

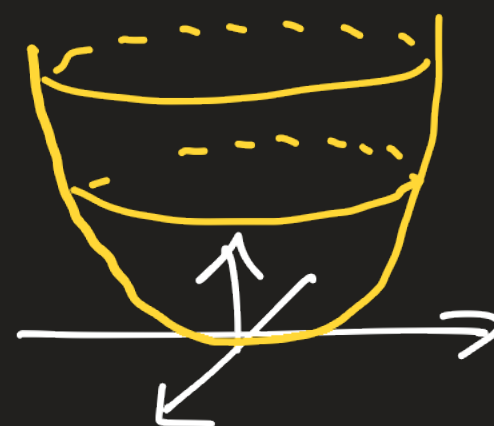
# Examples of manifolds

$$S^1 = \bigcirc \subseteq \mathbb{R}^2 \quad \text{circle}$$

1-dimensional manifold = curve



$$S^2 = \bigcirc \rightarrow \text{sphere}$$



2-dimensional manifold = surfaces.

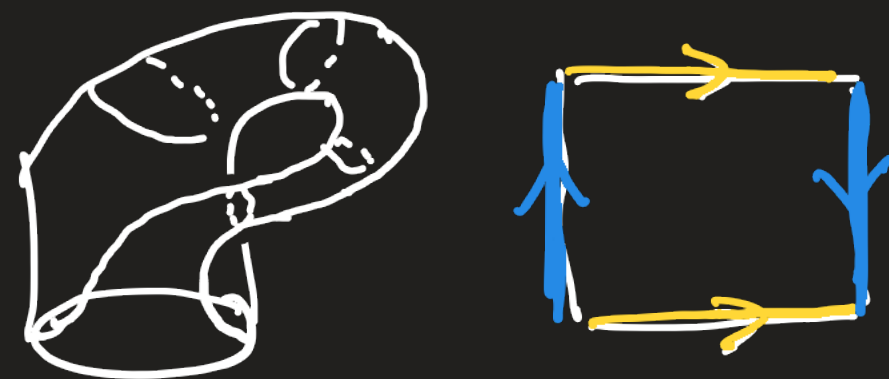
$$S^n = \{x \in \mathbb{R}^{n+1} : \|x\| = 1\} \quad n\text{-sphere} \quad n\text{-dim manifold.}$$

$\mathbb{R}^n$  is the prototype of an  $n$ -dim. manifold.  
locally an  $n$ -dim. manifold "looks like" an open subset of  $\mathbb{R}^n$ .

Remark Not all manifolds are subspaces of  $\mathbb{R}^n$  in a natural way.

Ex Klein bottle

2-dim. manifold.



Program for first weeks

- Review differentiation in  $\mathbb{R}^n$
- Give coordinate free description of the tangent space  $T_P \mathbb{R}^n$  for  $P \in \mathbb{R}^n$ . - Shall use this to define the tangent space at a point on a manifold.
- Introduce the exterior algebra of a vector space
  - Use this to define differential forms (eg.  $dx + dy + dz$ )

Homework: Read up on point set topology in App A.

## Differentiation in $\mathbb{R}^n$ $p \in \mathbb{R}^n, \epsilon > 0$

$B(p, \epsilon) = \{x \in \mathbb{R}^n \mid \|x - p\| < \epsilon\}$  open ball with centre  $p$ .

A subset  $U \subseteq \mathbb{R}^n$  is open if for every  $p \in U$ , there exists  $\epsilon > 0$  such that  $B(p, \epsilon) \subseteq U$ .



A neighborhood of  $p$  is an open set  $U$  st.  $p \in U$ .

Notation: Given  $x \in \mathbb{R}^n$ , write  $x = (x^1, x^2, \dots, x^n)$ , <sup>coordinates</sup> of  $x$ .

Definition  $U \subseteq \mathbb{R}^n$  open,  $f: U \rightarrow \mathbb{R}$  function

- $f$  is  $C^0$  if  $f$  is continuous.
- $f$  is  $C^1$  if  $\frac{\partial f}{\partial x^i}(p)$  exists for all  $p \in U$  and  $\frac{\partial f}{\partial x^i}: U \rightarrow \mathbb{R}$  is continuous for  $i=1, \dots, n$ .
- Inductively:  $f$  is  $C^k$  if  $\frac{\partial f}{\partial x^i}(p)$  exists for all  $p \in U$  and  $\frac{\partial f}{\partial x^i}: U \rightarrow \mathbb{R}$   $C^{k-1}$  for  $i=1, \dots, n$ .

- $f$  is  $C^\infty$  on  $U$  if  $f \in C^k$  for all  $k \geq 0$ . This means:  
All iterated partial derivatives  $\frac{\partial^k f}{\partial x^{i_1} \dots \partial x^{i_k}}$  exist and are continuous on  $U$ .

Terminology:  $f$  smooth  $\Leftrightarrow f$  is  $C^\infty$

The tangent space  $T_p \mathbb{R}^n$ ,  $p \in \mathbb{R}^n$

$T_p \mathbb{R}^n$  can be identified with  $\mathbb{R}^n$   
will give an alternative coordinate free description  
in terms of point derivations





Let  $U \subseteq \mathbb{R}^n$  be an open set containing  $p$ .

$C^0(U)$  is the real vector space of  $C^0$  functions  $f: U \rightarrow \mathbb{R}$ .

$C^0(U)$  has a multiplication  $(f \cdot g)(x) = f(x) \cdot g(x)$ .

The constant function 1 is the multiplicative unit.

This makes  $C^0(U)$  an  $\mathbb{R}$ -algebra (see book).

Definition A point derivation at  $p \in U \subseteq \mathbb{R}^n$  is an  $\mathbb{R}$ -linear function  $D: C^0(U) \rightarrow \mathbb{R}$  such that

$$D(f \cdot g) = D(f) g(p) + f(p) D(g) \quad , \text{ for all } f, g \in C^0(U).$$

Recall Given  $v \in \mathbb{R}^n$ . The directional derivative at  $P$  wrt.  $v$  is the point derivation  $D_v: C^\infty(U) \rightarrow \mathbb{R}$ ,

$$D_v(f) = \lim_{t \rightarrow 0} \frac{f(P+tv) - f(P)}{t}.$$

(i.e.,  $D_v(f)$  is the derivative of  $t \mapsto f(P+tv)$  at  $t=0$ .)

- $D_v(f+g) = D_v(f) + D_v(g)$ ,  $D_v(rf) = r D_v(f)$ ,  $r \in \mathbb{R}$ .

- $D_v(f \cdot g) = D_v(f) \cdot g(P) + f(P) D_v(g)$

Check:  $\frac{d}{dt} \Big|_{t=0} (t \mapsto f(P+tv) \cdot g(P+tv))$

$$= \frac{d}{dt} \Big|_{t=0} (t \mapsto f(P+tv) \cdot g(P) + f(P) \frac{d}{dt} \Big|_{t=0} (t \mapsto g(P+tv)))$$

Ex  $v = e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i$ ,  $D_{e_i}(f) = \frac{\partial f}{\partial x^i}(P)$ , write  $\frac{\partial}{\partial x^i} \Big|_P := D_{e_i}$

For  $v = \begin{bmatrix} v^1 \\ \vdots \\ v^n \end{bmatrix}$ ,  $D_v(f) = \sum_{i=1}^n v^i \frac{\partial f}{\partial x^i}(P)$  (chain rule)

There is a function  $T_p(\mathbb{R}^n) \cong \mathbb{R}^n \rightarrow \left\{ \begin{array}{l} \text{Point derivations} \\ \text{at } p, C^\infty(U) \rightarrow \mathbb{R} \end{array} \right\}$   
 $v \mapsto D_v$

will modify this to become independent of  $U$ .

### Function germs


Consider the collection of pairs  $(f, U)$ , where  $U$  is a nbh. of  $p$  and  $f: U \rightarrow \mathbb{R}$  is  $C^\infty$ .

Define an equivalence relation:  $(f, U) \sim (g, V)$  if there exists a nbh.  $W \subseteq U \cap V$  of  $p$  st.  $f|_W = g|_W$ .  
 conditions for equivalence relation:

- $(f, U) \sim (f, U)$  reflexive
- $(f, U) \sim (g, V) \Rightarrow (g, V) \sim (f, U)$  symmetry
- $(f, U) \sim (g, V)$  and  $(g, V) \sim (h, W) \Rightarrow (f, U) \sim (h, W)$   
 transitivity.

The equivalence relation defines a partition of the pairs  $(f, U)$  into equivalence classes:  $(f, U)$  and  $(g, V)$  are in the same class iff  $(f, U) \sim (g, V)$ .

An equivalence class is called a function germ at  $p$ .

Ex  For now write  $[f, U]$  for the function germ represented by  $(f, U)$

The set of equivalence classes (= function germs) is denoted  $C_p^\infty(\mathbb{R}^n)$  (or  $C_p^\infty$ ).

Define addition and scalar multiplication in  $C_p^\infty(\mathbb{R}^n)$ :

$$[f, U] + [g, V] = [f+g, U \cap V], \quad r[f, U] = [rf, U], \quad r \in \mathbb{R}$$

Exercise check this is well-defined and make  $C_p^\infty(\mathbb{R}^n)$  a real vector space,  $0 = [0, \mathbb{R}^n]$



There is also an associative and commutative multiplication on  $C_p^\infty(\mathbb{R}^n)$ :  $[f, 0] \cdot [g, v] = [f \cdot g, 0 \wedge v]$

This makes  $C_p^\infty(\mathbb{R}^n)$  an  $\mathbb{R}$ -algebra. (see book).

Def  $\mathcal{D}_p(\mathbb{R}^n)$  is the real vector space of point derivatives

$$D: C_p^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}. \quad (\text{i.e., } D(f \cdot g) = D(f)g(p) + f(p)D(g))$$

$$\bullet (D + D')(f) = D(f) + D'(f), \quad (rD)(f) = rD(f)$$

Exercise: check vector space axioms

There is a linear function  $\phi: T_p\mathbb{R}^n \cong \mathbb{R}^n \rightarrow \mathcal{D}_p(\mathbb{R}^n)$   
 $v \mapsto \phi(v) = D_v$ .

(since  $D_v(f)$  only depends on the function germ of  $f$  at  $p$ )

$$\text{For } v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}, \text{ then } D_v = \sum_{i=1}^n v_i \frac{\partial}{\partial x_i} \Big|_p \quad (\text{chain rule})$$

This shows  $\phi$  is linear in  $v$ .

Theorem  $\phi: T_p(\mathbb{R}^n) \cong \mathbb{R}^n \rightarrow \mathcal{D}_p(\mathbb{R}^n)$  is an isomorphism.  
(Proof Wednesday).