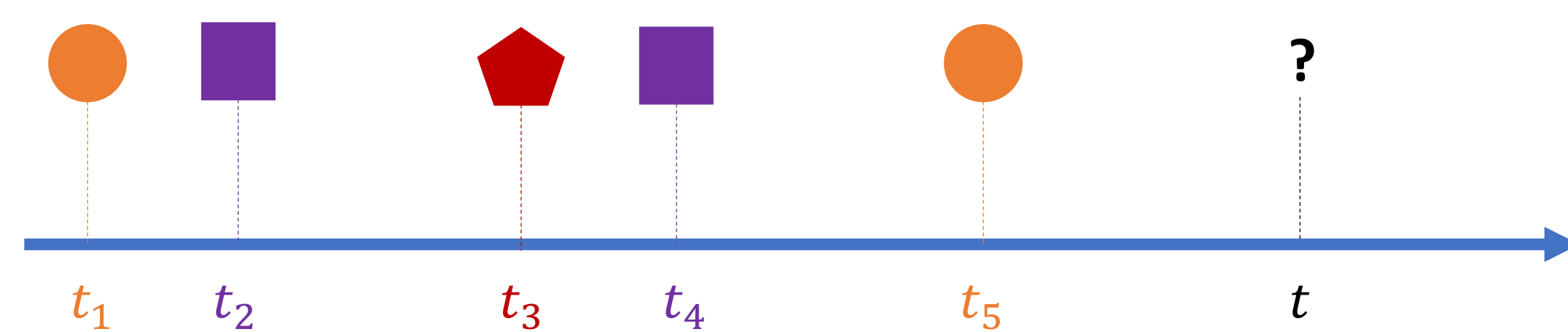


tl;dr

- Adaptive prediction for the next event
- Real time uncertainty estimation in asynchronous event prediction

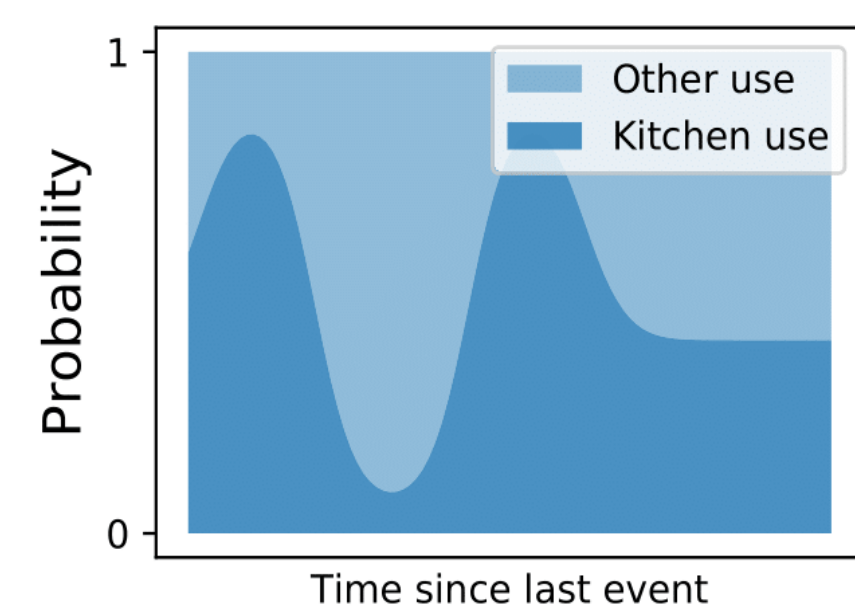
Asynchronous events

- Discrete events occurring *irregularly* over time
- At a given time, the most probable event can change

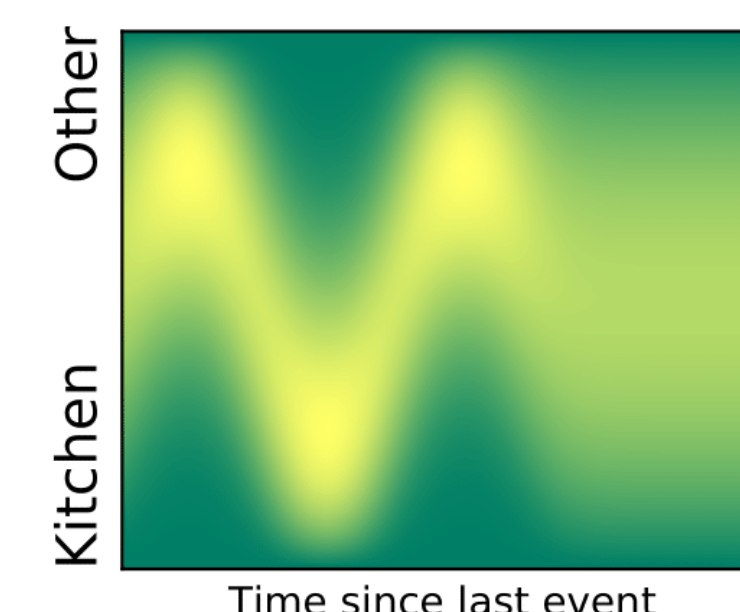


Research questions

- Prediction:** At a given time, what event is likely to occur?
- Uncertainty estimation:** How sure are we in our prediction?



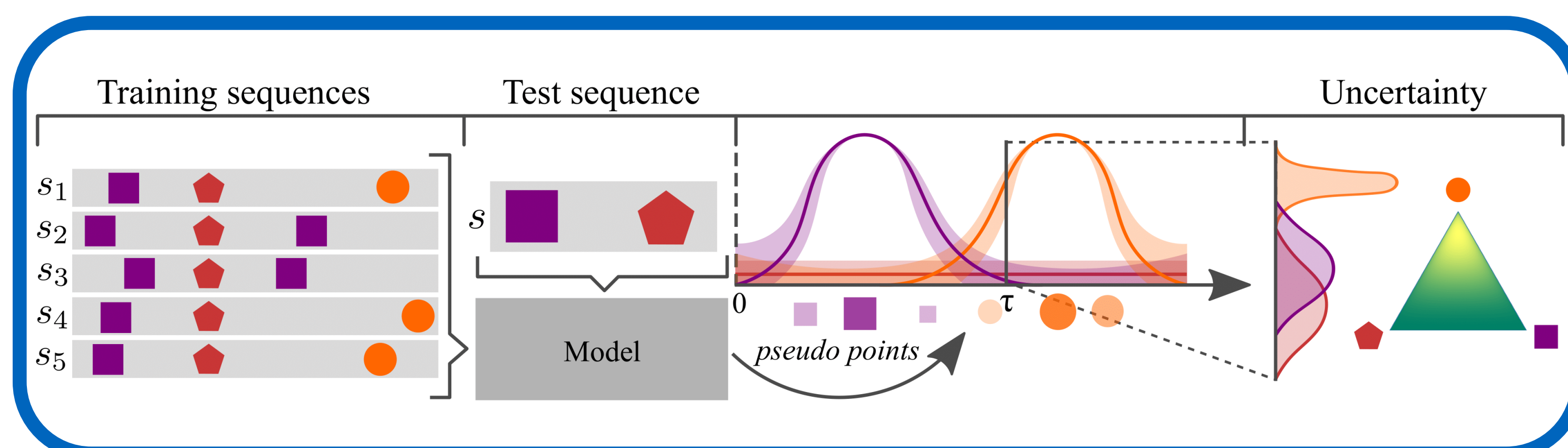
(1) Prediction



(2) Uncertainty estimation

Model overview

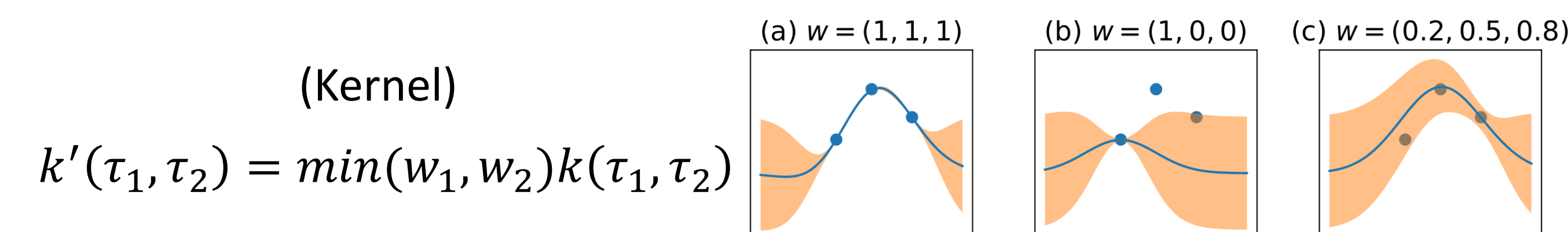
- For each class c , generate M **pseudo points** $(w_j^{(c)}, \tau_j^{(c)}, y_j^{(c)})$ based on a hidden state of an RNN whose input is a sequence.
- Fit a **complex** evolution of the predicted categorical distribution $p(\tau) \sim P(\theta(\tau))$. The distribution over the simplex $P(\theta(\tau))$ gives **certainty localized** around pseudo points.



*Equal contribution

Model 1: Logistic Normal via Weighted Gaussian Process

- The pseudo points $(\tau_j^{(c)}, y_j^{(c)})$ weighted with $w_j^{(c)}$ are used to generate a **Weighted Gaussian Process** in the logit-space. The weights $w_j^{(c)}$ allow to discard unnecessary training points in Gaussian Process.



- The distribution $p_c(\tau) \sim \text{logistic } N(\tau_c(\tau), \sigma_c^2(\tau))$ follows a **Logistic Normal distribution**.

Model 2: Dirichlet via Function Decomposition

- The pseudo points $(w_j^{(c)}, \tau_j^{(c)}, \sigma_j^{(c)})$ are used to describe the evolution of the Dirichlet parameters over time via **function decomposition**.

$$\log \alpha_c(\tau) = \sum_{j=1}^M w_j^{(c)} \cdot N(\tau | \tau_j^{(c)}, \sigma_j^{(c)}) + \vartheta$$

Effective number of observations of class c at time τ Function decomposition Prior

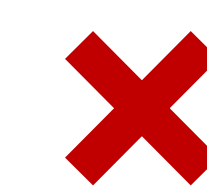
- The distribution $p(\tau) \sim \text{Dir}(\alpha_c(\tau))$ follows a **Dirichlet distribution**.

Uncertainty Cross Entropy

- The classic Cross Entropy loss looks only at the mean of the distribution $P(\theta(\tau))$:

$$\mathcal{L}_i^{UCE} = H[p_i^*, \bar{p}_i]$$

$$\text{where } \bar{p}_i(\tau) = \mathbb{E}_{p_i \sim P_i(\theta(\tau_i))}[p_i]$$



Not suited for uncertainty estimation

- The Uncertainty Cross entropy loss looks at the distribution $P(\theta(\tau))$:

$$\mathcal{L}_i^{UCE} = \mathbb{E}_{p_i \sim P_i(\theta(\tau_i^*))}[H[p_i^*, p_i]]$$



Take care of uncertainty estimation

- Regularizer adjust uncertainty estimation of out-of-distribution data:

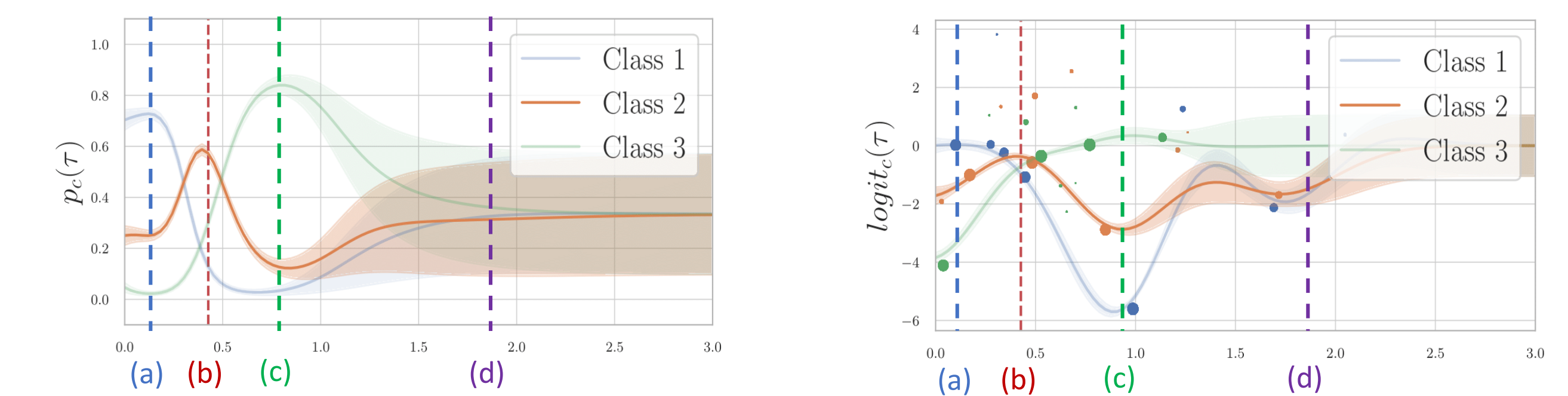
$$r_c = \alpha \int_0^T (\mu_c)^2 d\tau + \beta \int_0^T (\vartheta - \sigma_c^2) d\tau$$

Computed by sampling

Pushes mean to 0

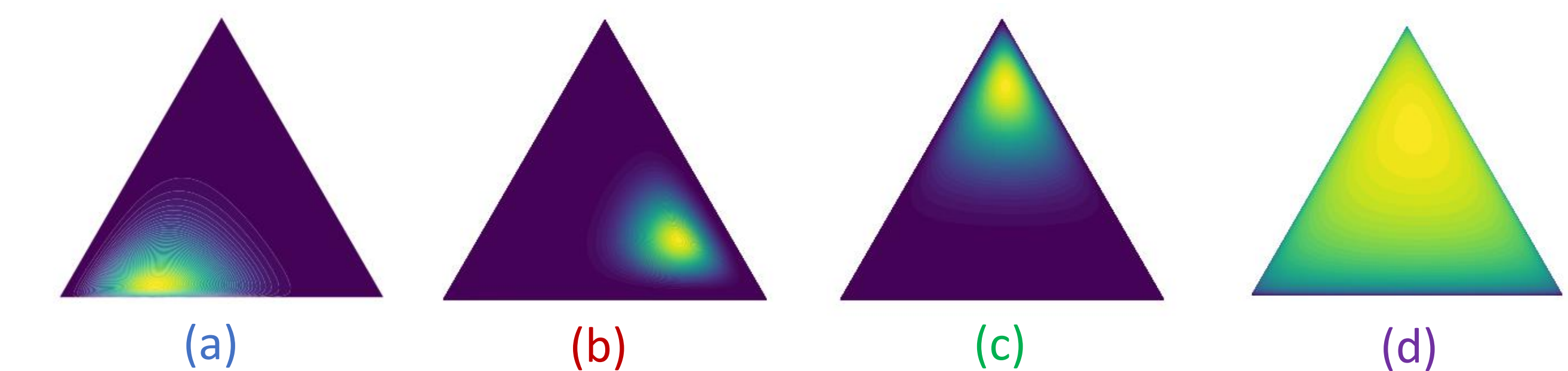
Pushes variance to ϑ

Experiment: Visualization

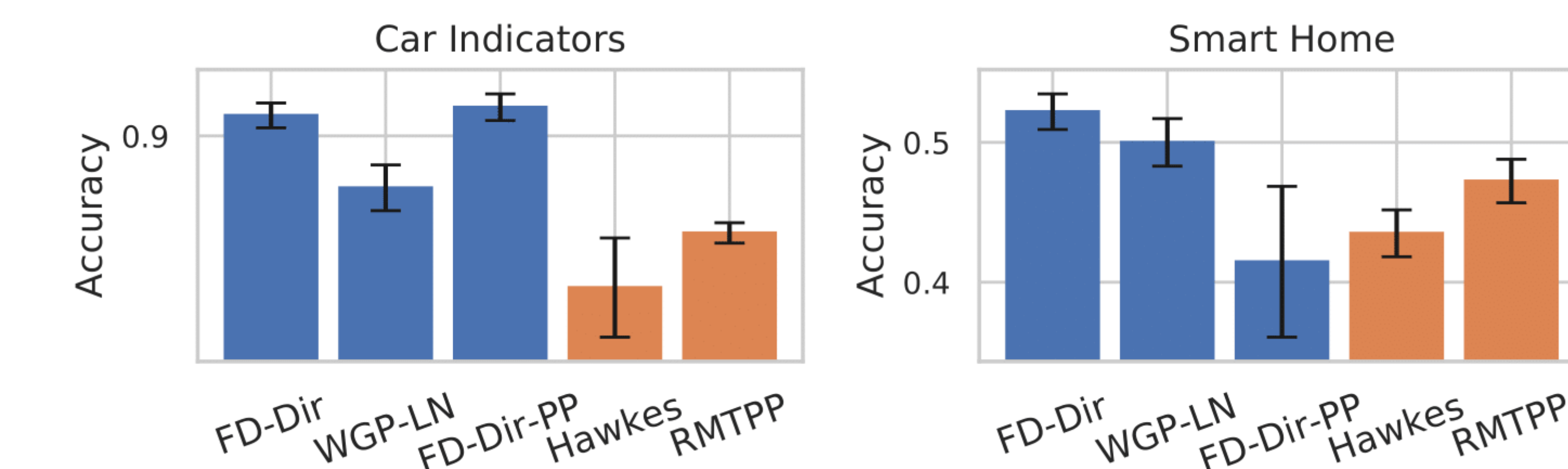


FD-Dir

LN-WGP



Experiment: Prediction



Experiment: Uncertainty

