HIGH-VOLTAGE MIXED-SIGNAL IC

UG1604

65x192 STN Controller-Driver

BUS

MP Specifications
Datasheet Revision: 1.1

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Table of Content

INTRODUCTION	3
MAIN APPLICATIONS	3
FEATURE HIGHLIGHTS	3
ORDERING INFORMATION	4
BLOCK DIAGRAM	5
PIN DESCRIPTION	
RECOMMENDED COG LAYOUT	8
CONTROL REGISTERS	
COMMAND TABLE	11
COMMAND DESCRIPTION	
LCD VOLTAGE SETTING	20
V _{LCD} QUICK REFERENCE	21
LCD DISPLAY CONTROLS	
ITO LAYOUT AND LC SELECTION	
HOST INTERFACE	
DISPLAY DATA RAM (DDRAM)	35
RESET & POWER MANAGEMENT MULTI-TIME PROGRAM NV MEMORY	37
MULTI-TIME PROGRAM NV MEMORY	41
MTP OPERATION FOR LCM MAKERS	42
ESD CONSIDERATION	46
ABSOLUTE MAXIMUM RATINGS	47
SPECIFICATIONS	48
AC CHARACTERISTICS	49
PHYSICAL DIMENSIONS	55
ALIGNMENT MARK INFORMATION	56
PAD COORDINATES	57
TRAY INFORMATION	65
REVISION HISTORY	66

UC1604

Single-Chip, Ultra-Low Power 65COM by 192SEG Passive Matrix LCD Controller-Driver

INTRODUCTION

混合信号

This chip employs UltraChip's unique DCC (Direct Capacitor Coupling) driver architecture to achieve near crosstalk free images.

In addition to low power column and row drivers, the IC contains all necessary circuits for high-V LCD power supply, bias voltage generation, timing generation and graphics data memory.

Advanced circuit design techniques are employed to minimize external component counts and reduce connector size while achieving extremely low power consumption. 连接器的尺寸

MAIN APPLICATIONS

 Cellular Phones, Smart Phones, PDA, and other battery operated palm top devices or portable Instruments

FEATURE HIGHLIGHTS

- Single chip controller-driver support 65x192 graphics STN LCD panels.液晶显示屏幕
- Support both row ordered and column ordered display buffer RAM access. 行阵列和列阵列
- A software-readable ID pin to support configurable vender identification.
- Support both row-ordered and column-ordered display buffer RAM access.

 Support industry standard 8-bit parallel bus (8080 or 6800 mode), 4-wire and 3-wire serial buses (S8 and S9), and 2-wire I²C serial interface. i2c串行接口

- Fully programmable Mux Rate, partial display, Bias Ratio and Frame Rate allow many flexible power 偏离率 management options. 帖速度
- Software programmable frame rates at 76, 95, 132 and 168 Hz.
- Four software programmable temperature compensation coefficients.
- 7-x internal charge pump with on-chip pumping capacitor requires only 3 external capacitors to operate.
- On-chip Power-ON Reset makes RST pin optional.
- Very low pin count (10-pin) allows exceptional image quality in COG format on conventional ITO glass.
- Flexible data addressing/mapping schemes to support wide ranges of software models and LCD layout placements.

 V_{DD} (digital) range (Typ.): 1.8V ~ 3.3V V_{DD} (analog) range (Typ.): 2.7V ~ 3.3V V_{LCD} range: 4.8V ~ 11.5V

- Available in gold bump dies
- COM/SEG bump information Bump pitch: 27.6 μM Bump gap: 12 μM

Bump surface: 2028 µM² (For UC1604cGAA)

1560 µM² (For UC1604cGBA)

3



ORDERING INFORMATION

Part Number	MTP	I ² C	Description
UC1604cGAA	Yes	Yes	Gold Bumped Die, Bump size 15.6uMx130uM
UC1604cGBA	Yes	Yes	Gold Bumped Die, Bump size 15.6uMx100uM, 15.6uMx115uM



General Notes

APPLICATION INFORMATION

说明书
For improved readability, the specification contains many application data points. When application information is given, it is advisory and does not form part of the specification for the device.

LISE OF I2C

The implementation of I²C is already included and tested in all silicon.

BARE DIE DISCLAIMER

All die are tested and are guaranteed to comply with all data sheet limits up to the point of wafer sawing. There is no post waffle saw/pack testing performed on individual die. Although the latest modern processes are utilized for wafer sawing and die pick-&-place into waffle pack carriers, UltraChip has no control of third party procedures in the handling, packing or assembly of the die. Accordingly, it is the responsibility of the customer to test and qualify their application in which the die is to be used. UltraChip assumes no liability for device functionality or performance of the die or systems after handling, packing or assembly of the die.

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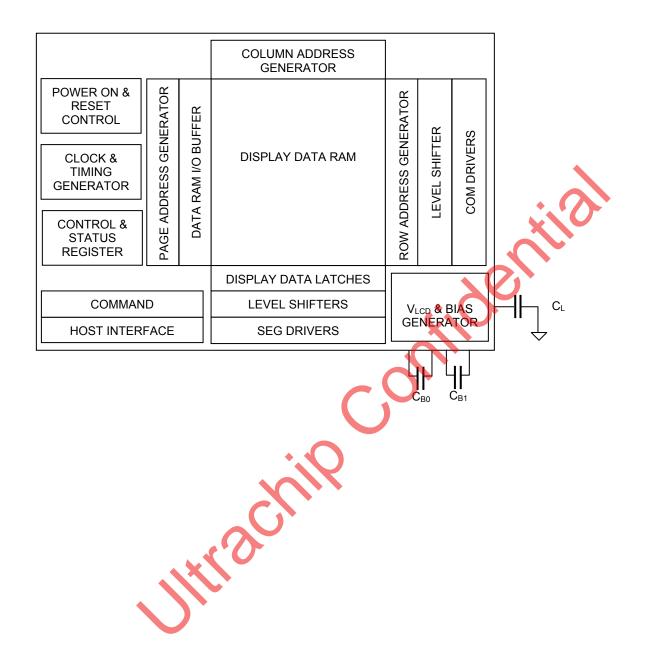
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CONTACT DETAILS

UltraChip Inc. (Headquarter) 4F, No. 618, Recom Road, Neihu District, Taipei 114, Taiwan, R. O. C. Tel: +886 (2) 8797-8947 Fax: +886 (2) 8797-8910

Sales e-mail: sales@ultrachip.com Web site: http://www.ultrachip.com

BLOCK DIAGRAM



PIN DESCRIPTION

Name	Type	Pins	Description
			MAIN POWER SUPPLY
			V_{DD} supplies for Display Data RAM and digital logic, V_{DD2} supplies for V_{LCD} and V_{D} generator, V_{DD3} supplies for V_{BIAS} and other analog circuits.
V_{DD} V_{DD2}	PWR	5 7	V_{DD2}/V_{DD3} should be connected to the same power source. But V_{DD} can be connected to a source voltage no higher than V_{DD2}/V_{DD3} .
V_{DD3}		5	Please maintain the following relationship: $V_{DD}+1.3V \ge V_{DD2/3} \ge V_{DD}$
			ITO trace resistance needs to be minimized for V _{DD2} /V _{DD3} .
V_{SS} V_{SS2}	GND	6 6	Ground. Connect V_{SS} and V_{SS2} to the shared GND pin. In COG applications, minimize the ITO resistance for both V_{SS} and V_{SS2} .
			LCD Power Supply & Voltage Control
V _{B1+} V _{B1-}	PWR	4 4	LCD Bias Voltages. These are the voltage sources to provide SEG driving currents. These voltages are generated internally. Connect capacitors of C_{BX} value between V_{BX+} and V_{BX-} . See the "LCD Voltage Setting" section for more details.
V_{B0+} V_{B0-}	PVVK	4 4	In COG application, the resistance of these ITO traces directly affects the SEG driving strength of the resulting LCD module. Minimize these trace resistance is critical in achieving high quality image.
V _{LCDIN}	PWR	4	Main LCD Power Supply. When internal V_{LCD} is used, connect these pins together. When external V_{LCD} source is used, connect external V_{LCD} source to V_{LCDIN} pins and leave V_{LCDOUT} open.
V _{LCDOUT}		4	Capacitor C_L should be connected between V_{CD} and V_{SS} . In COG applications, keep the ITO trace resistance around 70 Ω .

Recommended capacitor values: C_B : 2.2 μ F/5V or 300x(LCD load capacitance), whichever is higher C_L : 330nF/25V is appropriate for most applications.

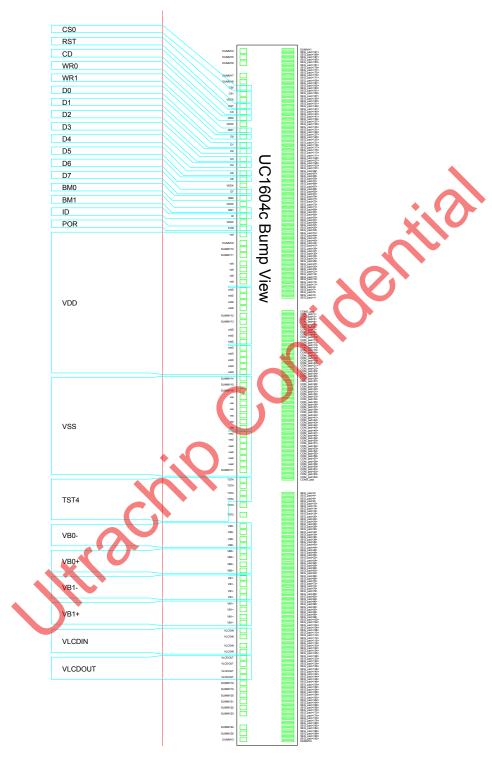
				Host	INTERFACE								
				Bus mode: The interface bus mode is determined by BM[1:0] and D[7] by the following relationship:									
			BM[1:0]	D[7]	Mode	Remark							
BM0		1	11	Data	6800/8-bit								
BM1	1 1	10	Data	8080/8-bit									
		00			4-wire SPI w/ 8-bit token	(S8: conventional)							
			01	0	3-wire SPI w/ 9-bit token	(S9: conventional)							
			01	1	2-wire serial (I ² C)								
CS1/A3 CS0/A2	I	1	D[7:0] will be o	thip Select. Chip is selected when CS1="H" and CS0 = "L". When the chip is not selected, [7:0] will be of high impedance. 1 ² C mode, these two pins specifies bits 3~2 of UC1604c' device address (A[3:2]).									
RST		1			gisters are re-initialized by their de RST pin is not required for proper	efault states. Since UC1604c has chip operation.							
Kol	1	_		as been include ed, connect the	ed on-chip. There is no need for epin to V_{DD} .	external RC noise filter. When							
CD	1	1	Select Control CD to V _{SS} whe		data for read/write operation. In	S9, CD pin is not used. Connect							
			"L": Control d	"L": Control data "H": Display data									
ID	1	1	ID may be use	ed for production	n identification.								
טו	ı	l 	Connect ID to	V_{DD} for "H" or V	/ _{SS} for "L".								



Name	Туре	Pins					Descript	ion							
WR0 WR1	ı	1	WR [1:0] controls details.												
VVIXI		'		parallel mode, the meaning of WR[1:0] depends on which interface it is in, 6800 or 8080 ode. In serial interface modes, these two pins are not used, Connect them to V _{SS} . directional bus for both serial and parallel host interfaces.											
			Bi-directional bus	for both	n serial a	nd parall	el host ir	nterfaces							
			In serial modes, o	connect	D[0] to S	CK, D[5	:3] to SD	A.							
				D0											
			8-bit (BM=1x) D7 D6 D5 D4 D3 D2 D1 D0												
D7~D0	I/O	8	s8 (BM=00)	s8 (BM=00) SDA SDA SDA SCK											
			S9 (BM=01)	•											
			I ² C (BM=01)	I ² C (BM=01) 1 SDA SDA SDA SCK											
			For better drive a	or better drive ability, connect D[5:3] together.											
			Always connect u	ways connect unused pins to either V _{SS} or V _{DD} .											
	HIGH VOLTAGE LCD DRIVER OUTPUT														
SEG1 ~ SEG192	HV	192		SEG (column) driver outputs. Support up to 192 pixels. Leave unused SEG drivers open-circuit.											
COM1 ~			COM (row) drive	COM (row) driver outputs. Support up to 64 rows.											
COM64	HV	64	When designing 64, set CEN to be								s and N	is less than			
CIC	HV	2	Icon driver outpu	ts. Leav	e it open	if not us	ed.								
					Misc. F	PINS									
V_{DDX}		5	Auxiliary V _{DD} . Thi chip configuration	s pin is is in CO	connecte G applic	ed to the ation.	main V _{DI}	bus wit	hin the I	C. It's pr	ovided to	o facilitate			
V DDX		5	There's no need to V _{DD} power to the		ect V _{DDX}	to main \	/ _{DD} exter	nally and	l it shoul	d <u>NOT</u> b	oe used t	o provide			
TST4	I	4	TST4 is used as COG designs, plo									ion. For			
TST2	I/O	2	Test I/O pins. Lea	est I/O pins. Leave these pins open during normal use.											
			Power-ON Reset	Power-ON Reset control.											
POR		1		Connect the POR pin to V _{DD} for "H"; to Vss for "L" to control the POR register.											
1 011		'		"L": Power-ON Reset Enable.											
			"H": Power-ON												
Dummy		25	Dummy pins are	NOT co	nnected	inside th	ie IC.								

Note: Several control registers will specify "0 based index" for COM and SEG electrodes. In those situations, $COM\underline{X}$ or $SEG\underline{X}$ will correspond to index \underline{X} -1, and the value range for those index register will be 0~63 for COM and 0~191 for SEG.

RECOMMENDED COG LAYOUT



Notes for V_{DD} with COG:

The operation condition, V_{DD} =1.8V (typical), should be satisfied under all operating conditions. UC1604c' peak current (I_{DD}) can be up to ~15mA during high speed data-write to UC1604c' on-chip SRAM. Such high pulsing current mandates very careful design of V_{DD} and V_{SS} ITO trances in COG modules. When V_{DD} and V_{SS} trace resistance is not low enough, the pulsing I_{DD} current can cause the actual on-chip V_{DD} to drop to below 1.7V and cause the IC to malfunction.

CONTROL REGISTERS

UC1604c contains registers, which control the chip operation. The following table is a summary of these control registers, a brief description and the default values. These registers can be modified by commands, which will be described in the next two sections, Command Table and Command Description.

Name: The Symbolic reference of the register. Note that, some symbol name refers to bits (flags) within another register.

Default: Numbers shown in **Bold** font are default values after Power-Up-Reset and System-Reset.

Name	Bits	Default	Description
SL	6	00H	Scroll Line. Scroll the displayed image up by SL rows. The valid SL value is between 0 (for no scrolling) and (64). Setting SL outside of this range causes undefined effect on the displayed image.
CA	8	00H	Display Data RAM Column Address. Value range is 0 ~ 191.
			(Used in Host to Display Data RAM access)
PA	4	0H	Display Data Page Row Address. Value range is 0 ~ 8.
			(Used in Host to Display Data RAM access)
BR	2	3H	Bias Ratio. The ratio between V _{LCD} and V _D .
			00b: 6 01b: 7 10b: 8 11b: 9
TC	2	0H	Temperature Compensation (per °C)
			00b: -0.00% 01b: -0.05% 10b: -0.10% 11b: -0.15%
PM	8	49H	Electronic Potentiometer to fine tune V _D and V _{LCD}
PMO	6	00H	PM offset.
PC	3	6H	Power Control.
			PC[1:0]: low pump charge current select
			00b: 0.6mA 01b: 1.0mA 10b: 1.4mA 11b: 2.3mA
			PC[2]: to program the build-in charge pump stages
			0b: External V _{LCD} 1b: Internal V _{LCD} (7x charge pump)
AC	3	1H	Address Control:
			AC[0]: WA: Automatic column/row Wrap Around (Default 1: ON)
			AC[1]: Auto-Increment order
			0: Column (CA) first 1: Page (PA) first
			AC[2]: RID: RA (row address) auto increment direction (L:+1 H:-1)
DC	3	0H	Display Control:
			DC[0]: PXV: Pixels Inverse. Bit-wise data inversion. (Default 0: OFF)
			DC[1]: APO: All Pixels ON (Default 0: OFF)
			DC[2]: Display ON/OFF (Default 0: OFF)
LC	6	08H	LCD Control:
			LC[0]: Reserved (always set to 0)
			LC[1]: MX, Mirror X. SEG/Column sequence inversion (Default: 0:OFF)
			LC[2]: MY, Mirror Y. COM/Row sequence inversion (Default: 0:OFF)
			LC[4:3]: Line Rate (Klps: Kilo-Line-per-second)
			00b: 76 fps 01b: 95 fps 10b: 132 fps 11b: 168 fps
			LC[5] : Partial Display.
			0b: Disabled . Mux-Rate = CEN+1 (DST, DEN not used)
			1b: Enabled. Mux-Rate = DEN-DST+1



Name	Bits	Default	Description										
CEN	6	3FH	COM scanning end (last COM with full line cycle, 0-based index)										
DST	6	00H	Display start (first COM with active scan pulse, 0-based index)										
DEN	6	3FH	splay end (last COM with active scan pulse, 0-based index)										
			ase maintain the following relationship:										
			ase maintain the following relationship: CEN = "the actual number of pixel rows on the LCD" – 1										
			CEN \geq DEN \geq DST+9										
MTPC	5	00H											
WITEC	5	001	MTP Cross NTP command										
			MTPC[2:0] : MTP command										
			000 : Idle 001 : Read										
			010 : Erase 011 : Program										
			1XX : For UltraChip debug use only										
			MTPC[3]: MTP Enable (automatically cleared after each MTP command)										
			MTPC[4]: Ignore/Use MTP.										
			0: Ignore 1: Use										
MTPM	6	00H	MTP Write Mask. For each bit, Bit =1: program, Bit=0: no action.										
APC		N/A	Advanced Program Control. For UltraChip only. Please do not use.										
			Status Registers										
OM	2	_	Operating Modes (Read only)										
			00b: Reset 01b: (Not used)										
		DIN	10b: Sleep 11b: Normal										
ID	1	PIN	Access the connected status of ID pins.										
POR	1	PIN	Power-ON Reset control. Controlled by the POR pin.										
			"L": Power-ON Reset Enable.										
			"H": Power-ON Reset Disabled.										

COMMAND TABLE

The following is a list of host commands supported by UC1604c

 $\overline{\text{C/D}}$: 0: Control, 1: Data $\overline{\text{W/R}}$: 0: Write Cycle, 1: Read Cycle $\overline{\text{D7}}$ \sim $\overline{\text{D0}}$: #: Useful Data bits -: Don't Care

No	Command	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Action	Default
1.	Write Data Byte	1	0	#	#	#	#	#	#	#	#	Write 1 byte	N/A
2.	Read Data Byte	1	1	#	#	#	#	#	#	#	#	Read 1 byte	N/A
3.	Get Status	0	1	ID	MX	MY	WA	DE	WS	MD	MS	Get Status	N/A
٥.		٠	'	VER	POR	#	#	#	#	#	#	PMO[5:0]	IN/A
4.	Set Column Address LSB	0	0	0	0	0	0	#	#	#	#	Set CA [3:0]	0
	Set Column Address MSB	0	0	0	0	0	1	#	#	#	#	Set CA [7:4]	0
5.	Set Temp. Compensation	0	0	0	0	1	0	0	1	#	#	Set TC[1:0]	00b
6.	Set Power Control	0	0	0	0	1	0	1	#	#	#	Set PC[2:0]	110b
7.	Set Adv. Program Control	0	0	0	0	1	1	0	0	R	R	Set APC[R][7:0],	N/A
	(double-byte command)	_	0	#	#	#	#	#	#	#	#	R = 0~3	
8.	Set Scroll Line	0	0	0 1	0	1	1	#	#	#	#	Set SL[5:0]	0
9.	Set Page Address Set V _{BIAS} Potentiometer	U	U	1	0	0	0	0	0	0	1	Set PA[3:0]	U
10.	(double-byte command)	0	0	#	#	#	#	#	#	#	#	Set PM[7:0]	49H
11.	Set Partial Display Control	0	0	1	0	0	0	0	1	0	#	Set LC[5]	0b
12.	Set RAM Address Control	0	0	1	0	0	0	1	#	#	#	Set AC[2:0]	001b
13.	Set Frame Rate	0	0	1	0	1	0	0	0	# .	#	Set LC[4:3]	01b
14.	Set All-Pixel-ON	0	0	1	0	1	0	0	1	0	#	Set DC[1]	0b
15.	Set Inverse Display	0	0	1	0	1	0	0	1	1	#	Set DC[0]	0b
16.	Set Display Enable	0	0	1	0	1	0	1	1	1	#	Set DC[2]	0b
17.	Set LCD Mapping Control	0	0	1	1	0	0	0	#	#	0	Set LC[2:1]	00b
18.	System Reset	0	0	1	1	1	0	0	0	1	0	System Reset	N/A
19.	NOP	0	0	1	1	1	0	0	0	1	1	No operation	N/A
20.	Set Test Control	0	0	1	1	1	0	0	1	T		For testing only.	N/A
	(double-byte command)	Ů	•	#	#	#	#	#	#	#	#	Do not use.	
21.	Set LCD Bias Ratio	0	0	1	1	1	0	1	0	#	#	Set BR[1:0]	11b: 9
22.	Set COM End	0	0	1	1	1	1	0	0	0	1 "	Set CEN[5:0]	63D
						#	#	#	#	#	#		
23.	Set Partial Display Start	0	0	1	1	1 4	#	0 #	0 #	1 #	0 #	Set DST[5:0]	0
						#		0	0	1			
24.	Set Partial Display End	0	0	1	_	#	1 #	#	#	#	1 #	Set DEN[5:0]	63D
				1		1	1	1	0	0	0		
25.	Set MTP Operation Control	0	0				#	#	#	#	#	Set MTPC[4:0]	00H
			A X	1	1	1	1	1	0	0	1		_
26.	Set MTP Write Mask	0	0			#	#	#	#	#	#	Set MTPM[5:0]	0
	Out Marketing and the			1	1	1	1	0	1	0	0	0.11/04TD4[7.0]	N 1/A
27.	Set V _{MTP1} Potentiometer	0	9	#	#	#	#	#	#	#	#	Set VMTP1[7:0]	N/A
20	Cat \/ Datantiamator	0		1	1	1	1	0	1	0	1	Cot \/MTD2[7:0]	NI/A
28.	Set V _{MTP2} Potentiometer	0	0	#	#	#	#	#	#	#	#	Set VMTP2[7:0]	N/A
29.	Set MTP Write Timer	0	0	1	1	1	1	0	1	1	0	Set MTPWT[7:0]	N/A
29.	Set WITE White Timer	U	U	#	#	#	#	#	#	#	#	Section FW [[1.0]	IN/A
30.	Set MTP Read Timer	0	0	1	1	1	1	0	1	1	1	Set MTPRT[7:0]	N/A
<u> </u>	Cot Will Road Fillion	<u> </u>		#	#	#	#	#	#	#	#	30t W 11 1tt[1.0]	14// \
		Sei	rial Re	ad Co	mmar	nd (En	abled	only i	n S8/S	9 mod	le)		
		0	0	1	1	1	1	1	1	1	0		
31.	Get Status	0	1	ID	MX	MY	WA	DE	WS	MD	MS	Get Status	N/A
				VER	POR	#	#	#	#	#	#	PMO[5:0]	
32.	Read Data	0	0	1	1	1	1	1	1	1	1		FFH
ر کے۔		1	1	#	#	#	#	#	#	#	#		

Any bit pattern other than those listed above may result in NOP (No Operation).

COMMAND DESCRIPTION

1. Write Data Byte to Memory

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Write data	1	0			8-k	oit data wr	ite to SRA	λM		

2. Read Data Byte from Memory

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Read data	1	1			8-bi	t data rea	d from SR	AM		

Write/Read Data Byte (Command 1,2) access Display Data RAM based on Page Address (PA) register and Column Address (CA) register. To minimize bus interface cycles, PA and CA will increase or decrease automatically after each bus cycle, depending on the setting of Access Control (AC) registers. PA and CA can also be programmed directly by issuing Set Page Address and Set Column Address commands.

If \underline{W} rap- \underline{A} round (WA) is OFF (AC[0] = 0), CA will stop increasing after reaching the end of the page, and system programmers need to set the values of PA and CA explicitly. If WA is ON (AC[0]=1), when CA reaches the end of the page, CA will be reset to 0 and PA will increase or decrease by 1, depending on the setting of \underline{P} age Increment \underline{D} irection (PID, AC[2]). When PA reaches the boundary of RAM, PA will be wrapped around to the other end of RAM and continue.

3. Get Status

Action	C/D	W/R	D7	D6	D5	D4		D3	D2	D1	D0
Get Status	0	1	ID	MX	MY	WA		DE	WS	MD	MS
Get Status	0	1	VER	POR	PMO5	PMO4	F	PMO3	PMO2	PMO1	PMO0

Status1 definitions:

ID: Provide access to ID pins connection status.

 $\it MX$: Status of register LC[1], mirror X.

MY: Status of register LC[2], mirror Y.

WA: Status of register AC[0]. Automatic column/row wrap around.

DE: Display Enable flag. DE=1 when display is enabled.

WS: MTP Operation succeeded

MD: MTP Option (1 for MTP version, 0 for non-MTP version)

MS: MTP action status

Status2 definitions:

Ver: IC Version, 0~ 1.

POR: Power-ON Reset control.

PMO[5:0]: PM offset value. Default: 00H

4. Set Column Address

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Column Address LSB CA[3:0]	0	0	0	0	0	0	CA3	CA2	CA1	CA0
Set Column Address MSB CA[7:4]	0	0	0	0	0	1	CA7	CA6	CA5	CA4

Set the SRAM column address before Write/Read memory from host interface.

CA value range: 0~191



5. Set Temperature Compensation

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Temperature Comp. TC[1:0]	0	0	0	0	1	0	0	1	TC1	TC0

Set V_{BIAS} temperature compensation coefficient (%-per-degree-C)

Temperature compensation curve definition:

10b= -0.10%/°C

11b= -0.15%/°C

6. Set Power Control

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Power Control PC[2:0]	0	0	0	0	1	0	1	PC2	PC1	PC0

PC[1:0]: to select low-pump charge current

00b: 0.6mA

01b: 1.0mA

10b: 1.4mA

11b: 2.3mA

Set PC[2]: to program the build-in charge pump stages.

0b: External V_{I CD}

1b: Internal V_{LCD} (7x charge pump)

7. Set Advanced Program Control

Action	C/D	W/R	D7	D6	D5	D4.	D3	D2	D1	D0
Set Adv. Program Control APC[R][7:0]	0	0	0	0	1	1	0	0	R	R
(Double-byte command)	0	0	APC7	APC6	APC5	APC4	APC3	APC2	APC1	APC0

For UltraChip only. Please Do NOT use.

8. Set Scroll Line

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Scroll Line SL[5:0]	0	0	0	1	SL5	SL4	SL3	SL2	SL1	SL0

Set the scroll line number.

Scroll line setting will scroll the displayed image up by SL rows Icon output CIC will not be affected by Set Scroll Line command.



9. Set Page Address

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Page Address PA[3:0]	0	0	1	0	1	1	PA3	PA2	PA1	PA0

Set the SRAM page address before write/read memory from host interface. Each page of SRAM corresponds to 8 COM lines on LCD panel, except for the last page. The last page corresponds to the icon output CIC.

Possible value = 0~8.



10. Set V_{BIAS} Potentiometer

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set V _{BIAS} Potentiometer PM [7:0]	0	0	1	0	0	0	0	0	0	1
(Double-byte command)	0	0	PM7	PM6	PM5	PM4	PM3	PM2	PM1	PM0

Program V_{BIAS} Potentiometer (PM[7:0]). See section LCD Voltage Setting for more detail.

Effective range: 0 ~ 255 (Default: 49H)

11. Set Partial Display Control

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Partial Display Enable LC [5]	0	0	1	0	0	0	0	1	0	LC5

This command is used to enable partial display function.

LC[5]: **0b: Disable Partial Display**, Mux-Rate = CEN+1 (DST, DEN not used.)

1b: Enable Partial Display, Mux-Rate = DEN-DST+1

12. Set RAM Address Control

Action	C/D	W/R	D7	D6	D5	D4	D3	Y	D2	D1	D0
Set AC [2:0]	0	0	1	0	0	0 🔸	1		AC2	AC1	AC0

Program registers AC[2:0] for RAM address control. It controls the auto-increment behavior of CA and PA.

AC[0] - WA, Automatic column/page wrap around.

0: CA or PA (depends on AC[1]= 0 or 1) will stop increasing after reaching boundary

1: CA or PA (depends on AC[1]= 0 or 1) will restart, and CA or PA will increase by one.

AC[1] – Auto-Increment order

0 : column (CA) increasing (+1) first until CA reach CA boundary, then PA will increase by (+/-1).

1 : page (PA) increasing (+/-1) first until PA reach PA boundary, then CA will increase by (+1).

AC[2] - PID, page address (PA) auto increment direction (0/1 + 1)

When WA=1 and CA reaches CA boundary, PID controls whether page address will be adjusted by

+1 or -1.

13. Set Frame Rate

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Frame Rate LC [4:3]	0	0	1	0	1	0	0	0	LC4	LC3

Program LC [3] for frame rate setting

00b: 76 fps **01b: 95 fps** 10b: 132 fps 11b: 168 fps

(fps: frame-per-second)

14. Set All Pixel ON

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set All Pixel ON DC [1]	0	0	1	0	1	0	0	1	0	DC1

Set DC[1] to force all SEG drivers to output ON signals. This function has no effect on the existing data stored in display RAM. (Default: 0)

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15. Set Inverse Display

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Inverse Display DC [0]	0	0	1	0	1	0	0	1	1	DC0

Set DC[0] to force all SEG drivers to output the inverse of the data (bit-wise) stored in display RAM. This function has no effect on the existing data stored in display RAM. (Default: 0)

16. Set Display Enable

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Display Enable DC[2]	0	0	1	0	1	0	1	1	1	DC2

This command is for programming register DC[2]. When DC[2] is set to 1, UC1604c will first exit from sleep mode, restore the power and then turn on COM drivers and SEG drivers. (Default: 0)

17. Set LCD Mapping Control

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set LCD Control LC[2:1]	0	0	1	1	0	0	0	MY	MX	0

Set LC[2:1] for COM (row) mirror (MY), SEG (column) mirror (MX). (Default: 00b)

MY is implemented by reversing the mapping order between RAM and COM (row) electrodes. The data stored in RAM is not affected by MY command. MY will have immediate effect on the display image.

MX is implemented by selecting the CA or 63-CA as write/read (from host interface) display RAM column address so this function will only take effect after rewriting the RAM data.

18. System Reset

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
System Reset	0	0	1	1	1	0	0	0	1	0

This command will activate the system reset.

Control register values will be reset to their default values. Data store in RAM will not be affected.

19. NOP

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
No Operation	0	0	1	1	1	0	0	0	1	1

This command is used for "no operation".

20. Set Test Control

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set TT	0	0	1	1	1	0	0	1	Т	Т
(Double byte command)	0	0				For te	st only			

This command is used for UltraChip production testing. Please do <u>NOT</u> use.

21. Set LCD Bias Ratio

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set Bias Ratio BR [1:0]	0	0	1	1	1	0	1	0	BR1	BR0

Bias ratio definition:

00b= 6 01b= 7 10b= 8 **11b= 9**



22. Set COM End

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set CEN [5:0]	0	0	1	1	1	1	0	0	0	1
(Double-byte command)	0	0	•	-		Ci	EN registe	r paramet	er	

This command programs the ending COM electrode. CEN defines the number of used COM electrodes, and it should correspond to the number of pixel-rows in the LCD. When the LCD has less than 64 pixel rows, the LCM designer should set CEN to N-I (where N is the number of pixel rows) and use COM1 through COM-N as COM driver electrodes. (Default: **63**)

23. Set Partial Display Start

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set DST [5:0]	0	0	1	1	1	1	0	0	1	0
(Double-byte command)	0	0	-	-		D.	ST registe	r paramet	er	

This command programs the starting COM electrode, which has been assigned a full scanning period and will output an active COM scanning pulse.

24. Set Partial Display End

Action	C/D	W/R	D7	D6	D5	D4 •		D3	D2	D1	D0
Set DEN [5:0]	0	0	1	1	1	1		0	0	1	1
(Double-byte command)	0	0	-	-		D	ΕN	registe	er paramet	er	

This command programs the ending COM electrode, which has been assigned a full scanning period and will output an active COM scanning pulse.

CEN, DST, and DEN are 0-based index of COM electrodes. They control only the COM electrode activity, and do not affect the mapping of display RAM to each COM electrodes. The image displayed by each pixel row is therefore not affected by the setting of these three registers.

When LC[5]=1b, the Mux-Rate is narrowed down to DEN – DST + 1. When MUX rate is reduced, reduce the frame rate accordingly to reduce power. Changing MUX rate also require BR and V_{LCD} to be reduced.

For minimum power consumption, set LC[5]=1b, set (DST, DEN, CEN) to minimize Mux rate, use slowest frame rate which satisfies the flicker requirement, set PC[0]=0b, and use lowest BR, lowest V_{LCD} which satisfies the contrast requirement. When Mux-Rate is under 16, it is recommended to set BR=6 for optimum power saving.

In either case, DST/DEN defines a small subsection of the display which will remain active while shutting down all the rest of the display to conserve energy.

Keep CEN ≥ DEN ≥ DST+9

Scan Method Display Result: Not scanned Pulse Enable Display segment Display segment Display segment



Display	Func	tion Se	etting	Image in DDRAM	Display	Fund	tion Se	etting	Image in DDRAM
Data Direction	AIO AC[1]	MX LC[1]	RID AC[2]	(Physical origin: upper left corner)	Data Direction	AIO AC[1]	MX LC[1]	RID AC[2]	(Physical origin: upper left corner)
Normal	0	0	0	UCT	X-Y Exchange	1	0	0	
Y-mirror	0	0	1	120	X-Y Exchange Y-mirror	1	0	1	
X-mirror	0	1	0	IJU	X-Y Exchange X-mirror	1	1	0	
X-mirror Y-mirror	0	1	1	120	X-Y Exchange X-mirror Y-mirror	1	1	7	DU

25. Set MTP Operation Control

Action	C/D	W/R	D7 [*]	D6		D5	D4	D3	D2	D1	D0
Set MTPC [4:0]	0	0	1	1	1	1	1	1	0	0	0
(Double-byte command)	0	0		\ -		-	MTPC4	MTPC3	MTPC2	MTPC1	MTPC0

This command is for MTP operation control: (MTPC[4:0] : default: **D0H**)

MTPC[2:0]: MTP command

000 : Sleep 001 : MTP Read 010 : MTP Erase 011 : MTP Program

1xx: For UltraChip use only.

MTPC[3]: MTP Enable (automatically cleared each time after MTP command is done)

MTPC[4]: MTP value valid (set H to active MTP value)

DC[2] and MTPC[3] are mutually exclusive. Only one of these two control flags can be set to ON at any time. In other words, when DC[2] is ON, all MTP operations will be blocked, and, when MTP operation is active, set DC[2] to 1 will be blocked.



26. Set MTP Write Mask

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set MTPM [5:0]	0	0	1	1	1	1	1	0	0	1
(Double-byte command)	0	0	-	-			MTPI	M[5:0]		

This command enables Write to each of the individual MTP bits. When MTPM[x]=1, the x-th bit of the MTP memory will be programmed to "1". MTPM[x]=0 means no Write action for x-th bit. And the content of this bit will not change.

The amount of "programming current" increases with the number of 1's in MTPM. If the "programming current" appears to be too high for the LCM design (e.g. TST4 ITO trace is not wide enough to supply the current), use multiple write cycles and distribute the 1's evenly into these cycles.

MTPM[5:0]: Set PMO value (Default: 00H)

27. Set V_{MTP1} Potentiometer

Action	C/D	W/R	D7	D6	D5	D4	D3	D2 •	D1	D0
Set VMTP1 [7:0]	0	0	1	1	1	1	0	1	0	0
(Double-byte command)	0	0				VMTF	71[7:0]		•	

This command is for fine tuning V_{OPT1} setting (with BR=00).

28. Set V_{MTP2} Potentiometer

Action	C/D	W/R	D7	D6	D5	D4		D3	D2	D1	D0
Set VMTP2 [7:0]	0	0	1	1	1			0	1	0	1
(Double-byte command)	0	0				VMTF	2[7:	:0]			

This command is for fine tuning V_{MTP2} setting (with BR=11).

29. Set MTP Write Timer

Action	C/D	W/R	D7	D6	1	D5	D4	D3	D2	D1	D0
Set MTPWT [7:0]	0	0	1	7		1	1	0	1	1	0
(Double-byte command)	0	0	1		1		MTPW	VT[7:0]			

This command is only valid when MTPC[3]=1.

30. Set MTP Read Timer

Action	C/E	W/R	D7	D6	D5	D4	D3	D2	D1	D0
Set MTPRT [7:0]	0	0	1	1	1	1	0	1	1	1
(Double-byte command)	0	0				MTPR	RT[7:0]			

This command is only valid when MTPC[3]=1.



Serial Read Command (Enable only in S8/S9 mode):

31. Get Status

Action	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0
	0	0	1	1	1	1	1	1	1	0
Get Status	0	1	ID	MX	MY	WA	DE	WS	MD	MS
	0	1	VER	POR	PMO5	PMO4	PMO3	PMO2	PMO1	PMO0

See command 3.

32. Read Data Byte from Memory

Read data (double-byte command) 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
te command 2 for more information.

LCD VOLTAGE SETTING

MULTIPLEX RATES

Multiplex Rate is completely software programmable in UC1604c via registers CEN, DST, DEN, and partial display control flags LC[5].

Combined with low power partial display mode and a low bias ratio of 6, UC1604c can support wide variety of display control options. For example, when a system goes into stand-by mode, a large portion of LCD screen can be turned off to conserve power.

BIAS RATIO SELECTION

Bias Ratio (BR) is defined as the ratio between V_{LCD} and V_{D} , i.e.

$$BR = V_{LCD}/V_D$$

where $V_D = V_{B1+} - V_{B1-} = V_{B0+} - V_{B0-}$

The theoretical optimum *Bias Ratio* can be estimated by $\sqrt{Mux} + 1$. *BR* of value 15~20% lower/higher than the optimum value calculated above will not cause significant visible change in image quality.

UC1604c supports four *BR* as listed below. BR can be selected by software program.

BR	0	1	2	3
Bias Ratio	6	7	8	9

Table 1: Bias Ratios

TEMPERATURE COMPENSATION

Four different temperature compensation coefficients can be selected via software. The four coefficients are given below:

TC	0	1	2	3
% per °C	-0.00	-0.05	-0.10	-0.15

Table 2: Temperature Compensation

V_{LCD} GENERATION

 V_{LCD} may be supplied either by internal charge pump or by external power supply. The source of V_{LCD} is controlled by PC[2].

When V_{LCD} is generated internally, the voltage level of V_{LCD} is determined by three control registers: BR (Bias Ratio), PM (Potentiometer), and TC (Temperature Compensation), with the following relationship:

$$V_{LCD} = (C_{V0} + C_{PM} \times PM) \times (1 + (T - 25) \times C_T)$$

where

 C_{V0} and C_{PM} are two constants, whose value depends on the setting of BR register, as illustrated in the table on the next page,

PM is the numerical value of PM register,

T is the ambient temperature in $^{\circ}$ C, and

 C_T is the temperature compensation coefficient as selected by TC register.

V_{LCD} FINE TUNING

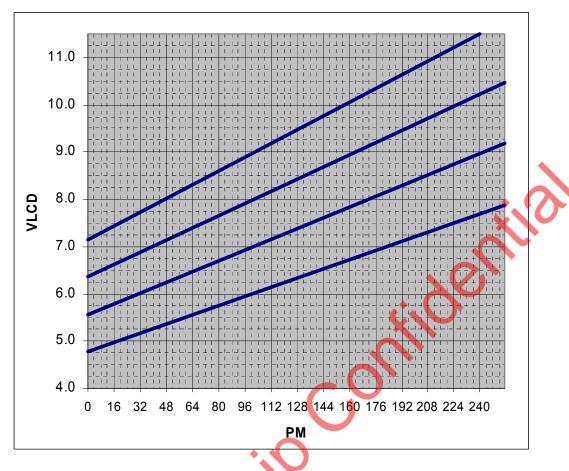
Black-and-white STN LCD is sensitive to even a 1% mismatch between IC driving voltage and the V_{OP} of LCD. However, it is difficult for LCD makers to guarantee such high precision matching of parts from different venders. It is therefore necessary to adjust V_{LCD} to match the actual V_{OP} of the LCD.

For the best result, software based approach for V_{LCD} adjustment or MTP is the recommended method for V_{LCD} finetuning. System designers should always consider the contrast fine tuning requirement before finalizing on the LCM design.

LOAD DRIVING STRENGTH

The power supply circuit of UC1604c is designed to handle LCD panels with loading up to ~24nF using 20- Ω /Sq ITO glass with V_{DD2/3} \geq 2.6V. For larger LCD panels, use lower resistance ITO glass packaging.

V_{LCD} QUICK REFERENCE



V_{LCD} Programming Curve.

BR	Cv ₀ (V)	С _{РМ} (mV)	PM	VLCD Range (V)
6	4,782	12.151	0	4.78
	4.702	12.131	255	7.88
7	5.570	14.141	0	5.57
,	3.370	17.171	255	9.18
8	6.360	16.149	0	6.36
	0.300	10.143	255	10.48
9	7.143	18.142	0	7.14
9	7.143	10.142	240	11.50

Note:

- 1. For good product reliability, keep V_{LCD} under **11.5V** over all temperature.
- 2. The integer values of BR above are for reference only and may have slight shift.

HI-V GENERATOR AND BIAS REFERENCE CIRCUIT

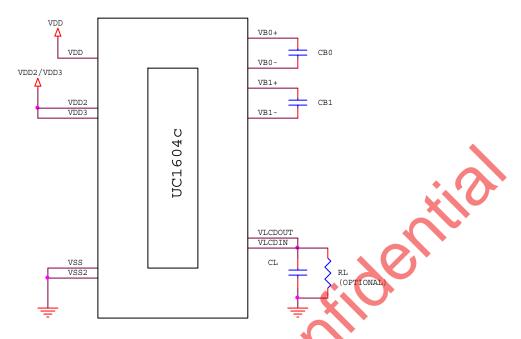


FIGURE 1: Reference circuit using internal Hi-V generator circuit

Note

Sample component values: (The illustrated circuit and component values are for reference only. Please optimize for specific requirements of each application.)

 C_{Bx} : 2.2 μ F/5V or 300x LCD load capacitance, whichever is higher.

C_L: 330nF(25V) is appropriate for most applications.

 R_L : 3.3M~10M Ω to act as a draining circuit when V_{DD} is shut down abruptly.

LCD DISPLAY CONTROLS

CLOCK & TIMING GENERATOR

UC1604c contains a built-in system clock. All required components for the clock oscillator are built-in. No external parts are required.

4 different frame rates are provided for system design flexibility. The frame rate is controlled by register LC[4:3]. When Mux-Rate is above 45, Frame rate: 76fps, 95fps, 132fps, and 168 fps.

When Mux-Rate is lowered to 44, 33, 22, and 17, frame rate will be scaled down automatically by 1.5, 2, 3, and 4 times to reduce power consumption.

Choose lower frame rate for lower power, and choose higher frame rate to improve LCD contrast and minimize flicker.

DRIVER MODES

COM and SEG drivers can be in either Idle mode or Active mode, controlled by Display Enable flag (DC[2]). When SEG and COM drivers are in idle mode, they will be connected together to ensure zero DC condition on the LCD.

DRIVER ARRANGEMENTS

The naming conventions are: COMx, where $x = 1\sim64$, refers to the row driver for the x-th row of pixels on the LCD panel.

The mapping of COM(x) to LCD pixel rows is fixed and it is not affected by SL, CEN, DST, DEN, MX or MY settings.

DISPLAY CONTROLS

There are three groups of display control flags in the control register DC: Driver Enable (DE), All-Pixel-ON (APO) and Inverse (PXV). DE has the overriding effect over PXV and APO.

DRIVER ENABLE (DE)

Driver Enable is controlled by the value of DC[2] via *Set Display Enable* command. When DC[2] is set to OFF (logic "0"), both COM and SEG drivers will become idle and UC1604c will put itself into Sleep Mode to conserve power.

When DC[2] is set to ON, the DE flag will become "1",and UC1604c will first exit from Sleep Mode, restore the power (V_{LCD} , V_D etc.) and then turn on COM and SEG drivers.

ALL PIXELS ON (APO)

When set, this flag will force all SEG drivers to output ON signals, disregarding the data stored in the display buffer.

This flag has no effect when Display Enable is OFF and it has no effect on data stored in RAM.

INVERSE (PXV)

When this flag set to ON, SEG drivers will output the inverse of the value it received from the display buffer RAM (bit-wise inversion). This flag has no impact on data stored in RAM.

PARTIAL DISPLAY

UC1604c provides flexible control of Mux Rate and active display area. Please refer to commands Set COM End, Set Partial Display Start, and Set Partial Display End for more detail.

ITO LAYOUT AND LC SELECTION

Since COM scanning pulses of UC1604c can be as short as $91\mu S$, it is critical to control the RC delay of COM and SEG signal to minimize crosstalk and maintain good mass production consistency.

COM TRACES

Excessive COM scanning pulse RC decay can cause fluctuation of contrast and increase COM direction crosstalk.

Please limit the worst case of COM signals RC delay (RC $_{\text{MAX}}$) as calculated below

$$(R_{ROW} / 2.7 + R_{COM}) \times C_{ROW} < 9.23 \mu S$$

where

 C_{ROW} : LCD loading capacitance of one row of pixels. It can be calculated by C_{LCD}/Mux -Rate, where C_{LCD} is the LCD panel capacitance.

R_{ROW}: ITO resistance over one row of pixels within the active area

R_{COM}: COM routing resistance from IC to the active area + COM driver output impedance.

In addition, please limit the min-max spread of RC decay to be:

$$|RC_{MAX} - RC_{MIN}| < 2.76 \mu S$$

so that the COM distortions on the top of the screen to the bottom of the screen are uniform.

(Use worst case values for all calculations)

SEG TRACES

Excessive SEG signal RC decay can cause image dependent changes of medium gray shades and sharply increase the crosstalk of SEG direction.

For good image quality, please minimize SEG ITO trace resistance and limit the worst case of SEG signal RC delay as calculated below.

$$(R_{COL} / 2.7 + R_{SEG}) \times C_{COL} < 6.30 \mu S$$

where

 C_{COL} : LCD loading capacitance of one pixel column. It can be calculated by C_{LCD} / (# of column), where C_{LCD} is the LCD panel capacitance.

R_{COL}: ITO resistance over one column of pixels within the active area

R_{SEG}: SEG routing resistance from IC to the active area + SEG driver output impedance.

(Use worst case values for all calculations)

SELECTING LIQUID CRYSTAL

The selection of LC material is crucial to achieve the optimum image quality of finished LCM.

When $(V_{90}-V_{10})/V_{10}$ is too large, image contrast will deteriorate, and images will look murky and dull.

When $(V_{90}-V_{10})/V_{10}$ is too small, image contrast will become too strong, and crosstalk will increase.

For the best result, it is recommended the LC material has the following characteristics:

$$(V_{90}-V_{10})/V_{10} = (V_{ON}-V_{OFF})/V_{OFF} \times 0.72 \sim 0.80$$

where V_{90} and V_{10} are the LC characteristics, and V_{ON} and V_{OHF} are the ON and OFF V_{RMS} voltage produced by LCD driver IC at the specific Mux-rate.

Two examples are provided below:

Duty	Bias	V _{ON} /V _{OFF} -1	x0.80	x0.72
1/65	1/9	13.3%	10.6%	9.6%
1/65	1/8	13.1%	10.5%	9.5%

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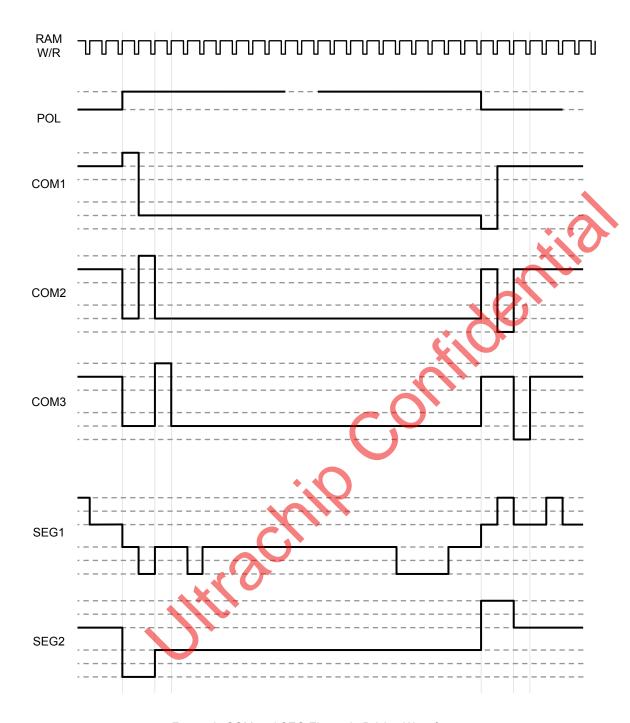


FIGURE 2: COM and SEG Electrode Driving Waveform

HOST INTERFACE

As summarized in the table below, UC1604c supports 2 8-bit parallel bus protocols and 3 serial bus protocols. Designers can choose either the 8-bit parallel bus to achieve high data transfer rate, or use serial bus to create compact LCD modules and minimize connector pins.

				Bus Type					
		8080	6800	S8(4-wire)	S9(3-wire)	I ² C(2-wire)			
	Width	8-bit	8-bit		Serial				
	Access	Read	/ Write	Read (stat	tus) / Write	R/W			
	BM[1:0]	10	11	00	01	01			
Pins	D[7]	Data	Data		0	1			
	CS[1:0]		Chip		A[3:2]				
Data	CD		Control/Data		()			
≪	WR0	WR	R/W		0				
Control	WR1	RD	EN		0				
ပိ	D[6,2,1]	Da	ata						
	D[5:3], D[0]	Da	ata	D[5:3]=SDA, D[0]=SCK					

Connect unused control pins and data bus pins to V_{DD} for "H" or V_{SS} for "L".

	CS Disable Bus Interface	CS Init. Bus State	RESET Init. Bus State
8-bit	✓	-	✓
S8 or S9	✓	/	✓
I ² C	_	<i>- -</i>	✓

CS disable bus interface – CS can be used to disable Bus Interface Write / Read Access.

"IHISCL

• RESET can be pin reset / soft reset / power on reset.

Table 3: Host interfaces Summary

PARALLEL INTERFACE

The timing relationship between UC1604c internal control signal RD, WR and their associated bus actions are shown in the figure below.

The Display RAM read interface is implemented as a twostage pipeline. This architecture requires that, every time memory address is modified, either in parallel mode or serial mode, by either Set CA or Set PA command, a dummy read cycle need to be performed before the actual data can propagate through the pipeline and be read from data port D[7:0].

There is no pipeline in write interface of Display RAM. Data is transferred directly from bus buffer to internal RAM on the rising edges of write pulses.

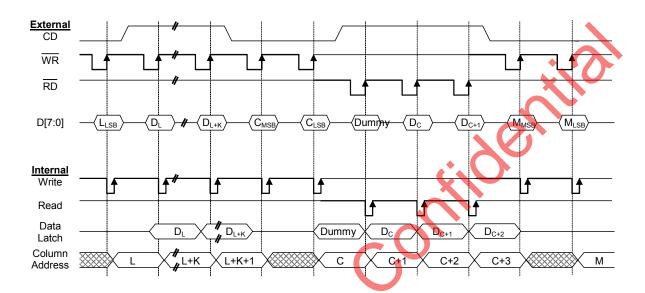


Figure 3: Parallel Interface & Related Internal Signals

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SERIAL INTERFACE

UC1604c supports three serial modes, one 4-wire SPI mode (S8), one 3-wire SPI mode (S9) and one 2-wire SPI mode (I²C). Bus interface mode is determined by the wiring of the BM[1:0] and D[7]. See table in last page for more detail.

S8 (4-WIRE) INTERFACE

Pins CS[1:0] are used for chip select and bus cycle reset. Pin CD is used to determine the content of the data been transferred. During each write cycle, 8 bits of data, MSB first, are latched on eight rising SCK edges into an 8-bit data holder.

If CD=0, the data byte will be decoded as command. If CD=1, these 8 bits will be treated as data and transferred to proper address in the Display Data RAM on the rising edge of the last SCK pulse. Pin CD is examined when SCK is pulled low for the LSB (D0) of each token.

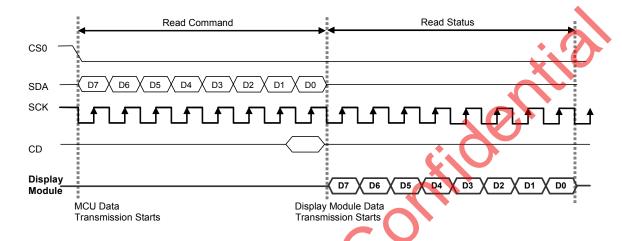


FIGURE 4.a: 4-wire Serial Interface (S8) - Read

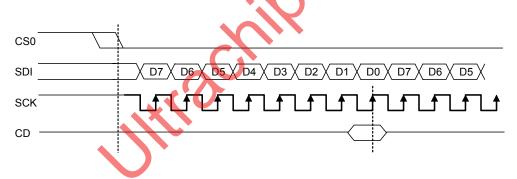


Figure 4.b: 4-wire Serial Interface (S8) - Write

S9 (3-WIER) INTERFACE

Pins CS[1:0] are used for chip select and bus cycle reset. On each write cycle, the first bit is CD, which determines the content of the following 8 bits of data, MSB first. These 8 command or data bits are latched on rising SCK edges into an 8-bit data holder. If CD=0, the data byte will be decoded as command. If CD=1, this 8-bit will be treated as data and

transferred to proper address in the Display Data RAM at the rising edge of the last SCK pulse.

By sending CD information explicitly in the bit stream, control pin CD is not used, and should be connected to either V_{DD} or V_{SS} . The toggle of CS0 (or CS1) for each byte of data/command is recommended but optional.

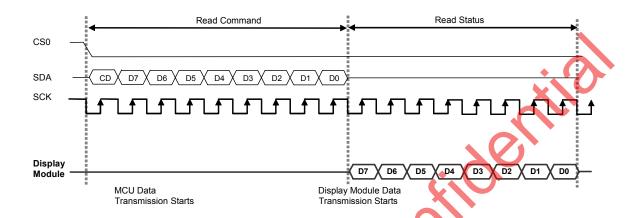


FIGURE 5.a: 3-wire Serial Interface (S9) - Read

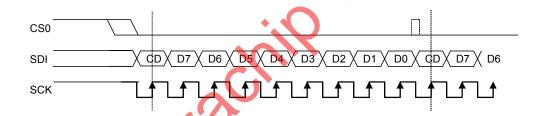


Figure 5.b: 3-wire Serial Interface (S9) - Write

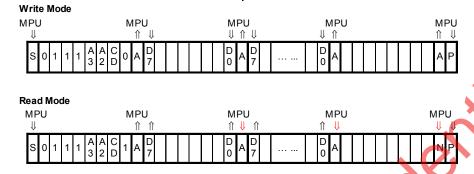
I²C (2-WIRE) INTERFACE

When BM[1:0] is set to "LH" and D[7] is set to "H", UC1604c is configured as an I²C bus signaling protocol compliant slave device. Please refer to I²C standard for details of the bus signaling protocol, and AC Characteristic section for timing parameters of UltraChip implementation.

In this mode, pins CS[1:0] become A[3:2] and is used to configure UC1604c' device address. Proper wiring to $V_{\rm DD}$ or $V_{\rm SS}$ is required for the IC to operate properly for I²C mode.

Each UC1604c I²C interface sequence starts with a "S" (Start) from the bus master, followed by a sequence header, containing a device address, the mode of transfer (CD, 0:Control, 1:Data), and the direction of the transfer (RW, 0:Write, 1:Read).

Since both WR and CD are expressed explicitly in the header byte, the control pins WR[1:0] and CD are not used in I^2C mode and should be connected to $V_{\rm SS}$.



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The direction (read or write) and content type (command or data) of the data bytes following each header byte are fixed for the sequence. To change the direction ($R\Leftrightarrow W$) or the content type ($C\Leftrightarrow D$), start a new sequence with a START (S) flag, followed by a new header.

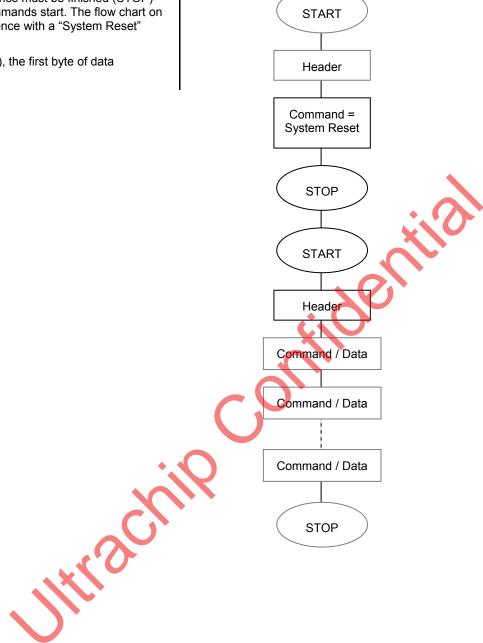
After receiving the header, the UC1604c will send out a "A" (Acknowledge signal, pull to "L"). Then, depends on the setting of the header, the transmitting device (either the bus master or UC1604c) will start placing data bits on SDA, MSB to LSB, and the sequence will repeat until a STOP signal (P, in WRITE mode), or an N (Not Acknowledged, in READ mode) is sent by the bus master.

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When using l^2C serial mode, if command System Reset is to be written, the writing sequence must be finished (STOP) before succeeding data or commands start. The flow chart on the right shows a writing sequence with a "System Reset" command.

Note that, for data read (CD=1), the first byte of data transmitted will be dummy.



HOST INTERFACE REFERENCE CIRCUIT

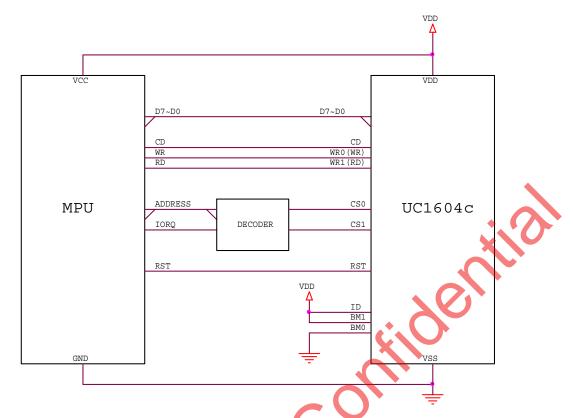


FIGURE 6: 8080/8bit parallel mode reference circuit

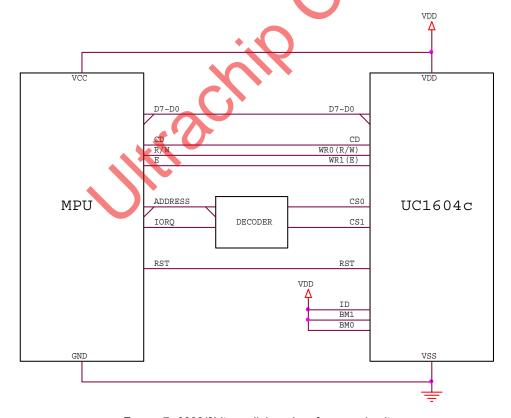


FIGURE 7: 6800/8bit parallel mode reference circuit

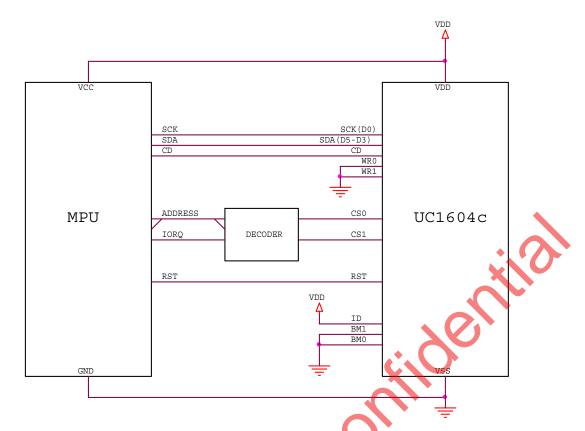


FIGURE 8: Serial-8 serial mode reference circuit

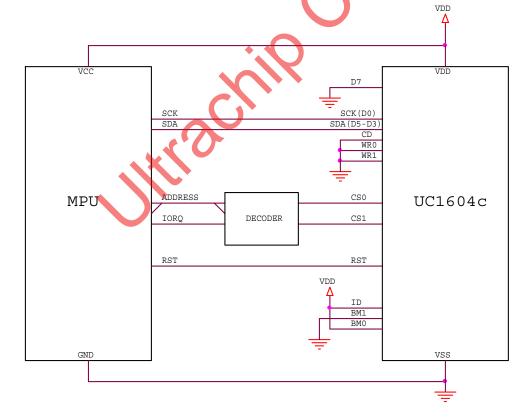


FIGURE 9: Serial-9 serial mode reference circuit

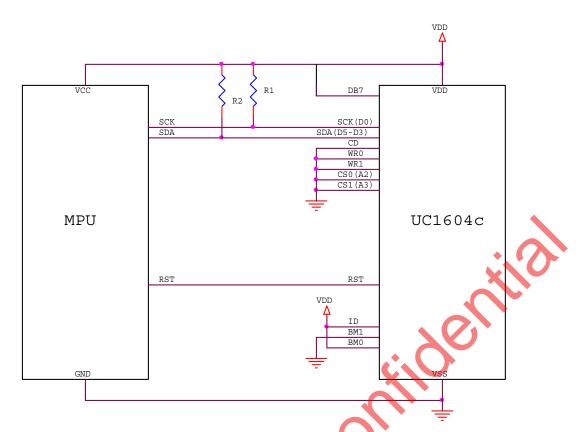


FIGURE 10: I²C serial mode reference circuit

Note

- The ID pins are for production control. The connection will affect the content of D[7] of the 1-st byte of the Get Status command. Connect to V_{DD} for "H" or V_{SS} for "L".
- RST pin is optional. When the RST pin is not used, connect it to V_{DD}.
- When using I²C serial mode, CS1/0 are user configurable and affect A[3:2] of device address.
- R1, R2: $2k \sim 10k \Omega$, use lower resistor for bus speed up to 3.6MHz, use higher resistor for lower power.

DISPLAY DATA RAM (DDRAM)

DATA ORGANIZATION

The input display data is stored to a dual port static DDRAM (DDRAM, for Display Data RAM) organized as 65x192.

After setting CA and RA, the subsequent data write cycle will store the data for the specified pixel to the proper memory location.

Please refer to the map in the following page between the relation of COM, SEG, SRAM, and various memory control registers.

DISPLAY DATA RAM ACCESS

The Display RAM is a special purpose dual port RAM which allows asynchronous access to both its column and row data. Thus, RAM can be independently accessed both for Host Interface and for display operations.

DISPLAY DATA RAM ADDRESSING

A Host Interface (HI) memory access operation starts with specifying Row Address (RA) and Column Address (CA) by issuing *Set Row Address* and *Set Column Address* commands.

If wrap-around (WA, AC[0]) is OFF (0), CA will stop increasing after reaching the end of row (191), and system programmers need to set the values of PA and CA explicitly.

If WA is ON (1), when CA reaches end of page, CA will be reset to 0 and PA will increase or decrease, depending on the setting of row Increment Direction (RID, AC[2]). When PA reaches the boundary of RAM (i.e. PA = 0 or 7), PA will be wrapped around to the other end of RAM and continue.

MX IMPLEMENTATION

Column Mirroring (MX) is implemented by selecting either (CA) or (191–CA) as the RAM column address. Changing MX affects the data written to the RAM.

Since MX has no effect of the data already stored in RAM, changing MX does not have immediate effect on the displayed pattern. To refresh the display, refresh the data stored in RAM after setting MX.

ROW MAPPING

COM electrode scanning orders are not affected by Start Line (SL), Fixed Line (FLT & FLB) or Mirror Y (MY, LC[2]). Visually, register SL having a non-zero value is equivalent to scrolling the LCD display up or down (depends on MY) by *SL* rows.

RAM ADDRESS GENERATION

The mapping of the data stored in the display SRAM and the scanning electrodes can be obtained by combining the fixed Rm scanning sequence and the following RAM address generation formula.

During the display operation, the RAM line address generation can be mathematically represented as following:

For the 1-st line period of each field

Line = SL

Otherwise

Line = Mod(Line+1, 64)

Where Mod is the modular operator, and *Line* is the bit slice line address of RAM to be outputted to column drivers. Line 0 corresponds to the first bit-slice of data in RAM.

The above *Line* generation formula produce the "loop around" effect as it effectively resets *Line* to 0 when *Line+1* reaches 64.

MY IMPLEMENTATION

Row Mirroring (MY) is implemented by reversing the mapping order between row electrodes and RAM, i.e. the mathematical address generation formula becomes:

For the 1st line period of each field

Line = Mod(SL + MR -1, 64)

Otherwise

Line = Mod(Line-1, 64)

Visually, the effect of MY is equivalent to flipping the display upside down. The data stored in display RAM is not affected by MY.



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PAGES 0 Address Do Rich Do Rich	DA 10 01		Line																	Panel		/=0		/=1
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Example for memory mapping: let MX = 0, MY = 0, SL = 0, according to the data shown in the above table:

 \Rightarrow Page 0 SEG 1 (D7-D0) : 0001 1111b \Rightarrow Page 0 SEG 2 (D7-D0) : 1100 1100b

RESET & POWER MANAGEMENT

TYPES OF RESET

UC1604c has two different types of Reset:

Power-ON-Reset and System-Reset.

Power-ON-Reset is performed right after V_{DD} is connected to power. Power-On-Reset will first wait for about ~5mS,

depending on the time required for V_{DD} to stabilize, and then trigger the $System\ Reset$.

System Reset can also be activated by connecting the RST pin to ground.

In the following discussions, Reset means System Reset.

The differences between pin reset and software reset are

Procedure (Restoring to default value)	Pin Reset (Power On Reset)	Software Reset
Column Address : CA[7:0]=0	V	V
Page Address : PA[3:0]=0	V	V
RAM Address Control : AC[2:0]=001b	V	V
Temp. Compensation : TC[1:0]=00b	V	X
Power Control : PC[2:0]=110b	V	X
Scroll Line : SL[5:0]=0	V	X
Vbias Potentiometer : PM[7:0]=49h	V	X
Partial Display Control : LC[5]=0b	V	X
Frame Rate : LC[4:3]	V	X
All-Pixel-On : DC[1]=0b	V	X
Inverse Display : DC[0]=0b	V	X
Display Enable : DC[2]=0b	V	X
LCD Mapping Control : LC[2:1]=00b	V	X
Test Control	V	X
LCD Bias Ratio : BR[1:0]=11b	V	X
COM End : CEN[6:0]=63d	V	X
Partial Display Command	V	X
MTP Function Control	V	X

RESET STATUS

When UC1604c enters RESET sequence:

- · Operation mode will be "Reset"
- All control registers are reset to default values. Refer to Control Registers for details of their default values.

OPERATION MODES

UC1604c has three operating modes (OM): Reset, Sleep, Normal.

For each mode, the related statuses are as below:

Mode	Reset	Sleep	Normal
OM	00	10	11
Host Interface	Active	Active	Active
Clock	OFF	OFF	ON
LCD Drivers	OFF	OFF	ON
Charge Pump	OFF	OFF	ON
Draining Circuit	ON	ON	OFF

Table 4: Operating Modes

65x192 STN Controller-Driver

CHANGING OPERATION MODE

In addition to Power-ON-Reset, two commands will initiate OM transitions:

Set Display Enable, and System Reset.

When DC[2] is modified by Set Display Enable, OM will be updated automatically. There is no other action required to enter Sleep mode.

OM changes are synchronized with the edges of UC1604c' internal clock. To ensure consistent system states, wait at least $10\mu S$ after issuing the Set Display Enable command or triggering System Reset.

Action	Mode	ОМ
RST_ pin pulled "L" Power ON reset	Reset	00
Set Driver Enable to "0"	Sleep	10
Set Driver Enable to "1"	Normal	11

Table 5: OM changes

Both Reset mode and Sleep mode drain the charges stored in the external capacitors C_{B0} , C_{B1} , and C_{L} . When entering Reset mode or Sleep mode, the display drivers will be disabled.

The difference between Sleep mode and Reset mode is that Reset mode clears all control registers and restores them to default values, while Sleep mode retains all the control registers values set by the user.

It is recommended to use Sleep Mode for Display OFF operations as UC1604c consumes very little energy in Sleep mode (typically under 5µA).

EXITING SLEEP MODE

UC1604c contains internal logic to check whether V_{LCD} and V_{D} are ready before releasing COM and SEG drivers from their idle states. When exiting Sleep or Reset mode, COM and SEG drivers will not be activated until UC1604c internal voltage sources are restored to their proper values.

Milachill

POWER-UP SEQUENCE

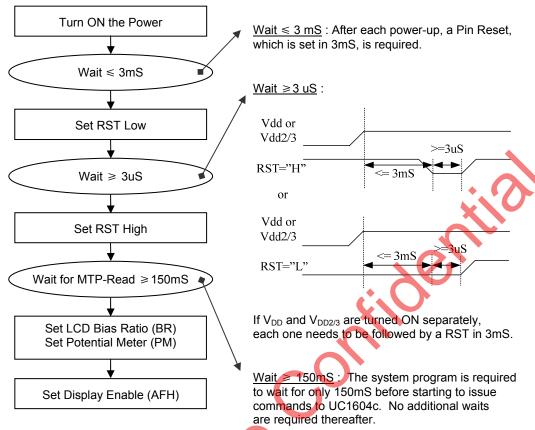


FIGURE 11: Reference Power-Up Sequence

There's no delay needed while turning ON V_{DD} and V_{DD2/3}, and either one can be turned ON first.

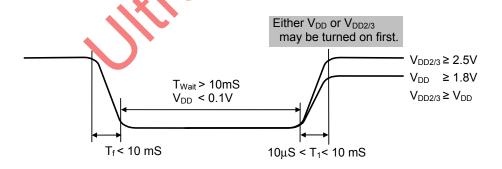


Figure 12: Power Off-On Sequence

ENTER/EXIT SLEEP MODE SEQUENCE

UC1604c enters Sleep mode from Display mode by issuing Set Display OFF command. To exit Sleep mode, Set Display ON.

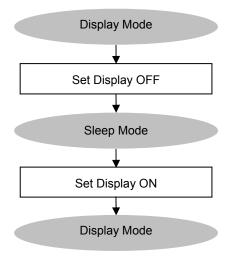


Figure 13: Enter/Exit Sleep Mode Sequence

Power-Down Sequence

To prevent the charge stored in capacitor C_L causing abnormal residue horizontal line on display when V_{DD} is switched off, use Reset mode to enable the built-in charge draining circuit to discharge these external capacitors.

When internal V_{LCD} is not used, UC1604c will *NOT* drain V_{LCD} during RESET. System designers need to make sure external V_{LCD} source is properly drained off before turning off V_{DD} .

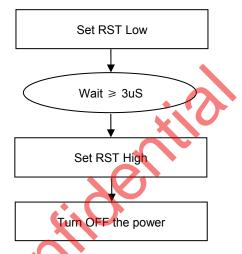


FIGURE 14: Reference Power-Down Sequence

Machil

MULTI-TIME PROGRAM NV MEMORY

OVERVIEW

MTP feature is available for UC1604c such that LCM makers can record an PM offset value in non-volatile memory cells, which can then be used to adjust the effective V_{LCD} value, in order to achieve high level of consistency for LCM contrast across all shipments.

To accomplish this purpose, three operations are supported by UC1604c:

MTP-Erase, MTP-Program, MTP-Read.

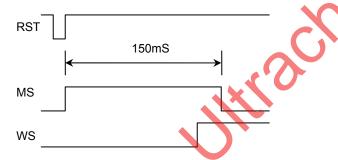
MTP-Program requires an external power source supplied to TST4 pin. MTP allows to program at least 10 times and should be performed only by the LCM makers.

MTP-Read is facilitated by the internal DC-DC converter builtin on UC1604c, no external power source is required, and it is performed automatically after hardware RESET (power-ON and pin RESET).

OPERATION FOR THE SYSTEM USERS

For the MTP version of UC1604c, the content of the NV memory will be read automatically after the power-on and hardware pin RESET. There is no user intervention or external power source required. When set up properly, the V_{LCD} will be fine tuned to achieve high level of consistency for the LCM contrast.

The MTP-READ is a relatively slow process and the time required can vary quite a bit. For a successful MTP-READ operation, the MS and WS bits in the *Read Status* commands will exhibit the following waveforms.



As illustrated above, the {MS, WS} will go through a $\{0,0\} \Rightarrow \{1,0\} \Rightarrow \{1,1\} \Rightarrow \{0,1\}$ transition. When the {MS, WS}= $\{0,1\}$ state is reached, it means the LCM is ready to be turned on.

Although user can use *Read Status* command in a polling loop to make sure {MS, WS}={0, 1} before proceeding with the normal operations, however, it may be simpler to just issue Set Display Enable command every 0.5~2 second, repeatedly, together with other LCM optimization settings, such as BR, CEN, TC, etc.

The above "Periodical re-initializing" approach is also an effective safeguard against accidental display off events such as

- ESD strikes
- Mechanical shocks causing LCM connector to malfunction temporarily

HARDWARE VS. SOFTWARE RESET

The auto-MTP-READ is only performed for hardware RESET (power-ON and RST pin), but not for software *RESET* command. This enables the lcs to turn on display faster without the delay caused by MTP-READ.

It is recommended to use software *RESET* for normal operation control purpose and hardware *RESET* only during the event of power up and power down.

OPERATION FOR THE LCM MAKERS

Always ERASE the MTP NV memory cells, before starting the Write process.

MTP OPERATION FOR LCM MAKERS

1. High voltage supply and timer setting

In MTP Program operation, two different high voltages are needed. In chip design, one high voltage is generated by internal charge pump ($V_{\rm LCD}$), the other high voltage must be input from TST4 by external voltage source.

 V_{LCD} value is controlled by register MTP3 and MTP2. The default values of these two registers are appropriate for most applications.

External TST4 power source is required for MTP Program operation. MTP Programming speed depends on the TST4 voltage. Considering the ITO trace resistance in COG modules, it is recommended to program the MTP cells one at a time, so that the required 10V at TST4 can be maintained with proper consistency.

No external power source is required for MTP Erase and Read operation. For these MTP operations, TST4 should be open, or connected to V_{DD3} .

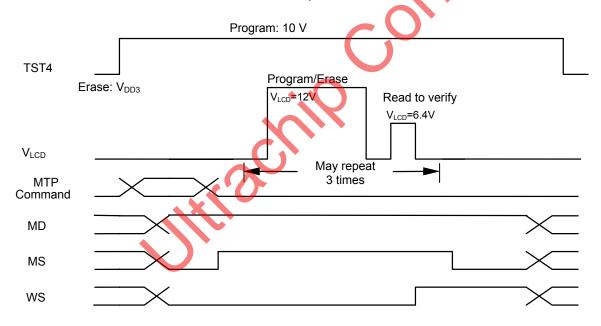
	V _{LCD}	TST4 (external input)
Program	MTP3 : FFh (12V)	10V (1mA per bit)
Erase	MTP3 : FFh (12V)	Floating or V _{DD3}
Read	MTP2:64h (6.4V)	Floating or V _{DD3}

Note: Do Erase before Program and program one bit at a time.

2. Read MTP status bits

With normal Get Status method (CD=0, W/R=1), MTP operation status can be monitored in the real time. There are 3 status bits (WS, MD, MS) in status register. MTP control circuit will read to verify if the operation (program, erase) success or not. If the operation succeeded, and current

operation will be ended with WS=1. If it failed, last operation will be automatically retried two more times. If it fails 3 times, WS will be set to 0 and the operation is aborted. MD is MTP ID, which is either 1 for MTP IC. No transition.



MTP status bits, TST4 & V_{LCD} Waveform

3. MTP Cell Value Usage

There are 6 MTP cell bits. They are divided into two groups for different purpose.

MTP[5:0]: V_{LCD} Trim

When PMO[5]=1: PM with trim = PM - PMO[4:0] When PMO[5]=0: PM with trim = PM + PMO[4:0]

MTP COMMAND SEQUENCE SAMPLE CODES

The following tables are examples of command sequence for MTP Program and Erase operations. These are only to demonstrate some "typical, generic" scenarios. Designers are encouraged to study related sections of the datasheet and find out what the best parameters and control sequences are for their specific design needs.

MTP operations (Erase, Program, Read) and Set Display ON is mutual exclusive. There is no harm done to the IC or the LCM if this is violated. However, the violating commands will be ignored.

Type Required: These items are required

<u>C</u>ustomized: These items are not necessary if customer parameters are the same as default <u>A</u>dvanced: We recommend new users to skip these commands and use default values.

Optional: These commands depend on what users want to do.

C/D The type of the interface cycle. It can be either Command (0) or Data (1)

W/R The direction of dataflow of the cycle. It can be either Write (0) or Read (1).

MTP Program Sample Code

Type	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Chip Action	Comments
R											Set RST pin Low	Wait 3uS after RST is Low
R											Set RST pin High	Wait 150mS
R	0	0	1	0	1	0	0	0	1	1	Set Line Rate	Set LC[4:3]=11b
R	0	0	1	1	1	1	0	1	0	0	Set V _{MTP1} Potentiometer	Set MTP V _{LCD}
R	0	0	0	1	1	0	0	1	0	0		MTP2: 64h (6.4V)
R	0	0	1	1	1	1	0	1	0	1	Set V _{MTP2} Potentiometer	Set MTP V _{LCD}
R	0	0	1	1	1	1	1	1	1	1		MTP3: FFh (12V)
R	0	0	1	1	1	1	0	1	1	0	Set MTP Write Timer	Set MTP Timer
R	0	0	0	0	0	0	0	0	1	0		MTP4: 02h (100mS)
R	0	0	1	1	1	1	0	1	1	1	Set MTP Read Timer	Set MTP Timer
R	0	0	0	0	0	0	0	0	1	0		MTP5: 02h (10mS)
R	0	0	1	1	1	1	1	0	0	1	Set MTP Write Mask	Set MTP Bit Mask
С	0	0	0	0	0	0	0	0	0	7	MTPM	Ex: To program MTPM[0] to be 1, set the value to 00000001b *
R												Apply TST4 voltage
K												Program: 10V
R	0	0	1	0	1	1	1	0	0	9	Set MTP Control	Set MTPC[3]=1
R	0	0	-	-	0	0	1 .	0	1	1		Set MTPC[2:0]=011
R	0	1	-	-	-	- •	X	WS	'	MS	Get Status & PM	Check MTP Status until MS=0, WS=1
R												Remove TST4 voltage
R					•						V _{DD} =0V	Power OFF

^{*} It is recommended that users program one bit at a time.

65x192 STN Controller-Driver

MTP Erase Sample Code

Type	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Chip action	Comments	
R											Set RST pin Low	Wait 3uS after RST is Low	
R											Set RST pin High	Wait 150mS	
R	0	0	1	0	1	0	0	0	1	1	Set Line Rate	Set LC[4:3]=11b	
R	0	0	1	1	1	1	0	1	0	0	Set V _{MTP1} Potentiometer	Set MTP V _{LCD}	
R	0	0	0	1	1	0	0	1	0	0		MTP2: 64h (6.4V)	
R	0	0	1	1	1	1	0	1	0	1	Set V _{MTP2} Potentiometer	Set MTP V _{LCD}	
R	0	0	1	1	1	1	1	1	1	1		MTP3: FFh (12V)	
R	0	0	1	1	1	1	0	1	1	0	Set MTP Write Timer	Set MTP Timer	
R	0	0	0	0	0	0	0	0	1	0		MTP4: 02h (100mS)	
R	0	0	1	1	1	1	0	1	1	1	Set MTP Read Timer	Set MTP Timer	
R	0	0	0	0	0	0	0	0	1	0		MTP5: 02h (10mS)	
R	0	0	1	1	1	1	1	0	0	1	Set MTP Write Mask	Set MTP Bit Mask	
С	0	0	0	0	0	0	1	1	1	1	MTPM1	Ex: To erase MTPM[3:0],	
		_										set the value to 00001111b	
R	0	0	1	0	1	1	1	0	0	0	Set MTP Control	Set MTPC[3]=1	
R	0	0	-	-	0	0	1	0	1	0		Set MTPC[2:0]=010	
R	0	1	-	-	-	-	-	WS	-	MS	Get Status & PM	Check MTP Status until MS=0 WS=1	
R											V _{DD} =0V	Power OFF	
	until MS=0 WS=1												



SAMPLE COMMAND SEQUENCES FOR POWER MANAGEMENT

The following tables are examples of command sequence for power-up, power-down and display ON/OFF operations. These are only to demonstrate some "typical, generic" scenarios. Designers are encouraged to study related

sections of the datasheet and find out what the best parameters and control sequences are for their specific design needs.

Type Required: These items are required

 $\underline{\underline{C}}$ ustomized: These items are not necessary if customer parameters are the same as default $\underline{\underline{A}}$ dvanced: We recommend new users to skip these commands and use default values.

Optional: These commands depend on what users want to do.

C/D The type of the interface cycle. It can be either Command (0) or Data (1)

W/R The direction of data flow of the cycle. It can be either Write (0) or Read (1).

Power-Up

Type	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Chip action	Comments
R											Turn on V_{DD} and $V_{DD2/3}$	Wait until V _{DD} , V _{DD2/3} are stable
R											Wait ≤ 3 mS	
R											Set RST pin Low	Wait 3 uS after RST is Low
R											Set RST pin High	Wait 150mS after RST is High
С	0	0	0	0	1	0	0	1	#	#	Set Temp. Compensation	Set up LCD format specific
R	0	0	1	1	0	0	0	#	#	#	Set LCD Mapping Control	parameters, MX, MY, etc.
Α	0	0	1	0	1	0	0	0	0	#	Set Frame Rate	Fine tune for power, flicker, contrast.
R	0	0	1	1	1	0	1	0	#	#	Set LCD Bias Ratio	
R	0	0	1	0	0	0	0	0	0	1	Set V _{BIAS} Potentiometer	LCD specific operating voltage setting
	0	0	#	#	#	#	#	#	#	#	COL ABIMS L OCCUPANION	
R	0	0	1	0	1	1	1	0	0	0	Set MTP function	Set MTP use & MTP read
	0	0	0	0	0	1	1	0	0	1		
R											Wait ≤ 50 mS	
	1	0	#	#	#	#	#	#	#	#		
0											Write display RAM	Set up display image
											White display IV IIV	cet up display image
	1	0	#	#	#	#	#	#	#	#	•	
R	0	0	1	0	1	0	1	1	1	1	Set Display Enable	

Power-Down

Type	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Chip action	Comments
R					•		7				Set RST pin Low	Wait 3 uS after RST is Low
R											Set RST pin High	
R											Draining capacitor	Wait ~3mS before V _{DD} OFF

DISPLAY-OFF

Type	C/D	W/R	D7	D6	D5	D4	D3	D2	D1	D0	Chip action	Comments
R	0	0	1	0	1	0	1	1	1	0	Set Display Disable	
С	1	0	# #	# #	# #	# #	# #	#	# #	#	Write display RAM	Set up display image (Image update is optional. Data in the RAM is retained through the SLEEP state.)
R	0	0	1	0	1	0	1	1	1	1	Set Display Enable	

ESD CONSIDERATION

UC1600 series products usually are provided in bare die format to customers. This makes the product particularly sensitive to ESD damage during handling and manufacturing process. It is, therefore, highly recommended that LCM makers strictly follow the "JESD 625-A Requirements for Handling Electrostatic-Discharge-Sensitive (ESDS) Devices" when manufacturing LCM.

The following pins in UC1604c require special "ESD Sensitivity" consideration in particular:

	Test Mode	Machin	e Mode	Human Body Mode			
Pins		V_{DD}	V _{SS}	V_{DD}	V _{SS}		
LCD	Driver	150V	150V	1.5KV	1.5KV		
LCM Digita	al Interface	300V	300V	3.0KV	3.0KV		
	TST1/2/4	300V	250V	3.0KV	3.0KV		
LCM HV	C _B pins	300V	300V	3.0KV	3.0KV		
Interface	V _{LCDIN}	200V	200V	3.0KV	3.0KV		
	V_{LCDOUT}	300V	300V	3.0KV	3.0KV		
PWR	/GND	-	300V	-	3.0KV		

According to UltraChip's Mass Production experiences, the ESD tolerance conditions are believed to be very stable and can produce high yield in multiple customer sites. However, special care is still required during handling and manufacturing process to avoid unnecessary yield loss due to ESD damages.

ABSOLUTE MAXIMUM RATINGS

In accordance with IEC134 - notes 1, 2 and 3.

Symbol	Parameter	Min.	Max.	Unit
V_{DD}	Logic Supply voltage	-0.3	+4.0	V
V_{DD2}	LCD Generator Supply voltage	-0.3	+4.0	V
V_{DD3}	Analog Circuit Supply voltage	-0.3	+4.0	V
$V_{DD2/3}$ - V_{DD}	Voltage difference between V _{DD} and V _{DD2/3}		1.2	V
V_{LCD}	LCD Generated voltage	-0.3	+13.2	V
V _{IN} / V _{OUT}	Any input/output	-0.4	V _{DD} + 0.3	V
T_{OPR}	Operating temperature range	-30	+85	°C
T _{STR}	Storage temperature	-55	+125	°C
 V_{DD} is based on V_S Stress values lister 	d above may cause permanent damages to the device.			

Notes

- 1. V_{DD} is based on $V_{SS} = 0V$
- 2. Stress values listed above may cause permanent damages to the device.

SPECIFICATIONS

DC CHARACTERISTICS

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V_{DD}	Supply for digital circuit		1.7	1.8~3.3	3.6	V
$V_{DD2/3}$	Supply for bias & pump		2.6	2.7~3.3	3.6	V
V_{LCD}	Charge pump output	$V_{DD2/3} \ge 2.6V, 25^{\circ}C$		4.8~11.5	11.5	V
V _D	LCD data voltage	$V_{DD2/3} \ge 2.6V, 25^{\circ}C$	0.80		1.32	V
V_{IL}	Input logic LOW				0.1V _{DD}	V
V _{IH}	Input logic HIGH		0.9V _{DD}			V
V _{OL}	Output logic LOW				0.2V _{DD}	V
V_{OH}	Output logic HIGH		0.8V _{DD}		•	V
I _{IL}	Input leakage current				1,5	μА
I _{SB}	Standby current	$V_{DD} = V_{DD2/3} = 3.3V,$ Temp = 85°C			50	μА
C _{IN}	Input capacitance			5	10	PF
C _{OUT}	Output capacitance			5	10	PF
R _{0(SEG)}	SEG output impedance	V _{LCD} = 9V		2200	2800	Ω
R _{0(COM)}	COM output impedance	V _{LCD} = 9V		2200	2800	Ω
F _{FR}	Average Frame Rate	LC[4:3] = 01b	-10%	95	+10%	Hz

POWER CONSUMPTION

 V_{DD} = 2.7V, V_{LCD} = 8.54V PM = 73,Bias Ratio = 11b, Frame Rate = 01b, PMO = 00H, Mux Rate = 65, Temperature = 25°C, Bus mode =6800,

 C_B = 2.2 μ F, All outputs are open circuit. $C_L = 330nF$

Display Pattern	Conditions	Тур.	Max.
All-ON	Bus = idle	175	350
All-OFF	Bus = idle	175	350
2-pixel checker	Bus = idle	196	392
-	Bus = idle (standby current)	-	5

AC CHARACTERISTICS

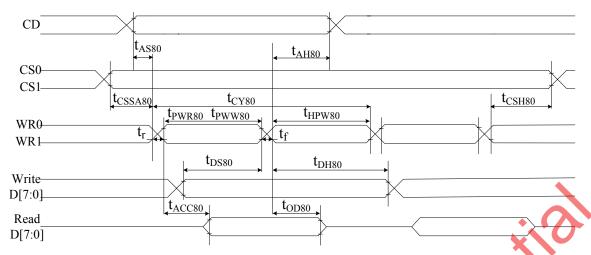


FIGURE 15: Parallel Bus Timing Characteristics (for 8080 MCU)

Symbol	Signal	Description	Condition	Min.	Max.	Unit
$(2.5V \le V_{DD} \le 3.6V$, Ta= –30 to +	85 [°] C)		(Read / Write)		
t _{AS80}	CD	Address setup time		5		nS
t _{AH80}	CD	Address hold time		10	_	110
t _{CSSA80}	CS1, CS0	Chip select setup time		5		nS
t _{CSH80}	CS1, CS0	Chip select hold time		5	_	113
t _{CY80}		System Cycle time		170 / 110		
t _{PWR80} / t _{PWW80}	WR0, WR1	Pulse width		70 / 40	_	nS
t _{HPW80}		High pulse width		70 / 40		
t _{DS80}	D7~D0	Data setup time		35		nS
t _{DH80}	(Write)	Data hold time		5	_	110
t _{ACC80}	D7~D0	Read access time	C _L = 100pF	_	70	nS
t _{OD80}	(Read)	Output disable time	C _L = 100pr	_	40	110
$(1.7V \le V_{DD} < 2.5V_{\odot})$, Ta= -30 to +8	85°C)		(Read / Write)		
t _{AS80}	CD	Address setup time		5		nS
t _{AH80}	CD	Address hold time		10	_	113
t _{CSSA80}	CS1, CS0	Chip select setup time		5		nS
t _{CSH80}	031, 030	Chip select hold time		5	_	113
t _{CY80}	•	System cycle time		270 / 190		
t _{PWR80} / t _{PWW80}	WR0, WR1	Pulse width		120 / 80	-	nS
t _{HPW80}		High pulse width		120 / 80		
t _{DS80}	D7~D0	Data setup time		60		nS
t _{DH80}	(Write)	Data hold time		5	_	113
t _{ACC80}	D7~D0	Read access time	C _L = 100pF	_	115	nS
t _{OD80}	(Read)	Output disable time	CL = 100pr	_	80	113

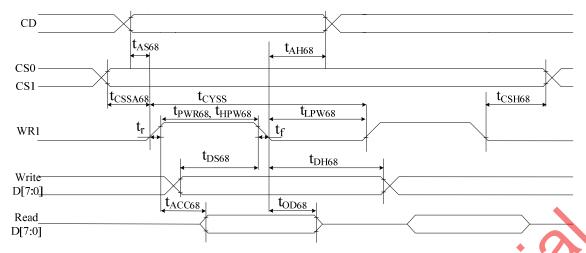


FIGURE 16: Parallel Bus Timing Characteristics (for 6800 MCU)

Symbol	Signal	Description	Condition	Min.	Max.	Unit
$(2.5V \le V_{DD} \le 3.6V$, Ta= –30 to +	85°C)		(Read / Write)		
t _{AS68} t _{AH68}	CD	Address setup time Address hold time		5	-	nS
t _{CSSA68} t _{CSH68}	CS1, CS0	Chip select setup time Chip select hold time		5 5	-	nS
t _{CY68} t _{PWR68} / t _{PWW68} t _{HPW68}	WR1	System cycle time Pulse width High pulse width	ري)	170 / 110 70 / 40 70 / 40	-	nS
t _{DS68} t _{DH68}	D7~D0 (Write)	Data setup time Data hold time		35 5	-	nS
t _{ACC68} t _{OD68}	D7~D0 (Read)	Read access time Output disable time	C _L = 100pF	-	70 40	nS
$(1.7V \le V_{DD} \le 2.5V,$	Ta= -30 to +	85°C)		(Read / Write)		
t _{AS68} t _{AH68}	CD	Address setup time Address hold time		5 10	-	nS
t _{CSSA68} t _{CSH68}	CS1, CS0	Chip select setup time Chip select hold time		5 5	_	nS
t _{CY68} t _{PWR68} / t _{PWW68} t _{HPW68}	WR1	System cycle time Pulse width High pulse width		270 / 190 120 / 80 120 / 80	-	nS
t _{DS68} t _{DH68}	D7~D0 (Write)	Data setup time Data hold time		60 5	-	nS
t _{ACC68}	D7~D0 (Read)	Read access time Output disable time	C _L = 100pF	-	115 80	nS

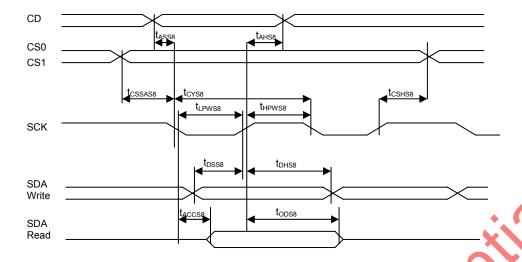


FIGURE 17: Serial Bus Timing Characteristics (for S8)

Symbol	Signal	Description	Condition	Min.	Max.	Unit
$(2.5V \le V_{DD} \le 3.6V)$	′, Ta= –30 to +	85 [°] C)	((Read / Write)		
t _{ASS8} t _{AHS8}	CD	Address setup time Address hold time		5 10	-	nS
t _{CSSAS8} t _{CSHS8}	CS1, CS0	Chip select setup time Chip select hold time		5 5	_	nS
t _{CYS8} t _{LPWS8} t _{HPWS8}	SCK	System Cycle time Low pulse width High pulse width		190 / 70 80 / 20 80 / 20	-	nS
t _{DSS8} t _{DHS8}	SDA (Write)	Data setup time Data hold time	Q	20 10	_	nS
t _{ACC8} t _{OD8}	SDA (Read)	Read access time Output disable time	C _L = 100pF	- -	80 30	nS
$(1.7V \le V_{DD} < 2.5V)$, Ta= –30 to +	85°C)		(Read / Write)		
t _{ASS8} t _{AHS8}	CD	Address setup time Address hold time		5 10	-	nS
t _{CSSAS8} t _{CSHS8}	CS1, CS0	Chip select setup time Chip select hold time		10 10	_	nS
t _{CYS8} t _{LPWS8} t _{HPWS8}	SCK	System Cycle time Low pulse width High pulse width		230 / 110 100 / 40 100 / 40	- - -	nS nS nS
t _{DSS8} t _{DHS8}	SDA (Write)	Data setup time Data hold time		24 10	_	nS
t _{ACC8}	SDA (Read)	Read access time Output disable time	C _L = 100pF	- -	100 60	nS

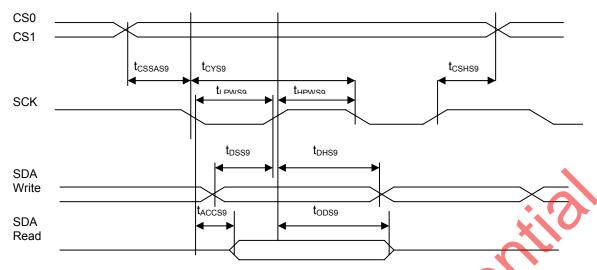


FIGURE 18: Serial Bus Timing Characteristics (for S9)

Symbol	Signal	Description	Condition	Min.	Max.	Unit
$(2.5V \le V_{DD} \le 3.6V$	$(2.5V \le V_{DD} \le 3.6V, Ta = -30 \text{ to } +85^{\circ}C)$					
t _{CSSAS9}	CS1, CS0	Chip select setup time		5	_	nS
t _{CSHS9}	001, 000	Chip select hold time		5		110
t _{CYS9}		System cycle time		190 / 70		
t _{LPWS9}	SCK	Low pulse width		80 / 20	_	nS
t _{HPWS9}		High pulse width		80 / 20		
t _{DSS9}	SDA	Data setup time		20		nS
t _{DHS9}	(Write)	Data hold time		10	_	113
t _{ACC9}	SDA	Read access time	- 100pF	_	80	nS
t _{OD9}	(Read)	Output disable time	C _L = 100pF	_	30	113
$(1.7V \le V_{DD} \le 2.5V,$	Ta= -30 to +	85 [°] C)		(Read / Write)		
t _{CSSAS9}	CS1, CS0	Chip select setup time		10		nS
t _{CSHS9}	CS1, CS0	Chip select setup time		10	_	113
t _{CYS9}		System cycle time		230 / 110		
t _{LPWS9}	SCK	Low pulse width		100 / 40	_	nS
t _{HPWS9}		High pulse width		100 / 40		
t _{DSS9}	SDA 👞	Data setup time		24		nS
t _{DHS9}	(Write)	Data hold time		15	_	113
t _{ACC9}	SDA	Read access time	C. = 100pE	_	100	nS
t _{OD9}	(Read)	Output disable time	C _L = 100pF		60	110

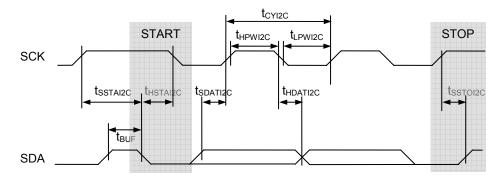


FIGURE 19: Serial bus timing characteristics (for I²C)

Symbol	Signal	Description	Condition	Min.	Max.	Unit
$(2.5V \le V_{DD} \le 3.6V$, Ta= -30 to +	-85°C)		(Read / Write)		
t _{CYI2C}		SCK cycle time		610 / 305		
t _{HPWI2C}	SCK	High pulse width		290 / 110	_	nS
t _{LPWI2C}		Low pulse width		290 / 165		
t _{SSTAI2C}		Setup time – START		28		
t _{HSTAI2C}	SCK	Hold time – START		55		
t _{SDAI2C}	SDA	Setup time – Data		40	_	nS
t _{HDAI2C}	J OBA	Hold time – Data		11		
tsstoi2c		Setup time – STOP		28		
t _{BUF}	SDA	Bus Free time between STOP and START		165	-	nS
$(1.7V \le V_{DD} < 2.5V_{\odot})$, Ta= –30 to +	85°C)		(Read / Write)		
t _{CYI2C}		SCK cycle time		780 / 360		
t _{HPWI2C}	SCK	High pulse width		375 / 130	-	nS
t _{LPWI2C}		Low pulse width		375 / 200		
t _{sstai2} c		Setup time – START		33		
t _{HSTAI2C}	SCK	Hold time – START		80		
t _{SDAI2C}	SDA	Setup time - Data		80	_	nS
t _{HDAI2C}		Hold time - Data		11		
t _{sstoi2C}		Setup time - STOP		33		
t _{BUF}	SDA	Bus Free Time between STOP and START		220	-	nS

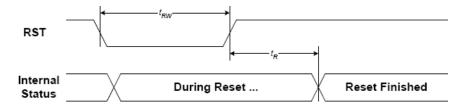
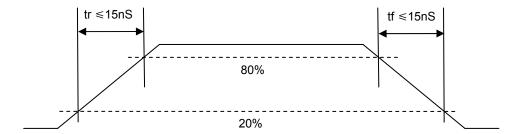


FIGURE 20: Reset Characteristics

 $(1.7V \le V_{DD} \le 3.6V, Ta = -30 \text{ to } +85^{\circ}C)$

Symbol	Signal	Description	Condition	Min.	Max.	Unit
t _{RW}	RST	Reset low pulse width		3	_	μS
t _R	RST, Internal Status	Reset to Internal Status pulse delay		6		mS
				Service		
Note:						

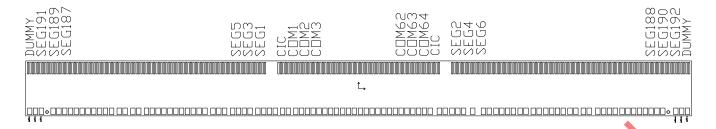






PHYSICAL DIMENSIONS

Circuit / Bump View:



For (Part Number) UC1604cGAA:

For (Part Number) UC1604cGBA:

Die Size: $7480 \mu M \times 652 \mu M \pm 40 \mu M$

Die Thickness: $400 \ \mu M \pm 20 \ \mu M$

Die TTV: $(D_{MAX} - D_{MIN})$ within die $\leq 2 \mu M$

Hardness: 90 Hv \pm 25 Hv Bump Height: 15 μ M \pm 3 μ M

 $(H_{MAX}-H_{MIN})$ within die $\leqslant 2~\mu M$

Bump Size: $15.6 \mu M \times 130 \mu M$

Bump Pitch: $27.6 \mu M$ Bump Area: $2028 \mu M^2$

Coordinate origin: Chip center
Pad reference: Pad center

Die Size: 7480 μM x 652 μM ± 40 μM

Die Thickness: $400 \mu M \pm 20 \mu M$

Die TTV: $(D_{MAX} - D_{MIN})$ within die $\leq 2 \mu M$

Hardness: $90 \text{ Hv} \pm 25 \text{ Hv}$ Bump Height: $12 \mu\text{M} \pm 3 \mu\text{M}$

 $(H_{MAX} - H_{MIN})$ within die $\leq 2 \mu M$

Bump Size:

COM1~64: 15.6 μM x 100 μM

SEG1~192: 15.6 μM x 115 μM

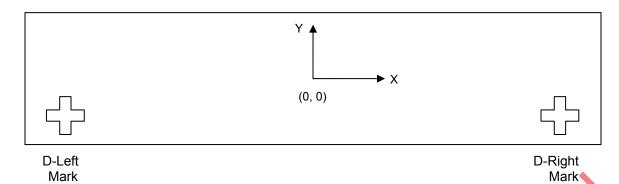
Bump Pitch:27.6 μMMin. Bump Area:1560 μ M^2 Shear Force:> 5g/μ M^2

Coordinate origin: Chip center

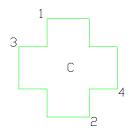
Pad reference: Pad center

65x192 STN Controller-Driver

ALIGNMENT MARK INFORMATION



Shape of the alignment mark:



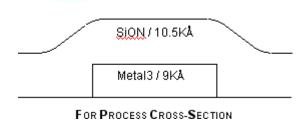
Remark:

The cross mark itself is symmetric both horizontally and vertically.

Coordinates:

	D-Left N	Mark (+)	D-Right Mark (+)		
Point	X	Υ	• X	Y	
1	-3489.5	-245.5	3454.5	-245.5	
2	-3474.5	-280.5	3469.5	-280.5	
3	-3499.5	-255.5	3444.5	-255.5	
4	-3464.5	-270.5	3479.5	-270.5	
С	-3482	-263	3462	-263	

Top Metal and Passivation:



Remark:

Alignment marks are on Metal3 under Passivation

PAD COORDINATES

For (Part Number) UC1604cGAA:

#	Pad	Х	Y	W	Н
1	DUMMY	-3676	-255	50	73
2	DUMMY	-3611	-255	50	73
3	DUMMY	-3546	-255	50	73
4	DUMMY	-3414.75	-255	50	73
5	DUMMY	-3349.75	-255	50	73
6	CS0	-3284.75	-255 -255	50	73
7	CS1	-3219.75	-255	50	73
8	VDDX	-3154.75	-255	50	73
9	RSTB	-3089.75	-255	50	73
10	CD	-3024.75	-255	50	73
11	WR0	-2959.75	-255	50	73
12	VDDX	-2894.75	-255	50	73
13	WR1	-2829.75	-255 -255	50	73
14	D0	-2761.35	-255	50	73
15	D1	-2674.65	-255	50	73
16	D2				73
		-2609.65	-255	50	
17	D3	-2522.95	-255	50	73
18	D4	-2457.95	-255	50	73
19	D5	-2371.25	-255	50	73
20	D6 VDDX	-2306.25	-255 255	50	73 73
22		-2241.25	-255	50	
	D7	-2176.25	-255	50	73
23	BM0	-2107.85	-255	50	73
24	VDDX	-2042.85	-255	50	73
25	BM1	-1977.85	-255	50	73
26	ID	-1912.85	-255	50	73
27	VDDX	-1847.85	-255	50	73
28 29	POR vdd	-1782.85 -1717	-255 -255	50 50	73 73
30	DUMMY	-1627.5	-255 -255	50	73
31	DUMMY	-1562.5	-255 -255	50	73
32	DUMMY	-1302.5	-255 -255	50	73
33	vdd	-1497.5	-255 -25 5	50	73
34	vdd	-1343	-255 -255	50	73
35	vdd	-1343	-255	50	73
36	vdd	-1213	-255	50	73
37	vdd2	-1126.3	-255	50	73
38	vdd2	-1061.3	-255	50	73
39	vdd2	-996.3	-255	50	73
40	vdd2	-931.3	-255	50	73
41	DUMMY	-849.3	-255	50	73
42	DUMMY	-784.3	-255	50	73
43	vdd2	-704.3	-255	50	73
44	vdd2	-637.3	-255	50	73
45	vdd2	-572.3	-255	50	73
46	vdd2 vdd3	-507.3	-255	50	73
47	vdd3	-442.3	-255	50	73
48	vdd3	-377.3	-255	50	73
49	vdd3	-312.3	-255	50	73
50	vdd3	-247.3	-255	50	73
50	vuus	-241.3	-200	50	13

#	Pad	Х	Υ	W	Н
51	DUMMY	-178.15	-255	50	73
52	DUMMY	-113.15	-255	50	73
53	DUMMY	-48.15	-255	50	73
54	VSS	21	-255	50	73
55	VSS	86	-255	50	73
56	VSS	151	-255	50	73
57	VSS	216	-255	50	73
58	VSS	281	-255	50	73
59	VSS	346	-255	50	73
60	vss2	411	-255	50	73
61	vss2	476	-255	50	73
62	vss2	541	-255	50	73
63	vss2	606	-255	50	73
64	vss2	671	-255	50	73
65	vss2	736	-255	50	73
66	DUMMY	801	-255	50	73
67	TST4	903	-255	50	73
68	TST4	968	-255	50	73
69	TST4	1044	-255	50	73
70	TST4	1109	-255	50	73
71	TST2	1174	-255	50	73
72	TST2	1275.45	-255	50	73
73	VB0-	1395.35	-255	50	73
74	VB0-	1460.35	-255	50	73
75	VB0-	1535.5	-255	50	73
76	VB0-	1600.5	-255	50	73
77	VB0+	1665.5	-255	50	73
78	VB0+	1730.5	-255	50	73
79	VB0+	1805.65	-255	50	73
80	VB0+	1870.65	-255	50	73
81	VB1-	1952.65	-255	50	73
82	VB1-	2017.65	-255	50	73
83	VB1-	2092.8	-255	50	73
84	VB1-	2157.8	-255	50	73
85	VB1+	2222.8	-255	50	73
86	VB1+	2287.8	-255	50	73
87	VB1+	2362.95	-255	50	73
88	VB1+	2427.95	-255	50	73
89	VLCDIN	2511.95	-255	50	73
90	VLCDIN	2576.95	-255	50	73
91	VLCDIN	2673.95	-255	50	73
92	VLCDIN	2738.95	-255	50	73
93	VLCDOUT	2803.95	-255	50	73
	VI CDOUT	2868.95	-255	50	73
94	VLCDOUT				
94 95	VLCDOUT	2944.95	-255	50	73
			-255 -255	50 50	73 73
95	VLCDOUT	2944.95			
95 96	VLCDOUT VLCDOUT	2944.95 3009.95	-255	50	73
95 96 97	VLCDOUT VLCDOUT DUMMY	2944.95 3009.95 3074.95	-255 -255	50 50	73 73

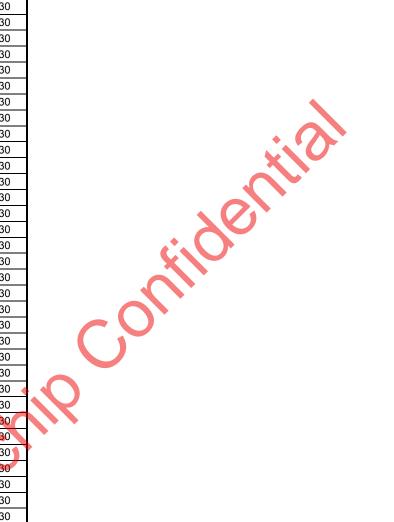
#	Pad	Х	Υ	W	Н
101	DUMMY	3334.95	-255	50	73
102	DUMMY	3399.95	-255	50	73
103	DUMMY	3546	-255	50	73
104	DUMMY	3611	-255	50	73
105	DUMMY	3676	-255	50	73
106	DUMMY	3694.2	225.5	15.6	130
107	SEG192	3666.6	225.5	15.6	130
108	SEG190	3639	225.5	15.6	130
109	SEG188	3611.4	225.5	15.6	130
110	SEG186	3583.8	225.5	15.6	130
111	SEG184	3556.2	225.5	15.6	130
112	SEG182	3528.6	225.5	15.6	130
113	SEG180	3501	225.5	15.6	130
114	SEG178	3473.4	225.5	15.6	130
115	SEG176	3445.8	225.5	15.6	130
116	SEG174	3418.2	225.5	15.6	130
117	SEG172	3390.6	225.5	15.6	130
118	SEG170	3363	225.5	15.6	130
119	SEG168	3335.4	225.5	15.6	130
120	SEG166	3307.8	225.5	15.6	130
121	SEG164	3280.2	225.5	15.6	130
122	SEG162	3252.6	225.5	15.6	130
123	SEG160	3225	225.5	15.6	130
124	SEG158	3197.4	225.5	15.6	130
125	SEG156	3169.8	225.5	15.6	130
126	SEG154	3142.2	225.5	15.6	130
127	SEG152	3114.6	225.5	15.6	130
128	SEG150	3087	225.5	15.6	130
129	SEG148	3059.4	225.5	15.6	130
130	SEG146	3031.8	225.5	15.6	130
131	SEG144	3004.2	225.5	15.6	130
132	SEG142	2976.6	225.5	15.6	130
133	SEG140	2949	225.5	15.6	130
134	SEG138	2921.4	225.5	15.6	130
135	SEG136	2893.8	225.5	15.6	130
136	SEG134	2866.2	225.5	15 .6	130
137	SEG132	2838.6	225.5	15.6	130
138	SEG130	2811	225.5	15.6	130
139	SEG128	2783.4	225.5	15.6	130
140	SEG126	2755.8	225.5	15.6	130
141	SEG124	2728.2	225.5	15.6	130
142	SEG122	2700.6	225.5	15.6	130
143	SEG120	2673	225.5	15.6	130
144	SEG118	2645.4	225.5	15.6	130
145	SEG116	2617.8	225.5	15.6	130
146	SEG114	2590.2	225.5	15.6	130
147	SEG112	2562.6	225.5	15.6	130
148	SEG110	2535	225.5	15.6	130
149	SEG108	2507.4	225.5	15.6	130
150	SEG106	2479.8	225.5	15.6	130
151	SEG104	2452.2	225.5	15.6	130
152	SEG102	2424.6	225.5	15.6	130
153	SEG100	2397	225.5	15.6	130
154	SEG98	2369.4	225.5	15.6	130

#	Pad	Χ	Υ	W	Н
155	SEG96	2341.8	225.5	15.6	130
156	SEG94	2314.2	225.5	15.6	130
157	SEG92	2286.6	225.5	15.6	130
158	SEG90	2259	225.5	15.6	130
159	SEG88	2231.4	225.5	15.6	130
160	SEG86	2203.8	225.5	15.6	130
161	SEG84	2176.2	225.5	15.6	130
162	SEG82	2148.6	225.5	15.6	130
163	SEG80	2121	225.5	15.6	130
164	SEG78	2093.4	225.5	15.6	130
165	SEG76	2065.8	225.5	15.6	130
166	SEG74	2038.2	225.5	15.6	130
167	SEG72	2010.6	225.5	15.6	130
168	SEG70	1983	225.5	15.6	130
169	SEG68	1955.4	225.5	15.6	130
170	SEG66	1927.8	225.5	15.6	130
171	SEG64	1900.2	225.5	15.6	130
172	SEG62	1872.6	225.5	15.6	130
173	SEG60	1845	225.5	15.6	130
174	SEG58	1817.4	225.5	15.6	130
175	SEG56	1789.8	225.5	15.6	130
176	SEG54	1762.2	225.5	15.6	130
177	SEG52	1734.6	225.5	15.6	130
178	SEG50	1707	225.5	15.6	130
	SEG48	1679.4	225.5		130
179 180	SEG46	1651.8	225.5	15.6 15.6	130
181	SEG44	1624.2	225.5	15.6	130
182	SEG42	1596.6	225.5	15.6	130
183	SEG40	1569	225.5	15.6	130
184	SEG38	1541.4	225.5	15.6	130
185	SEG36	1513.8	225.5	15.6	130
186	SEG34	1486.2	225.5	15.6	130
187	SEG32	1458.6	225.5	15.6	130
188	SEG30	1431	225.5	15.6	130
189	SEG28	1403.4	225.5	15.6	130
190	SEG26	1375.8	225.5	15.6	130
191				15.6	130
192	SEG24 SEG22	1348.2 1320.6	225.5 225.5	15.6	130
193	SEG20	1293	225.5	15.6	130
193	SEG18	1265.4	225.5	15.6	130
195	SEG16	1237.8	225.5	15.6	130
196	SEG14	1210.2	225.5	15.6	130
190	SEG12	1182.6	225.5	15.6	130
198	SEG10	1155	225.5	15.6	130
199	SEG8	1127.4	225.5	15.6	130
200	SEG6	1099.8	225.5	15.6	130
201	SEG4	1099.6	225.5	15.6	130
202	SEG2	1072.2	225.5	15.6	130
203	COMS	898.5	225.5	15.6	130
203	COM64	870.9	225.5	15.6	130
204	COM63	843.3	225.5	15.6	130
-	COM62				130
206	COM62 COM61	815.7	225.5	15.6 15.6	130
207		788.1 760.5	225.5	15.6	
208	COM60	7 00.5	225.5	15.6	130

#	Pad	X	Υ	W	Н
209	COM59	732.9	225.5	15.6	130
210	COM58	705.3	225.5	15.6	130
211	COM57	677.7	225.5	15.6	130
212	COM56	650.1	225.5	15.6	130
213	COM55	622.5	225.5	15.6	130
214	COM54	594.9	225.5	15.6	130
215	COM53	567.3	225.5	15.6	130
216	COM52	539.7	225.5	15.6	130
217	COM51	512.1	225.5	15.6	130
218	COM50	484.5	225.5	15.6	130
219	COM49	456.9	225.5	15.6	130
220	COM48	429.3	225.5	15.6	130
221	COM47	401.7	225.5	15.6	130
222	COM46	374.1	225.5	15.6	130
223	COM45	346.5	225.5	15.6	130
224	COM44	318.9	225.5	15.6	130
225	COM43	291.3	225.5	15.6	130
226	COM42	263.7	225.5	15.6	130
227	COM41	236.1	225.5	15.6	130
228	COM40	208.5	225.5	15.6	130
229	COM39	180.9	225.5	15.6	130
230	COM38	153.3	225.5	15.6	130
231	COM37	125.7	225.5	15.6	130
232	COM36	98.1	225.5	15.6	130
233	COM35	70.5	225.5	15.6	130
234	COM34	42.9	225.5	15.6	130
235	COM33	15.3	225.5	15.6	130
236	COM32	-12.3	225.5	15.6	130
237	COM31	-39.9	225.5	15.6	130
238	COM30	-67.5	225.5	15.6	130
239	COM29	-95.1	225.5	15.6	130
240	COM28	-122.7	225.5	15.6	130
241	COM27	-150.3	225.5	15.6	130
242	COM26	-177.9	225.5	15.6	130
243	COM25	-205.5	225.5	15.6	130
244	COM24	-233.1	225.5	15.6	130
245	COM23	-260.7	225.5	15.6	130
246	COM22	-288.3	225.5	15.6	130
247	COM21	-315.9	225.5	15.6	130
248	COM20	-343.5	225.5	15.6	130
249	COM19	-371.1	225.5	15.6	130
250	COM18	-398.7	225.5	15.6	130
251	COM17	-426.3	225.5	15.6	130
252	COM16	-453.9	225.5	15.6	130
253	COM15	-481.5	225.5	15.6	130
254	COM14	-509.1	225.5	15.6	130
255	COM13	-536.7	225.5	15.6	130
256	COM12	-564.3	225.5	15.6	130
257	COM10	-591.9 -619.5	225.5	15.6 15.6	130 130
258	COM10	-619.5	225.5	15.6	130
259	COM9	-647.1 -674.7	225.5 225.5	15.6 15.6	130
260	COM8	-674.7 -702.3	225.5	15.6 15.6	130
261	COM6	-702.3 -729.9	225.5	15.6 15.6	130
262	COM6	-129.9	223.3	15.6	130

#	Pad	Χ	Υ	W	Н
263	COM5	-757.5	225.5	15.6	130
264	COM4	-785.1	225.5	15.6	130
265	COM3	-812.7	225.5	15.6	130
266	COM2	-840.3	225.5	15.6	130
267	COM1	-867.9	225.5	15.6	130
268	COMS	-895.5	225.5	15.6	130
269	SEG1	-1045.1	225.5	15.6	130
270	SEG3	-1072.7	225.5	15.6	130
271	SEG5	-1100.3	225.5	15.6	130
272	SEG7	-1127.9	225.5	15.6	130
273	SEG9	-1155.5	225.5	15.6	130
274	SEG11	-1183.1	225.5	15.6	130
275	SEG13	-1210.7	225.5	15.6	130
276	SEG15	-1238.3	225.5	15.6	130
277	SEG17	-1265.9	225.5	15.6	130
278	SEG19	-1293.5	225.5	15.6	130
279	SEG21	-1321.1	225.5	15.6	130
280	SEG23	-1348.7	225.5	15.6	130
281	SEG25	-1376.3	225.5	15.6	130
282	SEG27	-1403.9	225.5	15.6	130
283	SEG29	-1431.5	225.5	15.6	130
284	SEG31	-1459.1	225.5	15.6	130
285	SEG33	-1486.7	225.5	15.6	130
286	SEG35	-1514.3	225.5	15.6	130
287	SEG37	-1541.9	225.5	15.6	130
288	SEG39	-1569.5	225.5	15.6	130
289	SEG41	-1597.1	225.5	15.6	130
290	SEG43	-1624.7	225.5	15.6	130
291	SEG45	-1652.3	225.5	15.6	130
292	SEG47	-1679.9	225.5	15.6	130
293	SEG49	-1707.5	225.5	15.6	130
294	SEG51	-1735.1	225.5	15.6	130
295	SEG53	-1762.7	225.5	15.6	130
296	SEG55	-1790.3	225.5	15.6	130
297	SEG57	-1817.9	225.5	15.6	130
298	SEG59	-1845.5	225.5	15.6	130
299	SEG61	-1873.1	225.5	15.6	130
300	SEG63	-1900.7	225.5	15.6	130
301	SEG65	-1928.3	225.5	15.6	130
302	SEG67	-1955.9	225.5	15.6	130
303	SEG69	-1983.5	225.5	15.6	130
304	SEG71	-2011.1	225.5	15.6	130
305	SEG73	-2038.7	225.5	15.6	130
306	SEG75	-2066.3	225.5	15.6	130
307	SEG77	-2093.9	225.5	15.6	130
308	SEG79	-2121.5	225.5	15.6	130
309	SEG81	-2149.1	225.5	15.6	130
310	SEG83	-2176.7	225.5	15.6	130
311	SEG85	-2204.3	225.5	15.6	130
312	SEG87	-2231.9	225.5	15.6	130
313	SEG89	-2259.5	225.5	15.6	130
314	SEG91	-2287.1	225.5	15.6	130
315	SEG93	-2314.7	225.5	15.6	130
316	SEG95	-2342.3	225.5	15.6	130

#	Pad	Х	Υ	W	Н
317	SEG97	-2369.9	225.5	15.6	130
318	SEG99	-2397.5	225.5	15.6	130
319	SEG101	-2425.1	225.5	15.6	130
320	SEG103	-2452.7	225.5	15.6	130
321	SEG105	-2480.3	225.5	15.6	130
322	SEG107	-2507.9	225.5	15.6	130
323	SEG109	-2535.5	225.5	15.6	130
324	SEG111	-2563.1	225.5	15.6	130
325	SEG113	-2590.7	225.5	15.6	130
326	SEG115	-2618.3	225.5	15.6	130
327	SEG117	-2645.9	225.5	15.6	130
328	SEG119	-2673.5	225.5	15.6	130
329	SEG121	-2701.1	225.5	15.6	130
330	SEG123	-2728.7	225.5	15.6	130
331	SEG125	-2756.3	225.5	15.6	130
332	SEG127	-2783.9	225.5	15.6	130
333	SEG129	-2811.5	225.5	15.6	130
334	SEG131	-2839.1	225.5	15.6	130
335	SEG133	-2866.7	225.5	15.6	130
336	SEG135	-2894.3	225.5	15.6	130
337	SEG137	-2921.9	225.5	15.6	130
338	SEG139	-2949.5	225.5	15.6	130
339	SEG141	-2977.1	225.5	15.6	130
340	SEG143	-3004.7	225.5	15.6	130
341	SEG145	-3032.3	225.5	15.6	130
342	SEG147	-3059.9	225.5	15.6	130
343	SEG149	-3087.5	225.5	15.6	130
344	SEG151	-3115.1	225.5	15.6	130
345	SEG153	-3142.7	225.5	15.6	130
346	SEG155	-3170.3	225.5	15.6	130
347	SEG157	-3197.9	225.5	15.6	130
348	SEG159	-3225.5	225.5	15.6	130
349	SEG161	-3253.1	225.5	15.6	130
350	SEG163	-3280.7	225.5	15.6	130
351	SEG165	-3308.3	225.5	15.6	130
352	SEG167	-3335.9	225.5	15.6	130
353	SEG169	-3363.5	225.5	15.6	130
354	SEG171	-3391.1	225.5	15.6	130
355	SEG173	-3418.7	225.5	15.6	130
356	SEG175	-3446.3	225.5	15.6	130
357	SEG177	-3473.9	225.5	15.6	130
358	SEG179	-3501.5	225.5	15.6	130
359	SEG181	-3529.1	225.5	15.6	130
360	SEG183	-3556.7	225.5	15.6	130
361	SEG185	-3584.3	225.5	15.6	130
362	SEG187	-3611.9	225.5	15.6	130
363	SEG189	-3639.5	225.5	15.6	130
364	SEG191	-3667.1	225.5	15.6	130
365	DUMMY	-3694.7	225.5	15.6	130



65x192 STN Controller-Driver

For (Part Number) UC1604cGBA:

For (Part Number) UC1	604CGBA:			
#	Pad	Χ	Υ	W	Н
1	DUMMY	-3676	-269	50	45
2	DUMMY	-3611	-269	50	45
3	DUMMY	-3546	-269	50	45
4	DUMMY	-3414.75	-269	50	45
5	DUMMY	-3349.75	-269	50	45
6	CS0	-3284.75	-269	50	45
7	CS1	-3219.75	-269	50	45
8	VDDX	-3154.75	-269	50	45
9	RSTB	-3089.75	-269	50	45
10	CD	-3024.75	-269	50	45
11	WR0	-2959.75	-269	50	45
12	VDDX	-2894.75	-269	50	45
13	WR1	-2829.75	-269	50	45
14	D0	-2761.35	-269	50	45
15	D1	-2674.65	-269	50	45
16	D2	-2609.65	-269	50	45
17	D3	-2522.95	-269	50	45
18	D4	-2457.95	-269	50	45
19	D5	-2371.25	-269	50	45
20	D6	-2306.25	-269	50	45
21	VDDX	-2241.25	-269	50	45
22	D7	-2176.25	-269	50	45
23	BM0	-2107.85	-269	50	45
24	VDDX	-2042.85	-269	50	45
25	BM1	-1977.85	-269	50	45
26	ID	-1912.85	-269	50	45
27	VDDX	-1847.85	-269	50	45
28	POR dis	-1782.85	-269	50	45
29	vdd!	-1717	-269	50	45
30	DUMMY	-1627.5	-269	50	45
31	DUMMY	-1562.5	-269	50	45
32	DUMMY	-1497.5		50	45
		-1497.5	-269		
33	vdd		-269	50	45
34	vdd	-1343	-269	50	45
35	vdd	-1278	-269	50	45
36	vdd	-1213	-269	50	45
37	vdd2	-1126.3	-269	50	45
38	vdd2	-1061.3	-269	50	45
39	vdd2	-996.3	-269	50	45
40	vdd2	-931.3	-269	50	45
41	DUMMY	-849.3	-269	50	45
42	DUMMY	-784.3	-269	50	45
43	vdd2	-702.3	-269	50	45
44	vdd2	-637.3	-269	50	45
45	vdd2	-572.3	-269	50	45
46	vdd3	-507.3	-269	50	45
47	vdd3	-442.3	-269	50	45
48	vdd3	-377.3	-269	50	45
49	vdd3	-312.3	-269	50	45
50	vdd3	-247.3	-269	50	45
51	DUMMY	-247.3 -178.15	-269	50	45
52			-269		
	DUMMY	-113.15		50	45 45
53	DUMMY	-48.15	-269	50	45
54	VSS	21	-269	50	45
55	VSS	86	-269	50	45
56	VSS	151	-269	50	45
57	VSS	216	-269	50	45
58	VSS	281	-269	50	45
59	VSS	346	-269	50	45

#	Pad	Х	Υ	W	Н
60	vss2	411	-269	50	45
61	vss2	476	-269	50	45
62	_	541	-269	50	45
63	vss2 vss2	606	-269	50	45
64		671			
	vss2		-269	50	45
65	vss2	736	-269	50	45
66	DUMMY	801	-269	50	45
67	TST4	903	-269	50	45
68	TST4	968	-269	50	45
69	TST4	1044	-269	50	45
70	TST4	1109	-269	50	45
71	TST2	1174	-269	50	45
72	TST2	1275.45	-269	50	45
45	VBN0	1395.35	-269	50	45
74	VBN0	1460.35	-269	50	45
75	VBN0	1535.5	-269	50	45
76	VBN0	1600.5	-269	50	45
77	VBP0	1665.5	-269	50	45
78	VBP0	1730.5	-269	50	45
79	VBP0	1805.65	-269	50	45
80	VBP0	1870.65	- 269	50	45
81	VBN1	1952.65	-269	50	45
82	VBN1	2017.65	-269	50	45
83	VBN1	2092.8	-269	50	45
84	VBN1	2157.8	-269	50	45
85	VBP1	2222.8	-269	50	45
86	VBP1	2287.8	-269	50	45
87	VBP1	2362.95	-269	50	45
88	VBP1	2427.95	-269	50	45
89	VLCDIN	2511.95	-269	50	45
90	VLCDIN	2576.95	-269	50	45
91	VLCDIN	2673.95	-269	50	45
92	VLCDIN	2738.95	-269	50	45
93	VLCDOUT	2803.95	-269	50	45
94	VLCDOUT	2868.95	-269	50	45
95	VLCDOUT	2944.95	-269	50	45
96	VLCDOUT	3009.95	-269	50	45
97	DUMMY	3074.95	-269	50	45
98	DUMMY	3139.95	-269	50	45
99	DUMMY	3204.95	-269	50	45
100	DUMMY	3269.95	-269	50	45
101	DUMMY	3334.95	-269	50	45
102	DUMMY	3399.95	-269	50	45
103	DUMMY	3546	-269	50	45
104	DUMMY	3611	-269	50	45
105	DUMMY	3676	-269	50	45
106	DUMMY	3694.2	226	15.6	115
107	SEG192	3666.6	226	15.6	115
108	SEG190	3639	226	15.6	115
109	SEG188	3611.4	226	15.6	115
110	SEG186	3583.8	226	15.6	115
111	SEG184	3556.2	226	15.6	115
112	SEG182	3528.6	226	15.6	115
113	SEG180	3501	226	15.6	115
114	SEG178	3473.4	226	15.6	115
115	SEG176	3445.8	226	15.6	115
116	SEG174	3418.2	226	15.6	115
117	SEG172	3390.6	226	15.6	115
118	SEG170	3363	226	15.6	115
119	SEG168	3335.4	226	15.6	115
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#	Pad	Χ	Υ	W	Н
120	SEG166	3307.8	226	15.6	115
121	SEG164	3280.2	226	15.6	115
122	SEG162	3252.6	226	15.6	115
123	SEG160	3225	226	15.6	115
124	SEG158	3197.4	226	15.6	115
125	SEG156	3169.8	226	15.6	115
126	SEG154	3142.2	226	15.6	115
127	SEG152	3114.6	226	15.6	115
128	SEG150	3087	226	15.6	115
129	SEG148	3059.4	226	15.6	115
115	SEG146	3031.8	226	15.6	115
131	SEG144	3004.2	226	15.6	115
132	SEG142	2976.6	226	15.6	115
133	SEG140	2949	226	15.6	115
134	SEG138	2921.4	226	15.6	115
135	SEG136	2893.8	226	15.6	115
136	SEG134	2866.2	226	15.6	115
137	SEG132	2838.6	226	15.6	115
138	SEG115	2811	226	15.6	115
139	SEG128	2783.4	226	15.6	115
140	SEG126	2755.8	226	15.6	115
141	SEG124	2728.2	226	15.6	115
142	SEG122	2700.6	226	15.6	115
143	SEG120	2673	226	15.6	115
144	SEG118	2645.4	226	15.6	115
145	SEG116	2617.8	226	15.6	115
146	SEG114	2590.2	226	15.6	115
147	SEG112	2562.6	226	15.6	115
148	SEG112	2535	226	15.6	115
149	SEG108	2507.4	226	15.6	115
150	SEG106	2479.8	226	15.6	115
151	SEG100	2479.0	226	15.6	115
152	SEG104 SEG102	2424.6	226	15.6	115
153	SEG102	2397	226	15.6	115
154	SEG98	2369.4	226	15.6	115
155	SEG96	2341.8	226	15.6	115
156	SEG94	2314.2	226	15.6	115
157	SEG92	2286.6	226	15.6	115
158	SEG90	2259	226	15.6	115
159	SEG88	2231.4	226	15.6	115
			-		115
160	SEG86	2203.8	226	15.6	115
161 162	SEG84 SEG82	2176.2	226 226	15.6 15.6	115
		2148.6 2121	226	_	
163 164	SEG80 SEG78	2093.4	226	15.6 15.6	115 115
	SEG78 SEG76	2093.4	226	15.6	
165				15.6	115 115
166 167	SEG74 SEG72	2038.2	226		
168	SEG72 SEG70	2010.6 1983	226 226	15.6 15.6	115 115
169	SEG68	1955.4	226	15.6	115
170	SEG66	1927.8	226	15.6	115
171	SEG64	1900.2	226	15.6	115
172	SEG62	1872.6	226	15.6	115
145	SEG60	1845	226	15.6	115
174	SEG58	1817.4	226	15.6	115
175	SEG56	1789.8	226	15.6	115
176	SEG54	1762.2	226	15.6	115
177	SEG52	1734.6	226	15.6	115
178	SEG50	1707	226	15.6	115
179	SEG48	1679.4	226	15.6	115

#	Pad	Х	Υ	W	Н	
180	SEG46	1651.8	226	15.6	115	
181		SEG44 1624.2		15.6	115	
182	SEG42	1596.6	226 226	15.6	115	
183	SEG40	1569	226	15.6	115	
184	SEG38	1541.4	226	15.6	115	
185	SEG36	1513.8	226	15.6	115	
186	SEG34	1486.2	226	15.6	115	
187	SEG32	1458.6	226	15.6	115	
188	SEG30	1431	226	15.6	115	
189	SEG28	1403.4	226	15.6	115	
190	SEG26	1375.8	226	15.6	115	
191	SEG24	1348.2	226	15.6	115	
192	SEG22	1320.6	226	15.6	115	
193	SEG20	1293	226	15.6	115	
194	SEG18	1265.4	226	15.6	115	
195	SEG16	1237.8	226	15.6	115	
196	SEG14	1210.2	226	15.6	115	
197	SEG12	1182.6	226	15.6	115	
198	SEG10	1155	226	15.6	115	
199	SEG8	1127.4	226	15.6	115	
200	SEG6	1099.8	226	15.6	115	
201	SEG4	1072.2	226	15.6	115	
202	SEG2	1044.6	226	15.6	115	
203	CIC	898.5	233.5	15.6	100	
204	COM64	870.9	233.5	15.6	100	
205	COM63	843.3	233.5	15.6	100	
206	COM62	815.7	233.5	15.6	100	
207	COM61	788.1	233.5	15.6	100	
208	COM60	760.1	233.5	15.6	100	
209	COM59	732.9	233.5	15.6	100	
210	COM58	705.3	233.5	15.6	100	
211	COM57	677.7	233.5	15.6	100	
212	COM56	650.1	233.5	15.6	100	
213	COM55	622.5	233.5	15.6	100	
214	COM54	594.9	233.5	15.6	100	
215	COM53	567.3	233.5	15.6	100	
216	COM52	539.7	233.5	15.6	100	
217	COM51	512.1	233.5	15.6	100	
218	COM50	484.5	233.5	15.6	100	
219	COM49	456.9	233.5	15.6	100	
220	COM48	429.3	233.5	15.6	100	
221	COM47	401.7	233.5	15.6	100	
222	COM46	374.1	233.5	15.6	100	
223	COM45	346.5	233.5	15.6	100	
224	COM44	318.9	233.5	15.6	100	
225	COM43	291.3	233.5	15.6	100	
226	COM42	263.7	233.5	15.6	100	
227	COM41	236.1	233.5	15.6	100	
228	COM40	208.5	233.5	15.6	100	
229	COM39	180.9	233.5	15.6	100	
230	COM38	153.3	233.5	15.6	100	
231	COM37	125.7	233.5	15.6	100	
232	COM36	98.1	233.5	15.6	100	
233	COM35	70.5	233.5	15.6	100	
234	COM34	42.9	233.5	15.6	100	
235	COM33	15.3	233.5	15.6	100	
236	COM32	-12.3	233.5	15.6	100	
237	COM31	-39.9	233.5	15.6	100	
238	COM30	-67.5	233.5	15.6	100	
239	COM29	-95.1	233.5	15.6	100	
			,			

#	Pad	Х	Υ	W	Н
240	COM28	-122.7	233.5	15.6	100
241	COM27	-150.3	233.5	15.6	100
242	COM26	-177.9	233.5	15.6	100
243	COM25	-205.5	233.5	15.6	100
244	COM24	-233.1	233.5	15.6	100
245	COM23	-260.7	233.5	15.6	100
246	COM22	-288.3	233.5	15.6	100
247	COM21	-315.9	233.5	15.6	100
248	COM20	-343.5	233.5	15.6	100
249	COM19	-371.1	233.5	15.6	100
250	COM18	-398.7	233.5	15.6	100
251	COM17	-426.3	233.5	15.6	100
252	COM16	-453.9	233.5	15.6	100
253	COM15	-481.5	233.5	15.6	100
254	COM14	-509.1	233.5	15.6	100
255	COM13	-536.7	233.5	15.6	100
256	COM12	-564.3	233.5	15.6	100
257	COM11	-591.9	233.5	15.6	100
258	COM10	-619.5	233.5	15.6	100
259	COM9	-647.1	233.5	15.6	100
260	COM8	-674.7	233.5	15.6	100
261	COM7	-702.3	233.5	15.6	100
262	COM6	-729.9	233.5	15.6	100
263	COM5	-757.5	233.5	15.6	100
264	COM4	-785.1	233.5	15.6	100
265	COM3	-812.7	233.5	15.6	100
266	COM2	-840.3	233.5	15.6	100
267	COM1	-867.9	233.5	15.6	100
268	CIC	-895.5	233.5	15.6	100
269	SEG1	-1045.1	226	15.6	115
270	SEG3	-1072.7	226	15.6	115
271	SEG5	-1100.3	226	15.6	115
272	SEG7	-1127.9	226	15.6	115
245	SEG9	-1155.5	226	15.6	115
274	SEG11	-1183.1	226	15.6	115
275	SEG13	-1210.7	226	15.6	115
276	SEG15	-1238.3	226	15.6	115
277	SEG17	-1265.9	226	15.6	115
278	SEG19	-1293.5	226	15.6	115
279	SEG21	-1321.1	226	15.6	115
280 281	SEG23 SEG25	-1348.7	226 226	15.6 15.6	115 115
	SEG27	-1376.3 -1403.9			115
282 283	SEG29	-1403.9	226 226	15.6 15.6	115
284	SEG31	-1451.5	226	15.6	115
285	SEG33	-1486.7	226	15.6	115
286	SEG35	-1514.3	226	15.6	115
287	SEG37	-1541.9	226	15.6	115
288	SEG39	-1569.5	226	15.6	115
289	SEG41	-1597.1	226	15.6	115
290	SEG43	-1624.7	226	15.6	115
291	SEG45	-1652.3	226	15.6	115
292	SEG47	-1679.9	226	15.6	115
293	SEG49	-1707.5	226	15.6	115
294	SEG51	-1735.1	226	15.6	115
295	SEG53	-1762.7	226	15.6	115
296	SEG55	-1790.3	226	15.6	115
297	SEG57	-1817.9	226	15.6	115
298	SEG59	-1845.5	226	15.6	115
299	SEG61	-1873.1	226	15.6	115

#	Pad	Х	Υ	W	Н
300	SEG63	-1900.7	226	15.6	115
301	SEG65	-1928.3	226	15.6	115
302	SEG67	-1955.9	226	15.6	115
303	SEG69	-1983.5	226	15.6	115
304	SEG71	-2011.1	226	15.6	115
305	SEG45	-2038.7	226	15.6	115
306	SEG75	-2066.3	226	15.6	115
307	SEG77	-2093.9	226	15.6	115
308	SEG79	-2121.5	226	15.6	115
309	SEG81	-2149.1	226	15.6	115
310	SEG83	-2176.7	226	15.6	115
311	SEG85	-2204.3	226	15.6	115
312	SEG87	-2231.9	226	15.6	115
313	SEG89	-2259.5	226	15.6	115
314	SEG91	-2287.1	226	15.6	115
315	SEG93	-2314.7	226	15.6	115
316	SEG95	-2342.3	226	15.6	115
317	SEG97	-2369.9	226	15.6	115
318	SEG99	-2397.5	226	15.6	115
319	SEG101	-2425.1	226	15.6	115
320	SEG103	-2452.7	226	15.6	115
321	SEG105	-2480.3	226	15.6	115
322	SEG107	-2507.9	226	15.6	115
323	SEG109	-2535.5	226	15.6	115
324	SEG111	-2563.1	226	15.6	115
325	SEG113	-2590.7	226	15.6	115
326	SEG115	-2618.3	226	15.6	115
327	SEG117	-2645.9	226	15.6	115
328	SEG119	-2673.5	226	15.6	115
329	SEG121	-2701.1	226	15.6	115
330	SEG123	-2728.7	226	15.6	115
331	SEG125	-2756.3	226	15.6	115
332	SEG127	-2783.9	226	15.6	115
333	SEG129	-2811.5	226	15.6	115
334	SEG131	-2839.1	226	15.6	115
335	SEG133	-2866.7	226	15.6	115
336	SEG135	-2894.3	226	15.6	115
337	SEG137	-2921.9	226	15.6	115
338	SEG139	-2949.5	226	15.6	115
339	SEG141	-2977.1	226	15.6	115
340	SEG143	-3004.7	226	15.6	115
341	SEG145	-3032.3	226	15.6	115
342	SEG147	-3059.9	226	15.6	115
343	SEG149	-3087.5	226	15.6	115
344	SEG151	-3115.1	226	15.6	115
345	SEG153	-3142.7	226	15.6	115
346	SEG155	-3170.3	226	15.6	115
347	SEG157	-3197.9	226	15.6	115
348	SEG159	-3225.5	226	15.6	115
349	SEG161	-3253.1	226	15.6	115
350	SEG163	-3280.7	226	15.6	115
351	SEG165	-3308.3	226	15.6	115
352	SEG167	-3335.9	226	15.6	115
353	SEG169	-3363.5	226	15.6	115
354	SEG171	-3391.1	226	15.6	115
355	SEG145	-3418.7	226	15.6	115
356	SEG175	-3446.3	226	15.6	115
357	SEG177	-3473.9	226	15.6	115
358	SEG179	-3501.5	226	15.6	115
359	SEG181	-3529.1	226	15.6	115
555	020101	55 <u>2</u> 5.1	220	.0.0	110

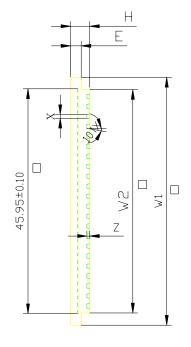


65x192 STN Controller-Driver

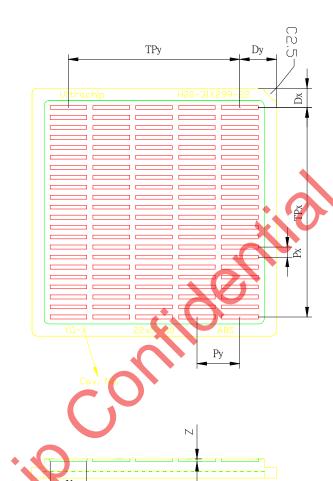
#	Pad	Х	Υ	W	Н
360	SEG183	-3556.7	226	15.6	115
361	SEG185	-3584.3	226	15.6	115
362	SEG187	-3611.9	226	15.6	115
363	SEG189	-3639.5	226	15.6	115
364	SEG191	-3667.1	226	15.6	115
365	DUMMY	-3694.7	226	15.6	115

Jitrachii?

TRAY INFORMATION



Z	~	×	Ру	P _X	ТРу	Dy	TPx	Dx	т	I	₹	√1
0,55±0,05 (22)	7.60±0.05 (299)	0.78±0.05 (31)	8.90±0.05 (350)	2.04±0.05 (80)	35.60±0.10(1402)	7.55±0.05 (297)	42.84±0.10(1687)	3.93±0.05 (155)	2.20±0.05 (87)	3,95±0,10 (156)	45,70±0.10 (1799)	50.70±0.10 (1996)





Spec

SURFACE RESISTANCE: 10 e 7~10 e 11 ohm/sq MATERIAL: ABS WITH ESD PROTECTION, COLOR: BLACK NO BURR AND FOREIGN MATERIAL(OIL) ON SURFACE OF CHIP TRAY. MAKER OF CHIP TRAY SHOULD CLEAN THE SURFACE OF CHIP TRAY.

OF POCKET: ROUGH SURFACE

REVISION HISTORY

Revision	Contents	Date
0.6	(First Release)	Jul. 22, 2010
	(1) The connections for the D[5:3] pins, related to SDA-read and SDA-write, are modified.	
	(2) The data for section "VLCD Quick Reference" is updated.	
0.8	(3) For DC characteristics, VDD (Min.) is adjusted: 1.65V> 1.7V	Jan. 11, 2011
0.0	(4) The typical value and the maximum value for R0(SEG) and R0(СОМ) are adjusted.	Jan. 11, 2011
	(5) The maximum power consumption presents.	
	(6) The AC timings present.	
1.0	(Same as revision 0.8)	Feb. 8, 2011
1.01	A Read command for S8 and S9 mode is added.	Jun. 27, 2011
1.1	Another set of pad information is provided.	Mar. 23, 2012