```
C:\ProgramData\Anaconda3\python.exe "D:/OneDrive - University of Florida/Documents/UF School Projects/Deep Learning/GameGAN/gan_example.py"
Random Seed:  999
Generator(
  (main): Sequential(
    (0): ConvTranspose2d(100, 512, kernel_size=(4, 4), stride=(1, 1), bias=False)
    (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (2): ReLU(inplace=True)
    (3): ConvTranspose2d(512, 256, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (4): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (5): ReLU(inplace=True)
    (6): ConvTranspose2d(256, 128, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (7): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (8): ReLU(inplace=True)
    (9): ConvTranspose2d(128, 64, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (10): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (11): ReLU(inplace=True)
    (12): ConvTranspose2d(64, 3, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (13): Tanh()
  )
)
Discriminator(
  (main): Sequential(
    (0): Conv2d(3, 64, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (1): LeakyReLU(negative_slope=0.2, inplace=True)
    (2): Conv2d(64, 128, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (3): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (4): LeakyReLU(negative_slope=0.2, inplace=True)
    (5): Conv2d(128, 256, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (6): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (7): LeakyReLU(negative_slope=0.2, inplace=True)
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    (8): Conv2d(256, 512, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
    (9): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (10): LeakyReLU(negative_slope=0.2, inplace=True)
    (11): Conv2d(512, 1, kernel_size=(4, 4), stride=(1, 1), bias=False)
    (12): Sigmoid()
  )
)
Starting Training Loop...
[0/5][0/1583]   Loss_D: 1.5918  Loss_G: 5.4597  D(x): 0.5836    D(G(z)): 0.5501 / 0.0071
[0/5][50/1583]  Loss_D: 0.2295  Loss_G: 20.7922 D(x): 0.9227    D(G(z)): 0.0000 / 0.0000
[0/5][100/1583] Loss_D: 1.3583  Loss_G: 14.9177 D(x): 0.9447    D(G(z)): 0.6459 / 0.0000
[0/5][150/1583] Loss_D: 0.9721  Loss_G: 1.2263  D(x): 0.5143    D(G(z)): 0.0223 / 0.3884
[0/5][200/1583] Loss_D: 0.4550  Loss_G: 6.0048  D(x): 0.8834    D(G(z)): 0.2357 / 0.0052
[0/5][250/1583] Loss_D: 1.6101  Loss_G: 10.0624 D(x): 0.9570    D(G(z)): 0.7052 / 0.0003
[0/5][300/1583] Loss_D: 0.3385  Loss_G: 5.2574  D(x): 0.8189    D(G(z)): 0.0797 / 0.0131
[0/5][350/1583] Loss_D: 0.7526  Loss_G: 3.3703  D(x): 0.5897    D(G(z)): 0.0255 / 0.0662
[0/5][400/1583] Loss_D: 0.5943  Loss_G: 3.3682  D(x): 0.6703    D(G(z)): 0.0244 / 0.0581
[0/5][450/1583] Loss_D: 0.6817  Loss_G: 7.0480  D(x): 0.9499    D(G(z)): 0.4070 / 0.0023
[0/5][500/1583] Loss_D: 1.0027  Loss_G: 2.1860  D(x): 0.5007    D(G(z)): 0.0128 / 0.2211
[0/5][550/1583] Loss_D: 0.6713  Loss_G: 5.6073  D(x): 0.6667    D(G(z)): 0.0205 / 0.0109
[0/5][600/1583] Loss_D: 0.3250  Loss_G: 3.4123  D(x): 0.9264    D(G(z)): 0.1888 / 0.0586
[0/5][650/1583] Loss_D: 0.4655  Loss_G: 5.2837  D(x): 0.7373    D(G(z)): 0.0379 / 0.0126
[0/5][700/1583] Loss_D: 0.4697  Loss_G: 3.3961  D(x): 0.7392    D(G(z)): 0.0809 / 0.0488
[0/5][750/1583] Loss_D: 1.0460  Loss_G: 4.3714  D(x): 0.5026    D(G(z)): 0.0077 / 0.0398
[0/5][800/1583] Loss_D: 0.9296  Loss_G: 1.8271  D(x): 0.5526    D(G(z)): 0.0754 / 0.2254
[0/5][850/1583] Loss_D: 0.3239  Loss_G: 5.6506  D(x): 0.
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56 9092    D(G(z)): 0.1601 / 0.0079
57 [0/5][900/1583] Loss_D: 1.7361  Loss_G: 10.3272 D(x): 0.
   9390    D(G(z)): 0.7633 / 0.0001
58 [0/5][950/1583] Loss_D: 0.4914  Loss_G: 4.6603  D(x): 0.
   6938    D(G(z)): 0.0328 / 0.0254
59 [0/5][1000/1583]    Loss_D: 0.9765  Loss_G: 7.2924  D(x):
   0.9781  D(G(z)): 0.5518 / 0.0014
60 [0/5][1050/1583]    Loss_D: 0.2666  Loss_G: 6.1004  D(x):
   0.8204  D(G(z)): 0.0236 / 0.0061
61 [0/5][1100/1583]    Loss_D: 0.5573  Loss_G: 2.3688  D(x):
   0.7269  D(G(z)): 0.1075 / 0.1272
62 [0/5][1150/1583]    Loss_D: 0.5601  Loss_G: 3.8881  D(x):
   0.7795  D(G(z)): 0.1955 / 0.0407
63 [0/5][1200/1583]    Loss_D: 0.4976  Loss_G: 4.1517  D(x):
   0.7181  D(G(z)): 0.0371 / 0.0315
64 [0/5][1250/1583]    Loss_D: 0.4517  Loss_G: 4.8939  D(x):
   0.8917  D(G(z)): 0.2192 / 0.0167
65 [0/5][1300/1583]    Loss_D: 0.9825  Loss_G: 5.6769  D(x):
   0.9028  D(G(z)): 0.5064 / 0.0078
66 [0/5][1350/1583]    Loss_D: 0.4574  Loss_G: 3.4318  D(x):
   0.8355  D(G(z)): 0.1977 / 0.0503
67 [0/5][1400/1583]    Loss_D: 0.3605  Loss_G: 3.4465  D(x):
   0.8108  D(G(z)): 0.1023 / 0.0505
68 [0/5][1450/1583]    Loss_D: 0.6681  Loss_G: 1.7035  D(x):
   0.6811  D(G(z)): 0.1459 / 0.2505
69 [0/5][1500/1583]    Loss_D: 2.7337  Loss_G: 2.7107  D(x):
   0.1358  D(G(z)): 0.0035 / 0.1184
70 [0/5][1550/1583]    Loss_D: 0.3848  Loss_G: 4.4620  D(x):
   0.8544  D(G(z)): 0.1766 / 0.0182
71 [1/5][0/1583]   Loss_D: 0.4767  Loss_G: 3.1798  D(x): 0.
   7769    D(G(z)): 0.1308 / 0.0667
72 [1/5][50/1583]  Loss_D: 0.8641  Loss_G: 1.5597  D(x): 0.
   5293    D(G(z)): 0.0162 / 0.2742
73 [1/5][100/1583] Loss_D: 0.4848  Loss_G: 4.6732  D(x): 0.
   6700    D(G(z)): 0.0118 / 0.0201
74 [1/5][150/1583] Loss_D: 0.4625  Loss_G: 2.9568  D(x): 0.
   7397    D(G(z)): 0.0921 / 0.0767
75 [1/5][200/1583] Loss_D: 1.0677  Loss_G: 6.9297  D(x): 0.
   8843    D(G(z)): 0.5065 / 0.0025
76 [1/5][250/1583] Loss_D: 1.5085  Loss_G: 2.5293  D(x): 0.
   3645    D(G(z)): 0.0225 / 0.1776
77 [1/5][300/1583] Loss_D: 0.4499  Loss_G: 3.2860  D(x): 0.
   8773    D(G(z)): 0.2330 / 0.0562
78 [1/5][350/1583] Loss_D: 0.5731  Loss_G: 1.6582  D(x): 0.
   6743    D(G(z)): 0.0704 / 0.2787
79 [1/5][400/1583] Loss_D: 0.7705  Loss_G: 4.7851  D(x): 0.
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 79 7845    D(G(z)): 0.3362 / 0.0152
 80 [1/5][450/1583] Loss_D: 0.4202  Loss_G: 2.6871  D(x): 0.
    7516    D(G(z)): 0.0683 / 0.1039
 81 [1/5][500/1583] Loss_D: 0.6888  Loss_G: 2.1421  D(x): 0.
    6430    D(G(z)): 0.1171 / 0.1620
 82 [1/5][550/1583] Loss_D: 0.9476  Loss_G: 6.2524  D(x): 0.
    9764    D(G(z)): 0.5420 / 0.0038
 83 [1/5][600/1583] Loss_D: 0.4726  Loss_G: 2.2285  D(x): 0.
    7630    D(G(z)): 0.1205 / 0.1444
 84 [1/5][650/1583] Loss_D: 0.5096  Loss_G: 3.7754  D(x): 0.
    8545    D(G(z)): 0.2660 / 0.0330
 85 [1/5][700/1583] Loss_D: 1.4746  Loss_G: 6.5215  D(x): 0.
    9878    D(G(z)): 0.6936 / 0.0063
 86 [1/5][750/1583] Loss_D: 0.4420  Loss_G: 3.3446  D(x): 0.
    7789    D(G(z)): 0.1357 / 0.0561
 87 [1/5][800/1583] Loss_D: 0.6884  Loss_G: 3.7245  D(x): 0.
    8075    D(G(z)): 0.3087 / 0.0400
 88 [1/5][850/1583] Loss_D: 2.6146  Loss_G: 6.8374  D(x): 0.
    9890    D(G(z)): 0.8768 / 0.0027
 89 [1/5][900/1583] Loss_D: 0.3749  Loss_G: 2.6383  D(x): 0.
    7771    D(G(z)): 0.0806 / 0.0965
 90 [1/5][950/1583] Loss_D: 0.6221  Loss_G: 2.1754  D(x): 0.
    6167    D(G(z)): 0.0501 / 0.1451
 91 [1/5][1000/1583]    Loss_D: 1.0061  Loss_G: 0.4073  D(x):
    0.4620  D(G(z)): 0.0269 / 0.7018
 92 [1/5][1050/1583]    Loss_D: 0.4377  Loss_G: 2.7406  D(x):
    0.8072  D(G(z)): 0.1714 / 0.0879
 93 [1/5][1100/1583]    Loss_D: 0.6339  Loss_G: 4.6699  D(x):
    0.9394  D(G(z)): 0.3924 / 0.0152
 94 [1/5][1150/1583]    Loss_D: 0.8127  Loss_G: 5.4041  D(x):
    0.9589  D(G(z)): 0.4723 / 0.0074
 95 [1/5][1200/1583]    Loss_D: 0.6086  Loss_G: 4.3503  D(x):
    0.9315  D(G(z)): 0.3711 / 0.0201
 96 [1/5][1250/1583]    Loss_D: 0.6289  Loss_G: 3.4261  D(x):
    0.8003  D(G(z)): 0.2712 / 0.0546
 97 [1/5][1300/1583]    Loss_D: 0.4301  Loss_G: 2.7215  D(x):
    0.7998  D(G(z)): 0.1486 / 0.0843
 98 [1/5][1350/1583]    Loss_D: 0.4743  Loss_G: 2.2206  D(x):
    0.7328  D(G(z)): 0.1101 / 0.1501
 99 [1/5][1400/1583]    Loss_D: 0.5278  Loss_G: 2.9643  D(x):
    0.8504  D(G(z)): 0.2748 / 0.0718
100 [1/5][1450/1583]    Loss_D: 1.1246  Loss_G: 1.1294  D(x):
    0.4125  D(G(z)): 0.0460 / 0.4068
101 [1/5][1500/1583]    Loss_D: 0.4695  Loss_G: 2.8411  D(x):
    0.8246  D(G(z)): 0.1974 / 0.0829
102 [1/5][1550/1583]    Loss_D: 0.5891  Loss_G: 2.0271  D(x):
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102 0.6578  D(G(z)): 0.1055 / 0.1788
103 [2/5][0/1583]   Loss_D: 1.2322  Loss_G: 6.1466  D(x): 0.
    9757    D(G(z)): 0.6471 / 0.0033
104 [2/5][50/1583]  Loss_D: 0.6669  Loss_G: 3.4929  D(x): 0.
    9375    D(G(z)): 0.3959 / 0.0507
105 [2/5][100/1583] Loss_D: 0.5032  Loss_G: 2.1608  D(x): 0.
    7674    D(G(z)): 0.1740 / 0.1490
106 [2/5][150/1583] Loss_D: 0.5911  Loss_G: 2.0231  D(x): 0.
    7186    D(G(z)): 0.1652 / 0.1675
107 [2/5][200/1583] Loss_D: 0.9226  Loss_G: 3.2813  D(x): 0.
    8595    D(G(z)): 0.4637 / 0.0564
108 [2/5][250/1583] Loss_D: 0.4314  Loss_G: 2.9283  D(x): 0.
    8443    D(G(z)): 0.2043 / 0.0701
109 [2/5][300/1583] Loss_D: 0.7165  Loss_G: 3.5987  D(x): 0.
    8000    D(G(z)): 0.3482 / 0.0377
110 [2/5][350/1583] Loss_D: 0.6730  Loss_G: 4.0261  D(x): 0.
    8829    D(G(z)): 0.3776 / 0.0251
111 [2/5][400/1583] Loss_D: 0.7580  Loss_G: 4.2597  D(x): 0.
    9273    D(G(z)): 0.4626 / 0.0200
112 [2/5][450/1583] Loss_D: 0.7365  Loss_G: 4.5159  D(x): 0.
    8998    D(G(z)): 0.3975 / 0.0223
113 [2/5][500/1583] Loss_D: 0.8086  Loss_G: 1.3333  D(x): 0.
    5802    D(G(z)): 0.1510 / 0.3030
114 [2/5][550/1583] Loss_D: 1.4943  Loss_G: 0.4932  D(x): 0.
    3122    D(G(z)): 0.0190 / 0.6595
115 [2/5][600/1583] Loss_D: 0.4589  Loss_G: 3.1693  D(x): 0.
    8572    D(G(z)): 0.2243 / 0.0600
116 [2/5][650/1583] Loss_D: 0.6049  Loss_G: 1.8836  D(x): 0.
    6880    D(G(z)): 0.1493 / 0.1858
117 [2/5][700/1583] Loss_D: 0.5689  Loss_G: 3.1882  D(x): 0.
    8242    D(G(z)): 0.2772 / 0.0554
118 [2/5][750/1583] Loss_D: 0.4869  Loss_G: 2.8370  D(x): 0.
    7630    D(G(z)): 0.1280 / 0.0832
119 [2/5][800/1583] Loss_D: 0.9424  Loss_G: 4.6697  D(x): 0.
    9382    D(G(z)): 0.5369 / 0.0157
120 [2/5][850/1583] Loss_D: 1.0867  Loss_G: 0.7338  D(x): 0.
    4426    D(G(z)): 0.0709 / 0.5255
121 [2/5][900/1583] Loss_D: 0.6354  Loss_G: 1.6458  D(x): 0.
    6427    D(G(z)): 0.1060 / 0.2289
122 [2/5][950/1583] Loss_D: 0.7523  Loss_G: 1.1882  D(x): 0.
    5584    D(G(z)): 0.0739 / 0.3562
123 [2/5][1000/1583]    Loss_D: 1.4147  Loss_G: 0.2441  D(x):
    0.3126  D(G(z)): 0.0565 / 0.8029
124 [2/5][1050/1583]    Loss_D: 1.3861  Loss_G: 0.3535  D(x):
    0.3283  D(G(z)): 0.0295 / 0.7492
125 [2/5][1100/1583]    Loss_D: 1.1007  Loss_G: 1.2930  D(x):
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125 0.4386  D(G(z)): 0.0541 / 0.3405
126 [2/5][1150/1583]    Loss_D: 0.6259  Loss_G: 2.8402  D(x):
    0.9269  D(G(z)): 0.3853 / 0.0808
127 [2/5][1200/1583]    Loss_D: 0.6398  Loss_G: 2.3106  D(x):
    0.7125  D(G(z)): 0.1915 / 0.1264
128 [2/5][1250/1583]    Loss_D: 0.3864  Loss_G: 2.7747  D(x):
    0.8696  D(G(z)): 0.1939 / 0.0757
129 [2/5][1300/1583]    Loss_D: 1.6018  Loss_G: 5.0926  D(x):
    0.6629  D(G(z)): 0.6345 / 0.0100
130 [2/5][1350/1583]    Loss_D: 0.5428  Loss_G: 2.0593  D(x):
    0.7948  D(G(z)): 0.2225 / 0.1668
131 [2/5][1400/1583]    Loss_D: 0.4843  Loss_G: 1.6450  D(x):
    0.7069  D(G(z)): 0.0850 / 0.2366
132 [2/5][1450/1583]    Loss_D: 0.6850  Loss_G: 3.7081  D(x):
    0.9518  D(G(z)): 0.4251 / 0.0344
133 [2/5][1500/1583]    Loss_D: 0.4936  Loss_G: 2.8467  D(x):
    0.8358  D(G(z)): 0.2408 / 0.0765
134 [2/5][1550/1583]    Loss_D: 0.4871  Loss_G: 2.1306  D(x):
    0.7784  D(G(z)): 0.1831 / 0.1451
135 [3/5][0/1583]   Loss_D: 1.1357  Loss_G: 1.4700  D(x): 0.
    4161    D(G(z)): 0.0359 / 0.2897
136 [3/5][50/1583]  Loss_D: 0.7877  Loss_G: 1.1609  D(x): 0.
    5320    D(G(z)): 0.0557 / 0.3594
137 [3/5][100/1583] Loss_D: 0.6214  Loss_G: 1.7761  D(x): 0.
    6599    D(G(z)): 0.1349 / 0.2074
138 [3/5][150/1583] Loss_D: 0.9499  Loss_G: 3.3906  D(x): 0.
    8233    D(G(z)): 0.4602 / 0.0441
139 [3/5][200/1583] Loss_D: 0.5910  Loss_G: 3.1253  D(x): 0.
    8644    D(G(z)): 0.3245 / 0.0587
140 [3/5][250/1583] Loss_D: 0.6496  Loss_G: 1.3246  D(x): 0.
    6168    D(G(z)): 0.0906 / 0.3149
141 [3/5][300/1583] Loss_D: 0.5270  Loss_G: 2.5967  D(x): 0.
    8514    D(G(z)): 0.2726 / 0.0958
142 [3/5][350/1583] Loss_D: 0.5545  Loss_G: 3.1883  D(x): 0.
    8510    D(G(z)): 0.2929 / 0.0553
143 [3/5][400/1583] Loss_D: 0.5865  Loss_G: 2.2572  D(x): 0.
    7314    D(G(z)): 0.2035 / 0.1317
144 [3/5][450/1583] Loss_D: 0.8535  Loss_G: 1.6745  D(x): 0.
    5191    D(G(z)): 0.0554 / 0.2440
145 [3/5][500/1583] Loss_D: 1.3695  Loss_G: 1.0962  D(x): 0.
    4392    D(G(z)): 0.2862 / 0.3925
146 [3/5][550/1583] Loss_D: 0.6613  Loss_G: 1.6361  D(x): 0.
    6238    D(G(z)): 0.1175 / 0.2295
147 [3/5][600/1583] Loss_D: 0.9184  Loss_G: 1.1648  D(x): 0.
    4703    D(G(z)): 0.0425 / 0.3752
148 [3/5][650/1583] Loss_D: 1.0849  Loss_G: 2.7988  D(x): 0.
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148 7930    D(G(z)): 0.5041 / 0.0870
149 [3/5][700/1583] Loss_D: 0.6386  Loss_G: 3.1799  D(x): 0.
    8793    D(G(z)): 0.3601 / 0.0540
150 [3/5][750/1583] Loss_D: 0.6542  Loss_G: 2.0810  D(x): 0.
    6733    D(G(z)): 0.1677 / 0.1626
151 [3/5][800/1583] Loss_D: 0.5495  Loss_G: 2.6888  D(x): 0.
    7853    D(G(z)): 0.2248 / 0.0876
152 [3/5][850/1583] Loss_D: 0.6327  Loss_G: 2.8387  D(x): 0.
    8580    D(G(z)): 0.3312 / 0.0815
153 [3/5][900/1583] Loss_D: 0.6607  Loss_G: 2.8690  D(x): 0.
    7731    D(G(z)): 0.3008 / 0.0695
154 [3/5][950/1583] Loss_D: 0.5300  Loss_G: 1.9856  D(x): 0.
    7516    D(G(z)): 0.1798 / 0.1696
155 [3/5][1000/1583]    Loss_D: 0.6397  Loss_G: 2.0522  D(x):
    0.6258  D(G(z)): 0.0919 / 0.1750
156 [3/5][1050/1583]    Loss_D: 0.7322  Loss_G: 3.7052  D(x):
    0.8605  D(G(z)): 0.3999 / 0.0356
157 [3/5][1100/1583]    Loss_D: 1.0464  Loss_G: 1.5835  D(x):
    0.4126  D(G(z)): 0.0306 / 0.2580
158 [3/5][1150/1583]    Loss_D: 0.7113  Loss_G: 3.0336  D(x):
    0.7785  D(G(z)): 0.3287 / 0.0611
159 [3/5][1200/1583]    Loss_D: 1.0937  Loss_G: 4.8021  D(x):
    0.9430  D(G(z)): 0.6031 / 0.0125
160 [3/5][1250/1583]    Loss_D: 0.7665  Loss_G: 1.6885  D(x):
    0.5936  D(G(z)): 0.1327 / 0.2228
161 [3/5][1300/1583]    Loss_D: 3.2998  Loss_G: 0.2287  D(x):
    0.0679  D(G(z)): 0.0209 / 0.8242
162 [3/5][1350/1583]    Loss_D: 0.6968  Loss_G: 2.7098  D(x):
    0.7416  D(G(z)): 0.2654 / 0.0927
163 [3/5][1400/1583]    Loss_D: 0.4728  Loss_G: 2.2028  D(x):
    0.7943  D(G(z)): 0.1870 / 0.1410
164 [3/5][1450/1583]    Loss_D: 0.6065  Loss_G: 1.9877  D(x):
    0.7276  D(G(z)): 0.2100 / 0.1609
165 [3/5][1500/1583]    Loss_D: 1.2276  Loss_G: 0.7982  D(x):
    0.3834  D(G(z)): 0.0475 / 0.5024
166 [3/5][1550/1583]    Loss_D: 0.7563  Loss_G: 3.6247  D(x):
    0.8359  D(G(z)): 0.4017 / 0.0343
167 [4/5][0/1583]   Loss_D: 0.7216  Loss_G: 1.6459  D(x): 0.
    5646    D(G(z)): 0.0620 / 0.2472
168 [4/5][50/1583]  Loss_D: 0.7328  Loss_G: 1.4794  D(x): 0.
    5787    D(G(z)): 0.0844 / 0.2805
169 [4/5][100/1583] Loss_D: 2.2541  Loss_G: 3.0769  D(x): 0.
    8644    D(G(z)): 0.8141 / 0.0703
170 [4/5][150/1583] Loss_D: 0.7420  Loss_G: 1.7439  D(x): 0.
    5679    D(G(z)): 0.0982 / 0.2146
171 [4/5][200/1583] Loss_D: 0.5607  Loss_G: 2.6178  D(x): 0.
```

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171 8228    D(G(z)): 0.2689 / 0.0943
172 [4/5][250/1583] Loss_D: 0.6236  Loss_G: 1.6015  D(x): 0.
    5941    D(G(z)): 0.0467 / 0.2395
173 [4/5][300/1583] Loss_D: 1.5956  Loss_G: 4.6873  D(x): 0.
    9197    D(G(z)): 0.7256 / 0.0148
174 [4/5][350/1583] Loss_D: 0.4584  Loss_G: 2.5813  D(x): 0.
    8403    D(G(z)): 0.2168 / 0.0972
175 [4/5][400/1583] Loss_D: 0.6654  Loss_G: 1.8826  D(x): 0.
    6217    D(G(z)): 0.0987 / 0.2035
176 [4/5][450/1583] Loss_D: 0.5910  Loss_G: 2.8118  D(x): 0.
    8170    D(G(z)): 0.2794 / 0.0789
177 [4/5][500/1583] Loss_D: 0.8112  Loss_G: 2.4788  D(x): 0.
    6556    D(G(z)): 0.2422 / 0.1093
178 [4/5][550/1583] Loss_D: 0.5854  Loss_G: 2.2619  D(x): 0.
    6450    D(G(z)): 0.0890 / 0.1328
179 [4/5][600/1583] Loss_D: 0.7073  Loss_G: 3.4554  D(x): 0.
    9186    D(G(z)): 0.4254 / 0.0424
180 [4/5][650/1583] Loss_D: 0.6949  Loss_G: 1.6728  D(x): 0.
    6889    D(G(z)): 0.2229 / 0.2206
181 [4/5][700/1583] Loss_D: 0.4998  Loss_G: 2.1635  D(x): 0.
    7364    D(G(z)): 0.1440 / 0.1417
182 [4/5][750/1583] Loss_D: 0.5800  Loss_G: 1.8631  D(x): 0.
    6649    D(G(z)): 0.1125 / 0.2041
183 [4/5][800/1583] Loss_D: 0.8134  Loss_G: 2.9043  D(x): 0.
    7374    D(G(z)): 0.3330 / 0.0760
184 [4/5][850/1583] Loss_D: 0.9117  Loss_G: 1.0189  D(x): 0.
    5228    D(G(z)): 0.1258 / 0.4103
185 [4/5][900/1583] Loss_D: 0.5429  Loss_G: 1.7079  D(x): 0.
    7027    D(G(z)): 0.1293 / 0.2168
186 [4/5][950/1583] Loss_D: 0.5842  Loss_G: 3.0329  D(x): 0.
    8768    D(G(z)): 0.3313 / 0.0647
187 [4/5][1000/1583]    Loss_D: 0.8462  Loss_G: 4.4959  D(x):
    0.8826  D(G(z)): 0.4678 / 0.0161
188 [4/5][1050/1583]    Loss_D: 0.6464  Loss_G: 2.9920  D(x):
    0.8068  D(G(z)): 0.3028 / 0.0698
189 [4/5][1100/1583]    Loss_D: 0.7514  Loss_G: 1.1926  D(x):
    0.5327  D(G(z)): 0.0422 / 0.3498
190 [4/5][1150/1583]    Loss_D: 0.5610  Loss_G: 3.5384  D(x):
    0.8547  D(G(z)): 0.2998 / 0.0385
191 [4/5][1200/1583]    Loss_D: 0.8598  Loss_G: 4.3095  D(x):
    0.9587  D(G(z)): 0.5146 / 0.0192
192 [4/5][1250/1583]    Loss_D: 0.7195  Loss_G: 1.5337  D(x):
    0.5684  D(G(z)): 0.0620 / 0.2695
193 [4/5][1300/1583]    Loss_D: 0.7392  Loss_G: 1.6890  D(x):
    0.6911  D(G(z)): 0.2623 / 0.2191
194 [4/5][1350/1583]    Loss_D: 1.2008  Loss_G: 4.7425  D(x):
```

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194 0.8964  D(G(z)): 0.6151 / 0.0130
195 [4/5][1400/1583]    Loss_D: 1.1807  Loss_G: 4.2280  D(x):
    0.9444  D(G(z)): 0.6085 / 0.0240
196 [4/5][1450/1583]    Loss_D: 0.5469  Loss_G: 3.1402  D(x):
    0.8597  D(G(z)): 0.2880 / 0.0589
197 [4/5][1500/1583]    Loss_D: 0.4588  Loss_G: 1.9041  D(x):
    0.7369  D(G(z)): 0.1162 / 0.1918
198 [4/5][1550/1583]    Loss_D: 0.6402  Loss_G: 3.0085  D(x):
    0.8543  D(G(z)): 0.3458 / 0.0623
199
200 Process finished with exit code 0
201
```