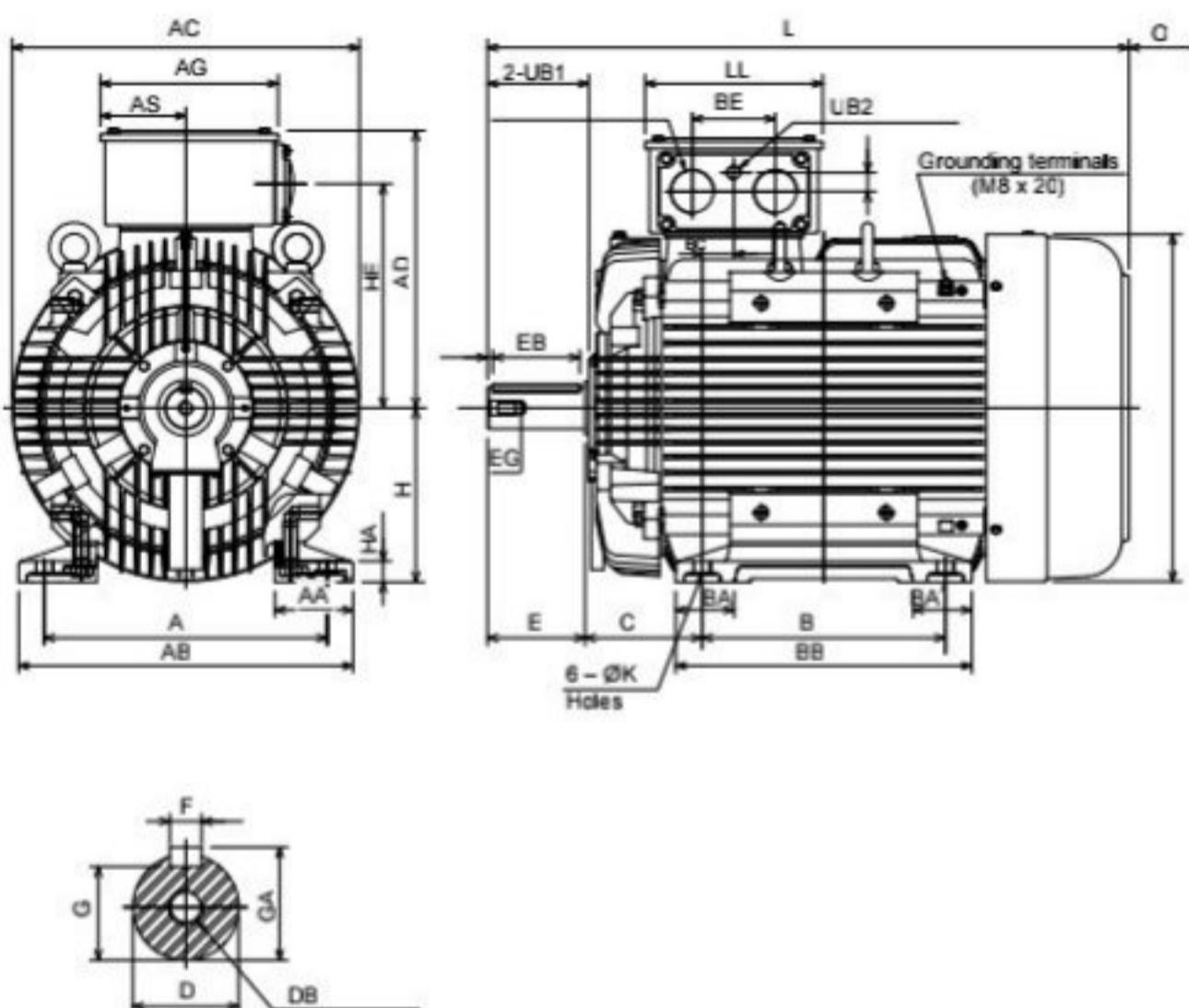


Figure 7-7: Outline drawing of cast iron design, feet version, mounting B3; frame size 200 – 250 (sample)

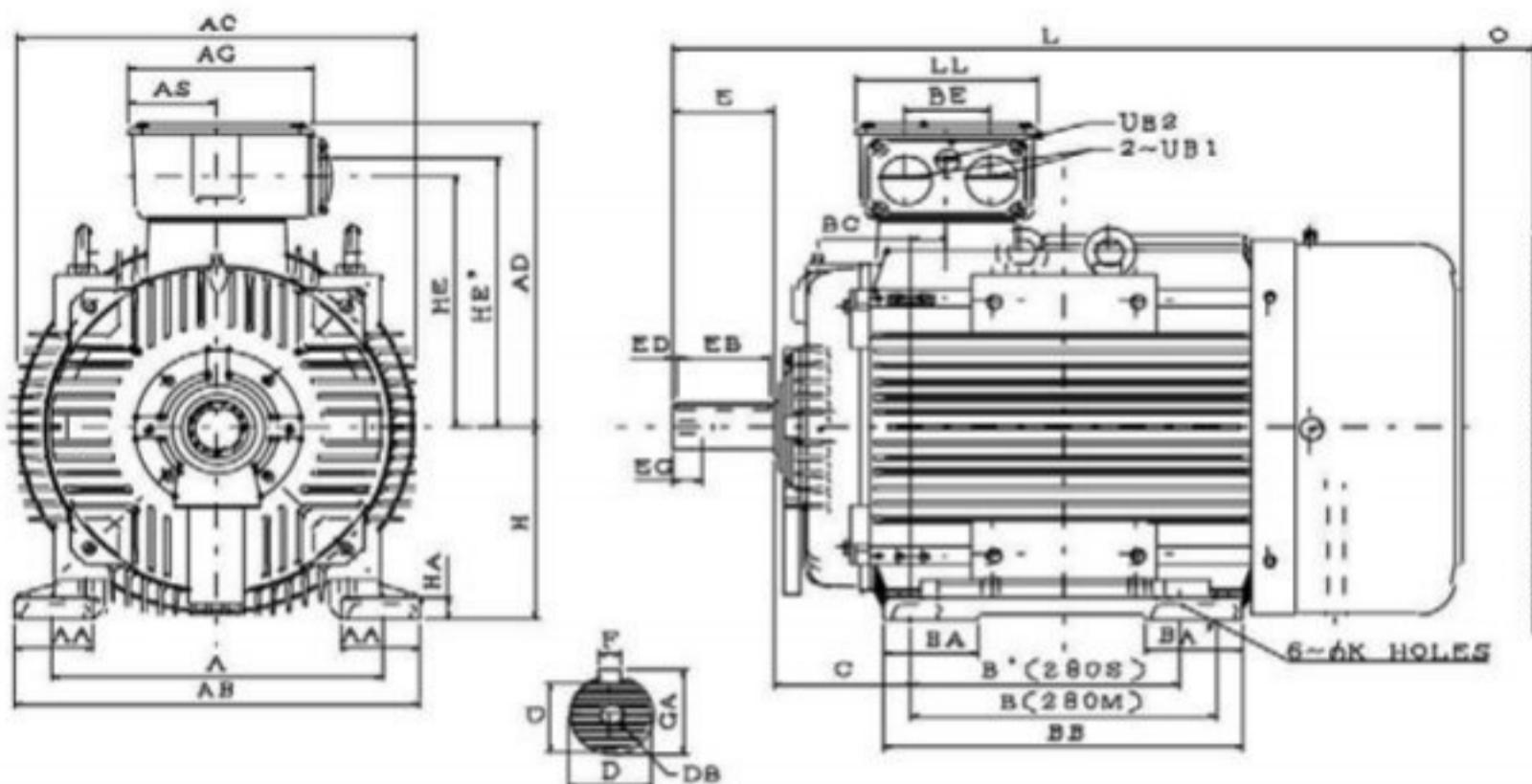


Figure 7-8: Outline drawing of cast iron design, feet version, mounting B3; frame size 280

Outline drawings

Frame size		Outline drawing of cast iron design, feet version, mounting B3; frame size 160 – 280, dimensions in [mm]																		
		A	AA	AB	AC	AD	AG	AS	B	B'	BA	BA'	BB	BE	BC	C	H	HA	HE	HE'
160	S																			
	M	254	71	300	317	271	193	91.5	210	—	46	46	256	77	38	108	160	18	215	—
	L	254	71	300	317	271	193	91.5	254	210	46	90	300	77	38	108	160	18	215	—
180	S																			
	M	279	72	330	354	297	193	91.5	241	—	57	57	292	77	34	121	180	20	241	—
	L	279	72	330	354	297	193	91.5	279	241	57	95	330	77	34	121	180	20	241	—
200	S																			
	M																			
	L	318	88	378	398	330	231	110.5	305	—	70	70	365	95	53	133	200	24	262	—
225	S	356	94	416	449	356	231	110.5	286	—	70	70	350	95	30.5	149	225	28	288	—
	M	356	94	416	449	356	231	110.5	311	286	70	95	375	95	30.5	149	225	28	288	—
	M*	356	94	416	449	356	231	110.5	311	286	70	95	375	95	30.5	149	225	28	288	—
	L																			
250	S																			
	M	406	112	480	498	398	255	122.5	349	—	84	84	425	111	45.5	168	250	30	322	—
	M*	406	112	480	498	398	255	122.5	349	—	84	84	425	111	45.5	168	250	30	322	—
	L																			
280	S	457	110	560	550	446	255	122.5	—	368	130	130	445	119	48	190	280	32	367	394
	S*	457	110	560	550	446	255	122.5	—	368	130	130	445	119	48	190	280	32	367	394
	S**	457	110	560	550	446	255	122.5	—	368	130	130	445	119	48	190	280	32	367	394
280	M	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394
	M*	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394
	M**	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version

Frame size		Overall dimensions						Shaft extension								Bearings			
		K	L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
160	S																		
	M	14.5	608	193	60	M40 x 1.5	M20 x 1.5	42 k6	110	100	5.0	32	12	37.0	45.0	M16	6309ZZC3	6307ZZC3	7-6
	L	14.5	652	193	60			42 k6	110	100	5.0	32	12	37.0	45.0	M16	6309ZZC3	6307ZZC3	7-6
180	S																		
	M	14.5	672	193	70	M40 x 1.5	M20 x 1.5	48 k6	110	100	5.0	32	14	42.5	51.5	M16	6311C3	6310C3	7-6
	L	14.5	710	193	70			48 k6	110	100	5.0	32	14	42.5	51.5	M16	6311C3	6310C3	7-6
200	S																		
	M																		
	L	18.5	770	231	80	M50 x 1.5	M20 x 1.5	55m6	110	100	5.0	40	16	49.0	59.0	M20	6312C3	6212C3	7-7
225	S	18.5	816	231	90			60m6	140	125	7.5	40	18	53.0	64.0	M20	6313C3	6213C3	7-7
	M	18.5	811	231	90			55m6	110	100	5.0	40	16	49.0	59.0	M20	6312C3	6212C3	7-7
	M*	18.5	841	231	90			60m6	140	125	7.5	40	18	53.0	64.0	M20	6313C3	6213C3	7-7
	L																		
250	S																		
	M	24.0	921	255	105	M63 x 1.5	M20 x 1.5	60m6	140	125	7.5	40	18	53.0	64.0	M20	6313C3	6313C3	7-7
	M*	24.0	921	255	105			65m6	140	125	7.5	40	18	58.0	69.0	M20	6315C3	6313C3	7-7
280	S	24.0	1037	255	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-8
	S*	24.0	1037	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-8
	S**	24.0	1037	255	—			75m6											

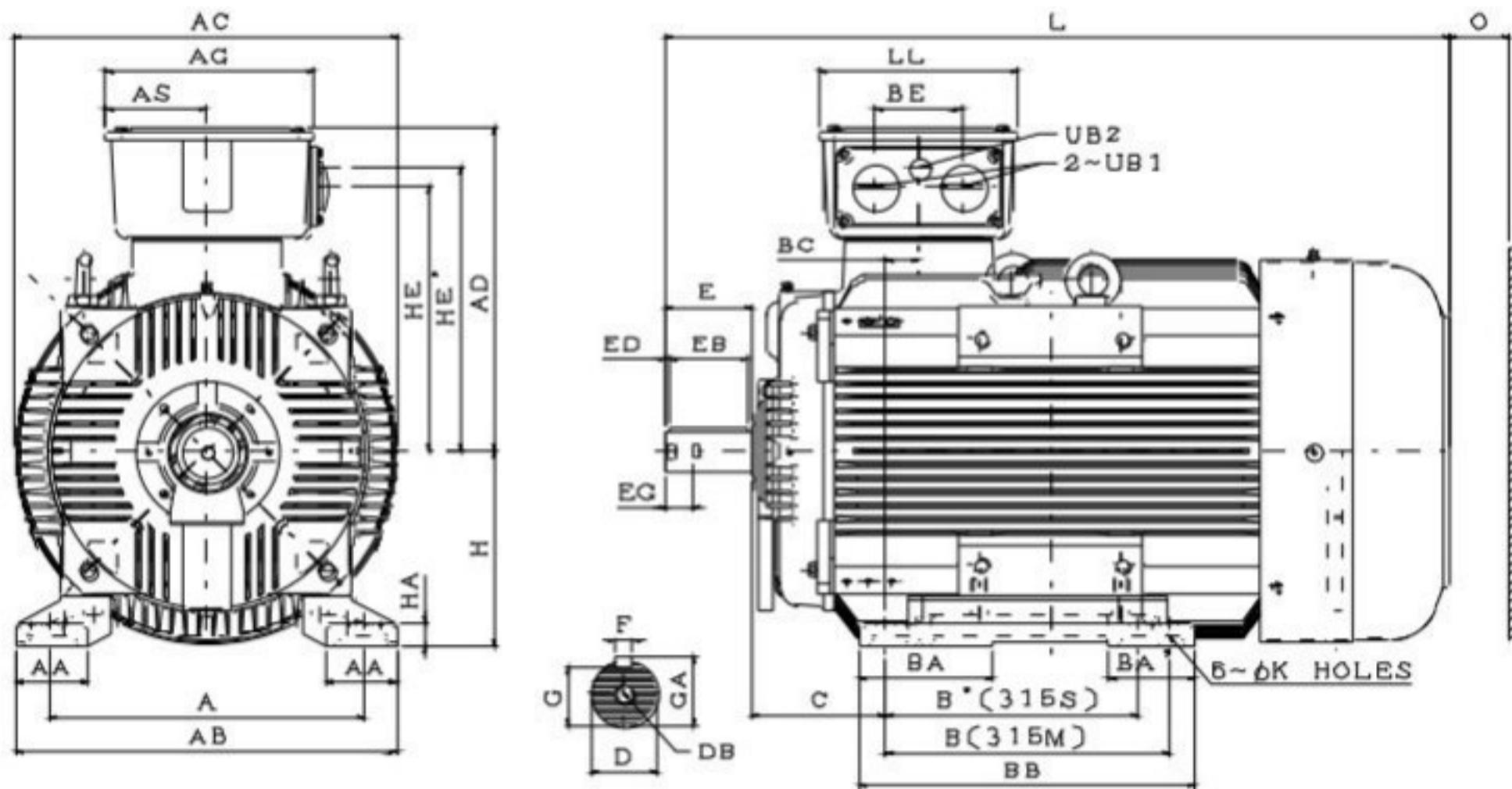


Figure 7-9: Outline drawing of cast iron design, feet version, mounting B3; frame size 315S – 315M (sample)

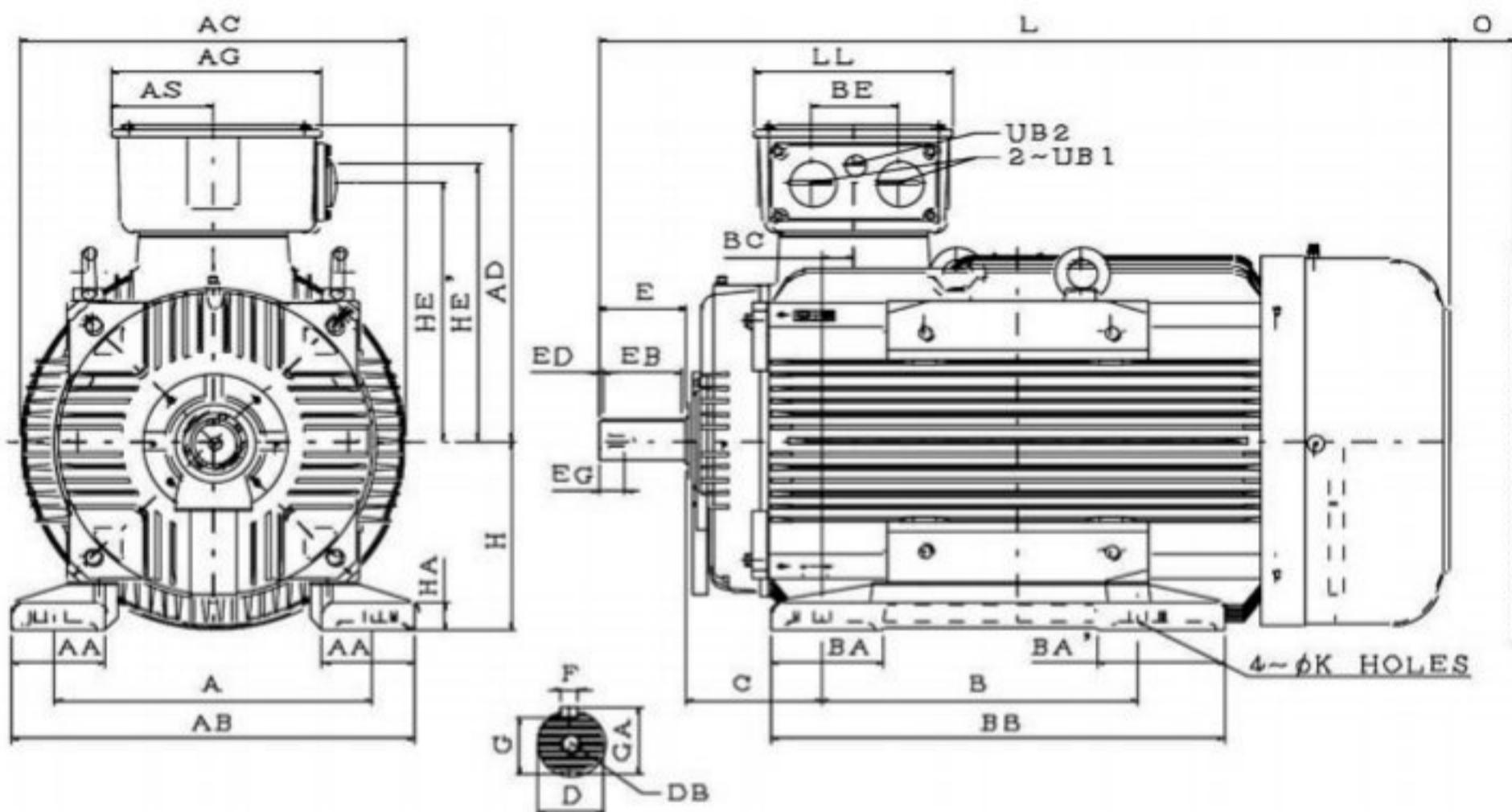


Figure 7-10: Outline drawing of cast iron design, feet version, mounting B3; frame size 315L

Outline drawings

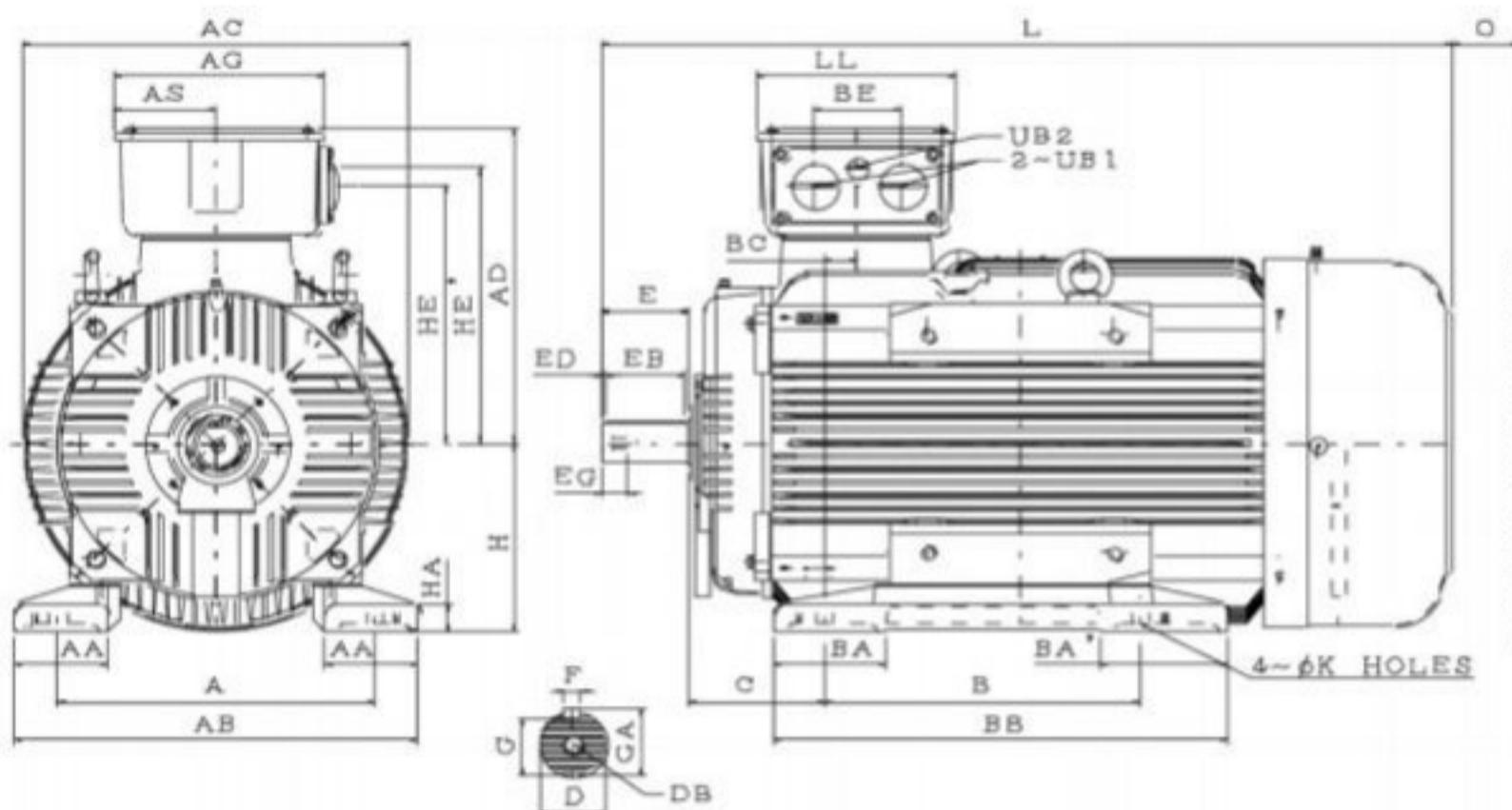


Figure 7-11: Outline drawing of cast iron design, feet version, mounting B3; frame size 315D

Frame size		Outline drawing of cast iron design, feet version, mounting B3; frame size 315S – 315M, 315L, 315D, dimensions in [mm]																		
		A	AA	AB	AC	AD	AG	AS	B	B'	BA	BA'	BB	BE	BC	C	H	HA	HE	HE'
315	S	508	115	615	620	527	336	163	406		150	150	508	140	53	216	315	35	430	460
	S*	508	115	615	620	527	336	163	406		150	150	508	140	53	216	315	35	430	460
	S**	508	115	615	620	527	336	163	406		150	150	508	140	53	216	315	35	430	460
315	M	508	115	615	620	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
	M*	508	115	615	620	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
	M**	508	115	615	620	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
315	L	508	150	650	620	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
	L*	508	150	650	620	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
	L**	508	150	650	620	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
315	D	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515
	D*	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515
	D**	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

Frame size		Overall dimensions						Shaft extension								Bearings			
		K	L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
315	S	28	1216	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-9
	S*	28	1246	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-9
	S**	28	1246	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-9
315	M	28	1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-9
	M*	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-9
	M**	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-9
315	L	28	1366	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-10
	L*	28	1396	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-10
	L**	28	1396	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-10
315	D	28	1674	372	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6316C3	7-11
	D*	28	1704	372	—			85m6	170	160	5	42	22	76	90	M20	6322C3	6322C3	7-11
	D**	28	1704	372	—			95m6	170	160	5	50	25	86	100	M24	NU322	6322C3	7-11

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

7.2.2 Cast iron design; flange version (B5)

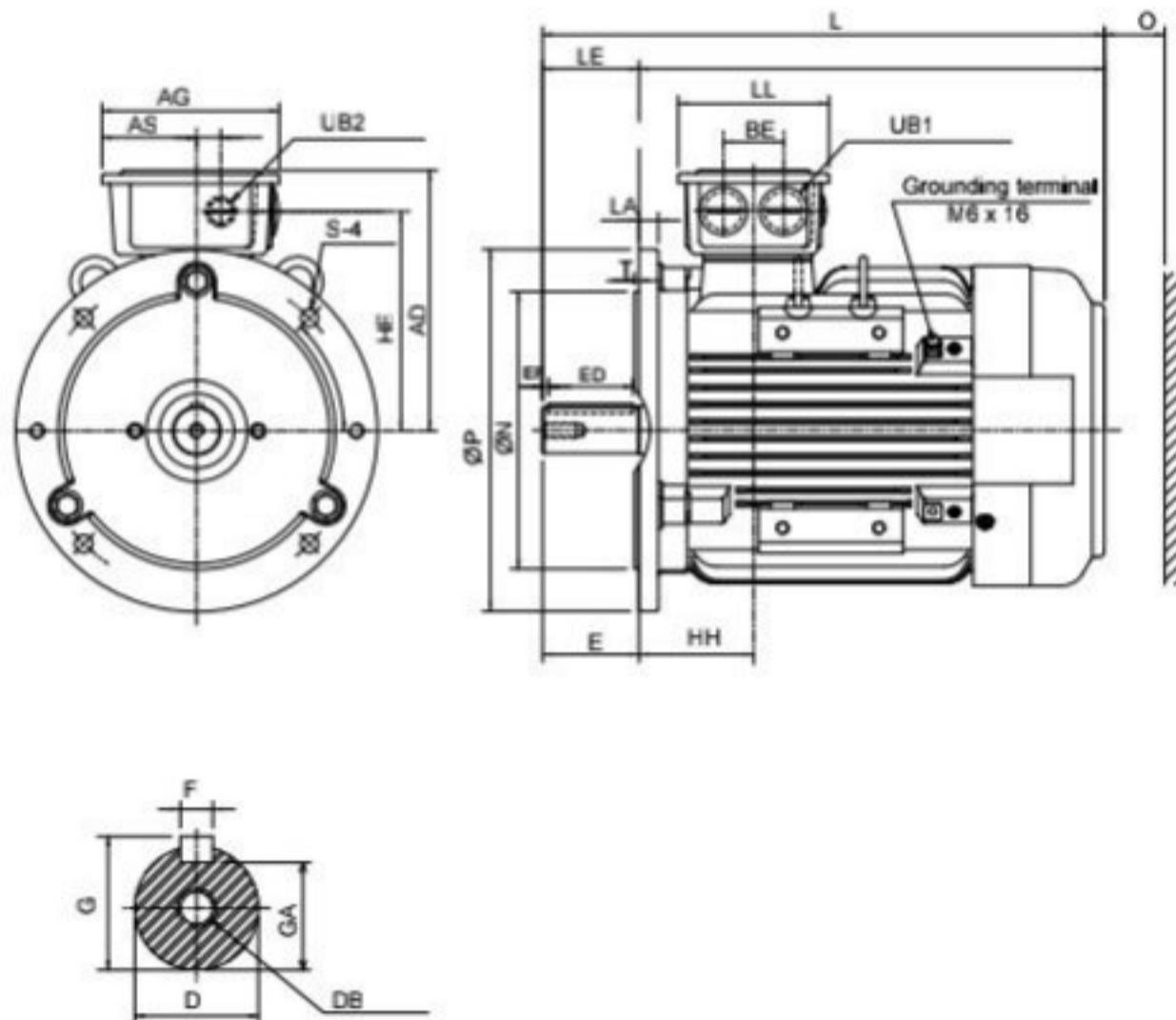


Figure 7-12: Outline drawing of cast iron design, flange version, mounting B5, frame size 160

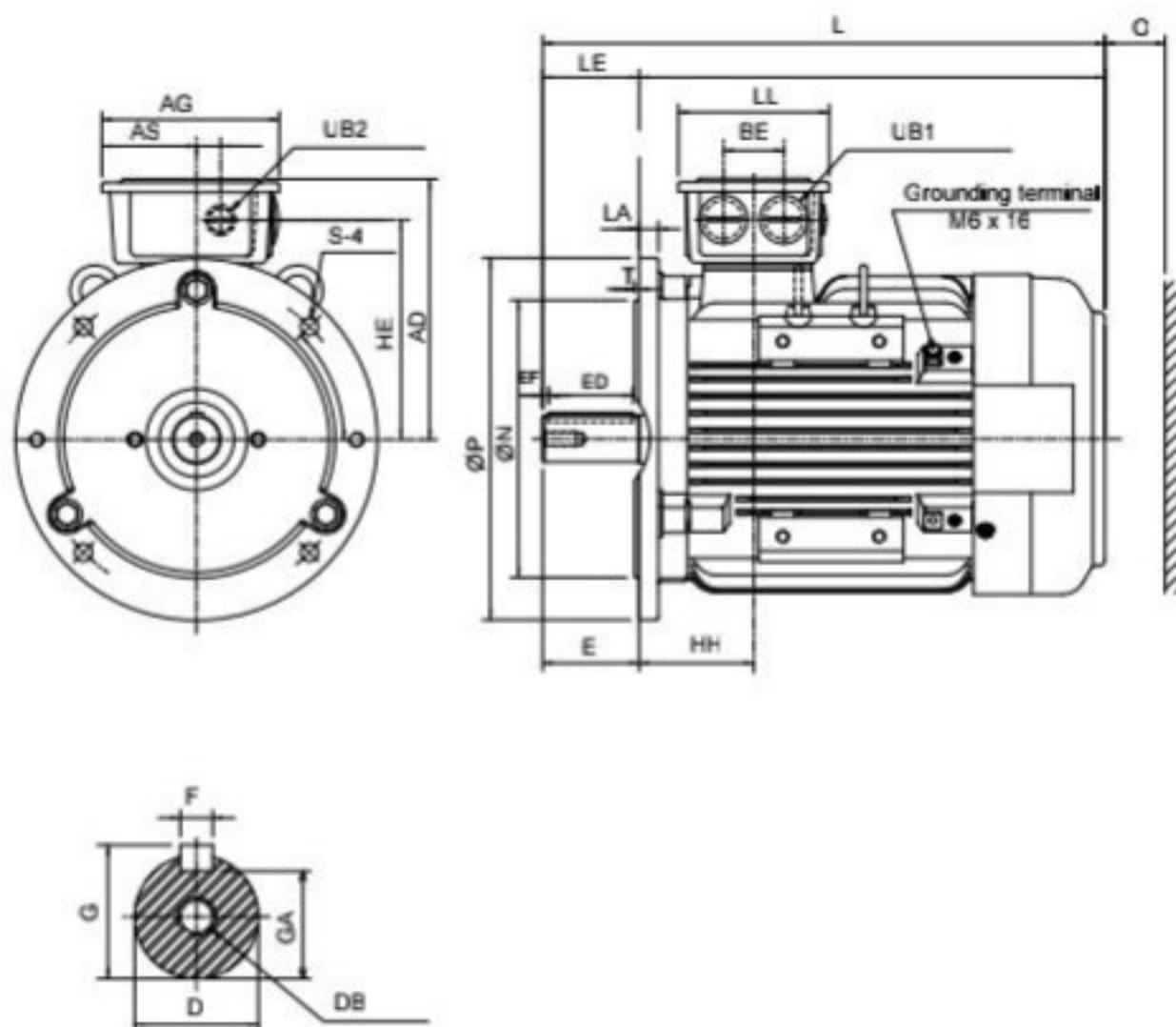


Figure 7-13: Outline drawing of cast iron design, flange version, mounting B5, frame size 160 – 180

Outline drawings

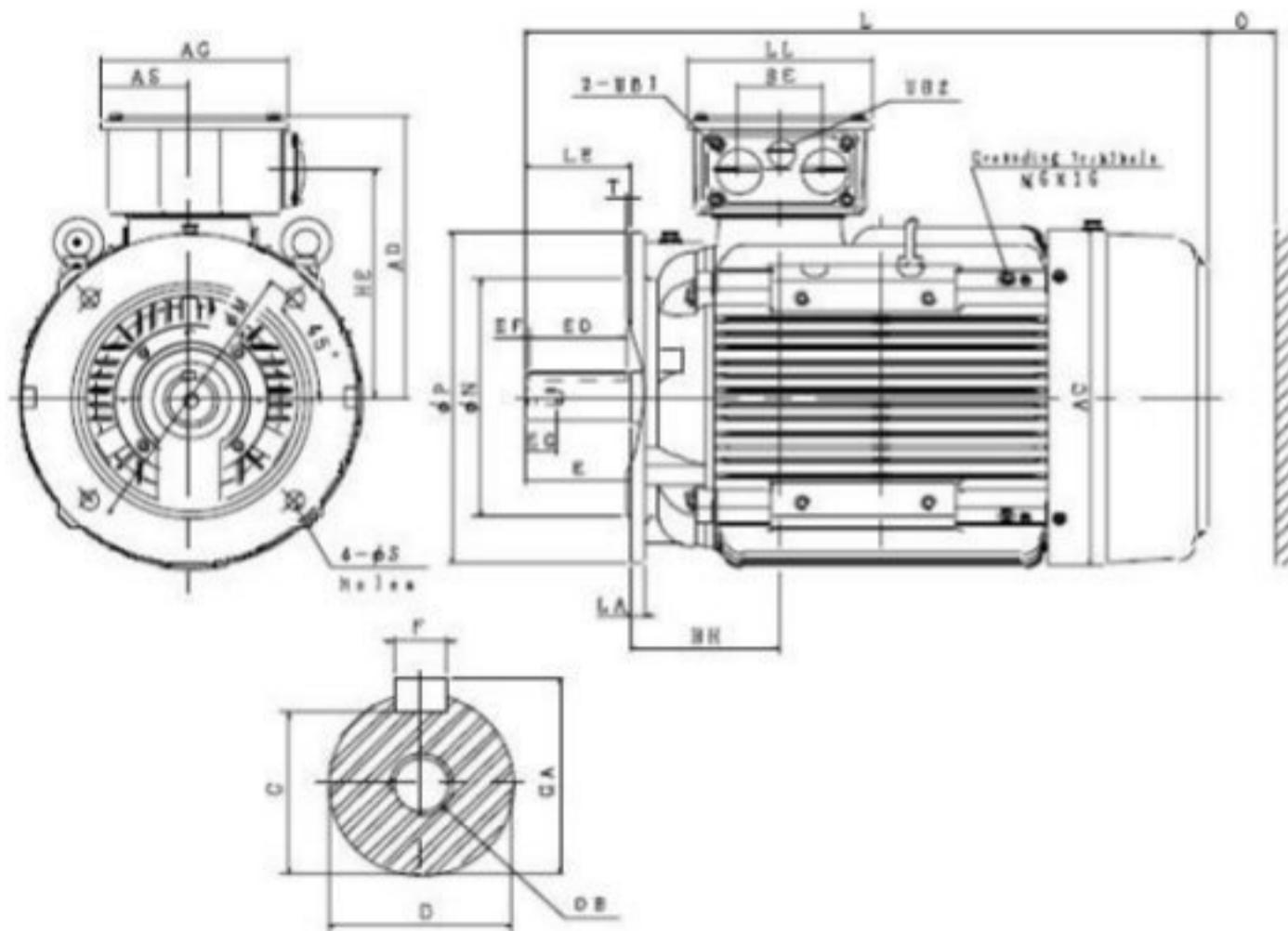


Figure 7-14: Outline drawing of cast iron design, flange version, mounting B5, frame size 200

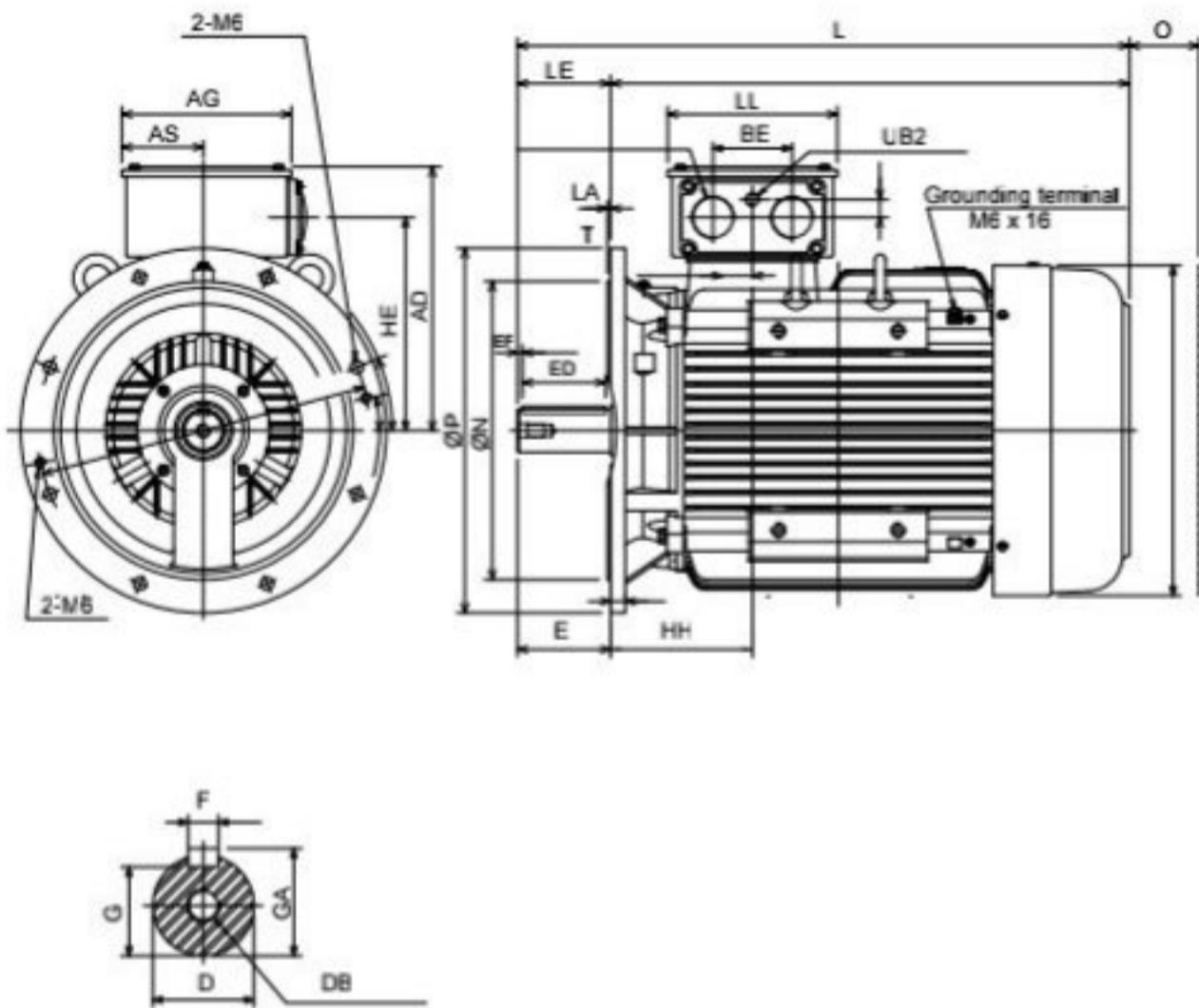


Figure 7-15: Outline drawing of cast iron design, flange version, mounting B5, frame size 225 – 250

Frame size		Outline drawing of cast iron design, flange version, mounting B5, frame size 80 – 250, dimensions in [mm]																	
		AC AD AG AS				BE HH HE HE'				Flange dimensions				M N P S T					
80	S																		
	M	156	161	125	67.5	40	68.5	123.5		12	40	165	130	200	12	3.5			
	L																		
90	S	176	171	125	67.5	40	92	133.5		12	50	165	130	200	12	3.5			
	M																		
	L	176	171	125	67.5	40	92	133.5		12	50	165	130	200	12	3.5			
100	S																		
	M																		
	L	196	191	147	78.5	50	84	157		16	60	215	180	250	14.5	4			
112	S																		
	M	218	198.5	147	78.5	50	98	164.5		15	60	215	180	250	14.5	4			
	L																		
132	S	258	216	147	78.5	50	95	182		16	80	265	230	300	14.5	4			
	M	258	216	147	78.5	50	95	182		16	80	265	230	300	14.5	4			
	L																		
160	S																		
	M	317	271	193	91.5	89	146	215		15	110	300	250j6	350	18.5	5			
	L	317	271	193	91.5	89	146	215		15	110	300	250j6	350	18.5	5			
180	S																		
	M	354	297	193	91.5	89	155	241		15	110	300	250j6	350	18.5	5			
	L	354	297	193	91.5	89	155	241		15	110	300	250j6	350	18.5	5			
200	S																		
	M																		
	L	398	330	231	110.5	106	193	262		17	110	350	300j6	400	18.5	5			
225	S	449	356	231	110.5	106	179.5	288		20	140	400	350j6	450	18.5	5			
	M	449	356	231	110.5	106	179.5	288		20	110	400	350j6	450	18.5	5			
	M*	449	356	231	110.5	106	179.5	288		20	140	400	350j6	450	18.5	5			
250	S																		
	M	498	398	255	122.5	119	213.5	322		22	140	500	450j6	550	18.5	5			
	M*	498	398	255	122.5	119	213.5	322		22	140	500	450j6	550	18.5	5			

*) = 4-, 6- and 8-pole version

Frame size		Overall dimensions					Shaft extension								Bearings				
		L	LL	O	UB1	UB2	D	E	EF	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.	
80	S						M25 x 1.5	M20 x 1.5											
	M	293	115	40					19	40	4	16	6	15.5	21.5	M6	6204ZZC3	6204ZZC3	
	L																		
90	S	344.5	115	40			M32 x 1.5	M20 x 1.5	24	50	5	19	8	20	27	M8	6207ZZC3	6205ZZC3	
	M																		
	L	369.5	115	40					24	50	5	19	8	20	27	M8	6205ZZC3	6205ZZC3	
100	S						M40 x 1.5	M20 x 1.5											
	M								28	60	5	22	8	24	31	M10	6206ZZC3	6206ZZC3	
	L	392	125	50															
112	S						M50 x 1.5	M20 x 1.5	28	60	5	22	8	24	31	M10	6306ZZC3	6306ZZC3	
	M	412.5	125	50															
	L																		
132	S	466	125	50			M50 x 1.5	M20 x 1.5	38	80	5	28	10	33	41	M12	6308ZZC3	6306ZZC3	
	M	504	125	50															
	L								38	80	5	28	10	33	41	M12	6308ZZC3	6306ZZC3	
160	S						M63 x 1.5	M20 x 1.5											
	M	608	193	60					42k6	110	5	100	32	12	37	45	M16	6309ZZC3	6307ZZC3
	L	652	193	60					42k6	110	5	100	32	12	37	45	M16	6309ZZC3	6307ZZC3

Outline drawings

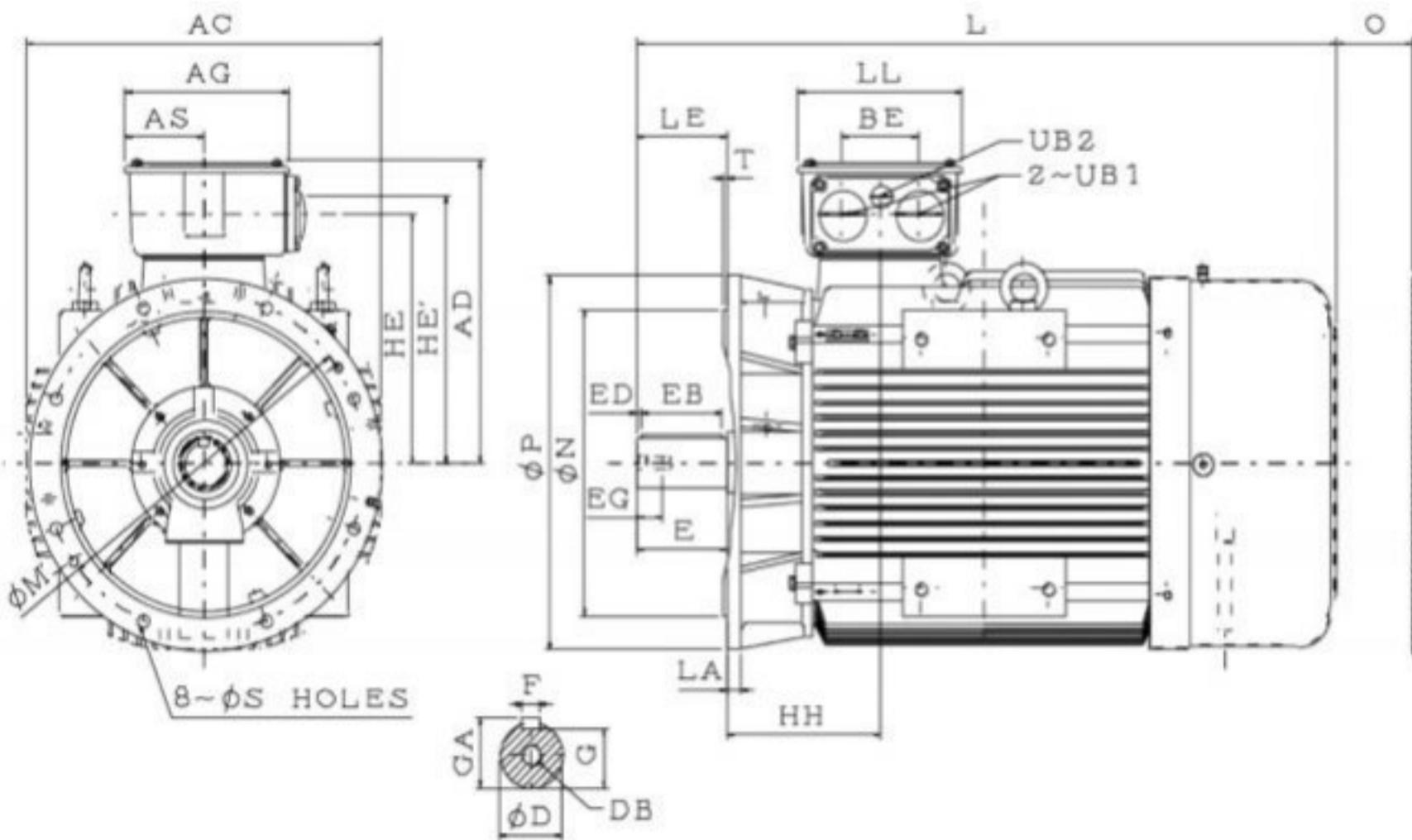


Figure 7-16: Outline drawing of cast iron design, flange version, mounting B5, frame size 280

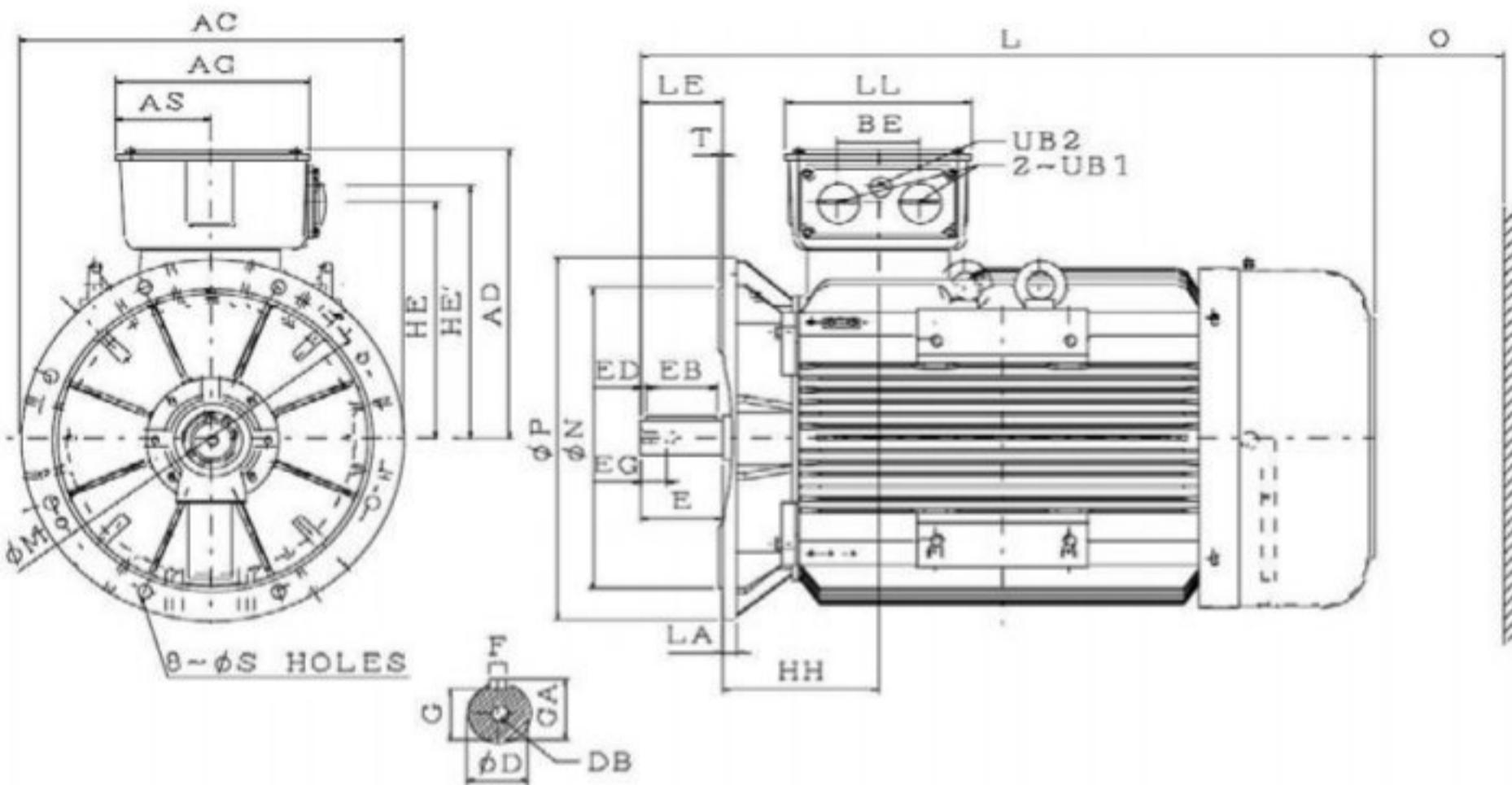


Figure 7-17: Outline drawing of cast iron design, flange version, mounting B5, frame size 315

Frame size		Outline dimensions of cast iron design, flange version horizontal, mounting B5, frame size 280 – 315, dimensions in [mm]																	
		Flange dimensions																	
280	S	AC	AD	AG	AS		BE	HH	HE	HE'		LA	LE	M	N	P	S	T	
	S*	550	446	255	122.5		119	238	367	394		22	140	500	450	550	18.5	5	
	S**	550	446	255	122.5		119	238	367	394		22	140	500	450	550	18.5	5	
280	M	550	446	255	122.5		119	238	367	394		22	140	500	450	550	18.5	5	
	M*	550	446	255	122.5		119	238	367	394		22	140	500	450	550	18.5	5	
	M**	550	446	255	122.5		119	238	367	394		22	140	500	450	550	18.5	5	
315	S	660	527	336	163		140	269	430	460		25	140	600	550	660	24	6	
	S*	660	527	336	163		140	269	430	460		25	170	600	550	660	24	6	
	S**	660	527	336	163		140	269	430	460		25	170	600	550	660	24	6	
315	M	660	527	336	163		140	269	430	460		25	140	600	550	660	24	6	
	M*	660	527	336	163		140	269	430	460		25	170	600	550	660	24	6	
	M**	660	527	336	163		140	269	430	460		25	170	600	550	660	24	6	

*) = 4-, 6- and 8-pole version
 **) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

Frame size		Overall dimensions						Shaft extension								Bearings			
			L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
280	S		1037	255	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-16
	S*		1037	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-16
	S**		1037	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-16
280	M		1087.5	255	—			65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-16
	M*		1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-16
	M**		1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-16
315	S		1216	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-17
	S*		1246	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-17
	S**		1246	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-17
315	M		1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-17
	M*		1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-17
	M**		1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-17

*) = 4-, 6- and 8-pole version
 **) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

7.2.3 Cast iron design; version with feet and flange (B35)

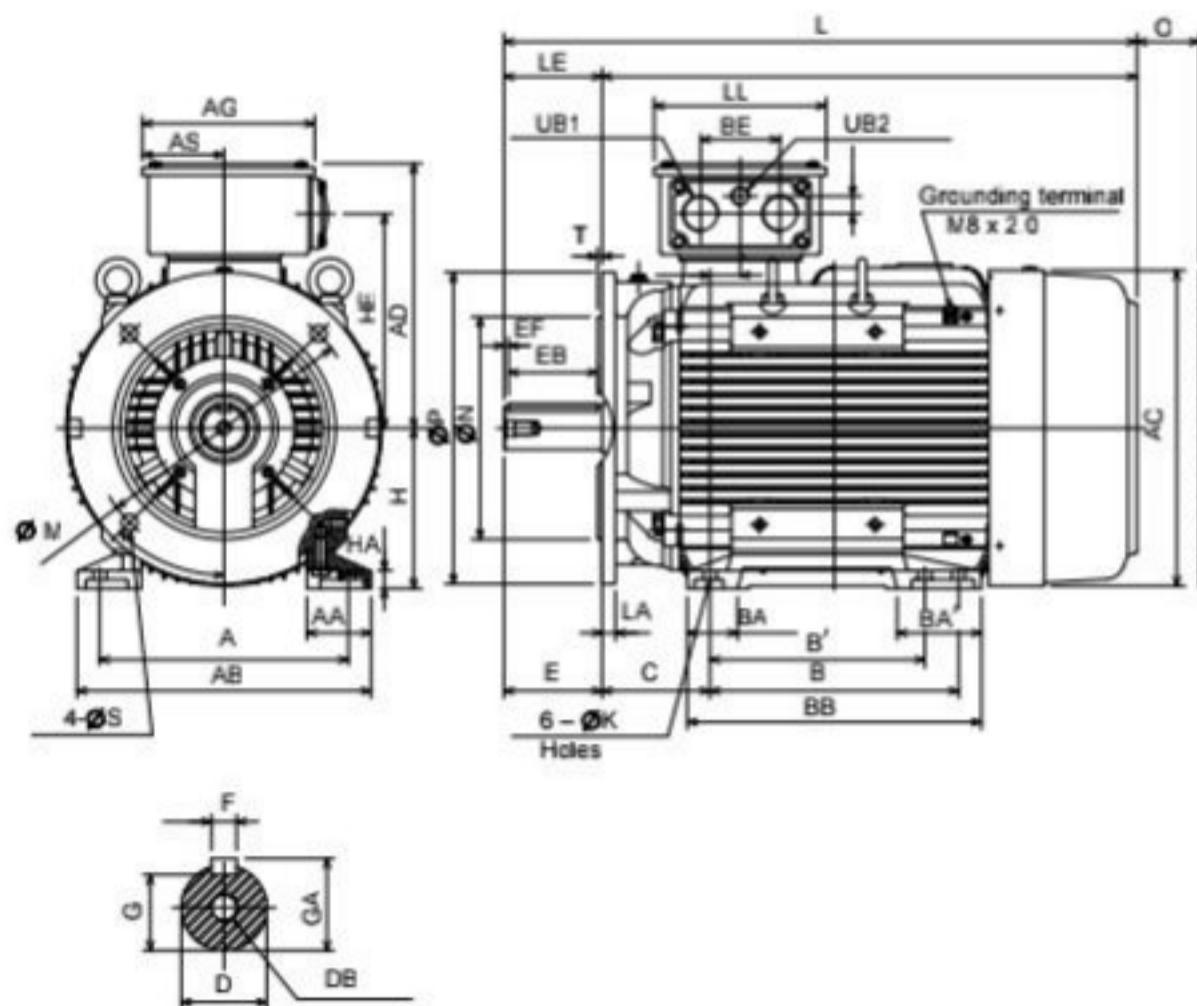


Figure 7-18: Outline drawing of cast iron design, mounting B35; frame size 160 – 180

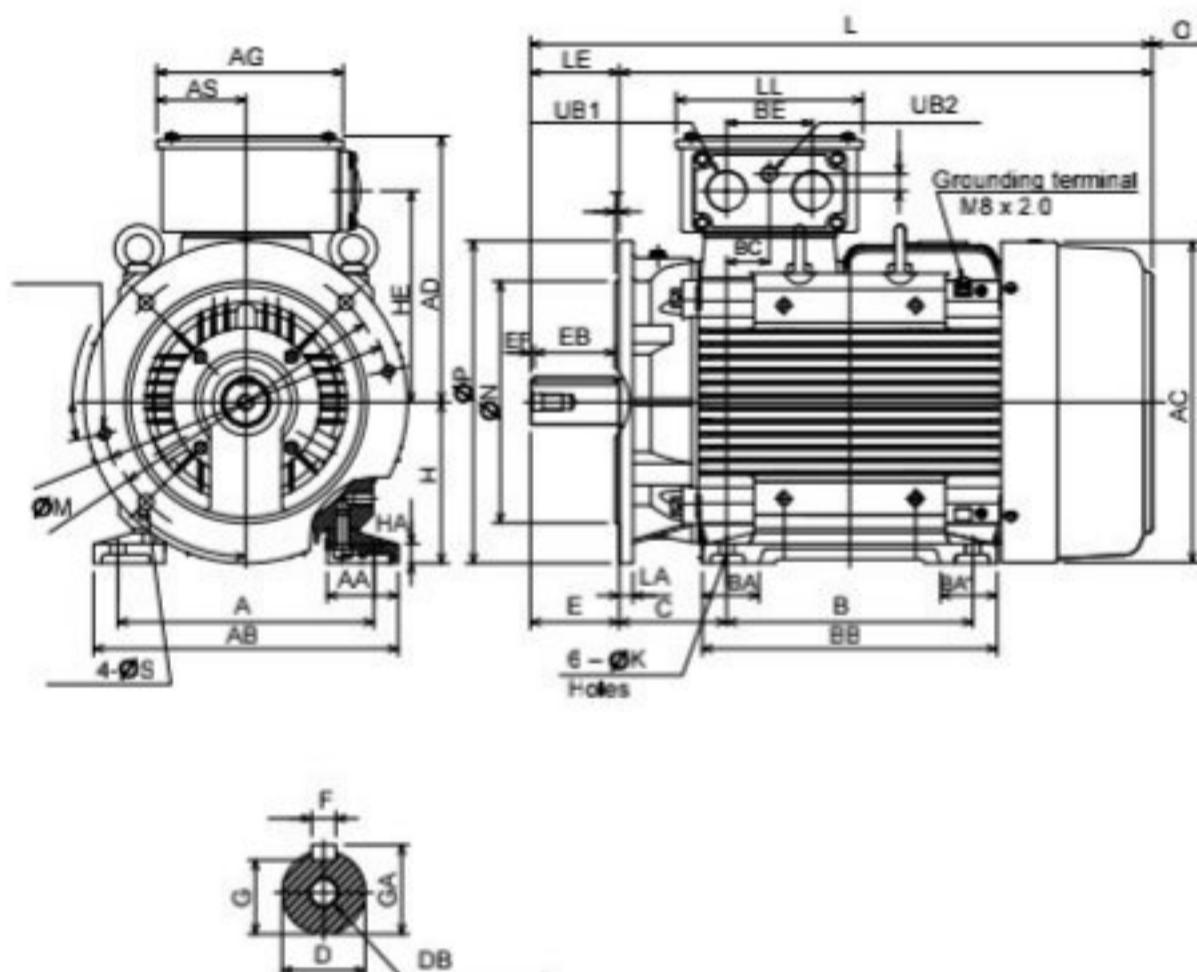


Figure 7-19: Outline drawing of cast iron design, mounting B35; frame size 200 – 250

		Outline dimensions of cast iron design, flange/feet version, mounting B35, frame size 80 – 250, dimensions in [mm]																		
Frame size		A	AA	AB	AC	AD	AG	AS	B	B'	BA	BA'	BB	BE	BC	C	H	HA	HE	HE'
80	S																			
	M	125	35	156	156	161	125	67,5	100		33,5	33,5	130	40	18,5	50	80	10	123,5	
	L																			
90	S	140	40	180	176	171	125	67,5	100		33	33	125	40	36	56	90	10	133,5	
	M																			
	L	140	40	180	176	171	125	67,5	125	100	33	33	125	40	36	56	90	10	133,5	
100	S																			
	M																			
	L	160	40	200	196	191	147	78,5	140		43,5	43,5	176	50	21	63	100	12	157	
112	S																			
	M	190	50	235	218	198,5	147	78,5	140		45,5	45,5	176	50	28	70	112	13	164,5	
	L																			
132	S	216	63,5	259	258	216	147	78,5	140		59	59	184	50	6	89	132	16	182	
	M	216	63,5	259	258	216	147	78,5	178	140	59	97	222	50	6	89	132	16	182	
	L																			
160	M	254	71	300	317	271	193	91,5	210	—	46	46	256	77	38	108	160	18	215	—
	L	254	71	300	317	271	193	91,5	254	210	46	90	300	77	38	108	160	18	215	—
180	S																			
	M	279	72	330	354	297	193	91,5	241	—	57	57	292	77	34	121	180	20	241	—
	L	279	72	330	354	297	193	91,5	279	241	57	95	330	77	34	121	180	20	241	—
200	M																			
	L	318	88	378	398	330	231	110,5	305	—	70	70	365	106	53	133	200	24	262	—
225	S	356	94	416	449	356	231	110,5	286	—	70	70	350	106	30,5	149	225	28	288	—
	M	356	94	416	449	356	231	110,5	311	286	70	95	375	106	30,5	149	225	28	288	—
	L																			
250	S																			
	M	406	112	480	498	398	255	122,5	349	—	84	84	425	119	45,5	168	250	30	322	—
	L																			

*) = 4-, 6- and 8-pole version

Frame size	Shaft extension													Bearings				
	K	L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
80	S				M20 x 1,5	M20 x 1,5												
	M	10	293	115			19	40	32	4	16	6	15,5	21,5	M6	6204ZZC3	6204ZZC3	
	L																	
90	S	10	344,5	115	40	M32 x 1,5	24	50	40	5	19	8	20	27	M8	6205ZZC3	6205ZZC3	7-18
	M																	
	L	10	369,5	115	40		24	50	40	5	19	8	20	27	M8	6205ZZC3	6205ZZC3	7-18
100	S				M32 x 1,5	M20 x 1,5												
	M																	
	L	12	392	125	50		28	60	50	5	22	8	24	31	M10	6206ZZC3	6206ZZC3	7-18
112	S				M31 x 1,5	M20 x 1,5												
	M	12	412,5	125			38	80	70	5	28	10	33	41	M12	6308ZZC3	6308ZZC3	7-18
	L						38	80	70	5	28	10	33	41	M12	6308ZZC3	6308ZZC3	7-18
132	S	12	466	125	50	M40 x 1,5	42k6	110	100	5,0	32	12	37,0	45,0	M16	6309ZZC3	6307ZZC3	7-18
	M	12	504	125	50		42k6	110	100	5,0	32	12	37,0	45,0	M16	6309ZZC3	6307ZZC3	7-18
	L																	
160	S	14,5	608	193	60	M40 x 1,5	48k6	110	100	5,0	32	14	42,5	51,5	M16	6311C3	6310C3	7-18
	M	14,5	652	193	60		48k6	110	100	5,0	32	14	42,5	51,5	M16	6311C3	6310C3	7-18
	L																	
180	S	14,5	672</															

Outline drawings

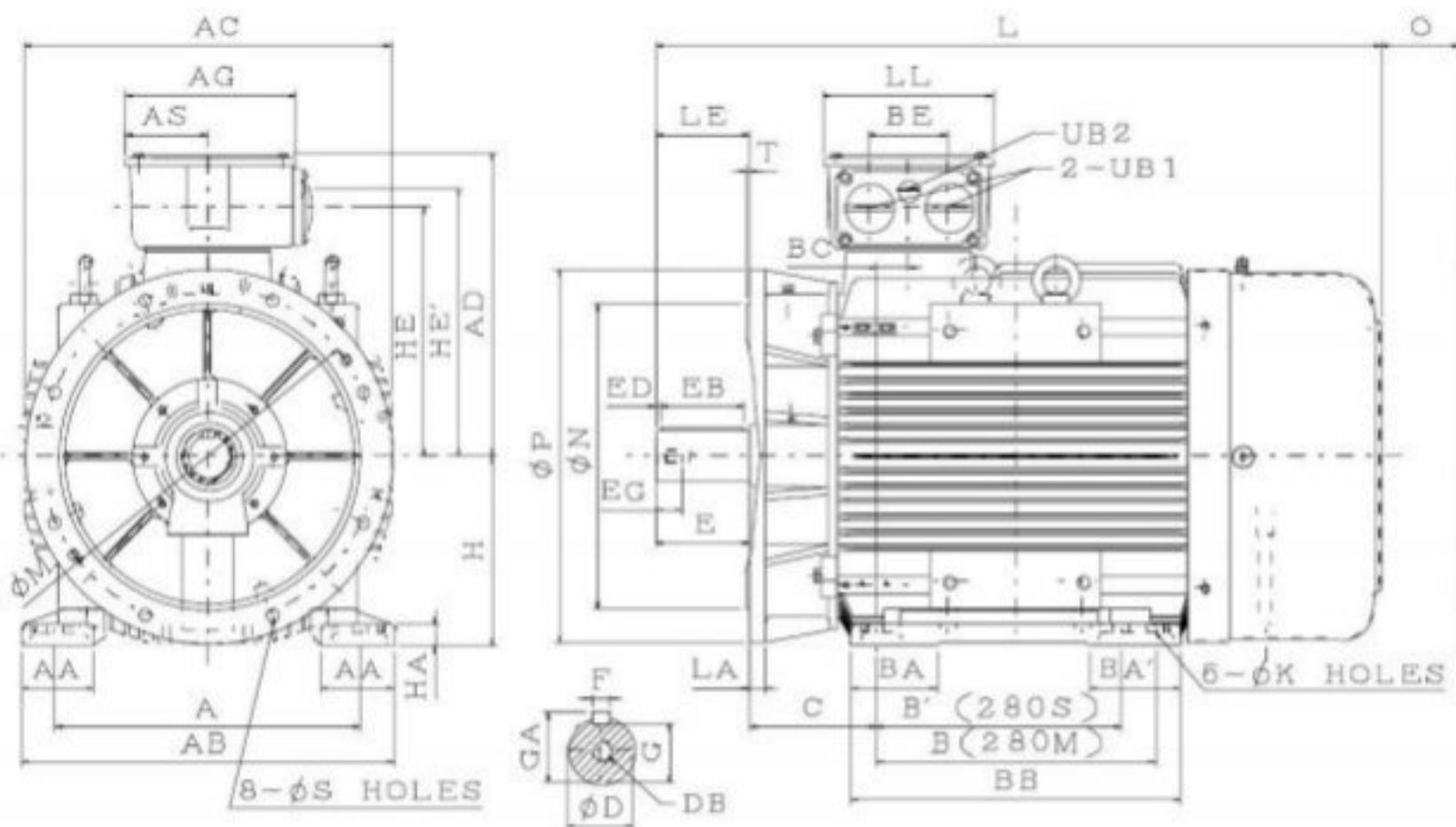


Figure 7-20: Outline drawing of cast iron design, mounting B35; frame size 280

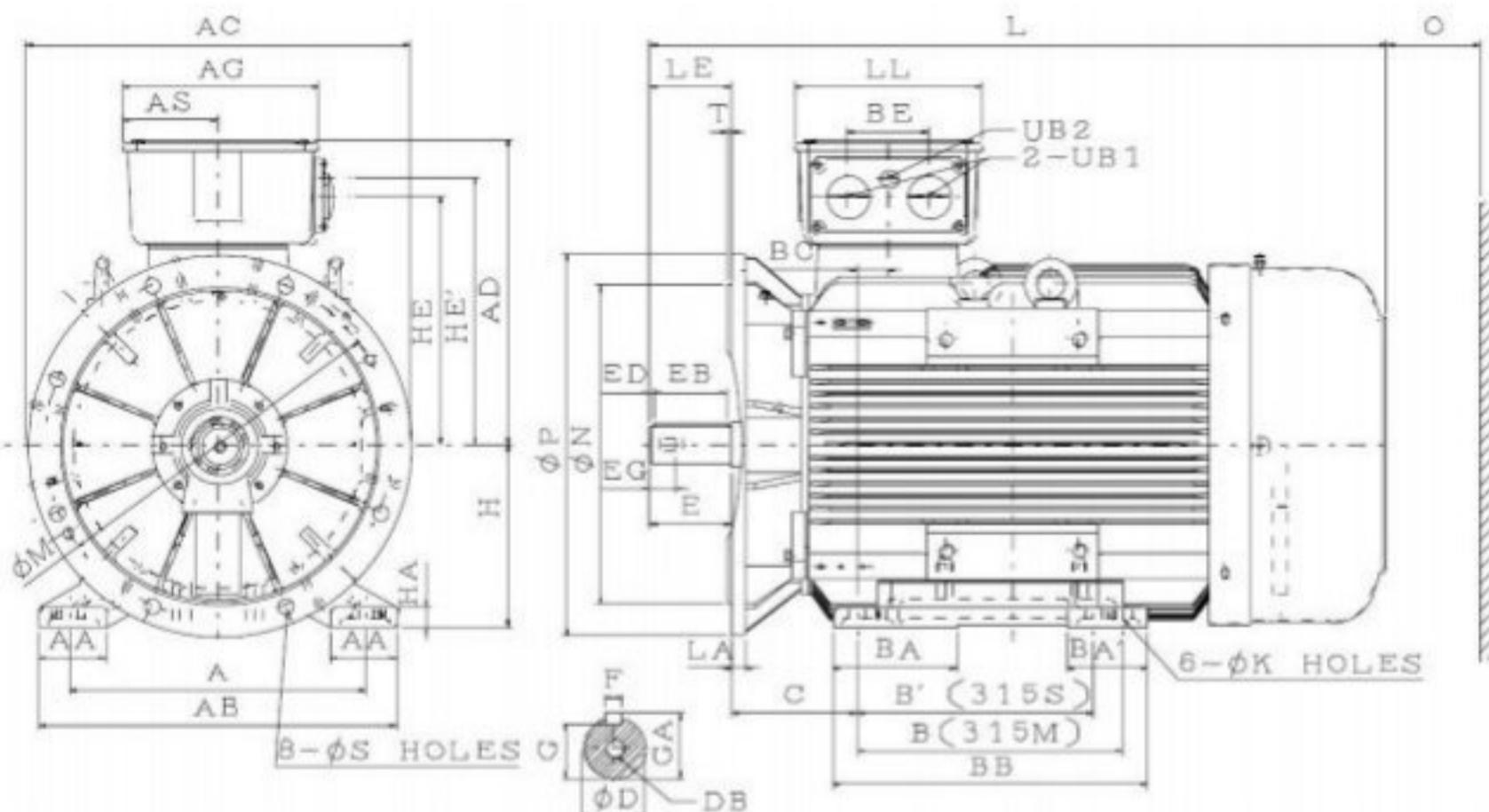


Figure 7-21: Outline drawing of cast iron design, mounting B35; frame size 315S – 315M

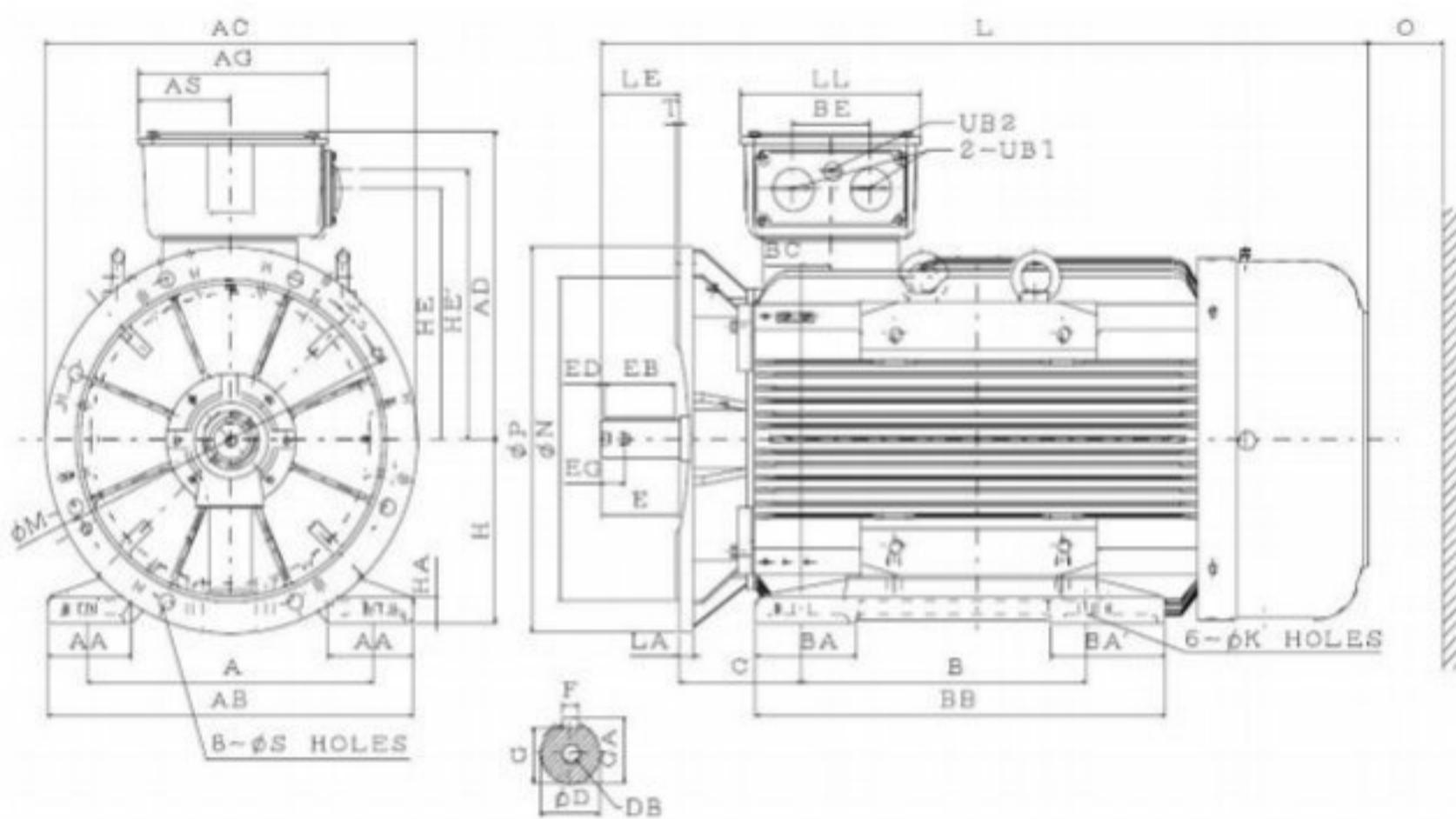


Figure 7-22: Outline drawing of cast iron design, mounting B35; frame size 315L

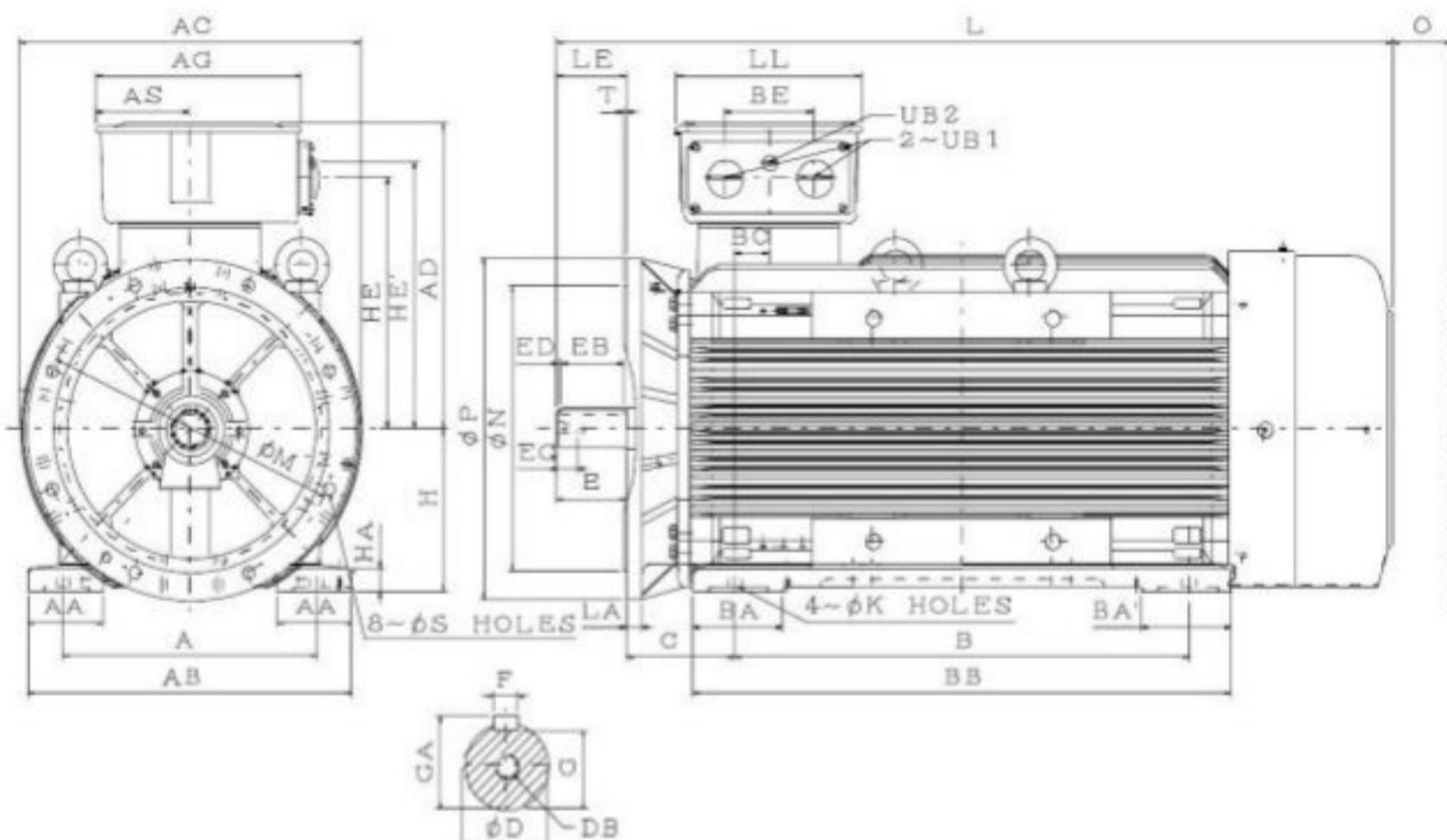


Figure 7-23: Outline drawing of cast iron design, mounting B35; frame size 315D

Outline drawings

Outline dimensions of cast iron design, flange/feet version, mounting B35, frame size 280 – 315, dimensions in [mm]																				
Frame size	A	AA	AB	AC	AD	AG	AS	B	B'	BA	BA'	BB	BE	BC	C	H	HA	HE	HE'	
280	S	457	110	560	550	446	255	122.5	—	368	130	137	495	119	48	190	280	32	367	394
	S*	457	110	560	550	446	255	122.5	—	368	130	137	495	119	48	190	280	32	367	394
	S**	457	110	560	550	446	255	122.5	—	368	130	137	495	119	48	190	280	32	367	394
280	M	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394
	M*	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394
	M**	457	110	560	550	446	255	122.5	419	—	130	137	495	119	48	190	280	32	367	394
315	S	508	115	615	660	527	336	163	—	406	213	137	540	140	53	216	315	35	430	460
	S*	508	115	615	660	527	336	163	—	406	213	137	540	140	53	216	315	35	430	460
	S**	508	115	615	660	527	336	163	—	406	213	137	540	140	53	216	315	35	430	460
315	M	508	115	615	660	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
	M*	508	115	615	660	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
	M**	508	115	615	660	527	336	163	457	—	213	137	540	140	53	216	315	35	430	460
315	L	508	150	650	660	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
	L*	508	150	650	660	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
	L**	508	150	650	660	527	336	163	508	—	180	205	730	140	53	216	315	45	430	460
315	D	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515
	D*	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515
	D**	508	150	650	682	590	412	189	900	—	255	255	1080	180	68	216	315	45	485	515

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

Frame size	Overall dimensions						Shaft extension								Bearings				
	K	L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.	
280	S	24.0	1087.5	255	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-20
	S*	24.0	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-20
	S**	24.0	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-20
280	M	24.0	1087.5	255	—			65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-20
	M*	24.0	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-20
	M**	24.0	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-20
315	S	28	1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-21
	S*	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-21
	S**	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-21
315	M	28	1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-21
	M*	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-21
	M**	28	1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-21
315	L	28	1366	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6314C3	7-22
	L*	28	1396	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-22
	L**	28	1396	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-22
315	D	28	1674	372	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	6316C3	6316C3	7-23
	D*	28	1704	372	—			85m6	170	160	5	42	22	76	90	M20	6322C3	6322C3	7-23
	D**	28	1704	372	—			95m6	170	160	5	50	25	86	100	M24	NU322	6322C3	7-23

*) = 4-, 6- and 8-pole version
**) =

Frame size		Flange dimensions						
		LA	LE	M	N	P	S	T
280	S	22	140	500	450	550	18.5	5
	S*	22	140	500	450	550	18.5	5
	S**	22	140	500	450	550	18.5	5
280	M	22	140	500	450	550	18.5	5
	M*	22	140	500	450	550	18.5	5
	M**	22	140	500	450	550	18.5	5
315	S	25	140	600	550	660	24	6
	S*	25	170	600	550	660	24	6
	S**	25	170	600	550	660	24	6
315	M	25	140	600	550	660	24	6
	M*	25	170	600	550	660	24	6
	M**	25	170	600	550	660	24	6
315	L	25	140	600	550	660	24	6
	L*	25	170	600	550	660	24	6
	L**	25	170	600	550	660	24	6
315	D	30	140	600	550	660	24	6
	D*	30	170	600	550	660	24	6
	D**	30	170	600	550	660	24	6

*) = 4-, 6- and 8-pole version
 **) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

7.2.4 Cast iron design; V1

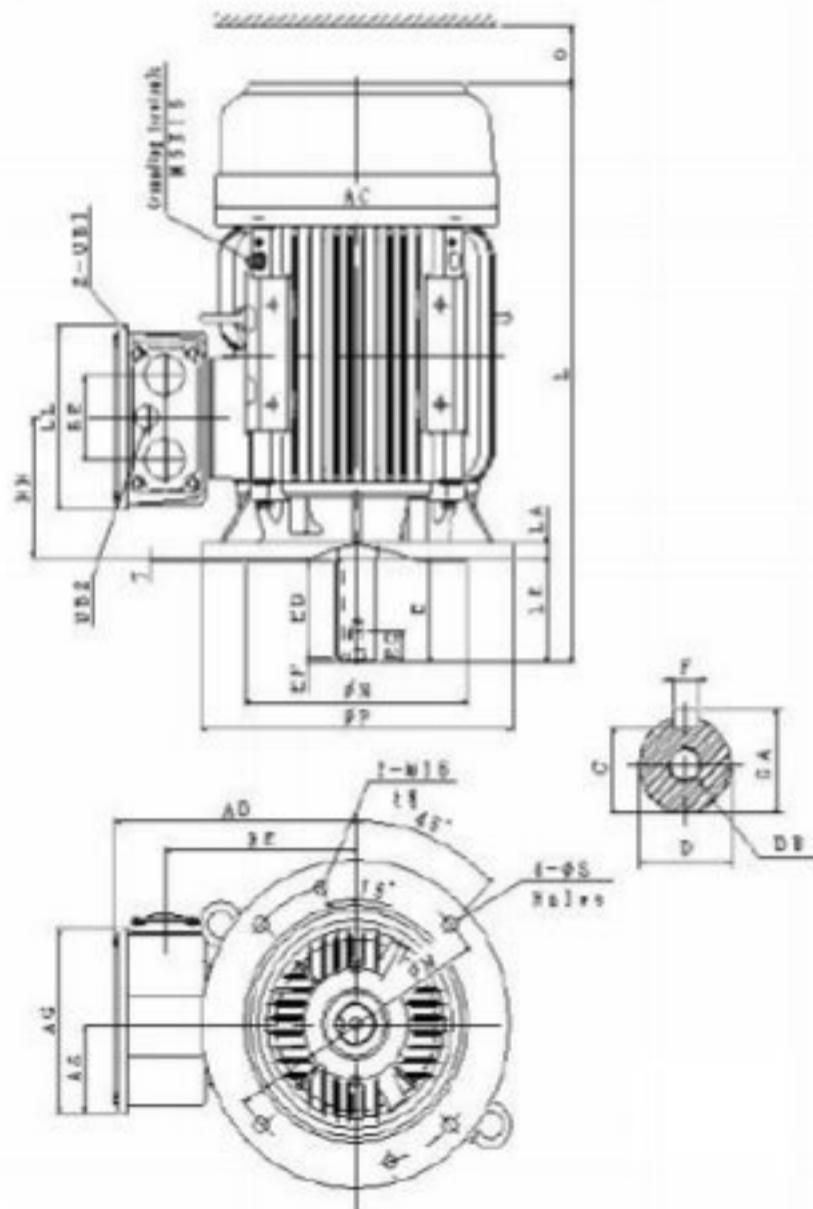


Figure 7-24: Outline drawing of cast iron design, mounting V1; frame size 160

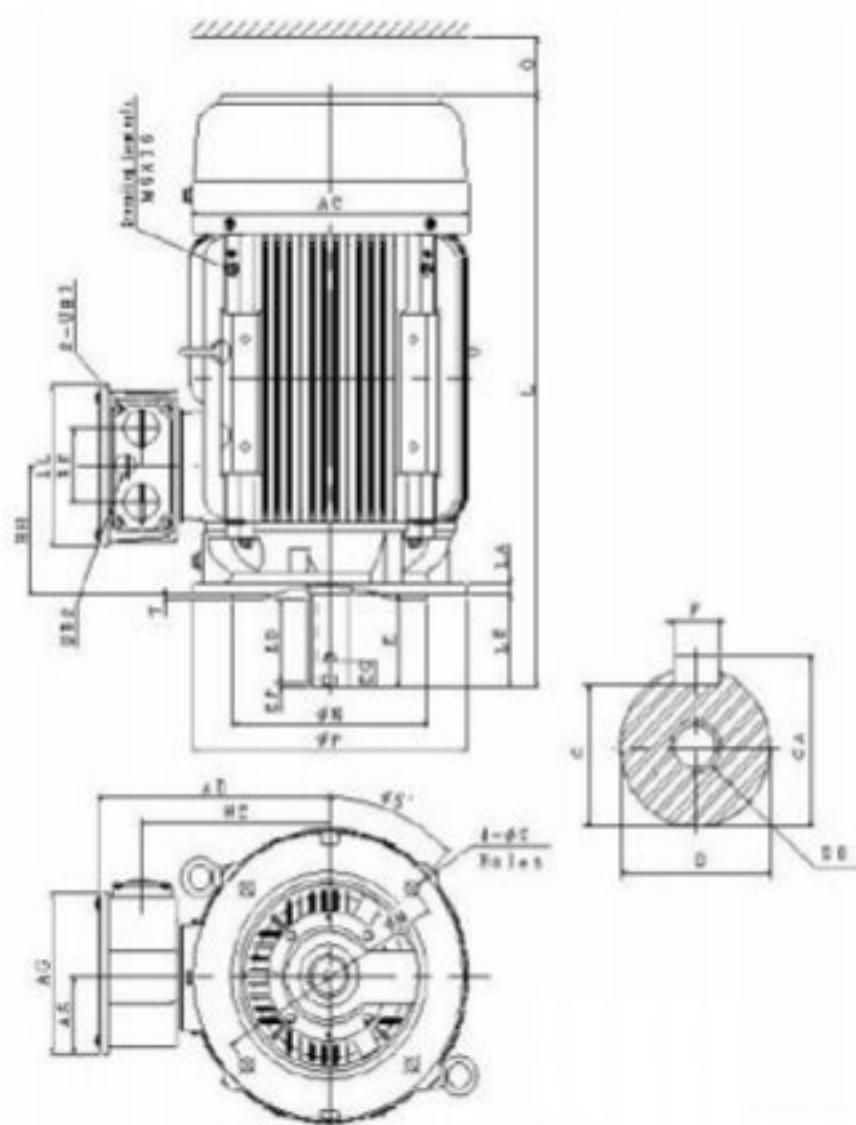


Figure 7-25: Outline drawing of cast iron design, mounting V1; frame size 180

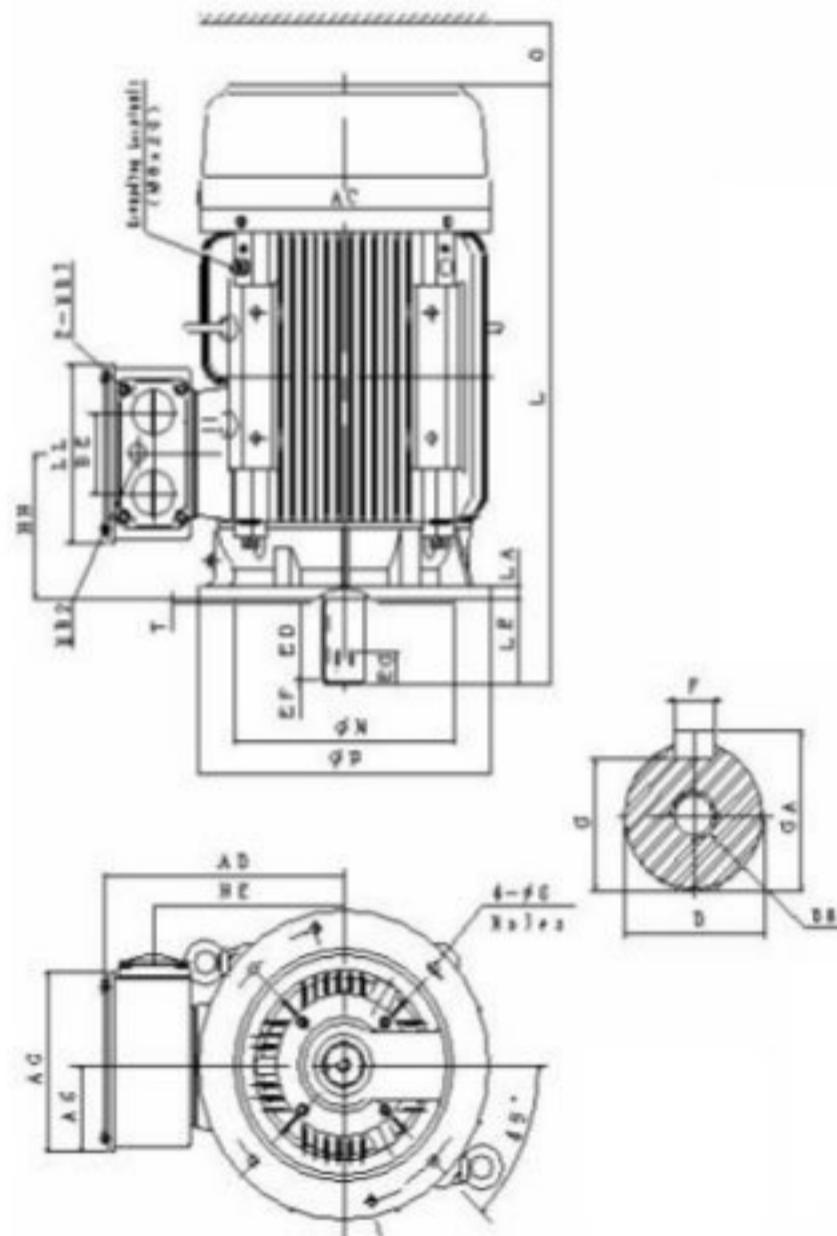


Figure 7-26: Outline drawing of cast iron design, mounting V1; frame size 200

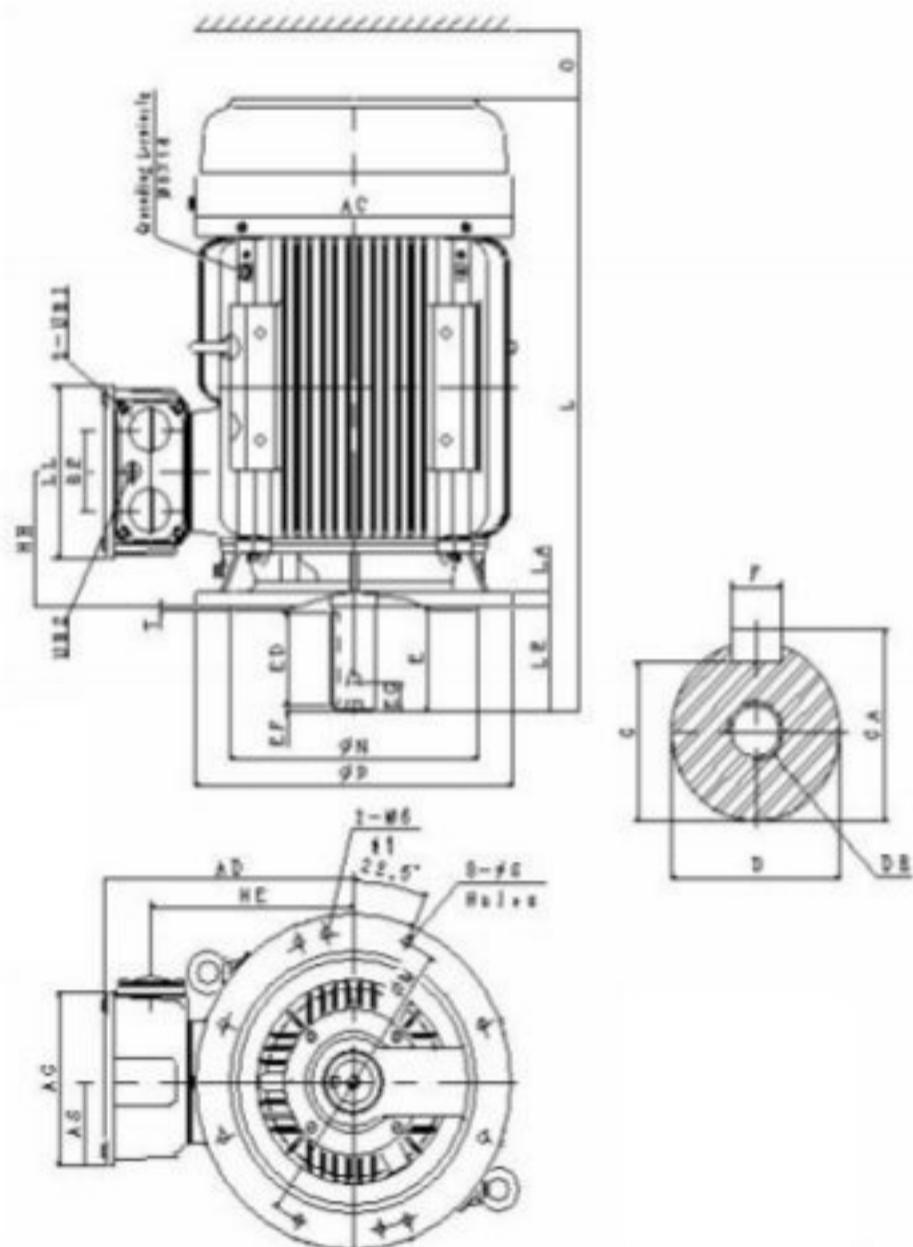


Figure 7-27: Outline drawing of cast iron design, mounting V1; frame size 225 – 250

Frame size		Outline dimensions of cast iron design, flange version, vertical mounting V1, frame size 160 – 250, dimensions in [mm]																
		AC AD AG AS BE HH HE HE'								Flange dimensions LA LE M N P S T								
160	S																	
	M	317	271	193	91,5		89	146	215		15	110	300	250j6	350	18,5	5	
	L	317	271	193	91,5		89	146	215		15	110	300	250j6	350	18,5	5	
180	S																	
	M	354	297	193	91,5		89	155	241		15	110	300	250j6	350	18,5	5	
	L	354	297	193	91,5		89	155	241		15	110	300	250j6	350	18,5	5	
200	S																	
	M																	
	L	398	330	231	110,5		106	193	262		17	110	350	300j6	400	18,5	5	
225	S	449	356	231	110,5		106	186,5	288		20	140	400	350j6	450	18,5	5	
	M	449	356	231	110,5		106	186,5	288		20	110	400	350j6	450	18,5	5	
	M*	449	356	231	110,5		106	186,5	288		20	140	400	350j6	450	18,5	5	
250	S																	
	M	498	398	255	122,5		119	225,5	322		22	140	500	450j6	550	18,5	5	
	M*	498	398	255	122,5		119	225,5	322		22	140	500	450j6	550	18,5	5	

*) = 4-, 6- and 8-pole version

Frame size		Overall dimensions						Shaft extension								Bearings		
		L	LL	O	UB1	UB2	D	E	EF	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
160	S				M40 x 1,5	M20 x 1,5												
	M	608	193	60			42k6	110	5	100	36	12	37	45	M16	6309ZZC3	6307ZZC3	7-24
	L	652	193	60			42k6	110	5	100	36	12	37	45	M16	6309ZZC3	6307ZZC3	7-24
180	S				M50 x 1,5	M20 x 1,5												
	M	672	193	70			48k6	110	5	100	36	14	42,5	51,5	M16	6311C3	6310C3	7-25
	L	710	193	70			48k6	110	5	100	36	14	42,5	51,5	M16	6311C3	6310C3	7-25
200	S				M63 x 1,5	M20 x 1,5												
	M																	
	L	770	231	80			55m6	110	5	100	42	16	49	59	M20	6312C3	6212C3	7-26
225	S	816	231	90	M63 x 1,5	M20 x 1,5	60m6	140	7,5	125	42	18	53	64	M20	6313C3	6213C3	7-27
	M	811	231	90			55m6	110	5	100	42	16	49	59	M20	6312C3	6212C3	7-27
	M*	841	231	90			60m6	140	7,5	125	42	18	53	64	M20	6313C3	6213C3	7-27
250	S																	
	M	921	255	105			60m6	140	7,5	125	42	18	53	64	M20	6313C3	6313C3	7-27
	M*	921	255	105			65m6	140	7,5	125	42	18	58	69	M20	6315C3	6313C3	7-27

*) = 4-, 6- and 8-pole version

Outline drawings

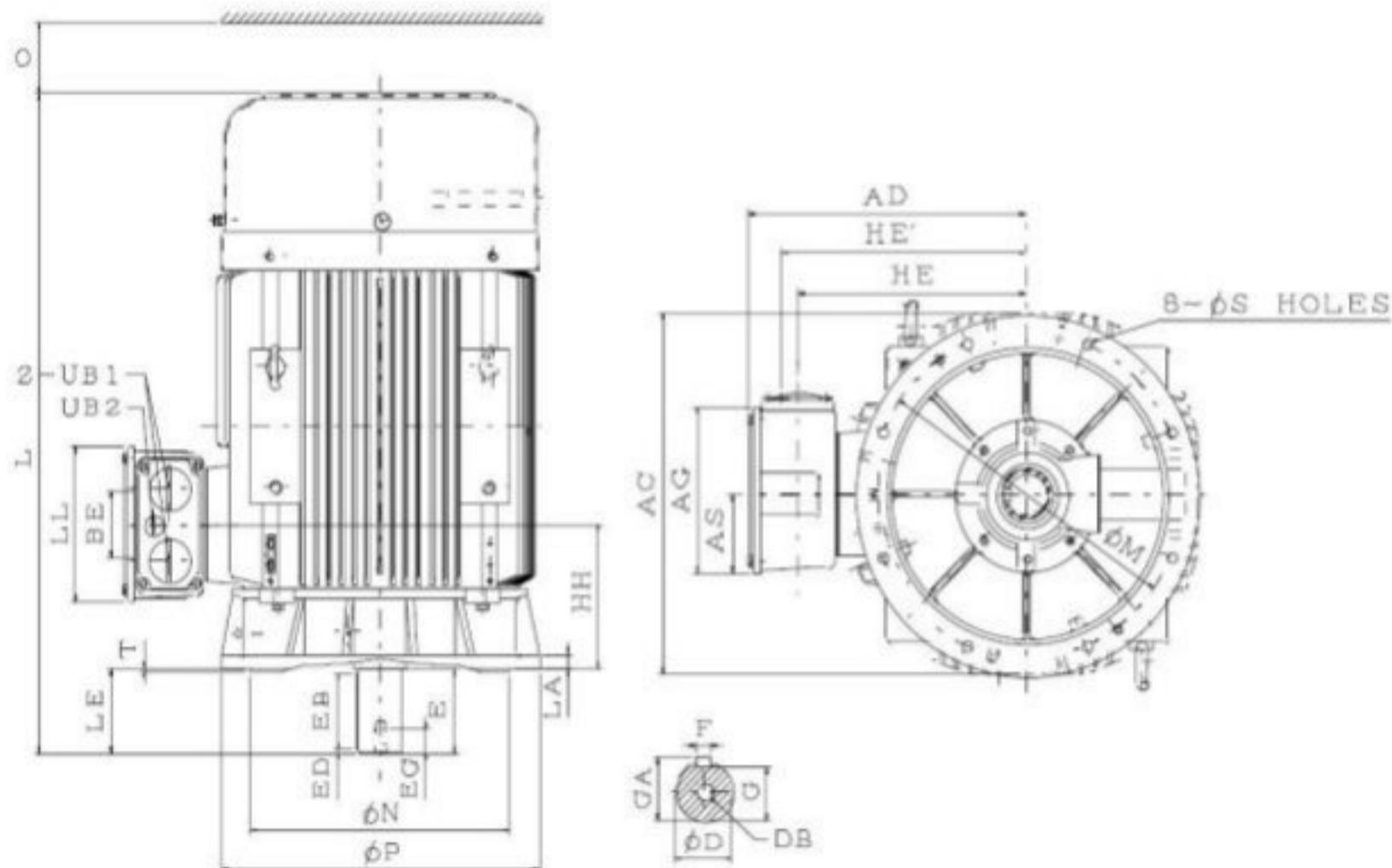


Figure 7-28: Outline drawing of cast iron design, mounting V1; frame size 280

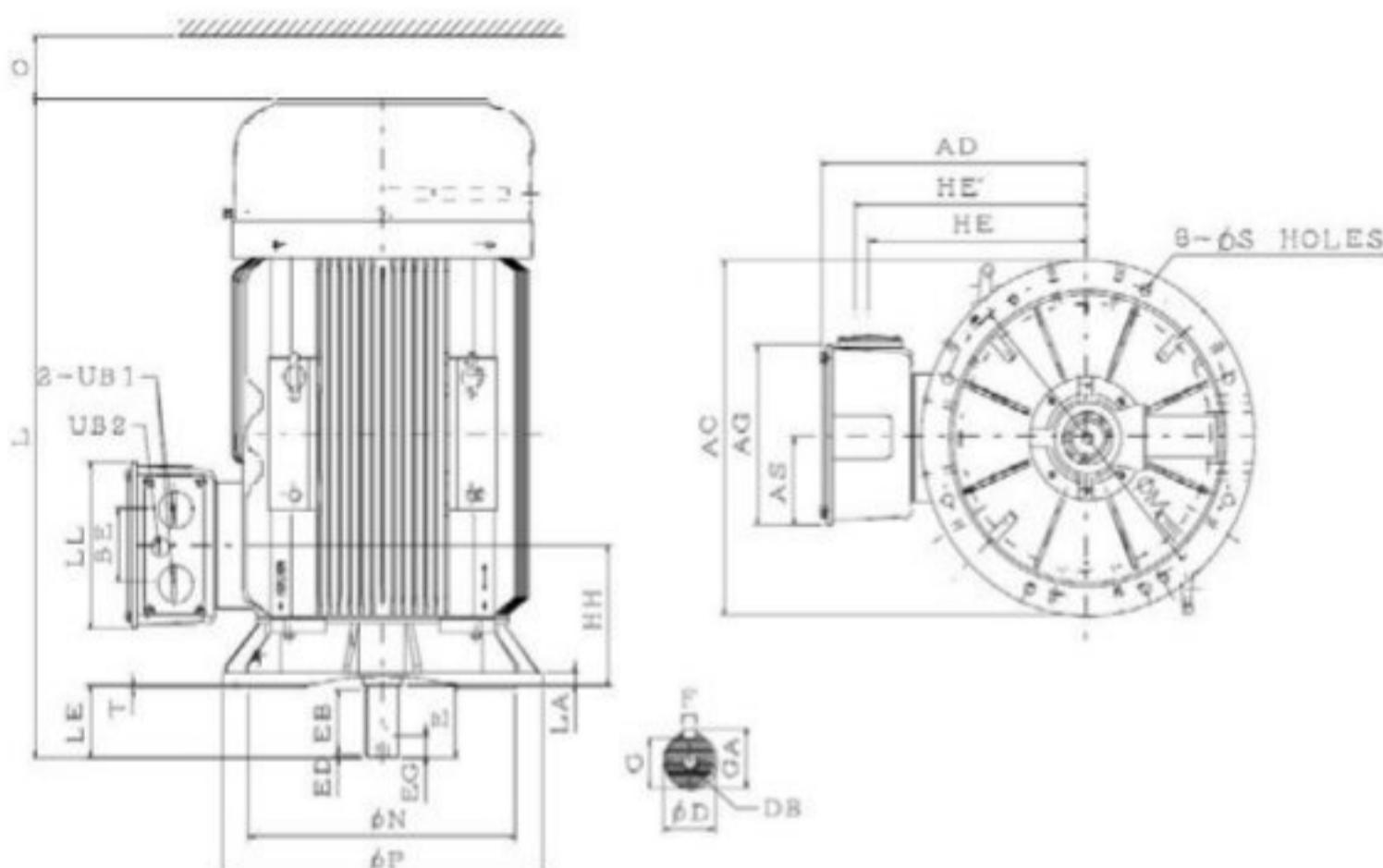


Figure 7-29: Outline drawing of cast iron design, mounting V1; frame size 315S – 315M

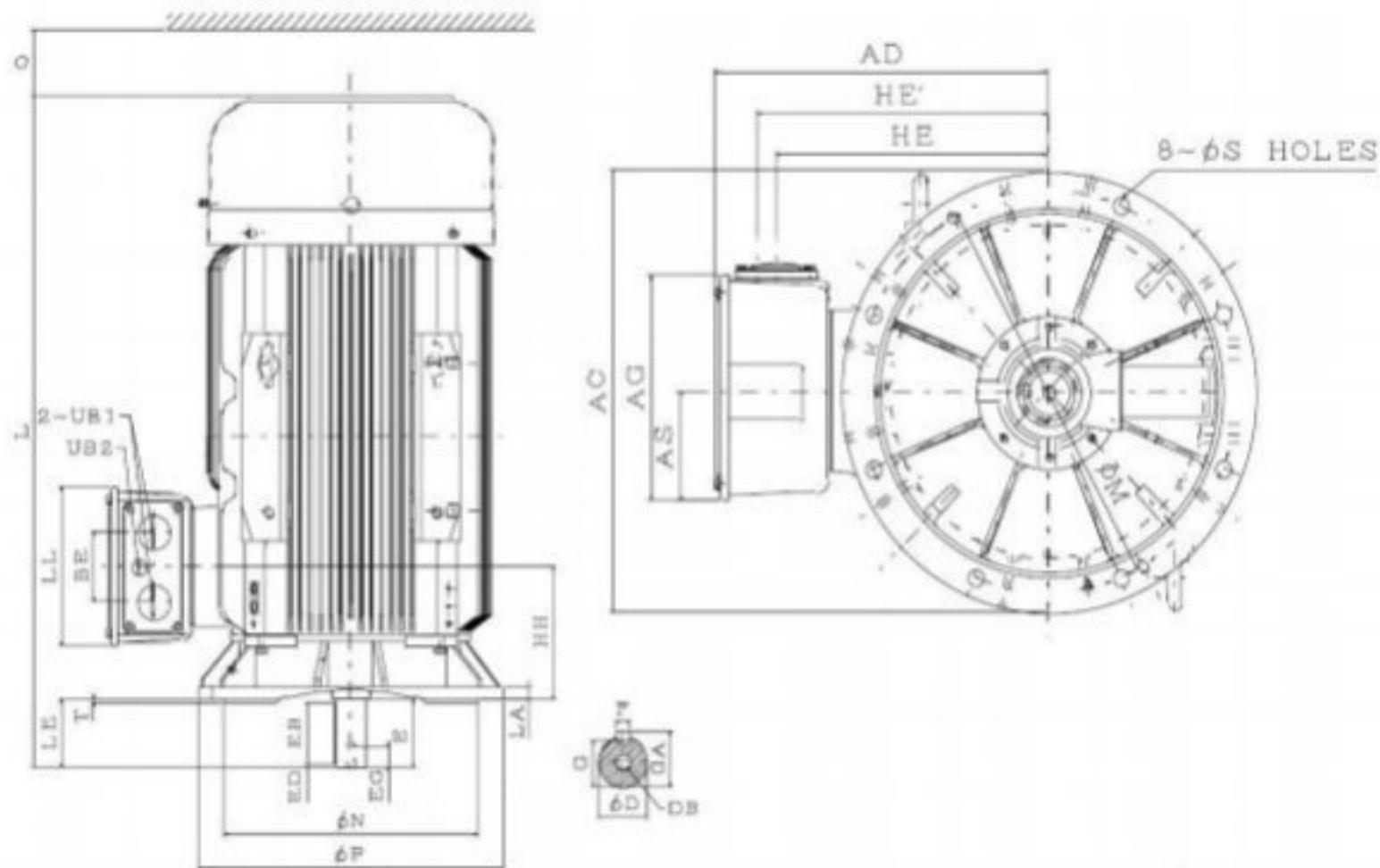


Figure 7-30: Outline drawing of cast iron design, mounting V1; frame size 315L

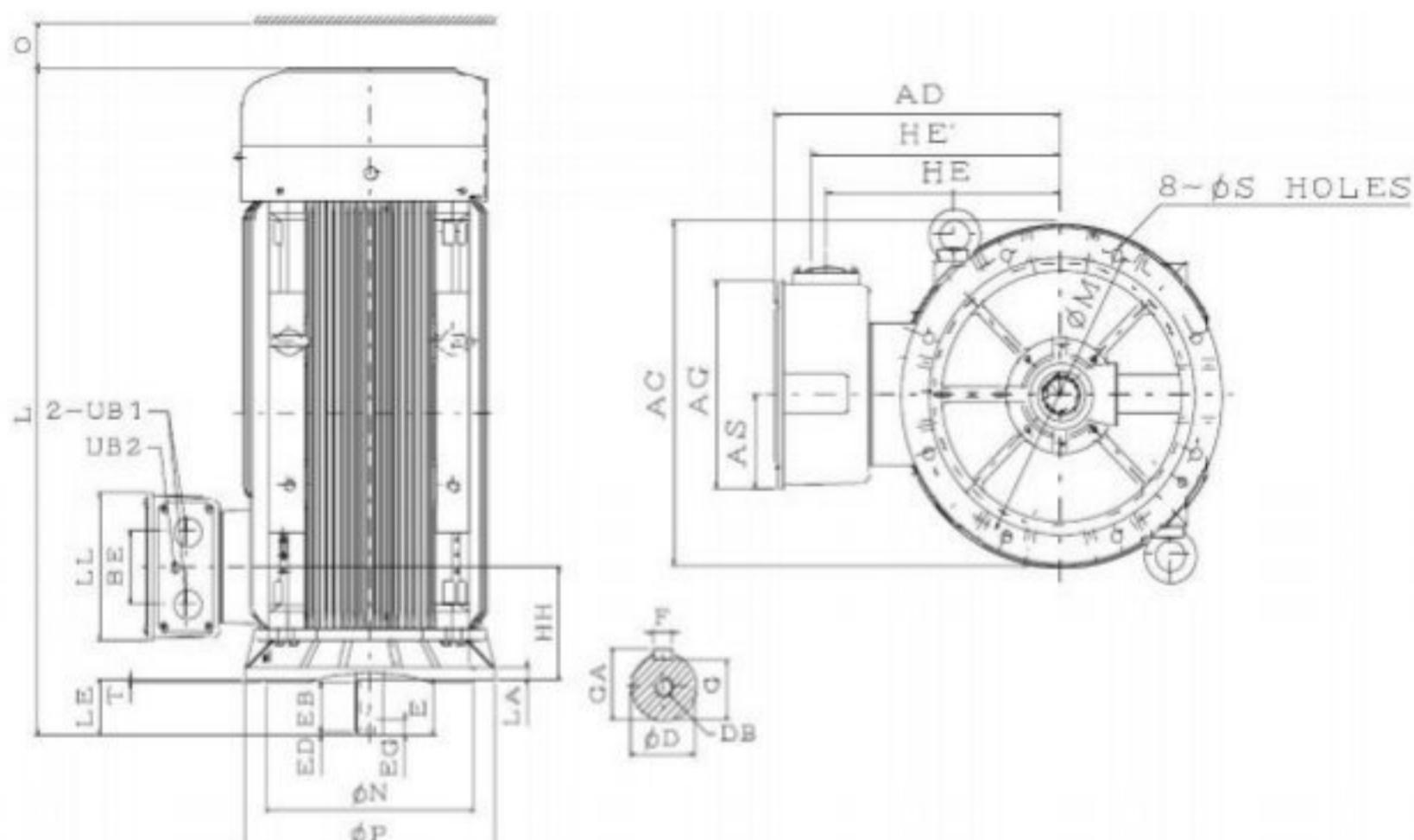


Figure 7-31: Outline drawing of cast iron design, mounting V1; frame size 315D

Outline drawings

Frame size		Outline dimensions of cast iron design, flange version vertical, mounting V1, frame size 280 – 315, dimensions in [mm]																	
										Flange dimensions									
		AC	AD	AG	AS	BE	HH	HE	HE'		LA	LE	M	N	P	S	T		
280	S	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
	S*	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
	S**	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
280	M	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
	M*	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
	M**	550	446	255	122.5	119	238	367	394		22	140	500	450	550	18.5	5		
315	S	660	527	336	163	140	269	430	460		25	140	600	550	660	24	6		
	S*	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
	S**	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
315	M	660	527	336	163	140	269	430	460		25	140	600	550	660	24	6		
	M*	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
	M**	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
315	L	660	527	336	163	140	269	430	460		25	140	600	550	660	24	6		
	L*	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
	L**	660	527	336	163	140	269	430	460		25	170	600	550	660	24	6		
315	D	682	590	412	189	180	284	485	515		30	140	600	550	660	24	6		
	D*	682	590	412	189	180	284	485	515		30	170	600	550	660	24	6		
	D**	682	590	412	189	180	284	485	515		30	170	600	550	660	24	6		

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

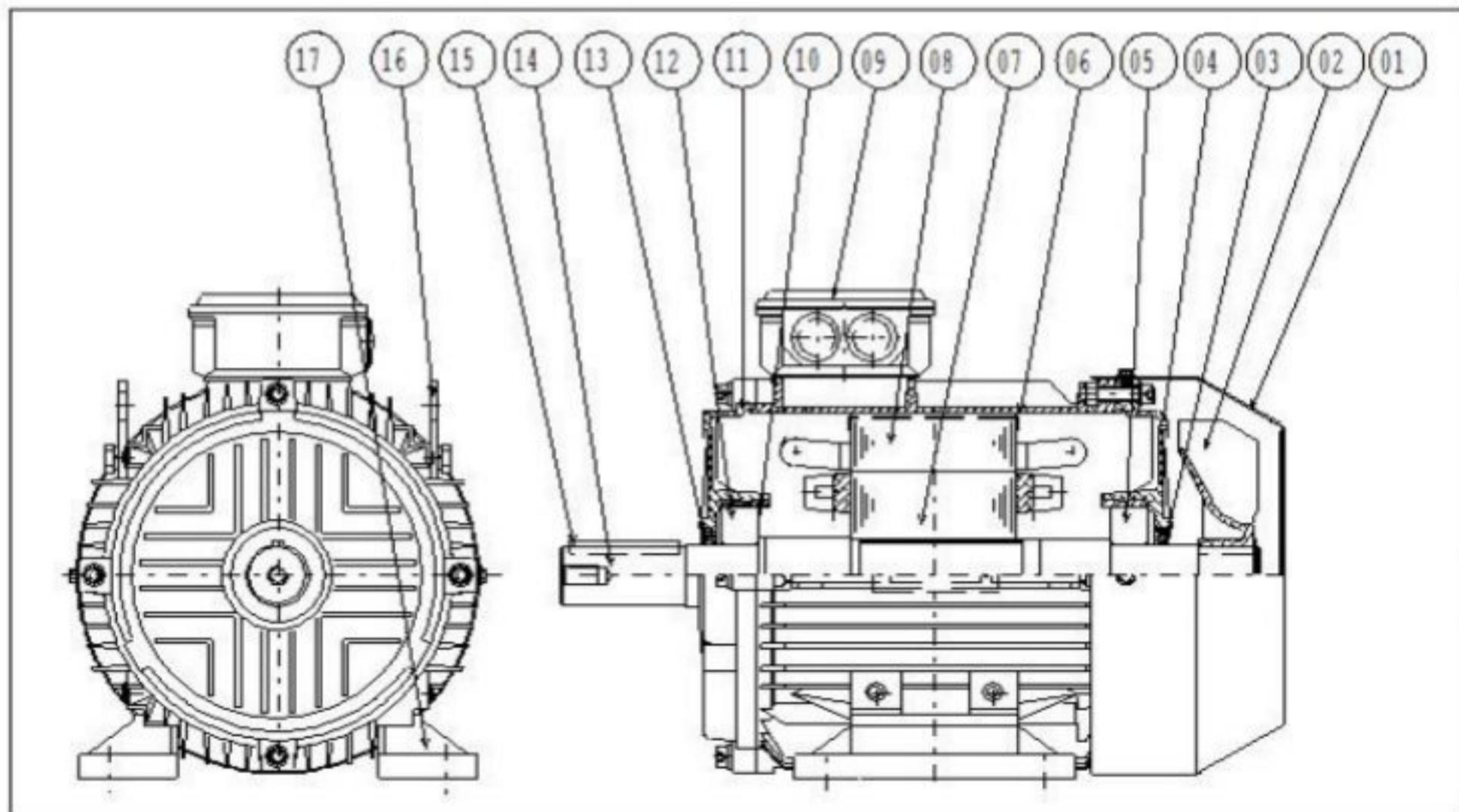
Frame size	Overall dimensions					Shaft extension								Bearings				
		L	LL	O	UB1	UB2	D	E	EB	ED	EG	F	G	GA	DB	at DE	at NDE	Fig.
280	S	1087.5	255	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-28
	S*	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-28
	S**	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-28
280	M	1087.5	255	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58.0	69.0	M20	6316C3	6314C3	7-28
	M*	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	6318C3	6316C3	7-28
	M**	1087.5	255	—			75m6	140	125	7.5	42	20	67.5	79.5	M20	NU318	6316C3	7-28
315	S	1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	7316C3	6314C3	7-29
	S*	1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-29
	S**	1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-29
315	M	1266	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	7316C3	6314C3	7-29
	M*	1296	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-29
	M**	1296	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-29
315	L	1366	322	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	7316C3	6314C3	7-30
	L*	1396	322	—			80m6	170	160	5	42	22	71	85	M20	6320C3	6316C3	7-30
	L**	1396	322	—			80m6	170	160	5	42	22	71	85	M20	NU320	6316C3	7-30
315	D	1674	372	—	M63 x 1.5	M20 x 1.5	65m6	140	125	7.5	42	18	58	69	M20	7316C3	6316C3	7-31
	D*	1704	372	—			85m6	170	160	5	42	22	76	90	M20	6322C3	6322C3	7-31
	D**	1704	372	—			95m6	170	160	5	50	25	86	100	M24	NU322	6322C3	7-31

*) = 4-, 6- and 8-pole version
**) = 4-, 6-, 8-pole version; 315D frame with optional roller bearing

8 Spare parts

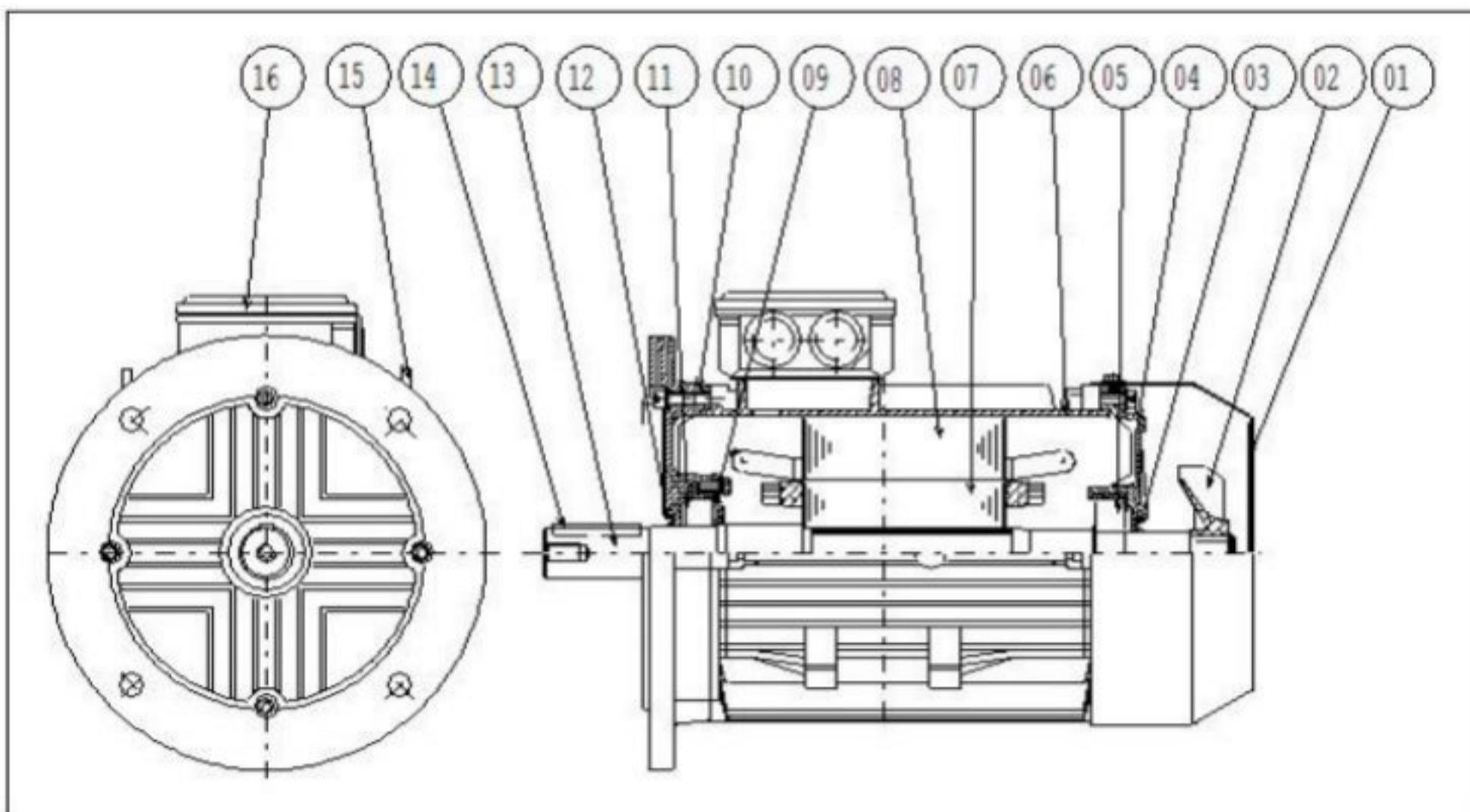
Spare parts are available according to figures below. The schematic diagrams are only representative for a product group.

8.1 Aluminium motors



01	Fan cowl	08	Stator	15	Key
02	External fan	09	Terminal box	16	Lifting eye
03	Oil seal	10	Cir-Clip	17	Feet
04	NDE end shield	11	DE end shield		
05	Bearing	12	Bearing		
06	Frame	13	Oil seal		
07	Rotor	14	Shaft		

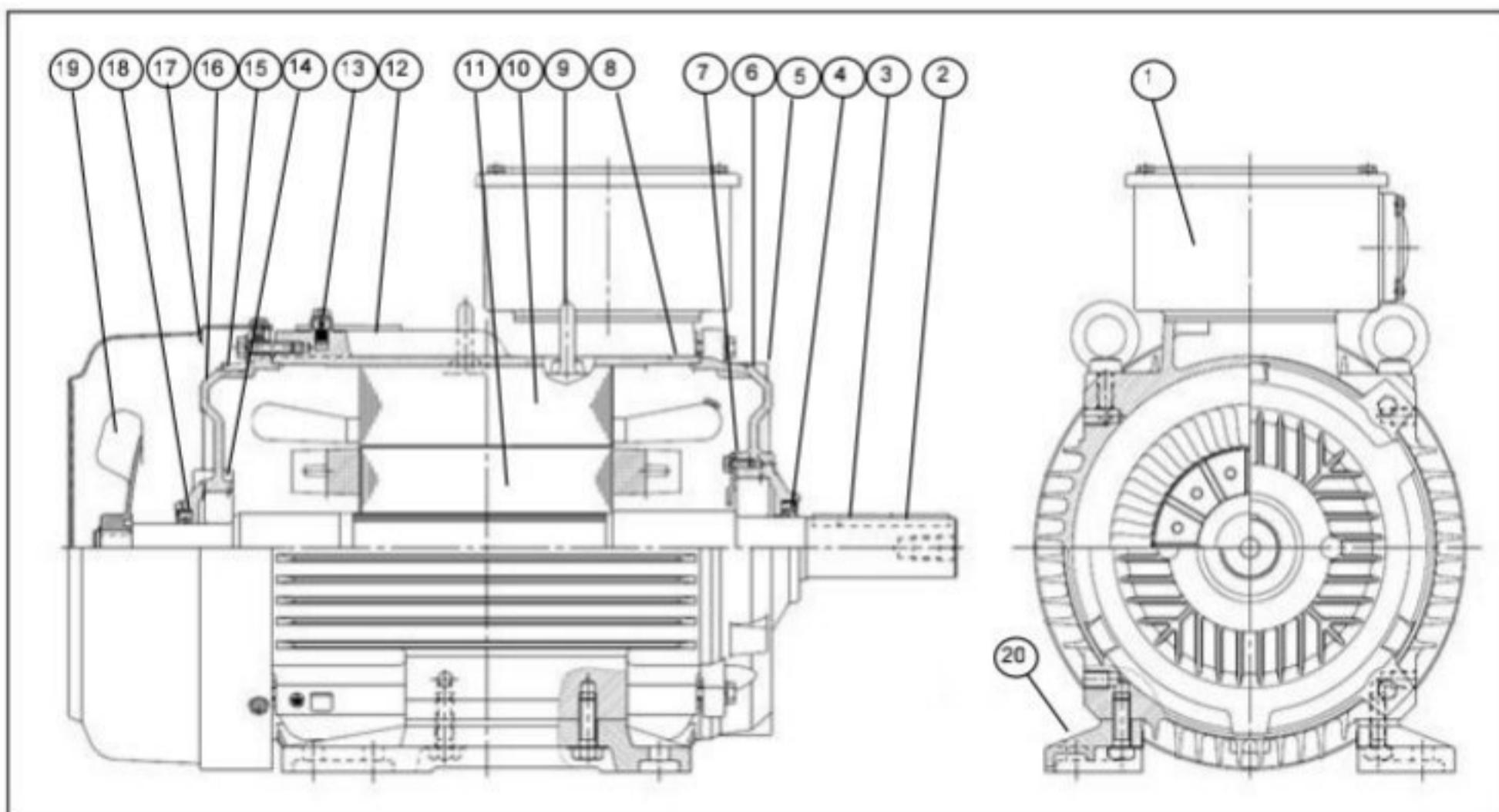
Figure 8-1: Schematic diagram of 63 – 132 frame aluminium motor, feet version



- | | | |
|-------------------|--------------------------|-----------------|
| 01 Fan cowl | 08 Stator | 15 Lifting eye |
| 02 External fan | 09 Inner bearing cover | 16 Terminal box |
| 03 Oil seal | 10 DE end shield, flange | |
| 04 NDE end shield | 11 Bearing | |
| 05 Bearing | 12 Oil seal | |
| 06 Frame | 13 Shaft | |
| 07 Rotor | 14 Key | |

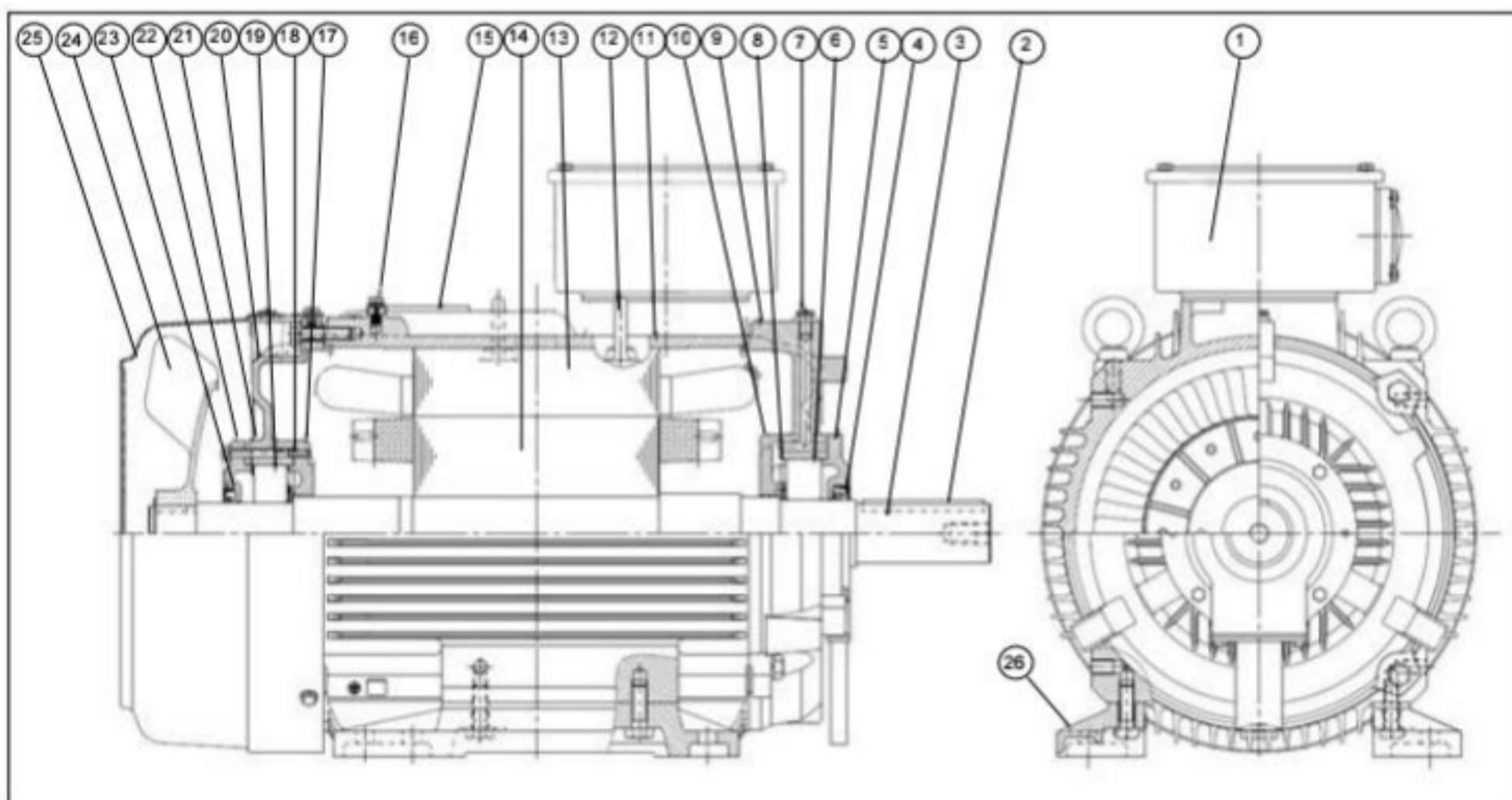
Figure 8-2: Schematic diagram of a 160 aluminium motor, flange version

8.2 Cast iron motors



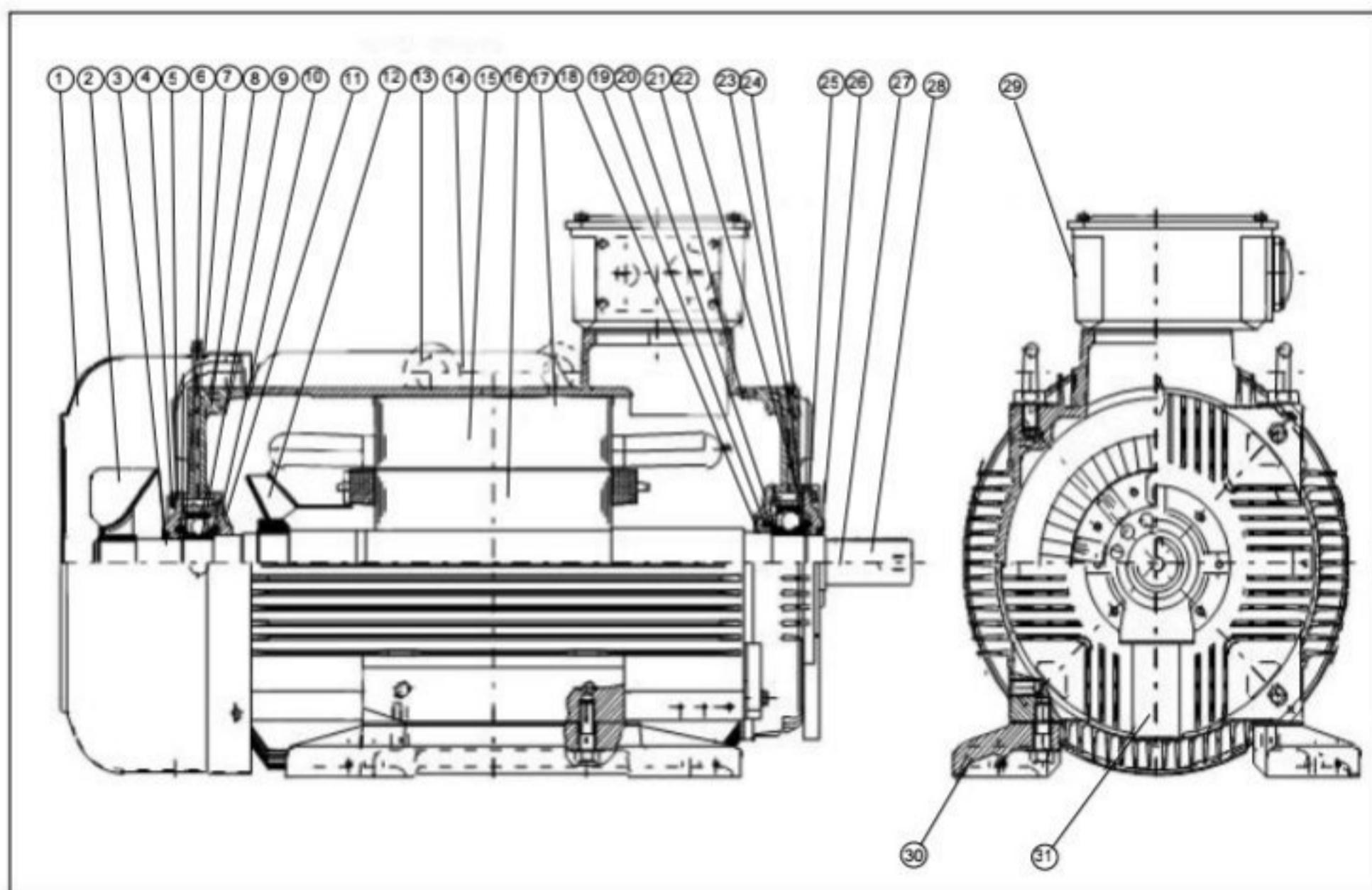
01	Terminal box	08	Frame	15	NDE end shield
02	Key	09	Lifting eye	16	Pre-load spring
03	Shaft	10	Stator	17	Fan cowl
04	Oil seal	11	Rotor	18	Oil seal
05	Bearing	12	Rating plate	19	External fan
06	DE end shield	13	Grounding terminal	20	Feet
07	Inner bearing cover	14	Bearing		

Figure 8-3: Cast iron motors; frame size ≤160 (sample)



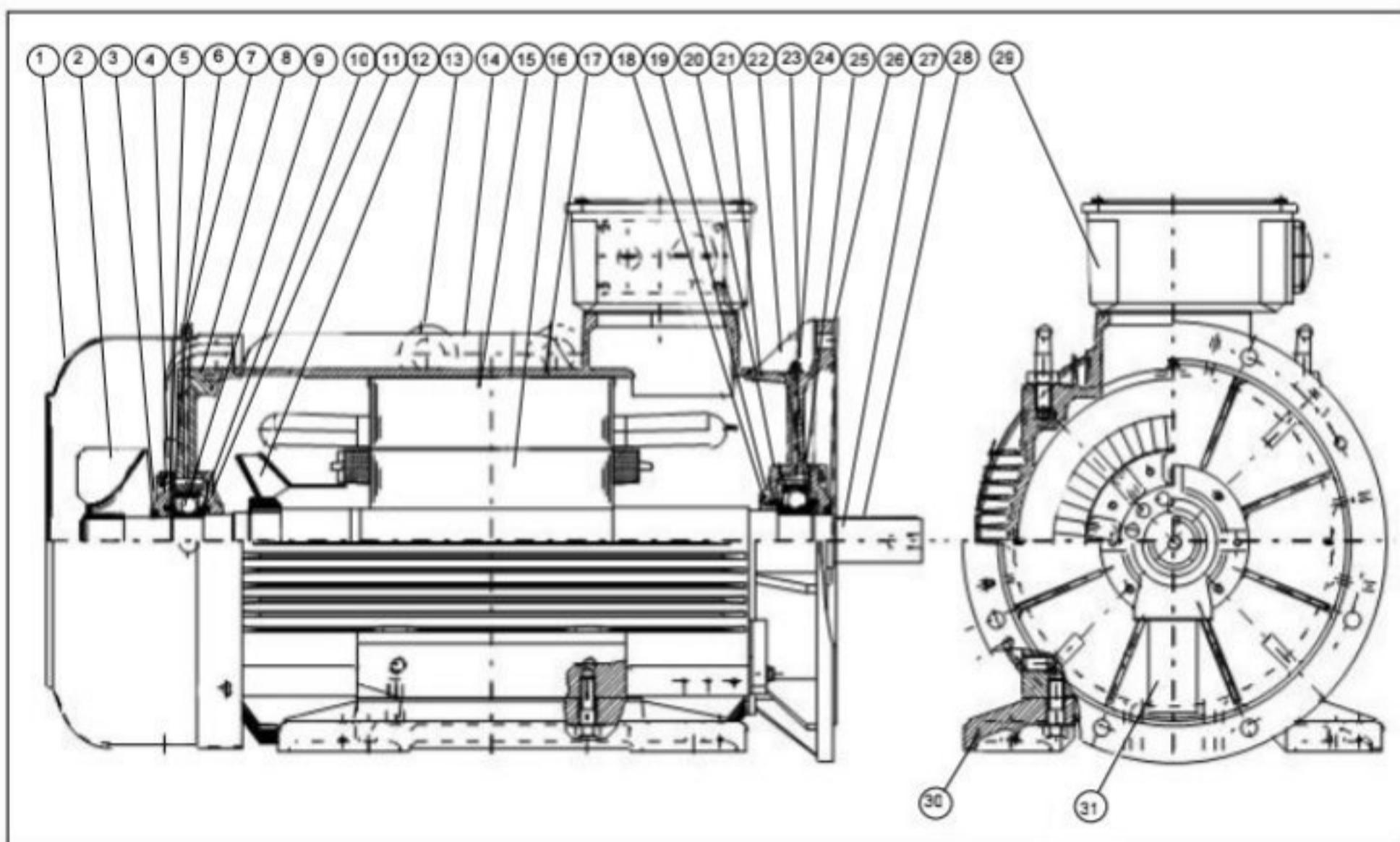
01	Terminal box	10	Inner bearing cover	19	Bearing
02	Key	11	Frame	20	NDE end shield
03	Shaft	12	Lifting eye	21	Pre-load spring
04	Oil seal	13	Stator	22	Outer bearing cover
05	Outer bearing cover	14	Rotor	23	Oil seal
06	Bearing	15	Rating plate	24	External fan
07	Grease nipple	16	Grounding terminal	25	Fan cowl
08	Bracket	17	Inner bearing cover	26	Feet
09	DE end shield	18	Bracket		

Figure 8-4: Cast iron motors; frame size 180 – 280



01	Fan cowl	12	Inner fan	23	Outside retaining ring
02	External fan	13	Lifting eye	24	Grease nipple
03	Oil seal	14	Rating plate	25	Outer bearing cover
04	Outer bearing cover	15	Stator	26	Oil seal
05	Outside retaining ring	16	Rotor	27	Shaft
06	Grease flinger	17	Frame	28	Key
07	Grease nipple	18	Inner bearing cover	29	Terminal box
08	DE end shield	19	Grease flinger	30	Feet
09	Bearing	20	Bearing	31	Oil drain cover
10	Grease flinger	21	NDE end shield		
11	Inner bearing cover	22	Grease flinger		

Figure 8-5: Cast iron motors; frame size 315; mounting B3



01	Fan cowl	12	Inner fan	23	Outside retaining ring
02	External fan	13	Lifting eye	24	Grease nipple
03	Oil seal	14	Rating plate	25	Outer bearing cover
04	Outer bearing cover	15	Stator	26	Oil seal
05	Outside retaining ring	16	Rotor	27	Shaft
06	Grease flinger	17	Frame	28	Key
07	Grease nipple	18	Inner bearing cover	29	Terminal box
08	DE end shield	19	Grease flinger	30	Feet
09	Bearing	20	Bearing	31	Oil drain cover
10	Grease flinger	21	NDE end shield		
11	Inner bearing cover	22	Grease flinger		

Figure 8-6: Cast iron motors; frame size 315; mounting B35

9 Packing, labelling

9.1 Packing design

If not otherwise specified, the motors are delivered as described below. Motors are appropriately packed for the shipping and transport method (mainly ship and truck). Within its individual cartons or crates the motors are sealed in foil to prevent spillage and mechanically fixed to avoid movement. A desiccant (like silica gel) is contained within the foil to prevent condensation.

9.1.1 Motors up to frame size 90

The motors are carton packed and placed on individually designed pallets. The motors cartons have two handling bars for carrying appropriate to withstand the motor weight. In a second function these handling bars give easy access to the nameplate of the motor. Therefore change of the brand label is possible without unpacking the motor.

The cartons can be piled in 1 – 3 layers on a pallet (see table below). The pallets for carton packed motors are designed for fork lifter use with similar fork access space (max. 145 mm centre blocks) as for euro pallets. (pallet dimensions see table below).

Frame size	Single carton dimensions	Max. pallet dimensions	Max. motors per unit	Max. mass, (depending on type)
	L x W x H [mm]	L x W x H [mm]	pieces	m [kg]
63	300 x 220 x 230	1100 x 800 x 900	52	
71	300 x 220 x 240	1100 x 800 x 900	52	
80	360 x 233 x 250	1100 x 800 x 900	30	730 – 900
90	450 x 250 x 270	1100 x 800 x 970	21	660 – 900

Table 9-1: Packing data of cartons and pallets

9.1.2 Motors frame size 100 to 315

The motors are packed in pallet based crates. It is possible to pile the crates according to table below:

Frame size	Single crate dimensions	Max. layer use layers	Max. pallet dimensions [mm]	Max. motors per unit pieces	Max. mass, (depending on type)
	L x W x H [mm]				m
	L x W x H [mm]				[kg]
100	530 x 350 x 385	3	1100 x 800 x 1000	18	900 – 1150
112	530 x 350 x 385	3	1050 x 930 x 900	12	750 – 1050
132	570 x 440 x 385	3	1160 x 800 x 1020	8	750 – 1050
160	750 x 450 x 590	3	750 x 900 x 720	2	300 – 425
180	840 x 490 x 625	3	980 x 840 x 1380	4	900 – 1250
200	990 x 580 x 740	2	990 x 590 x 750	1	300 – 400
225	990 x 580 x 740	2	990 x 590 x 750	1	370 – 520
250	1090 x 630 x 800	1	1090 x 630 x 800	1	500 – 650
280		1		1	
315		1		1	

Table 9-2: Packing data

9.2 Labelling

Each motor has an identification sticker which provides the following information encoded in clear text as well as in barcode (part of the 128 family).

The sticker is placed:

- with carton packed motors: on one side of the carton
- with crate packed motors: one sticker on side of the crate.

	Clear Text	Barcode
Article No.	X	X
Motor individual serial number	X	X
Catalogue No.	X	
Voltage	X	
Power	X	
Poles	X	
Mounting arrangement	X	

Table 9-3: Identification sticker contents

10 Quality assurance

According to the requirements of IEC 60 034-1 the following tests are carried out at least:

- Type test (for a certain type of motor) and
- Routine test (carried out on each individual motor).

The contents of these tests according to IEC are listed in the table below:

Code	Test Item	Type Test	Routine Test
1	Outline dimension inspection	X	X
2	Stator winding resistance (cold)	X	X
3	Insulation resistance (before high voltage test; item 8)	X	
4	Test of rotational direction	X	X
5	Locked rotor current	X	X
6.1	No load curve (current, power)	X	
6.2	Nominal no load point (current, power)	X	X
7.1	Heat run test	X	
7.2	Winding resistance hot (after heat run test)	X	
7.3	Losses segregation (evaluation of efficiency)	X	
8	High voltage test	X	X
9	Insulation resistance (after high voltage test; item 8)	X	X
10.1	Vibration test	X	
10.2	Acoustic noise test	X	

11 Documentation

Together with each motor the following documentation is delivered:

- Barcode label (see 9.2 Labelling, page 120)
- Safety instruction: A short form safety instructions according to demands of European directive 2006/95/EG is delivered together with each single motor (attached in carton box or safely fixed on eye bolt of crate packed motors). The manual is available in the most common EU languages.

The following documentation can be provided on request:

- A detailed start up and operation manual is available in English, German, French, Italian and Spanish language; it is available for download and as a hardcopy in TECO EU offices (TECO file name: "INSTALLATION, OPERATION and MAINTENANCE INSTRUCTIONS FOR TECO LOW VOLTAGE MOTORS TYPE ALAA and ALCA").
- EC certificate of conformity (Low Voltage Directive 2006/95/EC; EMC Directive 2004/108/EC)
- EC-Declaration of Incorporation according to Machinery Directive 2006/42/EC
- Data sheet and individual dimensional diagram
- Inspection certificate according to EN 10204: 2004.

EUROPE

Netherlands

Company Name: TECO Electric & Machinery B.V.
Address: Rivium 3e Straat 17
Country: 2909LH Capelle a/d IJssel
Tel: Netherlands
Fax: 0031-(0)10-266-6633
Email: 0031-(0)10-202-6415
Website: www.teco-group.eu

England

Company Name: TECO ELECTRIC EUROPE LTD.
Address: 7 Dakota Avenue
Country: Salford. M50 2PU
Tel: United Kingdom
Fax: 0044-161-877-8025
Email: 0044-161-877-8030
Website: enquiries@teco-group.eu
www.teco-group.eu

Germany

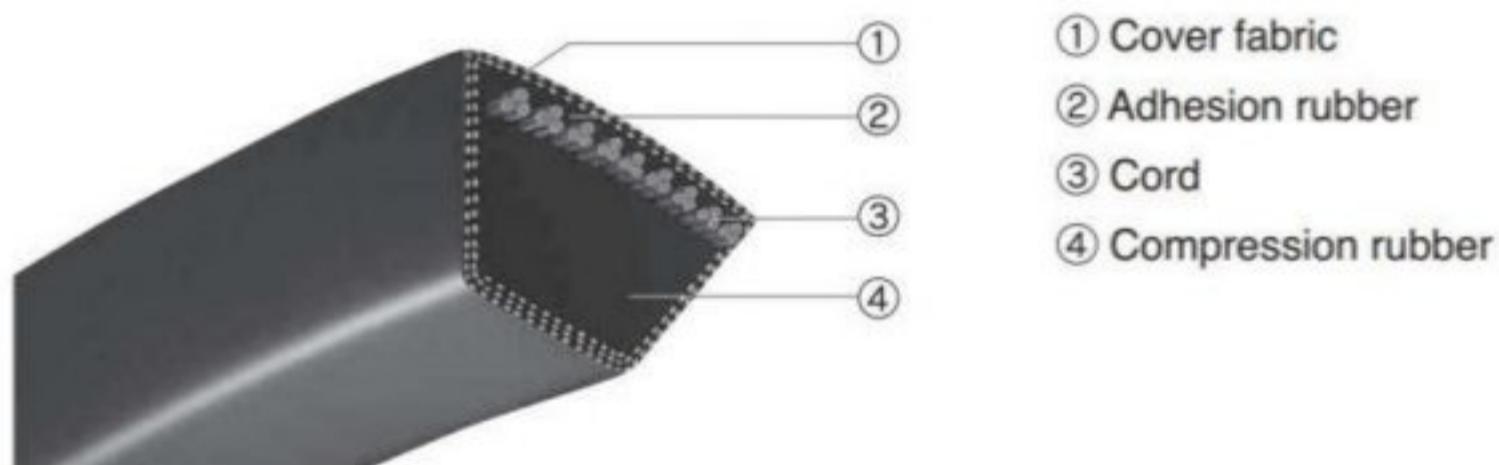
Company Name: TECO Electric and Machinery GmbH
Address 1: Bahnhofweg 7A
Country: 94060 Pocking
Tel: Germany
Fax: 0049-(0)-8531-913874-0
Email: 0049-(0)-8531-913874-9
Website:
Address 2: Poststrasse 6
Country: 37441 Bad Sachsa
Tel: Germany
Fax: 0049-(0)-5523-9534-0
Email: 0049-(0)-5523-9534-24
Website: www.teco-group.eu

Spain office

Company Name: Great TECO S.L.
Address: C/ Apostol Santiago, 40, 1A
Country: 28017 Madrid
Tel: Spain
Fax: 0034-91-326-30-91
Email: 0034-91-326-30-91
Website: www.teco-group.eu

SKMM3523 COMPONENT DESIGN

DESIGN OF MECHANICAL ELEMENT 3: V-BELT



In Imperial Unit

Reference:

V-Belt Manufacturer - **MITSUBOSHI**

LAST UPDATE: 2020-05-12 Version 3

Design Process for V-Belt Drive Design

Design Flow

1

Set conditions required in design work.

a. Type of machine

b. Transmission power

It is ideal to use the actual load applied to the belt as the value of the transmission power, but the rated power of the motor is commonly used for calculation.

c. Running hours in a single day

d. Small pulley speed

e. Speed ratio

$$\text{Speed ratio} = \frac{\text{Large pulley datum diameter}}{\text{Small pulley datum diameter}}$$

f. Interim center distance

g. Special uses and environmental conditions

Contact us for the case of exposure to high or low temperature, water, oil, acid or alkali.

Design Flow

2

Set the design power.

1. How to calculate the service factor (Ks)

$$Ks = Ko + Ki + Ke$$

Wherein, Ks : Service factor

Ko : Service correction factor >> (Table 2-1)

Ki : Idler correction factor >> (Table 2-2)

Ke : Environment correction factor >> (Table 2-3)

2. How to calculate the design power (Hd)

The value of transmission power used in designing is the power requirement of the driven machine, if obtained, or the power of driving unit (engine or motor).

Convert the value from SI unit (kW) into horse power (hp) with the formula below.

$$1 \text{ kW} = 1.341 \text{ hp}$$

$$Ht = \frac{Tq \times n}{63025}$$

Wherein, Ht: Transmission power (hp)

Tq : Torque (lb·in)

n : Shaft speed (rpm)

$$Hd = Ht \times Ks$$

Wherein, Hd : Design power (hp)

Ht : Transmission power (hp)

Ks : Service factor

1. Ko

Service correction factor (Ko)

Table 1-1

Driven Machine	Driving unit / Motor					
	Max power ≤ 300% of rated power		Max power > 300% of rated power			
	AC motors, single-and three-phase with star-delta start. DC shunt-wound motors, Multiple cylinder internal combustion engines.			AC motors, single and three-phase, series wound, slip-ring motors with direct start. DC motors, series and compound wound. Single cylinder internal combustion engines.		
	Running time (hrs./day)			Running time (hrs./day)		
	3 ~ 5	8 ~ 12	16 ~ 24	3 ~ 5	8 ~ 12	16 ~ 24
● Agitator for liquid ● Small centrifugal blower ● Fan up to 10 HP ● Light-duty conveyor	1.0	1.1	1.2	1.1	1.2	1.3
● Belt conveyor (for sand, grain, etc.) ● Dough mixer ● Fan over 10 hp ● Generator ● Machine tool ● Punching machine ● Pressing machine ● Shearing machine ● Printing machine ● Positive displacement rotary pump ● Vibrating and rotary screen	1.1	1.2	1.3	1.2	1.3	1.4
● Brick-making machinery ● Bucket elevator ● Piston compressor ● Screw conveyor ● Hammer mill ● Hollander ● Piston pump ● Positive displacement blower ● Crusher ● Woodworking machinery ● Textile machinery	1.2	1.3	1.4	1.4	1.5	1.6
● Gyratory and jaw-roll crusher ● Mill (ball/rod) ● Hoist (heavy load) ● Rolling mill, calender etc, for the rubber and plastic industry	1.3	1.4	1.5	1.5	1.6	1.8

2. Ki

Idler correction factor (Ki)

Table 1-2

Location of Idler	Ki
Belt slack side, inside of belt	0.0
Belt slack side, outside of belt	0.1
Belt tight side, inside of belt	0.1
Belt tight side, outside of belt	0.2

3. Ke

Environment correction factor (Ke)

Table 1-3

Environmental condition	Ke
Frequent start and stop of machine	0.2
Hard to conduct maintenance checkup	0.2
Dusty environment	0.2
High temperature	0.2
Oil or water splashing	0.2

● Avoid oil and water splash by cover to prevent belt slipping.

3

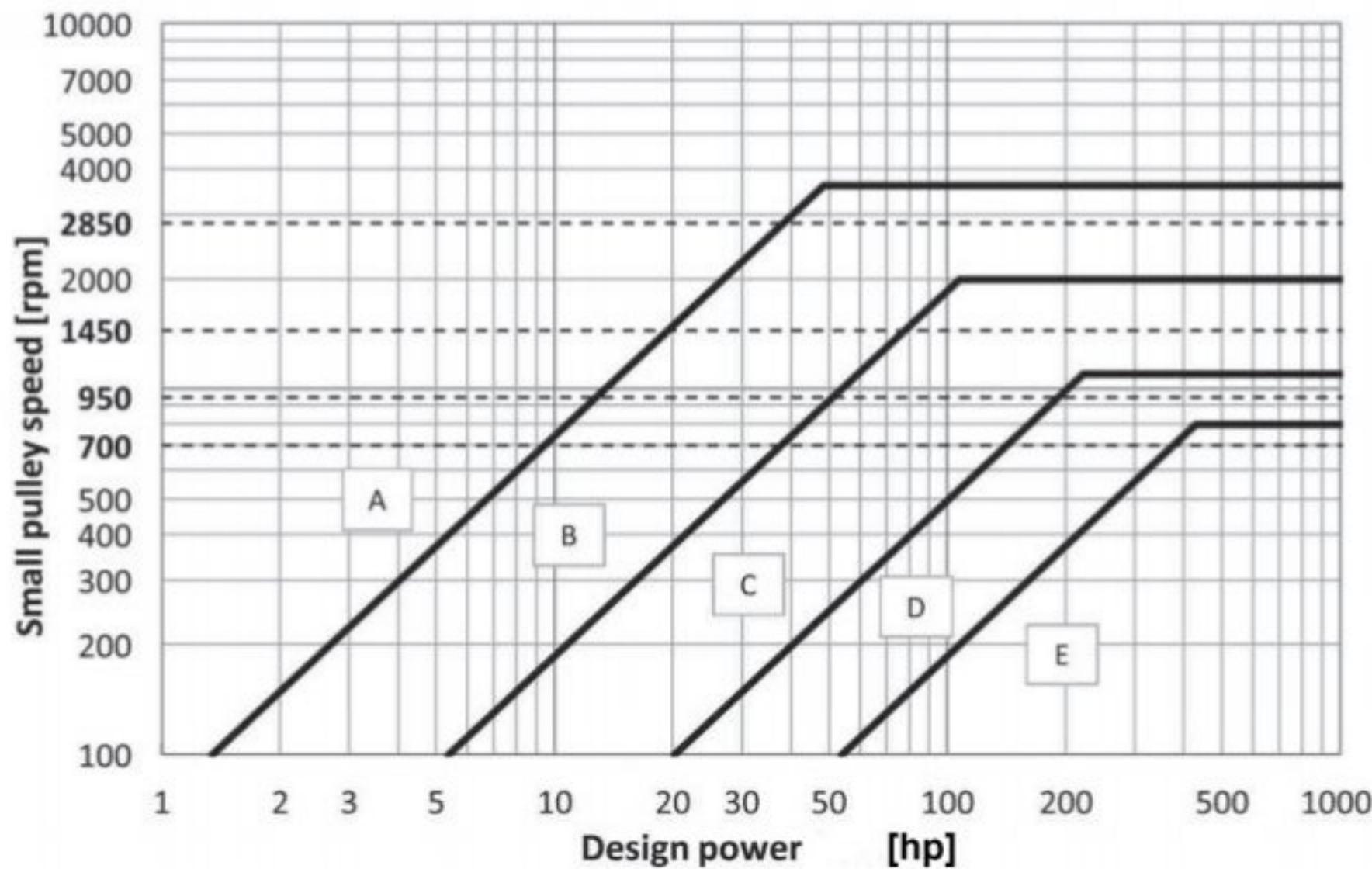
Select the belt type.

Select the belt type in the selection charts below according to design power and small pulley speed.

- Cross section selection chart for V-Belts

- If the intersection locates near the dividing line, select belt type considering other conditions such as pulley cost.

Fig. 1-1



4

Select the pulley size.

- Select the small pulley datum diameter larger than the minimum specified in the Table 1-4.

Inappropriate pulley reduces transmission efficiency and belts' durability significantly.

Minimum pulley datum diameter

Table 1-4

Belt type	A	B	C	D	E
Minimum pulley datum diameter (in)	3.0	5.4	9.0	13.0	17.7
Belt type	AX	BX	CX		
Minimum pulley datum diameter (in)	2.2	4.0	6.8		

- Calculate the large pulley datum diameter.

$$Dd = dd \times SR$$

Dd : Large pulley datum diameter (in)
dd : Small pulley datum diameter (in)
SR : Speed ratio

Difference between pulley outside diameter and datum diameter is specified in the following table.

Difference between pulley outside diameter and datum diameter Unit : mm Table 1-5

Belt type	M	A	B	C	D	E
Difference	5.4	9.0	11.0	14.0	19.0	25.4

5

Determine the belt length.

- Determine the interim belt datum length.

$$Ld' = 2C' + 1.57(Dd+dd)$$

Ld' : Interim belt datum length (in)
C' : Interim center distance (in)
Dd : Large pulley datum diameter (in)
dd : Small pulley datum diameter (in)

- Select the standard belt length closest to the Ld' from our lineup.

Center distance is calculated from the following formula.

$$C = \frac{b + \sqrt{b^2 - 8(Dd - dd)^2}}{8}$$

C : Center distance (in)
b : $2Ld \cdot \pi (Dd+dd)$
Ld : Belt datum length (in)

- If center distance is predetermined, use the following formula to determine interim belt datum length.

$$Ld' = 2C + \frac{\pi}{2}(Dd + dd) + \frac{(Dd - dd)^2}{4C}$$

6

Determine the required number of belts.

Required number of belts (nb) is determined as follows.

Round up the calculation results.

$$nb = \frac{Hd}{Hc}$$

$$\therefore Hc = (Hs + Ha) \times Kc$$

$$Kc = K\theta \times K\ell$$

$$\frac{Dd - dd}{C}$$

nb : Required number of belts

Hd : Design power (hp)

Hc : Corrected power rating per belt (hp)

Hs : Basic power rating per belt (hp)

Ha : Additional power rating for speed ratio (hp)

Kc : Power rating correction factor

Kθ : Arc of contact correction factor

Kl : Belt length correction factor

Dd : Large pulley datum diameter (in)

dd : Small pulley datum diameter (in)

C : Center distance (in)

●Belt length correction factor for V-Belts: Kl

Table 1-7

Length designation					
	A	B	C	D	E
20 ~ 25	0.77	0.72			
26 ~ 30	0.82	0.76			
31 ~ 34	0.85	0.79			
35 ~ 37	0.87	0.81	0.71		
38 ~ 41	0.89	0.83	0.73		
42 ~ 45	0.91	0.85	0.75		
46 ~ 50	0.93	0.87	0.77		
51 ~ 54	0.94	0.89	0.78		
55 ~ 59	0.96	0.91	0.80		
60 ~ 67	0.98	0.93	0.82		
68 ~ 74	1.01	0.95	0.84		
75 ~ 79	1.03	0.97	0.86		
80 ~ 84	1.04	0.98	0.87		
85 ~ 89	1.05	0.99	0.89		
90 ~ 95	1.07	1.01	0.90		
96 ~ 104	1.08	1.03	0.91	0.81	
105 ~ 111	1.10	1.04	0.93	0.82	
112 ~ 119	1.12	1.06	0.94	0.84	
120 ~ 127	1.13	1.07	0.96	0.85	
128 ~ 144	1.15	1.09	0.98	0.87	0.85
145 ~ 154	1.18	1.11	1.00	0.89	0.87
155 ~ 169	1.19	1.13	1.02	0.91	0.88
170 ~ 179	1.21	1.15	1.03	0.92	0.90
180 ~ 194	1.23	1.17	1.05	0.94	0.91
195 ~ 209	1.25	1.18	1.07	0.95	0.93
210 ~ 239	1.27	1.21	1.09	0.98	0.95
240 ~ 269	1.30	1.24	1.12	1.00	0.98
270 ~ 299	1.33	1.26	1.14	1.03	1.00
300 ~ 329	1.35	1.29	1.17	1.05	1.02
330 ~ 359	1.38	1.31	1.19	1.07	1.04
360 ~ 389	1.40	1.33	1.21	1.09	1.06
390 ~ 419		1.35	1.22	1.11	1.08
420 ~ 479		1.38	1.25	1.13	1.10
480 ~ 539		1.41	1.28	1.16	1.13
540 ~ 600		1.44	1.31	1.18	1.16
601 ~ 660		1.46	1.33	1.21	1.18

●Arc of contact correction factor : Kθ Table 1-6

Dd-dd C	Contact angle on small pulley θ(°)	Kθ
0.00	180	1.00
0.10	174	0.99
0.20	169	0.97
0.30	163	0.96
0.40	157	0.94
0.50	151	0.93
0.60	145	0.91
0.70	139	0.89
0.80	133	0.87
0.90	127	0.85
1.00	120	0.82
1.10	113	0.80
1.20	106	0.77
1.30	99	0.73
1.40	91	0.70
1.50	83	0.65

$$\text{Contact angle on small pulley} : \theta = 180 - 2\sin^{-1} \frac{Dd - dd}{2C}$$

$$\text{Contact angle on large pulley} : \theta = 180 + 2\sin^{-1} \frac{Dd - dd}{2C}$$

Dd : Large pulley datum diameter (in)

dd : Small pulley datum diameter (in)

C : Center distance (in)

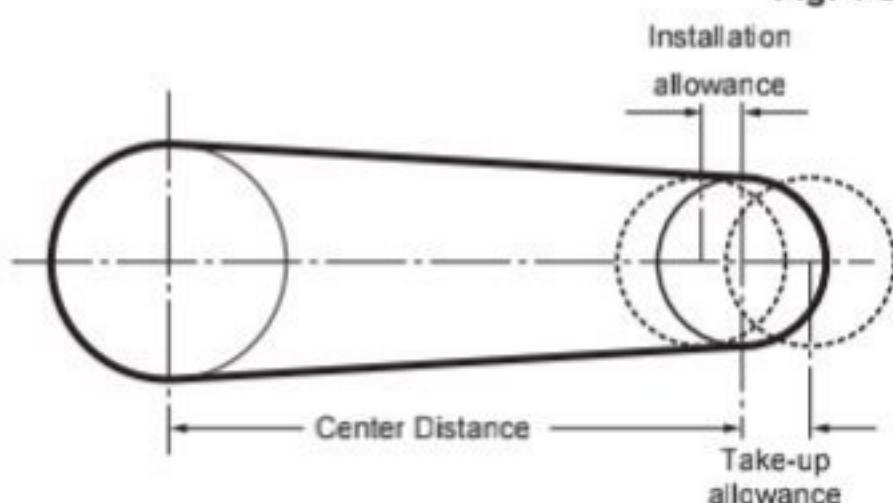
7

Installation and take-up allowance.

Installation and take-up allowance are as follows.

Use idler pulley if you cannot arrange allowance.

Fig. 1-2



● Installation and take-up allowance for V-Belt

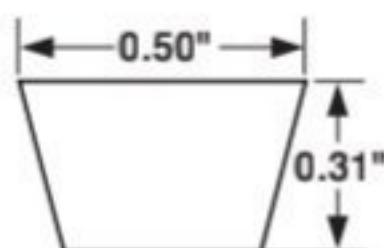
Table 1-8

Length designation	Installation allowance (in)					Take-up allowance (in) All sections
	A	B	C	D	E	
Up to and incl. 35	0.75	1.00				1.00
Over 35 to and incl. 55	0.75	1.00	1.50			1.50
Over 55 to and incl. 85	0.75	1.25	1.50			2.00
Over 85 to and incl. 112	1.00	1.25	1.50			2.50
Over 112 to and incl. 144	1.00	1.25	1.50	2.00	2.50	3.00
Over 144 to and incl. 180	1.00	1.25	2.00	2.00	2.50	3.50
Over 180 to and incl. 210	1.20	1.50	2.00	2.00	2.50	4.00
Over 210 to and incl. 240		1.50	2.00	2.50	2.50	4.50
Over 240 to and incl. 300		1.50	2.00	2.50	3.00	5.00
Over 300 to and incl. 390		1.80	2.00	2.60	3.00	6.00
Over 390 to and incl. 660			2.50	3.00	3.50	$L_d \times 0.015$

V-Belt

Table 1-9

A/13



Belt indication

A 64

Cross section

Belt Code(inch)

A-Section

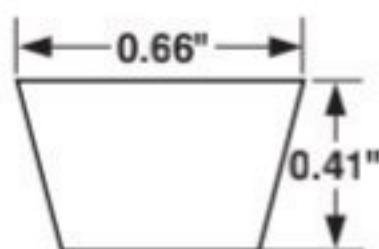
Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)
20	22	21.3	60	62	61.3	100	102	101.3
21	23	22.3	61	63	62.3	102	104	103.3
22	24	23.3	62	64	63.3	105	107	106.3
23	25	24.3	63	65	64.3	108	110	109.3
24	26	25.3	64	66	65.3	110	112	111.3
25	27	26.3	65	67	66.3	112	114	113.3
26	28	27.3	66	68	67.3	115	117	116.3
27	29	28.3	67	69	68.3	118	120	119.3
28	30	29.3	68	70	69.3	120	122	121.3
29	31	30.3	69	71	70.3	122	124	123.3
30	32	31.3	70	72	71.3	125	127	126.3
31	33	32.3	71	73	72.3	128	130	129.3
32	34	33.3	72	74	73.3	130	132	131.3
33	35	34.3	73	75	74.3	135	137	136.3
34	36	35.3	74	76	75.3	140	142	141.3
35	37	36.3	75	77	76.3	145	147	146.3
36	38	37.3	76	78	77.3	150	152	151.3
37	39	38.3	77	79	78.3	155	157	156.3
38	40	39.3	78	80	79.3	160	162	161.3
39	41	40.3	79	81	80.3	165	167	166.3
40	42	41.3	80	82	81.3	170	172	171.3
41	43	42.3	81	83	82.3	180	182	181.3
42	44	43.3	82	84	83.3			
43	45	44.3	83	85	84.3			
44	46	45.3	84	86	85.3			
45	47	46.3	85	87	86.3			
46	48	47.3	86	88	87.3			
47	49	48.3	87	89	88.3			
48	50	49.3	88	90	89.3			
49	51	50.3	89	91	90.3			
50	52	51.3	90	92	91.3			
51	53	52.3	91	93	92.3			
52	54	53.3	92	94	93.3			
53	55	54.3	93	95	94.3			
54	56	55.3	94	96	95.3			
55	57	56.3	95	97	96.3			
56	58	57.3	96	98	97.3			
57	59	58.3	97	99	98.3			
58	60	59.3	98	100	99.3			
59	61	60.3	99	101	100.3			

Size range: 20" ~ 360"

V-Belt

Table 1-10

B/17



Belt indication

B 59

Cross Section

Belt Code(inch)

B -Section

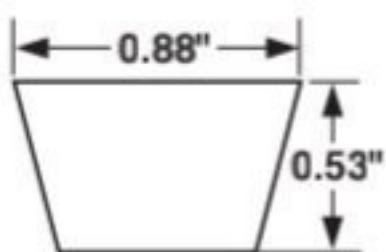
Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)
25	28	26.8	65	68	66.8	112	115	113.8
26	29	27.8	66	69	67.8	115	118	116.8
27	30	28.8	67	70	68.8	118	121	119.8
28	31	29.8	68	71	69.8	120	123	121.8
29	32	30.8	69	72	70.8	122	125	123.8
30	33	31.8	70	73	71.8	125	128	126.8
31	34	32.8	71	74	72.8	128	131	129.8
32	35	33.8	72	75	73.8	130	133	131.8
33	36	34.8	73	76	74.8	132	135	133.8
34	37	35.8	74	77	75.8	135	138	136.8
35	38	36.8	75	78	76.8	138	141	139.8
36	39	37.8	76	79	77.8	140	143	141.8
37	40	38.8	77	80	78.8	145	148	146.8
38	41	39.8	78	81	79.8	150	153	151.8
39	42	40.8	79	82	80.8	155	158	156.8
40	43	41.8	80	83	81.8	160	163	161.8
41	44	42.8	81	84	82.8	165	168	166.8
42	45	43.8	82	85	83.8	170	173	171.8
43	46	44.8	83	86	84.8	180	183	181.8
44	47	45.8	84	87	85.8	190	193	191.8
45	48	46.8	85	88	86.8	200	203	201.8
46	49	47.8	86	89	87.8	210	213	211.8
47	50	48.8	87	90	88.8	240	241	240.3
48	51	49.8	88	91	89.8	270	271	270.3
49	52	50.8	89	92	90.8			
50	53	51.8	90	93	91.8			
51	54	52.8	91	94	92.8			
52	55	53.8	92	95	93.8			
53	56	54.8	93	96	94.8			
54	57	55.8	94	97	95.8			
55	58	56.8	95	98	96.8			
56	59	57.8	96	99	97.8			
57	60	58.8	97	100	98.8			
58	61	59.8	98	101	99.8			
59	62	60.8	99	102	100.8			
60	63	61.8	100	103	101.8			
61	64	62.8	102	105	103.8			
62	65	63.8	105	108	106.8			
63	66	64.8	108	111	109.8			
64	67	65.8	110	113	111.8			

Size range: 23" ~ 660"

V-Belt

Table 1-11

C/22



Belt indication

C 93

Cross Section

Belt Code(inch)

C-Section

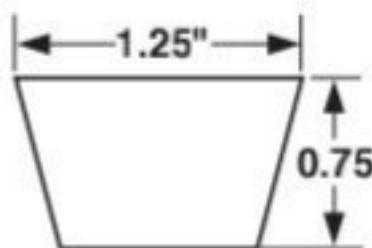
Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)	Belt Code	Outer length La (in)	Datum length Ld (in)
40	44	42.9	86	90	88.9	190	194	192.9
42	46	44.9	87	91	89.9	200	204	202.9
45	49	47.9	88	92	90.9	210	214	212.9
48	52	50.9	89	93	91.9	220	222	220.9
50	54	52.9	90	94	92.9	230	232	230.9
51	55	53.9	91	95	93.9	240	242	240.9
52	56	54.9	92	96	94.9	250	252	250.9
53	57	55.9	93	97	95.9	260	262	260.9
54	58	56.9	94	98	96.9	270	272	270.9
55	59	57.9	95	99	97.9			
56	60	58.9	96	100	98.9			
57	61	59.9	97	101	99.9			
58	62	60.9	98	102	100.9			
59	63	61.9	99	103	101.9			
60	64	62.9	100	104	102.9			
61	65	63.9	102	106	104.9			
62	66	64.9	105	109	107.9			
63	67	65.9	108	112	110.9			
64	68	66.9	110	114	112.9			
65	69	67.9	112	116	114.9			
66	70	68.9	115	119	117.9			
67	71	69.9	118	122	120.9			
68	72	70.9	120	124	122.9			
69	73	71.9	122	126	124.9			
70	74	72.9	125	129	127.9			
71	75	73.9	128	132	130.9			
72	76	74.9	130	134	132.9			
73	77	75.9	132	136	134.9			
74	78	76.9	135	139	137.9			
75	79	77.9	138	142	140.9			
76	80	78.9	140	144	142.9			
77	81	79.9	142	146	144.9			
78	82	80.9	145	149	147.9			
79	83	81.9	148	152	150.9			
80	84	82.9	150	154	152.9			
81	85	83.9	155	159	157.9			
82	86	84.9	160	164	162.9			
83	87	85.9	165	169	167.9			
84	88	86.9	170	174	172.9			
85	89	87.9	180	184	182.9			

Size range: 37" ~ 660"

V-Belt

Table 1-12

D/32



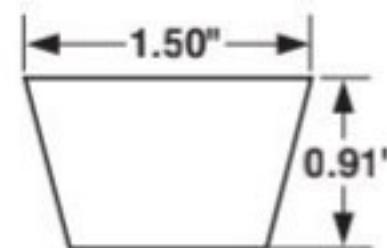
Belt indication

D 120

Cross Section

Belt Code (inch)

E/40



Belt indication

E 180

Cross Section

Belt Code (inch)

D-Section

Belt Code	Outer length La (in)	Datum length Ld (in)
100	105	103.3
105	110	108.3
110	115	113.3
115	120	118.3
120	125	123.3
125	130	128.3
130	135	133.3
135	140	138.3
140	145	143.3
145	150	148.3
150	155	153.3
155	160	158.3
160	165	163.3
165	170	168.3
170	175	173.3
180	185	183.3
190	195	193.3
200	205	203.3
210	215	213.3
220	223	220.8
230	233	230.8
240	243	240.8
250	253	250.8
260	263	260.8
270	273	270.8
280	283	280.8
300	303	300.8
310	313	310.8
330	333	330.8
360	363	360.8

Size range: 100" ~ 660"

E-Section

Belt Code	Outer length La (in)	Datum length Ld (in)
180	187	184.5
210	217	214.5
240	243	241
270	273	271
300	303	301
330	333	331
360	363	361
390	393	391
420	423	421

Size range: 144" ~ 660"

Cross Section Dimension of V-Belt

Table 1-13

Section		A	B	C	D	E
Top belt width	b_o (in)	0.50	0.66	0.88	1.25	1.50
Datum width	b_d (in)	0.418	0.530	0.757	1.076	1.267
Height of belt	h (in)	0.31	0.41	0.53	0.75	0.91
Recommended minimum pulley datum diameter	d_d (in)	3.0	5.4	9.0	13.0	17.7
Recommended maximum belt speed	V (fpm)	5900				

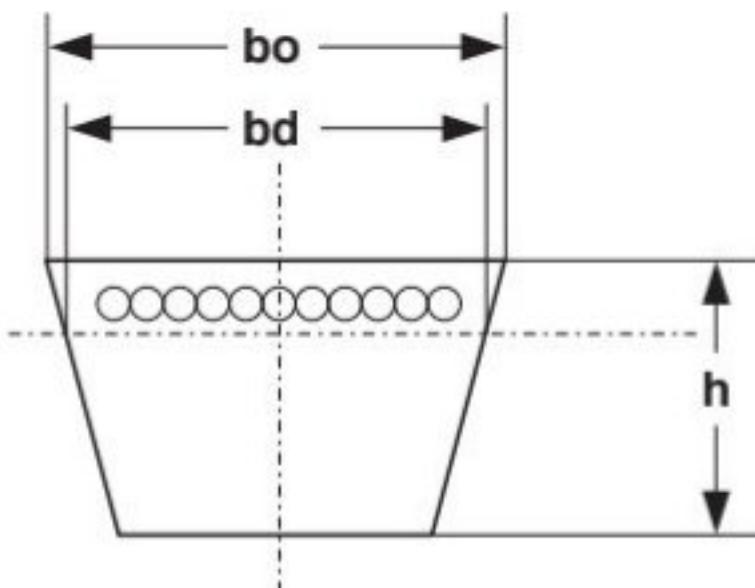


Fig. 1-3

A-Section Power Rating

Table 1-15

small pulley speed (rpm)	Basic power rating for small pulley datum diameter : Hs																		Additional power rating for speed ratio : Ha					
	Small pulley datum diameter (in)																		Speed ratio					
	3.00	3.20	3.40	3.60	3.80	4.00	4.20	4.40	4.60	4.80	5.00	5.20	5.40	5.60	5.80	6.00	6.20	6.40	6.60	7.00	1.01	1.06	1.27	>
700	0.91	1.08	1.24	1.40	1.57	1.73	1.89	2.05	2.21	2.36	2.52	2.68	2.83	2.99	3.14	3.30	3.45	3.60	3.75	4.05	0.02	0.11	0.16	0.20
950	1.13	1.35	1.56	1.78	1.99	2.20	2.41	2.62	2.83	3.03	3.24	3.44	3.64	3.84	4.04	4.24	4.44	4.64	4.83	5.22	0.02	0.15	0.22	0.27
1450	1.49	1.81	2.12	2.43	2.73	3.04	3.34	3.64	3.93	4.23	4.52	4.81	5.09	5.37	5.66	5.94	6.21	6.49	6.76	7.29	0.04	0.23	0.33	0.41
2850	2.12	2.67	3.20	3.73	4.24	4.75	5.24	5.73	6.20	6.67	7.12	7.57	8.00	8.42	8.83	9.23	9.62	9.99	10.36	11.04	0.07	0.46	0.65	0.80
100	0.20	0.23	0.26	0.28	0.31	0.34	0.37	0.39	0.42	0.45	0.48	0.50	0.53	0.56	0.58	0.61	0.64	0.66	0.69	0.74	0.00	0.02	0.02	0.03
200	0.35	0.40	0.46	0.51	0.56	0.61	0.66	0.72	0.77	0.82	0.87	0.92	0.97	1.02	1.07	1.12	1.17	1.22	1.27	1.37	0.00	0.03	0.05	0.06
300	0.48	0.56	0.63	0.71	0.79	0.86	0.94	1.01	1.09	1.16	1.23	1.31	1.38	1.45	1.53	1.60	1.67	1.74	1.81	1.96	0.01	0.05	0.07	0.08
400	0.60	0.70	0.80	0.90	1.00	1.09	1.19	1.29	1.39	1.48	1.58	1.67	1.77	1.86	1.96	2.05	2.14	2.24	2.33	2.51	0.01	0.06	0.09	0.11
500	0.71	0.83	0.95	1.07	1.20	1.31	1.43	1.55	1.67	1.79	1.90	2.02	2.14	2.25	2.37	2.48	2.59	2.71	2.82	3.04	0.01	0.08	0.11	0.14
600	0.81	0.96	1.10	1.24	1.38	1.53	1.66	1.80	1.94	2.08	2.22	2.35	2.49	2.63	2.76	2.89	3.03	3.16	3.29	3.56	0.01	0.10	0.14	0.17
700	0.91	1.08	1.24	1.40	1.57	1.73	1.89	2.05	2.21	2.36	2.52	2.68	2.83	2.99	3.14	3.30	3.45	3.60	3.75	4.05	0.02	0.11	0.16	0.20
800	1.00	1.19	1.37	1.56	1.74	1.92	2.10	2.28	2.46	2.64	2.81	2.99	3.16	3.34	3.51	3.68	3.85	4.02	4.19	4.53	0.02	0.13	0.18	0.22
900	1.09	1.29	1.50	1.70	1.91	2.11	2.31	2.51	2.71	2.90	3.10	3.29	3.49	3.68	3.87	4.06	4.25	4.44	4.62	5.00	0.02	0.14	0.21	0.25
1000	1.17	1.40	1.62	1.85	2.07	2.29	2.51	2.73	2.94	3.16	3.37	3.59	3.80	4.01	4.22	4.42	4.63	4.84	5.04	5.44	0.02	0.16	0.23	0.28
1100	1.25	1.50	1.74	1.98	2.23	2.47	2.70	2.94	3.18	3.41	3.64	3.87	4.10	4.33	4.55	4.78	5.00	5.22	5.44	5.88	0.03	0.18	0.25	0.31
1200	1.32	1.59	1.85	2.12	2.38	2.64	2.89	3.15	3.40	3.65	3.90	4.15	4.39	4.64	4.88	5.12	5.36	5.60	5.83	6.30	0.03	0.19	0.27	0.34
1300	1.39	1.68	1.96	2.24	2.52	2.80	3.07	3.35	3.62	3.89	4.15	4.42	4.68	4.94	5.20	5.45	5.71	5.96	6.21	6.71	0.03	0.21	0.30	0.37
1400	1.46	1.77	2.07	2.37	2.66	2.96	3.25	3.54	3.83	4.11	4.40	4.68	4.96	5.23	5.51	5.78	6.05	6.31	6.58	7.10	0.03	0.23	0.32	0.39
1500	1.53	1.85	2.17	2.49	2.80	3.11	3.42	3.73	4.03	4.34	4.63	4.93	5.22	5.52	5.80	6.09	6.37	6.65	6.93	7.48	0.04	0.24	0.34	0.42
1600	1.59	1.93	2.27	2.60	2.93	3.26	3.59	3.91	4.23	4.55	4.86	5.18	5.48	5.79	6.09	6.39	6.69	6.98	7.27	7.85	0.04	0.26	0.37	0.45
1700	1.65	2.01	2.36	2.71	3.06	3.41	3.75	4.09	4.43	4.76	5.09	5.41	5.74	6.06	6.37	6.68	6.99	7.30	7.60	8.19	0.04	0.27	0.39	0.48
1800	1.70	2.08	2.45	2.82	3.19	3.55	3.91	4.26	4.61	4.96	5.30	5.64	5.98	6.31	6.64	6.96	7.29	7.60	7.92	8.53	0.04	0.29	0.41	0.51
1900	1.75	2.15	2.54	2.93	3.31	3.69	4.06	4.43	4.79	5.16	5.51	5.87	6.21	6.56	6.90	7.24	7.57	7.89	8.22	8.85	0.05	0.31	0.43	0.53
2000	1.80	2.22	2.62	3.03	3.42	3.82	4.21	4.59	4.97	5.34	5.71	6.08	6.44	6.80	7.15	7.49	7.84	8.17	8.50	9.15	0.05	0.32	0.46	0.56
2100	1.85	2.28	2.70	3.12	3.54	3.94	4.35	4.74	5.14	5.53	5.91	6.29	6.66	7.03	7.39	7.74	8.09	8.44	8.78	9.44	0.05	0.34	0.48	0.59
2200	1.90	2.34	2.78	3.21	3.64	4.07	4.48	4.89	5.30	5.70	6.10	6.48	6.87	7.24	7.62	7.98	8.34	8.69	9.04	9.71	0.05	0.35	0.50	0.62
2300	1.94	2.40	2.85	3.30	3.75	4.18	4.61	5.04	5.46	5.87	6.28	6.67	7.07	7.45	7.83	8.21	8.57	8.93	9.28	9.97	0.06	0.37	0.53	0.65
2400	1.98	2.45	2.92	3.39	3.85	4.30	4.74	5.18	5.61	6.03	6.45	6.86	7.26	7.65	8.04	8.42	8.79	9.16	9.51	10.20	0.06	0.39	0.55	0.67
2500	2.01	2.51	2.99	3.47	3.94	4.40	4.86</																	

B-Section Power Rating

Table 1-16

small pulley speed (rpm)	Basic power rating for small pulley datum diameter : Hs																		Additional power rating for speed ratio : Ha			
	Small pulley datum diameter (in)																		Speed ratio			
	4.60	4.80	5.00	5.20	5.40	5.60	5.80	6.00	6.20	6.40	6.60	6.80	7.00	7.40	8.00	8.60	9.40	11.00	1.01 to 1.05	1.06 to 1.26	1.27 to 1.57	1.57<
700	2.34	2.59	2.84	3.09	3.34	3.58	3.83	4.08	4.32	4.56	4.80	5.05	5.29	5.76	6.47	7.17	8.09	9.88	0.04	0.25	0.36	0.44
950	2.91	3.24	3.57	3.89	4.21	4.54	4.86	5.17	5.49	5.80	6.12	6.43	6.74	7.35	8.26	9.15	10.32	12.58	0.05	0.34	0.48	0.60
1450	3.85	4.32	4.78	5.24	5.70	6.15	6.60	7.05	7.49	7.93	8.36	8.79	9.22	10.06	11.29	12.48	14.01	16.86	0.08	0.52	0.74	0.91
2850	5.15	5.89	6.62	7.32	8.01	8.68	9.34	9.97	10.59	11.18	11.76	12.31	12.84	13.84	15.17	16.29	17.42	-	0.16	1.02	1.45	1.79
100	0.50	0.54	0.59	0.63	0.67	0.71	0.76	0.80	0.84	0.88	0.93	0.97	1.01	1.09	1.22	1.34	1.51	1.83	0.01	0.04	0.05	0.06
200	0.88	0.96	1.04	1.13	1.21	1.29	1.37	1.45	1.53	1.61	1.69	1.77	1.84	2.00	2.24	2.47	2.78	3.38	0.01	0.07	0.10	0.13
300	1.22	1.34	1.46	1.57	1.69	1.81	1.92	2.04	2.15	2.27	2.38	2.50	2.61	2.84	3.17	3.51	3.95	4.82	0.02	0.11	0.15	0.19
400	1.53	1.68	1.83	1.99	2.14	2.29	2.44	2.59	2.74	2.88	3.03	3.18	3.33	3.62	4.06	4.49	5.06	6.18	0.02	0.14	0.20	0.25
500	1.82	2.00	2.19	2.37	2.56	2.74	2.93	3.11	3.29	3.47	3.65	3.83	4.01	4.37	4.90	5.42	6.11	7.47	0.03	0.18	0.26	0.31
600	2.08	2.30	2.52	2.74	2.96	3.17	3.39	3.60	3.82	4.03	4.24	4.45	4.66	5.08	5.70	6.31	7.12	8.70	0.03	0.22	0.31	0.38
700	2.34	2.59	2.84	3.09	3.34	3.58	3.83	4.08	4.32	4.56	4.80	5.05	5.29	5.76	6.47	7.17	8.09	9.88	0.04	0.25	0.36	0.44
800	2.58	2.86	3.14	3.42	3.70	3.98	4.25	4.53	4.80	5.08	5.35	5.62	5.88	6.42	7.21	7.99	9.01	11.00	0.04	0.29	0.41	0.50
900	2.80	3.12	3.43	3.74	4.05	4.35	4.66	4.96	5.27	5.57	5.87	6.16	6.46	7.05	7.92	8.77	9.90	12.07	0.05	0.32	0.46	0.56
1000	3.02	3.36	3.70	4.04	4.38	4.71	5.05	5.38	5.71	6.04	6.36	6.69	7.01	7.65	8.60	9.53	10.74	13.08	0.06	0.36	0.51	0.63
1100	3.22	3.59	3.96	4.33	4.70	5.06	5.42	5.78	6.14	6.49	6.84	7.19	7.54	8.23	9.25	10.24	11.54	14.03	0.06	0.40	0.56	0.69
1200	3.41	3.81	4.21	4.61	5.00	5.39	5.78	6.16	6.55	6.92	7.30	7.68	8.05	8.78	9.87	10.93	12.30	14.92	0.07	0.43	0.61	0.75
1300	3.59	4.02	4.45	4.87	5.29	5.71	6.12	6.53	6.94	7.34	7.74	8.14	8.53	9.31	10.46	11.58	13.02	15.74	0.07	0.47	0.66	0.82
1400	3.76	4.22	4.67	5.12	5.57	6.01	6.44	6.88	7.31	7.74	8.16	8.58	8.99	9.82	11.02	12.19	13.69	16.50	0.08	0.50	0.71	0.88
1500	3.93	4.41	4.89	5.36	5.83	6.29	6.75	7.21	7.66	8.11	8.56	9.00	9.43	10.29	11.55	12.76	14.32	17.20	0.08	0.54	0.77	0.94
1600	4.08	4.59	5.09	5.59	6.08	6.57	7.05	7.53	8.00	8.47	8.94	9.40	9.85	10.74	12.05	13.30	14.90	17.82	0.09	0.58	0.82	1.00
1700	4.22	4.75	5.28	5.80	6.31	6.82	7.33	7.83	8.32	8.81	9.29	9.77	10.24	11.17	12.51	13.80	15.43	18.37	0.09	0.61	0.87	1.07
1800	4.35	4.91	5.46	6.00	6.54	7.07	7.59	8.11	8.62	9.13	9.63	10.12	10.61	11.56	12.94	14.26	15.91	18.85	0.10	0.65	0.92	1.13
1900	4.48	5.05	5.62	6.19	6.75	7.30	7.84	8.38	8.91	9.43	9.94	10.45	10.95	11.93	13.34	14.68	16.34	19.24	0.11	0.68	0.97	1.19
2000	4.59	5.19	5.78	6.36	6.94	7.51	8.07	8.62	9.17	9.71	10.24	10.76	11.27	12.27	13.70	15.05	16.72	19.55	0.11	0.72	1.02	1.26
2100	4.69	5.31	5.92	6.53	7.12	7.71	8.29	8.86	9.41	9.97	10.51	11.04	11.56	12.58	14.03	15.38	17.04	19.77	0.12	0.75	1.07	1.32
2200	4.79	5.43	6.06	6.68	7.29	7.89	8.48	9.07	9.64	10.20	10.75	11.30	11.83	12.86	14.31	15.67	17.30	19.91	0.12	0.79	1.12	1.38
2300	4.87	5.53	6.18	6.82	7.44	8.06	8.67	9.26	9.84	10.42	10.98	11.53	12.06	13.10	14.56	15.90	17.50	19.95	0.13	0.83	1.17	1.44
2400	4.94	5.62	6.29	6.94	7.58	8.21	8.83	9.43	10.03	10.61	11.18	11.73	12.27	13.31	14.77	16.09	17.63	19.89	0.13	0.86	1.22	1.51
2500	5.01	5.70	6.38	7.05	7.70	8.35	8.97	9.59	10.19	10.78	11.35	11.91	12.45	13.49	14.94	16.23	17.71	19.73	0.14	0.90	1.28	1.57
2600	5.06	5.77	6.46	7.15	7.81	8.46	9.10	9.72	10.33	10.92	11.50	12.06	12.60	13.64	15.06	16.31	17.71	19.47	0.14	0.93	1.33	1.63
2																						

C-Section Power Rating

Table 1-17

small pulley speed (rpm)	Basic power rating for small pulley datum diameter : Hs									Additional power rating for speed ratio : Ha			
	Small pulley datum diameter (in)									Speed ratio			
	9.00	9.50	10.00	10.50	11.00	12.00	13.00	14.00	16.00	1.01 to 1.05	1.06 to 1.26	1.27 to 1.57	1.57<
700	9.93	10.88	11.83	12.77	13.70	15.52	17.32	19.07	22.46	0.09	0.58	0.84	1.03
950	12.48	13.70	14.90	16.08	17.24	19.51	21.71	23.83	27.83	0.12	0.80	1.14	1.40
1450	16.42	18.00	19.54	21.03	22.47	25.19	27.71	29.99	33.84	0.19	1.22	1.73	2.13
2850	17.07	18.11	18.86	19.31	-	-	-	-	-	0.37	2.40	3.41	4.19
50	1.07	1.16	1.25	1.34	1.43	1.60	1.78	1.95	2.30	0.01	0.04	0.06	0.07
100	1.96	2.13	2.25	2.46	2.63	2.96	3.29	3.62	4.27	0.01	0.08	0.12	0.15
150	2.77	3.02	3.26	3.51	3.75	4.23	4.71	5.18	6.12	0.02	0.13	0.18	0.22
200	3.54	3.86	4.18	4.50	4.81	5.43	6.05	6.67	7.88	0.03	0.17	0.24	0.29
250	4.28	4.67	5.06	5.45	5.83	6.59	7.35	8.10	9.57	0.03	0.21	0.30	0.37
300	4.99	5.45	5.91	6.36	6.81	7.71	8.59	9.47	11.21	0.04	0.25	0.36	0.44
350	5.67	6.20	6.72	7.24	7.76	8.79	9.80	10.81	12.79	0.05	0.29	0.42	0.51
400	6.34	6.93	7.52	8.10	8.68	9.84	10.98	12.10	14.32	0.05	0.34	0.48	0.59
450	6.98	7.64	8.29	8.94	9.58	10.85	12.11	13.36	15.79	0.06	0.38	0.54	0.66
500	7.60	8.32	9.04	9.75	10.45	11.84	13.22	14.57	17.23	0.07	0.42	0.60	0.74
550	8.21	8.99	9.76	10.53	11.30	12.81	14.29	15.75	18.61	0.07	0.46	0.66	0.81
600	8.80	9.64	10.47	11.30	12.12	13.74	15.33	16.90	19.94	0.08	0.51	0.72	0.88
650	9.37	10.27	11.16	12.04	12.92	14.65	16.34	18.00	21.23	0.08	0.55	0.78	0.96
700	9.93	10.88	11.83	12.77	13.70	15.52	17.32	19.07	22.46	0.09	0.59	0.84	1.03
750	10.47	11.48	12.48	13.47	14.45	16.38	18.26	20.10	23.65	0.10	0.63	0.90	1.10
800	11.00	12.06	13.11	14.15	15.18	17.20	19.17	21.09	24.78	0.10	0.67	0.96	1.18
850	11.51	12.62	13.73	14.82	15.89	18.00	20.05	22.04	25.85	0.11	0.72	1.02	1.25
900	12.00	13.17	14.32	15.46	16.58	18.77	20.90	22.96	26.87	0.12	0.76	1.08	1.32
950	12.48	13.70	14.90	16.08	17.24	19.51	21.71	23.83	27.83	0.12	0.80	1.14	1.40
1000	12.95	14.21	15.45	16.67	17.88	20.22	22.48	24.65	28.73	0.13	0.84	1.20	1.47
1050	13.40	14.70	15.99	17.25	18.49	20.90	23.22	25.44	29.57	0.14	0.88	1.26	1.54
1100	13.83	15.18	16.50	17.80	19.08	21.55	23.92	26.18	30.35	0.14	0.93	1.32	1.62
1150	14.25	15.64	17.00	18.34	19.64	22.17	24.58	26.87	31.06	0.15	0.97	1.38	1.69
1200	14.66	16.08	17.48	18.84	20.18	22.76	25.21	27.52	31.71	0.16	1.01	1.44	1.76
1250	15.04	16.50	17.93	19.33	20.69	23.31	25.79	28.12	32.28	0.16	1.05	1.50	1.84
1300	15.41	16.91	18.37	19.79	21.18	23.84	26.33	28.66	32.78	0.17	1.10	1.55	1.91
1350	15.77	17.29	18.78	20.23	21.64	24.32	26.83	29.16	33.21	0.18	1.14	1.61	1.99
1400	16.10	17.66	19.17	20.64	22.07	24.78	27.29	29.60	33.56	0.18	1.18	1.67	2.06
1450	16.42	18.00	19.54	21.03	22.47	25.19	27.71	29.99	33.84	0.19	1.22	1.73	2.13
1500	16.72	18.33	19.89	21.39	22.84	25.57	28.07	30.33	34.03	0.20	1.26	1.79	2.21
1550	17.01	18.64	20.21	21.73	23.18	25.92	28.40	30.60	34.14	0.20	1.31	1.85	2.28
1600	17.28	18.92	20.51	22.04	23.50	26.22	28.67	30.82	34.17	0.21	1.35	1.91	2.35
1650	17.52	19.19	20.79	22.32	23.78	26.49	28.90	30.98	34.11	0.22	1.39	1.97	2.43
1700	17.75	19.43	21.04	22.57	24.03	26.71	29.07	31.08	33.95	0.22	1.43	2.03	2.50
1750	17.96	19.65	21.26	22.80	24.25	26.90	29.19	31.11	33.71	0.23	1.47	2.09	2.57
1800	18.16	19.85	21.46	22.99	24.43	27.04	29.27	31.08	33.38	0.23	1.52	2.15	2.65
1850	18.33	20.03	21.64	23.16	24.58	27.14	29.28	30.98	32.94	0.24	1.56	2.21	2.72
1900	18.48	20.18	21.78	23.29	24.70	27.20	29.25	30.82	-	0.25	1.60	2.27	2.79
1950	18.61	20.31	21.91	23.40	24.78	27.21	29.16	30.59	-	0.25	1.64	2.33	2.87
2000	18.72	20.41	22.00	23.47	24.83	27.18	29.01	30.29	-	0.26	1.69	2.39	2.94
2050	18.81	20.50	22.06	23.51	24.84	27.10	28.80	29.91	-	0.27	1.73	2.45	3.02
2100	18.88	20.55	22.10	23.52	24.81	26.97	28.53	29.46	-	0.27	1.77	2.51	3.09
2150	18.93	20.58	22.11	23.50	24.75	26.79	28.20	28.94	-	0.28	1.81	2.57	3.16
2200	18.95	20.59	22.09	23.44	24.64	26.57	27.81	-	-	0.29	1.85	2.63	3.24
2250	18.95	20.57	22.04	23.35	24.50	26.29	27.36	-	-	0.29	1.90	2.69	3.31
2300	18.93	20.52	21.95	23.22	24.32	25.96	26.84	-	-	0.30	1.94	2.75</td	

D-Section Power Rating

Table 1-18

small pulley speed (rpm)	Basic power rating for small pulley datum diameter : Hs											Additional power rating for speed ratio : Ha			
	Small pulley datum diameter (in)											Speed ratio			
	13.00	13.50	14.00	14.50	15.00	15.50	16.00	17.00	18.00	20.00	22.00	1.01 to 1.05	1.06 to 1.26	1.27 to 1.57	1.57<
450	16.36	17.52	18.68	19.83	20.98	22.12	23.25	25.49	27.70	32.04	36.26	0.17	1.09	1.55	1.90
700	22.67	24.32	25.96	27.57	29.17	30.75	32.31	35.38	38.37	44.11	49.53	0.26	1.69	2.40	2.96
950	27.47	29.47	31.44	33.37	35.26	37.12	38.93	42.44	45.79	51.95	57.37	0.36	2.30	3.26	4.01
1450	31.82	34.00	36.07	38.03	39.87	41.59	43.18	46.00	48.28	51.14	-	0.54	3.51	4.98	6.12
20	1.16	1.23	1.30	1.37	1.44	1.51	1.57	1.71	1.85	2.12	2.39	0.01	0.05	0.07	0.08
40	2.13	2.26	2.40	2.53	2.66	2.79	2.92	3.18	3.44	3.95	4.46	0.01	0.10	0.14	0.17
60	3.03	3.23	3.42	3.61	3.80	3.99	4.18	4.55	4.93	5.67	6.41	0.02	0.15	0.21	0.25
80	3.89	4.14	4.39	4.64	4.88	5.13	5.38	5.87	6.35	7.32	8.28	0.03	0.19	0.27	0.34
100	4.71	5.02	5.32	5.63	5.93	6.23	6.53	7.13	7.73	8.91	10.09	0.04	0.24	0.34	0.42
120	5.50	5.87	6.23	6.59	6.94	7.30	7.66	8.36	9.07	10.47	11.85	0.04	0.29	0.41	0.51
140	6.27	6.69	7.10	7.52	7.93	8.34	8.75	9.56	10.37	11.98	13.57	0.05	0.34	0.48	0.56
160	7.02	7.49	7.96	8.43	8.89	9.35	9.81	10.73	11.65	13.46	15.25	0.06	0.39	0.55	0.68
180	7.76	8.28	8.80	9.32	9.83	10.35	10.86	11.88	12.89	14.90	16.89	0.07	0.44	0.62	0.76
200	8.47	9.04	9.62	10.19	10.75	11.32	11.88	13.00	14.12	16.32	18.50	0.07	0.48	0.69	0.84
220	9.17	9.80	10.42	11.04	11.66	12.27	12.88	14.10	15.32	17.71	20.08	0.08	0.53	0.76	0.93
240	9.86	10.53	11.20	11.87	12.54	13.21	13.87	15.19	16.49	19.08	21.63	0.09	0.58	0.82	1.01
260	10.53	11.25	11.98	12.70	13.41	14.12	14.84	16.25	17.65	20.42	23.16	0.10	0.63	0.89	1.10
280	11.19	11.96	12.73	13.50	14.27	15.03	15.79	17.29	18.79	21.74	24.65	0.10	0.68	0.96	1.18
300	11.84	12.66	13.48	14.29	15.11	15.91	16.72	18.32	19.90	23.04	26.12	0.11	0.73	1.03	1.27
320	12.47	13.34	14.21	15.07	15.93	16.79	17.64	19.33	21.00	24.31	27.56	0.12	0.77	1.10	1.35
340	13.10	14.02	14.93	15.84	16.74	17.65	18.54	20.32	22.08	25.56	28.97	0.13	0.82	1.17	1.44
360	13.71	14.68	15.64	16.59	17.54	18.49	19.43	21.30	23.14	26.79	30.36	0.13	0.87	1.24	1.52
380	14.32	15.33	16.33	17.33	18.33	19.32	20.30	22.26	24.19	27.99	31.72	0.14	0.92	1.30	1.60
400	14.91	15.97	17.02	18.06	19.10	20.13	21.16	23.20	25.21	29.18	33.05	0.15	0.97	1.37	1.69
420	15.50	16.60	17.69	18.78	19.86	20.94	22.01	24.13	26.22	30.34	34.35	0.16	1.02	1.44	1.77
440	16.07	17.22	18.35	19.48	20.61	21.73	22.84	25.04	27.21	31.47	35.63	0.16	1.06	1.51	1.86
460	16.64	17.82	18.90	20.18	21.34	22.50	23.65	25.93	28.18	32.59	36.88	0.17	1.11	1.58	1.94
480	17.19	18.42	19.64	20.86	22.06	23.26	24.45	26.81	29.13	33.68	38.10	0.18	1.16	1.65	2.03
500	17.74	19.01	20.27	21.53	22.77	24.01	25.24	27.67	30.07	34.75	39.29	0.19	1.21	1.72	2.11
520	18.27	19.59	20.89	22.19	23.47	24.75	26.01	28.52	30.98	35.80	40.45	0.19	1.26	1.79	2.20
540	18.80	20.15	21.50	22.83	24.16	25.47	26.77	29.35	31.88	36.82	41.59	0.20	1.31	1.85	2.28
560	19.32	20.71	22.09	23.47	24.83	26.18	27.52	30.16	32.76	37.82	42.69	0.21	1.35	1.92	2.36
580	19.82	21.26	22.68	24.09	25.49	26.87	28.25	30.96	33.62	38.79	43.76	0.22	1.40	1.99	2.45
600	20.32	21.79	23.25	24.70	26.13	27.55	28.96	31.74	34.46	39.74	44.80	0.22	1.45	2.06	2.53
620	20.81	22.32	23.82	25.30	26.77	28.22	29.66	32.50	35.28	40.67	45.81	0.23	1.50	2.13	2.62
640	21.29	22.84	24.37	25.88	27.39	28.87	30.35	33.24	36.08	41.57	46.79	0.24	1.55	2.20	2.70
660	21.76	23.34	24.91	26.46	27.99	29.51	31.02	33.97	36.86	42.44	47.74	0.25	1.60	2.27	2.79
680	22.22	23.84	25.44	27.02	28.59	30.14	31.67	34.68	37.63	43.29	48.65	0.25	1.65	2.34	2.87
700	22.67	24.32	25.96	27.57	29.17	30.75	32.31	35.38	38.37	44.11	49.53	0.26	1.69	2.40	2.96
720	23.11	24.80	26.46	28.11	29.74	31.35	32.93	36.05	39.09	44.91	50.37	0.27	1.74	2.47	3.04
740	23.54	25.26	26.96	28.64	30.29	31.93	33.54	36.71	39.79	45.67	51.18	0.28	1.79	2.54	3.12
760	23.97	25.71	27.44	29.15	30.83	32.50	34.14	37.35	40.47	46.41	51.95	0.28	1.84	2.61	3.21
780	24.38	26.16	27.91	29.65	31.36	33.05	34.71	37.97	41.12	47.12	52.68	0.29</			

E-Section Power Rating

Table 1-19

small pulley speed (rpm)	Basic power rating for small pulley datum diameter : Hs												Additional power rating for speed ratio : Ha			
	Small pulley datum diameter (in)												Speed ratio			
	17.70	19.70	22.00	24.80	26.40	28.00	29.50	31.50	33.50	35.40	37.40	39.40	1.01 to 1.05	1.06 to 1.26	1.27 to 1.57	1.57 <
450	31.13	37.13	43.83	51.70	56.04	60.28	64.14	69.14	73.94	78.32	82.73	86.93	0.26	1.87	2.65	3.26
700	42.19	50.16	58.76	68.36	73.39	78.07	82.12	87.00	91.24	94.66	97.58	99.78	0.45	2.90	4.12	5.07
950	48.92	57.54	66.17	74.68	78.48	81.45	83.45	84.87	-	-	-	-	0.61	3.94	5.59	6.88
1450	45.99	50.27	-	-	-	-	-	-	-	-	-	-	0.93	6.01	8.54	10.50
20	2.20	2.57	2.99	3.50	3.79	4.08	4.35	4.71	5.07	5.40	5.76	6.11	0.01	0.08	0.12	0.14
40	4.05	4.76	5.56	6.53	7.08	7.63	8.14	8.81	9.49	10.12	10.79	11.45	0.03	0.17	0.24	0.29
60	5.78	6.80	7.97	9.37	10.17	10.96	11.70	12.68	13.65	14.57	15.54	16.50	0.04	0.25	0.35	0.43
80	7.42	8.75	10.27	12.09	13.13	14.16	15.12	16.39	17.65	18.84	20.09	21.34	0.05	0.33	0.47	0.58
100	9.00	10.63	12.49	14.72	15.99	17.24	18.42	19.97	21.52	22.97	24.50	26.01	0.06	0.41	0.59	0.72
120	10.53	12.45	14.64	17.27	18.76	20.24	21.62	23.45	25.27	26.98	28.77	30.55	0.08	0.50	0.71	0.87
140	12.01	14.22	16.73	19.75	21.46	23.16	24.74	26.84	28.92	30.87	32.92	34.95	0.09	0.58	0.82	1.01
160	13.45	15.94	18.77	22.17	24.10	26.01	27.79	30.14	32.47	34.67	36.96	39.23	0.10	0.66	0.94	1.16
180	14.85	17.62	20.77	24.54	26.67	28.79	30.76	33.36	35.94	38.36	40.89	43.39	0.12	0.75	1.06	1.30
200	16.23	19.26	22.72	26.85	29.19	31.51	33.66	36.50	39.31	41.96	44.71	47.43	0.13	0.83	1.18	1.45
220	17.57	20.87	24.62	29.12	31.65	34.16	36.49	39.57	42.60	45.46	48.42	51.35	0.14	0.91	1.30	1.59
240	18.88	22.45	26.49	31.33	34.06	36.75	39.26	42.56	45.81	48.86	52.03	55.15	0.15	1.00	1.41	1.74
260	20.17	23.99	28.32	33.50	36.41	39.29	41.96	45.47	48.93	52.17	55.53	58.83	0.17	1.08	1.53	1.88
280	21.43	25.50	30.11	35.62	38.71	41.76	44.59	48.31	51.96	55.38	58.91	62.38	0.18	1.16	1.65	2.03
300	22.66	26.98	31.87	37.69	40.95	44.17	47.15	51.06	54.90	58.49	62.18	65.81	0.19	1.24	1.77	2.17
320	23.87	28.43	33.58	39.71	43.14	46.53	49.65	53.75	57.76	61.49	65.34	69.10	0.21	1.33	1.88	2.32
340	25.05	29.85	35.26	41.69	45.28	48.82	52.08	56.35	60.52	64.39	68.37	72.25	0.22	1.41	2.00	2.46
360	26.21	31.24	36.90	43.62	47.36	51.05	54.44	58.87	63.18	67.18	71.28	75.26	0.23	1.49	2.12	2.61
380	27.35	32.60	38.51	45.50	49.39	53.21	56.72	61.30	65.75	69.86	74.06	78.13	0.24	1.58	2.24	2.75
400	28.46	33.93	40.08	47.33	51.36	55.31	58.94	63.65	68.22	72.43	76.71	80.84	0.26	1.66	2.36	2.90
420	29.55	35.24	41.61	49.12	53.28	57.35	61.08	65.91	70.59	74.88	79.23	83.40	0.27	1.74	2.47	3.04
440	30.61	36.51	43.10	50.85	55.14	59.32	63.14	68.09	72.85	77.21	81.60	85.79	0.28	1.83	2.59	3.19
460	31.65	37.75	44.55	52.53	56.93	61.22	65.13	70.17	75.01	79.41	83.83	88.02	0.30	1.91	2.71	3.33
480	32.67	38.96	45.97	54.16	58.67	63.05	67.03	72.15	77.05	81.48	85.91	90.08	0.31	1.99	2.83	3.48
500	33.66	40.14	47.34	55.74	60.35	64.81	68.86	74.04	78.98	83.42	87.83	91.96	0.32	2.07	2.94	3.62
520	34.63	41.29	48.68	57.26	61.96	66.49	70.60	75.83	80.79	85.22	89.60	93.66	0.33	2.16	3.06	3.76
540	35.57	42.40	49.97	58.73	63.51	68.10	72.25	77.52	82.48	86.89	91.21	95.17	0.35	2.24	3.18	3.91
560	36.48	43.49	51.22	60.14	64.99	69.64	73.82	79.10	84.04	88.41	92.64	96.49	0.36	2.32	3.30	4.05
580	37.38	44.54	52.43	61.50	66.40	71.09	75.29	80.57	85.48	89.78	93.91	97.60	0.37	2.41	3.41	4.20
600	38.24	45.56	53.60	62.80	67.75	72.47	76.67	81.94	86.79	91.00	94.99	98.51	0.38	2.49	3.53	4.34
620	39.09	46.55	54.72	64.03	69.02	73.76	77.96	83.19	87.96	92.06	95.89	99.21	0.40	2.57	3.65	4.49
640	39.90	47.50	55.80	65.21	70.23	74.97	79.15	84.32	89.00	92.96	96.61	99.70	0.41	2.65	3.77	4.63
650	40.30	47.97	56.32	65.78	70.80	75.54	79.71	84.84	89.46	93.35	96.60	99.85	0.42	2.70	3.83	4.71
680	41.45	49.31	57.82	67.38	72.41	77.13	81.23	86.23	90.64	94.27	97.46	99.99	0.44	2.82	4.00	4.92
700	42.19	50.16	58.76	68.36	73.39	78.07	82.12	87.00	91.24	94.66	97.58	99.78	0.45	2.90	4.12	5.07
720	42.89	50.97	59.65	69.28	74.29	78.92	82.90	87.64	91.69	94.88	97.50	99.33	0.46	2.99	4.24	5.21
740	43.57	51.7														

■ Length Measurement

The V-Belt is laid over two equal size pulleys as following figure. These pulley grooves are designed to correspond with the belt section specified in Table 1-21. The measuring force is added to the measuring pulley in such a way. Belt length is calculated by the formula which is specified in Table 1-20.

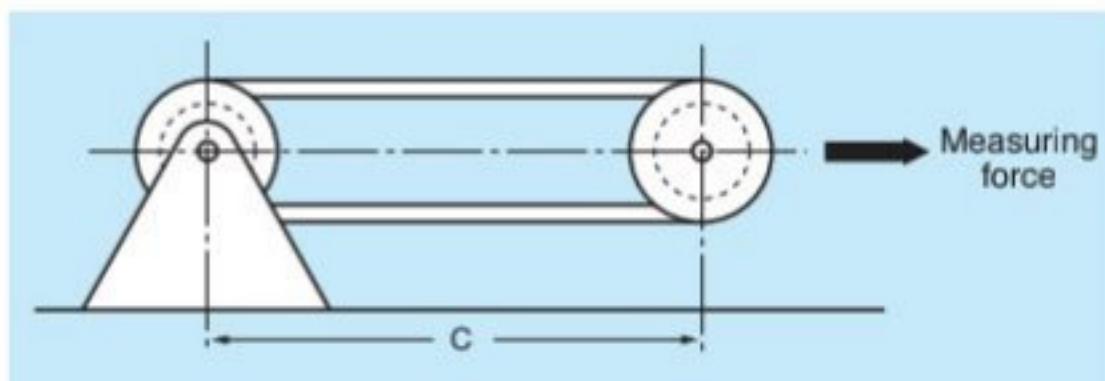


Fig. 1-4 Diagram of fixture for length measurement

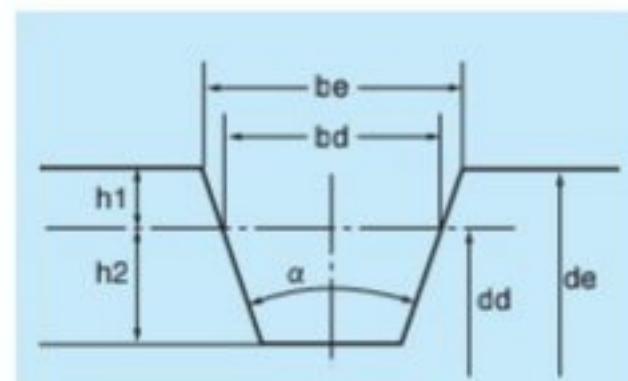


Fig. 1-5 Measuring pulley

Length calculation formula

Table 1-20

	Belt section	Length designation	Length calculation formula
V-Belt	A	Ld - 1.3"	$Ld = 2C + \pi dd$
	B (~ 210")	Ld - 1.8"	
	B (211" ~)	Ld - 0.3"	
	C (~ 210")	Ld - 2.9"	
	C (211" ~)	Ld - 0.9"	
	D (~ 210")	Ld - 3.3"	
	D (211" ~)	Ld - 0.8"	
	E (~ 210")	Ld - 4.5"	
	E (211" ~)	Ld - 1.0"	

■ Pulley Dimensions

Pulley dimensions and measuring force of V-Belts

Table 1-21

Belt section	A	B	C	D	E
Datum width : bd inch	0.418	0.530	0.757	1.076	1.267
Effective width : be inch	0.494	0.637	0.879	1.259	1.527
Datum diameter : dd inch	3.888	5.380	7.558	12.132	18.299
Effective diameter : de inch	4.138	5.730	7.958	12.732	19.099
Pulley datum circumference : πdd inch	12.214	16.902	23.744	38.114	57.487
Pulley effective circumference : πde inch	13.000	18.000	25.000	40.000	60.000
Angle : α °	34	34	34	34	36
Distance down to datum line : h1 inch	0.125	0.175	0.200	0.300	0.400
Measuring force pound	50	65	165	300	400

Belt weight per unit : W & Constant : Y

Table 1-22

Belt Section	W (kg/m)	Y (lb/pc)
A	0.12	3.3
B	0.20	4.4
C	0.30	6.6
D	0.65	13.2
E	1.00	24.3

Formulas for V-Belt Drives Design

Table 1-23

Item	Formula	Term
Design power	$H_d = H_t \times K_s$	H_d : Design power (hp) H_t : Transmission power (hp) K_s : Service factor
Service factor	$K_s = K_o + K_i + K_e$	K_s : Service factor K_o : Service correction factor K_i : Idler correction factor K_e : Environment correction factor
Power rating	$H_r = H_s + H_a$	H_r : Power rating (hp) H_s : Basic power rating (hp) H_a : Additional power rating for speed ratio (hp)
Correction power rating	$H_c = H_r \times K_l \times K_\theta$	H_c : Correction power rating (hp) H_r : Power rating (hp) K_l : Belt length correction factor K_θ : Arc of contact correction factor
Speed ratio	$SR = \frac{n_d}{n_D} = \frac{D_d}{d_d}$	SR : Speed ratio n_d : Small pulley speed (rpm) n_D : Large pulley speed (rpm) D_d : Large pulley datum diameter (in) d_d : Small pulley datum diameter (in)
Interim belt datum length	$L_d' = 2C' + 1.57(D_d + d_d)$	L_d' : Interim belt datum length (in) C' : Interim center distance (in) D_d : Large pulley datum diameter (in) d_d : Small pulley datum diameter (in)
Interim belt datum length	$L_d' = 2C + \frac{\pi(D_d + d_d)}{2} + \frac{(D_d - d_d)^2}{4C}$	* If center distance C is predetermined: L_d' : Interim belt datum length (in) C : Center distance (in) D_d : Large pulley datum diameter (in) d_d : Small pulley datum diameter (in) π : 3.1416
Center distance	$C = \frac{b + \sqrt{b^2 - 8(D_d - d_d)^2}}{8}$ $b = 2L_d - \pi(D_d + d_d)$	C : Center distance (in) D_d : Large pulley datum diameter (in) d_d : Small pulley datum diameter (in) L_d : Effective length (in) π : 3.1416
Arc of contact	$\theta = 180^\circ - \frac{57.3(D_d - d_d)}{C}$	θ : Arc of contact for small pulley ($^\circ$) D_d : Large pulley datum diameter (in) d_d : Small pulley datum diameter (in) C : Center distance (in)
Number of belts	$n_b = \frac{H_d}{H_c}$	n_b : Number of belts H_d : Design power (hp) H_c : Correction power rating (hp)

Table 1-24

Item	Formula	Term
Belt speed	$V = \frac{dd \times nd}{3.82}$	V : Belt speed (ft/min.) dd : Small pulley datum diameter (in) nd : Small pulley speed (rpm)
Transmission power	$Ht = \frac{Te \times V}{33000}$	Ht : Transmission power (hp) Te : Effective tension (lb) V : Belt speed (ft/min.)
Transmission power	$Ht = \frac{Tq \times n}{63025}$	Ht : Transmission power (hp) Tq : Torque (lb-in) n : Pulley speed (rpm)
Effective tension	$Te = \frac{2Tq}{dd}$	Te : Effective tension (lb) Tq : Torque (lb-in) dd : Small pulley datum diameter (in)
Effective tension	$Te = \frac{33000 \times Ht}{V}$	Te : Effective tension (lb) Ht : Transmission power (hp) V : Belt speed (ft/min.)
Torque	$Tq = Te \times \frac{dd}{2}$	Tq : Torque (lb-in) Te : Effective tension (lb) dd : Small pulley datum diameter (in)
Tight side tension	$Tt = \frac{33000 \times Hd}{nb \times V} \times \frac{2.5}{2 \times K\theta} + W \times V^2 \times 5.8 \times 10^{-6}$	Tt : Tight side tension (lb) Hd : Design power (hp) nb : Number of belts V : Belt speed (ft/min.) Kθ : Arc of contact correction factor W : Belt weight per unit (kg/m)
Slack side tension	$Ts = \frac{33000 \times Hd}{nb \times V} \times \frac{2.5 - 2 \times K\theta}{2 \times K\theta} + W \times V^2 \times 5.8 \times 10^{-6}$	Ts : Slack side tension (lb) Hd : Design power (hp) nb : Number of belts V : Belt speed (ft/min.) Kθ : Arc of contact correction factor W : Belt weight per unit (kg/m)
Tension ratio	$TR = \frac{Tt}{Ts}$	TR : Tension ratio Tt : Tight side tension (lb) Ts : Slack side tension (lb)
Minimum static tension	$To = 0.9 \times \frac{Tt + Ts}{2}$ $= 0.9 \times \left\{ \frac{33000 \times Hd}{nb \times V} \times \frac{2.5 - K\theta}{2 \times K\theta} + W \times V^2 \times 5.8 \times 10^{-6} \right\}$	To : Minimum static tension (lb) Kθ : Arc of contact correction factor Hd : Design power (hp) nb : Number of belts V : Belt speed (ft/min.) W : Belt weight per unit (kg/m)
Static shaft load	$Fs = 1.5 (2nb \times To \times \sin \frac{\theta}{2})$	Fs : Static shaft load (lb) nb : Number of belts To : Minimum static tension (lb) θ : Arc of contact for small pulley (°)
Span length	$Ls = \sqrt{C^2 - \frac{(Dd - dd)^2}{4}}$	Ls : Span length (in) C : Center distance (in) Dd : Large pulley datum diameter (in) dd : Small pulley datum diameter (in)

Calculation Example for V-Belt Drive Design

1

Set conditions required in design work.

- a. Type of machine … Compressor
- b. Transmission power … Four pole motor 5 hp/1750rpm
- c. Running hours in a single day … 8 hours / day
- d. Small pulley speed … 1750rpm

- e. Speed ratio … 2 : 1 (Deceleration)
- f. Interim center distance … 12"
- g. Special uses and environmental conditions … None

2

Set the design power.

Service correction factor : $K_o = 1.3$ (Table 1-1)
Idler correction factor : $K_i = 0$ (Table 1-2)
Environment correction factor : $K_e = 0$ (Table 1-3)
Service factor : $K_s = K_o + K_i + K_e$
 $= 1.3 + 0 + 0$
 $= 1.3$
Design power : $H_d = H_t \times K_s$
 $= 5 \times 1.3$
 $= 6.5 \text{ hp}$

5

Determine the belt length.

1) Determine the interim belt datum length.

$$L_d' = 2 \times 12 + 1.57 \times (6.00 + 3.00) = 38.1"$$

2) Select the standard belt length closest to the L_d' from Table 1-9.

Belt datum length 38.3": Length designation A37 is selected.

Center distance is calculated as follows.

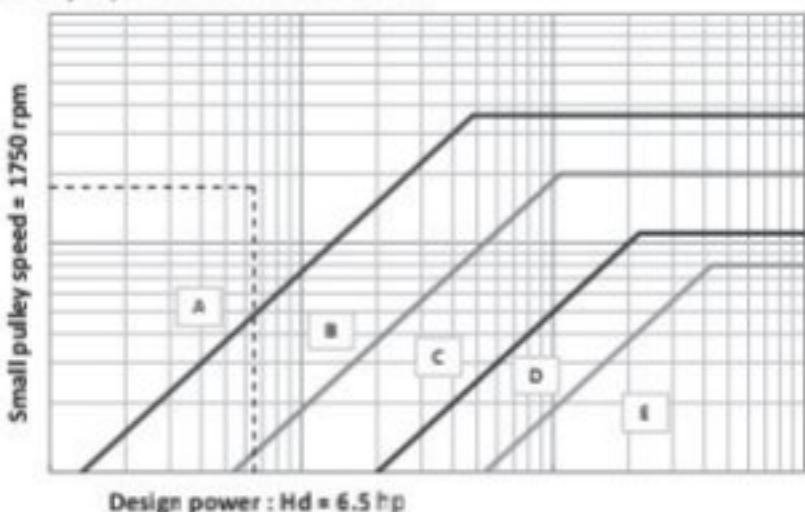
$$b = 2 \times 38.3 - 3.14 \times (6.00 + 3.00) = 48.3$$
$$C = \frac{48.3 + \sqrt{48.3^2 - 8 \times (6.00 + 3.00)^2}}{8} = 12.0$$

Center distance : $C = 12.0"$

3

Select the belt type.

Select the belt type in Cross section selection chart.
The lines of H_d (6.5 hp) and small pulley speed
(1750rpm) intersect in A section.



6

Determine the required number of belts.

$H_s = 1.68 \text{ hp}$ (Refer to Power Rating Table 1-15)
 $H_a = 0.50 \text{ hp}$ (Refer to Power Rating Table)
 $\frac{D_d - d_d}{C} = \frac{6.00 - 3.00}{12.0} = 0.25$
 $K_\theta = 0.96$ (Refer to Table 2-6).
 $K_\ell = 0.89$ (Refer to Table 2-7).
 $K_c = K_\theta \times K_\ell = 0.96 \times 0.87 = 0.84$
 $H_c = (H_s + H_a) \times K_c = (1.68 + 0.50) \times 0.84 = 1.83 \text{ hp}$
 $n_b = \frac{H_d}{H_c} = \frac{6.5}{1.83} = 3.6 \rightarrow 4 \text{ pcs.}$

4

Select the pulley size.

- 1) Select the small pulley of 3.00" datum diameter.
(The recommended minimum pulley datum diameter is specified in Table 1-4.)
- 2) Calculate the large pulley datum diameter.

$$\begin{aligned}\text{Large pulley datum diameter : } D_d &= d_d \times SR \\ &= 3.00 \times 2 \\ &= 6.00"\end{aligned}$$

7

Installation and take-up allowance.

Installation and take-up allowance are obtained from Table 1-8.
Installation allowance = 0.75"
→ Minimum center distance = $12.0 - 0.75 = 11.25"$
Take-up allowance = 1.50"
→ Maximum center distance = $12.0 + 1.5 = 13.5"$