

COMP 411/511

Computer Vision with Deep Learning

Probability Tutorial

Agenda

- Introduction to Probability
- Conditional Probability
- Random Variables
- Probability Distributions

Introduction to Probability

- **Sample Space S**

The set of all possible outcomes of an experiment is known as the sample space of the experiment and is denoted by S .

- Examples

- Coin toss: $\{H, T\}$
- 2 Coin toss: $\{(H_1, H_2), (H_1, T_2), (T_1, H_2), (T_1, T_2)\}$

Introduction to Probability and Combinatorics

- **Event E**

Any subset E of the sample space is known as an event. That is, an event is a set consisting of possible outcomes of the experiment. If the outcome of the experiment is contained in E , then we say that E has occurred.

- **Examples**

- Getting at least 2 tails in 3 coin toss, *ie*

$$E = \{(H_1, T_2, T_3), (T_1, H_2, T_3), (T_1, T_2, H_3), (T_1, T_2, T_3)\}$$

where

$$S = \{(H_1, H_2, H_3), (H_1, H_2, T_3), (H_1, T_2, H_3), (T_1, H_2, H_3), \\ (H_1, T_2, T_3), (T_1, H_2, T_3), (T_1, T_2, H_3), (T_1, T_2, T_3)\}$$

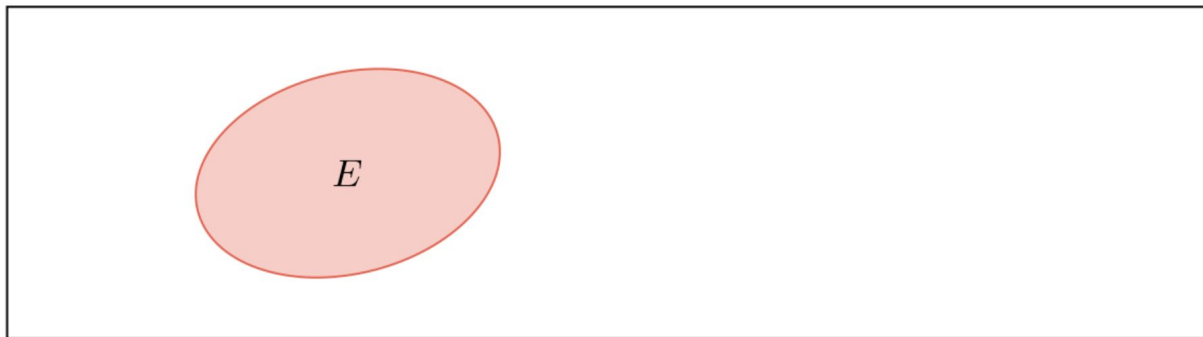
Introduction to Probability and Combinatorics

- **Axioms of Probability**

For each event E , we denote $P(E)$ as the probability of event E occurring.

- **Axiom 1** - Every probability is between 0 and 1 included.

$$0 \leq P(E) \leq 1$$



Introduction to Probability and Combinatorics

- **Axioms of Probability**

For each event E , we denote $P(E)$ as the probability of event E occurring.

- **Axiom 2** - The probability that at least one of the elementary events in the entire sample space will occur is 1.

$$P(S) = 1$$



S

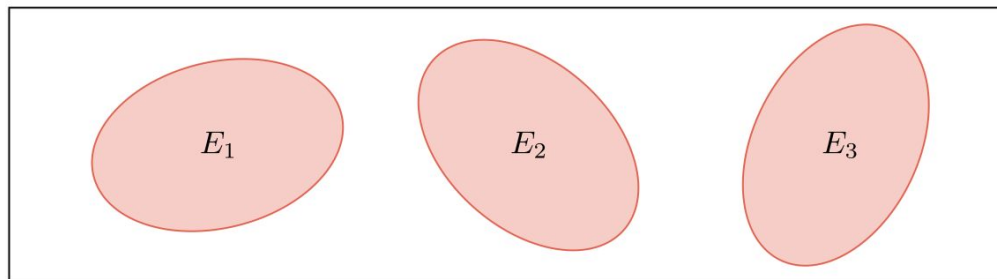
Introduction to Probability and Combinatorics

- **Axioms of Probability**

For each event E , we denote $P(E)$ as the probability of event E occurring.

- **Axiom 3** - For any sequence of mutually exclusive events E_1, \dots, E_n , we have:

$$P\left(\bigcup_{i=1}^n E_i\right) = \sum_{i=1}^n P(E_i)$$



Conditional Probability

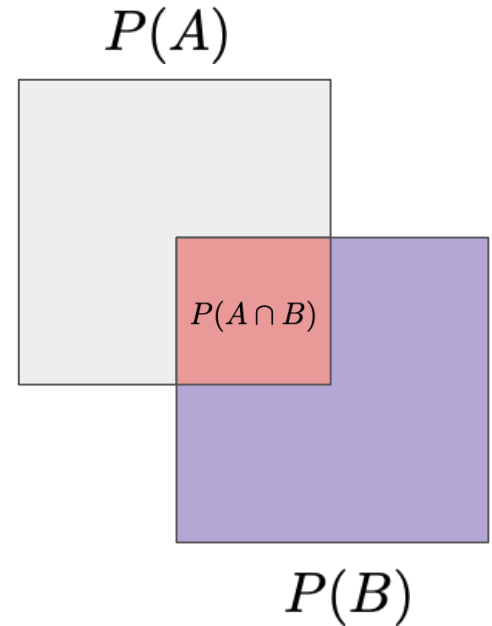
- **Conditional Probability**

For events **A** and **B**; the probability of event **A**, given that event **B** has happened is shown as:

$$P(A \mid B) = \frac{P(A \cap B)}{P(B)}$$

- For events **A** and **B**; the probability of event **A** and event **B** have happened is shown as:

$$P(A \cap B) \quad \text{or} \quad P(A, B)$$



Conditional Probability

- **Chain Rule**

Intersection of many events can be decomposed into conditional probabilities:

$$P(A_1 \cap A_2 \dots \cap A_n) = \prod_{i=1}^n P(A_i | \bigcap_{j=1}^{i-1} A_j)$$

- Example

$$\begin{aligned} P(A \cap B \cap C) &= P(A | B \cap C) P(B \cap C) \\ &= P(A | B \cap C) P(B | C) P(C) \end{aligned}$$

Conditional Probability

- **Bayes Rule**

For events **A** and **B** such that $P(B) > 0$, $P(A) > 0$, we have:

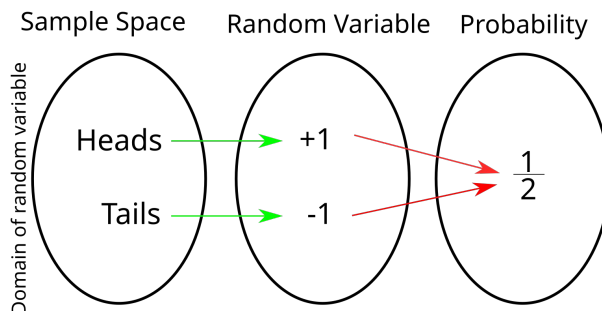
$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Random Variables

- **Random Variable**

A random variable, often noted X , is a mathematical formalization of a quantity or object which depends on random events

- The domain is the set of possible outcomes in a sample space \mathcal{S}
- The range is a measurable space corresponding to the domain



Random Variables

- **Probability Density Function (PDF)**

The probability density function f is the probability that \mathbf{X} takes on values between two adjacent realizations of the random variable.

Can be interpreted as providing a relative likelihood that the value of the \mathbf{X} .

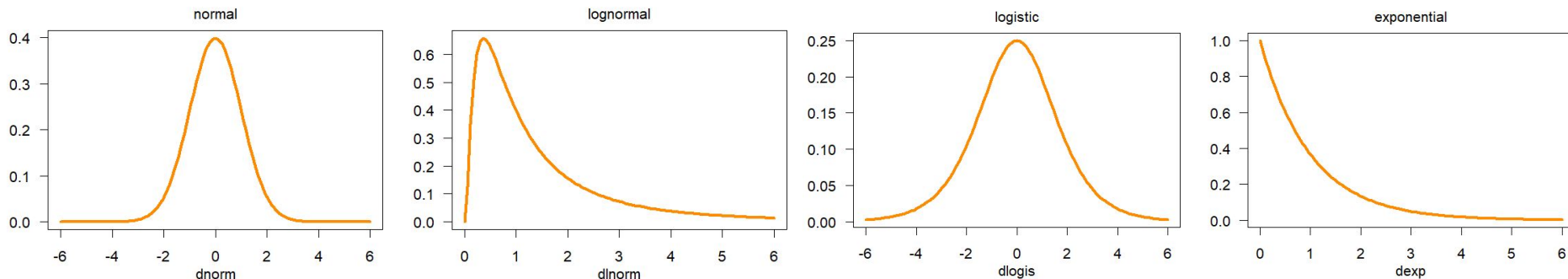


Figure: Some PDFs of different distributions

Random Variables

- **Cumulative Distribution Function (CDF)**

The cumulative distribution function F , which is monotonically non-decreasing and is such that $\lim_{x \rightarrow -\infty} F(x) = 0$ and $\lim_{x \rightarrow +\infty} F(x) = 1$ is defined as:

$$F(x) = P(X \leq x)$$

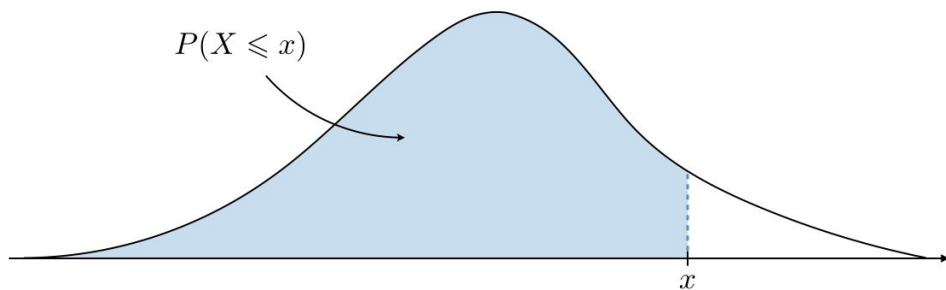


Figure: The definition of CDF over PDF

Random Variables

- Relations between CDF and PDF

CDF F	PDF f	Properties of PDF
$F(x) = \int_{-\infty}^x f(y)dy$	$f(x) = \frac{dF}{dx}$	$f(x) \geq 0 \text{ and } \int_{-\infty}^{+\infty} f(x)dx = 1$

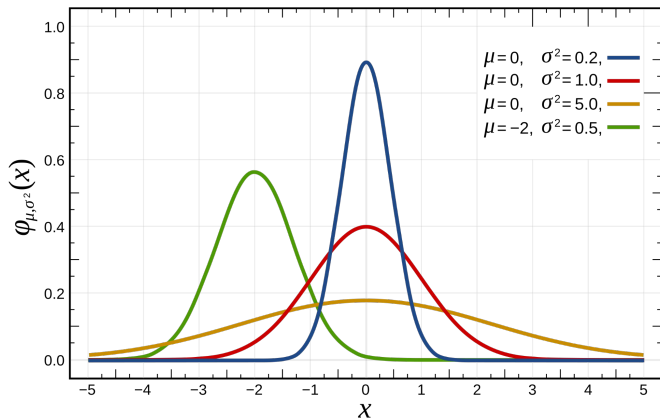


Figure: PDFs of Gaussians

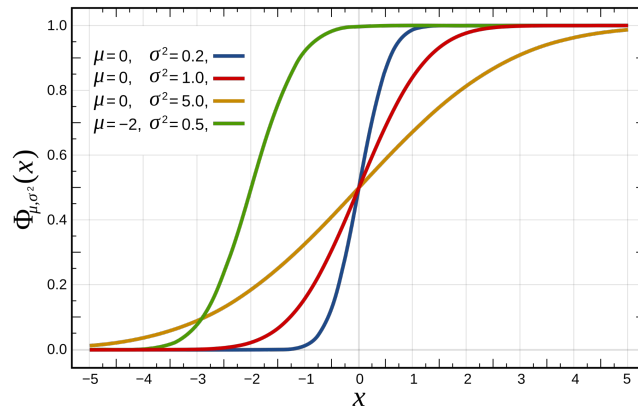


Figure: CDFs of Gaussians

Random Variables

- **Expected Value**

The expected value $E[X]$ is the mean of the possible values a random variable can take, weighted by the probability of those outcomes:

$$E[X] = \sum_x x P(x)$$

- Example

Let X represent the outcome of a roll of a fair six-sided die. The expectation of X is:

$$E[X] = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = 3.5$$

Random Variables

- **Variance**

The variance of a random variable, often noted **$\text{Var}(\mathbf{X})$** or σ^2 is a measure of the spread of its distribution function. It is determined as follows:

$$\begin{aligned}\text{Var}(X) &= \mathbf{E}[(X - \mathbf{E}[X])^2] \\ &= \mathbf{E}[X^2 - 2X\mathbf{E}[X] + \mathbf{E}[X]^2] \\ &= \mathbf{E}[X^2] - 2\mathbf{E}[X]\mathbf{E}[X] + \mathbf{E}[X]^2 \\ &= \mathbf{E}[X^2] - 2\mathbf{E}[X]^2 + \mathbf{E}[X]^2 \\ &= \mathbf{E}[X^2] - \mathbf{E}[X]^2\end{aligned}$$

Random Variables

- **Variance and Mean**

The variance of a collection of n equally likely values can be written as:

$$\text{Var}(X) = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

where μ is the average value, ie **mean**. That is,

$$\mu = \frac{1}{n} \sum_{i=1}^n x_i$$

Random Variables

- **Standard Deviation**

The standard deviation of a random variable, often noted σ , is a measure of the spread of its distribution function which is compatible with the units of the actual random variable. It is determined as follows:

$$\sigma = \sqrt{\text{Var}(X)}$$

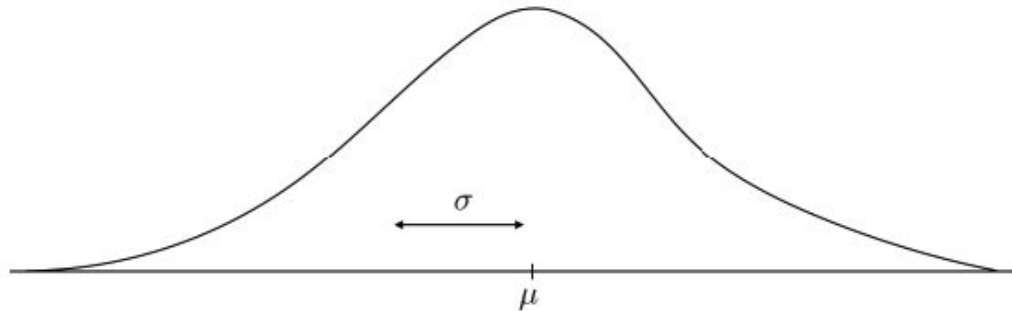
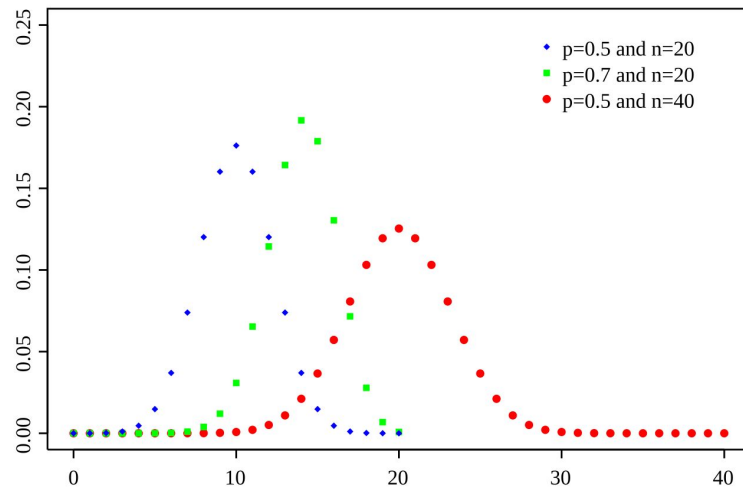


Figure: Standard Deviation of a Gaussian

Probability Distributions

- Main Distributions: Binomial (Discrete)

Distribution	PDF	$E[X]$	$\text{Var}(X)$
$X \sim B(n, p)$	$\binom{n}{k} p^k (1-p)^{n-k}$	np	$np(1-p)$



Probability Distributions

- Main Distributions: Uniform (Continuous)

Distribution	PDF	$E[X]$	$\text{Var}(X)$
$X \sim \mathcal{U}(a, b)$	$\frac{1}{b-a}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$

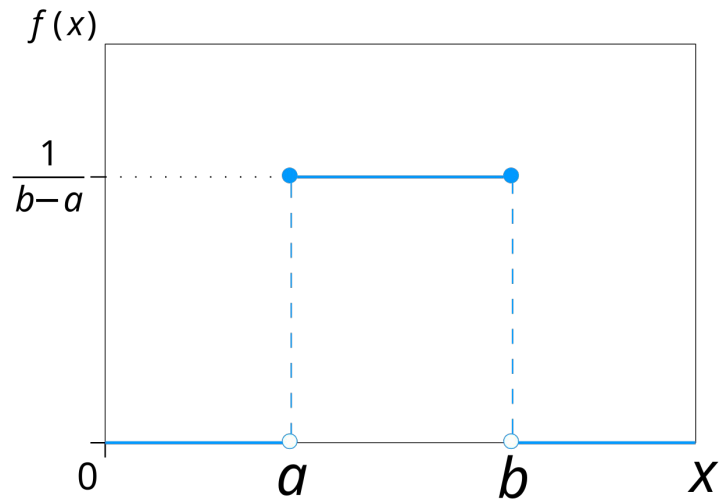


Figure: PDF of Uniform

Probability Distributions

- Main Distributions: Gaussian (Continuous)

Distribution	PDF	$E[X]$	$\text{Var}(X)$
$\mathcal{N}(\mu, \sigma^2)$	$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	μ	σ^2

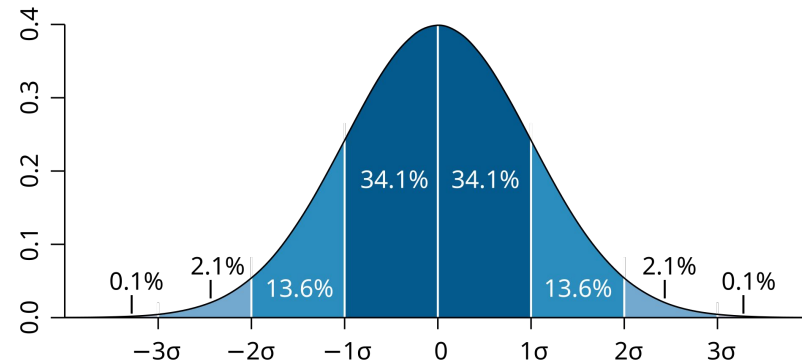
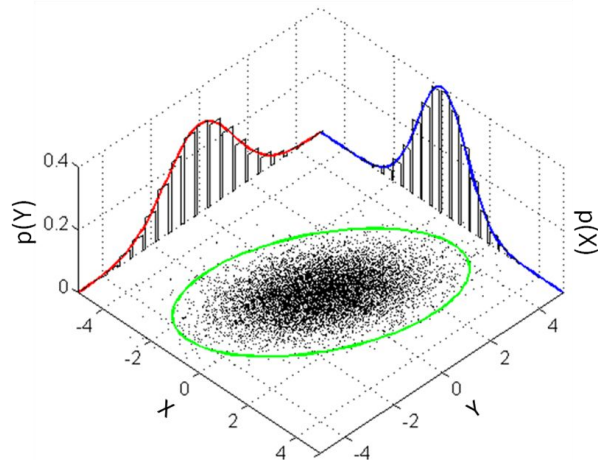


Figure: PDF of Gaussian

Probability Distributions

- **Main Distributions: Multivariate Gaussian (Continuous)**

The normal distribution generalizes to \mathbf{R}^n . It may be parametrized with a positive definite symmetric matrix Σ , ie covariance matrix:



$$\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sqrt{\frac{1}{(2\pi)^n \det(\boldsymbol{\Sigma})}} \exp \left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right)$$

Figure: PDF of Multivariate Gaussian

Probability Distributions

- Main Distributions: Laplace (Continuous)

Distribution	PDF	$E[X]$	$\text{Var}(X)$
Laplace(μ, b)	$\frac{1}{2b} \exp\left(-\frac{ x - \mu }{b}\right)$	μ	$2b^2$

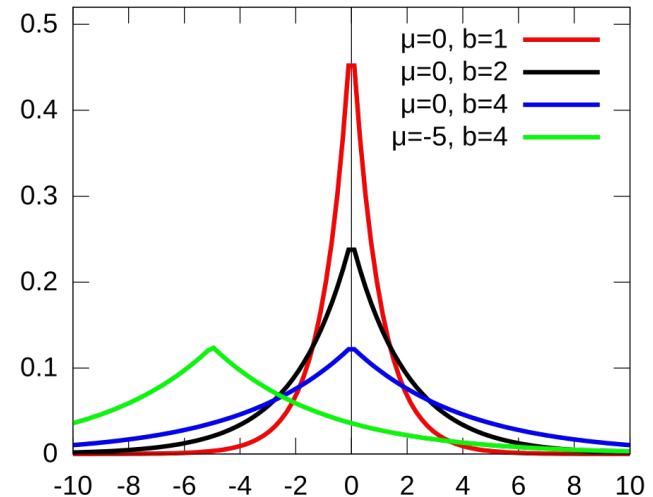


Figure: PDF of Laplace

Probability Distributions

- **Sigmoid Function**

Certain functions arise often while working with probability distributions, especially the probability distributions used in deep learning models, such as Logistic Sigmoid:

$$\sigma(x) = \frac{1}{1 + \exp(-x)}$$

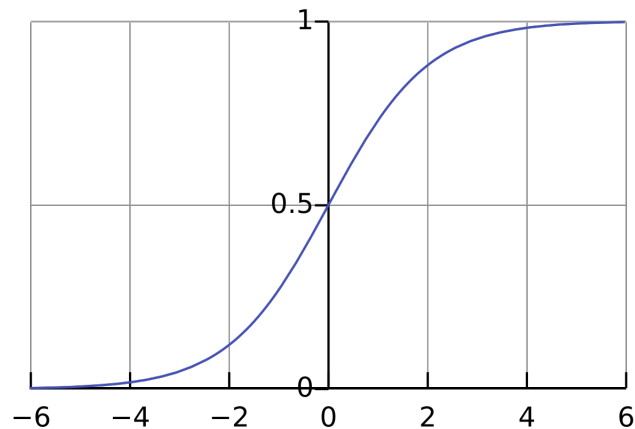


Figure: Logistic curve

Any Questions?