

QDT: Gaussian process models

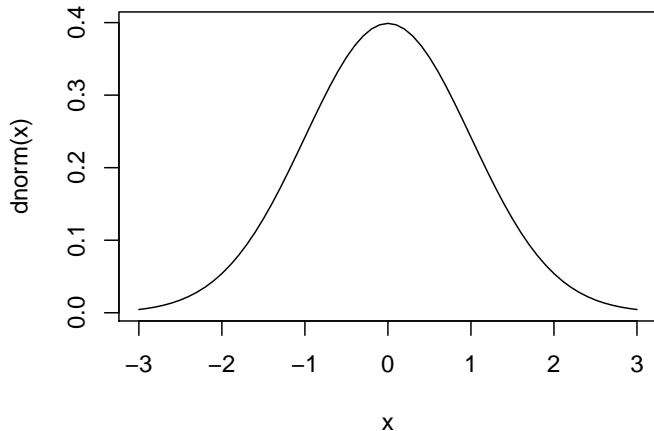
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October 21, 2015

Background: univariate normal

$$x \sim N(\mu, \sigma^2)$$

Normal(0, 1) probability density



Background: multivariate normal

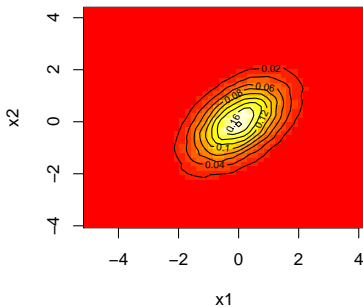
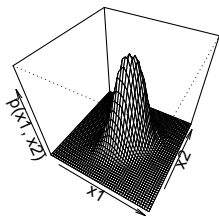
$$\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$\boldsymbol{\mu}$: vector of means

$\boldsymbol{\Sigma}$: covariance matrix

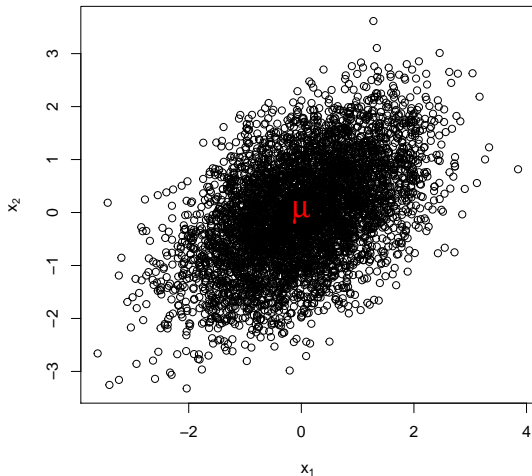
Bivariate normal probability density

$$\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$



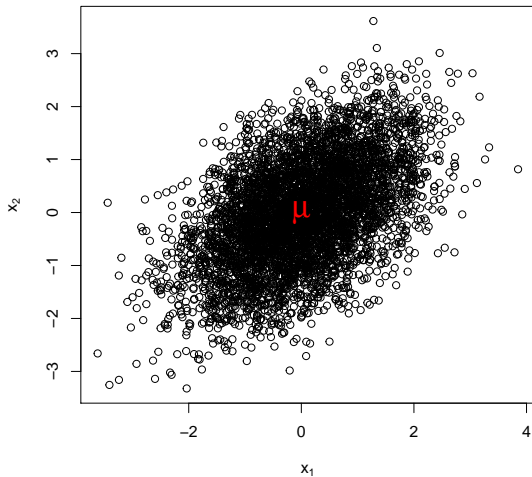
Bivariate normal parameters

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} \text{Cov}[X_1, X_1] & \text{Cov}[X_1, X_2] \\ \text{Cov}[X_2, X_1] & \text{Cov}[X_2, X_2] \end{bmatrix}$$



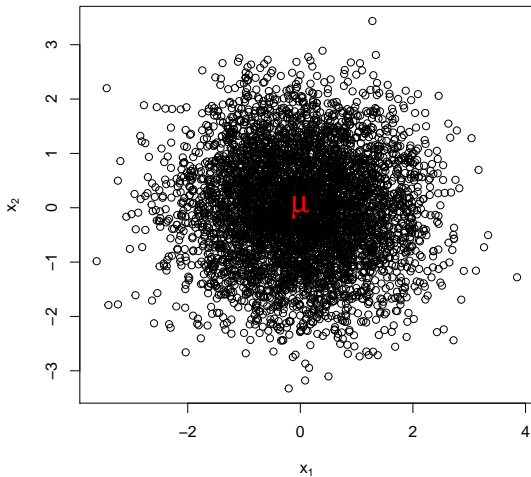
Bivariate normal parameters

$$\boldsymbol{\mu} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$



Uncorrelated bivariate normal

$$\boldsymbol{\mu} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



Common notation

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$$

Common notation

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$$

$$\text{Cov}[X_1, X_1] = \text{Var}[X_1] = \sigma_1^2$$

$$\text{Cov}[X_1, X_2] = \rho\sigma_1\sigma_2$$

Σ must be symmetric and positive definite

Relevant properties of multivariate normals

1. Marginal distributions are normal
2. Conditional distributions are normal

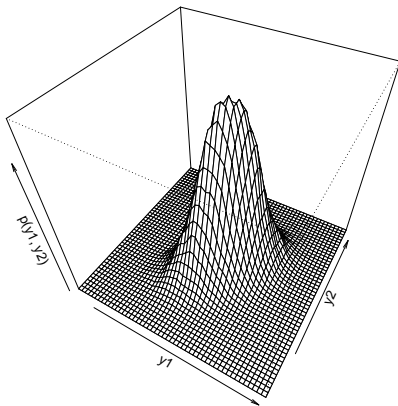
Marginals are normal

Joint distribution: $\mathbf{y} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$

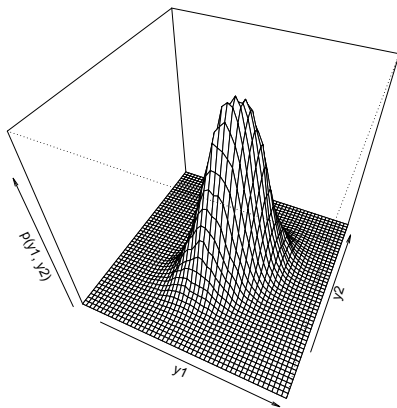
$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \boldsymbol{\Sigma} = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$$

Marginal distribution: $y_1 \sim N(\mu_1, \sigma_1^2)$

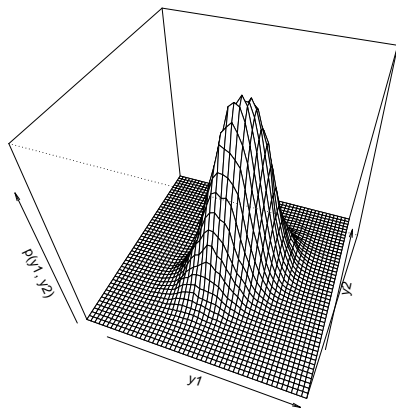
Graphical interpretation



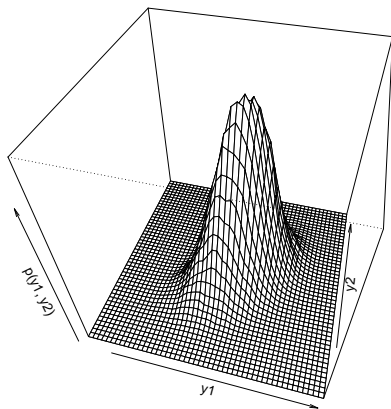
Graphical interpretation



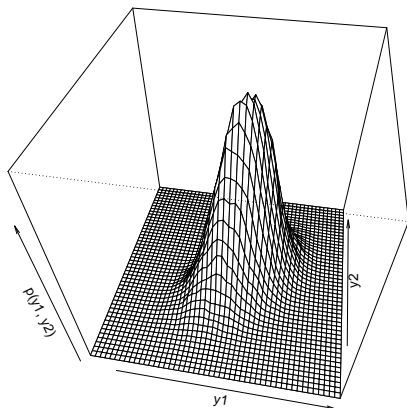
Graphical interpretation



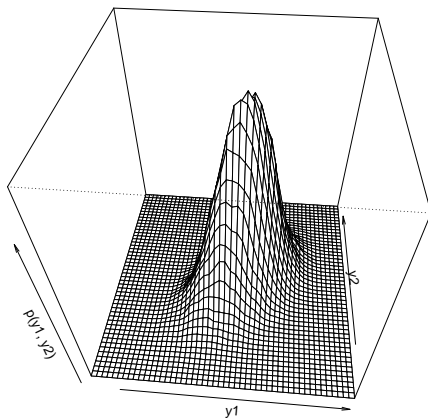
Graphical interpretation



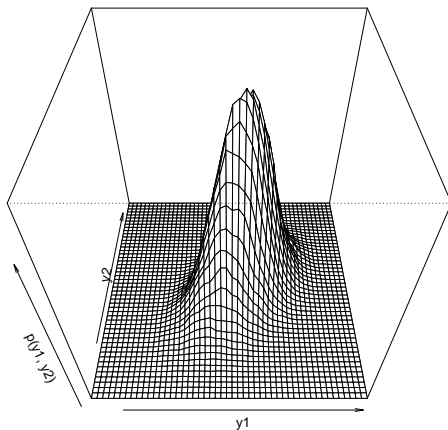
Graphical interpretation



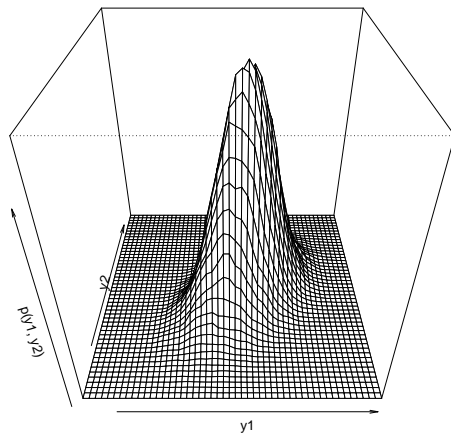
Graphical interpretation



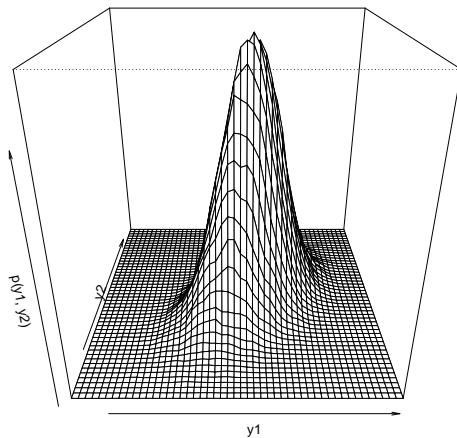
Graphical interpretation



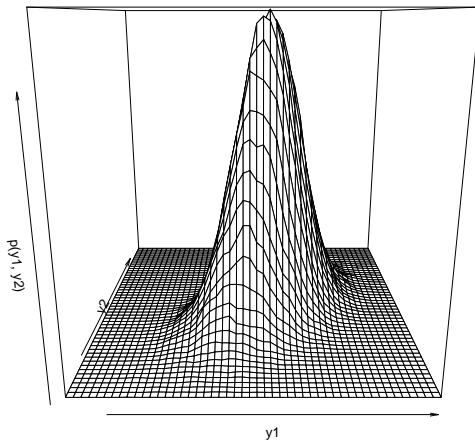
Graphical interpretation



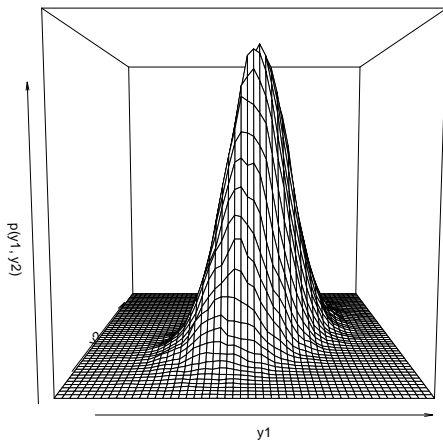
Graphical interpretation



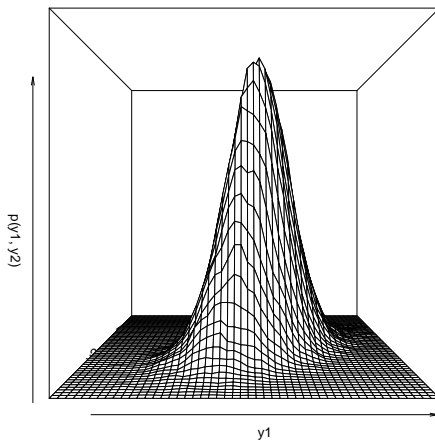
Graphical interpretation



Graphical interpretation

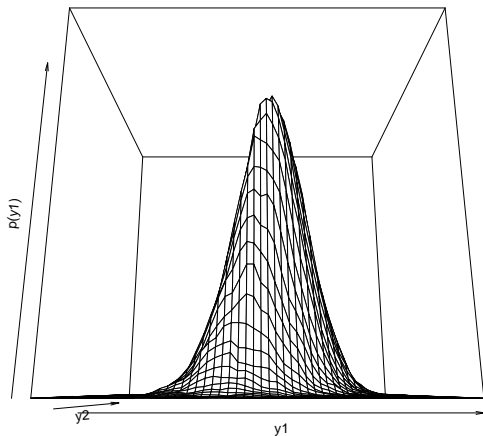


Graphical interpretation



Graphical interpretation: marginal of y_1

$$N(\mu_1, \sigma_1^2)$$



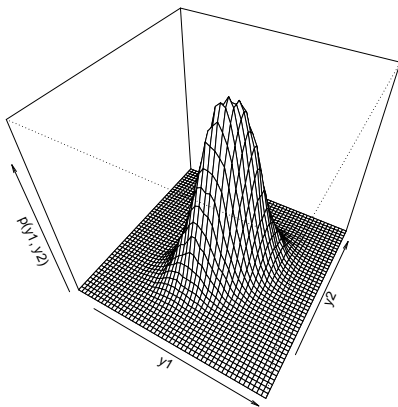
Conditional distributions are normal

Joint distribution:
$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{bmatrix} \right)$$

Conditional distribution:

$$Y_1 | Y_2 = y_2 \sim N(\mu, \Sigma)$$

Graphical interpretation of conditioning



Conditional of Y_1

Joint distribution:
$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{bmatrix} \right)$$

Conditional distribution:

$$Y_1|Y_2 \sim N(E(Y_1|Y_2), \text{Var}(Y_1|Y_2))$$

$$E(Y_1|Y_2) = \mu_1 + \Omega_{12}\Omega_{22}^{-1}(Y_2 - \mu_2)$$

$$\text{Var}(Y_1|Y_2) = \Omega_{11} - \Omega_{12}\Omega_{22}^{-1}\Omega_{21}$$

Now the fun stuff

Classic linear modeling

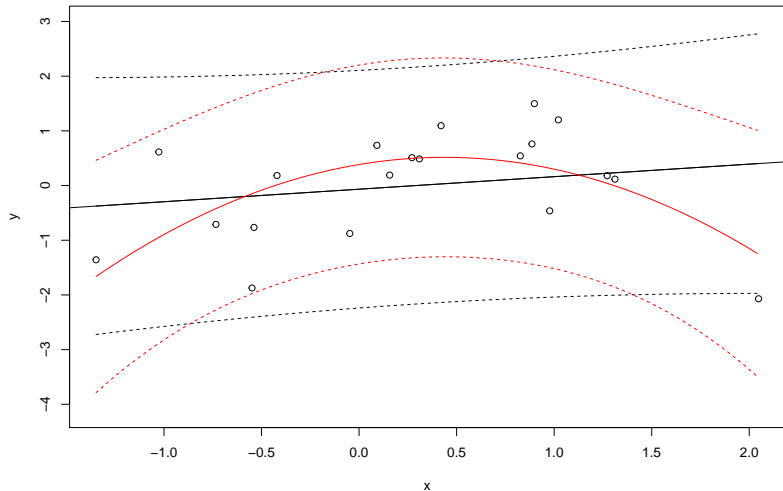
$$y = X\beta + \epsilon$$

$$\epsilon \sim N(0, \sigma^2)$$

Functional form determined by $X\beta$

Linear model functional forms

e.g. $y = \mu(x) + \epsilon$



Why not set a prior on $\mu(x)$?

Gaussian process as a prior for $\mu(x)$

$$y \sim N(\mu(x), \sigma^2)$$

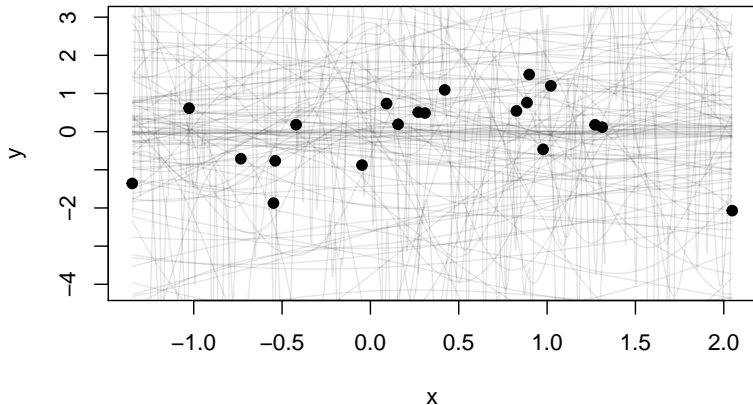
$$\mu(x) \sim GP(m, k)$$

GP prior for $\mu(x)$

$$y \sim N(\mu(x), \sigma^2)$$

$$\mu(x) \sim GP(m, k)$$

Data and realizations from a GP prior



Wait, what's Gaussian about that?

If $\mu(x) \sim GP(m, k)$, then

$$\mu(x_1), \dots, \mu(x_n) \sim N(m(x_1), \dots, m(x_n), K(x_1, \dots, x_n))$$

m and k are functions!

Mean function: m

Classic example: $m(x) = X\beta$

e.g., $\mu(x) \sim GP(X\beta, k(x))$

But, the covariance function $k(x)$ is the real star.

Covariance functions

k specifies covariance between two x values

Squared exponential covariance:

$$k(x, x') = \tau^2 \exp\left(-\frac{|x - x'|^2}{l^2}\right)$$

Lots of options: smooth, jaggedy, periodic

Example of squared exponential

$$\mathbf{K} = \begin{bmatrix} \tau^2 \exp(-\frac{|x_1 - x_1|^2}{l^2}) & \tau^2 \exp(-\frac{|x_1 - x_2|^2}{l^2}) \\ \tau^2 \exp(-\frac{|x_2 - x_1|^2}{l^2}) & \tau^2 \exp(-\frac{|x_2 - x_2|^2}{l^2}) \end{bmatrix}$$

Example of squared exponential

$$\mathbf{K} = \begin{bmatrix} \tau^2 \exp(-\frac{0^2}{l^2}) & \tau^2 \exp(-\frac{|x_1 - x_2|^2}{l^2}) \\ \tau^2 \exp(-\frac{|x_2 - x_1|^2}{l^2}) & \tau^2 \exp(-\frac{0^2}{l^2}) \end{bmatrix}$$

Example of squared exponential

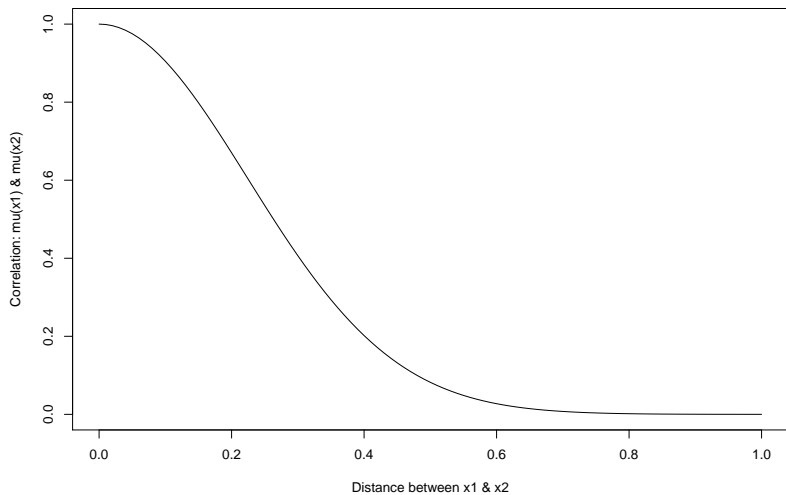
$$\mathbf{K} = \begin{bmatrix} \tau^2 \exp(0) & \tau^2 \exp(-\frac{|x_1 - x_2|^2}{l^2}) \\ \tau^2 \exp(-\frac{|x_2 - x_1|^2}{l^2}) & \tau^2 \exp(0) \end{bmatrix}$$

Example of squared exponential

$$\mathbf{K} = \begin{bmatrix} \tau^2 & \tau^2 \exp(-\frac{|x_1 - x_2|^2}{l^2}) \\ \tau^2 \exp(-\frac{|x_2 - x_1|^2}{l^2}) & \tau^2 \end{bmatrix}$$

$$\text{Cor}(\mu(x_1), \mu(x_2)) = \exp(-\frac{|x_1 - x_2|^2}{l^2}).$$

Correlation function



Let's check it out

`sim.R`: GP simulations with 1d and 2d inputs

`estimate.R`: GP estimation with 1d inputs