# Biologically inspired artificial intelligence

Report

Plant disease classification

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### 1. Introduction

The project involves developing a neural network model for processing images of plant diseases. Convolutional neural networks will be used for the project to ensure efficient processing of the given images. The data will be divided into two sets - training and test in a ratio of 80/20. Technologies such as Python, PyTorch, JupiterNotebook will be used for implementation, and data processing will be performed using CUDA architecture.

# 2. Project analysis

### a. Solution approaches

We decided to use a convolutional neural network (CNN) for our project. It operates on images which makes it ideally suited for creating our model. To solve the problem, we could use transfer learning with pre-trained models or create the structure of the artificial intelligence model from scratch. We decided to choose the second approach. This solution is more time-consuming and requires more resources than the alternative one using a pre-trained model. However, it makes the model learnable only for the data on which it will operate. It also provides full control over the structure of the model, making its behaviour easier to understand and making experiments on the model simpler to perform.

## b. Datasets description

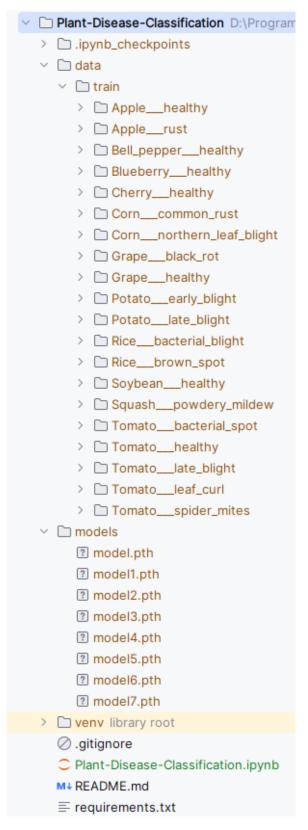
To find a suitable dataset we used the website kaggle.com, which contains a huge database of different types of datasets. The dataset we selected contains about 95,000 images divided into 60 classes of classified plants along with their diseases, and is a compound of other minor datasets.

# c. Tools analysis

- Python, with libraries such as:
  - PyTorch was selected over TensorFlow, because it is more accessible and easier to use
  - Matplotlib visualisations
  - o OpenCV2 image processing
  - Numpy and pandas arithmetical operations
- Jupiter Notebook better code presentation and output visualization
- CUDA architecture that enables GPU usage in data processing

# 3. Specification

### a. Project structure



Screenshot 1. Project structure

### b. Code structure

### 1. Data preparation

### a. Creating image path lists

Creating lists of paths where data is saved. Lists are divided - 80% in training set and 20% in test set. Paths are shuffled before assigning.

```
train_data_path = 'data\\train'
  classes, train_image_paths = [], []
  for data_path in glob(train_data_path + '\\*'):
       classes.append(" ".join(" - ".join(data_path.split('\\')[-1].split('_-_')).split('_-')))
       train_image_paths.append(glob(data_path + '\\*'))
9 train_image_paths = list(pandas.core.common.flatten(train_image_paths))
10
split_index = int(len(train_image_paths) * 0.8)
12 random.shuffle(train_image_paths)
13 train_image_paths, test_image_paths = train_image_paths[:split_index], train_image_paths[split_index:]
14
print('class example: ', classes[0])
16 print('Path example: ', train_image_paths[0], end='\n\n')
17
18 print(f'Classes size: {len(classes)}', end='\n\n')
19
20 print(f'Train size: {len(train_image_paths)}')
21 print(f'Test size: {len(test_image_paths)}')
```

#### Output:

```
class example: Apple - healthy
Path example: data\train\Tomato___late_blight\94f53287-b156-4ece-94a2-3c12783e4fbb___RS_Late.B 5409.JPG
Classes size: 20
Train size: 22114
Test size: 5529
```

#### b. Mapping classes with indexes

```
idx_to_class = {i: j for i, j in enumerate(classes)}
class_to_idx = {value: key for key, value in idx_to_class.items()}
```

#### c. Creating Datasets

Datasets contain images loaded from provided paths. Each image gets label that inform about type and disease of following plant and is scaled to 256x256 pixels.

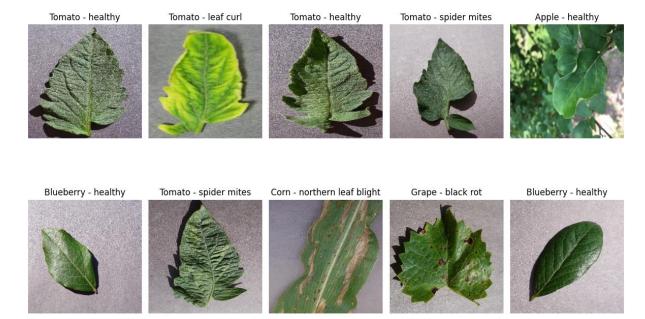
```
class PlantDataset(Dataset):
       def __init__(self, image_paths, transform=False):
           self.image_paths = image_paths
           self.transform = transform
4
       def __len__(self):
7
           return len(self.image_paths)
8
9
       def __getitem__(self, idx):
10
           image_path = self.image_paths[idx]
11
           image = cv2.imread(image_path)
12
           image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
13
           image = image.astype(np.float32)
           image = torch.tensor(image).permute(2, 0, 1)
14
15
           label = "".join(" - ".join(image_path.split('\\')[-2].split('\__')).split('\_'))
16
           index = class_to_idx[label]
18
19
           if self.transform:
20
               image = self.transform(image)
21
22
           return image, index
23
24 transforms = T.Compose([
       T.Resize((256, 256))
26 ])
27
28 train_dataset = PlantDataset(train_image_paths, transforms)
29 test_dataset = PlantDataset(test_image_paths, transforms)
```

#### d. Data visualization

Visualization of 10 random images from training set.

```
def visualize_augmentations(dataset, samples=10, cols=5):
1
2
        rows = samples // cols
3
        ax = plt.subplots(nrows=rows, ncols=cols, figsize=(12, 8))[1]
 4
5
        for i in range(samples):
            idx = np.random.randint(1,len(train_image_paths))
7
            image, index = dataset[idx]
            image = image.numpy().astype(np.uint8)
8
9
10
            ax.ravel()[i].imshow(np.transpose(image, (1, 2, 0)))
            ax.ravel()[i].set_axis_off()
11
12
            ax.ravel()[i].set_title(idx_to_class[index])
13
14
        plt.tight_layout(pad=1)
        plt.show()
15
16
   visualize_augmentations(train_dataset)
17
```

### Output:



### e. Defining dataloaders

```
train_loader = DataLoader(
    train_dataset, batch_size=32, shuffle=True

test_loader = DataLoader(
    test_dataset, batch_size=32, shuffle=False

)
```

### 2. AI model

a. Choosing data processing device.

```
device = (
    "cuda"
    if torch.cuda.is_available()
    else "mps"
    if torch.backends.mps.is_available()
    else "cpu"
    )
```

#### b. Defining AI model structure

```
def convBlock(in_channels, out_channels, pool=False):
2
       layers = [nn.Conv2d(in_channels, out_channels, kernel_size=3, padding=1),
3
                nn.ReLU(inplace=True)]
4
       if pool:
5
           layers.append(nn.MaxPool2d(4))
       return nn.Sequential(*layers)
   class NeuralNetwork(nn.Module):
9
        def __init__(self):
10
            super().__init__()
11
12
13
            self.conv1 = convBlock(3, 64)
            self.conv2 = convBlock(64, 128, pool=True)
14
            self.res1 = nn.Sequential(convBlock(128, 128), convBlock(128, 128))
15
16
17
            self.conv3 = convBlock(128, 256, pool=True)
            self.res2 = nn.Sequential(convBlock(256, 256), convBlock(256, 256))
18
19
20
            self.classifier = nn.Sequential(nn.AdaptiveAvgPool2d(1),
                                              nn.Flatten(),
22
                                              nn.Linear(256, len(classes)))
23
24
       def forward(self, x):
            out = self.conv1(x)
25
26
            out = self.conv2(out)
            out = self.res1(out)
27
28
            out = F.interpolate(out, scale_factor=2, mode='nearest')
29
            out = self.conv3(out)
30
            out = self.res2(out)
            out = F.interpolate(out, scale_factor=2, mode='nearest')
31
32
            out = self.classifier(out)
            return out
33
```

#### c. Model creation

```
1 net = NeuralNetwork().to(device)
2 | print(net)
```

#### Output:

```
NeuralNetwork(
  (conv1): Sequential(
    (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
  (conv2): Sequential(
    (0): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): MaxPool2d(kernel_size=4, stride=4, padding=0, dilation=1, ceil_mode=False)
  (res1): Sequential(
    (0): Sequential(
      (0): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (1): ReLU(inplace=True)
    (1): Sequential(
      (0): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (1): ReLU(inplace=True)
    )
  )
  (conv3): Sequential(
    (0): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): MaxPool2d(kernel_size=4, stride=4, padding=0, dilation=1, ceil_mode=False)
  (res2): Sequential(
    (0): Sequential(
      (0): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (1): ReLU(inplace=True)
    (1): Sequential(
      (0): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
      (1): ReLU(inplace=True)
    )
  (classifier): Sequential(
    (0): AdaptiveAvgPool2d(output_size=1)
    (1): Flatten(start_dim=1, end_dim=-1)
    (2): Linear(in_features=256, out_features=20, bias=True)
  )
)
```

### d. Optimizer and criterion creation

```
criterion = nn.CrossEntropyLoss()
ptimizer = Adam(net.parameters(), lr=1e-3)
```

#### e. Model training and validation

Training model and recording losses and accuracy either training and test DataLoader at the end of each epoch.

```
1 start = torch.cuda.Event(enable_timing=True)
 2 end = torch.cuda.Event(enable_timing=True)
3 train_losses, val_losses, train_accs, val_accs = [], [], [], []
5 start.record()
7 for epoch in range(10):
8
9
       train_loss = 0.0
10
       train_correct = 0
11
       train_total = 0
12
       net.train()
       for i, train_data in enumerate(train_loader, 0):
14
15
            train_inputs, train_labels = train_data
           train_inputs, train_labels = train_inputs.to(device), train_labels.to(device)
16
17
18
           optimizer.zero_grad()
           outputs = net(train_inputs)
19
           loss = criterion(outputs, train_labels)
21
           loss.backward()
           optimizer.step()
23
24
           train_loss += loss.item()
            _, predicted = torch.max(outputs.data, 1)
           train_correct += (predicted == train_labels).sum().item()
```

```
28
       train_loss_avg = train_loss / len(train_loader)
29
       train_acc = train_correct / len(train_loader.dataset)
       print(f'[Epoch {epoch + 1}] Train loss: {train_loss_avg:.3f}')
       print(f'[Epoch {epoch + 1}] Train acc: {train_acc:.3f}')
33
       valid_loss = 0.0
34
       valid_correct = 0
       valid_total = 0
36
       net.eval()
37
       with torch.no_grad():
            for i, valid_data in enumerate(test_loader, 0):
39
                valid_inputs, valid_labels = valid_data
40
                valid_inputs, valid_labels = valid_inputs.to(device), valid_labels.to(device)
               valid_outputs = net(valid_inputs)
42
43
               loss = criterion(valid_outputs, valid_labels)
                valid_loss += loss.item()
45
46
                _, predicted = torch.max(valid_outputs.data, 1)
                valid_correct += (predicted == valid_labels).sum().item()
48
49
       valid_loss_avg = valid_loss / len(test_loader)
       valid_acc = valid_correct / len(test_loader.dataset)
       print(f'[Epoch {epoch + 1}] Valid loss: {valid_loss_avg:.3f}')
52
       print(f'[Epoch {epoch + 1}] Valid acc: {valid_acc:.2%}')
53
       train_losses.append(train_loss_avg)
       train_accs.append(train_acc)
56
       val_losses.append(valid_loss_avg)
       val_accs.append(valid_acc)
59
    end.record()
60 torch.cuda.synchronize()
62 print('Finished Training')
63 print(start.elapsed_time(end))
```

### Output:

```
[1, 692] Train loss: 2.742
[1, 692] Train acc: 0.138
[Epoch 1] Valid loss: 5.239
[Epoch 1] Valid acc: 17.04%
[2, 692] Train loss: 1.305
[2, 692] Train acc: 0.586
[Epoch 2] Valid loss: 0.813
[Epoch 2] Valid acc: 73.65%
[3, 692] Train loss: 0.573
[3, 692] Train acc: 0.821
[Epoch 3] Valid loss: 0.581
[Epoch 3] Valid acc: 82.46%
```

#### f. Save model to file

```
1 torch.save(net.state_dict(), "./models/model8.pth")
```

### 3. Testing

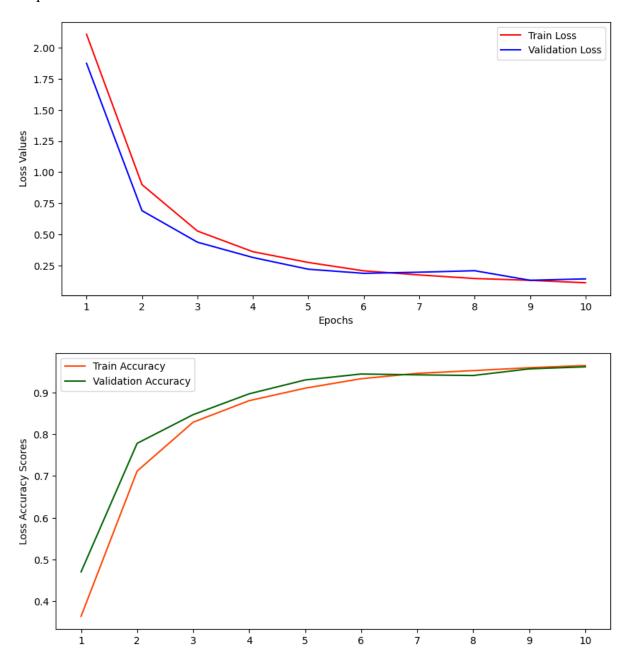
a. Load model from file

```
net.load_state_dict(torch.load("./models/model8.pth"))
net.eval()
net.to(device)
```

### b. Drawing loss and accuracy plots

```
plt.figure(figsize = (10, 5))
 2 plt.plot(train_losses, label = "Train Loss", c = "red")
 3 plt.plot(val_losses, label = "Validation Loss", c = "blue")
 4 plt.xlabel("Epochs")
 5 plt.ylabel("Loss Values")
 6 plt.xticks(ticks = np.arange(len(train_losses)), labels = [i for i in range(1, len(train_losses) + 1)])
7 plt.legend()
8 plt.show()
10 plt.figure(figsize = (10, 5))
plt.plot(train_accs, label = "Train Accuracy", c = "orangered")
12 plt.plot(val_accs, label = "Validation Accuracy", c = "darkgreen")
13 plt.xlabel("Epochs")
14 plt.ylabel("Loss Accuracy Scores")
15 plt.xticks(ticks = np.arange(len(train_accs)), labels = [i for i in range(1, len(train_accs) + 1)])
16 plt.legend()
17 plt.show()
```

# Output:



Epochs

c. Function for getting predicted and actual labels for provided model and DataLoader

```
def get_preds_and_actual(model, loader):
1
2
        predictions = torch.tensor([]).to(device)
        actuals = torch.tensor([]).to(device)
 3
        for batch in loader:
4
            images, actual = batch
5
            images, actual = images.to(device), actual.to(device)
 6
7
8
            pred = model(images)
9
            predictions = torch.cat((predictions, pred), dim=0)
            actuals = torch.cat((actuals, actual),dim=0)
10
11
12
        return predictions.argmax(dim=1).int(), actuals.int()
```

d. Function for getting correctness of the model

```
def get_correct(predictions, actuals):
    result = 0
    for i, _ in enumerate(predictions):
        if predictions[i] == actuals[i]:
            result += 1
    return result
```

e. Getting predictions and actuals

```
with torch.no_grad():
predictions, actuals = get_preds_and_actual(net, test_loader)
```

f. Getting model's correctness

```
correct = get_correct(predictions, actuals)
print(f'Accuracy of the network on the valid images: {(correct / len(actuals)):.2%}')
```

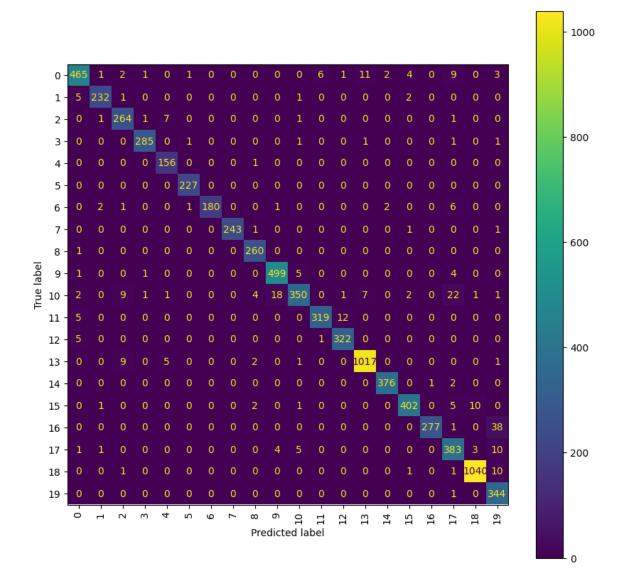
Output:

Accuracy of the network on the valid images: 94.16%

#### g. Draw confusion matrix

```
cm = confusion_matrix(actuals.cpu(), predictions.cpu())
1
 2
    disp = ConfusionMatrixDisplay(confusion_matrix=cm)
 4
    fig, ax = plt.subplots(figsize=(10, 10))
 5
    disp.plot(ax=ax, cmap='viridis', xticks_rotation='vertical')
 7
    plt.xticks(fontsize=10)
    plt.yticks(fontsize=10)
 8
    plt.grid(False)
10
11
    plt.show()
```

### Output:



### h. Showing random image and model prediction about its class

```
image, index = next(iter(train_loader))

image = image.to(device)

pred = net(image)

pred_label = pred.argmax(dim=1).int()

pred_value = torch.nn.functional.softmax(pred[0], dim=0)

percentage = (pred_value.max() * 100).cpu().item()

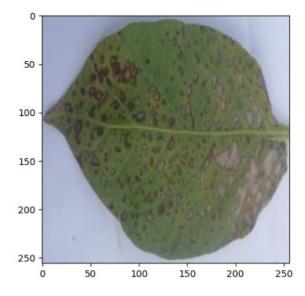
image = image[0].cpu().numpy().astype(np.uint8)

plt.imshow(np.transpose(image, (1, 2, 0)))

plt.show()

print(f"Prediction: {percentage:.2f}% | Prediction: {idx_to_class[pred_label[0].item()]} | Actual: {idx_to_class[index[0].item()]}")
```

#### Output:



Prediction: 84.26% | Prediction: Potato - early blight | Actual: Potato - early blight

### c. Interface

To visualize the results and comment blocks of code, we used Markdown and the outputs in Jupyter Notebook.

# 4. Experiments

The first models we created had a simple structure and relatively short training times (30-40 minutes), but their results were poor. After developing a model with better accuracy, we began further experiments, gradually changing various parameters to improve the model's accuracy. Initially, we trained our models on a complete dataset containing 60 classes. Training on the entire dataset was time-consuming, and the model we created was too simple to handle such a large number of different classes. Thus, after consulting with our supervisor, we decided to reduce the number of classes. To do this, we created a confusion matrix and used it to eliminate the worst-performing classes.

All our models utilized the convBlock structure we designed. This structure features a two-dimensional convolution layer that processes the image data. By incorporating additional layers, we increased the number of input and output channels. The convBlock also includes a ReLU activation layer and an optional MaxPool2d layer, which reduces the number of data points by pooling adjacent pixel values into a single value. This pooling reduces the data size without compromising accuracy. Once the data has passed through all the convolution layers, the data passes through an adaptive averaging layer that reduces the dimensions to 1. Then, the data is flattened into one-dimensional vectors. Finally, the processed vectors pass through a linear layer that generates classification results for each class.

### • Model 1

### Model Structure

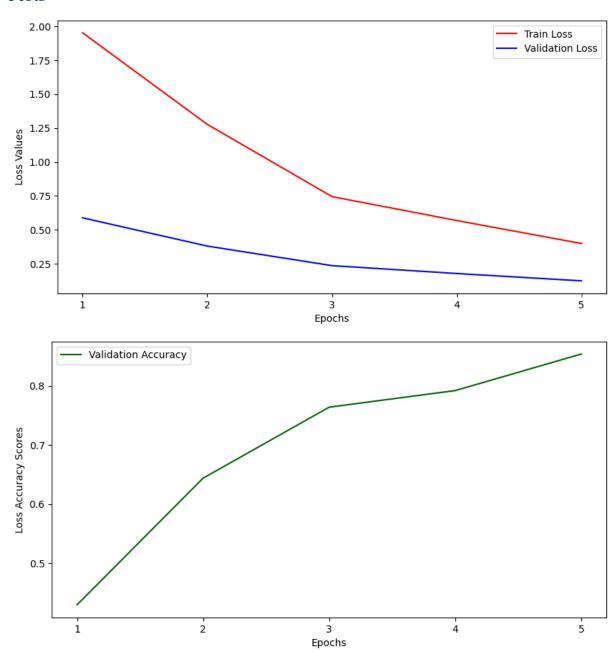
#### Characteristics

Classes: 30

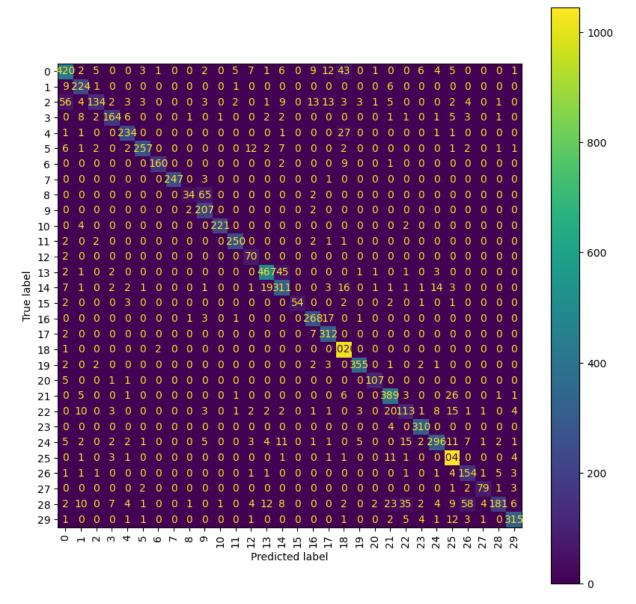
Training time: 13h15m23s

Accuracy: 85.39%

# Plots



### Confusion matrix



### Summary

Analysing the loss graphs on the training set and the validation set, we note that the model generalizes well and does not under-fit the training data (overfitting effect).

# • Model 2

### Model Structure

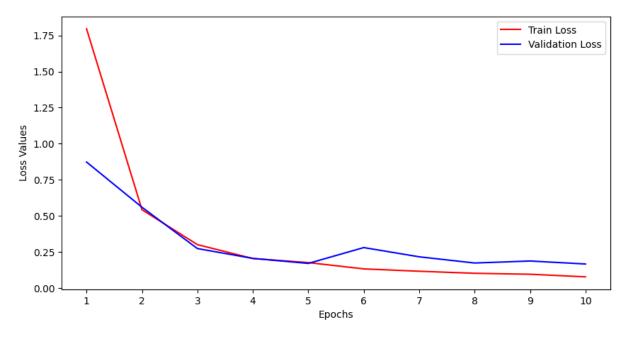
### Characteristics

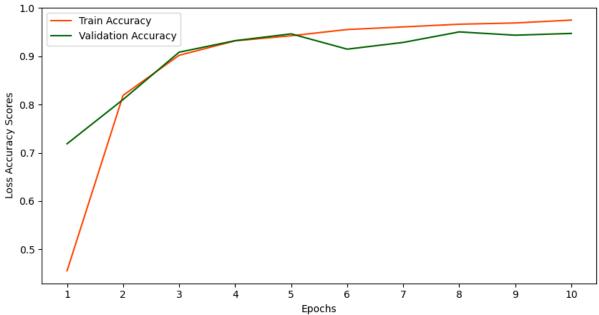
Classes: 20

Training time: 17h56m03s

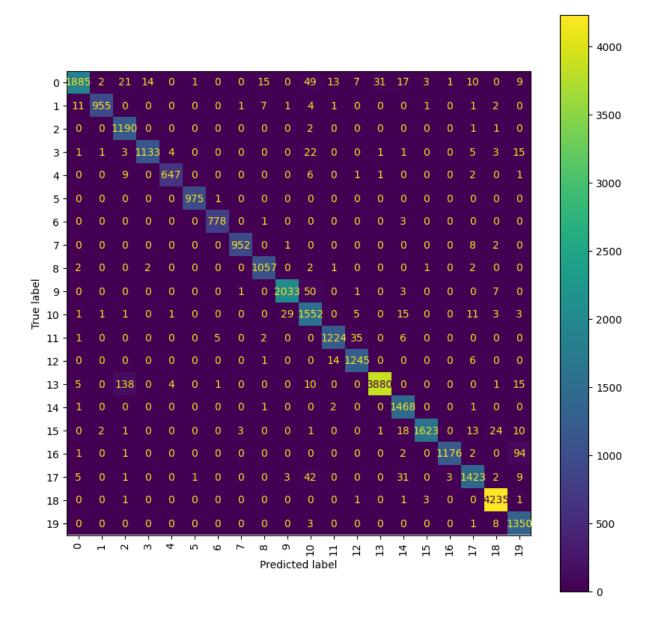
Accuracy: 94.75%

# Plots





### Confusion matrix



### Summary

In model no. 2, we decided not to change the structure of the model. We increased the number of epochs, in order to improve model accuracy and generalization. We limited the number of classes to 20 in order to reduce the complexity of the model and to reduce training time.

We can see an improvement in the precision of the model over the previous one by 9.36%. After the 5th epoch, we can see a slight increase in losses on the validation set, which means that the model fits the training data too closely, affecting the final precision of the model.

# • Model 3

### Model Structure

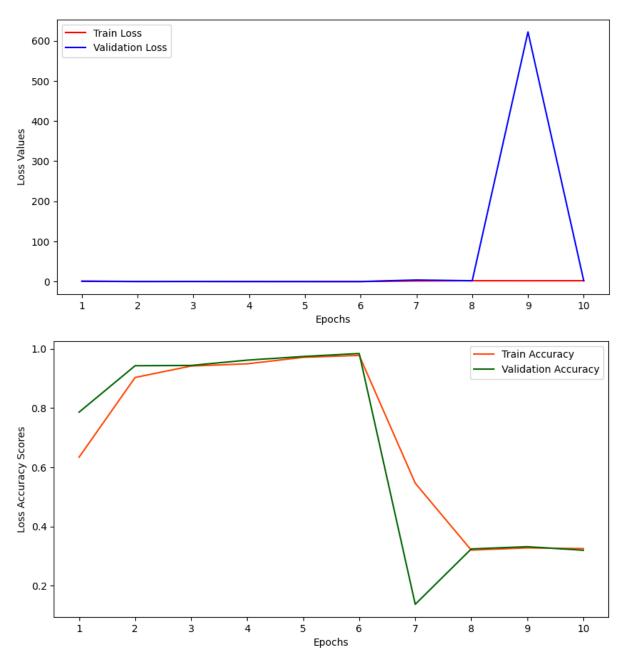
### Characteristics

Classes: 10

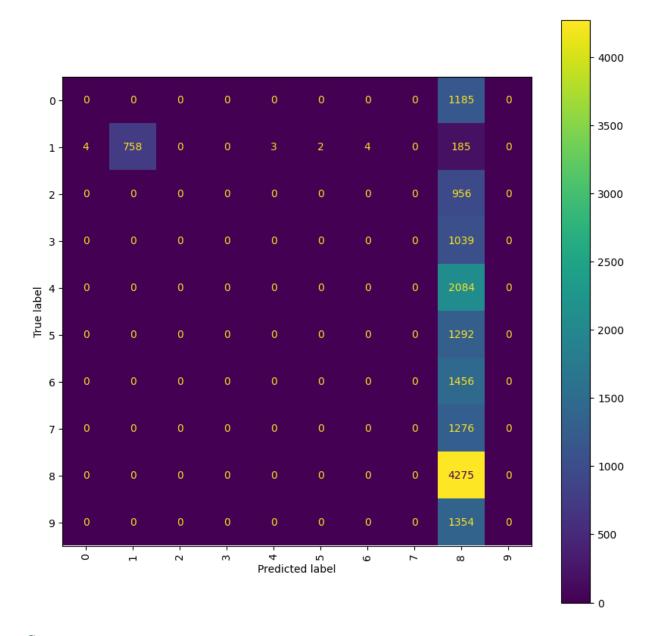
Training time: 10h03m25s

Accuracy: 31.95%

# Plots



### Confusion matrix



### Summary

In model no. 3, we decided not to change the structure of the model or number of epochs. We limited the number of classes to 10.

By epoch 6, the precision of the validation set could be seen at 98%. In the next epochs, a drastic drop in precision appeared on both sets and stabilized at 32%. From the graphs and the confusion matrix, we can conclude that due to insufficient or unbalanced data, the model erroneously learned a single case instead of actual patterns. This resulted in the recognition of all images as class no. 8 images.

# • Model 4

### Model Structure

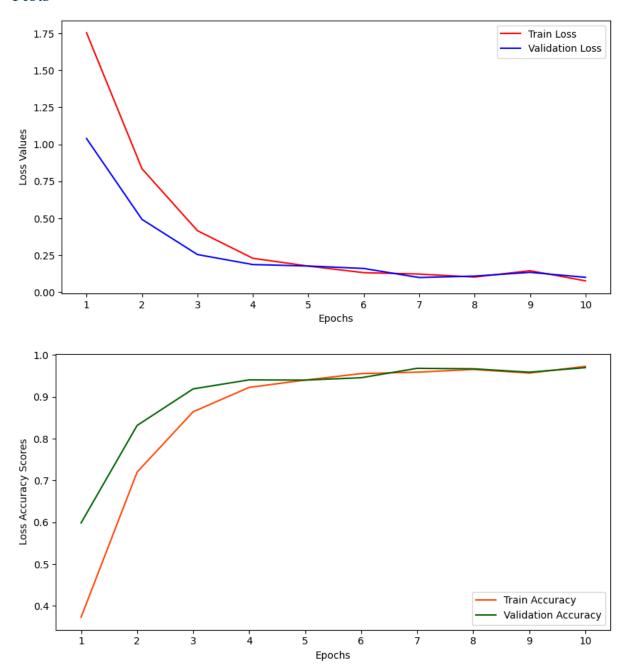
### Characteristics

Classes: 10

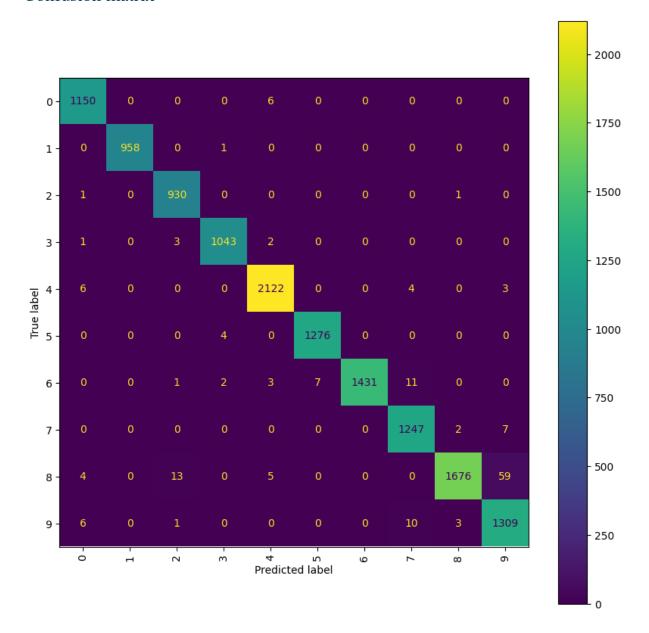
Training time: 6h25m45s

Accuracy: 96.99%

# Plots



### Confusion matrix



### Summary

In the 4th model, we reduced images in class no. 8 so that the model would not be biased by huge amount of data form a single class.

We can see an improvement in the precision of the model over the previous one by 65.04%. Achieving the best accuracy so far.

# • Model 5

### Model Structure

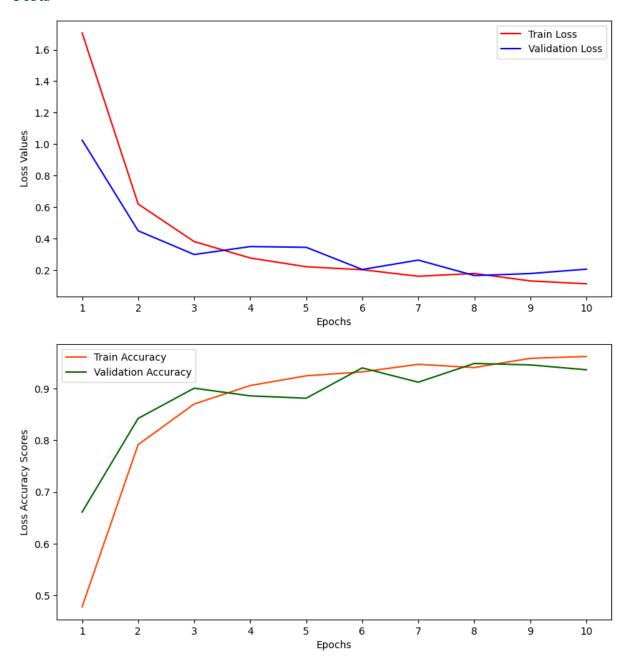
### Characteristics

Classes: 20

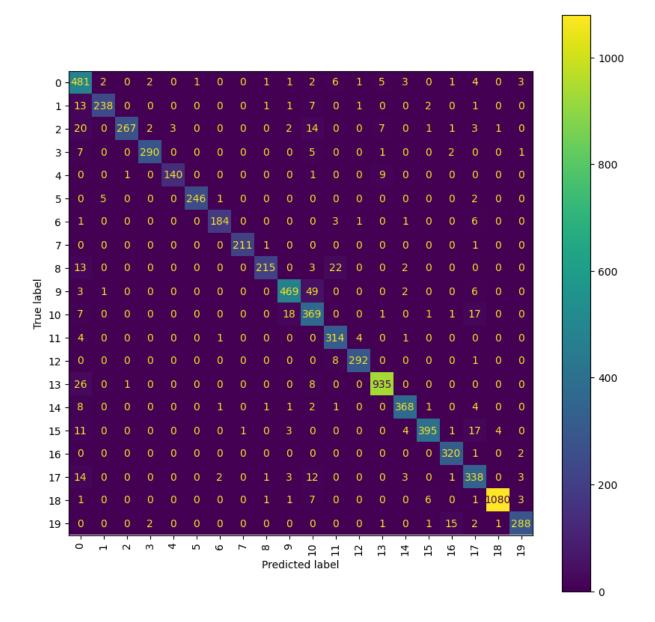
Training time: 30h25m04s

Accuracy: 93.64%

# Plots



### Confusion matrix



### **Summary**

In model no. 5, we applied an additional convolution layer, ReLU activation function and max pooling 2D layer increasing the output channels to 1024. We have also restored the number of classes to 20.

This resulted in a significant increase in training time and model complexity. Despite training time and an increase in the number of classes, the model's precision remained above 90%.

# • Model 6

### Model Structure

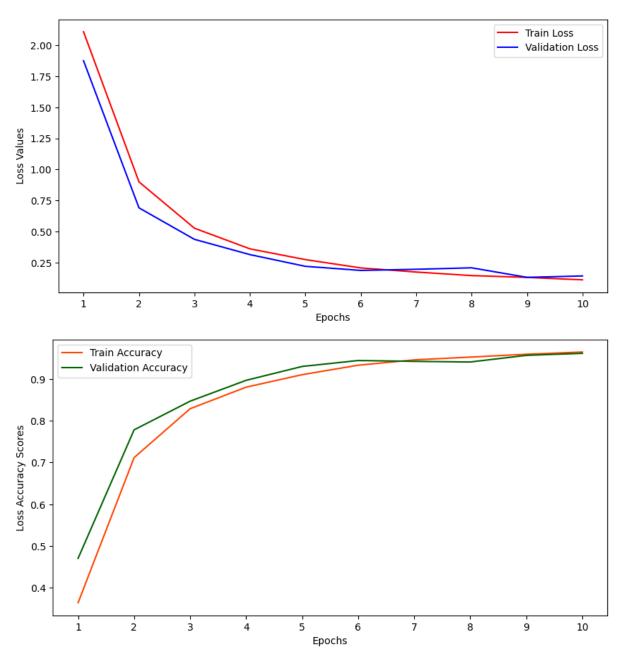
### Characteristics

Classes: 20

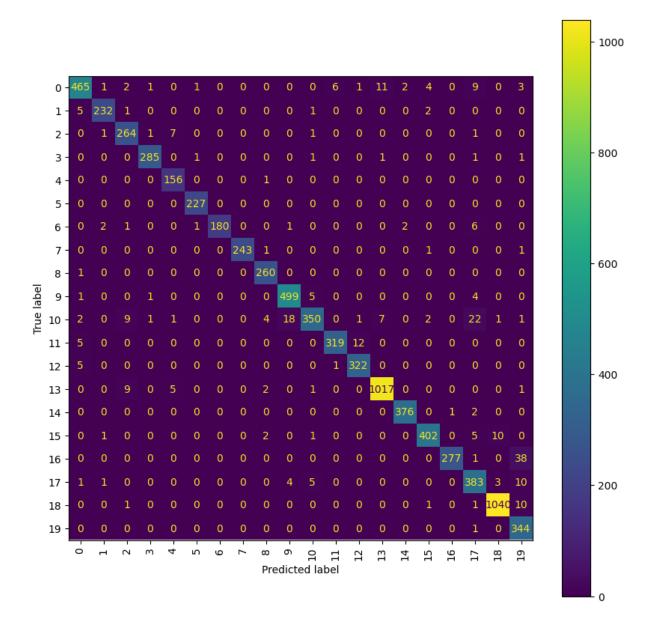
Training time: 18h37m40s

Accuracy: 96.17%

# Plots



### Confusion matrix



### **Summary**

In model no. 6, we removed 2 'convBlock' functions decreasing the output channels to 256 in order to reduce the complexity of the model.

We can see an in the precision of the model over the 4th one by 0.82%. This means that the previous model was too complicated for our dataset and learned the wrong patterns. Reducing the layers had a positive effect on the final precision, achieving the best accuracy so far.

# • Model 7

### Model Structure

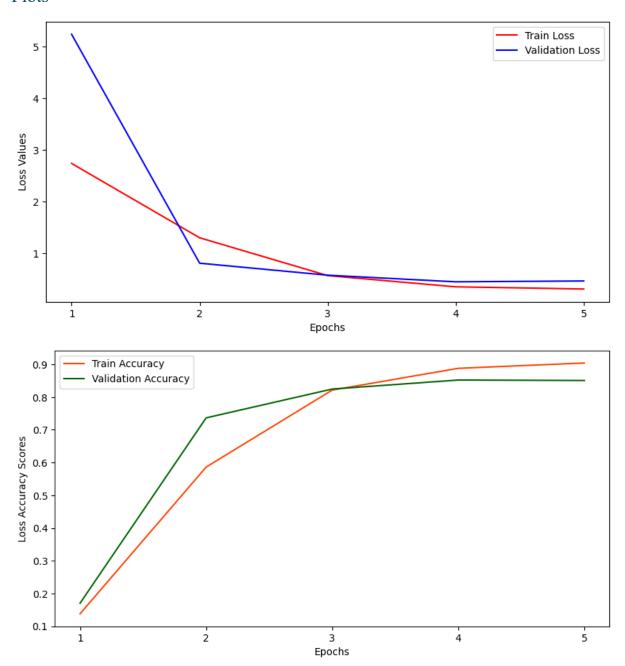
### Characteristics

Classes: 20

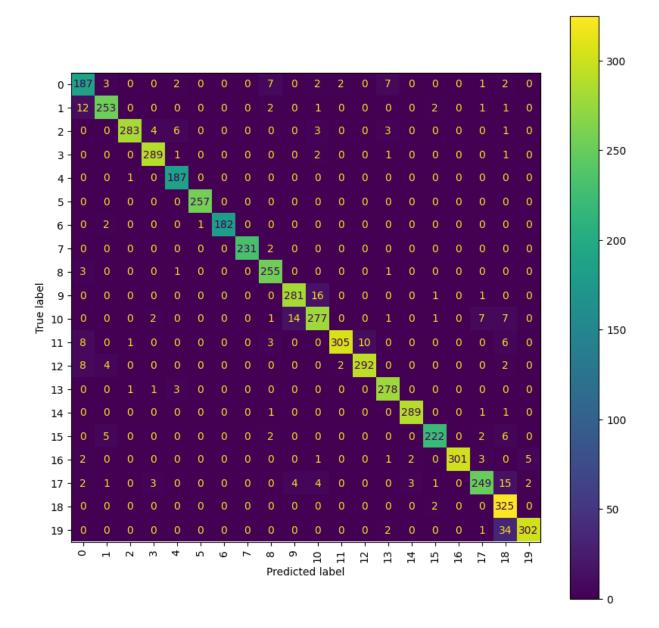
Training time: 11h01m26s

Accuracy: 85.06%

# Plots



### Confusion matrix



### Summary

In model no. 7, we balanced data trying to improve accuracy on lesser classes. During training accuracy for each epoch was lower than in previous model.

# 5. Summary

The implementation of convolutional neural network using the PyTorch library allowed us to learn about the operation of different layers such as convolution layer, normalization layer, activation layer, etc., and their usage in models.

The CUDA architecture had a big impact on the tests performed, which allowed us to significantly reduce the training time, which allowed us to launch more tests.

The tests conducted allowed us to observe various phenomena occurring when training the model. One of the most important is the relationship between the complexity of the model and the amount of data on which it was tested. Models with high complexity require large data sets to avoid overfitting. For small data sets, reducing model complexity or using data augmentation techniques such as data balancing positively affects model precision.

In our research, we did not use layers such as dropout layer that could have had a positive impact on the model's precision. We did not test different activation layer functions.

# 6. References

Plant Diseases Training Dataset - https://www.kaggle.com/

Plant Disease Test Dataset - https://www.kaggle.com/

Building an Image Classification Model From Scratch Using PyTorch | by Benedict Neo | bitgrit Data Science Publication | Medium - https://medium.com/

<u>Learn the Basics — PyTorch Tutorials 2.3.0+cu121 documentation - https://pytorch.org/</u>

# 7. Project link

Link: mc090/Plant-Disease-Classification - https://github.com/