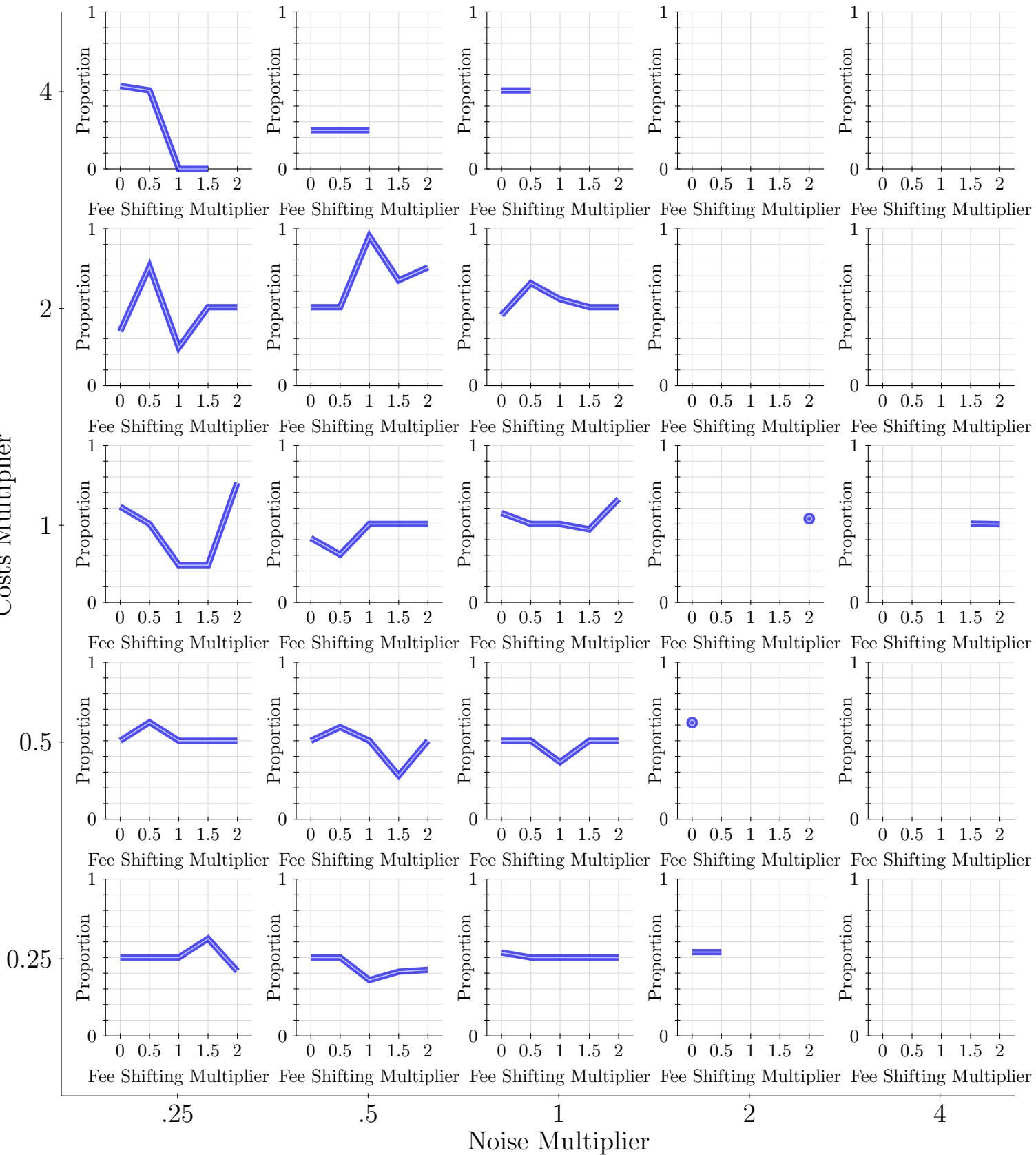


Costs Multiplier



Noise Multiplier

P Win Probability