## Mathematics II

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21/01/2025

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1 Highlights of Lesson 14

## Highlights of Lesson 14

- Determinant:  $\det(\mathbf{A}) \equiv |\mathbf{A}|$

 $[\det: \mathbb{R}^{n \times n} \longrightarrow \mathbb{R}]$ 

- Volume vs determinant
- Properties: 1, 2, 3
- We will deduce properties: 4 − 9

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You can find the last version of these course materials at

https://mbujosab.github.io/MatematicasII/

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## 2 Area or volume

1.  $\operatorname{Vol}(\underset{n \times n}{\mathbf{I}}) = 1$ .





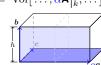
 $2. \ \operatorname{Vol} \left( \mathbf{A} \right) \ = \ \operatorname{Vol} \left( \mathbf{A}_{\underbrace{\left[ (\alpha) \mathbf{k} + \mathbf{j} \right]}{\mathbf{j}}} \right) \text{ for } j \neq k.$ 





3.  $|\alpha| \cdot \text{Vol}(\mathbf{A}) = |\alpha| \cdot \text{Vol}[\ldots; \mathbf{A}_{|k}; \ldots] = \text{Vol}[\ldots; \alpha \mathbf{A}_{|k}; \ldots]$ 





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3 Determinant: 3 properties that define the function

P-1 Determinant of identity matrices:

$$\det \mathop{\rm I}_{n\times n} = 1$$

P-2 Type I elemen. transf. do not change the determinant:

$$\det \mathbf{A} = \det \left( \mathbf{A}_{\underbrace{\mathbf{A}}_{[(\alpha)k+j]}}^{T} \right)$$

P-3 Multiplying a column by an scalar multiplies the det.

$${\color{blue}\alpha}\cdot\det\mathbf{A}\ =\ \det\big[\ldots;{\color{blue}\alpha}\mathbf{A}_{|k};\ldots\big] \text{ for any } k\in\{1:n\} \text{ and } \alpha\in\mathbb{R}$$

Absolute value of  $\det \mathbf{A} = \operatorname{Vol} \mathbf{A}$ 

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- 4 Determinant of a matrix with a zero column
- P-4 Det. of a matrix A with a zero column If A has a zero column 0, then

$$\det(\mathbf{A}) = 0$$

prove P-4

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## **Example**

Then, we know that in  $\mathbb{R}^3$ :

$$\begin{vmatrix} a_1 & (b_1 + \alpha c_1) & c_1 \\ a_2 & (b_2 + \alpha c_2) & c_2 \\ a_3 & (b_3 + \alpha c_3) & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix};$$

$$\det [\boldsymbol{a}; (\boldsymbol{b} + \alpha \boldsymbol{c}); c;] = \det [\boldsymbol{a}; \boldsymbol{b}; c;];$$

and also

$$\begin{vmatrix} a_1 & \alpha b_1 & c_1 \\ a_2 & \alpha b_2 & c_2 \\ a_3 & \alpha b_3 & c_3 \end{vmatrix}; = \alpha \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix};$$

$$\det [\boldsymbol{a}; \alpha \boldsymbol{b}; \boldsymbol{c};] = \alpha \det [\boldsymbol{a}; \boldsymbol{b}; \boldsymbol{c};];$$

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**5** Elementary matrices

We already know

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$$\det \left( \mathbf{A}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}+\boldsymbol{j}]}} \right) = |\mathbf{A}|; \qquad \det \left( \mathbf{A}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}]}} \right) = \alpha |\mathbf{A}|.$$

Determinant of elementary matrices

$$\det \left( \mathbf{I}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}+\boldsymbol{j}]}} \right) = 1 \qquad \text{and} \qquad \det \left( \mathbf{I}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{j}]}} \right) = \alpha.$$

Hence, since  $\mathbf{A}_{\tau} = \mathbf{A}(\mathbf{I}_{\tau})$ , then

$$\left| \mathbf{A}(\mathbf{I}_{\tau}) \right| = |\mathbf{A}| \cdot |\mathbf{I}_{\tau}| \tag{1}$$

where  $\mathbf{I}_{\tau}$  is an elementary matrix

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ve the following propositions

6 Determinant after a sequence of elementary transformations

- (a)  $\det(\mathbf{A}_{\tau_1\cdots\tau_k}) = |\mathbf{A}|\cdot|\mathbf{I}_{\tau_1}|\cdots|\mathbf{I}_{\tau_k}|$ .
- (b) If **B** is a full rank matrix, i.e., if  $\mathbf{B}=\mathbf{I}_{\tau_1\cdots\tau_k}$ , then  $|\mathbf{B}|=|\mathbf{I}_{\tau_1}|\cdots|\mathbf{I}_{\tau_k}|$ , and therefore  $|\mathbf{B}|\neq 0$ .
- (c) If  ${\bf A}$  and  ${\bf B}$  have order n and  ${\bf B}$  is full rank, then

$$\det(\mathbf{A}\mathbf{B}) = |\mathbf{A}| \cdot |\mathbf{B}| \tag{2}$$

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7 Antisymmetric property

# P-5 [Antisymmetric property]

Column exchange changes the sign of the determinant.

## Proof.

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Column exchange is a sequence of *Type I* transformation and just only one *Type II* transformation that multiplies a column by -1  $\Box$  Therefore:

$$\begin{vmatrix} c_1 & b_1 & a_1 \\ c_2 & b_2 & a_2 \\ c_3 & b_3 & a_3 \end{vmatrix} = (-1) \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

**Example** 

a sequence  $au_1 \cdots au_k$  of  $\mathit{Type\ I}$  elementary transformations does not change the determinant.

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$$|\mathbf{A}_{\tau_1\cdots\tau_h}| = |\mathbf{A}(\mathbf{I}_{\tau_1\cdots\tau_h})| = |\mathbf{A}|\cdot|\mathbf{I}_{\tau_1\cdots\tau_h}| = |\mathbf{A}|\cdot 1 = |\mathbf{A}|$$

### **E**xample

but a sequence of Type II can.

$$\begin{vmatrix} 2a & 3c \\ 2b & 3d \end{vmatrix} = \frac{?}{b} \begin{vmatrix} a & c \\ b & d \end{vmatrix}$$

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8 Singular matrices. Inverse of a matrix

**P-6** If A is singular then |A| = 0.

$$\boxed{\mathbf{P-7}} \qquad \det(\mathbf{A}^{-1}) = (\det \mathbf{A})^{-1}.$$

### Proof.

Let  $\mathbf{A}_{\tau_1\cdots\tau_k}=\underset{\scriptscriptstyle{n\times n}}{\mathbf{R}}$  be a reduced equelon form (and  $\mathbf{E}=\mathbf{I}_{\tau_1\cdots\tau_k}).$ 

Since AE = R, then:  $|A| \cdot |E| = |R|$ ; with only two cases:

$$\begin{cases} \mathbf{A} \text{ singular } (\mathbf{R}_{|n} = \mathbf{0} \ ) : & |\mathbf{A}| \cdot |\mathbf{E}| = 0 \ \Rightarrow \ |\mathbf{A}| = 0 \\ \\ \mathbf{A} \text{ not singular } (\mathbf{R} = \mathbf{I}) : & |\mathbf{A}| \cdot |\mathbf{E}| = 1 \ \Rightarrow \ |\mathbf{E}| = \left|\mathbf{A}^{-1}\right| = \left(|\mathbf{A}|\right)^{-1} \end{cases}$$

**Example** 

For 
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 2 \end{bmatrix}$$
:

$$\begin{bmatrix} 1 & 2 \\ 2 & 2 \\ \hline 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow[TypeI]{[(-2)^{7}+2]} \begin{bmatrix} 1 & 0 \\ 2 & -2 \\ \hline 1 & -2 \\ 0 & 1 \end{bmatrix} \xrightarrow[TypeII]{[(-1/2)2]} \begin{bmatrix} 1 & 0 \\ 2 & 1 \\ \hline 1 & 1 \\ 0 & -1/2 \end{bmatrix} \xrightarrow[TypeI]{[(-2)^{2}+1]} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \hline -1 & 1 \\ 1 & -1/2 \end{bmatrix}$$

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$$\left| \mathbf{A}^{-1} \right| = \left| \mathbf{I}_{[(-2) 1 + 2]} \right| \cdot \left| \mathbf{I}_{[(-1/2) 2]} \right| \cdot \left| \mathbf{I}_{[(-2) 2 + 1]} \right| = 1 \cdot \frac{-1}{2} \cdot 1 = \frac{-1}{2};$$

that is

$$|\mathbf{A}| = -2.$$

**EXERCISE 2.** [Transposed matrices]

- (a) What is the relation between the determinant of an elementary matrix  $I_{\tau}$  and the determinant of its transpose  $_{\tau}I$ ?
- (b) Consider B, a full rank matrix, proof that  $|B| = |B^{T}|$ .

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9 Determinant of a product

P-8 [Determinant of a product of matrices]

$$|\det(\mathbf{A}\mathbf{B}) = \det(\mathbf{A}) \cdot \det(\mathbf{B}).$$
 (3)

$$\begin{cases} \mathbf{B} \text{ singular, then so it is } \mathbf{A}\mathbf{B} \Rightarrow & \det(\mathbf{A}\mathbf{B}) = 0 = \det(\mathbf{A}) \cdot \det(\mathbf{B}) \\ \\ \mathbf{B} = \mathbf{I}_{\tau_1 \cdots \tau_k} \Rightarrow & \det(\mathbf{A}\mathbf{B}) = \det(\mathbf{A}) \cdot \det(\mathbf{B}) \end{cases}$$

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10 Determinant of a transpose

P-9 Determinant of a transpose

$$|\mathbf{A}| = |\mathbf{A}^{\mathsf{T}}|.$$

Proof.

$$\begin{cases} \text{if $\mathbf{A}$ singular:} & \mathbf{A}^\intercal \text{ singular } \Rightarrow \det \mathbf{A}^\intercal = \det \mathbf{A} = 0 \\ \\ \text{if $\mathbf{A}$ NO singular:} & \mathbf{A} = \mathbf{I}_{\tau_1 \cdots \tau_k} \Rightarrow \det \mathbf{A}^\intercal = \det \mathbf{A} \end{cases} .$$

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### Questions of the Lecture 14

(L-14) QUESTION 1. Complete the proofs of this lecture.

(L-14) QUESTION 2. Knowing that |BC| = |B||C|; prove that for any invertible matrix **A** (so det  $\mathbf{A} \neq 0$ )

$$\det(\mathbf{A}^{-1}) = \Big(\det(\mathbf{A})\Big)^{-1}.$$

(L-14) QUESTION 3. Consider  $\mathbf{A}$  and  $\mathbf{B}$  such that  $\det(\mathbf{A}) = 2$  and  $\det(\mathbf{B}) = -2$ 

- (a)  $(0.5^{\text{pts}})$  Compute the determinants of  $\mathbf{A}(\mathbf{B})^2$  and  $(\mathbf{A}\mathbf{B})^{-1}$
- (b)  $(0.5^{\text{pts}})$  Is it possible to compute the rank of  $\mathbf{A} + \mathbf{B}$ ? and the rank of  $\mathbf{AB}$ ?

(L-14) QUESTION 4. Use the Gauss-Jordan method to compute the determinant

$$\begin{aligned} & \textbf{(a)} \ \mathbf{A}_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \\ & \textbf{(b)} \ \mathbf{A}_2 = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \\ & \textbf{(c)} \ \mathbf{A}_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \end{aligned}$$

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1 Highlights of Lesson 15

# **Highlights of Lesson 15**

- Computing |A| by gaussian elimination
- P-10 Multilinear property
- Expansion of det A in Cofactors (Laplace expansion).
- Application of determinants
  - Cramer's rule for solving linear equations
  - Computing the inverse of A

(L-14) QUESTION 5. The 3 by 3 matrix A reduces to the identity matrix I by the following three column operations (in order):

$$au$$
: Subtract 4 times column 1 from column 2.  $[(-4)1+2]$ 

$$au$$
: Subtract  $3$  times column  $1$  from column  $3$ .

$$au$$
: Subtract column 3 from column 2.

Find the determinant of A.

(L-14) Question 6.

(a) Find the determinant of 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$
 and  $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ 

(a) Find the determinant of 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \text{ and } \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$
 (b) Find the determinant of 
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ a & b & c & d \end{bmatrix} \text{ using Gauss-Jordan}.$$

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2 Extended matrix

Extended matrix of B:

B
1

1. Given 
$$\tau$$
: 
$$\begin{bmatrix} \mathbf{B}_{\tau} \\ 1 \end{bmatrix} = \begin{bmatrix} \mathbf{B} \\ 1 \end{bmatrix}_{\tau}$$

2. Since  $\begin{bmatrix} \mathbf{I} \\ 1 \end{bmatrix}_{-}$  and  $\mathbf{I}_{\tau}$  same type Elem. Mat.  $\Rightarrow$  same det.

Applying 1. k times, and then 2.

$$\begin{split} \left| \begin{bmatrix} \mathbf{I}_{\tau_1 \cdots \tau_k} & \\ & 1 \end{bmatrix} \right| &= \left| \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_1 \cdots \tau_k} \right| = \left| \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_1} \cdots \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_k} \right| \\ &= \left| \mathbf{I}_{\tau_1} \right| \cdots \left| \mathbf{I}_{\tau_k} \right| = \left| \mathbf{I}_{\tau_1 \cdots \tau_k} \right|. \end{split}$$

If 
$${\bf A}$$
 is the extended matrix of  ${\bf B}$   $\begin{cases} \text{If } {\bf B} \text{ singular} & |{\bf B}|=0=|{\bf A}| \\ \text{If } {\bf B} \text{ invertible} & |{\bf B}|=|{\bf A}| \end{cases}$ 

#### **EXERCISE 7.** [Triangular matrices]

- (a) Find the determinant of a full rank lower triangular matrix L
- (b) Find the determinant of a triangular matrix with a zero entry in the main diagonal
- (c) Find the determinant of an upper triangular matrix **U**

In addition

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Matrices of order 1,  $\mathbf{A} = [a]$ :

$$\begin{bmatrix} a & 0 \\ \hline 0 & 1 \end{bmatrix} \Rightarrow |\mathbf{A}| = a.$$

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Matrices of order 2:

$$\begin{bmatrix} a & b & 0 \\ c & d & 0 \\ \hline 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{bmatrix} \left(-\frac{b}{a}\right) \mathbf{1} + \mathbf{2} \end{bmatrix}} \begin{bmatrix} a & 0 & 0 \\ c & d - \frac{bc}{a} & 0 \\ \hline 0 & 0 & 1 \end{bmatrix}$$

$$|\mathbf{A}| = ad - bc = a \det[d] - b \det[c].$$

Matrices of order 3:

$$|\mathbf{A}| = \underbrace{aei - afh - bdi + bfg + cdh - ceg}_{\text{(Rule of Sarrus)}} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

## **3** Computing by Gaussian elimination

## **Example**

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$$\mathbf{A} = \begin{bmatrix} 1 & 5 \\ 2 & 3 \end{bmatrix} : \quad \begin{bmatrix} 1 & 5 \\ 2 & 3 \end{bmatrix} \xrightarrow{[(-5)\mathbf{1}+\mathbf{2}]} \begin{bmatrix} 1 & 0 \\ 2 & -7 \end{bmatrix} \boxed{|\mathbf{A}| = -7}$$

## **Example**

$$\begin{bmatrix} 0 & 2 & 1 & 0 \\ 9 & 6 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ \hline 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\substack{[(2)\mathbf{3}] \\ [(-1)\mathbf{2}+\mathbf{3}] \\ \hline [(\frac{1}{2})\mathbf{4}]}} \begin{bmatrix} 0 & 2 & 0 & 0 \\ 9 & 6 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ \hline 0 & 0 & 0 & \frac{1}{2} \end{bmatrix} \xrightarrow{\substack{\boldsymbol{\tau} \\ [\mathbf{1} \stackrel{\boldsymbol{\tau}}{=} \mathbf{2}] \\ \hline [(-1)\mathbf{4}]}} \begin{bmatrix} 2 & 0 & 0 & 0 \\ 6 & 9 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \hline 0 & 0 & 0 & -\frac{1}{2} \end{bmatrix}$$

$$\begin{vmatrix} 0 & 2 & 1 \\ 9 & 6 & 3 \\ 0 & 1 & 1 \end{vmatrix} = -9,$$

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Matrices of order 4:

$$\begin{bmatrix} a & b & c & d & 0 \\ e & f & g & h & 0 \\ i & j & k & l & 0 \\ m & n & o & p & 0 \\ \hline 0 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{bmatrix} \left(-\frac{a}{a}\right)1+2 \\ \left(-\frac{a}{a}\right)1+4 \end{bmatrix}} \begin{bmatrix} \left(\frac{-ag+ce}{af-be}\right)2+3 \\ \left(\frac{-ag+ce}{af-be}\right)2+4 \\ \frac{(-ag+ce)}{af-be} + \frac{(-ah+ce)}{af-be} + \frac{(-ah+ce)}{af-be}$$

$$\begin{aligned} &afkp-aflo-agjp+agln+ahjo-ahkn-bekp+belo+bgip-bglm-bhio+bhkm+\\ &cejp-celn-cfip+cflm+chin-chjm-dejo+dekn+dfio-dfkm-dgin+dgjm\\ &=a\begin{vmatrix} f&g&h\\j&k&l&-b\\n&o&p\end{vmatrix} + \begin{vmatrix} e&g&h\\i&k&l&+c\\m&o&p\end{vmatrix} + \begin{vmatrix} e&f&h\\i&j&l&-d\\m&n&p\end{vmatrix} - \begin{vmatrix} e&f&g\\i&j&k\\m&n&o\end{vmatrix}$$

4 Multilinear property

# P-10 Multilinear property

$$\det\left[\ldots;(\beta \mathbf{b} + \psi \mathbf{c});\ldots\right] = \beta \det\left[\ldots;\mathbf{b};\ldots\right] + \psi \det\left[\ldots;\mathbf{c};\ldots\right]$$

## Example

Then, in the 2 dimensional case  $\mathbb{R}^2$ 

$$\begin{vmatrix} a + \alpha & c \\ b + \beta & d \end{vmatrix} = \begin{vmatrix} a & c \\ b & d \end{vmatrix} + \begin{vmatrix} \alpha & c \\ \beta & d \end{vmatrix};$$

therefore

$$\begin{vmatrix} a & c \\ b & d \end{vmatrix} = \begin{vmatrix} a & c \\ 0 & d \end{vmatrix} + \begin{vmatrix} c \\ d \end{vmatrix}.$$

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Example

For 
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$
, we have

$$egin{align*} {}^{1^{\eta}}\mathbf{A}^{^{\eta}\!2} = egin{bmatrix} 4 & 6 \ 7 & 9 \end{bmatrix}, \qquad {}^{3^{\eta}}\mathbf{A}^{^{\eta}\!3} = egin{bmatrix} 1 & 2 \ 4 & 5 \end{bmatrix} \end{split}$$

hence

$$\operatorname{cof}_{12}\left(\mathbf{A}\right) = (-1)^{\frac{1+2}{2}} \det \begin{pmatrix} 1^{\uparrow} \mathbf{A}^{\dagger 2} \end{pmatrix} = (-1) \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix}.$$

and

$$\operatorname{cof}_{33}\left(\mathbf{A}\right) = (-1)^{3+3} \det \begin{pmatrix} 3^{9} \mathbf{A}^{73} \end{pmatrix} = \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix}.$$

5 minors and cofactors

### **Definition minors and cofactors**

We denote a submatrix of  $\bf A$  obtained by deleting row i and column j of  $\bf A$  by

$$i^{\dagger} \mathbf{A}^{\dagger j};$$

Its determinant is called the minor of  $a_{ij}$ . And

$$\operatorname{cof}_{ij}\left(\mathbf{A}\right) = (-1)^{i+j} \det\left({}^{i^{\uparrow}}\mathbf{A}^{i^{\flat}}\right)$$

is called the cofactor of  $a_{ij}$ .

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**6** Expansion by cofactors

## Theorem [Laplace expansion]

For **A** n by n,  $det(\mathbf{A})$  may be computed as the sum of the products of the elements of any column (row) of **A** by their cofactors:

$$\det(\mathbf{A}) = \sum_{i=1}^{n} a_{ij} \operatorname{cof}_{ij}(\mathbf{A}),$$
 the expansion by the  $j$ th column

or

$$\det(\mathbf{A}) = \sum_{j=1}^{n} a_{ij} \operatorname{cof}_{ij} (\mathbf{A}),$$
 the expansion by the  $i$ th row

EXERCISE 8. Compute 
$$\det \mathbf{A} = \begin{vmatrix} 2 & 0 & 3 & 2 \\ 5 & 1 & 2 & 4 \\ 3 & 0 & 1 & 2 \\ 5 & 3 & 2 & 1 \end{vmatrix}$$

**7** Cramer's Rule

$$\mathbf{A}x = \mathbf{b}; \qquad |\mathbf{A}| \neq 0 \quad \text{then}$$

$$\boldsymbol{b} = (\mathbf{A}_{|1})x_1 + \dots + (\mathbf{A}_{|j})x_j + \dots + (\mathbf{A}_{|n})x_n.$$

$$\det \Big[ \mathbf{A}_{|1}; \; \dots \; \overbrace{\boldsymbol{b}}^{\mathsf{pos.} \; j}; \; \dots \; \mathbf{A}_{|n} \Big] = x_j \cdot \det(\mathbf{A}).$$

$$x_j = \frac{\det\left[\mathbf{A}_{|1}; \dots \underbrace{\mathbf{b}}_{|n}; \dots \mathbf{A}_{|n}\right]}{\det(\mathbf{A})}.$$

Computational issues when  $\det \mathbf{A} \simeq 0$  (tiny angle between vectors)

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## **Questions of the Lecture 15**

(L-15) QUESTION 1. Complete the proofs of the exercises of this lecture.

 $\text{(L-15) QUESTION 2. Consider } \mathbf{A} = \begin{bmatrix} \mathbf{A}_{|1}; & \mathbf{A}_{|2}; & \mathbf{A}_{|3}; \end{bmatrix} \text{ with } \det \mathbf{A} = 2.$ 

- (a) What are  $det(2\mathbf{A})$  and  $det \mathbf{A}^{-1}$ ?
- (b) What is  $\det \left[ (3{\bf A}_{|1} + 2{\bf A}_{|2}); \quad {\bf A}_{|3}; \quad {\bf A}_{|2}; \right]$

(L-15) QUESTION 3. The determinant of the 1000 by 1000 matrix  $\bf A$  is 12. What is the determinant of  $-{\bf A}^{T}$ ? (Careful: No credit for the wrong sign.) (MIT Course 18.06 Quiz 2, Fall, 2008)

(L-15) QUESTION 4. Consider the squared matrix **A**. True or false? (to receive full credit you must explain your answer in a clear and concise way)  $|\mathbf{A}\mathbf{A}^\intercal| = |\mathbf{A}|^2$ .

(L-15) QUESTION 5. We have a  $3 \times 3$  matrix  $\mathbf{A} = \begin{bmatrix} a & 1 & 2 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$  with  $\det \mathbf{A} = 3$ .

Compute the determinant of the following matrices

(a) (0.5 pts) 
$$\begin{bmatrix} a-2 & 1 & 2 \\ b-4 & 3 & 4 \\ c-6 & 5 & 6 \end{bmatrix}$$

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8 The inverse of a matrix

$$[Adj(A)] \cdot A =$$

$$\begin{bmatrix} \operatorname{cof}_{11}\left(\mathbf{A}\right) & \operatorname{cof}_{21}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{n1}\left(\mathbf{A}\right) \\ \operatorname{cof}_{12}\left(\mathbf{A}\right) & \operatorname{cof}_{22}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{n2}\left(\mathbf{A}\right) \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{cof}_{1n}\left(\mathbf{A}\right) & \operatorname{cof}_{2n}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{nn}\left(\mathbf{A}\right) \end{bmatrix} \underbrace{\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}}_{\mathbf{A}}$$

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(b) (0.5 pts) 
$$\begin{bmatrix} 7a & 7 & 14 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$$
(c) (1 pts)  $(2\mathbf{A})^{-1}\mathbf{A}^{\mathsf{T}}$ 

(d) (0.5 pts) 
$$\begin{bmatrix} a-2 & 1 & 2 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$$

#### (L-15) Question 6.

- (a) Escalone la matriz  ${\bf A} = \begin{bmatrix} 2 & 3 & 1 \\ 4 & 5 & 2 \\ 4 & 6 & 0 \end{bmatrix}$
- (b) ; Es A invertible?
- (c) En caso afirmativo calcule  $|\mathbf{A}^{-1}|$ ; en caso contrario calcule  $|\mathbf{A}|$
- (d) La matriz C es igual al producto de A con la traspuesta de la matriz B, es decir

$$\mathbf{C} = \mathbf{A}\mathbf{B}^{\mathsf{T}} \qquad \mathsf{donde} \qquad \mathbf{B} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 2 & 3 \end{bmatrix}$$

¿Cuánto vale el determinante de C? ¿Es C invertible?

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(L-15) QUESTION 10. Compute the value of det A using Laplace expansion

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 0 & 2 & 2 & \cdots & 2 \\ 0 & 0 & 3 & \cdots & 3 \\ \vdots & & & \ddots & \\ 0 & 0 & 0 & \cdots & n \end{bmatrix}$$

(L-15) QUESTION 11. Consider a n by n matrix  $\mathbf{A}_n$  full of 3s in its diagonal, and twos just below the diagonal, and another 2 at the position (1,n); for example, for n=4:

$$\mathbf{A}_4 = \begin{bmatrix} 3 & 0 & 0 & 2 \\ 2 & 3 & 0 & 0 \\ 0 & 2 & 3 & 0 \\ 0 & 0 & 2 & 3 \end{bmatrix}.$$

- (a) Find, using the cofactors of the first row, the determinant of  $A_4$ .
- (b) Find the determinant of  $\mathbf{A}_n$  for n > 4.

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(L-15) QUESTION 7. What is the determinant of the following matrices using Laplace expansions.

(a) 
$$\begin{bmatrix} 1 & 2 \\ -4 & 3 \end{bmatrix}$$
(b) 
$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 1 & -2 \end{bmatrix}$$
(c) 
$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \\ 2 & 0 & 1 & -2 \end{bmatrix}$$

(L-15) QUESTION 8. Compute the following determinant using Laplace expansions:

$$\begin{vmatrix} 0 & 0 & 0 & 3 & 0 \\ -2 & 0 & 0 & 2 & 0 \\ 8 & -1 & 0 & -7 & 2 \\ -1 & 2 & 2 & 3 & 2 \\ 2 & 2 & 3 & 6 & 4 \end{vmatrix}$$

(L-15) QUESTION 9. Compute 
$$\det \mathbf{A} = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 5 & 5 & 0 & 0 \\ 3 & 0 & 1 & 0 \\ 5 & 0 & 0 & 1 \end{bmatrix}$$

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(L-15) QUESTION 12. Consider the following block matrix

$$\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{0} \\ \mathbf{0} & \mathbf{C} \end{bmatrix}$$

Prove  $|\mathbf{A}| = |\mathbf{B}||\mathbf{C}|$ .

(L-15) QUESTION 13. Solve the following linear systems using Cramer's Rule

(a) 
$$\begin{cases} 2x + 5y = 1 \\ x + 4y = 2 \end{cases}$$
(b) 
$$\begin{cases} 2x + y = 1 \\ x + 2y + z = 0 \\ y + 2z = 0 \end{cases}$$

(exercise 13 from section 4.4 of Strang (2006))

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(L-15) QUESTION 14. Find the inverse of the following matrices using the *adjoint matrix* 

(a) 
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 0 & 4 & 1 \end{bmatrix}$$
  
(b)  $\mathbf{B} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$ 

(exercise 18 from section 4.4 of Strang (2006))

(L-15) QUESTION 15. Consider the matrices

$$\mathbf{A} = \begin{bmatrix} 1 & 4 & 2 & 3 \\ 2 & 3 & 3 & 7 \\ 0 & 1 & 0 & 3 \\ 0 & 2 & 0 & a \end{bmatrix}, \ \mathbf{B} = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}; \ \text{and the vector } \boldsymbol{b} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

- (a)  $(0.5^{\rm pts})$  For wich values of a the matrix **A** is invertible?
- (b) (1<sup>pts</sup>) Consider a=5. Using the Cramer's rule, compute the fourth coordinate  $x_4$  of x for linear system  $\mathbf{A}x=\mathbf{b}$ .
- (c) (1<sup>pts</sup>) Compute  $\mathbf{B}^{-1}$ . Use the matrix  $\mathbf{B}^{-1}$  to solve  $\mathbf{B}x = b$ .

Strang, G. (2006). *Linear algebra and its applications*. Thomson Learning, Inc., fourth ed. ISBN 0-03-010567-6.