Mathematics II

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1 Highlights of Lesson 14

Highlights of Lesson 14

- $\det(\mathbf{A}) \equiv |\mathbf{A}|$ • Determinant:

 $[\det: \mathbb{R}^{n \times n} \longrightarrow \mathbb{R}]$

- Volume vs determinant
- Properties: 1, 2, 3
- We will deduce properties: 4 − 9

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You can find the last version of these course materials at

https://github.com/mbujosab/MatematicasII/tree/main/Eng

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2 Area or volume

1. $\operatorname{Vol}(\underset{n \times n}{\mathbf{I}}) = 1$.





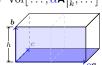
 $2. \ \operatorname{Vol} \left(\mathbf{A} \right) \ = \ \operatorname{Vol} \left(\mathbf{A}_{\underbrace{\left[(\alpha) \mathbf{k} + \mathbf{j} \right]}{\mathbf{j}}} \right) \text{ for } j \neq k.$





3. $|\alpha| \cdot \text{Vol}(\mathbf{A}) = |\alpha| \cdot \text{Vol}[\ldots; \mathbf{A}_{|k}; \ldots] = \text{Vol}[\ldots; \alpha \mathbf{A}_{|k}; \ldots]$





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3 Determinant: 3 properties that define the function

P-1 Determinant of identity matrices:

$$\det \mathop{\rm I}_{n\times n} = 1$$

P-2 Type I elemen. transf. do not change the determinant:

$$\det \mathbf{A} = \det \left(\mathbf{A}_{\underbrace{\mathbf{A}}_{[(\alpha)k+j]}}^{T} \right)$$

P-3 Multiplying a column by an scalar multiplies the det.

$${\color{blue}\alpha}\cdot\det\mathbf{A}\ =\ \det\big[\ldots;{\color{blue}\alpha}\mathbf{A}_{|k};\ldots\big] \text{ for any } k\in\{1:n\} \text{ and } \alpha\in\mathbb{R}$$

Absolute value of $\det \mathbf{A} = \operatorname{Vol} \mathbf{A}$

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- 4 Determinant of a matrix with a zero column
- P-4 Det. of a matrix A with a zero column If A has a zero column 0, then

$$\det(\mathbf{A}) = 0$$

prove P-4

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Example

Then, we know that in \mathbb{R}^3 :

$$\begin{vmatrix} a_1 & (b_1 + \alpha c_1) & c_1 \\ a_2 & (b_2 + \alpha c_2) & c_2 \\ a_3 & (b_3 + \alpha c_3) & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix};$$

$$\det [\boldsymbol{a}; (\boldsymbol{b} + \alpha \boldsymbol{c}); c;] = \det [\boldsymbol{a}; \boldsymbol{b}; c;];$$

and also

$$\begin{vmatrix} a_1 & \alpha b_1 & c_1 \\ a_2 & \alpha b_2 & c_2 \\ a_3 & \alpha b_3 & c_3 \end{vmatrix}; = \alpha \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix};$$

$$\det [\boldsymbol{a}; \alpha \boldsymbol{b}; \boldsymbol{c};] = \alpha \det [\boldsymbol{a}; \boldsymbol{b}; \boldsymbol{c};];$$

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5 Elementary matrices

We already know

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$$\det \left(\mathbf{A}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}+\boldsymbol{j}]}} \right) = |\mathbf{A}|; \qquad \det \left(\mathbf{A}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}]}} \right) = \alpha |\mathbf{A}|.$$

Determinant of elementary matrices

$$\det \left(\mathbf{I}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{k}+\boldsymbol{j}]}} \right) = 1 \qquad \text{and} \qquad \det \left(\mathbf{I}_{\underbrace{\boldsymbol{\tau}}_{[(\alpha)\boldsymbol{j}]}} \right) = \alpha.$$

Hence, since $\mathbf{A}_{\tau} = \mathbf{A}(\mathbf{I}_{\tau})$, then

$$\left| \mathbf{A}(\mathbf{I}_{\tau}) \right| = |\mathbf{A}| \cdot |\mathbf{I}_{\tau}| \tag{1}$$

where \mathbf{I}_{τ} is an elementary matrix

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ve the following propositions

6 Determinant after a sequence of elementary transformations

- (a) $\det(\mathbf{A}_{\tau_1\cdots\tau_k}) = |\mathbf{A}|\cdot|\mathbf{I}_{\tau_1}|\cdots|\mathbf{I}_{\tau_k}|$.
- (b) If **B** is a full rank matrix, i.e., if $\mathbf{B}=\mathbf{I}_{\tau_1\cdots\tau_k}$, then $|\mathbf{B}|=|\mathbf{I}_{\tau_1}|\cdots|\mathbf{I}_{\tau_k}|$, and therefore $|\mathbf{B}|\neq 0$.
- (c) If ${\bf A}$ and ${\bf B}$ have order n and ${\bf B}$ is full rank, then

$$\det(\mathbf{A}\mathbf{B}) = |\mathbf{A}| \cdot |\mathbf{B}| \tag{2}$$

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7 Antisymmetric property

P-5 [Antisymmetric property]

Column exchange changes the sign of the determinant.

Proof.

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Column exchange is a sequence of *Type I* transformation and just only one *Type II* transformation that multiplies a column by -1 \Box Therefore:

$$\begin{vmatrix} c_1 & b_1 & a_1 \\ c_2 & b_2 & a_2 \\ c_3 & b_3 & a_3 \end{vmatrix} = (-1) \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

Example

a sequence $au_1 \cdots au_k$ of $\mathit{Type\ I}$ elementary transformations does not change the determinant.

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$$|\mathbf{A}_{\tau_1\cdots\tau_h}| = |\mathbf{A}(\mathbf{I}_{\tau_1\cdots\tau_h})| = |\mathbf{A}|\cdot|\mathbf{I}_{\tau_1\cdots\tau_h}| = |\mathbf{A}|\cdot 1 = |\mathbf{A}|$$

Example

but a sequence of Type II can.

$$\begin{vmatrix} 2a & 3c \\ 2b & 3d \end{vmatrix} = \frac{?}{b} \begin{vmatrix} a & c \\ b & d \end{vmatrix}$$

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8 Singular matrices. Inverse of a matrix

P-6 If A is singular then |A| = 0.

$$\boxed{\mathbf{P-7}} \qquad \det(\mathbf{A}^{-1}) = (\det \mathbf{A})^{-1}.$$

Proof.

Let $\mathbf{A}_{\tau_1\cdots\tau_k}=\underset{\scriptscriptstyle{n\times n}}{\mathbf{R}}$ be a reduced equelon form (and $\mathbf{E}=\mathbf{I}_{\tau_1\cdots\tau_k}).$

Since AE = R, then: $|A| \cdot |E| = |R|$; with only two cases:

$$\begin{cases} \mathbf{A} \text{ singular } (\mathbf{R}_{|n} = \mathbf{0} \) : & |\mathbf{A}| \cdot |\mathbf{E}| = 0 \ \Rightarrow \ |\mathbf{A}| = 0 \\ \\ \mathbf{A} \text{ not singular } (\mathbf{R} = \mathbf{I}) : & |\mathbf{A}| \cdot |\mathbf{E}| = 1 \ \Rightarrow \ |\mathbf{E}| = \left|\mathbf{A}^{-1}\right| = \left(|\mathbf{A}|\right)^{-1} \end{cases}$$

Example

For
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 2 \end{bmatrix}$$
:

$$\begin{bmatrix} 1 & 2 \\ 2 & 2 \\ \hline 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow[TypeI]{[(-2)^{7}+2]} \begin{bmatrix} 1 & 0 \\ 2 & -2 \\ \hline 1 & -2 \\ 0 & 1 \end{bmatrix} \xrightarrow[TypeII]{[(-1/2)2]} \begin{bmatrix} 1 & 0 \\ 2 & 1 \\ \hline 1 & 1 \\ 0 & -1/2 \end{bmatrix} \xrightarrow[TypeI]{[(-2)^{2}+1]} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \hline -1 & 1 \\ 1 & -1/2 \end{bmatrix}$$

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$$\left| \mathbf{A}^{-1} \right| = \left| \mathbf{I}_{[(-2) 1 + 2]} \right| \cdot \left| \mathbf{I}_{[(-1/2) 2]} \right| \cdot \left| \mathbf{I}_{[(-2) 2 + 1]} \right| = 1 \cdot \frac{-1}{2} \cdot 1 = \frac{-1}{2};$$

that is

$$|\mathbf{A}| = -2.$$

EXERCISE 2. [Transposed matrices]

- (a) What is the relation between the determinant of an elementary matrix I_{τ} and the determinant of its transpose $_{\tau}I$?
- (b) Consider B, a full rank matrix, proof that $|B| = |B^{T}|$.

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9 Determinant of a product

P-8 [Determinant of a product of matrices]

$$|\det(\mathbf{A}\mathbf{B}) = \det(\mathbf{A}) \cdot \det(\mathbf{B}).$$
 (3)

$$\begin{cases} \mathbf{B} \text{ singular, then so it is } \mathbf{A}\mathbf{B} \Rightarrow & \det(\mathbf{A}\mathbf{B}) = 0 = \det(\mathbf{A}) \cdot \det(\mathbf{B}) \\ \\ \mathbf{B} = \mathbf{I}_{\tau_1 \cdots \tau_k} \Rightarrow & \det(\mathbf{A}\mathbf{B}) = \det(\mathbf{A}) \cdot \det(\mathbf{B}) \end{cases}$$

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10 Determinant of a transpose

P-9 Determinant of a transpose

$$|\mathbf{A}| = |\mathbf{A}^{\mathsf{T}}|.$$

Proof.

$$\begin{cases} \text{if \mathbf{A} singular:} & \mathbf{A}^\intercal \text{ singular } \Rightarrow \det \mathbf{A}^\intercal = \det \mathbf{A} = 0 \\ \\ \text{if \mathbf{A} NO singular:} & \mathbf{A} = \mathbf{I}_{\tau_1 \cdots \tau_k} \Rightarrow \det \mathbf{A}^\intercal = \det \mathbf{A} \end{cases} .$$

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Questions of the Lecture 14

(L-14) QUESTION 1. Complete the proofs of this lecture.

(L-14) QUESTION 2. Knowing that |BC| = |B||C|; prove that for any invertible matrix **A** (so det $\mathbf{A} \neq 0$)

$$\det(\mathbf{A}^{-1}) = \Big(\det(\mathbf{A})\Big)^{-1}.$$

(L-14) QUESTION 3. Consider \mathbf{A} and \mathbf{B} such that $\det(\mathbf{A}) = 2$ and $\det(\mathbf{B}) = -2$

- (a) (0.5^{pts}) Compute the determinants of $\mathbf{A}(\mathbf{B})^2$ and $(\mathbf{A}\mathbf{B})^{-1}$
- (b) (0.5^{pts}) Is it possible to compute the rank of $\mathbf{A} + \mathbf{B}$? and the rank of \mathbf{AB} ?

(L-14) QUESTION 4. Use the Gauss-Jordan method to compute the determinant

$$\begin{aligned} & \textbf{(a)} \ \mathbf{A}_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \\ & \textbf{(b)} \ \mathbf{A}_2 = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \\ & \textbf{(c)} \ \mathbf{A}_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \end{aligned}$$

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1 Highlights of Lesson 15

Highlights of Lesson 15

- Computing |A| by gaussian elimination
- P-10 Multilinear property
- Expansion of det A in Cofactors (Laplace expansion).
- Application of determinants
 - Cramer's rule for solving linear equations
 - Computing the inverse of A

(L-14) QUESTION 5. The 3 by 3 matrix A reduces to the identity matrix I by the following three column operations (in order):

$$au$$
: Subtract 4 times column 1 from column 2. $[(-4)1+2]$

$$au$$
: Subtract 3 times column 1 from column 3 .

$$au$$
: Subtract column 3 from column 2.

Find the determinant of A.

(L-14) Question 6.

(a) Find the determinant of
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$
 and $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$

(a) Find the determinant of
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \text{ and } \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$
 (b) Find the determinant of
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ a & b & c & d \end{bmatrix} \text{ using Gauss-Jordan}.$$

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2 Extended matrix

Extended matrix of B:

B
1

1. Given
$$\tau$$
:
$$\begin{bmatrix} \mathbf{B}_{\tau} \\ 1 \end{bmatrix} = \begin{bmatrix} \mathbf{B} \\ 1 \end{bmatrix}_{\tau}$$

2. Since $\begin{bmatrix} \mathbf{I} \\ 1 \end{bmatrix}_{-}$ and \mathbf{I}_{τ} same type Elem. Mat. \Rightarrow same det.

Applying 1. k times, and then 2.

$$\begin{split} \left| \begin{bmatrix} \mathbf{I}_{\tau_1 \cdots \tau_k} & \\ & 1 \end{bmatrix} \right| &= \left| \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_1 \cdots \tau_k} \right| = \left| \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_1} \cdots \begin{bmatrix} \mathbf{I} & \\ & 1 \end{bmatrix}_{\tau_k} \right| \\ &= \left| \mathbf{I}_{\tau_1} \right| \cdots \left| \mathbf{I}_{\tau_k} \right| = \left| \mathbf{I}_{\tau_1 \cdots \tau_k} \right|. \end{split}$$

If
$${\bf A}$$
 is the extended matrix of ${\bf B}$ $\begin{cases} \text{If } {\bf B} \text{ singular} & |{\bf B}|=0=|{\bf A}| \\ \text{If } {\bf B} \text{ invertible} & |{\bf B}|=|{\bf A}| \end{cases}$

EXERCISE 7. [Triangular matrices]

- (a) Find the determinant of a full rank lower triangular matrix L
- (b) Find the determinant of a triangular matrix with a zero entry in the main diagonal
- (c) Find the determinant of an upper triangular matrix **U**

In addition

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Matrices of order 1, $\mathbf{A} = [a]$:

$$\begin{bmatrix} a & 0 \\ \hline 0 & 1 \end{bmatrix} \Rightarrow |\mathbf{A}| = a.$$

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Matrices of order 2:

$$\begin{bmatrix} a & b & 0 \\ c & d & 0 \\ \hline 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{bmatrix} \left(-\frac{b}{a}\right) \mathbf{1} + \mathbf{2} \end{bmatrix}} \begin{bmatrix} a & 0 & 0 \\ c & d - \frac{bc}{a} & 0 \\ \hline 0 & 0 & 1 \end{bmatrix}$$

$$|\mathbf{A}| = ad - bc = a \det[d] - b \det[c].$$

Matrices of order 3:

$$|\mathbf{A}| = \underbrace{aei - afh - bdi + bfg + cdh - ceg}_{\text{(Rule of Sarrus)}} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

3 Computing by Gaussian elimination

Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 5 \\ 2 & 3 \end{bmatrix} : \quad \begin{bmatrix} 1 & 5 \\ 2 & 3 \end{bmatrix} \xrightarrow{[(-5)\mathbf{1}+\mathbf{2}]} \begin{bmatrix} 1 & 0 \\ 2 & -7 \end{bmatrix} \boxed{|\mathbf{A}| = -7}$$

Example

$$\begin{bmatrix} 0 & 2 & 1 & 0 \\ 9 & 6 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ \hline 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\substack{[(2)\mathbf{3}] \\ [(-1)\mathbf{2}+\mathbf{3}] \\ \hline [(\frac{1}{2})\mathbf{4}]}} \begin{bmatrix} 0 & 2 & 0 & 0 \\ 9 & 6 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ \hline 0 & 0 & 0 & \frac{1}{2} \end{bmatrix} \xrightarrow{\substack{\boldsymbol{\tau} \\ [\mathbf{1} \stackrel{\boldsymbol{\tau}}{=} \mathbf{2}] \\ \hline [(-1)\mathbf{4}]}} \begin{bmatrix} 2 & 0 & 0 & 0 \\ 6 & 9 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ \hline 0 & 0 & 0 & -\frac{1}{2} \end{bmatrix}$$

$$\begin{vmatrix} 0 & 2 & 1 \\ 9 & 6 & 3 \\ 0 & 1 & 1 \end{vmatrix} = -9,$$

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Matrices of order 4:

$$\begin{bmatrix} a & b & c & d & 0 \\ e & f & g & h & 0 \\ i & j & k & l & 0 \\ m & n & o & p & 0 \\ \hline 0 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{bmatrix} \left(-\frac{a}{a}\right)1+2 \\ \left(-\frac{a}{a}\right)1+4 \end{bmatrix}} \begin{bmatrix} \left(\frac{-ag+ce}{af-be}\right)2+3 \\ \left(\frac{-ag+ce}{af-be}\right)2+4 \\ \frac{(-ag+ce)}{af-be} + \frac{(-ah+ce)}{af-be} + \frac{(-ah+ce)}{af-be}$$

$$\begin{aligned} &afkp-aflo-agjp+agln+ahjo-ahkn-bekp+belo+bgip-bglm-bhio+bhkm+\\ &cejp-celn-cfip+cflm+chin-chjm-dejo+dekn+dfio-dfkm-dgin+dgjm\\ &=a\begin{vmatrix} f&g&h\\j&k&l&-b\\n&o&p\end{vmatrix} + \begin{vmatrix} e&g&h\\i&k&l&+c\\m&o&p\end{vmatrix} + \begin{vmatrix} e&f&h\\i&j&l&-d\\m&n&p\end{vmatrix} - \begin{vmatrix} e&f&g\\i&j&k\\m&n&o\end{vmatrix}$$

4 Multilinear property

P-10 Multilinear property

$$\det\left[\ldots;(\beta \mathbf{b} + \psi \mathbf{c});\ldots\right] = \beta \det\left[\ldots;\mathbf{b};\ldots\right] + \psi \det\left[\ldots;\mathbf{c};\ldots\right]$$

Example

Then, in the 2 dimensional case \mathbb{R}^2

$$\begin{vmatrix} a + \alpha & c \\ b + \beta & d \end{vmatrix} = \begin{vmatrix} a & c \\ b & d \end{vmatrix} + \begin{vmatrix} \alpha & c \\ \beta & d \end{vmatrix};$$

therefore

$$\begin{vmatrix} a & c \\ b & d \end{vmatrix} = \begin{vmatrix} a & c \\ 0 & d \end{vmatrix} + \begin{vmatrix} c \\ d \end{vmatrix}.$$

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Example

For
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$
, we have

$$egin{align*} {}^{1^{\eta}}\mathbf{A}^{^{\eta}\!2} = egin{bmatrix} 4 & 6 \ 7 & 9 \end{bmatrix}, \qquad {}^{3^{\eta}}\mathbf{A}^{^{\eta}\!3} = egin{bmatrix} 1 & 2 \ 4 & 5 \end{bmatrix} \end{split}$$

hence

$$\operatorname{cof}_{12}\left(\mathbf{A}\right) = (-1)^{\frac{1+2}{2}} \det \begin{pmatrix} 1^{\uparrow} \mathbf{A}^{\dagger 2} \end{pmatrix} = (-1) \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix}.$$

and

$$\operatorname{cof}_{33}\left(\mathbf{A}\right) = (-1)^{3+3} \det \begin{pmatrix} 3^{9} \mathbf{A}^{73} \end{pmatrix} = \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix}.$$

5 minors and cofactors

Definition minors and cofactors

We denote a submatrix of $\bf A$ obtained by deleting row i and column j of $\bf A$ by

$$i^{\dagger} \mathbf{A}^{\dagger j};$$

Its determinant is called the minor of a_{ij} . And

$$\operatorname{cof}_{ij}\left(\mathbf{A}\right) = (-1)^{i+j} \det\left({}^{i^{\uparrow}}\mathbf{A}^{i^{\flat}}\right)$$

is called the cofactor of a_{ij} .

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6 Expansion by cofactors

Theorem [Laplace expansion]

For **A** n by n, $det(\mathbf{A})$ may be computed as the sum of the products of the elements of any column (row) of **A** by their cofactors:

$$\det(\mathbf{A}) = \sum_{i=1}^{n} a_{ij} \operatorname{cof}_{ij}(\mathbf{A}),$$
 the expansion by the j th column

or

$$\det(\mathbf{A}) = \sum_{j=1}^{n} a_{ij} \operatorname{cof}_{ij} (\mathbf{A}),$$
 the expansion by the i th row

EXERCISE 8. Compute
$$\det \mathbf{A} = \begin{vmatrix} 2 & 0 & 3 & 2 \\ 5 & 1 & 2 & 4 \\ 3 & 0 & 1 & 2 \\ 5 & 3 & 2 & 1 \end{vmatrix}$$

7 Cramer's Rule

$$\mathbf{A}x = \mathbf{b}; \qquad |\mathbf{A}| \neq 0 \quad \text{then}$$

$$\boldsymbol{b} = (\mathbf{A}_{|1})x_1 + \dots + (\mathbf{A}_{|j})x_j + \dots + (\mathbf{A}_{|n})x_n.$$

$$\det \Big[\mathbf{A}_{|1}; \; \dots \; \overbrace{\boldsymbol{b}}^{\mathsf{pos.} \; j}; \; \dots \; \mathbf{A}_{|n} \Big] = x_j \cdot \det(\mathbf{A}).$$

$$x_j = \frac{\det\left[\mathbf{A}_{|1}; \dots \underbrace{\mathbf{b}}_{|n}; \dots \mathbf{A}_{|n}\right]}{\det(\mathbf{A})}.$$

Computational issues when $\det \mathbf{A} \simeq 0$ (tiny angle between vectors)

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Questions of the Lecture 15

(L-15) QUESTION 1. Complete the proofs of the exercises of this lecture.

 $\text{(L-15) QUESTION 2. Consider } \mathbf{A} = \begin{bmatrix} \mathbf{A}_{|1}; & \mathbf{A}_{|2}; & \mathbf{A}_{|3}; \end{bmatrix} \text{ with } \det \mathbf{A} = 2.$

- (a) What are $det(2\mathbf{A})$ and $det \mathbf{A}^{-1}$?
- (b) What is $\det \left[(3{\bf A}_{|1} + 2{\bf A}_{|2}); \quad {\bf A}_{|3}; \quad {\bf A}_{|2}; \right]$

(L-15) QUESTION 3. The determinant of the 1000 by 1000 matrix $\bf A$ is 12. What is the determinant of $-{\bf A}^{T}$? (Careful: No credit for the wrong sign.) (MIT Course 18.06 Quiz 2, Fall, 2008)

(L-15) QUESTION 4. Consider the squared matrix **A**. True or false? (to receive full credit you must explain your answer in a clear and concise way) $|\mathbf{A}\mathbf{A}^\intercal| = |\mathbf{A}|^2$.

(L-15) QUESTION 5. We have a 3×3 matrix $\mathbf{A} = \begin{bmatrix} a & 1 & 2 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$ with $\det \mathbf{A} = 3$.

Compute the determinant of the following matrices

(a) (0.5 pts)
$$\begin{bmatrix} a-2 & 1 & 2 \\ b-4 & 3 & 4 \\ c-6 & 5 & 6 \end{bmatrix}$$

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8 The inverse of a matrix

$$[Adj(A)] \cdot A =$$

$$\begin{bmatrix} \operatorname{cof}_{11}\left(\mathbf{A}\right) & \operatorname{cof}_{21}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{n1}\left(\mathbf{A}\right) \\ \operatorname{cof}_{12}\left(\mathbf{A}\right) & \operatorname{cof}_{22}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{n2}\left(\mathbf{A}\right) \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{cof}_{1n}\left(\mathbf{A}\right) & \operatorname{cof}_{2n}\left(\mathbf{A}\right) & \cdots & \operatorname{cof}_{nn}\left(\mathbf{A}\right) \end{bmatrix} \underbrace{\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}}_{\mathbf{A}}$$

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(b) (0.5 pts)
$$\begin{bmatrix} 7a & 7 & 14 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$$
(c) (1 pts) $(2\mathbf{A})^{-1}\mathbf{A}^{\mathsf{T}}$

(d) (0.5 pts)
$$\begin{bmatrix} a-2 & 1 & 2 \\ b & 3 & 4 \\ c & 5 & 6 \end{bmatrix}$$

(L-15) Question 6.

- (a) Escalone la matriz ${\bf A} = \begin{bmatrix} 2 & 3 & 1 \\ 4 & 5 & 2 \\ 4 & 6 & 0 \end{bmatrix}$
- (b) ; Es A invertible?
- (c) En caso afirmativo calcule $|\mathbf{A}^{-1}|$; en caso contrario calcule $|\mathbf{A}|$
- (d) La matriz C es igual al producto de A con la traspuesta de la matriz B, es decir

$$\mathbf{C} = \mathbf{A}\mathbf{B}^{\mathsf{T}} \qquad \mathsf{donde} \qquad \mathbf{B} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 2 & 3 \end{bmatrix}$$

¿Cuánto vale el determinante de C? ¿Es C invertible?

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(L-15) QUESTION 10. Compute the value of det A using Laplace expansion

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 0 & 2 & 2 & \cdots & 2 \\ 0 & 0 & 3 & \cdots & 3 \\ \vdots & & & \ddots & \\ 0 & 0 & 0 & \cdots & n \end{bmatrix}$$

(L-15) QUESTION 11. Consider a n by n matrix \mathbf{A}_n full of 3s in its diagonal, and twos just below the diagonal, and another 2 at the position (1,n); for example, for n=4:

$$\mathbf{A}_4 = \begin{bmatrix} 3 & 0 & 0 & 2 \\ 2 & 3 & 0 & 0 \\ 0 & 2 & 3 & 0 \\ 0 & 0 & 2 & 3 \end{bmatrix}.$$

- (a) Find, using the cofactors of the first row, the determinant of A_4 .
- (b) Find the determinant of \mathbf{A}_n for n > 4.

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(L-15) QUESTION 7. What is the determinant of the following matrices using Laplace expansions.

(a)
$$\begin{bmatrix} 1 & 2 \\ -4 & 3 \end{bmatrix}$$
(b)
$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 1 & -2 \end{bmatrix}$$
(c)
$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \\ 2 & 0 & 1 & -2 \end{bmatrix}$$

(L-15) QUESTION 8. Compute the following determinant using Laplace expansions:

$$\begin{vmatrix} 0 & 0 & 0 & 3 & 0 \\ -2 & 0 & 0 & 2 & 0 \\ 8 & -1 & 0 & -7 & 2 \\ -1 & 2 & 2 & 3 & 2 \\ 2 & 2 & 3 & 6 & 4 \end{vmatrix}$$

(L-15) QUESTION 9. Compute
$$\det \mathbf{A} = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 5 & 5 & 0 & 0 \\ 3 & 0 & 1 & 0 \\ 5 & 0 & 0 & 1 \end{bmatrix}$$

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(L-15) QUESTION 12. Consider the following block matrix

$$\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{0} \\ \mathbf{0} & \mathbf{C} \end{bmatrix}$$

Prove $|\mathbf{A}| = |\mathbf{B}||\mathbf{C}|$.

(L-15) QUESTION 13. Solve the following linear systems using Cramer's Rule

(a)
$$\begin{cases} 2x + 5y = 1 \\ x + 4y = 2 \end{cases}$$
(b)
$$\begin{cases} 2x + y = 1 \\ x + 2y + z = 0 \\ y + 2z = 0 \end{cases}$$

(exercise 13 from section 4.4 of Strang (2006))

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(L-15) QUESTION 14. Find the inverse of the following matrices using the *adjoint matrix*

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 0 & 4 & 1 \end{bmatrix}$$

(b) $\mathbf{B} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$

(exercise 18 from section 4.4 of Strang (2006))

(L-15) QUESTION 15. Consider the matrices

$$\mathbf{A} = \begin{bmatrix} 1 & 4 & 2 & 3 \\ 2 & 3 & 3 & 7 \\ 0 & 1 & 0 & 3 \\ 0 & 2 & 0 & a \end{bmatrix}, \ \mathbf{B} = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}; \ \text{and the vector } \boldsymbol{b} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

- (a) $(0.5^{\rm pts})$ For wich values of a the matrix **A** is invertible?
- (b) (1^{pts}) Consider a=5. Using the Cramer's rule, compute the fourth coordinate x_4 of x for linear system $\mathbf{A}x=\mathbf{b}$.
- (c) (1^{pts}) Compute \mathbf{B}^{-1} . Use the matrix \mathbf{B}^{-1} to solve $\mathbf{B}x = b$.

Strang, G. (2006). *Linear algebra and its applications*. Thomson Learning, Inc., fourth ed. ISBN 0-03-010567-6.