## Mathematics II

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1 Highlights of Lesson 15

## Always squared matrices in this topic

## **Highlights of Lesson 15**

- **Eigenvalues, eigenvectors** (prefix eigen is the German word for innate, distinct, self)
- $\bullet \ |\mathbf{A} \lambda \mathbf{I}| = 0$

Characteristic equation

• tr (**A**), det **A** 

(demo in the next lesson)

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You can find the last version of these course materials at

https://github.com/mbujosab/MatematicasII/tree/main/Eng

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2 Eigenvalues and eigenvectors

Consider the equation

$$\mathbf{A} \mathbf{x} = \lambda \mathbf{x}$$
 (with  $\mathbf{x} \neq \mathbf{0}$ )

- *Eigenvalue* is any  $\lambda$  such that there are solutions.
- Such non-null solutions x are called eigenvectors.  $x \neq 0$  such that  $\mathbf{A}x$  is multiple x

When  $\lambda$  is 0, What are the eigenvectors?

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- **3** Example: projection matrix
- Orthogonal projection
- Which vectors are eigenvectors?
   What vectors are projected in the same starting direction?
- What are the eigenvalues of those eigenvectors?
- are there any other eigenvectors? with what eigenvalue?
- Two eigen-spaces

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**5** how to find eigenvalues and eigenvectors?

How to solve

$$\mathbf{A}x = \widehat{\lambda} \stackrel{?}{\underbrace{\lambda}} ?$$

Here's the trick (simple idea). Bring the x s onto the same side  $\dots$ 

$$(\mathbf{A} - \lambda \mathbf{I}) \boldsymbol{x} =$$

idea If  $x \neq 0$  what kind of matrix must be  $(\mathbf{A} - \lambda \mathbf{I})$ ?

and then its determinant must be?  $|\mathbf{A} - \lambda \mathbf{I}| =$ 

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4 Another example: Interchange or swap matrix

$$\mathbf{A} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- A vector that does not change after interchange?
- What is the eigenvalue?
- Is there an eigenvector corresponding to  $\lambda_2 = -1$ ?

$$\mathbf{A}\boldsymbol{x}_2 = -\boldsymbol{x}_2$$

Note:  $\operatorname{tr}(\mathbf{A}) = 0 = \lambda_1 + \lambda_2$ ;  $\det \mathbf{A} = -1 = \lambda_1 \cdot \lambda_2$ .

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- **6** how to find eigenvalues and eigenvectors?
- 1. Eigenvalues are  $\lambda$ 's such that:  $|\mathbf{A} \lambda \mathbf{I}| =$  ( Characteristic polynomial  $P_{\mathbf{A}}(\lambda)$  )
- 2. How to compute x so that  $(\mathbf{A} \lambda \mathbf{I}) x = \mathbf{0}$ ?

Eigenspace (Set of eigenvectors + 0):

$$\mathcal{E}_{\lambda}(\mathbf{A}) = \left\{ \left. oldsymbol{x} \in \mathbb{R}^n 
ight| \mathbf{A} oldsymbol{x} = \lambda oldsymbol{x} 
ight\}$$

*Spectrum*: set  $\{\lambda_1, \dots \lambda_k\}$  of eigenvalues (roots of  $P_{\mathbf{A}}(\lambda)$ )

7 Example (we must compute the eigevalues first!)

We are looking for a null determinant (Characteristic polynomial)

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}; \qquad \det(\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 1 & 3 - \lambda \end{vmatrix} = (3 - \lambda)^2 - 1 = 0$$

Note:  $\operatorname{tr}(\mathbf{A}) = 6 = \lambda_1 + \lambda_2$ ;  $\det \mathbf{A} = 8 = \lambda_1 \cdot \lambda_2$ .

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 $\mathbf{Q} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ 

- How much do the eigenvalues add up to?
- What is the determinant?

## Difficulties

$$\lambda_1 + \lambda_2 = 0 \quad \text{and} \quad \lambda_1 \cdot \lambda_2 = 1 \qquad \qquad (+) \cdot (-) = (+)$$

What kind of vector can be parallel to itself after a  $90^{\circ}$  rotation?

$$\det (\mathbf{Q} - \lambda \mathbf{I}) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 =$$

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8 Example (...and then the eigenspaces)

And now we compute the null space  $\mathcal{N}(\mathbf{A} - \lambda \mathbf{I})$  ... for each  $\lambda$ .

For 
$$\lambda_1 = 4$$

$$(\mathbf{A} - 4\mathbf{I}) = \begin{bmatrix} 3 - 4 & 1 \\ 1 & 3 - 4 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \Rightarrow$$

For 
$$\lambda_2 = 2$$

$$(\mathbf{A} - 2\mathbf{I}) = \begin{bmatrix} 3 - 2 & 1 \\ 1 & 3 - 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow$$

Are they the only two eigenvectors?

$$\mathbf{A} oldsymbol{x}_i = \lambda oldsymbol{x}_i; \qquad egin{bmatrix} 3 & 1 \ 1 & 3 \end{bmatrix} oldsymbol{x}_i = \lambda oldsymbol{x}_i.$$

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**10** There are even worse examples

$$\mathbf{A} = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

Eigenvalues

$$\det (\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} 3 - \lambda & 1 \\ 0 & 3 - \lambda \end{vmatrix} = (3 - \lambda)(3 - \lambda) = 0 \begin{cases} \lambda_1 = 3 \\ \lambda_2 = 3 \end{cases}$$

Eigenvectors

• for 
$$\lambda_1$$
:  $(\mathbf{A} - \lambda \mathbf{I}) \boldsymbol{x} = \mathbf{0} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \boldsymbol{x}_1; \qquad \boldsymbol{x}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ 

• for  $\lambda_2$ :

 $\lambda = 3$  is repeated twice, but  $\dim \mathcal{E}_3(\mathbf{A}) = 1$ 

$$\mu(3) = 2 \neq 1 = \gamma(3)$$

## Summary:

- 1. The eigenvalues are those numbers  $\lambda$  that makes the matrix  $(\mathbf{A} \lambda \mathbf{I})$  singular. In other words, they are the roots of the Characteristic polynomial:  $\det(\mathbf{A} \lambda \mathbf{I})$ .
- 2. Any n by n matrix has a caracteristic polynomial of degree n
- 3. A polynomial of degree n has n roots (perhaps some repeated roots).
- 4. The sum of eigenvalues of a matrix equals its trace
- 5. The product of eigenvalues of a matrix equals its determinant
- 6. The eigenvectors associated with  $\lambda$  are the non-zero vectors in  $\mathcal{N}\left(\mathbf{A}-\lambda\mathbf{I}\right)$ .

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(b)

$$\mathbf{B} = \begin{bmatrix} a & b \\ b & a \end{bmatrix}$$

(?, exercise 12 from section 5.1.)

(L-15) QUESTION 3. If **B** has eigenvalues 1, 2, 3, **C** has eigenvalues 4, 5, 6, and **D** has eigenvalues 7, 8, 9, what are the eigenvalues of the 6 by 6 matrix  $\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{0} & \mathbf{D} \end{bmatrix}$ ? where **B**, **C**, **D** are upper triangular matrices. (?, exercise 13 from section 5.1.)

 $\left(L\text{-}15\right)~\mathrm{QUESTION}~4.$  Find the eigenvalues and eigenvectors of

(a)

$$\mathbf{A} = \begin{bmatrix} 3 & 4 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

(b)

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 2 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

(?, exercise 5 from section 5.1.)

## Questions of the Lecture 15

(L-15) QUESTION 1. Consider the matrix

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$$\mathbf{A} = \begin{bmatrix} -3 & 4 & -4 \\ -3 & 5 & -3 \\ -1 & 2 & 0 \end{bmatrix}$$

(a) The three eigenvalues of  $\bf A$  are -1, 1 and 2; and two of its eigenvectors are

$$v = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}; \qquad w = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

Check that both vectors are eigenvenctors of **A**. What are the corresponding eigenvalues?

(b) Find a third linearly independent eigenvector.

(L-15) QUESTION 2. Find the eigenvalues and eigenvectors of

(a)

$$\mathbf{A} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

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(L-15) QUESTION 5. The eigenvalues of **A** equal the eigenvalues of **A**<sup>T</sup>. This is because  $\det(\mathbf{A} - \lambda \mathbf{I})$  equals  $\det(\mathbf{A}^T - \lambda \mathbf{I})$ .

- (a) That is true because
- (b) Show by an example that, nevertheless, the eigenvectors of A and A<sup>T</sup> are not the same.
- (?, exercise 11 from section 5.1.)

(L-15) QUESTION 6. Consider the matrix **B** and its eigenvector  $\boldsymbol{x}$  associated to the eigenvalue  $\lambda$ , that is  $\mathbf{B}\boldsymbol{x} = \lambda \boldsymbol{x}$ ; and also consider the matrix  $\mathbf{A} = (\mathbf{B} + \alpha \mathbf{I})$ . Prove that  $\boldsymbol{x}$  is also an eigenvector of  $\mathbf{A}$  with eigenvalue  $(\lambda + \alpha)$ .

(L-15) Question 7.

- (a) Encuentre los autovalores y los auto-vectores de la matriz  $\mathbf{A} = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$  Compruebe que la traza es igual a la suma de los autovalores, y que el determinante es igual a su producto.
- (b) Si consideramos una nueva matriz, generada a partir de la anterior como

$$\mathbf{B} = (\mathbf{A} - 7\mathbf{I}) = \begin{bmatrix} -6 & -1 \\ 2 & -3 \end{bmatrix}.$$

¿Cuáles son los autovalores y auto-vectores de la nueva matriz, y como están relacionados con los de  ${\bf A}$ ?

(?, exercise 1 and 3 from section 5.1.)

(L-15) QUESTION 8. Suponga que  $\lambda$  es un auto-valor de  ${\bf A}$ , y que  ${\bf x}$  es un auto-vector tal que  ${\bf A}{\bf x}=\lambda {\bf x}$ .

- (a) Demuestre que ese mismo x es un auto-vector de  $\mathbf{B} = \mathbf{A} 7\mathbf{I}$ , y encuentre el correspondiente auto-valor de  $\mathbf{B}$ .
- (b) Suponga que  $\lambda \neq 0$  ( y que **A** es invertible), demuestre que x también es un auto-vector de  $\mathbf{A}^{-1}$ , y encuentre el correspondiente auto-valor. ¿Qué relación tiene con  $\lambda$ ?

(?, exercise 7 from section 5.1.)

(L-15) QUESTION 9. Suponga que  $\bf A$  es una matriz de dimensiones  $n\times n$ , y que  $\bf A^2=\bf A$ . ¿Qué posibles valores pueden tomar los autovalores de  $\bf A$ ?

(L-15) QUESTION 10. Suponga la matriz  $\mathbf{A}$  con autovalores 1, 2 y 3. Si  $v_1$  es un auto-vector asociado al auto-valor 1,  $v_2$  al auto-valor 2 y  $v_3$  al auto-valor 3; entonces ¿cuanto es  $\mathbf{A}(v_1+v_2-v_3)$ ?

(L-15) QUESTION 11. Proporcione un ejemplo que muestre que los auto-valores pueden cambiar cuando un múltiplo de una columna se resta de otra. ¿Por qué los pasos de eliminación no modifican los autovalores nulos? (?, exercise 6 from section 5.1.)

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(L-15) QUESTION 15. The equation  $(\mathbf{A}^2 - 4\mathbf{I})x = b$  has no solution for some right-hand side b. Give as much information as possible about the eigenvalues of the matrix  $\mathbf{A}$  (the matrix  $\mathbf{A}$  is diagonalizable).

(L-15) QUESTION 16. You are given the matrix

$$\mathbf{A} = \begin{bmatrix} 0.5 & 0.2 & 0.2 \\ 0.1 & 0.5 & 0.5 \\ 0.4 & 0.3 & 0.3 \end{bmatrix}$$

One of the eigenvalues is  $\lambda=1$ . What are the eigenvalues of **A**? [Hint: Very little calculation required! You should be able to see another eigenvalue by inspection of the form of **A**, and the third by an easy calculation. You shouldn't need to compute  $\det(\mathbf{A}-\lambda\mathbf{I})$  unless you really want to do it the hard way.]

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(L-15) QUESTION 12. El polinomio característico de una matriz  ${\bf A}$  se puede factorizar como

$$\det(\mathbf{A} - \lambda \mathbf{I}) = (\lambda_1 - \lambda)(\lambda_2 - \lambda) \cdots (\lambda_n - \lambda).$$

Demuestre, partiendo de esta factorización, que el determinante de  ${\bf A}$  es igual al producto de sus valores propios (autovalores). Para ello haga una elección inteligente del valor de  $\lambda$ .

(?, exercise 8 from section 5.1.)

(L-15) QUESTION 13. Calcule los valores característicos (autovalores o valores propios) y los vectores característicos de  $\bf A$  y  $\bf A^2$ :

$$\mathbf{A} = \begin{bmatrix} -1 & 3 \\ 2 & 0 \end{bmatrix} \qquad \mathbf{y} \qquad \mathbf{A}^2 = \begin{bmatrix} 7 & -3 \\ -2 & 6 \end{bmatrix}$$

 ${\bf A}^2$  tiene los mismos \_\_\_\_\_ que  ${\bf A}$ . Cuando los autovalores de  ${\bf A}$  son  $\lambda_1$  y  $\lambda_2$ , los autovalores de  ${\bf A}^2$  son \_\_\_\_. (?, exercise 22 from section 5.1.)

(L-15) QUESTION 14. Suponga que los valores característicos de  $\mathbf{A}$  son 1, 2 y 4, ¿cuál es la traza de  $\mathbf{A}^2$ ? ¿Cuál es el determinante de  $(\mathbf{A}^{-1})^{\mathsf{T}}$ ? (?, exercise 10 from section 5.2.)

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1 Highlights of Lesson 16

## Highlights of Lesson 16

- Similar matrices:  $\mathbf{C} = \mathbf{S}^{-1}\mathbf{A}\mathbf{S}$
- Triangular block diagonalizing a matrix

• Diagonalizable matrices: when **C** is diagonal.

2 Similar matrices

## **Similarity**

A and C are similar if there is an invertible S such that

$$\mathbf{C} = \mathbf{S}^{-1} \mathbf{A} \mathbf{S}$$

If **A** and **C** are similar (see demos in the book):

- The same determinant:  $\det \mathbf{A} = \det \mathbf{C}$
- The same caracteristic polinomial:  $|\mathbf{A} \lambda \mathbf{I}| = |\mathbf{C} \lambda \mathbf{I}|$
- The same eigenvalues (same algebraic and geometric multiplicities).
- The same trace.

$$\textit{Mirror} \text{ inverse transf.: } \left(\mathbf{I}_{(\tau_1\cdots\tau_k)}\right)^{-1} \ = \ _{esp(\tau_{\scriptscriptstyle L}^{-1}\cdots\tau_{\scriptscriptstyle 1}^{-1})}\mathbf{I}$$

$$\mathbf{I} = \underset{[(-\alpha)\mathbf{j}+\mathbf{i}]}{\mathbf{T}} \underset{[(\alpha)\mathbf{i}+\mathbf{j}]}{\mathbf{T}} = \underset{[\left(\frac{1}{\alpha}\right)\mathbf{j}]}{\mathbf{T}} \underset{[(\alpha)\mathbf{j}]}{\mathbf{T}} \Rightarrow \mathbf{A} \text{ similar to } \underset{esp(\tau_1\cdots\tau_k)^{-1}}{\operatorname{esp}(\tau_1\cdots\tau_k)^{-1}} \mathbf{A}_{\tau_1\cdots\tau_k}$$

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4 Block diagonalizing a matrix (toothed matrix)

Consider 
$$\mathbf{A} = \begin{bmatrix} \mathbf{C} & \| & \| & \mathbf{L} \end{bmatrix} \in \mathbb{C}^{n \times n}$$
 where

**C** (of order m) is singular and **L** is full rank lower triangular, then there exists S = RP (invertible) such that

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3 Block diagonalizing a matrix (toothed matrix)

Consider 
$$\mathbf{A} = \left[ \begin{array}{c|c} \mathbf{C} & \\ \hline * & \mathbf{L} \end{array} \right] \in \mathbb{C}^{n \times n}$$
 where

**C** (of order m) is singular and **L** is full rank lower triangular; then there exists an invertible R such that

 $\left(\dots \frac{\tau}{\left[\left(-\alpha_{j}\right)^{m+j}\right]}\dots\right)^{\mathbf{A}}\left(\dots \frac{\tau}{\left[\left(\alpha_{j}\right)^{j+m}\right]}\dots\right); \qquad \mathbf{j}=1,\dots,m-1.$ 

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**5** A very simple example

## Example

Consider 
$$\mathbf{A}=\begin{bmatrix}1 & -1 & 0\\ 0 & 0 & 0\\ 0 & -2 & 1\end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{\begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\mathbf{0I}} \overset{\textbf{(-)}}{\underset{\mathbf{0}}{\mathbf{0}}} + \underbrace{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \xrightarrow{\begin{bmatrix} (1)1+2 \\ [(2)3+2] \\ [2=3] \\ [2=3] \end{bmatrix}}_{\mathbf{0}} \overset{\textbf{T}}{\underset{[(2)3+2] \\ [(2)3+2] \\ [0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}}_{\mathbf{0}} \xrightarrow{\begin{smallmatrix} \mathbf{T} \\ [2=3] \\ [(-2)2+3] \\ [(-1)2+1] \\ [(-1)2+1] \end{bmatrix}}_{\mathbf{0}} \overset{\textbf{T}}{\underset{\mathbf{0}}{\mathbf{0}}} \overset{\textbf{T}}{\underset{\mathbf{0}}{\mathbf{0}}}$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{\text{diagonal}}$$

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**6** A not so simple example

## Example

Consider 
$$\mathbf{A} = \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix}$$
 with eigenvalues  $\mathbf{1}$ ,  $\mathbf{1}$  and  $\mathbf{0}$ .

$$\begin{array}{c} (-) \\ \hline 11 \\ \hline \end{array} \end{array} \overbrace{ \begin{bmatrix} -3 & 0 & 3 \\ 3 & -3 & -9 \\ -1 & 2 & 5 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+3 \\ [(-2)2+3] \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} -3 & 0 & 0 \\ 3 & -3 & 0 \\ -1 & 2 & 0 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (2)3+2 \\ [(-1)3+1] \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} -2 & -2 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 11 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)1+2 \\ 0 & 0 & 1 \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 3 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 1 & 1 \\ \hline \end{bmatrix} }^{\tau} \overbrace{ \begin{bmatrix} (-1)2+1 \\ 0 & 1 & 1 \\ \hline \end{bmatrix} }^{\tau}$$

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8 Back to the simple, "toothless" example

Consider 
$$\mathbf{A}=\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$
 with eigenvalues 0, 1 and 1.

$$\underbrace{\begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}}_{\mathbf{0}\mathbf{I}} \overset{(-)}{\underset{\mathbf{0}}{\mathbf{0}}} + \underbrace{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{\mathbf{0}} \overset{\tau}{\underset{[2:3]}{\overset{[(1)1+2]}{\underset{[2:3]}{\overset{[(1)1+2]}{\underset{[2:3]}{\overset{[(1)1+2]}{\underset{[0,1]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2]}{\overset{[(1)1+2]}{\underset{[1,1]}{\overset{[(1)1+2$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\mathbf{A}(\mathbf{S}_{|i}) = \lambda_i(\mathbf{S}_{|i}) \quad \Rightarrow \quad \mathbf{S}_{|i}$$
 is an eigenvector.

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**7** Every matrix is similar to a toothed matrix

For every  $\boldsymbol{A}$  there exists  $\boldsymbol{S}$  such that

$$S^{-1}AS = C$$
  $\Rightarrow$   $AS = SC$ 

where **C**, toothed, has the eigenvalues on the diagonal **Example** 

$$\begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -2 & 0 & 3 \\ 3 & -2 & -9 \\ -1 & 2 & 6 \end{bmatrix} \begin{bmatrix} 6 & -1 & 1 \\ -9 & 1 & -2 \\ 4 & 0 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix}}_{\text{toothed}}$$
Consequences

- $\sum \lambda_i = \operatorname{tr} \left( \mathbf{A} 
  ight)$  and  $\prod \lambda_i = \det \mathbf{A}$
- $\mathbf{AS}_{|j} = \mathbf{SC}_{|j}$   $\Rightarrow$  for j such that  $\mathbf{C}_{|j} = \lambda_i \mathbf{I}_{|j}$ :  $\mathbf{A}(\mathbf{S}_{|j}) = \lambda_i (\mathbf{S}_{|j}) \quad \Rightarrow \quad \mathbf{S}_{|j} \text{ is an eigenvector.}$

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9 Diagonalizable matrices

- A matrix is diagonalizable **if and only if** *algebraic* and *geometric* multiplicities are equal for each eigenvalue
- If there are no repeated eigenvalues, there are no "teeth" either
- When there are no repeated eigenvalues  $\mathbf{A}$  is diagonalizable (is sure to have n independent eigenvectors)

## **10** Diagonalizing a matrix

- Find the spectrum:  $\{\lambda_1, \lambda_2, \ldots\}$
- Find the algebraic multiplicity of each eigenvalue:  $\mu(\lambda_i)$

then choose one of these alternatives:

- 1. teething the matrix (implemented in NAcAL)
- 2. ... or for every  $\lambda_i$ 
  - find the eigenspace

$$\mathcal{E}_{\lambda_i}(\mathbf{A}) = \left\{ \left. oldsymbol{x} \in \mathbb{R}^n \right| \mathbf{A} oldsymbol{x} = \lambda_i oldsymbol{x} 
ight\} \ = \ \mathcal{N}(\mathbf{A} - \lambda_i \mathbf{I}).$$

ullet check  $\mu(\lambda_i)=\dim\mathcal{E}_{\lambda_i}(\mathbf{A})$  (algebraic and geometric multiplicities are equal)

$$\mathbf{D} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_k \end{bmatrix}; \quad \mathbf{S} = \begin{bmatrix} \mathsf{Basis} \ \mathsf{for} \ \mathcal{E}_{\lambda_1}(\mathbf{A}) \# \cdots \# \mathsf{Basis} \ \mathsf{for} \ \mathcal{E}_{\lambda_k}(\mathbf{A}) \end{bmatrix}$$

$$S^{-1}AS = D \Leftrightarrow A = SDS^{-1}$$

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Questions of the Lecture 16

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(L-16) QUESTION 1. Factor these two matrices into SDS<sup>-1</sup>;

(a) 
$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

(b) 
$$\mathbf{B} = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

(?, exercise 15 from section 5.2.)

(L-16) QUESTION 2. Which of these matrices cannot be diagonalized?

(a)

$$\mathbf{A}_1 = \begin{bmatrix} 2 & -2 \\ 2 & -2 \end{bmatrix}$$

(b)

$$\mathbf{A}_2 = \begin{bmatrix} 2 & 0 \\ 2 & -2 \end{bmatrix}$$

(c)

$$\mathbf{A}_3 = \begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix}$$

(?, exercise 5 from section 5.2.)

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11 Matrix powers

If  $\mathbf{A}x = \lambda x$  then  $\mathbf{A}^2 x = \mathbf{A} \mathbf{A} x = \mathbf{A}(\lambda x) = \lambda \mathbf{A} x = \mathbf{A}(\lambda x)$ 

- What can I say about the eigenvectors?
- What is the relationship between the eigenvalues of A and those of  $\mathbf{A}^2$

In a matrix form (if **A** is diagonalizable,  $\mathbf{A} = \mathbf{SDS}^{-1}$ ):

$$A^2 = SDS^{-1}SDS^{-1} = SD^2S^{-1}$$

In general, for,  $n \in \mathbb{Z}$ , n > 0,...  $\mathbf{A}^n =$ what about A both diagonalizable and invertible?

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(L-16) QUESTION 3. If  ${\bf A}=\begin{bmatrix} 4 & 3 \\ 1 & 2 \end{bmatrix}$  find  ${\bf A}^{100}$  by diagonalizing  ${\bf A}$ . (?, exercise 7 from section  $5.\overline{2}$ .)

(L-16) QUESTION 4. If the eigenvalues of  $\,$  A  $\,$  are 1, 1 and 2, which of the following are certain to be true? Give a reason if true or a counterexample if false:

- (a) A is invertible.
- (b) A is diagonalizable.
- (c) A is not diagonalizable
- (?. exercise 11 from section 5.2.)

(L-16) QUESTION 5. Let **A** be the matrix

$$\mathbf{A} = \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 1 & 0 & 0 & 2 \end{bmatrix}$$

- (a) (1<sup>pts</sup>) Determine if **A** is diagonalizable, and if so, diagonalize it.
- (b)  $(0.5^{\text{pts}})$  Compute  $(\mathbf{A}^6)\mathbf{v}$ , where  $\mathbf{v} = (0, 0, 0, 1)$ .
- (c)  $(0.5^{\text{pts}})$  Using the the eigenvalues found in part (a) justify that **A** is invertible.
- (d)  $(0.5^{pts})$  What is the relation between the eigenvalues of **A** and the eigenvalues of  $\dot{\mathbf{A}}^{-1}$ ?

(L-16) QUESTION 6. Si  $A = SDS^{-1}$ ; entonces  $A^3 = ($  )( )  $A^{-1} = ($  )( )( ). (?, exercise 16 from section 5.2.)

(L-16) QUESTION 7. Considere la matriz

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$$

- (a) Encuentre los autovalores de A
- (b) Encuentre los auto-vectores de A
- (c) Diagonalice **A**: escríbalo como  $\mathbf{A} = \mathbf{SDS}^{-1}$ .

(L-16) QUESTION 8. ¿Falso o verdadero? Si los autovalores de **A** son 2, 2 y 3 entonces sabemos que la matriz es

- (a) Invertible
- (b) Diagonalizable
- (c) No diagonalizable.

(L-16) QUESTION 9. Sean las matrices

$$\mathbf{A}_1 = \begin{bmatrix} 8 & \\ & 2 \end{bmatrix}; \qquad \mathbf{A}_2 = \begin{bmatrix} 9 & 4 \\ & 1 \end{bmatrix}; \qquad \mathbf{A}_3 = \begin{bmatrix} 10 & 5 \\ -5 & \end{bmatrix}$$

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- (a) Encuentre los autovalores y auto-vectores de la matriz  $\mathbf{A}=\begin{bmatrix}1&0&0\\-2&1&0\\1&0&1\end{bmatrix}$  .
- (b) Explique por qué (o por qué no) la matriz A es diagonalizable.

(L-16) QUESTION 14. Sea **A** una matriz  $3\times 3$ . Asuma que sus autovalores son 1 y 0, que una base de los autovectores asociados a  $\lambda=1$  son [1,0,1] y [0,0,1]; mientras que los asociados a  $\lambda=0$  son paralelos a [1,1,2].

- (a) ¿Es A diagonalizable? En caso afirmativo escriba la matriz diagonal  $\bf D$  y la matriz  $\bf S$  tales que  $\bf A = \bf S \bf D \bf S^{-1}$ .
- (b) Encuentre A.

(L-16) QUESTION 15. Let  $\bf A$  be a  $2\times 2$  matrix such that  $\begin{pmatrix} 2\\0 \end{pmatrix}$  is an eigenvector for  $\bf A$  with eigenvalue 2, and  $\begin{pmatrix} 2\\-1 \end{pmatrix}$  is another eigenvector for  $\bf A$  with eigenvalue -2. If  ${\bf v}=\begin{pmatrix} 1\\-1 \end{pmatrix}$ , compute  $\begin{pmatrix} {\bf A}^3 \end{pmatrix} {\bf v}$ .

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- (a) Complete dichas matrices de modo que en los tres casos  $\det \mathbf{A}_i = 25$ . Así, la traza es en todos los casos igual a 10, y por tanto para las tres matrices el único auto-valor  $\lambda = 5$  está repetido dos veces ( $\lambda^2 = 25$  y  $\lambda + \lambda = 10$  implica  $\lambda = 5$ ).
- (b) Encuentre un vector característico con  $\mathbf{A}x=5x$ . Estas tres matrices no son diagonalizable porque no hay un segundo auto-vector linealmente independiente del primero.

(?, exercise 27 from section 5.2.)

(L-16) QUESTION 10. Factorice las siguientes matrices en S D  $S^{-1}$ 

(a) 
$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$
  
(b)  $\mathbf{B} = \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix}$ 

(?, exercise 1 from section 5.2.)

(L-16) QUESTION 11. Encuentre la matriz **A** cuyos autovalores son 1 y 4, cuyos autovectores son  $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$  y  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  respectivamente. (?, exercise 2 from section 5.2.)

(L-16) QUESTION 12. Si los elementos diagonales de una matriz triangular superior de orden  $3\times3$  son 1, 2 y 7, ¿puede saber si la matriz es diagonalizable? ¿Quién es **D**? (?, exercise 4 from section 5.2.)

(L-16) QUESTION 13.

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1 Highlights of Lesson 17

## Highlights of Lesson 17

- Symetric matrices  $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$ 
  - Eigenvalues and eigenvectors
- Introd. positive Definiteness matrices

# **2** Symmetric matrices $\mathbf{A} = \mathbf{A}^{\mathsf{T}}$

what's special about  $\mathbf{A} oldsymbol{x} = \lambda oldsymbol{x}$  when  $oldsymbol{\mathbf{A}}_{n imes n}$  is symmetric?

- 1. A symmetric matrix has only REAL EIGENVALUES
- 2. n EIGENVECTORS can be choosen ORTHOGONAL

(always diagonalizable)

The usual diagonalizable case:

$$S^{-1}AS = D \longleftrightarrow A = SDS^{-1}$$

## Symmetric case:

I can choose perpendicular unit eigenvectors (ortho*normal* columns of  $\mathbf{S} = \mathbf{Q}$ )

(if 
$$\mathbf{A} = \mathbf{A}^{\mathsf{T}}$$
)  $\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}}$  Spectral thm.

Orthogonally diagonalizable.

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4 Quadratic forms

## Quadratic form:

$$xAx$$
; with  $A^{T} = A$ 

Since  $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$  (with  $\mathbf{Q}^{\mathsf{T}} \mathbf{Q} = \mathbf{Q} \mathbf{Q}^{\mathsf{T}} = \mathbf{I}$ ), then

$$x A x = x Q D Q^{\mathsf{T}} x = (Q^{\mathsf{T}} x) D (Q^{\mathsf{T}} x)$$
 (weighted sum of squares)

## Positive definite quadratic form:

$$x\mathbf{A}x > 0 \quad \forall x \neq \mathbf{0} \qquad \Longleftrightarrow \qquad \lambda_i > 0, \quad i = 1:n.$$

then we also say **A** is positive definite.

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3 Eigenspaces are orthogonal for symmetric matrices

Eigenvectors (corresponding to different eigenvalues) of a symmetric matrix are orthogonal.

#### Proof.

Consider  $\mathbf{A}x = \lambda_1 x$  and  $\mathbf{A}y = \lambda_2 y$  (with  $\lambda_1 \neq \lambda_2$ ). then

$$\lambda_1 \boldsymbol{x} \cdot \boldsymbol{y} = \mathbf{A} \boldsymbol{x} \cdot \boldsymbol{y} = \boldsymbol{x} (\mathbf{A}^\intercal) \boldsymbol{y} = \boldsymbol{x} \mathbf{A} \boldsymbol{y} = (\boldsymbol{x} \cdot \boldsymbol{y}) \lambda_2.$$

Since  $\lambda_1 \neq \lambda_2$  then:

$$\lambda_1(\boldsymbol{x}\cdot\boldsymbol{y}) - \lambda_2(\boldsymbol{x}\cdot\boldsymbol{y}) = 0 \implies (\lambda_1 - \lambda_2)\boldsymbol{x}\cdot\boldsymbol{y} = 0 \implies \boldsymbol{x}\cdot\boldsymbol{y} = 0.$$

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5 Positive definite matrices

#### Meaning:

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 (except for  $\boldsymbol{x} = \mathbf{0}$ )

#### Some properties

Consider a positive definite symmetric A: What about  $A^{-1}$ ?

$$\mathbf{A} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{-}1} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\text{T}}$$

Consider two positive definite symmetric matrices A, B: What about A + B?

the answer must be...

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**6** The matrix product **A**<sup>T</sup>**A** 

Consider the rectangular matrix  $\mathbf{A}$ . Is  $\mathbf{A}^{\mathsf{T}}\mathbf{A}$  positive definite?

$$\boldsymbol{x}(\mathbf{A}^{\intercal}\mathbf{A})\boldsymbol{x} =$$

It can only be 0 when  $\mathbf{A}x$  is  $\mathbf{0}$ 

How can we guarantee that  $\mathbf{A}x \neq \mathbf{0}$  when  $x \neq \mathbf{0}$ ?

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8 Positive definite symmetric matrices

- All eigenvalues are:
- All pivots are:

$$\begin{bmatrix} 5 & 2 \\ 2 & 3 \end{bmatrix}$$

**Pivots:** 

What is the sign of each eigenvalue?

$$\lambda^2 - 8\lambda + 11 = 0 \rightarrow \lambda = 4 \pm \sqrt{5} > 0$$

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7 Symmetric matrices: signs of eigenvalues

are all  $\lambda_i$  positive? are they negative?

Computing eigenvalues of  ${\bf A}$  is impossible in general! (5th degree polynomial)

**Good news:** The signs of the pivots of echelon form are the same as the signs of the eigenvalues  $\lambda_i$  (if we do not change the sign of the determinant with *Type II* elementary transformations)

num. of positive pivots = num. of positive eigenvalues

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**Summary** (for symmetric matrices):

- 1. Symmetric matrices have *real eigenvalues* and *perpendicular eigenvectors* can be choosen
- 2.  $\mathbf{A} = \mathbf{Q} \mathbf{D} \mathbf{Q}^{\mathsf{T}}$  where  $\mathbf{Q}$  is orthogonal
- 3. A is symmetric if and only if it is *orthogonally* diagonalizable
- 4. The signs of the pivots in the echelon form are same as the signs of the eigenvalues  $\lambda_i$  (only if we do not change the sign of the determinant with  $Type\ II$  elementary transformations)

## **Questions of the Lecture 17**

(L-17) QUESTION 1. Write A, B and C in the form  $QDQ^T$  of the spectral theorem:

(a) 
$$\mathbf{A} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

(b) 
$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(c) 
$$\mathbf{C} = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}$$

(?, exercise 11 from section 5.5.)

(L-17) QUESTION 2. Find the eigenvalues and the unit eigenvectors of

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

(?, exercise 3 from section 6.4.)

(L-17) QUESTION 3. Find an orthonormal **Q** that diagonalizes this symmetric matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{bmatrix}$$

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(L-17) QUESTION 6. Sean

- (a) Encuentre los valores característicos de **A** (recuerde que  $i^2 = -1$ ).
- (b) Encuentre los valores característicos de B (en este caso quizá le resulte más sencillo encontrar primero los autovectores, y deducir entonces los autovalores).
- (c) De los siguientes tipos de matrices: ortogonales, invertibles, permutación, hermíticas, de rango 1. diagonalizables, de Markov ¿a qué tipos pertenece A?
- (d) ¿y **B**?

(?, exercise 14 from section 5.5.)

(L-17) QUESTION 7. Si  ${\bf A}^3={\bf 0}$  entonces los autovalores de  ${\bf A}$  deben ser \_\_\_\_\_. De un ejemplo tal que  ${\bf A}\neq{\bf 0}$ . Ahora bien, si  ${\bf A}$  es además simétrica, demuestre que entonces  ${\bf A}^3$  es necesariamente  ${\bf 0}$ .

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(?, exercise 5 from section 6.4.)

(L-17) QUESTION 4. Suppose A is a symmetric 3 by 3 matrix with eigenvalues 0, 1,2.

- (a) What properties can be guaranteed for the corresponding unit eigenvectors  $u,\,v$  and w
- (b) In terms of u, v, w, describe the nullspace, left nullspace, row space, and column space of  $\mathbf{A}$ .
- (c) Find a vector x that satisfies Ax = v + w. Is x unique?
- (d) Under what conditions on b does Ax = b have a solution?
- (e) If u, v, w are the columns of S, what are  $S^{-1}$  and  $S^{-1}AS$ .
- (?, exercise 13 from section 5.5.)

(L-17) QUESTION 5. Escriba un hecho destacado sobre los valores característicos de cada uno de estos tipos de matrices:

- (a) Una matriz simétrica real.
- (b) Una matriz diagonalizable tal que  $\mathbf{A}^n \to \mathbf{0}$  cuando  $n \to \infty$ .
- (c) Una matriz no diagonalizable
- (d) Una matriz singular
- (?, exercise 16 from section 5.5.)

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(L-17) QUESTION 8. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} a & 1 & 1 \\ 0 & 3 & 1 \\ 0 & 0 & 2 \end{bmatrix}.$$

- (a) Prove that **A** is not diagonalizable when a=3.
- (b) Is **A** diagonalizable when a=2? (explain). If it is diagonalizable, find an eigenvalue diagonal matrix **D** and an eigenvector matrix **S** such as  $\mathbf{A} = \mathbf{SDS}^{-1}$ .
- (c) Is A<sup>T</sup>A diagonalizable for any value a? Is it possible to find a full set of orthonormal eigenvectors of A<sup>T</sup>A?
- (d) Find all posible values a such as **A** is invertible and diagonalizable.
- (L-17) QUESTION 9. Sea la matriz

$$\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix};$$

- (a) Exprese B en la forma  $B = A = QDQ^{T}$  del teorema espectral.
- (b) ¿Es B diagonalizable? Si no lo es, diga las razones; y en caso contrario genere una matriz S que diagonalice a B.

1 Highlights of Lesson 18

## **Highlights of Lesson 18**

- Positive and Negative (semi)definite matrices
- Completing the squares
- Diagonalization by congruence

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## Example

What number do I have to put there for the matrix **A** to be singular?

$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix}$$

- Eigenvalues:
- Leading principal minors:
- For the following quadratic form

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + y^2$$

Is there a  ${m x} \neq {m 0}$  such that  ${m x} {m A} {m x} = 0$ ?

2 Our direction forms

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2 Quadratic forms

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- Positive definite:  $\forall x \neq 0 \Rightarrow xAx > 0$ .
- Positive semi-definite:  $\forall x \neq 0 \Rightarrow x \land x \geq 0$ .
- Negative definite:  $\forall x \neq 0 \Rightarrow x A x < 0$ .
- Negative semi-definite:  $\forall x \neq 0 \Rightarrow x \land x \leq 0$ .
- Indefinite: neither positive semi-definite, nor negative semi-definite.

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#### **Example**

If 
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & \mathbf{7} \end{bmatrix}$$
 then  $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 7 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + \mathbf{?} y^2$ 

- Are there numbers x and y that make xAx negative?
- Does the function go through the origin?
- When y = 0 and x = 1, is it possitive? (and when x = -1?)
- When x = 0 and y = 1, is it possitive? (and when y = -1?)
- Is it always positive?

(0,0,) saddle  $\mbox{point}\colon$  minimum in some directions, maximum in others.

$$\lambda_1 = -2, \quad \begin{pmatrix} -6\\4 \end{pmatrix}; \qquad \lambda_1 = 11, \quad \begin{pmatrix} 6\\9 \end{pmatrix}$$

## **Example**

If 
$$\mathbf{A} = \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix}$$
 then  $\begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 2x^2 + 12xy + 20y^2$ 

#### Positive definite.

Does it pass the tests?

- Are the leading principal minors positive?
- Are the eigenvalues positive?

$$q_{\mathbf{A}}(\boldsymbol{x}) = \boldsymbol{x} \mathbf{A} \boldsymbol{x} > 0$$
 for all  $\boldsymbol{x} \neq \mathbf{0}$ 

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## 4 Congruent matrices

 $\boldsymbol{A}$  and  $\boldsymbol{C}$  are congruent if there exists an invertible  $\boldsymbol{B}$  such that  $\boxed{\boldsymbol{C} = \boldsymbol{B}^{\mathsf{T}}\boldsymbol{A}\boldsymbol{B}}$ 

## Diagonalization by congruence

For each **A** (symmetric) exists  $\mathbf{B} = \mathbf{I}_{ au_1 \cdots au_k}$  (invertible) such that

$$\mathbf{D} = \mathbf{B}^{\mathsf{T}} \mathbf{A} \mathbf{B}$$
 is diagonal  $(\mathbf{B}^{\mathsf{T}} = {}_{\tau_{\iota} \cdots \tau_{1}} \mathbf{I})$ 

Spectral Theorem: ¡Diagonalization by similarity and congruence!

$$\mathbf{D} = \mathbf{Q}^{-1} \mathbf{A} \mathbf{Q} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}.$$

Hence, every quadratic form can be written as a sum of squares

$$x \mathbf{A} x = x (\mathbf{B}^{-1})^{\mathsf{T}} \mathbf{D} \mathbf{B}^{-1} x = y \mathbf{D} y;$$
 where  $y = \mathbf{B}^{-1} x$ .

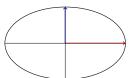
## **3** Completing the squares

If we could express q(x) as a sum of squares, we would know whether q(x) is positive definite.

Let's complete the square!

- $q(x,y) = 2x^2 + 12xy + 20y^2 = 2(x + ?y)^2 + ?$
- $q(x,y) = 2x^2 + 12xy + 7y^2$
- $q(x,y) = 2x^2 + 12xy + 18y^2$
- $q(x,y) = 2x^2 + 12xy + 200y^2$  (graph)

If positive definite: q(x,y) = a; a > 0: ellipse



is  $q(x,y,z,w,t) = 2t^2 - 2tx - 2tz + w^2 - 2wy + 2x^2 - 2xy + 2y^2 + z^2$ 

positive definite? ② ② ② ② ② !!!????

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# **5** Completing the squares

$$2x^2 + 12xy + 20y^2$$

$$\begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \xrightarrow{[(-3)\mathbf{1}+\mathbf{2}]} \begin{bmatrix} \mathbf{2} & 0 \\ 6 & 2 \end{bmatrix} \xrightarrow{\boldsymbol{\tau}} \begin{bmatrix} \mathbf{2} & 0 \\ 0 & 2 \end{bmatrix};$$

therefore, we get:

$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \mathbf{D} = \mathbf{E}^{\mathsf{T}} \mathbf{A} \mathbf{E} = \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 6 \\ 6 & 20 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}$$

hence  $\mathbf{A} = (\mathbf{E}^{\intercal})^{-1} \mathbf{D} \mathbf{E}^{-1}$  so

$$\boldsymbol{x} \mathbf{A} \boldsymbol{x} = \begin{pmatrix} x, & y, \end{pmatrix} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \boldsymbol{x} (\mathbf{E}^{-1})^{\mathsf{T}} \end{pmatrix} \mathbf{D} \begin{pmatrix} \mathbf{E}^{-1} \boldsymbol{x} \end{pmatrix}$$
$$= \begin{pmatrix} (x+3y), & y, \end{pmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{pmatrix} (x+3y) \\ y \end{pmatrix} = 2(x+3y)^2 + 2y^2$$

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**6** example 3 by 3

Is 
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$
 positive definite?

$$\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{1}{2}\right)\mathbf{1}+\mathbf{2}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{1}{2}\right)\mathbf{1}+\mathbf{2}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & -1 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow[\left(\frac{2}{3}\right)\mathbf{2}+\mathbf{3}]{\boldsymbol{\tau}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & \frac{3}{2} & 0 \\ 0 & 0 & \frac{4}{3} \end{bmatrix}$$

$$x\mathbf{A}x = 2x^2 + 2y^2 + 2z^2 - 2xy - 2yz > 0$$

 $x \mathbf{A} x = 1$ : (ellipsoid) axes are eigenvectors  $\mathbf{A} = \mathbf{Q}^{\mathsf{T}} \lambda \mathbf{Q}$ 

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8 Another example 3 by 3

Is  $\mathbf{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$  positive definite?

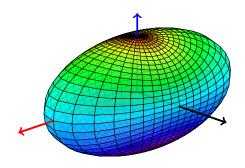
$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(1)3+1]{\textbf{7}} \begin{bmatrix} 2 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \xrightarrow[[(-\frac{1}{2})1+3]{\textbf{7}} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} \xrightarrow[\textbf{2}=3]{\textbf{2}=3} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Indefinite matrix

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7 Positive definite matrices and ellipsoids: example 3 by 3

- The region (xAx = a) is an (ellipsoid).
- The eigenvectors of Q are in the direction of the three principal axes.
- Lengths of axes determined by the eigenvalues



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9 "Classification" of quadratic

$$x \mathbf{A} x \stackrel{\leq}{=} 0; \quad \text{for all } x \neq \mathbf{0}$$

#### Methods

Check the signs of

- 1. Elem. diag.:  $D = B^{T}AB$  (Diagonalization by congruence)
- 2. Computing eigenvalues: (Roots of a polynomial) ©
- 3. Leading principal minors: (Sylvester's criterion) ②

#### Law of inertia

the number of positive, negative and zero entries of the diagonal of  $\mathbf{D}$  is an invariant of  $\mathbf{A}$ , i.e. it does not depend on  $\mathbf{B}$  (Orthogonal diagonalization  $\mathbf{D} = \mathbf{Q}^{\mathsf{T}} \mathbf{A} \mathbf{Q}$  is a special case)

## **Questions of the Lecture 18**

(L-18) QUESTION 1. Decide for or against the positive definiteness of these matrices, and write out the corresponding quadratic form  $f=x\mathbf{A}x$ :

- (a)  $\begin{bmatrix} 1 & 3 \\ 3 & 5 \end{bmatrix}$
- (b)  $\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$
- (c)  $\begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$
- (d)  $\begin{bmatrix} -1 & 2 \\ 2 & -8 \end{bmatrix}$
- (e) The determinant in (b) is zero; along what line is f(x,y) = 0?
- (?, exercise 2 from section 6.1.)

(L-18) QUESTION 2. What is the quadratic  $f=ax^2+2bxy+cy^2$  for each of these matrices? Complete the square to write f as a sum of one or two squares  $d_1(-)^2+d_2(-)^2$ .

- (a)  $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$
- (b)  $\mathbf{B} = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$

(?, exercise 15 from section 6.1.)

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(L-18) QUESTION 6. Consider the following quadratic forms

$$q_1(x, y, z) = x^2 + 4y^2 + 5z^2 - 4xy.$$
  

$$q_2(x, y, z) = -x^2 + 4y^2 + z^2 + 2xy - 2axz.$$

- (a) Show that  $q_1(x, y, z)$  is positive semi-definite.
- (b) Find, if it is possible, any value of a such as  $q_2(x,y,z)$  is negative definite.

(L-18) QUESTION 7. Decide for or against the positive definiteness of

(a) 
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -1 & -1 \end{bmatrix}$$

(b) 
$$\mathbf{B} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & 1 \\ -1 & 1 & 2 \end{bmatrix}$$

(c) 
$$\mathbf{C} = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{bmatrix}^2$$

(?, exercise 2 from section 6.2.)

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(L-18) QUESTION 3. Which one of the following matrices has two positive eigenvalues? Test a>0 and  $ac>b^2$ , don't compute the eigenvalues.  $x\mathbf{A}x<0$ .

- (a)  $\mathbf{A} = \begin{bmatrix} 5 & 6 \\ 6 & 7 \end{bmatrix}$
- (b)  $\mathbf{B} = \begin{bmatrix} -1 & -2 \\ -2 & -5 \end{bmatrix}$
- (c)  $\mathbf{C} = \begin{bmatrix} 1 & 10 \\ 10 & 100 \end{bmatrix}$
- (d)  $\mathbf{D} = \begin{bmatrix} 1 & 10 \\ 10 & 101 \end{bmatrix}$

(?, exercise 14 from section 6.1.)

(L-18) QUESTION 4. Show that  $f(x,y)=x^2+4xy+3y^2$  does not have a minimum at (0,0) even though it has positive coefficients. Write f(x,y) as a difference of squares and find a point (x,y) where f(x,y) is negative. (?, exercise 16 from section 6.1.)

(L-18) QUESTION 5. Show from the eigenvalues that if  ${\bf A}$  is positive definite, so is  ${\bf A}^2$  and so is  ${\bf A}^{-1}$ .

(?, exercise 4 from section 6.2.)

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(L-18) QUESTION 8. Consider the following quadratic form

$$q(x, y, z) = x^2 + 6xy + y^2 + az^2;$$

Decide for which values a the quadratic form is positive definite, negative definite, semidefinite, or indefinite.

(L-18) QUESTION 9. Si  $\mathbf{A}=\left[\begin{smallmatrix}a&b\\b&d\end{smallmatrix}\right]$  es definida positiva, pruebe que  $\mathbf{A}^{\text{-}1}$  es definida positiva.

(?, exercise 8 from section 6.1.)

(L-18) QUESTION 10. Si una matriz simétrica de 2 por 2 satisface a>0, y  $ac>b^2$ , demuestre que sus autovalores son reales y positivos (definida positiva). Emplee la ecuación característica y el hecho de que el producto de los autovalores es igual al determinante.

(?, exercise 3 from section 6.1.)

(L-18) QUESTION 11. Decida si las siguientes matrices son definidas positivas, definidas negativas, semi-definidas, o indefinidas.

(a) 
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 4 \\ 3 & 4 & 9 \end{bmatrix}$$
  
(b)  $\mathbf{B} = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 6 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 3 \end{bmatrix}$   
(c)  $\mathbf{C} = -\mathbf{B}$   
(d)  $\mathbf{D} = \mathbf{A}^{-1}$ 

(L-18) QUESTION 12. Una matriz definida positiva no puede tener un cero (o incluso peor; un número negativo) en su diagonal principal. Demuestre que esta matriz no cumple  $x\mathbf{A}x > 0$ , para todo  $x \neq 0$ :

$$\begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{bmatrix} 4 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 2 & 5 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad \text{no es positiva cuando} \quad \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} = \begin{pmatrix} & & & \\ & & & \end{pmatrix}$$

(?, exercise 21 from section 6.2.)

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(L-18) QUESTION 16. Consider the following matrices

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & a & 0 \\ 0 & 0 & a & a \end{bmatrix} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

- (a)  $(0.5^{\text{pts}})$  Compute the eigenvalues of **A**.
- (b)  $(0.5^{\text{pts}})$  Prove that when a=2 the matrix **A** is not diagonalisable.
- (c)  $(1^{pts})$  For matrix B, find a diagonal matrix D and an orthonormal matrix P such as  $B = PDP^T$
- (d)  $(0.5^{\rm pts})$  Find the quadratic form f(x,y,z) associated to  ${\bf B}$ , and prove it is positive defined.

(L-18) QUESTION 17. Given the matrix  $\mathbf{A} = \begin{pmatrix} a & 3/5 \\ b & 4/5 \end{pmatrix}$ , compute the values (if they exist) of a and b such as

- (a)  $(0.5^{pts})$  **A** is ortho-normal.
- (b)  $(0.5^{\text{pts}})$  Columns of **A** are linearly independent.
- (c)  $(0.5^{\text{pts}}) \lambda = 0$  is an eigenvalue of **A**.
- (d)  $(0.5^{pts})$  **A** is a symmetric definite negative matrix.

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(L-18) QUESTION 13. Demuestre que si  $\bf A$  y  $\bf B$  son definidas positivas entonces  $\bf A+\bf B$  también es definida positiva. Para esta demostración los pivotes y los valores característicos no son convenientes. Es mejor emplear  $\bf x(\bf A+\bf B)x>0$  (?, exercise 5 from section 6.2.)

(L-18) QUESTION 14. Find the  $\dot{\textbf{L}}\textbf{D}\dot{\textbf{L}}^\intercal$  factorization for the following symmetric matrices.

(a)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix}$$

(b)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 3 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

(L-18) QUESTION 15. La forma cuadrática  $f(x,y)=3(x+2y)^2+4y^2$  es definida positiva. Encuentre la matriz **A**, factorícela en **LDL**<sup>T</sup>, y relacione los elementos en **D** y **L** con 3, 2 y 4 en f. (?, exercise 9 from section 6.1.)

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(L-18) Question 18.

- (a) Consider the quadratic form  $q(x,y,z)=x^2+2xy+ay^2+8z^2$  and find its corresponding symmetric matrix  $\mathbf{Q}$ ; determine if  $\mathbf{Q}$  is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite when the parameter a is equal to one (a=1).
- (b) If  $a \neq 1$ , determine whether the matrix is positive-definite, positive-semidefinite, negative-definite, negative-semidefinite or indefinite.

## **Questions of the Optional Lecture 2**

(L-OPT-2) QUESTION 1. Consider the following matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & a & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

- (a)  $(0.5^{\text{pts}})$  Prove **A** is invertible if and only if  $a \neq 0$ .
- (b)  $(0.5^{pts})$  Is **A** positive definite when a=1? Explain your answer.
- (c)  $(1^{\text{pts}})$  Compute  $\mathbf{A}^{-1}$  when a=2.
- (d) (0.5<sup>pts</sup>) How many variables can be chosen as pivot (or exogenous) variables in the system  $\mathbf{A}x = \mathbf{o}$  when a = 0? Which ones?

(L-OPT-2) QUESTION 2. True or false (to receive full credit you must explain your answers in a clear and concise way)

- (a) If **A** is symmetric, then so it is  $A^2$ .
- (b) If  $\mathbf{A}^2 = \mathbf{A}$  then  $(\mathbf{I} \mathbf{A})^2 = (\mathbf{I} \mathbf{A})$  where  $\mathbf{I}$  is the identity matrix.
- (c) If  $\lambda=0$  is an eigenvalue of the squared matrix **A**, then the linear system  $\mathbf{A}x=\mathbf{0}$  is is always solvable and has only one solution.
- (d) If  $\lambda=0$  is an eigenvalue of the squared matrix **A**, then the linear system  $\mathbf{A}x=b$  could be unsolvable.
- (e) If a matrix is orthogonal (perpendicular columns of norm one), then so it is the inverse of that matrix.

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(L-OPT-2) QUESTION 4. En las preguntas siguientes  $\bf A$  y  $\bf B$  son matrices  $n \times n$ . Indique si las siguientes afirmaciones son verdaderas o falsas (incluya una breve explicación, o un contra ejemplo que justifique su respuesta):

- (a) Si A no es cero entonces  $det(A) \neq 0$
- (b) Si  $det(AB) \neq 0$  entonces A es invertible.
- (c) Si intercambio las dos primeras filas de A sus autovalores cambian.
- (d) Si A es real y simétrica, entonces sus autovalores son reales (aquí no es necesaria una justificación).
- (e) Si la forma reducida de echelon de  $({\bf A}-5{\bf I})$  es la matriz identidad, entonces 5 no es un autovalor de  ${\bf A}$ .
- (f) Sea  ${m b}$  un vector columna de  $\mathbb{R}^n$ . Si el sistema  ${f A}{m x}={m b}$  no tiene solución, entonces  $\det({f A}) 
  eq 0$
- (g) Sea C de orden  $3 \times 5$ . El rango de C puede ser 4.
- (h) Sea C de orden  $n \times m$ , y b un vector columna de  $\mathbb{R}^n$ . Si  $\mathbf{C} x = b$  no tiene solución, entonces  $\operatorname{rg}(\mathbf{C}) < n$ .
- (i) Toda matriz diagonalizable es invertible.
- (j) Si A es invertible, entonces su forma reducida de echelon es la matriz identidad.

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(f) If 1 is the only eigenvalue of a  $2\times 2$  matrix  ${\bf A}$ , then  ${\bf A}$  must be the identity matrix

(L-OPT-2) QUESTION 3. complete los blancos, o responda Verdadero/Falso.

- (a) Cualquier sistema generador de un espacio vectorial contiene una base del espacio  $(\mathsf{V}/\mathsf{F})$
- (b) Que los vectores  $v_1, v_2, \ldots, v_n$  sean linealmente independientes significa que
- (c) El conjunto que sólo contiene el vector  ${\bf 0}$  es un conjunto linealmente independiente. (V/F)
- (d) Una matriz cuadrada de orden n por n es diagonalizable cuando:

(e) Si 
$$u = (1, 2, -1, 1)$$
, entonces  $||u|| =$ \_\_\_\_\_\_

(f) Si 
$$u = (1, 2, -1, 1)$$
 y  $v = (-2, 1, 0, 0)$ , entonces  $u \cdot v =$ 

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(L-OPT-2) QUESTION 5. Sean

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 4 \\ 0 & 0 & 5 \end{bmatrix}; \quad \mathbf{B} = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}; \quad \mathbf{C} = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 0 & 4 \\ 0 & 0 & 6 \end{bmatrix}; \quad \mathbf{D} = \begin{bmatrix} 2 & 3 & 0 \\ 3 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Los autovalores de  ${\bf B}$  son 0 y 2. Use esta información para responder a las siguientes cuestiones. Para cada matriz debe dar una explicación. Puede haber más de una matriz que cumpla la condición:

- (a) ¿ Qué matrices son invertibles?
- (b) ¿Qué matrices tienen un autovalor repetido?
- (c) ¿Qué matrices tienen rango menor a tres?
- (d) ¿ Qué matrices son diagonalizables?
- (e) ¿Para qué matrices diagonalizables podemos encontrar tres autovectores ortogonales entre si?

(L-OPT-2) QUESTION 6. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix}$$

- (a) Find the eigenvalues and eigenvectors of A.
- (b) Is A diagonalizable?

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- (c) Is it possible to find a matrix P such as  $A = PDP^{T}$ , where D is diagonal?
- (d) Find  $|{\bf A}^{-1}|$ .

(L-OPT-2) QUESTION 7. Consider a 3 by 3 matrix **A** with eigenvalues  $\lambda_1=1$ ,  $\lambda_2=2$ , and  $\lambda_3=-1$ ; and let  $\boldsymbol{v}_1=(1,0,1)^{\mathsf{T}}$  and  $\boldsymbol{v}_2=(1,1,1)^{\mathsf{T}}$  be the corresponding eigenvectors to  $\lambda_1$  and  $\lambda_2$ .

- (a) Is A diagonalizable?
- (b) Is  $\mathbf{v}_3 = (-1, 0, -1)^{\mathsf{T}}$  an eigenvector associated to the eigenvalue  $\lambda_3 = -1$ ?
- (c) Compute  $\mathbf{A}(v_1 v_2)$ .

#### (L-Opt-2) Question 8.

(a)  $(0.5^{\rm pts})$  Find an homogeneous system  $\mathbf{A} x = \mathbf{0}$  such as its solutions set is

$$\left\{ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} \in \mathbb{R}^4 \ \middle| \ \exists \alpha, \beta, \gamma \in \mathbb{R} \quad \text{such that} \ \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \beta \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \gamma \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}. \right\}$$

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(b) (0.5<sup>pts</sup>) If the characteristic polynomial of a matrix **A** is  $p(\lambda) = \lambda^5 + 3\lambda^4 - 24\lambda^3 + 28\lambda^2 - 3\lambda + 10$ , find the rank of **A**.

(L-OPT-2) QUESTION 9. Suponga una matriz cuadrada e invertible  $\mathbf{A}$ 

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(a) ¿Cuáles son sus espacios columna  $\mathcal{C}(\mathbf{A})$  y espacio nulo  $\mathcal{N}(\mathbf{A})$ ? (no responda con la definición, diga qué conjunto de vectores compone cada espacio).

(b) Suponga que A puede ser factorizada en A = LU:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 7 & 3 & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{12} & u_{13} \\ 0 & 0 & u_{13} \end{bmatrix}$$

Describa el primer paso de eliminación en la reducción de **A** a **U**. ¿porqué sabe que **U** es también una matriz invertible? ¿Cuanto vale el determinante de **A**?

(c) Encuentre una matriz particular de dimensiones  $3\times 3$  e invertible **A** que no pueda ser factorizada en la forma **LU** (sin permutar previamente las filas). ¿Qué factorización es todavía posible en su ejemplo? (no es necesario que realice la factorización). ¿Cómo sabe que su matriz **A** es invertible?