

C++

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1 Basics

We define a bunch of terms. This may seem unnecessary, but it becomes very useful when getting into the weeds of C++.

Definition 1.1 (Variables)

1. A **literal** is a value that is directly inserted into code, e.g. 5, 3.2, 'a'.^a
 2. A **variable** can be assigned to a literal, e.g. `x`.
 3. The **identifier** is simply the name of the variable, and its **linkage** determines whether a declaration of that same identifier in a different scope refers to the same object.
 4. An **operation** consists of an **operator** (+) and one or more **operands** (3, 4.3).
 5. An **expression** is simply a line of code containing variables, operations, and literals, e.g. `int x = 3 + 4;`
 6. The process of executing an expression is called **evaluation**.
- Variables can be **constructed** in two ways.

1. We first **declare** a variable, which tells the compiler about the existence of the variable (`int x;`). Then, we can **define** the variable, which assigns it a literal (`x = 4;`).
2. We can **initialize** a variable, which both declares it and defines it at once (`int x = 4;`).

Definition 1.2 (Functions)

1. The **declaration** of a function states the existence of the function.

```
1 double foo(int x, double y); // one way
2 double foo(int, double); // another way
```

This declaration is also called the **function prototype**, or the **function identifier**.

2. The **definition** of a function tells us the actual implementation.

```
1 double foo(int x, double y) {
2     ...
3 }
```

1.1 Scope

Definition 1.3 (Scope)

The **scope** of an identifier refers to where it is accessible by. The **duration** of an identifier governs how it will be constructed and destroyed, over its **lifetime**. There are two types of variables, **local variables** and **global variables**.

1.1.1 Local Variables

Definition 1.4 (Local Variables)

Local variables are variables constructed inside a block scope.

1. They have **automatic duration**, which means that their lifetime begins at the start of the block (at {) and is destroyed at the end of the block }.

^aUsually, using literals by themselves such as `return 4;` should be avoided since the reader can't determine what it represents through the identifier name. We must resort to a comment or external documentation.

Example 1.1 (Automatic Duration)

You can see that every block contains its own scope with its own local variables. When the block ends all variables in this block are destroyed on the stack.

```
1  int main() {
2      int x = 2;
3      std::cout << x << std::endl; // 2
4      {
5          int y = 1;
6          std::cout << x << std::endl; // 2
7          std::cout << y << std::endl; // 1
8      }
9      return 0;
10 }
```

Example 1.2 (Accessing Parent Block Scope)

Local variables in a nested block have access to the parent block's scope. Both of these programs are valid. The left accesses the parent block's `x` while the right one access `x` newly created in the local scope.

```
1  int main() {
2      int x = 2;
3      for (int i = 0; i < 10; i++) {
4          x += 1;
5      }
6      std::cout << x << std::endl; // 12
7      return 0;
8  }
9  .
```

```
1  int main() {
2      int x = 2;
3      for (int i = 0; i < 10; i++) {
4          int x = 1;
5          x += 1;
6      }
7      std::cout << x << std::endl; // 2
8      return 0;
9  }
```

Example 1.3 (Variable Shadowing)

You can see that the `x` is initialized in the `main()` block scope, but it gets “shadowed” by the `x` in the nested block. Once the block terminates, then it is “revealed” again.

```
1  int main() {
2      int x = 2;
3      std::cout << x << std::endl; // 1
4      {
5          int x = 1;
6          std::cout << x << std::endl; // 1
7      }
8      std::cout << x << std::endl; // 2
9      return 0;
10 }
```

1.1.2 Global Variables

Definition 1.5 (Global Variables)

Global variables are constructed outside of the main function, in the global namespace.

1. They have **static duration**, which means they are created when the program starts (before `main()`) and destroyed when it ends.
2. Usually it is preferred to define global variables in a namespace. If not, many developers prefer the prefix global variable identifiers with `g` or `g_` to indicate that they are global and do not have naming conflicts.
3. Unlike local variables, which are uninitialized by default, variables with static duration are 0-initialized by default (e.g. `int g_x;` is really `int g_x = 0;`).

Just like local variables, global variables can be `const` as well, and like all `const` variables, must be initialized.

2 Translation

Translating C++ code to a binary consists of multiple steps:

1. Preprocessing the code.
2. Compiling each file independently.
3. Linking all the files.

Conventionally, all of these are called *compiling*, but it really isn't.

2.1 Preprocessing

When preprocessing, we do some boring stuff like removing comments. However, the main job is to take care of **preprocessing directives**, which are expressions with the `#` symbol. The most obvious is the `#include` directives, which **replaces the include directive with the contents of the included file**. That is, `#include` is really just a way to substitute code.

1. including with angle brackets, e.g. `#include <iostream>`, means that the compiler is looking for this file in the standard library files.
2. including with double quotes, e.g. `#include "tensor.h"`, means that the compiler is looking for this file locally in your project directory. It means you've written it.

Other directives is the `#define` directive.

1. You can define it to substitute text. It is conventionally in all upper-case.

```
1 #define NAME "Muchang" // all instances of NAME will be replaced with "Muchang"
```

2. Or you can define it without substitution text, where further occurrences of `NAME` will be replaced by nothing.

```
1 #define NAME
```

The second isn't used for substitution, but rather for **conditional compilation**, which can be useful. You just wrap C++ statements around as such.

```
1 #ifdef NAME
2 ...
3 #endif
```

```
1 #ifndef NAME
2 ...
3 #endif
```

To see the output after preprocessing, use the `-E` flag.

```
1 g++ main.cpp -E
```

2.2 Compilation

We only compile files one at a time and independently. When the compiler compiles a file, it goes through each line sequentially. Therefore, we must ensure that all functions/variables/classes are *declared* first before they are called. *Forward declaration* makes this a lot easier.

There is a difference between a declaration and a definition.

Definition 2.1 (ODR)

Remember the ODR (One Definition Rule):

1. Within a file, each function, variable, type, or template in a given scope can only have one definition. Definitions occurring in different scopes (e.g. local variables defined inside different functions, or functions defined inside different namespaces) do not violate this rule.
2. Within a program, each function or variable in a given scope can only have one definition.^a

To be honest, ODR 2 really implies ODR 1, since once the directives are preprocessed or the object files are linked, we are really left with one executable file.

Example 2.1 (ODR 1 Violation)

The following shows that in the same file, there are multiple variables defined in the function scope of `main`, and there are two definitions of `foo` in the global scope.

<pre>1 int main() { 2 int x; 3 int x; 4 5 return 0; 6 } 7 .</pre>	<pre>1 int foo() { return 5; } 2 int foo() { return 5; } 3 4 int main() { 5 std::cout << foo(); 6 return 0; 7 }</pre>
---	---

Example 2.2 (ODR 2 Violation)

Say that `main.cpp` has the `main()` method that calls on `int add(int x, int y)`, which is forward declared. However, say that we define `add` in two places.

<pre>1 // foo.cpp 2 int add(int x, int y) { 3 return x + y; 4 }</pre>	<pre>1 // bar.cpp 2 int add(int x, int y) { 3 return x + y; 4 }</pre>
---	---

Then, if we run `g++ main.cpp foo.cpp bar.cpp`, the linker will complain that there is a function redefinition.

2.3 Linking

Remember, declaration is not the same thing as definition. When we do the linking, we go through all the source files in our project and match all the declarations with our definitions. The source files must all be

^aThis rule exists because programs can have more than one file. For example, if you have two definitions of `int add(int, int)` in two different files, the linker does not know which one to connect the declaration to.

written in the compile command.

```
1 g++ main.cpp add.cpp
2 g++ add.cpp main.cpp
```

This should not be order dependent. The source files can be

```
1 // main.cpp
2 int add(int x, int y); // declaration
3
4 int main() {
5     int z = add(2, 3);
6     return 0;
7 }
```

```
1 // add.cpp
2 // definition
3 int add(int x, int y) {
4     return x + y;
5 }
6 .
7 .
```

2.4 Header Files

To be honest, we can just include forward declarations everywhere, but this does not scale well to large projects. If we had a set of declarations that we wanted to use over a bunch of files, we can package them nicely using a **header file**.

If we have a bunch of functions and classes written in `foo.cpp`, then it is conventional to write a `foo.h` that contains all the declarations of these expressions. Then, whenever we need to write a new file `bar.cpp` that uses functions from `foo.cpp`, we can just `#include "foo.h"`, which replaces this directive (by the preprocessor) with all the forward declarations in `foo.h`. Boom easy.

```
1 // add.cpp
2 int add(int x, int y) {
3     return x + y;
4 }
```

```
1 // add.h
2 int add(int x, int y);
3 .
4 .
```

Therefore when we call `add` in `main.cpp`, we can just `#include "add.h"` to put in the declarations, making everything good. Conventionally, it is best practice for a source file to also include its paired header (e.g. `add.cpp` should also contain `#include "add.h"` at the top). This allows the compiler to discover inconsistencies between the two files, and this extra cost is negligible.¹

Example 2.3 (Definitions inside Header Files)

You should not add definitions (only declarations) to header files since if they are included in multiple header files, then we would have different definitions of the same function, leading to ODR 2 violation. Take a look at the following.

```
1 // square.h
2 int getSquareSides() {
3     return 4;
4 }
```

```
1 // wave.h
2 #include "square.h"
```

With the following.

```
1 #include "square.h"
2 #include "wave.h"
3 int main() {
4     return 0;
5 }
```

¹<https://www.learncpp.com/cpp-tutorial/cpp-faq/#pairedheader>

This won't compile since

1. by including `square.h`, we have defined `getSquareSides()` in the global scope of `main.cpp`.
2. by including `wave.h`, we have included `square.h` which then substitutes this line with the definition of `getSquareSides()` again.

This is an ODR 1 violation.

The simple fix to the above is to just remove the `#include "wave.h"`, but what if we needed some other function from `wave.h`? Resolving this issue is not trivial if say, half of the functions in `square.h` is needed in `wave.h` and the other half is needed in `main.cpp`. We must include both of them in `main.cpp`, but then we have an inevitable redefinition. Without separating `square.h` into separate files, solving this is impossible.

Even if we didn't have definitions in header files in the first place (which is bad practice in general), repeated declarations, which are still fine, are also not really ideal either. Furthermore, custom types are typically defined in header files, so redefining them leads to an ODR violation.

Definition 2.2 (Header Guards)

Fortunately, we have **header guards**, which are conditional compilation directives that tell the compiler to include a header file at most once to the main file. You can do this in two ways.

1. Just put this to the top of the header file. The compiler will take care of redeclaration/redefinitions for you. This isn't always fail-safe.

```
1 #pragma once
```

2. More manually, we can use a conditional compilation directive. Put this on the top of the header.

```
1 #ifndef HEADERFILE_H
2 #define HEADERFILE_H
3
4 ...Header Contents...
5
6 #endif
```

In the beginning, `HEADERFILE_H` is not defined, so we include all of this. In a second inclusion though, `HEADERFILE_H` is defined, so the preprocessor removes this.

Note that header guards limit the number of times a header can be included in a single given file, but the header may still be repeated across separate project files. This is what we want.

2.5 Namespaces

Perhaps we want to have two functions of the same name, but we get a redefinition error. This is where namespaces come in.

Definition 2.3 (Namespace)

We can wrap each function around a **namespace**, which is written with an upper-case letter.

```
1 namespace Foo {
2     int bar() {}
3 }
```

To access identifiers defined in the namespace, we must use the **scope resolution operator** `::`. If

no scope resolution is given, or an empty one is given, then we look for the identifier in the global namespace.

```
1 int x = Foo::bar(); // Foo namespace
2 int y = bar();      // global namespace
3 int z = ::bar();    // global namespace
```

Example 2.4 (Namespace)

Say that we have two files with the same-name function in different namespaces.

<pre>1 namespace Foo { 2 int doSomething(int x, int y) { 3 return x + y; 4 } 5 }</pre>	<pre>1 namespace Goo { 2 int doSomething(int x, int y) {} 3 return x - y; 4 } 5 }</pre>
--	---

When we put our forward declarations, we must make sure to add the namespace using the scope resolution operator. If the namespace is not included, then the linker will look for the function in the global namespace rather than the user-defined namespace.

```
1 int doSomething(int x, int y); // this results in an error
2 int Foo::doSomething(int x, int y); // correct
3 int Goo::doSomething(int x, int y); // correct
4
5 int main() {
6   std::cout << Foo::doSomething(4, 3) << '\n';
7   std::cout << Goo::doSomething(4, 3) << '\n';
8   return 0;
9 }
```

Let's talk about a few properties of namespaces.

Lemma 2.1 (Identifiers in Parent Namespaces)

If an identifier A in a namespace uses another identifier B without a scope resolution, then A will look for B within A 's namespace. If no matching identifier for B is found, then the compiler will then check each containing namespace in sequence to see if a match is found, with the global namespace being checked last.

```
1 #include <iostream>
2 void print() // this print() lives in the global namespace
3 {
4   std::cout << " there\n";
5 }
6
7 namespace Foo {
8   void print() // this print() lives in the Foo namespace
9   {
10    std::cout << "Hello";
11  }
12
13  void printHelloThere()
14  {
```



```
15     print(); // calls print() in Foo namespace
16     ::print(); // calls print() in global namespace
17 }
18 }
19
20 int main() {
21     Foo::printHelloThere(); // prints "Hello there"
22     return 0;
23 }
```

Lemma 2.2 (Nested Namespaces)

Namespaces can be nested as well, either of 2 ways.

<pre>1 namespace Foo { 2 namespace Goo{ 3 ... 4 } 5 } 6 . 7 .</pre>	<pre>1 namespace Foo { 2 3 } 4 5 namespace Foo::Goo { 6 7 }</pre>
---	---

Lemma 2.3 (Namespace aliases)

You can shorten namespaces using **namespace aliases**.

```
1 namespace Active = Foo::Goo;
2 int x = Active::doSomething();
```

Lemma 2.4 (Using Namespace)

The **using namespace** is a directive that allows access to all members of a namespace.

3 Types and Expressions

Some types have the `_t` suffix, which just represents type. Some types have this and others don't. In C++, there is no exact size for each fundamental type (except for `char`, which is always 1 byte). There is however a lower bound, so you should always use the lower bound and for maximum portability, never assume that a type can store more bytes.

1. `sizeof(short) = 4`
2. `sizeof(int) = 4`
3. `sizeof(long) = 4`
4. `sizeof(long long) = 8`
5. `sizeof(float) = 4`
6. `sizeof(double) = 8`
7. `sizeof(long double) = 8`

Where does the `sizeof` operator come from?

3.1 Casting

We can also convert some types to different types. If the types are relatively similar, then the C++ implementation may do an **implicit typecast**. If not, then we do an **explicit typecast** in the following ways.

1. `static_cast<T>(foo)`
2. `(T)foo`
3. `dynamic_cast<T>(foo)`

4 Constants and Constant Expressions

4.1 Compiler Optimization

By default, all expressions are evaluated at runtime, but compilers have different levels of optimization. Here are some methods in which it optimizes, which follow the **as-if rule** that states that a compiler can modify a program however it likes in order to produce more optimized code, so long as those modification do not affect a program's observable behavior.

Definition 4.1 (Constant Folding)

The compiler replaces expressions that have literal operands with the result of the operation, e.g. `3 + 4` automatically gets evaluated to `7`.

Definition 4.2 (Constant Propagation)

In the code below, `x` is initialized to be `7` and will be stored in the memory allocated for `x`. On the next line, the program will go out to memory to fetch the same value to print. This is redundant. Therefore, the compiler will realize that `x` always has the constant value `7` and will replace all instances of `x` with `7`.

```
1  #include <iostream>
2
3  int main() {
4      int x { 7 };
5      std::cout << x << '\n';
6      return 0;
7  }
```

Definition 4.3 (Dead Code Elimination)

The compiler removes all code that has no noticeable effect on the program's behavior. Note that this is not a preprocessing step.

```
1  #include <iostream>
2  int main() {
3      int x { 7 }; // this line is removed.
4      std::cout << 7 << '\n';
5      return 0;
6  }
```

A slightly higher level optimization evaluates certain expressions during compile time.

Definition 4.4 (Compile-Time Expression)

A **compile-time expression** is an expression that must always be capable of being evaluated at compile-time.

Example 4.1 ()

Say we have the following code.

```
1  const double x { 1.2 };  
2  const double y { 3.4 };  
3  const double z { x + y };
```

`z` may or may not be evaluated to 4.6 at runtime. By default it is evaluated at runtime, but it depends on the compiler and level of optimization.

Shifting some of the evaluation from runtime to compile time makes your code faster, though it may make it more difficult to debug since the compiler might rearrange the logic of your program (though in an equivalent way). Therefore, at runtime, the compiled code no longer correlates with the original source code.

4.2 Constants

Now we talk about a seemingly separate, but very related concept.

Definition 4.5 (Constant Variables)

Named constants are variables that cannot change.

1. They cannot be declared and must be initialized since they cannot change. This is called **constant expression initialization**.
2. If a variable can be made constant, it should be. It reduces bugs and gives more opportunity for compiler optimization, effectively reducing runtime and increasing compile time.
3. Function parameters that are `const` just tells the compiler that it won't be changed during the function execution. But since the variable is thrown away after the body, it doesn't really matter anyways. You can also return `const` types, but this is again a temporary copy and may impede compiler optimizations so it not recommended.
4. In a way, `const`s are just like object-like directives with substitution text, but `const`s follow scoping, so use `const`s whenever you can rather than macros.

Theorem 4.1 ()

All compiler-time expressions must be `const`s. However, a `const` variable does not guarantee that it will be evaluated in compile time. With only `const`s, only *const integral* variables can be a part of a constant expression. No other `const` variable is allowed.

Proof.

It is not surprising to see that if an expression can be evaluated at compile time, it must be a `const` variable. Consider the contrapositive: if it wasn't a `const` variable, then it may be initialized or changed during runtime and therefore the expression cannot be evaluated at compile time. However, the converse is not true.

4.3 Compile-Time Programming

Notice that when we really want a section of code to be evaluated at compile-time, the best we can do is use `const` variables and hope that the compiler executes it. In other words, we are dependent on the sophistication of the compiler, which is not ideal. To allow more explicit control over which parts of code we want to execute at compile-time, we can use **compile-time programming**. In C++11, compile-time programming was introduced with constant expressions, or **constexprs**.

Definition 4.6 (Constant Expression)

A **constant expression** is an expression that must be entirely evaluable at compile-time.^a They generally contain the following:

1. Literals
2. Most operators with constant expression operands, e.g. `3 + 4`, `2 * sizeof(int)`
3. `constexpr` variables
4. `constexpr` function calls with constant expression arguments.

Any expression not a constant expression is called a **runtime expression**. The following cannot be used in a constant expression.

1. Non-const variables (e.g. `int x = 3;`)
2. Const non-integral variables, even when they have a constant expression initializer (e.g. `const double d = 1.2`). To use such variables, we need to define them with `constexpr`.
3. Function parameters.

There is a complex list of literals, operators, and variables that can and cannot be used in constant expressions.

There are still two problems. First, the limitations of constant expressions not being able to contain const non-integral variables is quite restricting. Second, even if we did have a constant expression, the compiler will by default evaluate it at runtime. Fortunately, `constexpr` addresses both problems.

Definition 4.7 (`constexpr` Keyword)

The **constexpr** variable is always a compile-time constant. As a result, a `constexpr` variable must be initialized with a constant expression, otherwise a compilation error will result. Here are some examples.

```
1 constexpr double gravity = 9.8; // works for doubles now
```

Since a `constexpr` variable is really a constant expression, it is implicitly a `const` variable.

^aalong with rules that determine how the compiler should handle these expressions.