

## Real-Time Object Detection with YOLOv3 and OpenCV

### Features

- Real-time object detection with YOLOv3.
- Confidence threshold for filtering low-probability detections.
- Non-Maximum Suppression (NMS) to eliminate redundant bounding boxes.
- Dynamically displays detected object count.
- Highlights detected objects with bounding boxes and class labels.

### Prerequisites

1. Python 3.x installed on your system.
  2. Install the required Python libraries:  
`pip install opencv-python numpy`
  3. Download the YOLOv3 model files:
    - [YOLOv3 Weights](<https://pjreddie.com/media/files/yolov3.weights>)
    - [YOLOv3 Config](<https://github.com/pjreddie/darknet/blob/master/cfg/yolov3.cfg>)
    - [COCO Names](<https://github.com/pjreddie/darknet/blob/master/data/coco.names>)
- Place these files in the same directory as the script or adjust the file paths accordingly.

### Usage

1. Clone this repository to your local system:  
`git clone https://github.com/<your-username>/YOLOv3-Object-Detection.git`
2. Navigate to the project directory:  
`cd YOLOv3-Object-Detection`
3. Run the script:  
`python yolov3_object_detection.py`

4. The script will activate your webcam and display the video feed with detected objects.

### Code Structure

- File Paths : Define paths to the YOLOv3 model files (``weights``, ``cfg``, ``names``).
- YOLO Initialization : Load the YOLO model using OpenCV's ``cv2.dnn``.
- Webcam Feed : Capture video frames in real time.
- Preprocessing : Convert frames into YOLO-compatible blobs for detection.
- Detection Logic : Apply object detection using YOLO's forward pass and use confidence thresholds and NMS for accuracy.
- Visual Output : Draw bounding boxes and labels. Display object count dynamically.

### Customization

- Adjust Confidence Threshold: Modify the confidence threshold to control detection sensitivity.
- Non-Maximum Suppression (NMS) : Fine-tune the NMS threshold for overlapping boxes.
- Use a Video File : Instead of a webcam, analyze a video file.

### Example Output

Example frame showing real-time detections with bounding boxes and labels.

### Troubleshooting

- Webcam Not Detected : Ensure the correct webcam index is used.
- File Paths : Verify that ``yolov3.weights``, ``yolov3.cfg``, and ``coco.names`` are in the correct locations.