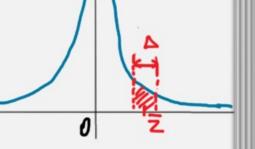
Probability as "Measure"
Consider a normally distributed random variable

Z,~N(0,1)

Probability density function:

$$f(\overline{z}_t) = \frac{1}{\sqrt{2JJ}} e^{-\frac{1}{2}\overline{z}_t^2}$$



The probability that Z falls near a specific value Z is:

$$\mathcal{P}(\bar{z}_{-\frac{1}{2}\Delta} < \bar{z}_{t} < \bar{z}_{t+\frac{1}{2}\Delta}) = \int_{\bar{z}_{-\frac{1}{2}\Delta}}^{\bar{z}_{+\frac{1}{2}\Delta}} \frac{1}{|\bar{z}_{1}|} e^{-\frac{1}{2}\bar{z}_{t}^{2}} dz_{t}$$

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If the region \triangle around \overline{Z} is small => $f(\overline{Z}) \cong f(\overline{Z})$: $\int_{\overline{Z}-\frac{1}{2}\Delta}^{\overline{Z}+\frac{1}{2}\Delta} e^{-\frac{1}{2}\overline{Z}+\frac{1}{2}\Delta} dz \cong \int_{\overline{Z}-\frac{1}{2}\Delta}^{\overline{Z}+\frac{1}{2}\Delta} e^{-\frac{1}{2}\overline{Z}+\frac{1}{2}\Delta} = \lim_{\overline{Z}-\frac{1}{2}\Delta} e^{-\frac{1}{2}\overline{Z}+\frac{1}{2}\Delta} dz = \lim_{\overline{Z}-\frac{1}{2}\Delta} e^{-\frac{1}{2}\overline{Z}+\frac{1}{$

This probability is a "mass" represented by a rectangle:

(第一) 年(年) 二个(至一) 人名 天(至十) 人)

That is, probability corresponds to a "measure" associated with possible values of Zt.

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For infinitesimal △=d=, We denote these measures by the symbol dP(Z,): JT(スノ)=ア(豆」ナカスくろナナカスと S dP(Z,)=1 The expected value of It is the "center of probability mass" $\mathbb{E}[Z_t] = \int_{-\infty}^{\infty} Z_t d\mathbb{P}(Z_t)$ The variance indicates how-the probability mass spreads around the center: $E[z_t-E[z_t]]^2 = \sum_{z=1}^{\infty} [z_t-E[z_t]]^2 + \sum_{z=1}^{\infty} [z_t-E[z_t]^2 + \sum_{z=1}^{\infty} [z_t-E[z_t]]^2 + \sum_{z=1}^{\infty} [z_t-E[z_t]^2 + \sum_{z=1}^{\infty} [z$

We Change Probability Measures To Justify Prices

Game: You flip a coin, the values of the payoff are:

Z= \\
\begin{align*}
\frac{\\$1, if you flip heads}{\} \text{tails}

How much would you pay to play this game?

Real-World Measure The Game Dealer Asks \$0.60

Real-World Measure

\\$0.| tails

$$\frac{1}{2} \cdot \$1 + \frac{1}{2} \cdot \$0.1 = \$0.55$$

New Probability
Measure
\$0.10 tails

\$1.2 + \$0.10(1-2) = \$0.60
0.9
$$q = 0.5 = 9 = \frac{5}{2}$$

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Forward Measure.pdf Page 5 of 15

Static Theory

$$Z > 0$$
, Q a.s., $F[Z] = 1$

Define $\overline{Q}(A) \triangleq E[1_A \cdot Z]$
 $\overline{Q}(\emptyset) = 0 : \overline{Q}(\emptyset) = E[1_2 \cdot Z] = E[0 \cdot Z] = E[0] = 0$
 $\overline{Q}(\Omega) = 1 : \overline{Q}(\Omega) = F[1_3 \cdot Z] = F[1 \cdot Z] = F[Z] = 1$
 $A \in \mathcal{F} \Rightarrow \overline{Q}(A) > 0 :$ Denote $N = \{ \omega \in A \mid Z(\omega) < 0 \}$
 $\overline{Q}(A) = F[1_4 \cdot Z] = \sum_{A} ZdQ = \sum_{A \in A} ZdQ + \sum_{A \in A} ZdQ > \sum_{A \in A} ZdQ > 0$
 $\overline{Q}(A \cup B) = \int_{A} ZdQ + \int_{B} ZdQ = \overline{Q}(A) + \overline{Q}(B)$
 $\overline{Q}(A \cup B) = \int_{A} ZdQ + \int_{B} ZdQ = \overline{Q}(A) + \overline{Q}(B)$

Dynamic Measure Change Consistency Condition For $0 \le t \le T$, $\mathcal{F}_{t} \subset \mathcal{F}_{t} : A \in \mathcal{F}_{t} \Rightarrow A \in \mathcal{F}_{t}$ $\widetilde{Q}_{t}(A) = \widetilde{Q}_{\tau}(A)$, $\forall A \in \mathcal{F}_{t}$ A=F_ => A, 1, -F_-measurable Z_t is a martingale => Z_t = E[Z₇/F_e] Q_t(A) = E[4, Z_t] = E[4, Z_t/F] = E[4, E[Z_t/F]/F] = E[E[4Z₇/I]/I] = E[4, Z₁|I] = E[4, Z₁] = Q=1

If 0 & t ≤ T, and X is an F-measurable r.v. so that [E[|X|] < + ∞, then [E[X/]===E[Z_X|]_] By definition, $Y = \widetilde{E}[X/f_{t}]$ is the conditional expectation of X if $\widetilde{E}[I_{t},Y] = \widetilde{E}[I_{t},X]$. Set $Y=Z_t^{-1}E[Z_tX]_{\frac{\pi}{4}}$ and fix $A \in \mathcal{F}_t \Rightarrow$ Yand of are F-measurable Zisa martingale => Zt = E[ZT] Created with Doceri

Tower Rue
$$\widetilde{E}[I_{A}Y] = E[Z_{T}I_{A}Y] = E[Z_{T}I_{A}Y] + \widetilde{f}_{0}] = E[I_{A}Y + \widetilde{f}_{0}] + E[I_{A}Y + \widetilde{f}_{0}]$$

$$= E[I_{A}Y + E[Z_{T}|f_{0}] + \widetilde{f}_{0}] + E[I_{A}Y + \widetilde{f}_{0}]$$

$$= E[I_{A}Z_{t} + E[Z_{T}X|f_{0}] + \widetilde{f}_{0}] + E[I_{A}Z_{T}X|f_{0}]$$

$$= E[I_{A}Z_{t} + \widetilde{f}_{0}] + E[I_{A}Z_{T}X|f_{0}]$$

$$= E[I_{A}Z_{T}X|f_{0}] + E[I_{A}X] + \widetilde{f}_{0}X + \widetilde{f}_{0}X$$

$$= E[I_{A}X] + E[I_$$

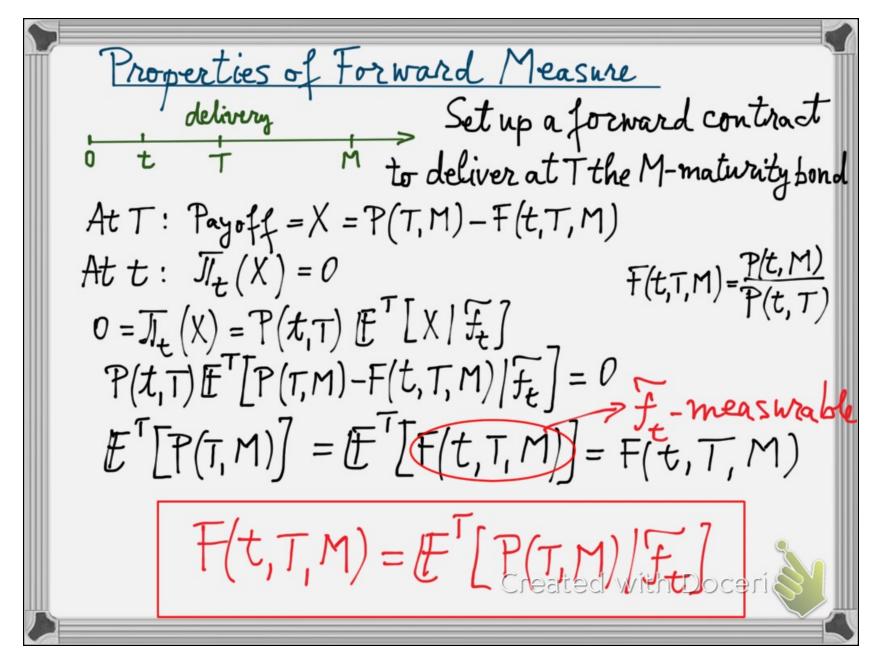
Forward Measure Pricing Formula

X is an
$$\mathcal{F}_{T}$$
-measurable payoff. Then

 $J_{t}(X) = P(t,T) \notin [X/f_{t}]$
 $B_{t} = \frac{P(t,T)}{Z(t,T)}; B_{T}^{-1} = Z(T,T)$
 $J_{t}(X) = B_{t} \notin [B_{T}^{-1}X/f_{t}] = \frac{P(t,T)}{Z(t,T)} \notin [Z(T,T)X/f_{t}]$
 $= P(t,T) \frac{Z(0,T)}{Z(t,T)} \notin [Z(T,T) \times |f_{t}]$
 $= P(t,T) \frac{1}{Z(t,T)} \notin [X/f_{t}] \rightarrow \mathcal{B}$

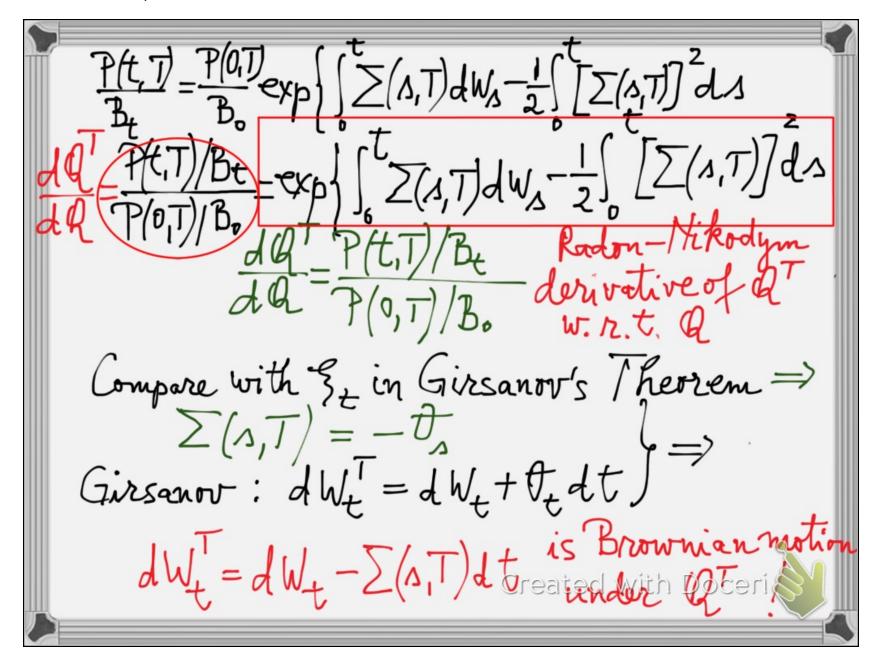
and \mathcal{F}_{T}
 $= P(t,T) \frac{Z(0,T)}{Z(t,T)} \notin [X/f_{t}] \rightarrow \mathcal{B}$
 $= P(t,T) \notin [X/f_{t}] \rightarrow \mathcal{B}$

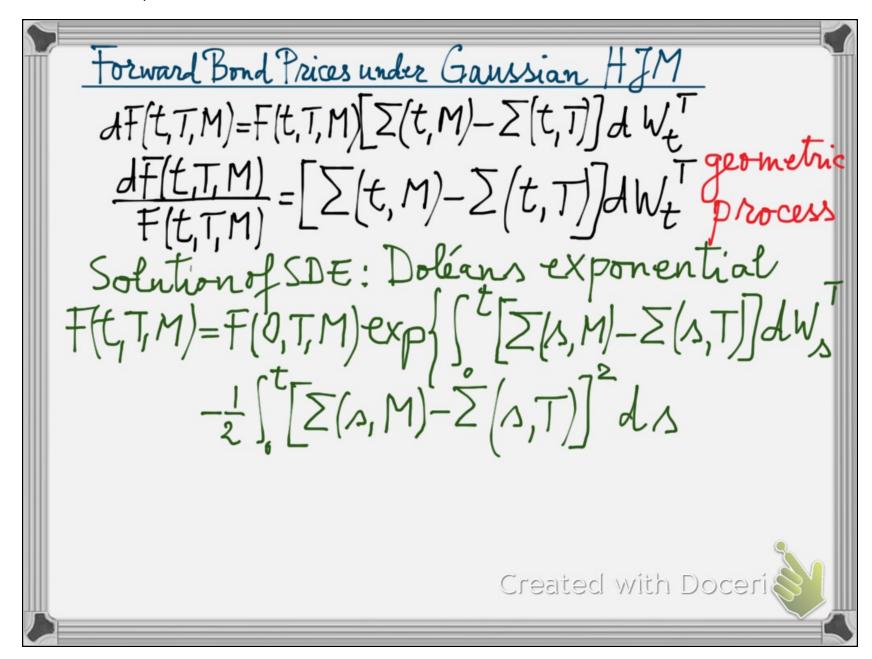
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The process
$$\{F(t,T,M)\}_{t=0}^{T}$$
 is a martingale under Q^{T}
 $F(t,T,M) = \frac{P(t,M)}{P(t,T)}$
 $t=T: F(T,T,M) = \frac{P(T,M)}{P(T,T)} = P(T,M)$
 $F(t,T,M) = E^{T}[P(T,M)|\mathcal{F}_{t}]$
 $F(t,T,M) = E^{T}[F(T,T,M)|\mathcal{F}_{t}] \Rightarrow F(t,T,M)$ is a Q^{T} -martingale created with Doceri

orward Measure in Gaussian H = P(t, T) - is a martingale under Q $dZ(t,T) = \sum (t,T)Z(t,T)dW_t / : Z(t,T)$ dZ(t,T) = \(\bar{Z}(t,T) dW_t \Rightarrow \begin{array}{c} \text{geometric} \\ \frac{1}{2}(t,T) dW_t \Rightarrow \text{process} \end{array} Solution of SDE: Doléans exponential & Brownian motion Created with Doce





$$log(\frac{F(t,T,M)}{F(0,T,M)}) = \int_{0}^{t} \left[\sum(A,M) - \sum(A,T) \right] dW_{A}^{T} - \frac{1}{2} \int_{0}^{t} \left[\sum(A,M) - \sum(A,T) \right]^{2} dA$$

$$= -\frac{1}{2} \int_{0}^{t} \left[\sum(A,M) - \sum(A,T) \right]^{2} dA$$

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