Mathematics II

Marcos Bujosa

Universidad Complutense de Madrid

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1 Highlights of Lesson 16

Always squared matrices in this topic

Highlights of Lesson 16

- **Eigenvalues, eigenvectors** (prefix eigen is the German word for innate, distinct, self)
- $\bullet \ |\mathbf{A} \lambda \mathbf{I}| = 0$

Characteristic equation

• tr (**A**), det **A**

(demo in the next lesson)

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You can find the last version of these course materials at

https://github.com/mbujosab/MatematicasII/tree/main/Eng

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2 Eigenvalues and eigenvectors

Consider the equation

$$\mathbf{A} \mathbf{x} = \lambda \mathbf{x}$$
 (with $\mathbf{x} \neq \mathbf{0}$)

- *Eigenvalue* is any λ such that there are solutions.
- Such non-null solutions x are called eigenvectors. $x \neq 0$ such that $\mathbf{A}x$ is multiple x

When λ is 0, What are the eigenvectors?

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- **3** Example: projection matrix
- Orthogonal projection
- Which vectors are eigenvectors?
 What vectors are projected in the same starting direction?
- What are the eigenvalues of those eigenvectors?
- are there any other eigenvectors? with what eigenvalue?
- Two eigen-spaces

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5 how to find eigenvalues and eigenvectors?

How to solve

$$\mathbf{A}x = \widehat{\lambda} \stackrel{?}{\underbrace{x}} ?$$

Here's the trick (simple idea). Bring the x s onto the same side . . .

$$(\mathbf{A} - \lambda \mathbf{I}) \boldsymbol{x} =$$

idea If $x \neq 0$ what kind of matrix must be $(\mathbf{A} - \lambda \mathbf{I})$?

and then its determinant must be? $|\mathbf{A} - \lambda \mathbf{I}| =$

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4 Another example: Interchange or swap matrix

$$\mathbf{A} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- A vector that does not change after interchange?
- What is the eigenvalue?
- Is there an eigenvector corresponding to $\lambda_2 = -1$?

$$\mathbf{A}\boldsymbol{x}_2 = -\boldsymbol{x}_2$$

Note: $\operatorname{tr}(\mathbf{A}) = 0 = \lambda_1 + \lambda_2$; $\det \mathbf{A} = -1 = \lambda_1 \cdot \lambda_2$.

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. . . .

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- **6** how to find eigenvalues and eigenvectors?
- 1. Eigenvalues are λ 's such that: $|\mathbf{A} \lambda \mathbf{I}| =$ (Characteristic polynomial $P_{\mathbf{A}}(\lambda)$)
- 2. How to compute x so that $(\mathbf{A} \lambda \mathbf{I}) x = \mathbf{0}$?

Eigenspace (Set of eigenvectors + 0):

$${\cal E}_{\lambda}({f A}) = \left\{ \left. {m x} \in \mathbb{R}^n
ight| {f A} {m x} = \lambda {m x}
ight\}$$

Spectrum: set $\{\lambda_1, \dots \lambda_k\}$ of eigenvalues (roots of $P_{\mathbf{A}}(\lambda)$)

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For $\lambda_1 = 4$

For $\lambda_2 = 2$

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 $(\mathbf{A} - 4\mathbf{I}) = \begin{bmatrix} 3 - 4 & 1 \\ 1 & 3 - 4 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \Rightarrow$

 $(\mathbf{A} - 2\mathbf{I}) = \begin{bmatrix} 3 - 2 & 1 \\ 1 & 3 - 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow$

Are they the only two eigenvectors?

8 Example (...and then the eigenspaces)

And now we compute the null space $\mathcal{N}(\mathbf{A} - \lambda \mathbf{I})$... for each λ .

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7 Example (we must compute the eigevalues first!)

We are looking for a null determinant (Characteristic polynomial)

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}; \qquad \det(\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 1 & 3 - \lambda \end{vmatrix} = (3 - \lambda)^2 - 1 = 0$$

Note:
$$\operatorname{tr}(\mathbf{A}) = 6 = \lambda_1 + \lambda_2$$
; $\det \mathbf{A} = 8 = \lambda_1 \cdot \lambda_2$.

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 $\mathbf{A}oldsymbol{x}_i = \lambda oldsymbol{x}_i; \qquad egin{bmatrix} 3 & 1 \ 1 & 3 \end{bmatrix} oldsymbol{x}_i = \lambda oldsymbol{x}_i.$

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10 There are even worse examples

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

Eigenvalues

$$\det (\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 0 & 3 - \lambda \end{vmatrix} = (3 - \lambda)(3 - \lambda) = 0 \begin{cases} \lambda_1 = 3 \\ \lambda_2 = 3 \end{cases}$$

- Eigenvectors
 - for λ_1 : $(\mathbf{A} \lambda \mathbf{I}) \boldsymbol{x} = \mathbf{0} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \boldsymbol{x}_1; \qquad \boldsymbol{x}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
 - for λ_2 :

 $\lambda = 3$ is repeated twice, but $\dim \mathcal{E}_3(\mathbf{A}) = 1$

$$\mu(3)=2\ \neq\ 1=\gamma(3)$$

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9 Another example: 90° rotation matrix

$$\mathbf{Q} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

- How much do the eigenvalues add up to?
- What is the determinant?

Difficulties

$$\lambda_1 + \lambda_2 = 0$$
 and $\lambda_1 \cdot \lambda_2 = 1$ $(+)$

What kind of vector can be parallel to itself after a 90° rotation?

$$\det (\mathbf{Q} - \lambda \mathbf{I}) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 =$$

Summary:

- 1. The eigenvalues are those numbers λ that makes the matrix $(\mathbf{A} \lambda \mathbf{I})$ singular. In other words, they are the roots of the Characteristic polynomial: $\det(\mathbf{A} \lambda \mathbf{I})$.
- 2. Any n by n matrix has a caracteristic polynomial of degree n
- 3. A polynomial of degree n has n roots (perhaps some repeated roots).
- 4. The sum of eigenvalues of a matrix equals its trace
- 5. The product of eigenvalues of a matrix equals its determinant
- 6. The eigenvectors associated with λ are the non-zero vectors in $\mathcal{N}(\mathbf{A} \lambda \mathbf{I})$.

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(b)

$$\mathbf{B} = \begin{bmatrix} a & b \\ b & a \end{bmatrix}$$

(Strang, 2006, exercise 12 from section 5.1.)

(L-16) QUESTION 3. If B has eigenvalues 1, 2, 3, C has eigenvalues 4, 5, 6, and D has eigenvalues 7, 8, 9, what are the eigenvalues of the 6 by 6 matrix $\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{0} & \mathbf{D} \end{bmatrix}$? where B, C, D are upper triangular matrices. (Strang, 2006, exercise 13 from section 5.1.)

 $\left(L\text{-}16\right)$ QUESTION 4. Find the eigenvalues and eigenvectors of

(a)

$$\mathbf{A} = \begin{bmatrix} 3 & 4 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

(b)

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 2 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

(Strang, 2006, exercise 5 from section 5.1.)

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Questions of the Lecture 16

(L-16) QUESTION 1. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} -3 & 4 & -4 \\ -3 & 5 & -3 \\ -1 & 2 & 0 \end{bmatrix}$$

(a) The three eigenvalues of $\bf A$ are -1, 1 and 2; and two of its eigenvectors are

Check that both vectors are eigenvenctors of **A**. What are the corresponding eigenvalues?

(b) Find a third linearly independent eigenvector.

(L-16) QUESTION 2. Find the eigenvalues and eigenvectors of

(a)

$$\mathbf{A} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

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(L-16) QUESTION 5. The eigenvalues of **A** equal the eigenvalues of **A**^T. This is because $\det(\mathbf{A} - \lambda \mathbf{I})$ equals $\det(\mathbf{A}^T - \lambda \mathbf{I})$.

- (a) That is true because
- (b) Show by an example $\overline{\text{that, nevertheless, the eigenvectors of } \mathbf{A}$ and \mathbf{A}^{T} are not the

(Strang, 2006, exercise 11 from section 5.1.)

(L-16) QUESTION 6. Consider the matrix **B** and its eigenvector \boldsymbol{x} associated to the eigenvalue λ , that is $\mathbf{B}\boldsymbol{x}=\lambda\boldsymbol{x}$; and also consider the matrix $\mathbf{A}=(\mathbf{B}+\alpha\mathbf{I})$. Prove that \boldsymbol{x} is also an eigenvector of \mathbf{A} with eigenvalue $(\lambda+\alpha)$.

(L-16) Question 7.

- (a) Encuentre los autovalores y los auto-vectores de la matriz $\mathbf{A} = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$ Compruebe que la traza es igual a la suma de los autovalores, y que el determinante es igual a su producto.
- (b) Si consideramos una nueva matriz, generada a partir de la anterior como

$$\mathbf{B} = (\mathbf{A} - 7\mathbf{I}) = \begin{bmatrix} -6 & -1 \\ 2 & -3 \end{bmatrix}.$$

¿Cuáles son los autovalores y auto-vectores de la nueva matriz, y como están relacionados con los de A?

(Strang, 2006, exercise 1 and 3 from section 5.1.)

(L-16) QUESTION 8. Suponga que λ es un auto-valor de $\bf A$, y que $\bf x$ es un auto-vector tal que $\bf A x = \lambda x$.

- (a) Demuestre que ese mismo x es un auto-vector de $\mathbf{B} = \mathbf{A} 7\mathbf{I}$, y encuentre el correspondiente auto-valor de \mathbf{B} .
- (b) Suponga que $\lambda \neq 0$ (y que **A** es invertible), demuestre que x también es un auto-vector de \mathbf{A}^{-1} , y encuentre el correspondiente auto-valor. ¿Qué relación tiene con λ ?

(Strang, 2006, exercise 7 from section 5.1.)

(L-16) QUESTION 9. Suponga que $\bf A$ es una matriz de dimensiones $n \times n$, y que $\bf A^2 = \bf A$. ¿Qué posibles valores pueden tomar los autovalores de $\bf A$?

(L-16) QUESTION 10. Suponga la matriz \mathbf{A} con autovalores 1, 2 y 3. Si \boldsymbol{v}_1 es un auto-vector asociado al auto-valor 1, \boldsymbol{v}_2 al auto-valor 2 y \boldsymbol{v}_3 al auto-valor 3; entonces ¿cuanto es $\mathbf{A}(\boldsymbol{v}_1+\boldsymbol{v}_2-\boldsymbol{v}_3)$?

(L-16) QUESTION 11. Proporcione un ejemplo que muestre que los auto-valores pueden cambiar cuando un múltiplo de una columna se resta de otra. ¿Por qué los pasos de eliminación no modifican los autovalores nulos? (Strang, 2006, exercise 6 from section 5.1.)

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(L-16) QUESTION 15. The equation $(\mathbf{A}^2 - 4\mathbf{I})x = b$ has no solution for some right-hand side b. Give as much information as possible about the eigenvalues of the matrix \mathbf{A} (the matrix \mathbf{A} is diagonalizable).

(L-16) QUESTION 16. You are given the matrix

$$\mathbf{A} = \begin{bmatrix} 0.5 & 0.2 & 0.2 \\ 0.1 & 0.5 & 0.5 \\ 0.4 & 0.3 & 0.3 \end{bmatrix}$$

One of the eigenvalues is $\lambda=1$. What are the eigenvalues of **A**? [Hint: Very little calculation required! You should be able to see another eigenvalue by inspection of the form of **A**, and the third by an easy calculation. You shouldn't need to compute $\det(\mathbf{A}-\lambda\mathbf{I})$ unless you really want to do it the hard way.]

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(L-16) QUESTION 12. El polinomio característico de una matriz ${\bf A}$ se puede factorizar como

$$\det(\mathbf{A} - \lambda \mathbf{I}) = (\lambda_1 - \lambda)(\lambda_2 - \lambda) \cdots (\lambda_n - \lambda).$$

Demuestre, partiendo de esta factorización, que el determinante de ${\bf A}$ es igual al producto de sus valores propios (autovalores). Para ello haga una elección inteligente del valor de λ .

(Strang, 2006, exercise 8 from section 5.1.)

(L-16) QUESTION 13. Calcule los valores característicos (autovalores o valores propios) y los vectores característicos de $\bf A$ y $\bf A^2$:

$$\mathbf{A} = \begin{bmatrix} -1 & 3 \\ 2 & 0 \end{bmatrix} \qquad \mathbf{y} \qquad \mathbf{A}^2 = \begin{bmatrix} 7 & -3 \\ -2 & 6 \end{bmatrix}$$

 ${\bf A}^2$ tiene los mismos _____ que ${\bf A}$. Cuando los autovalores de ${\bf A}$ son λ_1 y λ_2 , los autovalores de ${\bf A}^2$ son ____. (Strang, 2006, exercise 22 from section 5.1.)

(L-16) QUESTION 14. Suponga que los valores característicos de ${\bf A}$ son 1, 2 y 4, ¿cuál es la traza de ${\bf A}^2$? ¿Cuál es el determinante de $({\bf A}^{-1})^{\sf T}$? (Strang, 2006, exercise 10 from section 5.2.)

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1 Highlights of Lesson 17

Highlights of Lesson 17

- Similar matrices: $\mathbf{C} = \mathbf{S}^{-1}\mathbf{A}\mathbf{S}$
- Triangular block diagonalizing a matrix

• Diagonalizable matrices: when **C** is diagonal.

2 Similar matrices

Similarity

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A and C are similar if there is an invertible S such that

$$C = S^{-1}AS$$

If **A** and **C** are similar (see demos in the book):

- The same determinant: $\det \mathbf{A} = \det \mathbf{C}$
- The same caracteristic polinomial: $|\mathbf{A} \lambda \mathbf{I}| = |\mathbf{C} \lambda \mathbf{I}|$
- The same eigenvalues (same *algebraic* and *geometric* multiplicities).
- The same trace.

$$\textit{Mirror} \text{ inverse transf.: } \left(\mathbf{I}_{(\tau_1\cdots\tau_k)}\right)^{-1} \ = \ _{esp(\tau_k^{-1}\cdots\tau_1^{-1})}\mathbf{I}$$

$$\mathbf{I} = \underset{[(-\alpha)\mathbf{j} + \mathbf{i}]}{\mathbf{T}} = \underset{[(\alpha)\mathbf{i} + \mathbf{j}]}{\mathbf{T}} = \underset{[(\alpha)\mathbf{j}]}{\mathbf{T}} \xrightarrow{\mathbf{T}} \qquad \Rightarrow \qquad \mathbf{A} \text{ similar to } \underset{esp(\boldsymbol{\tau}_1 \cdots \boldsymbol{\tau}_k)^{-1}}{\mathbf{A}_{\tau_1 \cdots \tau_k}}$$

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4 Block diagonalizing a matrix (toothed matrix)

Consider
$$\mathbf{A} = \left[\begin{array}{c|c} \mathbf{C} & \parallel \\ \hline * & \parallel \mathbf{L} \end{array} \right] \in \mathbb{C}^{n \times n}$$
 where

C (of order m) is singular and **L** is full rank lower triangular, then there exists S = RP (invertible) such that

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3 Block diagonalizing a matrix (toothed matrix)

Consider
$$\mathbf{A} = \left[\begin{array}{c|c} \mathbf{C} & \\ \hline * & \mathbf{L} \end{array} \right] \in \mathbb{C}^{n \times n}$$
 where

 ${\bf C}$ (of order m) is singular and ${\bf L}$ is full rank lower triangular; then there exists an invertible ${\bf R}$ such that

$$\mathbf{R}^{-1}\mathbf{A}\mathbf{R} = \begin{bmatrix} & & 0 & & & & \\ & \star & & \vdots & & & \\ & & \mathbf{m} \times (m-1) & 0 & & & & \\ & & & d_{m+1} & \beta_{m+1} & & \\ & & & d_{m+2} & * & \beta_{m+2} & & \\ & & \vdots & * & * & \ddots & \\ & & d_n & * & * & \cdots & \beta_n \end{bmatrix}$$

$$\left(\dots \begin{array}{c} & & & & \\ & & & \\ & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & &$$

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5 A very simple example

Example

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Consider
$$\mathbf{A}=\begin{bmatrix}1 & -1 & 0\\ 0 & 0 & 0\\ 0 & -2 & 1\end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{\begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \end{subarray}} \underbrace{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\begin{subarray}{c} [(1)1+2] \\ [(2)3+2] \\ [(2)3+2] \\ [(2)3+2] \\ [(2)3+2] \\ [(3)1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{subarray}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \\ \mathbf{I} \end{subarray}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \\ \mathbf{I} \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \end{subarray}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{subarray}}_{\begin{subarray}{c} \mathbf{I} \\ \mathbf{I} \end{subarray}}_{\begin{subarray}{c} \mathbf$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{\text{diagonal}}$$

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6 A not so simple example

Example

Consider
$$\mathbf{A} = \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix}$$
 with eigenvalues $\mathbf{1}$, $\mathbf{1}$ and $\mathbf{0}$.

$$\begin{array}{c} (-) \\ \hline 11 \\ \hline \end{array} \end{array} \overbrace{ \begin{array}{c} -3 \\ 3 \\ -3 \\ -3 \\ -2 \\ \hline \end{array} } \xrightarrow{0} \xrightarrow{0} \\ \hline \begin{array}{c} -3 \\ 3 \\ -3 \\ -3 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ -1 \\ 2 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} \underbrace{ \begin{array}{c} -3 \\ 3 \\ -3 \\ -3 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 3 \\ -3 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 3 \\ -3 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 3 \\ -3 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 3 \\ -3 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -3 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -2 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \hline \end{array} = 0 \\ \end{array} = 0 \\ \hline \begin{array}{c} -1 \\ 0 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \end{array} = 0 \\ \begin{array}{c} -1 \\ 0 \\ \end{array} = 0 \\ =$$

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8 Back to the simple, "toothless" example

Consider
$$\mathbf{A} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{ \begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\mathbf{0} \mathbf{I}} \overset{(-)}{\underset{\mathbf{0}}{\mathbf{0}}} \underbrace{ \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ [(-2)2+3] \\ ([-1)2+1] \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 1 & 0 & 1 \\ 0 & 0 & 1 \\ \hline 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 1 & 0 & 1 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline 0 & 0 & 1 \\ \hline 0 & 1 & 2 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \end{bmatrix}}_{\mathbf{0}} \underbrace{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\mathbf{A}(\mathbf{S}_{|i}) = \lambda_i(\mathbf{S}_{|i}) \quad \Rightarrow \quad \mathbf{S}_{|i}$$
 is an eigenvector.

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7 Every matrix is similar to a toothed matrix

For every **A** there exists **S** such that

$$S^{-1}AS = C$$
 \Rightarrow $AS = SC$

where **C**, toothed, has the eigenvalues on the diagonal **Example**

$$\begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix} \begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix}}_{\text{toothed}}$$
Consequences

• $\sum \lambda_i = \operatorname{tr} \left(\mathbf{A}
ight)$ and $\prod \lambda_i = \det \mathbf{A}$

 $\bullet \quad \mathbf{AS}_{|j} = \mathbf{SC}_{|j} \qquad \Rightarrow \qquad \text{for j such that } \mathbf{C}_{|j} = \lambda_i \mathbf{I}_{|j} :$

$$\mathbf{A}(\mathbf{S}_{|j}) = \lambda_i(\mathbf{S}_{|j}) \quad \Rightarrow \quad \mathbf{S}_{|j} \text{ is an eigenvector.}$$

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9 Diagonalizable matrices

- A matrix is diagonalizable **if and only if** *algebraic* and *geometric* multiplicities are equal for each eigenvalue
- If there are no repeated eigenvalues, there are no "teeth" either
- When there are no repeated eigenvalues \mathbf{A} is diagonalizable (is sure to have n independent eigenvectors)

10 Diagonalizing a matrix

- Find the spectrum: $\{\lambda_1, \lambda_2, \ldots\}$
- Find the algebraic multiplicity of each eigenvalue: $\mu(\lambda_i)$

then choose one of these alternatives:

- 1. teething the matrix (implemented in NAcAL)
- 2. ... or for every λ_i
 - find the eigenspace

$${\mathcal E}_{\lambda_i}({\mathbf A}) = \left\{ \left. {f x} \in {\mathbb R}^n \right| {\mathbf A} {f x} = \lambda_i {f x}
ight\} \ = \ {\mathcal N}({\mathbf A} - \lambda_i {\mathbf I}).$$

ullet check $\mu(\lambda_i)=\dim {\mathcal E}_{\lambda_i}({f A})$ (algebraic and geometric multiplicities are equal)

$$\mathbf{D} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_k \end{bmatrix}; \quad \mathbf{S} = \begin{bmatrix} \mathsf{Basis for } \, \mathcal{E}_{\lambda_1}(\mathbf{A}) \# \cdots \# \mathsf{Basis for } \, \mathcal{E}_{\lambda_k}(\mathbf{A}) \end{bmatrix}$$

$$S^{-1}AS = D \Leftrightarrow A = SDS^{-1}$$

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Questions of the Lecture 17

(L-17) QUESTION 1. Factor these two matrices into SDS⁻¹;

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

(Strang, 2006, exercise 15 from section 5.2.)

(L-17) QUESTION 2. Which of these matrices cannot be diagonalized?

(a)

$$\mathbf{A}_1 = \begin{bmatrix} 2 & -2 \\ 2 & -2 \end{bmatrix}$$

(b)

$$\mathbf{A}_2 = \begin{bmatrix} 2 & 0 \\ 2 & -2 \end{bmatrix}$$

(c)

$$\mathbf{A}_3 = \begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix}$$

(Strang, 2006, exercise 5 from section 5.2.)

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11 Matrix powers

If $\mathbf{A}x = \lambda x$ then $\mathbf{A}^2 x = \mathbf{A} \mathbf{A} x = \mathbf{A}(\lambda x) = \lambda \mathbf{A} x = \mathbf{A}(\lambda x)$

- What can I say about the eigenvectors?
- What is the relationship between the eigenvalues of ${\bf A}$ and those of ${\bf A}^2$

In a matrix form (if **A** is diagonalizable, $\mathbf{A} = \mathbf{SDS}^{-1}$):

$$A^2 = SDS^{-1}SDS^{-1} = SD^2S^{-1}$$

In general, for, $n \in \mathbb{Z}$, $n \ge 0...$ $\mathbf{A}^n =$ what about \mathbf{A} both diagonalizable and invertible?

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(L-17) QUESTION 3. If $\mathbf{A} = \begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$ find \mathbf{A}^{100} by diagonalizing \mathbf{A} .

(Strang, 2006, exercise 7 from section 5.2.)

(L-17) QUESTION 4. If the eigenvalues of $\mathbf{A}_{3\times3}$ are 1, 1 and 2, which of the following are certain to be true? Give a reason if true or a counterexample if false:

- (a) A is invertible.
- (b) A is diagonalizable.
- (c) A is not diagonalizable

(Strang. 2006, exercise 11 from section 5.2.)

(L-17) QUESTION 5. Let **A** be the matrix

$$\mathbf{A} = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 1 & 0 & 0 & 2 \end{bmatrix}$$

- (a) (1^{pts}) Determine if **A** is diagonalizable, and if so, diagonalize it.
- (b) (0.5^{pts}) Compute $(\mathbf{A}^6)\mathbf{v}$, where $\mathbf{v} = (0, 0, 0, 1)$.
- (c) (0.5^{pts}) Using the the eigenvalues found in part (a) justify that **A** is invertible.
- (d) (0.5^{pts}) What is the relation between the eigenvalues of A and the eigenvalues of A⁻¹?

(L-17) QUESTION 6. Si
$$A = SDS^{-1}$$
; entonces $A^3 = ($)()() $A^{-1} = ($)()(). (Strang, 2006, exercise 16 from section 5.2.)

(L-17) QUESTION 7. Considere la matriz

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$$

- (a) Encuentre los autovalores de A
- (b) Encuentre los auto-vectores de A
- (c) Diagonalice **A**: escríbalo como $\mathbf{A} = \mathbf{SDS}^{-1}$.

(L-17) QUESTION 8. ¿Falso o verdadero? Si los autovalores de ${\bf A}$ son 2, 2 y 3 entonces sabemos que la matriz es

- (a) Invertible
- (b) Diagonalizable
- (c) No diagonalizable.

(L-17) QUESTION 9. Sean las matrices

$$\mathbf{A}_1 = \begin{bmatrix} 8 & \\ & 2 \end{bmatrix}; \qquad \mathbf{A}_2 = \begin{bmatrix} 9 & 4 \\ & 1 \end{bmatrix}; \qquad \mathbf{A}_3 = \begin{bmatrix} 10 & 5 \\ -5 & \end{bmatrix}$$

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- (a) Encuentre los autovalores y auto-vectores de la matriz $\mathbf{A}=\begin{bmatrix}1&0&0\\-2&1&0\\1&0&1\end{bmatrix}$.
- (b) Explique por qué (o por qué no) la matriz A es diagonalizable.

(L-17) QUESTION 14. Sea **A** una matriz 3×3 . Asuma que sus autovalores son 1 y 0, que una base de los autovectores asociados a $\lambda=1$ son [1,0,1] y [0,0,1]; mientras que los asociados a $\lambda=0$ son paralelos a [1,1,2].

- (a) ¿Es A diagonalizable? En caso afirmativo escriba la matriz diagonal $\bf D$ y la matriz $\bf S$ tales que $\bf A = \bf S \bf D \bf S^{-1}$.
- (b) Encuentre A.

(L-17) QUESTION 15. Let $\bf A$ be a 2×2 matrix such that $\begin{pmatrix} 2\\0 \end{pmatrix}$ is an eigenvector for $\bf A$ with eigenvalue 2, and $\begin{pmatrix} 2\\-1 \end{pmatrix}$ is another eigenvector for $\bf A$ with eigenvalue -2. If ${\bf v}=\begin{pmatrix} 1\\-1 \end{pmatrix}$, compute $\begin{pmatrix} {\bf A}^3 \end{pmatrix} {\bf v}$.

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 - (a) Complete dichas matrices de modo que en los tres casos $\det {\bf A}_i=25$. Así, la traza es en todos los casos igual a 10, y por tanto para las tres matrices el único auto-valor $\lambda=5$ está repetido dos veces ($\lambda^2=25$ y $\lambda+\lambda=10$ implica $\lambda=5$).
 - (b) Encuentre un vector característico con $\mathbf{A}x=5x$. Estas tres matrices no son diagonalizable porque no hay un segundo auto-vector linealmente independiente del primero.

(Strang, 2006, exercise 27 from section 5.2.)

(L-17) QUESTION 10. Factorice las siguientes matrices en S D S⁻¹

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

(b) $\mathbf{B} = \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix}$

(Strang, 2006, exercise 1 from section 5.2.)

(L-17) QUESTION 11. Encuentre la matriz **A** cuyos autovalores son 1 y 4, cuyos autovectores son $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$ y $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ respectivamente. (Strang, 2006, exercise 2 from section 5.2.)

(L-17) QUESTION 12. Si los elementos diagonales de una matriz triangular superior de orden 3×3 son 1, 2 y 7, ¿puede saber si la matriz es diagonalizable? ¿Quién es **D**? (Strang, 2006, exercise 4 from section 5.2.)

(L-17) QUESTION 13.

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1 Highlights of Lesson 18

Highlights of Lesson 18

- Symetric matrices $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$
 - Eigenvalues and eigenvectors
- Introd. positive Definiteness matrices

2 Symmetric matrices $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$

what's special about $\mathbf{A} oldsymbol{x} = \lambda oldsymbol{x}$ when $\prod_{n \times n}$ is symmetric?

- 1. A symmetric matrix has only REAL EIGENVALUES
- 2. n EIGENVECTORS can be choosen ORTHOGONAL (always diagonalizable)

The usual diagonalizable case:

$$S^{-1}AS = D \longleftrightarrow A = SDS^{-1}$$

Symmetric case:

I can choose perpendicular unit eigenvectors (ortho*normal* columns of $\mathbf{S}=\mathbf{Q}$)

(if
$$\mathbf{A} = \mathbf{A}^{\mathsf{T}}$$
) $\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}}$ Spectral thm.

Orthogonally diagonalizable.

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4 Quadratic forms

Quadratic form:

$$xAx$$
; with $A^{T}=A$

Since $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$ (with $\mathbf{Q}^{\mathsf{T}} \mathbf{Q} = \mathbf{Q} \mathbf{Q}^{\mathsf{T}} = \mathbf{I}$), then

$$x \mathbf{A} x = x \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}} x = (\mathbf{Q}^{\mathsf{T}} x) \mathbf{D} (\mathbf{Q}^{\mathsf{T}} x)$$
 (weighted sum of squares)

Positive definite quadratic form:

$$x\mathbf{A}x > 0 \quad \forall x \neq \mathbf{0} \qquad \Longleftrightarrow \qquad \lambda_i > 0, \quad i = 1:n.$$

then we also say **A** is positive definite.

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3 Eigenspaces are orthogonal for symmetric matrices

Eigenvectors (corresponding to different eigenvalues) of a symmetric matrix are orthogonal.

Proof.

Consider $\mathbf{A}x = \lambda_1 x$ and $\mathbf{A}y = \lambda_2 y$ (with $\lambda_1 \neq \lambda_2$). then

$$\lambda_1 \boldsymbol{x} \cdot \boldsymbol{y} = \mathbf{A} \boldsymbol{x} \cdot \boldsymbol{y} = \boldsymbol{x} (\mathbf{A}^{\intercal}) \boldsymbol{y} = \boldsymbol{x} \mathbf{A} \boldsymbol{y} = (\boldsymbol{x} \cdot \boldsymbol{y}) \lambda_2.$$

Since $\lambda_1 \neq \lambda_2$ then:

$$\lambda_1(\boldsymbol{x}\cdot\boldsymbol{y}) - \lambda_2(\boldsymbol{x}\cdot\boldsymbol{y}) = 0 \implies (\lambda_1 - \lambda_2)\boldsymbol{x}\cdot\boldsymbol{y} = 0 \implies \boldsymbol{x}\cdot\boldsymbol{y} = 0.$$

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5 Positive definite matrices

Meaning:

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 (except for $\boldsymbol{x} = \mathbf{0}$)

Some properties

Consider a positive definite symmetric A: What about A^{-1} ?

$$\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{-}1} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{T}}$$

Consider two positive definite symmetric matrices A, B: What about A + B?

the answer must be...

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6 The matrix product **A**^T**A**

Consider the rectangular matrix \mathbf{A} . Is $\mathbf{A}^{\mathsf{T}}\mathbf{A}$ positive definite?

$$\boldsymbol{x}(\mathbf{A}^{\intercal}\mathbf{A})\boldsymbol{x} =$$

It can only be 0 when $\mathbf{A}x$ is $\mathbf{0}$

How can we guarantee that $\mathbf{A}x \neq \mathbf{0}$ when $x \neq \mathbf{0}$?

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8 Positive definite symmetric matrices

- All eigenvalues are:
- All pivots are:

$$\begin{bmatrix} 5 & 2 \\ 2 & 3 \end{bmatrix}$$

Pivots:

What is the sign of each eigenvalue?

$$\lambda^2 - 8\lambda + 11 = 0 \rightarrow \lambda = 4 \pm \sqrt{5} > 0$$

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7 Symmetric matrices: signs of eigenvalues

are all λ_i positive? are they negative?

Computing eigenvalues of \mathbf{A} is impossible in general! (5th degree polynomial)

Good news: The signs of the pivots of echelon form are the same as the signs of the eigenvalues λ_i (if we do not change the sign of the determinant with *Type II* elementary transformations)

num. of positive pivots = num. of positive eigenvalues

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Summary (for symmetric matrices):

- 1. Symmetric matrices have *real eigenvalues* and *perpendicular eigenvectors* can be choosen
- 2. $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$ where \mathbf{Q} is orthogonal
- 3. A is symmetric if and only if it is *orthogonally* diagonalizable
- 4. The signs of the pivots in the echelon form are same as the signs of the eigenvalues λ_i (only if we do not change the sign of the determinant with $Type\ II$ elementary transformations)

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Questions of the Lecture 18

(L-18) QUESTION 1. Write A, B and C in the form QDQ^T of the spectral theorem:

(a)
$$\mathbf{A} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

(Strang, 2006, exercise 11 from section 5.5.)

(L-18) QUESTION 2. Find the eigenvalues and the unit eigenvectors of

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

(Strang, 2003, exercise 3 from section 6.4.)

(L-18) QUESTION 3. Find an orthonormal **Q** that diagonalizes this symmetric matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{bmatrix}$$

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(L-18) QUESTION 6. Sean

- (a) Encuentre los valores característicos de **A** (recuerde que $i^2 = -1$).
- (b) Encuentre los valores característicos de B (en este caso quizá le resulte más sencillo encontrar primero los autovectores, y deducir entonces los autovalores).

(Strang, 2006, exercise 14 from section 5.5.)

(L-18) QUESTION 7. Si ${\bf A}^3={\bf 0}$ entonces los autovalores de ${\bf A}$ deben ser _____. De un ejemplo tal que ${\bf A}\neq{\bf 0}$. Ahora bien, si ${\bf A}$ es además simétrica, demuestre que entonces ${\bf A}^3$ es necesariamente ${\bf 0}$.

(L-18) QUESTION 4. Suppose **A** is a symmetric 3 by 3 matrix with eigenvalues 0, 1.2.

- (L-18) QUESTION 4. Suppose **A** is a symmetric 3 by 3 matrix with eigenvalues 0, 1,
- (a) What properties can be guaranteed for the corresponding unit eigenvectors $oldsymbol{u},\,oldsymbol{v}$ and $oldsymbol{w}$
- (b) In terms of u, v, w, describe the nullspace, left nullspace, row space, and column space of \mathbf{A} .
- (c) Find a vector x that satisfies Ax = v + w. Is x unique?
- (d) Under what conditions on b does $\mathbf{A}x = \mathbf{b}$ have a solution?
- (e) If u, v, w are the columns of S, what are S^{-1} and $S^{-1}AS$

(Strang, 2006, exercise 13 from section 5.5.)

(Strang, 2003, exercise 5 from section 6.4.)

(L-18) QUESTION 5. Escriba un hecho destacado sobre los valores característicos de cada uno de estos tipos de matrices:

- (a) Una matriz simétrica real.
- (b) Una matriz diagonalizable tal que $\mathbf{A}^n \to \mathbf{0}$ cuando $n \to \infty$.
- (c) Una matriz no diagonalizable
- (d) Una matriz singular

(Strang, 2006, exercise 16 from section 5.5.)

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(L-18) QUESTION 8. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} a & 1 & 1 \\ 0 & 3 & 1 \\ 0 & 0 & 2 \end{bmatrix}.$$

- (a) Prove that **A** is not diagonalizable when a=3.
- (b) Is **A** diagonalizable when a=2? (explain). If it is diagonalizable, find an eigenvalue diagonal matrix **D** and an eigenvector matrix **S** such as $\mathbf{A} = \mathbf{SDS}^{-1}$.
- (c) Is A^TA diagonalizable for any value a? Is it possible to find a full set of orthonormal eigenvectors of A^TA?
- (d) Find all posible values a such as **A** is invertible and diagonalizable.
- (L-18) QUESTION 9. Sea la matriz

$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix};$$

- (a) Exprese B en la forma $B = A = QDQ^{T}$ del teorema espectral.
- (b) ¿Es B diagonalizable? Si no lo es, diga las razones; y en caso contrario genere una matriz S que diagonalice a B.
- (L-18) QUESTION 10. Suppose the vectors ${m q}_1,\ {m q}_2,\ {m q}_3$ form an orthonormal basis for \mathbb{R}^3 and the matrix ${m A}$ satisfies ${m A}{m q}_1=(1,0,0,), \quad {m A}{m q}_2=(0,1,0,),$ and ${m A}{m q}_3=(0,0,1,).$

- (a) (0.5pts) Write the matrix ${\bf A}$ explicitly in terms of the vectors ${\bf q}_1,\,{\bf q}_2,\,{\bf q}_3.$
- (b) (1^{pts}) Write down all possibilities for det **A**.
- (c) Which of the following statementes are correct: The eigenvalues of A must...
 - be real numbers.
 - be positive real numbers.
 - be imaginary numbers.
 - have absolute value $|\lambda| = 1$.

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- Positive definite: $\forall x \neq 0 \Rightarrow x Ax > 0$.
- Positive semi-definite: $\forall x \neq 0 \Rightarrow x \land x \geq 0$.
- Negative definite: $\forall x \neq 0 \ \Rightarrow \ x \mathbf{A} x < 0$.
- Negative semi-definite: $\forall x \neq 0 \Rightarrow x Ax \leq 0$.
- Indefinite: neither positive semi-definite, nor negative semi-definite.

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1 Highlights of Lesson 19

Highlights of Lesson 19

- Positive and Negative (semi)definite matrices
- Completing the squares
- Diagonalization by congruence

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Example

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What number do I have to put there for the matrix **A** to be singular?

$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix}$$

- Eigenvalues:
- Leading principal minors:
- For the following quadratic form

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + y^2$$

Is there a $x \neq 0$ such that xAx = 0?

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Example

If
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & 7 \end{bmatrix}$$
 then $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 7 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + ?y^2$

- Are there numbers x and y that make xAx negative?
- Does the function go through the origin?
- When y=0 and x=1, is it possitive? (and when x=-1?)
- When x=0 and y=1, is it possitive? (and when y=-1?)
- Is it always positive?

(0,0,) saddle point: minimum in some directions, maximum in others.

$$\lambda_1 = -2, \quad \begin{pmatrix} -6\\4 \end{pmatrix}; \qquad \lambda_1 = 11, \quad \begin{pmatrix} 6\\9 \end{pmatrix}$$

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Example

If
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix}$$
 then $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + 20y^2$

Positive definite.

Does it pass the tests?

- Are the leading principal minors positive?
- Are the eigenvalues positive?

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 for all $\boldsymbol{x} \neq \mathbf{0}$

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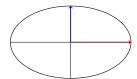
3 Completing the squares

If we could express q(x) as a sum of squares, we would know whether q(x) is positive definite.

Let's complete the square!

- $q(x,y) = 2x^2 + 12xy + 20y^2 = 2(x + ?y)^2 + ?$
- $q(x,y) = 2x^2 + 12xy + 7y^2$
- $q(x,y) = 2x^2 + 12xy + 18y^2$
- $q(x,y) = 2x^2 + 12xy + 200y^2$ (graph)

If positive definite: q(x,y) = a; a > 0: ellipse



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4 Congruent matrices

 \boldsymbol{A} and \boldsymbol{C} are congruent if there exists an invertible \boldsymbol{B} such that $\boxed{\boldsymbol{C} = \boldsymbol{B}^{\mathsf{T}}\boldsymbol{A}\boldsymbol{B}}$

Diagonalization by congruence

For each **A** (symmetric) exists $\mathbf{B} = \mathbf{I}_{\tau_1 \cdots \tau_k}$ (invertible) such that

$$\mathbf{D} = \mathbf{B}^{\mathsf{T}} \mathbf{A} \mathbf{B}$$
 is diagonal $(\mathbf{B}^{\mathsf{T}} = {}_{\tau_{b} \cdots \tau_{1}} \mathbf{I})$

Spectral Theorem: ¡Diagonalization by similarity and congruence!

$$\mathbf{D} = \mathbf{Q}^{-1} \mathbf{A} \mathbf{Q} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}.$$

Hence, every quadratic form can be written as a sum of squares

$$x \mathbf{A} x = x (\mathbf{B}^{-1})^{\mathsf{T}} \mathbf{D} \mathbf{B}^{-1} x = y \mathbf{D} y;$$
 where $y = \mathbf{B}^{-1} x.$

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5 Completing the squares

$$2x^{2} + 12xy + 20y^{2}$$

$$\begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \xrightarrow{[(-3)\mathbf{1}+\mathbf{2}]} \begin{bmatrix} 2 & 0 \\ 6 & 2 \end{bmatrix} \xrightarrow{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix};$$

therefore, we get:

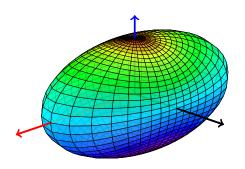
$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \mathbf{D} = \mathbf{E}^{\mathsf{T}} \mathbf{A} \mathbf{E} = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}$$

hence $\mathbf{A} = (\mathbf{E}^{\intercal})^{-1} \mathbf{D} \mathbf{E}^{-1}$ so

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \boldsymbol{x} (\mathbf{E}^{-1})^{\mathsf{T}} \end{pmatrix} \mathbf{D} \begin{pmatrix} \mathbf{E}^{-1} \boldsymbol{x} \end{pmatrix}$$
$$= \begin{pmatrix} (x+3y), & y, \end{pmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{pmatrix} (x+3y) \\ y \end{pmatrix} = 2(x+3y)^2 + 2y^2$$

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- 7 Positive definite matrices and ellipsoids: example 3 by 3
- The region (xAx = a) is an (ellipsoid).
- The eigenvectors of Q are in the direction of the three principal axes.
- Lengths of axes determined by the eigenvalues



6 example 3 by 3

Is
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$
 positive definite?

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\begin{bmatrix} \left(\frac{1}{2}\right)\mathbf{1}+2 \right]]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\begin{bmatrix} \left(\frac{2}{3}\right)\mathbf{2}+3 \right]]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & 0 \\ 0 & 0 & \frac{4}{3} \end{bmatrix}$$

$$x\mathbf{A}x = 2x^2 + 2y^2 + 2z^2 - 2xy - 2yz > 0$$

 $x \mathbf{A} x = 1$: (ellipsoid) axes are eigenvectors $\mathbf{A} = \mathbf{Q}^{\intercal} \lambda \mathbf{Q}$

Is
$$\mathbf{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$
 positive definite?

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(1)\mathbf{3}+1]{\textcolor{red}{\mathbf{7}}} \begin{bmatrix} 2 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(-\frac{1}{2})\mathbf{1}+3]{\textcolor{red}{\mathbf{7}}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} \xrightarrow[\mathbf{2}=3]{\textcolor{red}{\mathbf{2}}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Indefinite matrix

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9 "Classification" of quadratic

$$oxed{x \mathbf{A} x \lessapprox 0;} \quad ext{for all } oxed{x
eq 0}$$

Methods

Check the signs of

- 1. Elem. diag.: $D = B^{T}AB$ (Diagonalization by congruence)
- 2. Computing eigenvalues: (Roots of a polynomial) ©
- 3. Leading principal minors: (Sylvester's criterion)

Law of inertia

the number of positive, negative and zero entries of the diagonal of \mathbf{D} is an invariant of \mathbf{A} , i.e. it does not depend on \mathbf{B} (Orthogonal diagonalization $\mathbf{D} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}$ is a special case)

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(L-19) QUESTION 3. Which one of the following matrices has two positive eigenvalues? Test a>0 and $ac>b^2$, don't compute the eigenvalues. $x\mathbf{A}x<0$.

(a)
$$\mathbf{A} = \begin{bmatrix} 5 & 6 \\ 6 & 7 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} -1 & -2 \\ -2 & -5 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 1 & 10 \\ 10 & 100 \end{bmatrix}$$

(d)
$$\mathbf{D} = \begin{bmatrix} 1 & 10 \\ 10 & 101 \end{bmatrix}$$

(Strang, 2006, exercise 14 from section 6.1.)

(L-19) QUESTION 4. Show that $f(x,y)=x^2+4xy+3y^2$ does not have a minimum at (0,0) even though it has positive coefficients. Write f(x,y) as a difference of squares and find a point (x,y) where f(x,y) is negative. (Strang, 2006, exercise 16 from section 6.1.)

(L-19) QUESTION 5. Show from the eigenvalues that if **A** is positive definite, so is A^2 and so is A^{-1} . (Strang. 2006. exercise 4 from section 6.2.)

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Questions of the Lecture 19

(L-19) QUESTION 1. Decide for or against the positive definiteness of these matrices, and write out the corresponding quadratic form $f = x \mathbf{A} x$:

(a)
$$\begin{bmatrix} 1 & 3 \\ 3 & 5 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

(c)
$$\begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$$

(d)
$$\begin{bmatrix} -1 & 2 \\ 2 & -8 \end{bmatrix}$$

(e) The determinant in (b) is zero; along what line is f(x,y)=0?

(Strang, 2006, exercise 2 from section 6.1.)

(L-19) QUESTION 2. What is the quadratic $f=ax^2+2bxy+cy^2$ for each of these matrices? Complete the square to write f as a sum of one or two squares $d_1(-)^2+d_2(-)^2$.

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$$

(Strang, 2006, exercise 15 from section 6.1.)

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(L-19) QUESTION 6. Consider the following quadratic forms

$$q_1(x, y, z) = x^2 + 4y^2 + 5z^2 - 4xy.$$

$$q_2(x, y, z) = -x^2 + 4y^2 + z^2 + 2xy - 2axz.$$

- (a) Show that $q_1(x, y, z)$ is positive semi-definite.
- (b) Find, if it is possible, any value of a such as $q_2(x, y, z)$ is negative definite.

(L-19) QUESTION 7. Decide for or against the positive definiteness of

(a)
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

(b)
$$\mathbf{B} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & 1 \\ -1 & 1 & 2 \end{bmatrix}$$

(c)
$$\mathbf{C} = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{bmatrix}^2$$

(Strang, 2006, exercise 2 from section 6.2.)

(L-19) QUESTION 8. Consider the following quadratic form

$$q(x, y, z) = x^2 + 6xy + y^2 + az^2;$$

Decide for which values a the quadratic form is positive definite, negative definite, semidefinite, or indefinite.

(L-19) QUESTION 9. Si ${\bf A}=\left[\begin{smallmatrix} a & b \\ b & d \end{smallmatrix} \right]$ es definida positiva, pruebe que ${\bf A}^{-1}$ es definida positiva.

(Strang, 2006, exercise 8 from section 6.1.)

(L-19) QUESTION 10. Si una matriz simétrica de 2 por 2 satisface a>0, y $ac>b^2$, demuestre que sus autovalores son reales y positivos (definida positiva). Emplee la ecuación característica y el hecho de que el producto de los autovalores es igual al determinante.

(Strang, 2006, exercise 3 from section 6.1.)

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(L-19) QUESTION 13. Demuestre que si **A** y **B** son definidas positivas entonces **A** + **B** también es definida positiva. Para esta demostración los pivotes y los valores característicos no son convenientes. Es mejor emplear $x(\mathbf{A} + \mathbf{B})x > 0$ (Strang, 2006, exercise 5 from section 6.2.)

(L-19) QUESTION 14. Find the $\dot{\mathbf{L}}\mathbf{D}\dot{\mathbf{L}}^\mathsf{T}$ factorization for the following symmetric matrices.

(a)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix}$$

(b)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 3 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

(L-19) QUESTION 15. La forma cuadrática $f(x,y)=3(x+2y)^2+4y^2$ es definida positiva. Encuentre la matriz **A**, factorícela en **LDL**^T, y relacione los elementos en **D** y **L** con 3, 2 y 4 en f.

(Strang, 2006, exercise 9 from section 6.1.)

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(L-19) QUESTION 11. Decida si las siguientes matrices son definidas positivas, definidas negativas, semi-definidas, o indefinidas.

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 4 \\ 3 & 4 & 9 \end{bmatrix}$$

(b) $\mathbf{B} = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 6 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 3 \end{bmatrix}$
(c) $\mathbf{C} = -\mathbf{B}$
(d) $\mathbf{D} = \mathbf{A}^{-1}$

(L-19) QUESTION 12. Una matriz definida positiva no puede tener un cero (o incluso peor; un número negativo) en su diagonal principal. Demuestre que esta matriz no cumple $x\mathbf{A}x>0$, para todo $x\neq 0$:

(Strang, 2006, exercise 21 from section 6.2.)

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(L-19) QUESTION 16. Consider the following matrices

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & a & 0 \\ 0 & 0 & a & a \end{bmatrix} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

- (a) (0.5^{pts}) Compute the eigenvalues of **A**.
- (b) (0.5^{pts}) Prove that when a=2 the matrix **A** is not diagonalisable.
- (c) (1^{pts}) For matrix **B**, find a diagonal matrix **D** and an orthonormal matrix **P** such as $B = PDP^T$.
- (d) $(0.5^{\rm pts})$ Find the quadratic form f(x,y,z) associated to ${\bf B}$, and prove it is positive defined

(L-19) QUESTION 17. Given the matrix $\mathbf{A}=\begin{pmatrix} a&3/5\\b&4/5 \end{pmatrix}$, compute the values (if they exist) of a and b such as

- (a) (0.5^{pts}) **A** is ortho-normal.
- (b) (0.5^{pts}) Columns of **A** are linearly independent.
- (c) $(0.5^{\text{pts}}) \lambda = 0$ is an eigenvalue of **A**.
- (d) (0.5^{pts}) A is a symmetric definite negative matrix.

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(L-19) QUESTION 18.

(a) Consider the quadratic form $q(x,y,z)=x^2+2xy+ay^2+8z^2$ and find its corresponding symmetric matrix \mathbf{Q} ; determine if \mathbf{Q} is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite when the parameter a is equal to one (a=1).

(b) If $a \neq 1$, determine whether the matrix is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite.

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(f) If 1 is the only eigenvalue of a 2×2 matrix ${\bf A}$, then ${\bf A}$ must be the identity matrix

(L-OPT-2) QUESTION 3. complete los blancos, o responda Verdadero/Falso.

- (a) Cualquier sistema generador de un espacio vectorial contiene una base del espacio (V/F)
- (b) Que los vectores ${m v}_1,\ {m v}_2,\ \dots,\ {m v}_n$ sean linealmente independientes significa que
- (c) El conjunto que sólo contiene el vector ${\bf 0}$ es un conjunto linealmente independiente. (V/F)
- (d) Una matriz cuadrada de orden n por n es diagonalizable cuando:
- (e) Si u = (1, 2, -1, 1), entonces ||u|| =______
- (f) Si $\boldsymbol{u}=(1,2,-1,1)$ y $\boldsymbol{v}=(-2,1,0,0)$, entonces $\boldsymbol{u}\cdot\boldsymbol{v}=$

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Questions of the Optional Lecture 2

(L-OPT-2) QUESTION 1. Consider the following matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & a & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

- (a) (0.5^{pts}) Prove **A** is invertible if and only if $a \neq 0$.
- (b) (0.5^{pts}) Is **A** positive definite when a=1? Explain your answer.
- (c) (1^{pts}) Compute \mathbf{A}^{-1} when a=2.
- (d) $(0.5^{\rm pts})$ How many variables can be chosen as pivot (or exogenous) variables in the system ${\bf A}x={\bf o}$ when a=0? Which ones?

(L-OPT-2) QUESTION 2. True or false (to receive full credit you must explain your answers in a clear and concise way)

- (a) If A is symetric, then so it is A^2 .
- (b) If $A^2 = A$ then $(I A)^2 = (I A)$ where I is the identity matrix.
- (c) If $\lambda=0$ is an eigenvalue of the squared matrix **A**, then the linear system $\mathbf{A}x=0$ is is always solvable and has only one solution.
- (d) If $\lambda=0$ is an eigenvalue of the squared matrix ${\bf A}$, then the linear system ${\bf A}x={m b}$ could be unsolvable.
- (e) If a matrix is orthogonal (perpendicular columns of norm one), then so it is the inverse of that matrix.

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(L-OPT-2) QUESTION 4. En las preguntas siguientes $\bf A$ y $\bf B$ son matrices $n \times n$. Indique si las siguientes afirmaciones son verdaderas o falsas (incluya una breve explicación, o un contra ejemplo que justifique su respuesta):

- (a) Si A no es cero entonces $det(A) \neq 0$
- (b) Si $det(AB) \neq 0$ entonces A es invertible.
- (c) Si intercambio las dos primeras filas de A sus autovalores cambian.
- (d) Si A es real y simétrica, entonces sus autovalores son reales (aquí no es necesaria una justificación).
- (e) Si la forma reducida de echelon de $({\bf A}-5{\bf I})$ es la matriz identidad, entonces 5 no es un autovalor de ${\bf A}$.
- (f) Sea ${m b}$ un vector columna de ${\mathbb R}^n$. Si el sistema ${f A}{m x}={m b}$ no tiene solución, entonces $\det({f A})
 eq 0$
- (g) Sea C de orden 3×5 . El rango de C puede ser 4.
- (h) Sea ${\bf C}$ de orden $n \times m$, y ${\bf b}$ un vector columna de \mathbb{R}^n . Si ${\bf C}{\bf x} = {\bf b}$ no tiene solución, entonces $\operatorname{rg}({\bf C}) < n$.
- (i) Toda matriz diagonalizable es invertible.
- (j) Si A es invertible, entonces su forma reducida de echelon es la matriz identidad.

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(L-OPT-2) QUESTION 5. Sean

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 4 \\ 0 & 0 & 5 \end{bmatrix}; \quad \mathbf{B} = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}; \quad \mathbf{C} = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 0 & 4 \\ 0 & 0 & 6 \end{bmatrix}; \quad \mathbf{D} = \begin{bmatrix} 2 & 3 & 0 \\ 3 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Los autovalores de **B** son 0 y 2. Use esta información para responder a las siguientes cuestiones. Para cada matriz debe dar una explicación. Puede haber más de una matriz que cumpla la condición:

- (a) ¿Qué matrices son invertibles?
- (b) ¿ Qué matrices tienen un autovalor repetido?
- (c) ¿Qué matrices tienen rango menor a tres?
- (d) ¿Qué matrices son diagonalizables?
- (e) ¿Para qué matrices diagonalizables podemos encontrar tres autovectores ortogonales entre si?

(L-OPT-2) QUESTION 6. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix}$$

- (a) Find the eigenvalues and eigenvectors of A.
- (b) Is A diagonalizable?

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- (a) ¿Cuáles son sus espacios columna $\mathcal{C}(\mathbf{A})$ y espacio nulo $\mathcal{N}(\mathbf{A})$? (no responda con la definición, diga qué conjunto de vectores compone cada espacio).
- (b) Suponga que A puede ser factorizada en A = LU:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 7 & 3 & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{12} & u_{13} \\ 0 & 0 & u_{13} \end{bmatrix}$$

Describa el primer paso de eliminación en la reducción de **A** a **U**. ¿porqué sabe que **U** es también una matriz invertible? ¿Cuanto vale el determinante de **A**?

- (c) Encuentre una matriz particular de dimensiones 3 x 3 e invertible A que no pueda ser factorizada en la forma LU (sin permutar previamente las filas). ¿Qué factorización es todavía posible en su ejemplo? (no es necesario que realice la factorización). ¿Cómo sabe que su matriz A es invertible?
- Strang, G. (2003). *Introduction to Linear Algebra*. Wellesley-Cambridge Press, Wellesley, Massachusetts. USA, third ed. ISBN 0-9614088-9-8.
- Strang, G. (2006). *Linear algebra and its applications*. Thomson Learning, Inc., fourth ed. ISBN 0-03-010567-6.

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- (c) Is it possible to find a matrix P such as $A = PDP^{T}$, where D is diagonal?
- (d) Find $|{\bf A}^{-1}|$.

(L-OPT-2) QUESTION 7. Consider a 3 by 3 matrix ${\bf A}$ with eigenvalues $\lambda_1=1,$ $\lambda_2=2,$ and $\lambda_3=-1;$ and let ${\bf v}_1=(1,0,1)^{\rm T}$ and ${\bf v}_2=(1,1,1)^{\rm T}$ be the corresponding eigenvectors to λ_1 and $\lambda_2.$

- (a) Is A diagonalizable?
- (b) Is $v_3 = (-1, 0, -1)^T$ an eigenvector associated to the eigenvalue $\lambda_3 = -1$?
- (c) Compute $\mathbf{A}(v_1 v_2)$.

(L-Opt-2) Question 8.

(a) $(0.5^{\rm pts})$ Find an homogeneous system $\mathbf{A}x=\mathbf{0}$ such as its solutions set is

$$\left\{ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} \in \mathbb{R}^4 \ \middle| \ \exists \alpha, \beta, \gamma \in \mathbb{R} \quad \text{such that} \ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \beta \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \gamma \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}. \right\}$$

(b) (0.5^{pts}) If the characteristic polynomial of a matrix **A** is $p(\lambda) = \lambda^5 + 3\lambda^4 - 24\lambda^3 + 28\lambda^2 - 3\lambda + 10$, find the rank of **A**.

(L-Opt-2) Question 9. Suponga una matriz cuadrada e invertible $\,$ A $\,$

...