Mathematics II

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1 Highlights of Lesson 15

Always squared matrices in this topic

Highlights of Lesson 15

- **Eigenvalues, eigenvectors** (prefix eigen is the German word for innate, distinct, self)
- $\bullet \ |\mathbf{A} \lambda \mathbf{I}| = 0$

Characteristic equation

• tr (**A**), det **A**

(demo in the next lesson)

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2 Eigenvalues and eigenvectors

Consider the equation

$$\mathbf{A} \frac{\mathbf{x}}{\mathbf{x}} = \lambda \frac{\mathbf{x}}{\mathbf{x}}$$
 (with $\mathbf{x} \neq \mathbf{0}$)

- *Eigenvalue* is any λ such that there are solutions.
- Such non-null solutions x are called eigenvectors. $x \neq 0$ such that $\mathbf{A}x$ is multiple x

When λ is 0, What are the eigenvectors?

.

- **3** Example: projection matrix
- Orthogonal projection
- Which vectors are eigenvectors?
 What vectors are projected in the same starting direction?
- What are the eigenvalues of those eigenvectors?
- are there any other eigenvectors? with what eigenvalue?
- Two eigen-spaces

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5 how to find eigenvalues and eigenvectors?

How to solve

$$\mathbf{A}x = \widehat{\lambda} \stackrel{?}{\underbrace{\lambda}} ?$$

Here's the trick (simple idea). Bring the x s onto the same side . . .

$$(\mathbf{A} - \lambda \mathbf{I}) \boldsymbol{x} =$$

idea If $x \neq 0$ what kind of matrix must be $(\mathbf{A} - \lambda \mathbf{I})$?

and then its determinant must be? $|\mathbf{A} - \lambda \mathbf{I}| =$

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1.0

4 Another example: Interchange or swap matrix

$$\mathbf{A} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- A vector that does not change after interchange?
- What is the eigenvalue?
- Is there an eigenvector corresponding to $\lambda_2 = -1$?

$$\mathbf{A}x_2 = -x_2$$

Note: $\operatorname{tr}(\mathbf{A}) = 0 = \lambda_1 + \lambda_2$; $\det \mathbf{A} = -1 = \lambda_1 \cdot \lambda_2$.

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. . . .

1.

- 6 how to find eigenvalues and eigenvectors?
- 1. Eigenvalues are λ 's such that: $|\mathbf{A} \lambda \mathbf{I}| =$ (Characteristic polynomial $P_{\mathbf{A}}(\lambda)$)
- 2. How to compute x so that $(\mathbf{A} \lambda \mathbf{I}) x = \mathbf{0}$?

Eigenspace (Set of eigenvectors + 0):

$$\mathcal{E}_{\lambda}(\mathbf{A}) = \left\{ \left. oldsymbol{x} \in \mathbb{R}^n
ight| \mathbf{A} oldsymbol{x} = \lambda oldsymbol{x}
ight\}$$

Spectrum: set $\{\lambda_1, \dots \lambda_k\}$ of eigenvalues (roots of $P_{\mathbf{A}}(\lambda)$)

7 Example (we must compute the eigevalues first!)

We are looking for a null determinant (Characteristic polynomial)

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}; \qquad \det(\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 1 & 3 - \lambda \end{vmatrix} = (3 - \lambda)^2 - 1 = 0$$

Note: $\operatorname{tr}(\mathbf{A}) = 6 = \lambda_1 + \lambda_2$; $\det \mathbf{A} = 8 = \lambda_1 \cdot \lambda_2$.

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9 Another example: 90° rotation matrix

$$\mathbf{Q} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

- How much do the eigenvalues add up to?
- What is the determinant?

Difficulties

$$\lambda_1 + \lambda_2 = 0$$
 and $\lambda_1 \cdot \lambda_2 = 1$ $(+) \cdot (-) = (+)$

What kind of vector can be parallel to itself after a 90° rotation?

$$\det (\mathbf{Q} - \lambda \mathbf{I}) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 =$$

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8 Example (...and then the eigenspaces)

And now we compute the null space $\mathcal{N}(\mathbf{A} - \lambda \mathbf{I})$... for each λ .

For
$$\lambda_1 = 4$$

$$(\mathbf{A} - 4\mathbf{I}) = \begin{bmatrix} 3 - 4 & 1 \\ 1 & 3 - 4 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \Rightarrow$$

For
$$\lambda_2 = 2$$

$$(\mathbf{A} - 2\mathbf{I}) = \begin{bmatrix} 3 - 2 & 1 \\ 1 & 3 - 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow$$

Are they the only two eigenvectors?

$$\mathbf{A} oldsymbol{x}_i = \lambda oldsymbol{x}_i; \qquad egin{bmatrix} 3 & 1 \ 1 & 3 \end{bmatrix} oldsymbol{x}_i = \lambda oldsymbol{x}_i.$$

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10 There are even worse examples

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

Eigenvalues

$$\det (\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 0 & 3 - \lambda \end{vmatrix} = (3 - \lambda)(3 - \lambda) = 0 \begin{cases} \lambda_1 = 3 \\ \lambda_2 = 3 \end{cases}$$

Eigenvectors

• for
$$\lambda_1$$
: $(\mathbf{A} - \lambda \mathbf{I}) \boldsymbol{x} = \mathbf{0} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \boldsymbol{x}_1; \qquad \boldsymbol{x}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

• for λ_2 :

 $\lambda = 3$ is repeated twice, but $\dim \mathcal{E}_3(\mathbf{A}) = 1$

$$\mu(3) = 2 \neq 1 = \gamma(3)$$

Summary:

- 1. The eigenvalues are those numbers λ that makes the matrix $(\mathbf{A} \lambda \mathbf{I})$ singular. In other words, they are the roots of the Characteristic polynomial: $\det(\mathbf{A} \lambda \mathbf{I})$.
- 2. Any n by n matrix has a caracteristic polynomial of degree n
- 3. A polynomial of degree n has n roots (perhaps some repeated roots).
- 4. The sum of eigenvalues of a matrix equals its trace
- 5. The product of eigenvalues of a matrix equals its determinant
- 6. The eigenvectors associated with λ are the non-zero vectors in $\mathcal{N}(\mathbf{A} \lambda \mathbf{I})$.

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(b)

$$\mathbf{B} = \begin{bmatrix} a & b \\ b & a \end{bmatrix}$$

(Strang, 2006, exercise 12 from section 5.1.)

(L-15) QUESTION 3. If B has eigenvalues 1, 2, 3, C has eigenvalues 4, 5, 6, and D has eigenvalues 7, 8, 9, what are the eigenvalues of the 6 by 6 matrix $\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{0} & \mathbf{D} \end{bmatrix}$? where B, C, D are upper triangular matrices. (Strang, 2006, exercise 13 from section 5.1.)

 $\left(L\text{-}15\right)$ QUESTION 4. Find the eigenvalues and eigenvectors of

(a)

$$\mathbf{A} = \begin{bmatrix} 3 & 4 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

(b)

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 2 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

(Strang, 2006, exercise 5 from section 5.1.)

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Questions of the Lecture 15

(L-15) QUESTION 1. Consider the matrix

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$$\mathbf{A} = \begin{bmatrix} -3 & 4 & -4 \\ -3 & 5 & -3 \\ -1 & 2 & 0 \end{bmatrix}$$

(a) The three eigenvalues of $\bf A$ are -1, 1 and 2; and two of its eigenvectors are

Check that both vectors are eigenvenctors of **A**. What are the corresponding eigenvalues?

(b) Find a third linearly independent eigenvector.

(L-15) QUESTION 2. Find the eigenvalues and eigenvectors of

(a)

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$$\mathbf{A} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

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(L-15) QUESTION 5. The eigenvalues of **A** equal the eigenvalues of **A**^T. This is because $\det(\mathbf{A} - \lambda \mathbf{I})$ equals $\det(\mathbf{A}^T - \lambda \mathbf{I})$.

(a) That is true because

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(b) Show by an example that, nevertheless, the eigenvectors of A and A^T are not the same.

(Strang, 2006, exercise 11 from section 5.1.)

(L-15) QUESTION 6. Consider the matrix **B** and its eigenvector \boldsymbol{x} associated to the eigenvalue λ , that is $\mathbf{B}\boldsymbol{x}=\lambda\boldsymbol{x}$; and also consider the matrix $\mathbf{A}=(\mathbf{B}+\alpha\mathbf{I})$. Prove that \boldsymbol{x} is also an eigenvector of \mathbf{A} with eigenvalue $(\lambda+\alpha)$.

(L-15) Question 7.

- (a) Encuentre los autovalores y los auto-vectores de la matriz $\mathbf{A} = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$ Compruebe que la traza es igual a la suma de los autovalores, y que el determinante es igual a su producto.
- (b) Si consideramos una nueva matriz, generada a partir de la anterior como

$$\mathbf{B} = (\mathbf{A} - 7\mathbf{I}) = \begin{bmatrix} -6 & -1 \\ 2 & -3 \end{bmatrix}.$$

¿Cuáles son los autovalores y auto-vectores de la nueva matriz, y como están relacionados con los de ${\bf A}$?

(Strang, 2006, exercise 1 and 3 from section 5.1.)

(L-15) QUESTION 8. Suponga que λ es un auto-valor de ${\bf A}$, y que ${\bf x}$ es un auto-vector tal que ${\bf A}{\bf x}=\lambda {\bf x}$.

- (a) Demuestre que ese mismo x es un auto-vector de $\mathbf{B} = \mathbf{A} 7\mathbf{I}$, y encuentre el correspondiente auto-valor de \mathbf{B} .
- (b) Suponga que $\lambda \neq 0$ (y que **A** es invertible), demuestre que x también es un auto-vector de \mathbf{A}^{-1} , y encuentre el correspondiente auto-valor. ¿Qué relación tiene con λ ?

(Strang, 2006, exercise 7 from section 5.1.)

(L-15) QUESTION 9. Suponga que $\bf A$ es una matriz de dimensiones $n\times n$, y que $\bf A^2=\bf A$. ¿Qué posibles valores pueden tomar los autovalores de $\bf A$?

(L-15) QUESTION 10. Suponga la matriz \mathbf{A} con autovalores 1, 2 y 3. Si v_1 es un auto-vector asociado al auto-valor 1, v_2 al auto-valor 2 y v_3 al auto-valor 3; entonces ¿cuanto es $\mathbf{A}(v_1+v_2-v_3)$?

(L-15) QUESTION 11. Proporcione un ejemplo que muestre que los auto-valores pueden cambiar cuando un múltiplo de una columna se resta de otra. ¿Por qué los pasos de eliminación no modifican los autovalores nulos? (Strang, 2006, exercise 6 from section 5.1.)

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(L-15) QUESTION 15. The equation $(\mathbf{A}^2 - 4\mathbf{I})x = b$ has no solution for some right-hand side b. Give as much information as possible about the eigenvalues of the matrix \mathbf{A} (the matrix \mathbf{A} is diagonalizable).

(L-15) QUESTION 16. You are given the matrix

$$\mathbf{A} = \begin{bmatrix} 0.5 & 0.2 & 0.2 \\ 0.1 & 0.5 & 0.5 \\ 0.4 & 0.3 & 0.3 \end{bmatrix}$$

One of the eigenvalues is $\lambda=1$. What are the eigenvalues of **A**? [Hint: Very little calculation required! You should be able to see another eigenvalue by inspection of the form of **A**, and the third by an easy calculation. You shouldn't need to compute $\det(\mathbf{A}-\lambda\mathbf{I})$ unless you really want to do it the hard way.]

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(L-15) QUESTION 12. El polinomio característico de una matriz ${\bf A}$ se puede factorizar como

$$\det(\mathbf{A} - \lambda \mathbf{I}) = (\lambda_1 - \lambda)(\lambda_2 - \lambda) \cdots (\lambda_n - \lambda).$$

Demuestre, partiendo de esta factorización, que el determinante de ${\bf A}$ es igual al producto de sus valores propios (autovalores). Para ello haga una elección inteligente del valor de λ .

(Strang, 2006, exercise 8 from section 5.1.)

(L-15) QUESTION 13. Calcule los valores característicos (autovalores o valores propios) y los vectores característicos de **A** y **A**²:

$$\mathbf{A} = \begin{bmatrix} -1 & 3 \\ 2 & 0 \end{bmatrix} \qquad \mathbf{y} \qquad \mathbf{A}^2 = \begin{bmatrix} 7 & -3 \\ -2 & 6 \end{bmatrix}$$

 ${\bf A}^2$ tiene los mismos _____ que ${\bf A}$. Cuando los autovalores de ${\bf A}$ son λ_1 y λ_2 , los autovalores de ${\bf A}^2$ son ____. (Strang, 2006, exercise 22 from section 5.1.)

(L-15) QUESTION 14. Suponga que los valores característicos de \mathbf{A} son 1, 2 y 4, ¿cuál es la traza de \mathbf{A}^2 ? ¿Cuál es el determinante de $(\mathbf{A}^{-1})^{\mathsf{T}}$? (Strang, 2006, exercise 10 from section 5.2.)

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1 Highlights of Lesson 16

Highlights of Lesson 16

- Similar matrices: $\mathbf{C} = \mathbf{S}^{-1}\mathbf{A}\mathbf{S}$
- Triangular block diagonalizing a matrix

• Diagonalizable matrices: when **C** is diagonal.

2 Similar matrices

Similarity

A and C are similar if there is an invertible S such that

$$\mathbf{C} = \mathbf{S}^{\text{-}1}\mathbf{A}\mathbf{S}$$

If **A** and **C** are similar (see demos in the book):

- The same determinant: $\det \mathbf{A} = \det \mathbf{C}$
- The same caracteristic polinomial: $|\mathbf{A} \lambda \mathbf{I}| = |\mathbf{C} \lambda \mathbf{I}|$
- The same eigenvalues (same algebraic and geometric multiplicities).
- The same trace.

$$\textit{Mirror} \text{ inverse transf.: } \left(\mathbf{I}_{(\tau_1\cdots\tau_k)}\right)^{-1} \ = \ _{esp(\tau_k^{-1}\cdots\tau_l^{-1})}\mathbf{I}$$

$$\mathbf{I} = \frac{\boldsymbol{\tau}}{\boldsymbol{\tau}_1 \cdots \boldsymbol{\tau}_k [(-\alpha) \mathbf{j} + \mathbf{i}]} \boldsymbol{\tau}_{(k+1)} \cdots \boldsymbol{\tau}_p [(\alpha) \mathbf{i} + \mathbf{j}]} \mathbf{I} = \frac{\boldsymbol{\tau}}{\boldsymbol{\tau}_1 \cdots \boldsymbol{\tau}_k [\left(\frac{1}{\alpha}\right) \mathbf{j}\right]} \boldsymbol{\tau}_{(k+1)} \cdots \boldsymbol{\tau}_p [(\alpha) \mathbf{j}]} \quad \Rightarrow \quad \mathbf{A} \text{ similar to } \boldsymbol{\tau}_1 \cdots \boldsymbol{\tau}_{n-1} \boldsymbol{\tau}$$

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4 Block diagonalizing a matrix (toothed matrix)

Consider
$$\mathbf{A} = \begin{bmatrix} \mathbf{C} & \\ \hline * & \mathbf{L} \end{bmatrix} \in \mathbb{C}^{n \times n}$$
 where

C (of order m) is singular and **L** is full rank lower triangular, then there exists S = RP (invertible) such that

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3 Block diagonalizing a matrix (toothed matrix)

Consider
$$\mathbf{A} = \left[\begin{array}{c|c} \mathbf{C} & \\ \hline * & \mathbf{L} \end{array} \right] \in \mathbb{C}^{n \times n}$$
 where

C (of order m) is singular and **L** is full rank lower triangular; then there exists an invertible R such that

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5 A very simple example

Consider
$$\mathbf{A}=\begin{bmatrix}1&-1&0\\0&0&0\\0&-2&1\end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{\begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\mathbf{0I}} \overset{(-)}{\underset{\mathbf{0}}{\mathbf{I}}} \underbrace{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \xrightarrow{\begin{bmatrix} [(1)1+2] \\ [(2)3+2] \\ [2=3] \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \xrightarrow{\begin{bmatrix} \mathbf{1} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ \hline \begin{bmatrix} [2=3] \\ [(-2)2+3] \\ [(-1)2+1] \end{bmatrix}}_{\mathbf{I}} \xrightarrow{\begin{bmatrix} \mathbf{1} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \xrightarrow{(+)}_{\mathbf{I}} \underbrace{\begin{bmatrix} \mathbf{C} \\ \mathbf{S} \end{bmatrix}}_{\mathbf{I}}$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{\text{diagonal}}$$

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6 A not so simple example

Example

Consider
$$\mathbf{A} = \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix}$$
 with eigenvalues $\mathbf{1}$, $\mathbf{1}$ and $\mathbf{0}$.

$$\begin{array}{c} (-) \\ \hline 11 \\ \hline \end{array} \end{array} \overbrace{ \begin{bmatrix} -3 & 0 & 3 \\ 3 & -3 & -9 \\ -1 & 2 & 5 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+3 \\ [(-2)2+3] \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} -3 & 0 & 0 \\ 3 & -3 & 0 \\ -1 & 2 & 0 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (2)3+2 \\ [(-1)3+1] \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} -2 & -2 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 11 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 1 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 1 & 1 \\ \hline \end{bmatrix} }^{\tau}$$

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8 Back to the simple, "toothless" example

Consider
$$\mathbf{A}=\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{\begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\mathbf{0}\mathbf{I}} \overset{(-)}{\underset{\mathbf{0}}{\mathbf{I}}} \underbrace{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ [2 = 3] \\ [(-2)2 + 3] \\ [(-1)2 + 1] \end{bmatrix}}_{\mathbf{T}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{I}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\mathbf{A}(\mathbf{S}_{|i}) = \lambda_i(\mathbf{S}_{|i}) \quad \Rightarrow \quad \mathbf{S}_{|i}$$
 is an eigenvector.

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7 Every matrix is similar to a toothed matrix

For every \boldsymbol{A} there exists \boldsymbol{S} such that

$$S^{-1}AS = C$$
 \Rightarrow $AS = SC$

where **C**, toothed, has the eigenvalues on the diagonal **Example**

$$\begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix} \begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix}}_{\text{toothed}}$$
Consequences

- $\sum \lambda_i = \operatorname{tr} \left(\mathbf{A}
 ight)$ and $\prod \lambda_i = \det \mathbf{A}$
- $\mathbf{AS}_{|j} = \mathbf{SC}_{|j}$ \Rightarrow for j such that $\mathbf{C}_{|j} = \lambda_i \mathbf{I}_{|j}$: $\mathbf{A}(\mathbf{S}_{|j}) = \lambda_i (\mathbf{S}_{|j}) \quad \Rightarrow \quad \mathbf{S}_{|j} \text{ is an eigenvector.}$

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9 Diagonalizable matrices

- A matrix is diagonalizable **if and only if** *algebraic* and *geometric* multiplicities are equal for each eigenvalue
- If there are no repeated eigenvalues, there are no "teeth" either
- When there are no repeated eigenvalues \mathbf{A} is diagonalizable (is sure to have n independent eigenvectors)

10 Diagonalizing a matrix

- Find the spectrum: $\{\lambda_1, \lambda_2, \ldots\}$
- Find the algebraic multiplicity of each eigenvalue: $\mu(\lambda_i)$

then choose one of these alternatives:

- 1. teething the matrix (implemented in NAcAL)
- 2. ... or for every λ_i
 - find the eigenspace

$$\mathcal{E}_{\lambda_i}(\mathbf{A}) = \left\{ \left. oldsymbol{x} \in \mathbb{R}^n \right| \mathbf{A} oldsymbol{x} = \lambda_i oldsymbol{x}
ight\} \ = \ \mathcal{N}(\mathbf{A} - \lambda_i \mathbf{I}).$$

ullet check $\mu(\lambda_i)=\dim \mathcal{E}_{\lambda_i}(\mathbf{A})$ (algebraic and geometric multiplicities are equal)

$$\mathbf{D} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_k \end{bmatrix}; \quad \mathbf{S} = \begin{bmatrix} \mathsf{Basis} \ \mathsf{for} \ \mathcal{E}_{\lambda_1}(\mathbf{A}) \# \cdots \# \mathsf{Basis} \ \mathsf{for} \ \mathcal{E}_{\lambda_k}(\mathbf{A}) \end{bmatrix}$$

$$\mathsf{S}^{ extsf{-}1}\mathsf{A}\mathsf{S} = \mathsf{D} \quad \Leftrightarrow \quad \mathsf{A} = \mathsf{S}\mathsf{D}\mathsf{S}^{ extsf{-}1}$$

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Questions of the Lecture 16 __

(L-16) QUESTION 1. Factor these two matrices into SDS⁻¹;

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

(Strang, 2006, exercise 15 from section 5.2.)

(L-16) QUESTION 2. Which of these matrices cannot be diagonalized?

(a)

$$\mathbf{A}_1 = \begin{bmatrix} 2 & -2 \\ 2 & -2 \end{bmatrix}$$

(b)

$$\mathbf{A}_2 = \begin{bmatrix} 2 & 0 \\ 2 & -2 \end{bmatrix}$$

(c)

$$\mathbf{A}_3 = \begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix}$$

(Strang, 2006, exercise 5 from section 5.2.)

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11 Matrix powers

If $\mathbf{A}x = \lambda x$ then $\mathbf{A}^2 x = \mathbf{A}\mathbf{A}x = \mathbf{A}(\lambda x) = \lambda \mathbf{A}x = \mathbf{A}(\lambda x)$

- What can I say about the eigenvectors?
- What is the relationship between the eigenvalues of ${\bf A}$ and those of ${\bf A}^2$

In a matrix form (if **A** is diagonalizable, $\mathbf{A} = \mathbf{SDS}^{-1}$):

$$A^2 = SDS^{-1}SDS^{-1} = SD^2S^{-1}$$

In general, for, $n \in \mathbb{Z}$, $n \ge 0...$ $\mathbf{A}^n =$ what about \mathbf{A} both diagonalizable and invertible?

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(L-16) QUESTION 3. If $\mathbf{A} = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$ find \mathbf{A}^{100} by diagonalizing \mathbf{A} . (Strang, 2006, exercise 7 from section 5.2.)

(L-16) QUESTION 4. If the eigenvalues of $\mathbf{A}_{3\times3}$ are 1, 1 and 2, which of the following are certain to be true? Give a reason if true or a counterexample if false:

- (a) A is invertible.
- (b) A is diagonalizable.
- (c) A is not diagonalizable

(Strang. 2006, exercise 11 from section 5.2.)

(L-16) QUESTION 5. Let **A** be the matrix

$$\mathbf{A} = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 1 & 0 & 0 & 2 \end{bmatrix}$$

- (a) (1^{pts}) Determine if **A** is diagonalizable, and if so, diagonalize it.
- (b) (0.5^{pts}) Compute $(\mathbf{A}^6)\mathbf{v}$, where $\mathbf{v} = (0, 0, 0, 1)$.
- (c) (0.5^{pts}) Using the the eigenvalues found in part (a) justify that **A** is invertible.
- (d) (0.5^{pts}) What is the relation between the eigenvalues of A and the eigenvalues of A⁻¹?

(L-16) QUESTION 6. Si $A = SDS^{-1}$; entonces $A^3 = ($)()() $A^{-1} = ($)()(). (Strang, 2006, exercise 16 from section 5.2.)

(L-16) QUESTION 7. Considere la matriz

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$$

- (a) Encuentre los autovalores de A
- (b) Encuentre los auto-vectores de A
- (c) Diagonalice **A**: escríbalo como $\mathbf{A} = \mathbf{SDS}^{-1}$.

(L-16) QUESTION 8. ¿Falso o verdadero? Si los autovalores de ${\bf A}$ son 2, 2 y 3 entonces sabemos que la matriz es

- (a) Invertible
- (b) Diagonalizable
- (c) No diagonalizable.

(L-16) QUESTION 9. Sean las matrices

$$\mathbf{A}_1 = \begin{bmatrix} 8 & \\ & 2 \end{bmatrix}; \qquad \mathbf{A}_2 = \begin{bmatrix} 9 & 4 \\ & 1 \end{bmatrix}; \qquad \mathbf{A}_3 = \begin{bmatrix} 10 & 5 \\ -5 & \end{bmatrix}$$

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- (a) Encuentre los autovalores y auto-vectores de la matriz $\mathbf{A}=\begin{bmatrix}1&0&0\\-2&1&0\\1&0&1\end{bmatrix}$.
- (b) Explique por qué (o por qué no) la matriz A es diagonalizable.

(L-16) QUESTION 14. Sea **A** una matriz 3×3 . Asuma que sus autovalores son 1 y 0, que una base de los autovectores asociados a $\lambda=1$ son [1,0,1] y [0,0,1]; mientras que los asociados a $\lambda=0$ son paralelos a [1,1,2].

- (a) ¿Es A diagonalizable? En caso afirmativo escriba la matriz diagonal $\bf D$ y la matriz $\bf S$ tales que $\bf A = \bf S \bf D \bf S^{-1}$.
- (b) Encuentre A.

(L-16) QUESTION 15. Let $\bf A$ be a 2×2 matrix such that $\begin{pmatrix} 2\\0 \end{pmatrix}$ is an eigenvector for $\bf A$ with eigenvalue 2, and $\begin{pmatrix} 2\\-1 \end{pmatrix}$ is another eigenvector for $\bf A$ with eigenvalue -2. If ${\bf v}=\begin{pmatrix} 1\\-1 \end{pmatrix}$, compute $({\bf A}^3){\bf v}$.

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- (a) Complete dichas matrices de modo que en los tres casos $\det \mathbf{A}_i = 25$. Así, la traza es en todos los casos igual a 10, y por tanto para las tres matrices el único auto-valor $\lambda = 5$ está repetido dos veces ($\lambda^2 = 25$ y $\lambda + \lambda = 10$ implica $\lambda = 5$).
- (b) Encuentre un vector característico con $\mathbf{A}x=5x$. Estas tres matrices no son diagonalizable porque no hay un segundo auto-vector linealmente independiente del primero.

(Strang, 2006, exercise 27 from section 5.2.)

(L-16) QUESTION 10. Factorice las siguientes matrices en S D S^{-1}

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

(b) $\mathbf{B} = \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix}$

(Strang, 2006, exercise 1 from section 5.2.)

(L-16) QUESTION 11. Encuentre la matriz **A** cuyos autovalores son 1 y 4, cuyos autovectores son $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$ y $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ respectivamente. (Strang, 2006, exercise 2 from section 5.2.)

(L-16) QUESTION 12. Si los elementos diagonales de una matriz triangular superior de orden 3×3 son 1, 2 y 7, ¿puede saber si la matriz es diagonalizable? ¿Quién es **D**? (Strang, 2006, exercise 4 from section 5.2.)

(L-16) Question 13.

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1 Highlights of Lesson 17

Highlights of Lesson 17

- Symetric matrices $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$
 - Eigenvalues and eigenvectors
- Introd. positive Definiteness matrices

2 Symmetric matrices $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$

what's special about $\mathbf{A} oldsymbol{x} = \lambda oldsymbol{x}$ when $oldsymbol{\mathbf{A}}$ is symmetric?

- 1. A symmetric matrix has only REAL EIGENVALUES
- 2. n EIGENVECTORS can be choosen ORTHOGONAL

(always diagonalizable)

The usual diagonalizable case:

$$S^{-1}AS = D \longleftrightarrow A = SDS^{-1}$$

Symmetric case:

I can choose perpendicular unit eigenvectors (ortho*normal* columns of $\mathbf{S} = \mathbf{Q}$)

(if
$$\mathbf{A} = \mathbf{A}^{\mathsf{T}}$$
) $\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}}$ Spectral thm.

Orthogonally diagonalizable.

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4 Quadratic forms

Quadratic form:

$$xAx$$
; with $A^{T} = A$

Since $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$ (with $\mathbf{Q}^{\mathsf{T}} \mathbf{Q} = \mathbf{Q} \mathbf{Q}^{\mathsf{T}} = \mathbf{I}$), then

$$x A x = x Q D Q^{\mathsf{T}} x = (Q^{\mathsf{T}} x) D (Q^{\mathsf{T}} x)$$
 (weighted sum of squares)

Positive definite quadratic form:

$$x\mathbf{A}x > 0 \quad \forall x \neq \mathbf{0} \qquad \Longleftrightarrow \qquad \lambda_i > 0, \quad i = 1:n.$$

then we also say **A** is positive definite.

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3 Eigenspaces are orthogonal for symmetric matrices

Eigenvectors (corresponding to different eigenvalues) of a symmetric matrix are orthogonal.

Proof.

Consider $\mathbf{A}x = \lambda_1 x$ and $\mathbf{A}y = \lambda_2 y$ (with $\lambda_1 \neq \lambda_2$). then

$$\lambda_1 \boldsymbol{x} \cdot \boldsymbol{y} = \mathbf{A} \boldsymbol{x} \cdot \boldsymbol{y} = \boldsymbol{x} (\mathbf{A}^\intercal) \boldsymbol{y} = \boldsymbol{x} \mathbf{A} \boldsymbol{y} = (\boldsymbol{x} \cdot \boldsymbol{y}) \lambda_2.$$

Since $\lambda_1 \neq \lambda_2$ then:

$$\lambda_1(\boldsymbol{x}\cdot\boldsymbol{y}) - \lambda_2(\boldsymbol{x}\cdot\boldsymbol{y}) = 0 \implies (\lambda_1 - \lambda_2)\boldsymbol{x}\cdot\boldsymbol{y} = 0 \implies \boldsymbol{x}\cdot\boldsymbol{y} = 0.$$

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5 Positive definite matrices

Meaning:

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 (except for $\boldsymbol{x} = \mathbf{0}$)

Some properties

Consider a positive definite symmetric A: What about A^{-1} ?

$$\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{-}1} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{T}}$$

Consider two positive definite symmetric matrices A, B: What about A + B?

the answer must be...

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6 The matrix product **A**^T**A**

Consider the rectangular matrix \mathbf{A} . Is $\mathbf{A}^{\mathsf{T}}\mathbf{A}$ positive definite?

$$\boldsymbol{x}(\mathbf{A}^{\intercal}\mathbf{A})\boldsymbol{x} =$$

It can only be 0 when $\mathbf{A}x$ is $\mathbf{0}$

How can we guarantee that $\mathbf{A}x \neq \mathbf{0}$ when $x \neq \mathbf{0}$?

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8 Positive definite symmetric matrices

- All eigenvalues are:
- All pivots are:

$$\begin{bmatrix} 5 & 2 \\ 2 & 3 \end{bmatrix}$$

Pivots:

What is the sign of each eigenvalue?

$$\lambda^2 - 8\lambda + 11 = 0 \rightarrow \lambda = 4 \pm \sqrt{5} > 0$$

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7 Symmetric matrices: signs of eigenvalues

are all λ_i positive? are they negative?

Computing eigenvalues of ${\bf A}$ is impossible in general! (5th degree polynomial)

Good news: The signs of the pivots of echelon form are the same as the signs of the eigenvalues λ_i (if we do not change the sign of the determinant with *Type II* elementary transformations)

num. of positive pivots = num. of positive eigenvalues

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Summary (for symmetric matrices):

- 1. Symmetric matrices have *real eigenvalues* and *perpendicular eigenvectors* can be choosen
- 2. $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$ where \mathbf{Q} is orthogonal
- 3. A is symmetric if and only if it is *orthogonally* diagonalizable
- 4. The signs of the pivots in the echelon form are same as the signs of the eigenvalues λ_i (only if we do not change the sign of the determinant with $Type\ II$ elementary transformations)

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Questions of the Lecture 17

(L-17) QUESTION 1. Write A, B and C in the form QDQ^T of the spectral theorem:

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(a)
$$\mathbf{A} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

(Strang, 2006, exercise 11 from section 5.5.)

(L-17) QUESTION 2. Find the eigenvalues and the unit eigenvectors of

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

(Strang, 2003, exercise 3 from section 6.4.)

(L-17) QUESTION 3. Find an orthonormal **Q** that diagonalizes this symmetric matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{bmatrix}$$

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(L-17) QUESTION 6. Sean

- (a) Encuentre los valores característicos de **A** (recuerde que $i^2 = -1$).
- (b) Encuentre los valores característicos de B (en este caso quizá le resulte más sencillo encontrar primero los autovectores, y deducir entonces los autovalores).
- (c) De los siguientes tipos de matrices: ortogonales, invertibles, permutación, hermíticas, de rango 1. diagonalizables, de Markov ¿a qué tipos pertenece A?
- (d) ¿y **B**?

(Strang, 2006, exercise 14 from section 5.5.)

(L-17) QUESTION 7. Si ${\bf A}^3={\bf 0}$ entonces los autovalores de ${\bf A}$ deben ser _____. De un ejemplo tal que ${\bf A}\neq {\bf 0}$. Ahora bien, si ${\bf A}$ es además simétrica, demuestre que entonces ${\bf A}^3$ es necesariamente ${\bf 0}$.

(Strang, 2003, exercise 5 from section 6.4.)

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(L-17) QUESTION 4. Suppose **A** is a symmetric 3 by 3 matrix with eigenvalues 0, 1,2.

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- (a) What properties can be guaranteed for the corresponding unit eigenvectors $oldsymbol{u},\,oldsymbol{v}$ and $oldsymbol{w}$
- (b) In terms of u, v, w, describe the nullspace, left nullspace, row space, and column space of \mathbf{A} .
- (c) Find a vector x that satisfies Ax = v + w. Is x unique?
- (d) Under what conditions on b does Ax = b have a solution?
- (e) If u, v, w are the columns of S, what are S^{-1} and $S^{-1}AS$.

(Strang, 2006, exercise 13 from section 5.5.)

(L-17) QUESTION 5. Escriba un hecho destacado sobre los valores característicos de cada uno de estos tipos de matrices:

- (a) Una matriz simétrica real.
- (b) Una matriz diagonalizable tal que $\mathbf{A}^n \to \mathbf{0}$ cuando $n \to \infty$.
- (c) Una matriz no diagonalizable
- (d) Una matriz singular

(Strang, 2006, exercise 16 from section 5.5.)

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(L-17) QUESTION 8. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} a & 1 & 1 \\ 0 & 3 & 1 \\ 0 & 0 & 2 \end{bmatrix}.$$

- (a) Prove that **A** is not diagonalizable when a=3.
- (b) Is **A** diagonalizable when a=2? (explain). If it is diagonalizable, find an eigenvalue diagonal matrix **D** and an eigenvector matrix **S** such as $\mathbf{A} = \mathbf{SDS}^{-1}$.
- (c) Is A^TA diagonalizable for any value a? Is it possible to find a full set of orthonormal eigenvectors of A^TA?
- (d) Find all posible values a such as **A** is invertible and diagonalizable.
- (L-17) QUESTION 9. Sea la matriz

$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix};$$

- (a) Exprese B en la forma $B = A = QDQ^{T}$ del teorema espectral.
- (b) ¿Es B diagonalizable? Si no lo es, diga las razones; y en caso contrario genere una matriz S que diagonalice a B.

1 Highlights of Lesson 18

Highlights of Lesson 18

- Positive and Negative (semi)definite matrices
- Completing the squares
- Diagonalization by congruence

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Example

What number do I have to put there for the matrix **A** to be singular?

$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix}$$

- Eigenvalues:
- Leading principal minors:
- For the following quadratic form

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + y^2$$

Is there a ${m x} \neq {m 0}$ such that ${m x} {m A} {m x} = 0$?

2 Our direction forms

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2 Quadratic forms

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- Positive definite: $\forall x \neq 0 \Rightarrow xAx > 0$.
- Positive semi-definite: $\forall x \neq 0 \Rightarrow x \land x \geq 0$.
- Negative definite: $\forall x \neq 0 \Rightarrow x A x < 0$.
- Negative semi-definite: $\forall x \neq 0 \Rightarrow x \land x \leq 0$.
- Indefinite: neither positive semi-definite, nor negative semi-definite.

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Example

If
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & \mathbf{7} \end{bmatrix}$$
 then $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 7 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + \mathbf{?} y^2$

- Are there numbers x and y that make xAx negative?
- Does the function go through the origin?
- When y = 0 and x = 1, is it possitive? (and when x = -1?)
- When x = 0 and y = 1, is it possitive? (and when y = -1?)
- Is it always positive?

(0,0,) saddle $\mbox{point}\colon$ minimum in some directions, maximum in others.

$$\lambda_1 = -2, \quad \begin{pmatrix} -6\\4 \end{pmatrix}; \qquad \lambda_1 = 11, \quad \begin{pmatrix} 6\\9 \end{pmatrix}$$

Example

If
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix}$$
 then $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + 20y^2$

Positive definite.

Does it pass the tests?

- Are the leading principal minors positive?
- Are the eigenvalues positive?

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 for all $\boldsymbol{x} \neq \mathbf{0}$

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4 Congruent matrices

 \boldsymbol{A} and \boldsymbol{C} are congruent if there exists an invertible \boldsymbol{B} such that $\boxed{\boldsymbol{C} = \boldsymbol{B}^{\mathsf{T}}\boldsymbol{A}\boldsymbol{B}}$

Diagonalization by congruence

For each **A** (symmetric) exists $\mathbf{B} = \mathbf{I}_{ au_1 \cdots au_k}$ (invertible) such that

$$\mathbf{D} = \mathbf{B}^{\mathsf{T}} \mathbf{A} \mathbf{B}$$
 is diagonal $(\mathbf{B}^{\mathsf{T}} = {}_{\tau_{\iota} \cdots \tau_{1}} \mathbf{I})$

Spectral Theorem: ¡Diagonalization by similarity and congruence!

$$\mathbf{D} = \mathbf{Q}^{-1} \mathbf{A} \mathbf{Q} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}.$$

Hence, every quadratic form can be written as a sum of squares

$$x \mathbf{A} x = x (\mathbf{B}^{-1})^{\mathsf{T}} \mathbf{D} \mathbf{B}^{-1} x = y \mathbf{D} y;$$
 where $y = \mathbf{B}^{-1} x$.

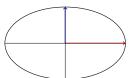
3 Completing the squares

If we could express q(x) as a sum of squares, we would know whether q(x) is positive definite.

Let's complete the square!

- $q(x,y) = 2x^2 + 12xy + 20y^2 = 2(x + ?y)^2 + ?$
- $q(x,y) = 2x^2 + 12xy + 7y^2$
- $q(x,y) = 2x^2 + 12xy + 18y^2$
- $q(x,y) = 2x^2 + 12xy + 200y^2$ (graph)

If positive definite: q(x,y) = a; a > 0: ellipse



is $q(x,y,z,w,t) = 2t^2 - 2tx - 2tz + w^2 - 2wy + 2x^2 - 2xy + 2y^2 + z^2$

positive definite? ② ② ② ② ② !!!????

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5 Completing the squares

$$2x^2 + 12xy + 20y^2$$

$$\begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \xrightarrow{[(-3)\mathbf{1}+\mathbf{2}]} \begin{bmatrix} \mathbf{2} & 0 \\ 6 & 2 \end{bmatrix} \xrightarrow{\boldsymbol{\tau}} \begin{bmatrix} \mathbf{2} & 0 \\ 0 & 2 \end{bmatrix};$$

therefore, we get:

$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \mathbf{D} = \mathbf{E}^{\mathsf{T}} \mathbf{A} \mathbf{E} = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}$$

hence $\mathbf{A} = (\mathbf{E}^{\intercal})^{-1} \mathbf{D} \mathbf{E}^{-1}$ so

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \boldsymbol{x} (\mathbf{E}^{-1})^{\mathsf{T}} \end{pmatrix} \mathbf{D} \begin{pmatrix} \mathbf{E}^{-1} \boldsymbol{x} \end{pmatrix}$$
$$= \begin{pmatrix} (x+3y), & y, \end{pmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{pmatrix} (x+3y) \\ y \end{pmatrix} = 2(x+3y)^2 + 2y^2$$

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6 example 3 by 3

Is
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$
 positive definite?

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{1}{2}\right)\mathbf{1}+\mathbf{2}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{1}{2}\right)\mathbf{1}+\mathbf{2}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{2}{3}\right)\mathbf{2}+\mathbf{3}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & 0 \\ 0 & 0 & \frac{4}{3} \end{bmatrix}$$

$$x\mathbf{A}x = 2x^2 + 2y^2 + 2z^2 - 2xy - 2yz > 0$$

 $x \mathbf{A} x = 1$: (ellipsoid) axes are eigenvectors $\mathbf{A} = \mathbf{Q}^{\mathsf{T}} \lambda \mathbf{Q}$

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8 Another example 3 by 3

Is $\mathbf{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ positive definite?

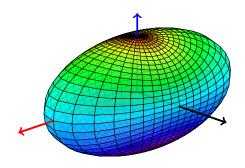
$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(1)3+1]{\textbf{7}} \begin{bmatrix} 2 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(-\frac{1}{2})1+3]{\textbf{7}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} \xrightarrow[\textbf{2}=3]{\textbf{2}=3} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Indefinite matrix

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7 Positive definite matrices and ellipsoids: example 3 by 3

- The region (xAx = a) is an (ellipsoid).
- The eigenvectors of Q are in the direction of the three principal axes.
- Lengths of axes determined by the eigenvalues



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9 "Classification" of quadratic

$$x \mathbf{A} x \stackrel{\leq}{=} 0; \quad \text{for all } x \neq \mathbf{0}$$

Methods

Check the signs of

- 1. Elem. diag.: $D = B^{T}AB$ (Diagonalization by congruence)
- 2. Computing eigenvalues: (Roots of a polynomial) ©
- 3. Leading principal minors: (Sylvester's criterion) ②

Law of inertia

the number of positive, negative and zero entries of the diagonal of \mathbf{D} is an invariant of \mathbf{A} , i.e. it does not depend on \mathbf{B} (Orthogonal diagonalization $\mathbf{D} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}$ is a special case)

Questions of the Lecture 18

(L-18) QUESTION 1. Decide for or against the positive definiteness of these matrices, and write out the corresponding quadratic form $f=x\mathbf{A}x$:

- (a) $\begin{bmatrix} 1 & 3 \\ 3 & 5 \end{bmatrix}$
- (b) $\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$
- (c) $\begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$
- (d) $\begin{bmatrix} -1 & 2 \\ 2 & -8 \end{bmatrix}$
- (e) The determinant in (b) is zero; along what line is f(x,y)=0?

(Strang, 2006, exercise 2 from section 6.1.)

(L-18) QUESTION 2. What is the quadratic $f=ax^2+2bxy+cy^2$ for each of these matrices? Complete the square to write f as a sum of one or two squares $d_1(-)^2+d_2(-)^2$.

- (a) $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$
- (b) $\mathbf{B} = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$

(Strang, 2006, exercise 15 from section 6.1.)

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(L-18) QUESTION 6. Consider the following quadratic forms

$$q_1(x, y, z) = x^2 + 4y^2 + 5z^2 - 4xy.$$

$$q_2(x, y, z) = -x^2 + 4y^2 + z^2 + 2xy - 2axz.$$

- (a) Show that $q_1(x, y, z)$ is positive semi-definite.
- (b) Find, if it is possible, any value of a such as $q_2(x,y,z)$ is negative definite.

(L-18) QUESTION 7. Decide for or against the positive definiteness of

(a)
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & 1 \\ -1 & 1 & 2 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{bmatrix}^2$$

(Strang, 2006, exercise 2 from section 6.2.)

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(L-18) QUESTION 3. Which one of the following matrices has two positive eigenvalues? Test a>0 and $ac>b^2$, don't compute the eigenvalues. $x\mathbf{A}x<0$.

(a)
$$\mathbf{A} = \begin{bmatrix} 5 & 6 \\ 6 & 7 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} -1 & -2 \\ -2 & -5 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 1 & 10 \\ 10 & 100 \end{bmatrix}$$

(d)
$$\mathbf{D} = \begin{bmatrix} 1 & 10 \\ 10 & 101 \end{bmatrix}$$

(Strang, 2006, exercise 14 from section 6.1.)

(L-18) QUESTION 4. Show that $f(x,y)=x^2+4xy+3y^2$ does not have a minimum at (0,0) even though it has positive coefficients. Write f(x,y) as a difference of squares and find a point (x,y) where f(x,y) is negative. (Strang, 2006, exercise 16 from section 6.1.)

(L-18) QUESTION 5. Show from the eigenvalues that if $\bf A$ is positive definite, so is $\bf A^2$ and so is $\bf A^{-1}$.

(Strang, 2006, exercise 4 from section 6.2.)

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(L-18) QUESTION 8. Consider the following quadratic form

$$q(x, y, z) = x^2 + 6xy + y^2 + az^2;$$

Decide for which values a the quadratic form is positive definite, negative definite, semidefinite, or indefinite.

(L-18) QUESTION 9. Si ${\bf A}=\left[\begin{smallmatrix} a & b \\ b & d \end{smallmatrix} \right]$ es definida positiva, pruebe que ${\bf A}^{-1}$ es definida positiva.

(Strang, 2006, exercise 8 from section 6.1.)

(L-18) QUESTION 10. Si una matriz simétrica de 2 por 2 satisface a>0, y $ac>b^2$, demuestre que sus autovalores son reales y positivos (definida positiva). Emplee la ecuación característica y el hecho de que el producto de los autovalores es igual al determinante.

(Strang, 2006, exercise 3 from section 6.1.)

(L-18) QUESTION 11. Decida si las siguientes matrices son definidas positivas, definidas negativas, semi-definidas, o indefinidas.

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 4 \\ 3 & 4 & 9 \end{bmatrix}$$

(b) $\mathbf{B} = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 6 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 3 \end{bmatrix}$
(c) $\mathbf{C} = -\mathbf{B}$
(d) $\mathbf{D} = \mathbf{A}^{-1}$

(L-18) QUESTION 12. Una matriz definida positiva no puede tener un cero (o incluso peor; un número negativo) en su diagonal principal. Demuestre que esta matriz no cumple $x\mathbf{A}x>0$, para todo $x\neq 0$:

$$\begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{bmatrix} 4 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 2 & 5 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad \text{no es positiva cuando} \quad \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} = \begin{pmatrix} & & & \\ & & & \\ & & & \end{pmatrix}$$

(Strang, 2006, exercise 21 from section 6.2.)

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(L-18) QUESTION 16. Consider the following matrices

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & a & 0 \\ 0 & 0 & a & a \end{bmatrix} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

- (a) (0.5^{pts}) Compute the eigenvalues of **A**.
- (b) (0.5^{pts}) Prove that when a=2 the matrix **A** is not diagonalisable.
- (c) (1^{pts}) For matrix B, find a diagonal matrix D and an orthonormal matrix P such as $B = PDP^{T}$.
- (d) $(0.5^{\rm pts})$ Find the quadratic form f(x,y,z) associated to **B**, and prove it is positive defined.

(L-18) QUESTION 17. Given the matrix $\mathbf{A} = \begin{pmatrix} a & 3/5 \\ b & 4/5 \end{pmatrix}$, compute the values (if they exist) of a and b such as

- (a) (0.5^{pts}) **A** is ortho-normal.
- (b) (0.5^{pts}) Columns of **A** are linearly independent.
- (c) (0.5^{pts}) $\lambda = 0$ is an eigenvalue of **A**.
- (d) (0.5^{pts}) **A** is a symmetric definite negative matrix.

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(L-18) QUESTION 13. Demuestre que si $\bf A$ y $\bf B$ son definidas positivas entonces $\bf A+\bf B$ también es definida positiva. Para esta demostración los pivotes y los valores característicos no son convenientes. Es mejor emplear $\bf x(\bf A+\bf B)x>0$ (Strang, 2006, exercise 5 from section 6.2.)

(L-18) QUESTION 14. Find the $\dot{\textbf{L}}\textbf{D}\dot{\textbf{L}}^{\intercal}$ factorization for the following symmetric matrices.

(a)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix}$$

(b)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 3 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

(L-18) QUESTION 15. La forma cuadrática $f(x,y) = 3(x+2y)^2 + 4y^2$ es definida positiva. Encuentre la matriz **A**, factorícela en **LDL**^T, y relacione los elementos en **D** y **L** con 3, 2 y 4 en f. (Strang, 2006, exercise 9 from section 6.1.)

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(L-18) Question 18.

- (a) Consider the quadratic form $q(x,y,z)=x^2+2xy+ay^2+8z^2$ and find its corresponding symmetric matrix \mathbf{Q} ; determine if \mathbf{Q} is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite when the parameter a is equal to one (a=1).
- (b) If $a \neq 1$, determine whether the matrix is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite.

Questions of the Optional Lecture 2

(L-OPT-2) QUESTION 1. Consider the following matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & a & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

- (a) (0.5^{pts}) Prove **A** is invertible if and only if $a \neq 0$.
- (b) (0.5^{pts}) Is **A** positive definite when a=1? Explain your answer.
- (c) (1^{pts}) Compute \mathbf{A}^{-1} when a=2.
- (d) (0.5^{pts}) How many variables can be chosen as pivot (or exogenous) variables in the system $\mathbf{A}x = \mathbf{o}$ when a = 0? Which ones?

(L-OPT-2) QUESTION 2. True or false (to receive full credit you must explain your answers in a clear and concise way)

- (a) If \mathbf{A} is symmetric, then so it is \mathbf{A}^2 .
- (b) If $\mathbf{A}^2 = \mathbf{A}$ then $(\mathbf{I} \mathbf{A})^2 = (\mathbf{I} \mathbf{A})$ where \mathbf{I} is the identity matrix.
- (c) If $\lambda=0$ is an eigenvalue of the squared matrix **A**, then the linear system $\mathbf{A}x=\mathbf{0}$ is is always solvable and has only one solution.
- (d) If $\lambda=0$ is an eigenvalue of the squared matrix ${\bf A}$, then the linear system ${\bf A} x=b$ could be unsolvable.
- (e) If a matrix is orthogonal (perpendicular columns of norm one), then so it is the inverse of that matrix.

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(L-OPT-2) QUESTION 4. En las preguntas siguientes $\bf A$ y $\bf B$ son matrices $n \times n$. Indique si las siguientes afirmaciones son verdaderas o falsas (incluya una breve explicación, o un contra ejemplo que justifique su respuesta):

- (a) Si A no es cero entonces $det(A) \neq 0$
- (b) Si $det(AB) \neq 0$ entonces A es invertible.
- (c) Si intercambio las dos primeras filas de A sus autovalores cambian.
- (d) Si A es real y simétrica, entonces sus autovalores son reales (aquí no es necesaria una justificación).
- (e) Si la forma reducida de echelon de $({\bf A}-5{\bf I})$ es la matriz identidad, entonces 5 no es un autovalor de ${\bf A}$.
- (f) Sea ${m b}$ un vector columna de ${\mathbb R}^n.$ Si el sistema ${f A}{m x}={m b}$ no tiene solución, entonces $\det({f A})
 eq 0$
- (g) Sea C de orden 3×5 . El rango de C puede ser 4.
- (h) Sea C de orden $n \times m$, y b un vector columna de \mathbb{R}^n . Si $\mathbf{C} x = b$ no tiene solución, entonces $\operatorname{rg}(\mathbf{C}) < n$.
- (i) Toda matriz diagonalizable es invertible.
- (j) Si A es invertible, entonces su forma reducida de echelon es la matriz identidad.

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(f) If 1 is the only eigenvalue of a 2×2 matrix ${\bf A}$, then ${\bf A}$ must be the identity matrix ${\bf I}$.

(L-OPT-2) QUESTION 3. complete los blancos, o responda Verdadero/Falso.

- (a) Cualquier sistema generador de un espacio vectorial contiene una base del espacio (V/F)
- (b) Que los vectores v_1, v_2, \ldots, v_n sean linealmente independientes significa que
- (c) El conjunto que sólo contiene el vector ${\bf 0}$ es un conjunto linealmente independiente. (V/F)
- (d) Una matriz cuadrada de orden n por n es diagonalizable cuando:

(e) Si
$$u = (1, 2, -1, 1)$$
, entonces $||u|| =$ ______

(f) Si
$$u = (1, 2, -1, 1)$$
 y $v = (-2, 1, 0, 0)$, entonces $u \cdot v =$

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(L-OPT-2) QUESTION 5. Sean

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 4 \\ 0 & 0 & 5 \end{bmatrix}; \quad \mathbf{B} = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}; \quad \mathbf{C} = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 0 & 4 \\ 0 & 0 & 6 \end{bmatrix}; \quad \mathbf{D} = \begin{bmatrix} 2 & 3 & 0 \\ 3 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Los autovalores de ${\bf B}$ son 0 y 2. Use esta información para responder a las siguientes cuestiones. Para cada matriz debe dar una explicación. Puede haber más de una matriz que cumpla la condición:

- (a) ¿ Qué matrices son invertibles?
- (b) ¿Qué matrices tienen un autovalor repetido?
- (c) ¿Qué matrices tienen rango menor a tres?
- (d) ¿ Qué matrices son diagonalizables?
- (e) ¿Para qué matrices diagonalizables podemos encontrar tres autovectores ortogonales entre si?

(L-OPT-2) QUESTION 6. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix}$$

- (a) Find the eigenvalues and eigenvectors of A.
- (b) Is A diagonalizable?

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- (c) Is it possible to find a matrix P such as $A = PDP^{T}$, where D is diagonal?
- (d) Find $|{\bf A}^{-1}|$.

(L-OPT-2) QUESTION 7. Consider a 3 by 3 matrix **A** with eigenvalues $\lambda_1=1$, $\lambda_2=2$, and $\lambda_3=-1$; and let $\boldsymbol{v}_1=(1,0,1)^{\mathsf{T}}$ and $\boldsymbol{v}_2=(1,1,1)^{\mathsf{T}}$ be the corresponding eigenvectors to λ_1 and λ_2 .

- (a) Is A diagonalizable?
- (b) Is $v_3 = (-1, 0, -1)^{\mathsf{T}}$ an eigenvector associated to the eigenvalue $\lambda_3 = -1$?
- (c) Compute $\mathbf{A}(v_1-v_2)$.

(L-Opt-2) Question 8.

(a) $(0.5^{\rm pts})$ Find an homogeneous system $\mathbf{A}x=\mathbf{0}$ such as its solutions set is

$$\left\{ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} \in \mathbb{R}^4 \ \middle| \ \exists \alpha, \beta, \gamma \in \mathbb{R} \quad \text{such that} \ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \beta \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \gamma \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}. \right\}$$

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(b) $(0.5^{\rm pts})$ If the characteristic polynomial of a matrix **A** is $p(\lambda) = \lambda^5 + 3\lambda^4 - 24\lambda^3 + 28\lambda^2 - 3\lambda + 10$, find the rank of **A**.

(L-OPT-2) QUESTION 9. Suponga una matriz cuadrada e invertible A.

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- (a) ¿Cuáles son sus espacios columna $\mathcal{C}(\mathbf{A})$ y espacio nulo $\mathcal{N}(\mathbf{A})$? (no responda con la definición, diga qué conjunto de vectores compone cada espacio).
- (b) Suponga que A puede ser factorizada en A = LU:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 7 & 3 & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{12} & u_{13} \\ 0 & 0 & u_{13} \end{bmatrix}$$

Describa el primer paso de eliminación en la reducción de A a U. ¿porqué sabe que U es también una matriz invertible? ¿Cuanto vale el determinante de A?

- (c) Encuentre una matriz particular de dimensiones 3×3 e invertible **A** que no pueda ser factorizada en la forma **LU** (sin permutar previamente las filas). ¿Qué factorización es todavía posible en su ejemplo? (no es necesario que realice la factorización). ¿Cómo sabe que su matriz **A** es invertible?
- Strang, G. (2003). *Introduction to Linear Algebra*. Wellesley-Cambridge Press, Wellesley, Massachusetts. USA, third ed. ISBN 0-9614088-9-8.
- Strang, G. (2006). *Linear algebra and its applications*. Thomson Learning, Inc., fourth ed. ISBN 0-03-010567-6.