

# CS 451 – Operating Systems

## Lab 04 Assignment

**Due: 11:59 PM on Tuesday, 18 August 2020**

**You are to submit your files, to the Lab 4 folder on Blackboard by the due date and time.**

### Objective

- To understand priority scheduling and implementing priority scheduling mechanism in xv6
- Add a priority attribute to a process in xv6
- Change a priority of a process

**Note: This lab is an extension of Lab 4 (In order to finish this lab, you have to complete lab 4)**

### Implement Priority Scheduling

1. Default priority value of a process is 10
2. The smaller the priority value the higher the priority
3. Modify the **scheduler()** routine inside the proc.c to implement the priority scheduler

Below are the steps to follow:

1. Add priority to struct proc in proc.h

```
int priority; // Process priority
```

2. Assign default priority in allocproc() routine in proc.c (you have to place in the appropriate location)

```
p->priority = 10; //default priority
```

3. If a process is loaded from the shell, make it high priority. This change should be made in exec.c. After line 101 add the following.

```
curproc->priority = 3;
```

4. Modify **procStat** in proc.c discussed in the last lab to include the printout of the priority like the following

Name	ProcID	State	Priority
init	1	SLEEPING	3
sh	2	SLEEPING	3
ps	27	RUNNING	3

5. Write a user program named **tester.c** that creates some child processes and consumes some computing time. The parent should be always waiting. The child should compute some useless calculations such as following:

```
for ( i = 0; i < 8000000.0; i += 0.01 )
    x = x + 3.14 * 89.64;
```

Remember this is a user file, hence you will be required to modify the Makefile. (**Refer to the previous lab**)

6. Add the function `chpr()` (meaning change priority) in `proc.c`

```
//change priority
int
chpr( int pid, int priority )
{
    struct proc *p;


    acquire(&ptable.lock);
    for(p = ptable.proc; p < &ptable.proc[NPROC]; p++){
        if(p->pid == pid ) {
            p->priority = priority;
            break;
        }
    }
    release(&ptable.lock);

    return pid;
}
```

7. Add `sys_chpr()` in `sysproc.c`

```
int
sys_chpr (void)
{
    int pid, pr;
    if(argint(0, &pid) < 0) // built-in functions for passing
                            // arguments into a kernel function
        return -1;
    if(argint(1, &pr) < 0)
        return -1;

    return chpr ( pid, pr );
}
```

8. Add `chpr()` as a system call to `xv6` as discussed in the previous lab (Refer to the previous lab manual)
9. Add the user file `chngp.c` (provided) which calls `chpr`. Remember this is a user file, hence you will be required to modify the Makefile. (**Refer to the previous lab**)
10. Also make sure the number of CPU's used is 2. (Look into makefile)
11. Test `chngp` using `tester` by creating a few process in the background and use `ps` command to check the process states and priority. Your output should look something like below: (**run tester always as daemons**  )

```
$ tester 4 &
```

```
$ ps
```

Name	ProcID	State	Priority
init	1	SLEEPING	3
sh	2	SLEEPING	3
tester	7	RUNNING	10
tester	6	SLEEPING	3
ps	8	RUNNING	3

12. Change the priority of a process using `chngp` and check the status using `ps` again

```
$ chngp 7 5
```

```
$ ps
```

Name	ProcID	State	Priority
init	1	SLEEPING	3
sh	2	SLEEPING	3
tester	7	RUNNING	5
tester	6	SLEEPING	3
ps	11	RUNNING	3

13. Observe the default round-robin (RR) scheduling by creating a few `tester` processes in the background and running `ps` a few times at random time intervals in `xv6`

```
$ tester & tester & tester &
```

You can observe that the three `tester` child processes are running alternately while the parents are sleeping.

## Implement Priority Scheduling.

1. Modify the scheduler function in `proc.c` to select the highest priority runnable process. The code skeleton is provided (**scheduler**) with few comments. Modify the code and implement the priority scheduling.
2. **Observe the priority scheduling.**
  - a. Run xv6 with the scheduler and again use `tester` and `ps` to see how it works. Use `chngp` to change the priority of a process. If you have implemented your program correctly, you should observe that the lower priority process is always in running state.

## What to turn in

- Compress the parent folder (xv6) along with your created files, to zip and upload the zipped folder.
- A README file specifying the changes you made including a brief description of the implemented scheduling mechanism, the user command and the system call.