

Raindrops on a Tin Roof: Exploring the Cyberinet

Matthew A. Bardin
- PHD Candidate

Louisiana State
University -
Experimental
Music & Digital
Media

04/18/2023



The main event will begin soon.

Please take your seat.

Access the event program, various examples and music scores with this QR code.

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Augmented Instruments

WHAT IS THE CYBERINET?

What is an Augmented Instrument?

- ▶ Augmented Instruments are any instrument that has been altered or enhanced from its base capabilities in some way.
 - ▶ This can be done in a variety of methods.
 - ▶ Augmentation methods can be any combination of manual, automatic, acoustic, mechanical, or electronic.
 - ▶ Many modern augmentations include electronic components, sensors and computers.
-
- ▶ Reid, Sarah, Sithi-Amnaui, Sara, & Kapur, Ajay. (2018). *Women who Build Things: Gestural Controllers, Augmented Instruments, and Musical Mechatronics*. Proceedings of the International Conference on New Interfaces for Musical Expression, 178-183.

Recent Eras of Augmented Instruments

Pre-20th Century

- Completely acoustic/mechanical.
- Generally looking to improve an instrument or create a new one.
- Brass Mutes, Player Pianos, Calliope.

20th Century

- Early electronics improve over course of century
- Early computer augmentations begin to appear.
- Prepared Piano, Amplification, Effect Pedals, Recording Developments.

21st Century (so far)

- Largely computer-based.
- Exploring new timbres and instrument functionality with new technology.
- Cyberinet, MIGSI Trumpet, SABRe, Overtone Violin, MataSax.

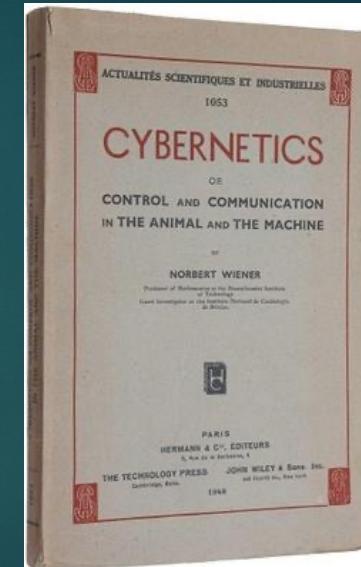
A General Historical Context. Visit 120years.net for a more detailed timeline.



Cybernetic + Clarinet

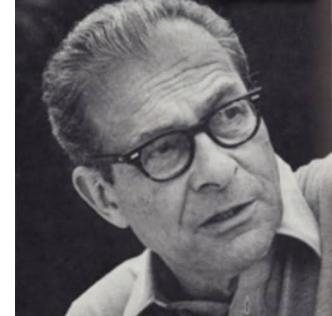
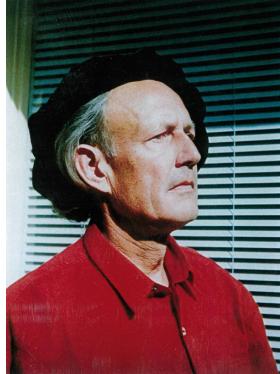
What are Cybernetics?

- ▶ Cybernetic: *The science of communications and automatic control systems in both machines and living things* – Oxford Dictionary
 - ▶ Definition ca. 1948 from the Greek “Kubernetes” meaning captain, pilot, conductor, etc.
 - ▶ Norbert Wiener first defined the term in his book *Cybernetics: Or Control and Communication in the Animal and the Machine*. It came from the concept of a sailor steering a ship, then seeing the ship move and responding to that in a feedback loop.
 - ▶ Later refined to: Circular causal and feedback mechanisms in biological and social systems.
 - ▶ Cyborg: portmanteau of cybernetic and organism. A being with organic and inorganic body parts. (ca. 1960)
 - ▶ Many crossovers and definition variances stemming from the core concept of automated control and feedback loops.
- ▶ The Cyberinet is used to collect performance data and automatically control the audio processing and other electronic elements of an electroacoustic performance.



Cybernetic Music

- ▶ Several composers have utilized cybernetics in some way in their music. A small sample includes:
- ▶ Roland Kayn (1933-2011):
 - ▶ Composer focusing on Cybernetic Concepts and electronics.
 - ▶ Mix of random and intentional aspects.
 - ▶ Allows the sound to grow and evolve on its own.
- ▶ Herbert Brün (1918-2000):
 - ▶ Composer and computer scientist.
 - ▶ Utilized early computing languages in the creation of new music.
 - ▶ Creates new timbre synthesis techniques similar to granular synthesis.
- ▶ Pauline Oliveros (1932-2016):
 - ▶ Composer and post-war experimental musician.
 - ▶ Inspired by Cybernetic concepts in the 1960's.
 - ▶ Led to experiments with sounds creating sounds, tape, and other methods of creating and listening to music.



How does the Cyberinet factor in?

- The Cyberinet is a sensor array designed to be easily adapted the instrument for electronic music without impeding the performance of the instrument.
- The Cyberinet can still be used as a regular clarinet barrel while powered off.
- Utilizes cybernetic principles (automatic control of various sound processes) to create an augmented instrument.
- Easily implement a feedback loop where the sound can effect the player making the sound.

Why use this Instrument?

- ▶ Easy to implement.
- ▶ Does not reduce the Clarinet's capabilities.
- ▶ Can easily add harmonic capabilities to the Clarinet.
- ▶ Intuitive controls.
- ▶ Can be used by performers, composers, and programmers.

Creating the Cyberinet

OEM Components

OEM Components are standardized to be compatible with each other.

- ▶ The Cybernet is comprised of a main unit and smaller secondary unit.
- ▶ Main Unit:
 - ▶ 1200mAh Li-Po battery to power the device.
 - ▶ TP-4056 Type C board. (controls the charging and power distribution)
 - ▶ MPU-6050 board. (6 axis gyroscope and accelerometer)
 - ▶ SDP-31 Qwiic Connect board. (differential air pressure/flow and temperature)
 - ▶ ESP-32 DEVKIT board. (microcontroller and transmitter)
- ▶ Secondary Unit:
 - ▶ 2 momentary switches with independently programmable LEDs.

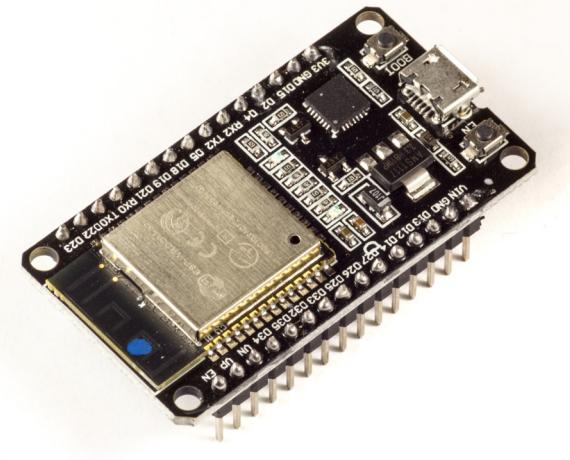
Also, the Cybernet has 2 programmable LEDs, which are not OEM.



MPU 6050 (Gyro + Accelerometer)



0602 Size SMD LEDs

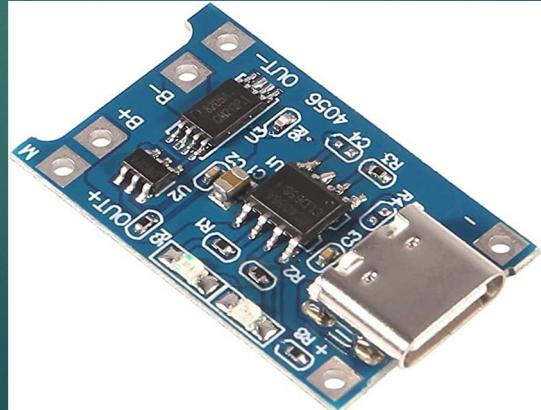


ESP-32 Microcontroller



Pushbuttons

Version 1 Components



TP-4056 (Power Distribution)



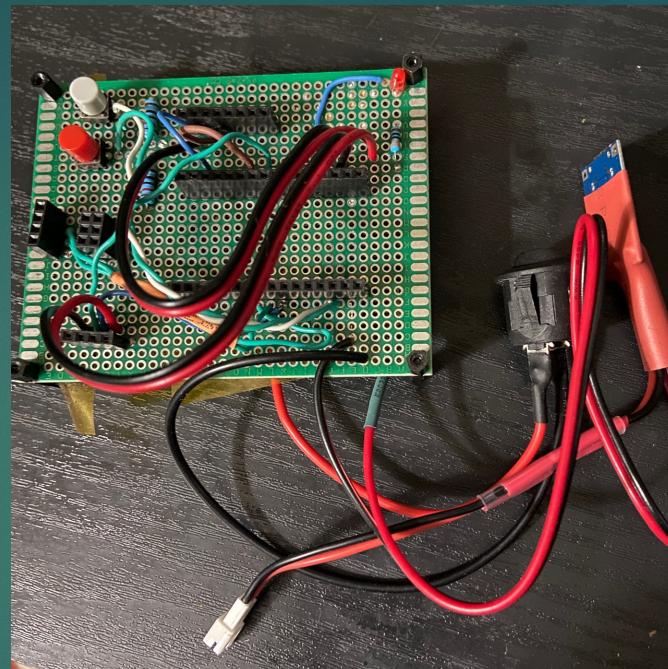
SDP-31 Differential Pressure Sensor



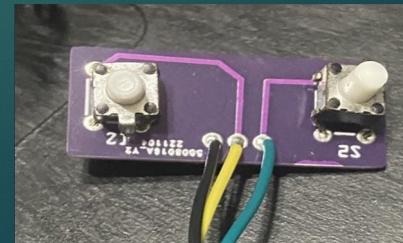
Top



Bottom



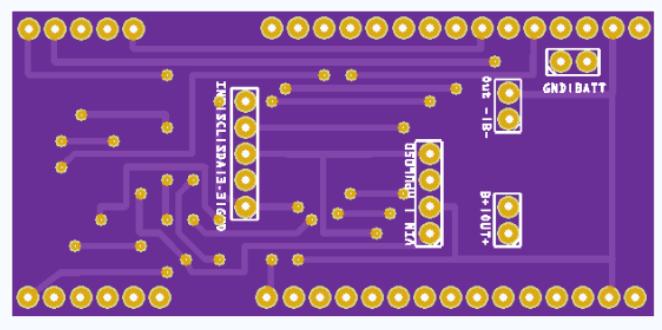
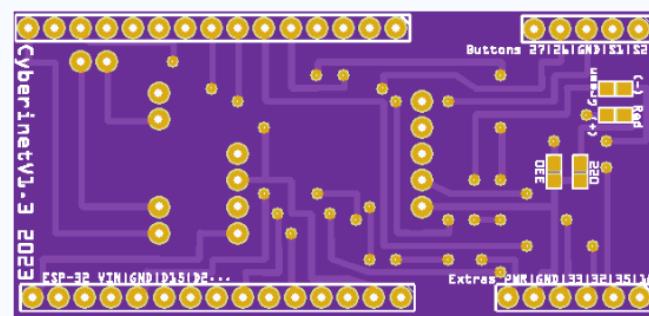
Original Prototype Socket Board



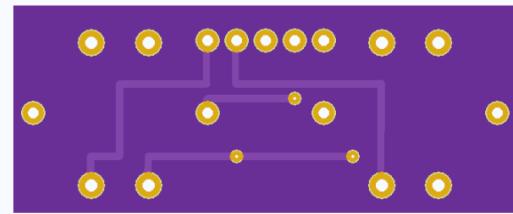
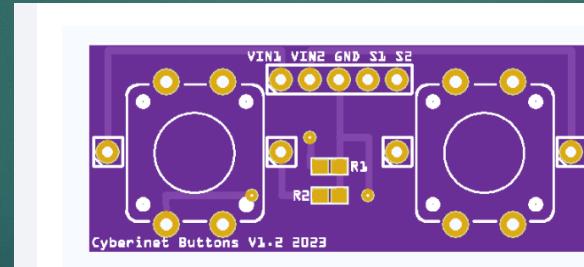
Buttons

Main Unit & Button Expansion Prototypes

Main Board



Button Expansion



Version 1 Final PCB Diagrams

- ▶ To further expand the functionality of the Cyberinet, multiple optional expansion units contain a variety of other sensors and can be utilized through the same expansion port.
- ▶ These include:
 - ▶ Microphone
 - ▶ Finger pressure sensors
 - ▶ Secondary movement sensor
 - ▶ Speaker
- ▶ All of these are still in development, with the microphone closest to being functional.

Future Optional add-ons

Music



Puzzle of a Park (2023)

- ▶ All works heard today are the FIRST pieces written for this instrument.
- ▶ Written to utilize the optional button add-on.
- ▶ Performer triggers the on-stage microphone & playback of recordings with a single button.
- ▶ Functions similarly to a loop pedal.
 - ▶ Allows performer to multi-track and harmonize with themselves.

Adam Cope- Cyberinet

Puzzle of a Park opening page

Puzzle of a Park

Matthew A. Bardin (2023)

For the Cyberinet

Cyberinet *d* = 50 rec.

For the Cyberinet

6 **A** *d* = 72

10

12

15

17

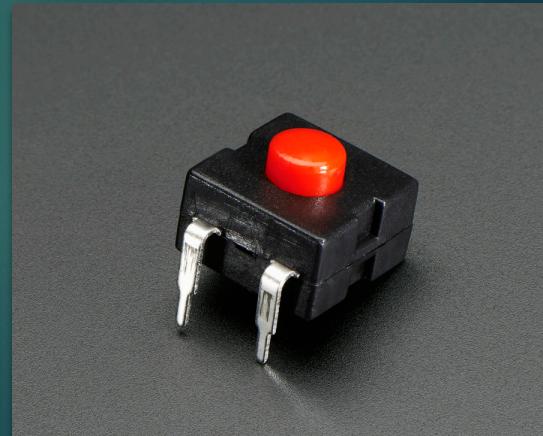
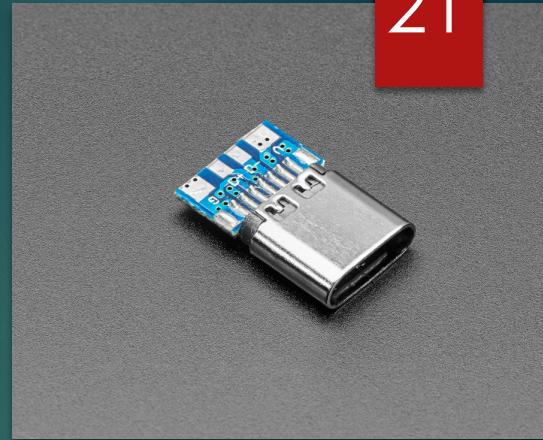
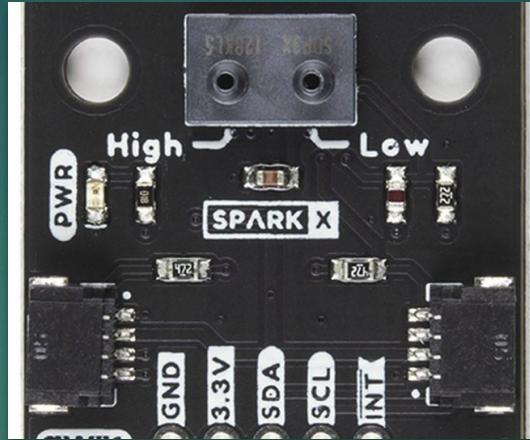
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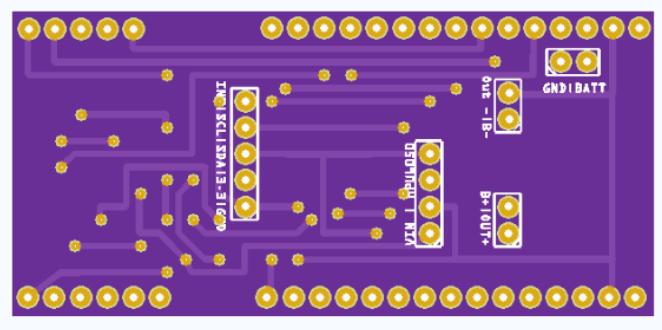
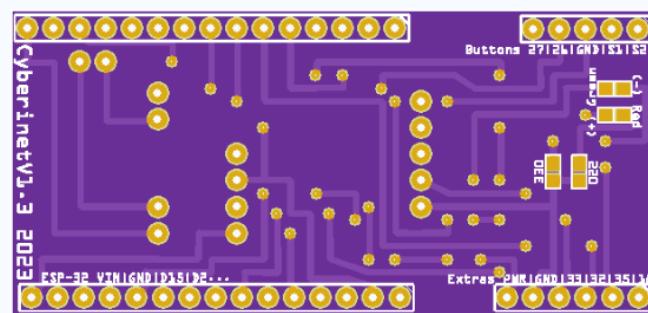
Assembling the Cyberinet

Assembling the Cyberinet

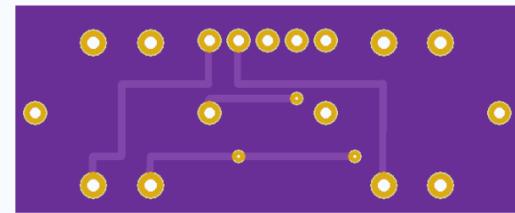
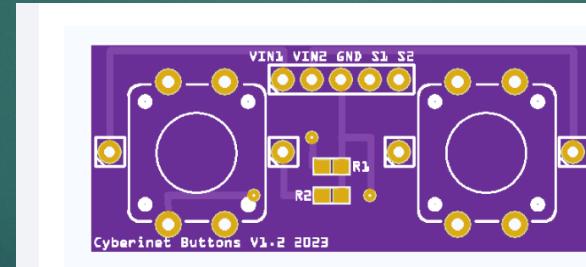
- 1: Attach LEDs and Resistors (SMD Components) to the PCBs.
- 2: Solder the USB-C and JST connectors. These are supported by the outer case.
- 3: Solder the larger components directly to the PCBs. The microcontroller and SDP chip should be elevated with pin headers.
- 4: Add the power switch. When done, connect the battery Glue/Sand as needed.



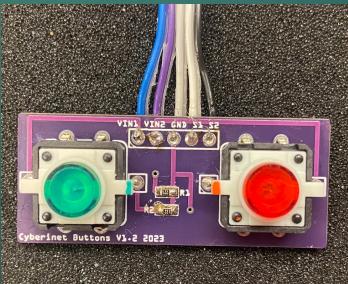
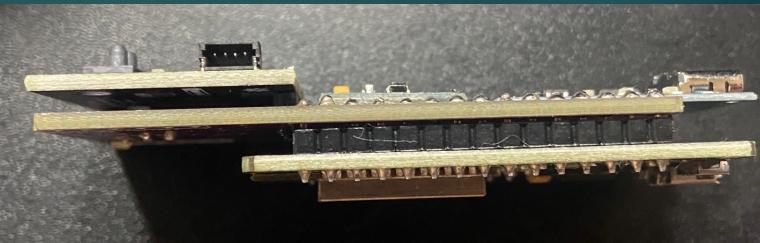
Main Board



Button Expansion



Version 1 Final PCB Diagrams

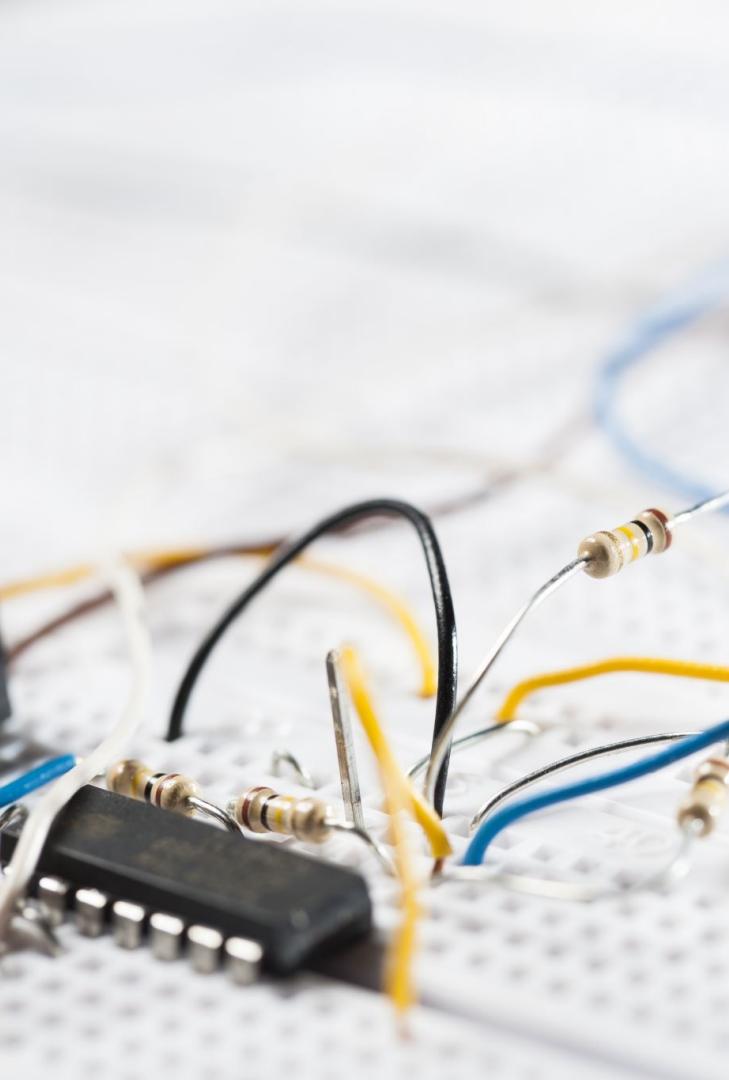


Version 1 with Button Board

How the Cyberinet works



Collects data



► The Cyberinet's .ino code and attached sensors manage the collection of the performance data.

- ▶ SDP31: Measures differential air pressure between the inside and outside of the instrument. Small tubes connect to the sensor to facilitate this. Also measures temperature.
- ▶ MPU6050: Measures performer movement in 6 axis.
- ▶ Buttons: triggerable by the performer.
- ▶ Other Expansion Add-Ons.

```

void get6050() {
    //////////////Collect Data
    Wire.beginTransmission(MPU_ADDR);
    Wire.write(0xE0); // wake up device
    Wire.endTransmission(true);

    Wire.requestFrom(MPU_ADDR, 6); //Request Accel Registers (3B - 40)
    while (Wire.available() < 6);
    AcX = Wire.read() << 8 | Wire.read(); // operator first bitshifts the sensor value by 8 bits,
    AcY = Wire.read() << 8 | Wire.read(); // then does a bitwise OR to compare to raw data
    AcZ = Wire.read() << 8 | Wire.read(); // enbd result is a combined original and bitshift

    Wire.beginTransmission(MPU_ADDR); //I2C address of the MPU
    Wire.write(0x43); //Starting register for Gyro Readings
    Wire.endTransmission();
    Wire.requestFrom(MPU_ADDR, 6); //Request Gyro/Accel Registers (43 - 48)
    while (Wire.available() < 6);
    GyX = Wire.read() << 8 | Wire.read();
    GyY = Wire.read() << 8 | Wire.read();
    GyZ = Wire.read() << 8 | Wire.read();

    //////////////Format Data
    rotX = GyX * 0.007633587786; // gravity and rotation offsets
    rotY = GyY * 0.007633587786;
    rotZ = GyZ * 0.007633587786;

    gForceX = AcX * 0.00006103515;
    gForceY = AcY * 0.00006103515;
    gForceZ = AcZ * 0.00006103515;

    //////////////Transmit Data
    digitalWrite(msgLED, HIGH); // turn on LED when transmitting
    SerialBT.print("GyroX ");
    SerialBT.println(rotX);
    SerialBT.print("GyroY ");
    SerialBT.println(rotY);
    SerialBT.print("GyroZ ");
    SerialBT.println(rotZ);

    SerialBT.print("AccelX ");
    SerialBT.println(gForceX);
    SerialBT.print("AccelY ");
    SerialBT.println(gForceY);
    SerialBT.print("AccelZ ");
    SerialBT.println(gForceZ);
    digitalWrite(msgLED, LOW); // turn off led when done transmitting
}

```

```

void getButtons() {
    //////////////Collect Data
    button1State = digitalRead(button1);
    button2State = digitalRead(button2);

    //////////////Transmit Data (every frame. CNET.receive Max Object filters out repetitions.)
    digitalWrite(msgLED, HIGH); // turn LED on when transmitting data
    SerialBT.print("B1 ");
    SerialBT.println(button1State); // value
    digitalWrite(b1LED, button1State); // on-board led state matches button state
    // repeat for other button
    SerialBT.print("B2 ");
    SerialBT.println(button2State);
    digitalWrite(b2LED, button2State);
    digitalWrite(msgLED, LOW); // turn off led when done transmitting
}

void getAir() {
    //////////////Collect Data
    airFlow.readMeasurement(&diffPressure, &temperature);

    //////////////Transmit Data
    digitalWrite(msgLED, HIGH); // turn on LED when transmitting
    SerialBT.print(F("AirP "));
    SerialBT.println(diffPressure, 2); // value

    SerialBT.print(F("Temp "));
    SerialBT.println(temperature, 2);
    digitalWrite(msgLED, LOW); // turn off LED when done transmitting
}

```

Data Collection Code

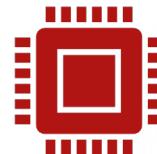
Transmits wirelessly



The main unit's ESP-32 board
the transmitting as well as
the data collection.



By utilizing the Arduino library
“BluetoothSerial” the DEVKIT
can transmit serial
communications through a
Bluetooth connection. The
device name is
“CyberinetV1X” and
currently requires no
password to connect.



These values can be read
by any serial terminal
program on the host device.
The Max objects utilize an
additional node script to
receive the data more
reliably.

Performer Opinions

- ▶ We will take a few moments to ask Adam about his thoughts with using the device.
- ▶ What are your honest opinions on the usability, flexibility, and anything else you would like to mention?

Music



Ethereal Presence (2022)

- ▶ Utilizes gyroscope and airflow sensors.
- ▶ As the performer moves, the position of their instrument changes the pitch content of the accompaniment.
- ▶ Computer synthesis has 2 main textures:
 - ▶ Filtered pink noise to provide backing texture
 - ▶ Modified FM synthesis to provide accompaniment to the soloist
- ▶ Music alters between different styles to encourage a variety of performance movements.
- ▶ Wide tempo variety helps encourage a non-identical performances.

Adam Cope- Cyberinet

Ethereal Presence opening page

Ethereal Presence

For the Cyberinet

Matthew A. Bardin (2022)

31

Cyberinet

Slowly, tempo ad lib. $\text{♩} = \text{c. 44-72}$

A

a tempo

accel.

ffff

ppp

f

ppp

ffff

ppp

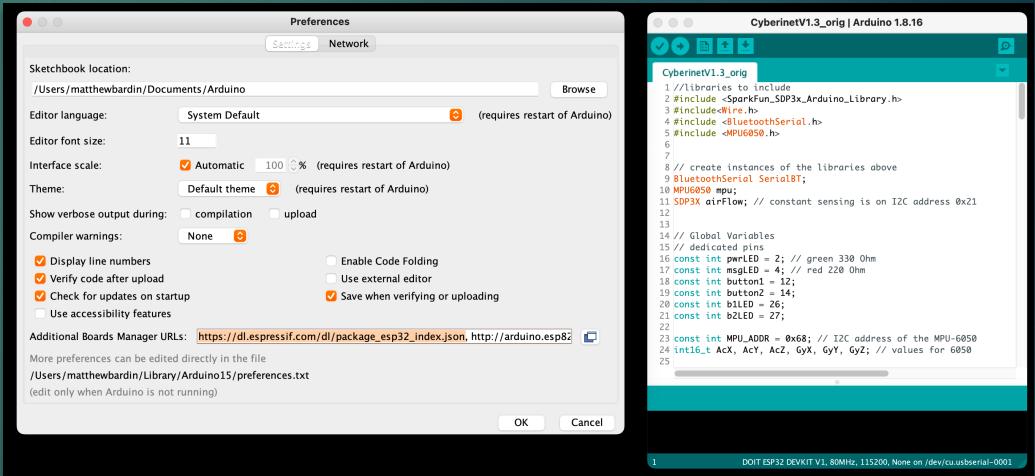
ppp



Computer Processing

Driver Installation

- ▶ A few drivers are needed to utilize the wireless communications.
 - ▶ ESP-32 Drivers: These can be easily installed via the Arduino IDE program.
 - ▶ Node and NPM: Can be installed from the Node website and managed via the Terminal.
 - ▶ These extra steps only need to be run once, whenever it is the first time a computer has paired with a Cybernet.
 - ▶ NPM can be managed from the Max objects as well.
 - ▶ Looking to streamline this step in future revisions.



Processing/Manipulation in Max

The main goal of the Cyberinet is to collect and transmit the sensor data.

From there it is largely up to the user to decide what they want to do with the data.

To help with that I have also created a series of Max patches that can be used to control various elements of a Max patch including:

- Reverb
- Various Delays
- Gain
- Debug testing tool
- Tuner
- Playback Control
- DMX Control
- More coming soon!



Early effects are simpler alterations to the Clarinet's sounds and software control. More complex uses to come as the hardware continues to be refined.

QR Code reminder

- ▶ You can find screenshots of a selection of max patches here.
- ▶ I'll keep this up for a few seconds if anyone needs it.



Max Patches Continued

►CNET.receive receives all the data from the Cybernet, sorts and scales it for use, then outputs the numbers to unique object outlets.

►Port defaults to the expected MacOS formatting. If everything matches, steps 2 and 3 can be skipped.

CNET.test

Patch by Matthew Bardin
For more information:
matthewbardin.com

0. Install node packages

1. start script

2. List All Available Serial Ports (Console)

3. type desired port name. Bang to set

4. Open set port

5. Enable Communication

6. Toggle All Raw Inputs in Max Console

7. Stop script

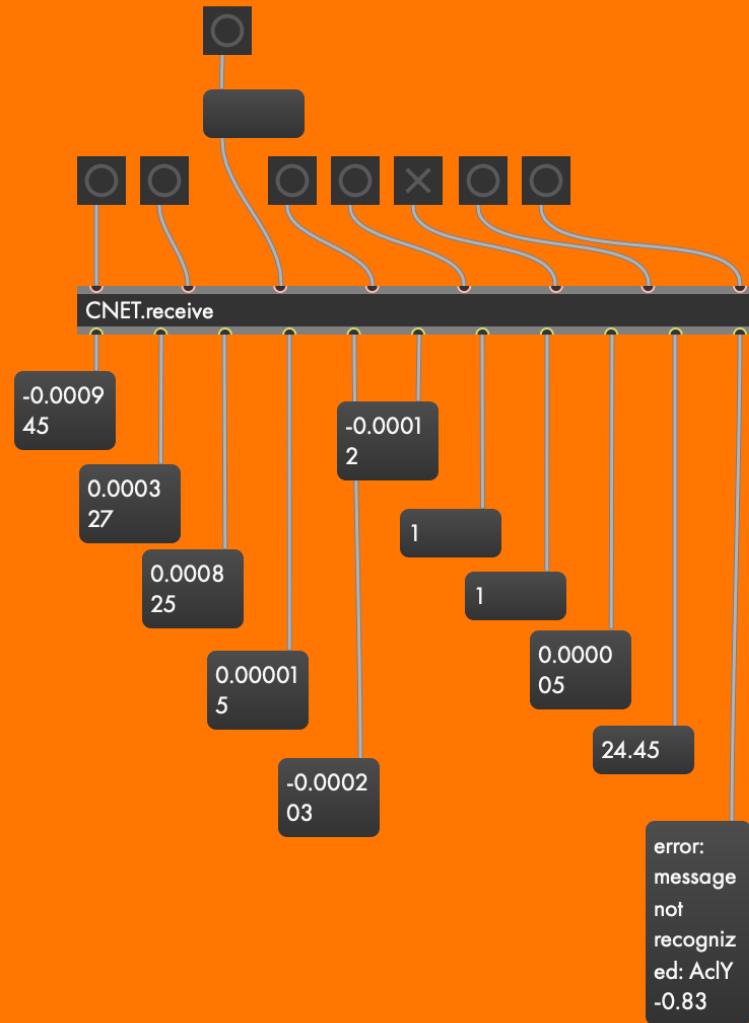
Gyroscope X,Y,Z Accelerometer X,Y,Z Airflow and Temperature Buttons Errors and Raw Data

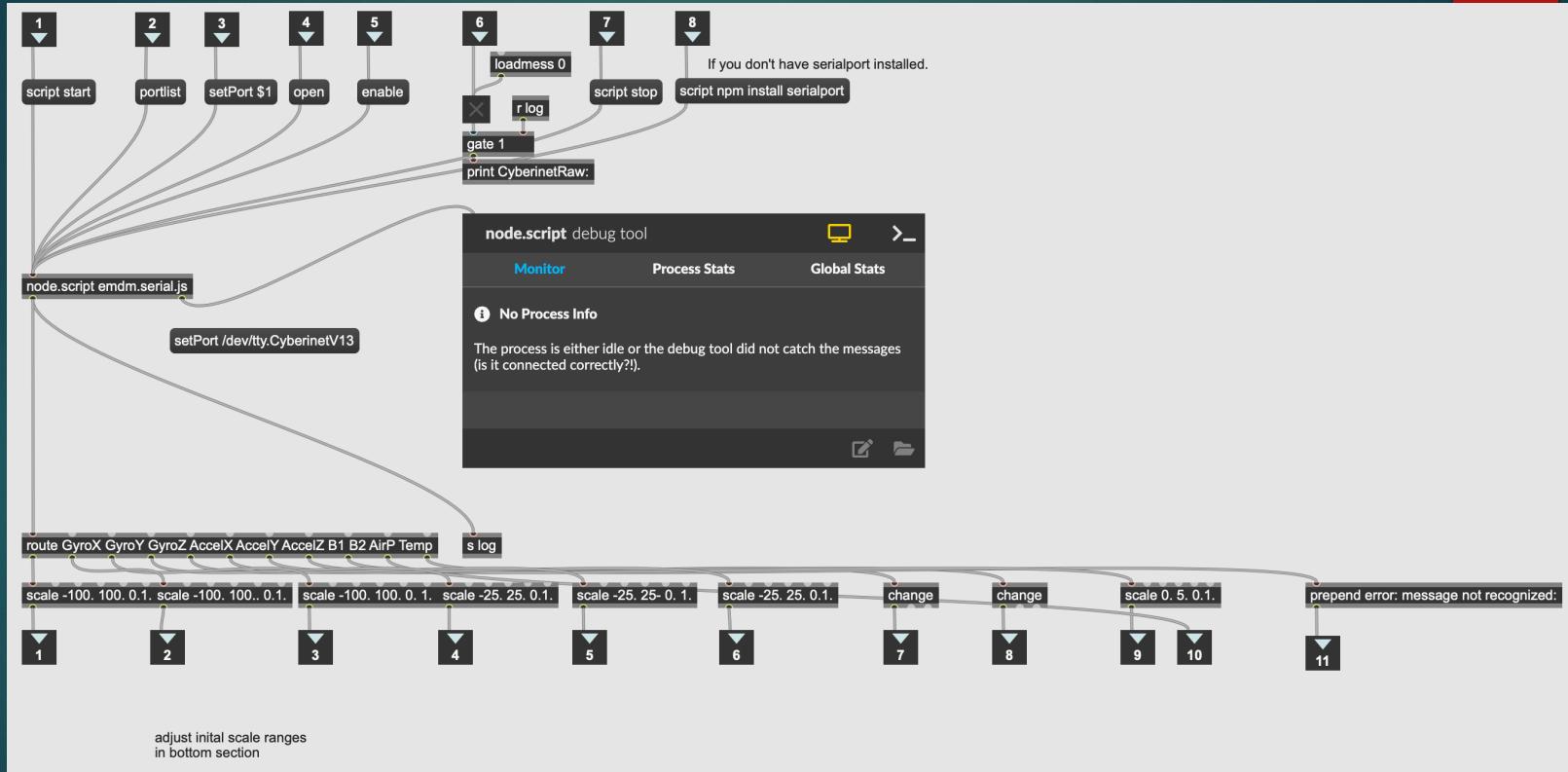
-0.0009 45	0.0003 27	0.0008 25	0.00001 5	-0.0002 03	-0.0001 2	0.0000 05	24.45	1	1
---------------	--------------	--------------	--------------	---------------	--------------	--------------	-------	---	---

error: message not recognized: AclY -0.83

This patch is used for Calibrating and Testing the Cybernet hardware with a max patch.
It simply connects to a Cybernet unit and displays the incoming values in the above message boxes. Each outlet on CNET.receive has its own box, and these are broken up by the accompanying sensor on the Cybernet.
The goal for this patch is to test that your device can be seen by the computer, and then to display the incoming values to see if your patch will need any value scaling between the Cybernet and the process you wish to control with the hardware.
Begin by powering your Cybernet and connecting it via your computer's bluetooth capabilities.
If you do not already have the appropriate node scripts installed, begin with the rightmost bang to install them. (recommended when using the device for the first time)
When all scripts are installed, you will move from left to right across the patch. click the bang object to start the script
List all of the available ports displays them in the Max console. Find the port labeled with the Cybernet, paste that into the message box and press the third bang object to set it. (this will usually be formatted as "/dev/tyCybernetV13" on Mac devices, and COM# on Windows devices. The shown Mac serial address is the default setting.)
After the desired port is selected, use the next two bangs to open said port and enable the communications. You should now see values populating the message boxes. You can toggle displaying the raw data values in the Max console if desired.
Press the final bang to stop communications. Begin at step 1 to resume communications (port setting can be skipped at this point, assuming the desired port did not change)
If your computer is not receiving data from the Cybernet, make sure the unit is charged, navigate to your computer's bluetooth settings, forget, then repair the Cybernet.

CNET.receive



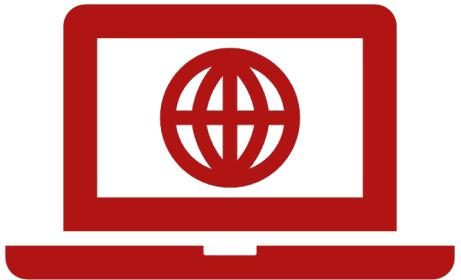


CNET.recieve patch inner workings

Sending data to other programs

- ▶ Data from the Cybernet can be read by any Serial Monitor.
 - ▶ Data is formatted for Max by default.
 - ▶ Programs like Max can then convert the messages to different formats and transmit them to other devices and software as needed.

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Online Resources

Github Repo

Contains all code, diagrams,
and other information



github.com/mbardin/Cyberinet

	Lecture Recital	documentation photos and slide updates	5 hours ago
	Max Tools	draft of pan object	last week
	Music Composition Scores	file name changes	yesterday
	V_1.3	forgot to add file drafts to last push. uwu	yesterday
	other documentation	documentation photos and slide updates	5 hours ago
	.DS_Store	documentation photos and slide updates	5 hours ago
	.gitattributes	Initial commit	5 months ago
	.gitignore	updates	yesterday
	Cyberinet Lecture Recital.pptx	documentation photos and slide updates	5 hours ago
	LICENSE	Initial commit	5 months ago
	Matthew Bardin Lecture Recital Prog...	working on presentation slides	5 days ago
	README.md	slide and readme updates	5 hours ago

Code, Patches, Diagrams, & Resources.

Cybernet units will be available for purchase at a future date.

All materials are open-source.

A person can build their own unit using the online resources.

Music



Raindrops on a Tin Roof (2022- 2023)

- ▶ Utilizes all the included sensors:
 - ▶ Gyroscope/Accelerometer
 - ▶ Airflow
 - ▶ Buttons
- ▶ The performer cues up various sound files and musical sections using the buttons.
- ▶ Other sensors are used to control the processing of the sounds.
- ▶ Sounds range from relaxing to extremely chaotic.
- ▶ Text by Matthew A. Bardin

Adam Cope - Cyberinet Matthew Bardin - Narrator

Raindrops on a Tin Roof

opening page

Raindrops on a Tin Roof

Transposing Performance Score

Matthew A. Bardin (ASCAP)

walk to stand 1

Vamp. Press button 1 and enter in time on measure 2.

Cybernet in Bb

1

Synthesizer

p

White flesh... 9,10,11... crash! —
but it didn't seem to be moving any faster than before. (1:32)

2

p

mf

5

pp

Bassoon

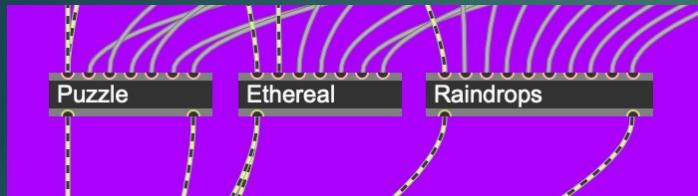
Future Directions

Potential Future Directions Include:

- ▶ Optimal serial communications and installations for Windows and Mac operating systems.
- ▶ Completing and refining the options for expansion units.
- ▶ Custom-made PCBs without OEM to make smaller units.
- ▶ OSC Formatting for easier multi-platform use cases.
- ▶ Permanent embedding within a clarinet.
- ▶ Making versions for other instruments.
- ▶ Password locking units to avoid miss-connections.

Final Notes

All the compositions are available in Max.



- ▶ Each of the patches used to make these performances has been created as an object in Max. Performers can download these from the GitHub repo for performance, or experiment with their own processing.

Scores, patches and other info available at matthewbardin.com



Questions?



Thank
You for
coming!

