

Lecture III: Compactness, EVT, Correspondences

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1. Compactness

So I’m gonna say, straight up, that the first time I encountered compactness (way back in undergrad real analysis) it seemed like an inscrutable concept. If you get it right away, then awesome, but if you don’t then no worries! It can take a little bit for this to sink in.

1.1. Introduction.

Definition 1. A class $\mathcal{F} = \{\mathcal{F}_\omega\}_{\omega \in \Omega}$ is said to **cover** a set S if $S \subseteq \bigcup_{\omega \in \Omega} \mathcal{F}_\omega$. If all members of the class \mathcal{F} are open, we say it is an **open cover**.

Definition 2. A set S is **compact** if every open cover of S has a **finite subcover** of S .

Some examples of sets that are and are not compact:

- $S = (0, 1)$ is not compact. $\mathcal{F} = \{(1/n, 1) : n \in \mathbb{N}\}$ covers S . However, there is no finite sub-cover: Any finite sub-cover gives the interval $(1/N, 1)$; take $z = (1/2N)$ and $z \in (0, 1)$ but $z \notin (1/N, 1)$.
- $S = [0, \infty)$ is not compact. $\mathcal{F} = \{(-1, n) : n \in \mathbb{N}\}$ covers S . However, there is no finite sub-cover: Any finite sub-cover gives the interval $(-1, N)$; take $z = N + 1$ and $z \in [0, \infty)$ but $z \notin (-1, N)$.
- $[0, 1]$ is compact. Compactness is really trying to get to a notion of “finiteness,” and there is a sense in which intervals that are open or not bounded are not finite. Of course, compactness is more general than that, but at least in \mathbb{R}^N we will get a more intuitive definition of compactness.

Remark 1. Any finite set A is compact. Take any open cover $\mathcal{F} = \{\mathcal{F}_\omega\}_{\omega \in \Omega}$. For $x \in A$, $x \in \mathcal{F}_\omega$ for some $\omega \in \Omega$ (there may be several, and a single \mathcal{F}_ω may contain many $x \in A$). Name this ω_x for each x ; since A is finite, $\{\omega_x\}_{x \in A}$ is a finite. Hence

$$\mathcal{F}_A = \{\mathcal{F}_{\omega_x}\}_{x \in A}$$

is a finite sub-cover of A . □

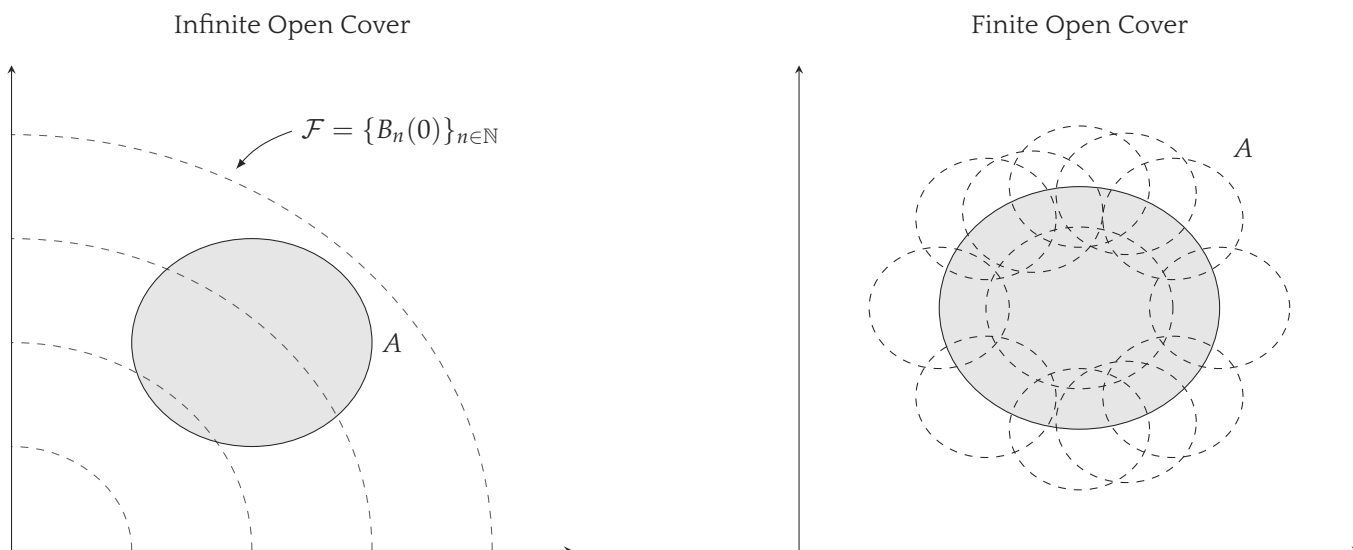


Figure 1: Examples of Open Covers in \mathbb{R}^2

Definition 3. A set S **sequentially compact** if every sequence in S has a sub-sequence that converges to a point in S ($\forall (x_m) \in S \exists (x_{m_k})$ s.t. $x_{m_k} \rightarrow x \in S$).

Theorem 1. A set S is compact $\iff S$ is sequentially compact.

1.2. Heine-Borel and Other Theorems.

Theorem 2 (Heine-Borel). For any finite N , $S \subseteq \mathbb{R}^N$ is compact iff S is closed and bounded.

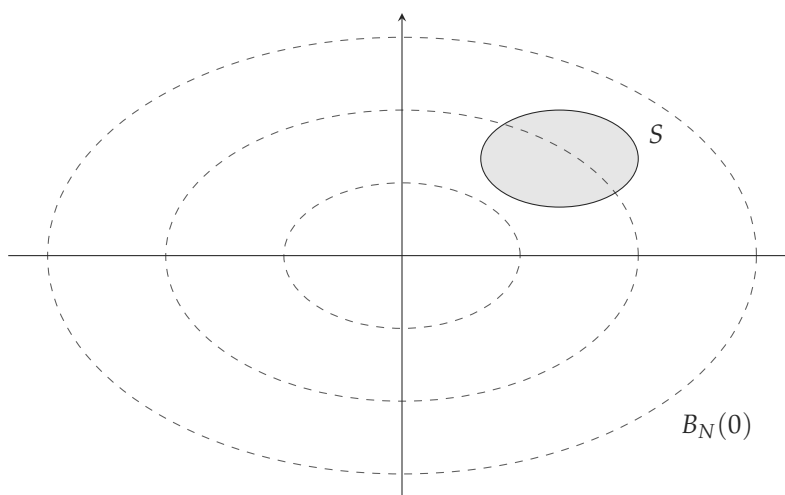
Proof. We show that compactness \implies closed and bounded. The converse is a bit more involved. Let S be a compact set; first we show it is bounded. Take

$$\mathcal{F} = \{\mathcal{F}_n = B_n(0)\}_{n \in \mathbb{N}}$$

\mathcal{F} is an open cover for \mathbb{R}^N , and hence an open cover for $S \subseteq \mathbb{R}^N$. Since S is compact, it admits a finite subcover. Since $\mathcal{F}_n \subseteq \mathcal{F}_{n+1}$,

$$\bigcup_{n \leq N} \mathcal{F}_n = \mathcal{F}_N = B_N(0)$$

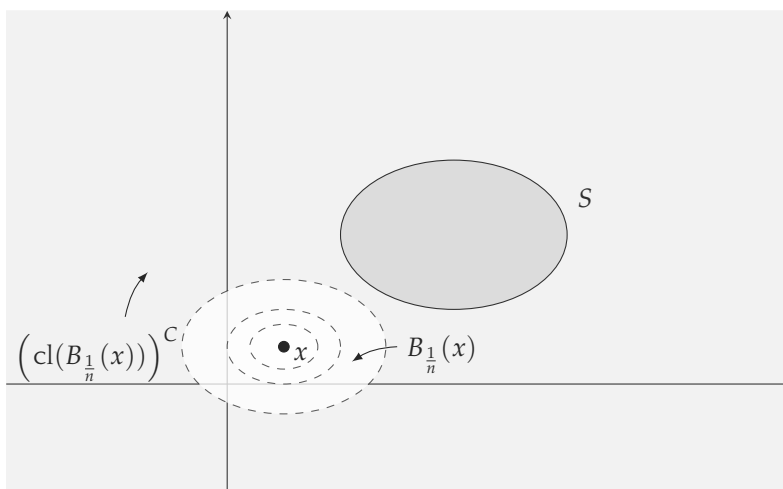
But by definition any $x \in B_N(0)$ is s.t. $d(x, 0) < N$. Since $B_N(0)$ is bounded and $S \subseteq B_N(0)$ then S is also bounded. Visually,



Now we show that it is closed. Take any $x \in S^C = \mathbb{R}^N \setminus S$, the complement of S in \mathbb{R}^N . Define the collection

$$\mathcal{F} = \left\{ \mathcal{F}_n = \left(\text{cl}(B_{\frac{1}{n}}(x)) \right)^C \right\}_{n \in \mathbb{N}}$$

that is, the **complement** of the collection of closed balls of radius $\frac{1}{n}$ around x . A graphical example in \mathbb{R}^2 :



Note we need the complements of the *closed* balls because we want the sets in the collection to be open. Now $\text{cl}(B_{\frac{1}{n}}(x)) \rightarrow \{x\}$, so

$$\bigcup_{n \in \mathbb{N}} \left(\text{cl}(B_{\frac{1}{n}}(x)) \right)^C = \mathbb{R}^N \setminus \{x\}$$

That is, the union of the complements converges to the entire space *except* for x . Since $S \subseteq \mathbb{R}^N \setminus \{x\}$ ($S \subseteq \mathbb{R}^N$ and $x \in S^C \implies x \notin S$), then \mathcal{F} is an open cover of S . By compactness of S , we know that it admits a finite sub-cover. Note

$$B_{\frac{1}{n+1}}(x) \subseteq B_{\frac{1}{n}}(x) \implies \left(\text{cl}(B_{\frac{1}{n}}(x)) \right)^C \subseteq \left(\text{cl}(B_{\frac{1}{n+1}}(x)) \right)^C$$

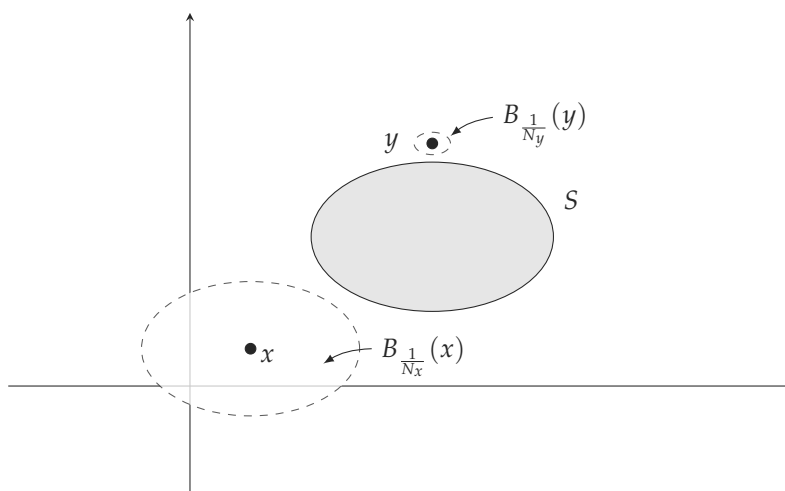
Hence any finite union gives

$$\bigcup_{n \leq N} \left(B_{\frac{1}{n}}(x) \right)^C = \left(\text{cl}(B_{\frac{1}{N}}(x)) \right)^C$$

Since $S \subseteq \left(\text{cl}(B_{\frac{1}{N}}(x)) \right)^C$, it must be that $B_{\frac{1}{N}}(x) \subseteq S^C$. Finally, we can say $\forall x \in S^C \exists \varepsilon > 0$ (any $\varepsilon < 1/N$) s.t.

$$B_\varepsilon(x) \subseteq S^C$$

which is the definition of an open set. This shows S^C is open, so S is closed. Graphically, we see that at any point x outside of the set we can construct a ball of radius $1/N_x$ for some N_x that is entirely outside of S :

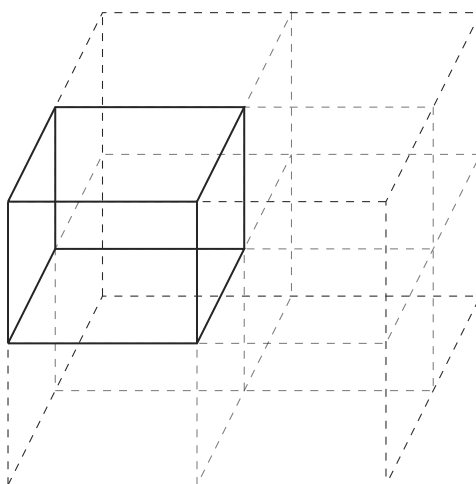


□

The other direction follows from [Theorems 3 and 4](#) below. If a set S is bounded in \mathbb{R}^N then it is the subset of some N -dimensional cube. Once we show the cube is compact, [Theorem 4](#) gives that S is compact. For the curious, I sketch the proof here. (Note: Details of this particular proof omitted from lecture.)

Theorem 3. $\forall -\infty < a < b < \infty$, the N -dimensional cube $[a, b]^N$ is compact.

Proof. Suppose $-\infty < a < b < \infty$ and let $S = [a, b]^N$ be such that for some open cover \mathcal{F} of S there does not exist a finite sub-cover. Bisect S into 2^N equal closed hypercubes with planes parallel to the faces of S (by the way, this is why I call this proof a “sketch,” as I have not defined hypercube, plane, parallel, or face). While that sounds fairly complicated, we can visualize it in 3-dimensional space:



Note that at least one of the hypercubes cannot admit a finite sub-cover (maybe none of them admit a finite sub-cover, but we only need one). Let this cube be C_1 . We proceed recursively, and now take C_m to be our main cube, and construct C_{m+1} by partitioning C_m into 2^N equal closed cubes where at least one non-empty cube does not admit a finite-sub-cover.

1. C_m are closed.
2. C_m are non-empty. If at any point all sub-hypercubes of C_m are empty, then C_m itself is empty, a contradiction (since we started with a non-empty hypercube).
3. $C_{m+1} \subset C_m$
4. Let δ be the maximum distance between any two points in S . The maximum distance in C_m is $\frac{\delta}{2^m}$.
5. C_m is not covered by any finite sub-cover of \mathcal{F} . Since \mathcal{F} covers C_m , if all sub-hypercubes of C_m admit a finite sub-cover, the union of these will be a finite sub-cover of C_m , a contradiction.

For each m , let x_m be any element of C_m . This sequence is Cauchy: For any $\varepsilon > 0$,

$$k, l > M > \frac{\log(\delta) - \log(\varepsilon)}{\log(2)} \implies d(x_k, x_l) < \frac{\delta}{2^M} < \varepsilon$$

Because \mathbb{R}^N is complete, we know that $x_m \rightarrow x$ for some $x \in \mathbb{R}^N$. Therefore,¹

$$x \in C_m \quad \forall m$$

Since \mathcal{F} has an infinite sub-cover of C_m (which might be comprised of all the sets in \mathcal{F}), $x \in \mathcal{F}_\omega$ for some set in that infinite sub-cover. \mathcal{F}_ω is open, so for some $\varepsilon > 0$,

$$d(y, x) < \varepsilon \implies y \in \mathcal{F}_\omega$$

But $x \in C_m$ for any m , and the maximum distance between any two points in C_m is $\delta/2^m$. Hence for M s.t.

$$M > \frac{\log(\delta) - \log(\varepsilon)}{\log(2)} \implies d(x, y) < \varepsilon \quad \forall y \in C_M \implies y \in \mathcal{F}_\omega \implies C_M \subseteq \mathcal{F}_\omega$$

$\{\mathcal{F}_\omega\}$ is a finite sub-cover of C_M , a contradiction. Therefore $[a, b]^N$ is compact. □

Theorem 4. Any closed subset of a compact set is compact.

Proof. X be compact and S be a closed subset of X . Let \mathcal{F} be any open cover of S and consider

$$\mathcal{G} = \mathcal{F} \cup \mathbb{R}^N \setminus S$$

Since S is closed, $\mathbb{R}^N \setminus S$ is open. Since \mathcal{F} is an open cover of S , \mathcal{G} is therefore an open cover of $S \cup (\mathbb{R}^N \setminus S) = \mathbb{R}^N \supseteq X$. Since X is compact, \mathcal{G} has a finite sub-cover $\{\mathcal{G}_n : n \in \mathbb{N}, n \leq N\}$ s.t.

$$S \subseteq X \subseteq \bigcup_{n=1}^N \mathcal{G}_n$$

The only set in \mathcal{G} that is not in \mathcal{F} is $\mathbb{R}^N \setminus S$, but by definition $S \not\subseteq \mathbb{R}^N \setminus S$. Hence $S \subseteq (\bigcup_{n=1}^N \mathcal{G}_n) \setminus \{\mathbb{R}^N \setminus S\}$, which means $\{\mathcal{G}_n : n \in \mathbb{N}, n \leq N\} \setminus \{\mathbb{R}^N \setminus S\} \subseteq \mathcal{F}$ is a finite sub-cover of S . □

1.3. Weierstrass Extreme Value Theorem (EVT).

Theorem 5. Let $S \subseteq \mathbb{R}$ with $S \neq \emptyset$ a compact set; then S has a minimum and a maximum.

¹This uses the fact that each C_m is closed and $x_{m+n} \in C_m$ for all n ; hence the limit is also in C_m .

Proof. Since S is compact, it is closed and bounded. Since it is bounded, $\sup S$ exists. Suppose $\sup S \notin S$. Since S is closed, we can find some $\varepsilon > 0$ s.t. $B_\varepsilon(\sup S) \cap S = \emptyset$. However, any such $y \in B_\varepsilon(\sup S)$ has the property that

$$\sup S - \varepsilon < y < \sup S + \varepsilon$$

Further, we know that $x \in S \implies x \notin B_\varepsilon(\sup S)$. Hence

$$x < \sup S - \varepsilon < y < \sup S < \sup S + \varepsilon$$

for every $x \in S$ and some $y \in B_\varepsilon(\sup S)$, which means that y is an upper bound for S that is smaller than $\sup S$, a contradiction. Thus $\max S = \sup S$; the proof for $\min S = \inf S$ is analogous. \square

Theorem 6. Let $f : S \rightarrow T$ be a continuous function. If S is compact, then $f(S)$ is compact.

Proof. Take any open cover of $f(S)$:

$$\mathcal{F} = \{\mathcal{F}_\omega : \omega \in \Omega\} \quad \text{with} \quad f(S) \subseteq \bigcup_{\omega \in \Omega} \mathcal{F}_\omega$$

Consider the inverse-image of each set in the open cover:

$$f^{-1}(\mathcal{F}) = \{f^{-1}(\mathcal{F}_\omega) : \omega \in \Omega\}$$

For each $s \in S$, we know $f(s) \in f(S)$, and in turn for each $f(s) \in f(S)$ there is some ω s.t. $f(s) \in \mathcal{F}_\omega$, which implies $s \in f^{-1}(\mathcal{F}_\omega)$. In other words $f^{-1}(\mathcal{F})$ covers S . Since f is continuous, we know the pre-image of open sets is open, meaning this is an open cover. Since S is compact, it admits a finite sub-cover:

$$\mathcal{G} = \{f^{-1}(\mathcal{F}_{\omega_i}) : i = 1, \dots, N\} \quad \text{with} \quad S \subseteq \bigcup_{i=1}^N f^{-1}(\mathcal{F}_{\omega_i})$$

The image of a finite union of sets is just the union of their individual images. Hence

$$f(S) \subseteq f\left(\bigcup_{i=1}^N f^{-1}(\mathcal{F}_{\omega_i})\right) = \bigcup_{i=1}^N f\left(f^{-1}(\mathcal{F}_{\omega_i})\right) = \bigcup_{i=1}^N \mathcal{F}_{\omega_i} \cap f(S) \subseteq \bigcup_{i=1}^N \mathcal{F}_{\omega_i}$$

\mathcal{F} was arbitrary and we found a finite sub-cover $\{\mathcal{F}_{\omega_i} : i = 1, \dots, N\}$. By definition $f(S)$ is compact. (We remark that we need to write $\mathcal{F}_{\omega_i} \cap f(S)$ because the image of the pre-image of an arbitrary set need not be the set itself! Even if, in this case, we know the pre-image is non-empty, there is no reason why every element in the set will map to an element in S or even in S . For example, let $f(x) = x$ with $S = (0, 3)$. Note $f([1, 2]) = [1, 2] \subseteq (0, 4)$, but $f(f^{-1}((0, 4))) = f((0, 3)) = (0, 3) \neq (0, 4)$.) \square

Theorem 7 (Weierstrass' EVT). If S is a compact set $\varphi : S \rightarrow \mathbb{R}$ is continuous then $\exists x, y$ s.t. $\varphi(x) = \sup \varphi(S)$ and $\varphi(y) = \inf \varphi(S)$.

Proof. The **EVT** follows directly from other theorems in this section. Since S is compact and φ continuous, $\varphi(S)$ is compact. Since $\varphi(S) \subseteq \mathbb{R}$ is compact, it has a minimum and a maximum. \square

Application to Economics Consider a standard utility maximization problem

$$\max_{x \in B(p, w)} u(x)$$

with $B(p, w) = \{x : p \cdot x \leq w\}$ and $x, p \in \mathbb{R}_+^N$. $B(p, w)$ is closed and bounded, so if $u(x)$ is continuous the maximum exist and the problem has a solution at some $x^* \in B(p, w)$.

1.4. Using Sequential Definitions. The idea here is to show examples of how to construct sequences in a way that helps when doing proofs. We saw these proofs already without using sequences; however, we have seen that various definitions often have a sequential version, so let us see how they might help.

1. Let us show if $f : S \rightarrow T$ is continuous function, then S is compact implies $f(S)$ compact.

Proof. • Take any sequence $y_m \in f(S)$; we know $\forall m \exists x_m \in S$ s.t. $f(x_m) = y_m$.

- S is compact, so it is sequentially compact; that is, $\exists x_{m_k} \rightarrow x$ for some $x \in S$.
- f is continuous, so $y_{m_k} = f(x_{m_k}) \rightarrow f(x) \in f(S)$. Let $y \equiv f(x)$.
- Hence $\forall y_m \in f(S) \exists y_{m_k} \rightarrow y$ for some $y \in f(S)$.

By definition, $f(S)$ is sequentially compact, which means it is compact. □

2. Let us show [Weierstrass' EVT](#):

Proof. • Since S is compact and φ is continuous, $\varphi(S)$ is compact.

- $\varphi(S)$ is compact, so it is closed and bounded.
- $\varphi(S)$ bounded means $-\infty < \inf \varphi(S) \leq \sup \varphi(S) < \infty$.
- By definition of $\sup \varphi(S)$, $\forall \varepsilon_m = 1/m \exists z_m \in \varphi(S)$ s.t. $\sup \varphi(S) - \varepsilon < z_m \leq \sup \varphi(S)$ (if not, then $\sup \varphi(S) - \varepsilon$ would be the sup, contradiction). Note $z_m \rightarrow \sup \varphi(S)$.
- $\varphi(S)$ closed means it has all its limits, so $\sup \varphi(S) \in \varphi(S)$. Hence $\exists x \in S$ s.t. $x = \sup \varphi(S)$.
- For the inf, construct a sequence $z_m \in \varphi(S)$ s.t. $\inf \varphi(S) \leq z_m < \inf \varphi(S) + \varepsilon$. $z_m \rightarrow \inf \varphi(S)$ so $\inf \varphi(S) \in \varphi(S)$, and $\exists y \in S$ s.t. $\varphi(y) = \inf \varphi(S)$.

Therefore φ attains its sup and its inf. □

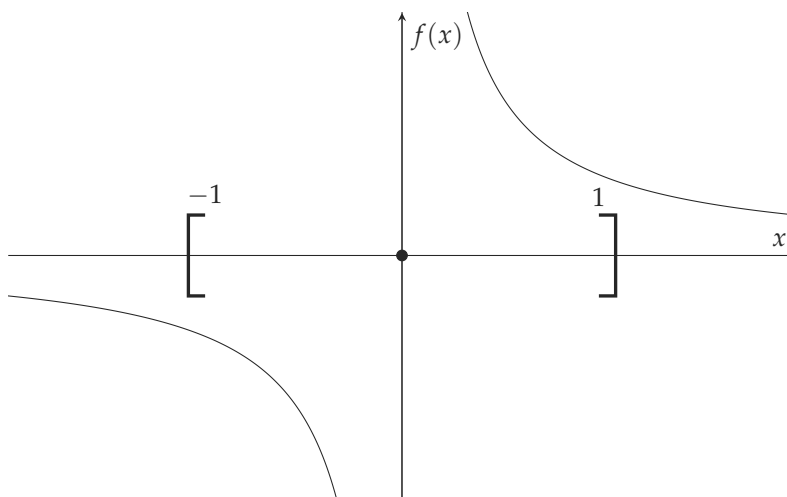
1.5. Review. I think focusing on the *properties* of compactness can be more important than all the proofs above. Further, since we'll typically work with the reals, I think the intuition of compactness as equivalent to closed and bounded is fine (certainly for this course).

Table 1: Compactness! What is it good for? Actually, quite a bit.

<i>S</i> is compact:	
Definition	For any open cover there exists a finite sub-cover . $\forall \mathcal{O} = \{O_\omega : \omega \in \Omega\} \text{ open cover } \exists W \subseteq \Omega \text{ s.t. } W \text{ finite and } S = \bigcup_{\omega \in W} O_\omega$
Characterization	\iff sequentially compact : Any sequence has a convergent subsequence. $\forall (x_m) \in S \ \exists x \in S \text{ and } (x_{m_k}) \text{ s.t. } x_{m_k} \rightarrow x.$
Implications	\implies <i>S</i> is closed and bounded . \implies any closed subset of <i>S</i> is compact. \implies <i>f</i> (<i>S</i>) is compact for any continuous <i>f</i> . \implies <i>f</i> (<i>S</i>) has a min and a max for any continuous <i>f</i> (EVT).
Heine-Borel	In Euclidean space only (\mathbb{R}^N): \iff <i>S</i> is closed and bounded .

- If *S* is compact, then I can construct an **arbitrary collection of open sets** that contains *S*, and I know I will get **something finite** out of it.
- If *S* is compact, then I can construct an **arbitrary sequence** in *S*, and I know I will get something **convergent** out of it.

Finally, I wanted to make a note about why continuity is additionally required to get maxima and minima. It's easiest to visualize with real functions: Consider $f(x) = 1/x$ if $x \neq 0$ and $f(x) = 0$ if $x = 0$. This is not continuous, and does not have a min or a max on, say, $[-1, 1]$, which is a compact set. Visually:



The set is compact, but the function diverges to ∞ as it approaches 0 from the right, and to $-\infty$ as it approaches 0 from the left.

2. Correspondences

2.1. “Set-Valued Functions”. A correspondence, denoted $\Gamma : X \rightrightarrows Y$, assigns a non-empty subset of Y to each point in X . In a sense, a correspondence is a “set-valued function” with “input” $x \in X$ and “output” is $\Gamma(x) \subseteq Y$.² Some terminology is completely analogous relative to when we were working with functions:

- X is the **domain** and Y is the **co-domain**.
- $\forall S \subseteq X$ let $\Gamma(S) \equiv \bigcup \{\Gamma(x) : x \in S\}$ is the **image** of S .
- $\Gamma(X)$ is the range, and if $\Gamma(X) = Y$ we say Γ is **surjective**.

Here’s the first roadblock: What would it mean for a correspondence to be *injective*? For functions, we want to capture the idea of *one-to-one*. A correspondence, however, starts from the premise that a mapping can be one to many. Is there an analogous idea that we *should* try to capture? We leave this question unanswered as an example of why we need to be specially careful when dealing with correspondences.

Example 1. If $\Gamma(X) \subseteq X$ then we say it’s a “self-correspondence.” An example of such a correspondence is the choice correspondence from utility maximization.

$$\operatorname{argmax}_{\mathbb{R}_+^N} u(x) \quad \text{s.t.} \quad p \cdot x \leq w$$

We can go a step further and also define the problem over correspondences. Let

$$\Gamma(p, w) = \{x \in \mathbb{R}^+ : p \cdot x \leq w\}$$

be the budget correspondence. Then we can define the argmax correspondence as

$$\operatorname{argmax} u(x) \quad \text{s.t.} \quad x \in \Gamma(p, w)$$

Why go through the trouble? The idea is that if we can prove enough theorems and properties of correspondences, re-expressing some problems we’re familiar with in terms of correspondences might make how to solve them and what their properties are more transparent. \square

Remark 2. Since correspondences map points to sets, it is typical to refer to correspondences as [property]-valued, where [property] is any property of a set. For example, they can be closed-valued, compact-valued, convex-valued, and so on. \square

2.2. Inverse Images. With functions we had a nice characterizations of continuity: f^{-1} the inverse image maps open sets to open sets. What is the analogue for Γ^{-1} ?

- $f^{-1}(O) = \{x \in X : \{f(x)\} \subseteq O\}$.
- $f^{-1}(O) = \{x \in X : \{f(x)\} \cap O \neq \emptyset\}$.

These are analogous for functions, but for correspondences it defines two distinct sets, the *upper* inverse image and the *lower* inverse image, which will give rise to two different notions of continuity:

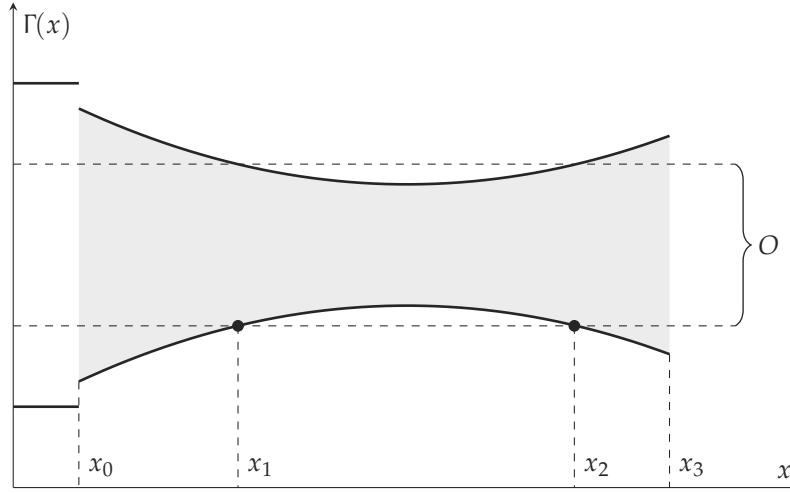
Definition 4. Given a correspondence $\Gamma : X \rightrightarrows Y$

²Conversely, functions are “singleton-valued correspondences,” where $f(x)$ is equivalent to the correspondence $\Gamma(x) = \{f(x)\}$.

- $\Gamma^{-1}(O) \equiv \{x \in X : \Gamma(x) \subseteq O\}$ is the **upper inverse image**.
- $\Gamma_{-1}(O) \equiv \{x \in X : \Gamma(x) \cap O \neq \emptyset\}$ is the **lower inverse image**.

Note that $\Gamma(x) \neq \emptyset$ and $\Gamma(x) \subseteq O \implies \Gamma(x) \cap O \neq \emptyset$. So necessarily $\Gamma^{-1}(O) \subseteq \Gamma_{-1}(O)$.

Figure 2: Visualizing the Upper and Lower Inverse Image



In the image above, every point $x \in [x_0, x_3]$ is s.t. $\Gamma(x) \cap O \neq \emptyset$, so $\Gamma_{-1}(O) = [x_0, x_3]$; however, not every point is s.t. $\Gamma(x) \subseteq O$. In this case, only points $y \in (x_1, x_2)$ are s.t. $\Gamma(y) \subseteq O$, so $\Gamma^{-1}(O) = (x_1, x_2)$. Last, if $z \in [0, x_0]$ then $\Gamma(z)$ is neither contained in nor intersects with O .

2.3. Hemicontinuity. We present two distinct definitions of continuity. If we use the *upper* inverse image:

Definition 5. $\Gamma : X \rightrightarrows Y$ is **upper hemi-continuous** (uhc) if whenever $O \subseteq Y$ is open, $\Gamma^{-1}(O)$ is also open.

If $\Gamma(x) \subseteq O$ then $x \in \Gamma^{-1}(O)$; if $\Gamma^{-1}(O)$ is open $\exists \delta > 0$ s.t. $B_\delta(x) \subseteq \Gamma^{-1}(O)$, so $\Gamma(B_\delta(x)) \subseteq O$. Therefore we have the following equivalent definition of uhc.

Definition 6. $\Gamma : X \rightrightarrows Y$ is uhc iff $\forall O \subseteq Y$ open with $\Gamma(x) \subseteq O \exists \delta > 0$ s.t. $\Gamma(B_\delta(x)) \subseteq O$.

We can similarly define continuity in terms of the *lower* inverse image instead:

Definition 7. $\Gamma : X \rightrightarrows Y$ is **lower hemi-continuous** (lhc) if whenever $O \subseteq Y$ is open, $\Gamma_{-1}(O)$ is also open.

If $\Gamma(x) \cap O \neq \emptyset$ then $x \in \Gamma_{-1}(O)$; if $\Gamma_{-1}(O)$ is open $\exists \delta > 0$ s.t. $B_\delta(x) \subseteq \Gamma_{-1}(O)$, so $z \in B_\delta(x) \implies \Gamma(z) \cap O \neq \emptyset$. Therefore we can equivalently write the following definition:

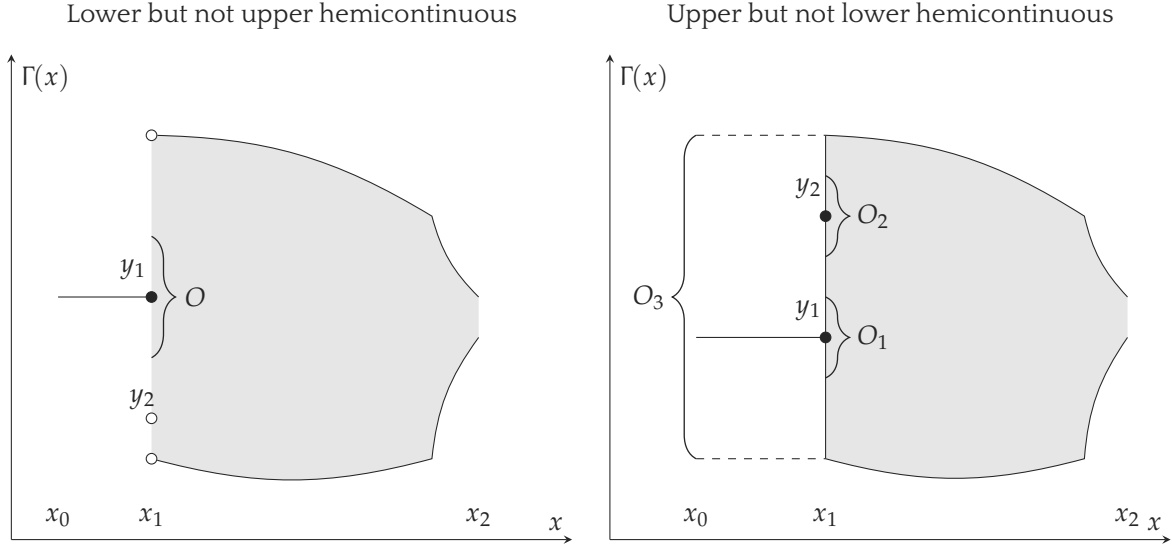
Definition 8. $\Gamma : X \rightrightarrows Y$ is lhc iff $\forall O \subseteq Y$ open with $\Gamma(x) \cap O \neq \emptyset \exists \delta > 0$ s.t. $\Gamma(z) \cap O \neq \emptyset \forall z \in B_\delta(x)$.

- Intuitively, if Γ is uhc at x and z is “close” to x , every point in $\Gamma(z)$ will be “close” to some point in $\Gamma(x)$.
If there is some neighborhood around x s.t. every open set *containing* $\Gamma(x)$ also contains $\Gamma(z)$ for z in the neighborhood, then nothing in $\Gamma(z)$ can be suddenly “far” from the all values of x .
- By contrast, if Γ is lhc at x and z “close” to x , each point in $\Gamma(x)$ will be “close” to some point in $\Gamma(z)$.

Intersections, unlike containment, can happen at *any* point. Hence *lhc* does *not* require every point in $\Gamma(z)$ to always be close to $\Gamma(x)$; rather, it requires every point in $\Gamma(x)$ to be close to *some* point in $\Gamma(z)$.

We will formalize the intuition above when we discuss the sequential definition of *uhc* and *lhc*.

Figure 3: Upper and Lower Hemicontinuity (Inverse Images)



Let $\Gamma : [x_0, x_2] \rightrightarrows \mathbb{R}$ be as depicted above:

- In the left figure, $\Gamma(x_1) = y_1 \subseteq O$; however, no matter how small the δ $y_2 \in \Gamma(x_1 + \delta) \notin O$, meaning the set values of points near x_1 always have elements far away from $\Gamma(x_1)$. Hence it cannot be *uhc*. Formally, $\Gamma^{-1}(O) = [x_0, x_1]$, which is not open.

But it is *lhc*: The set values of every point near x_1 will intersect O , and generally every set intersecting $\Gamma(x_1)$. Formally, for any such set $\Gamma^{-1}(O) = [x_0, x_2]$ (note $X = [x_0, x_2]$, and X is open relative to X).

- In the right figure, $y_1 \in \Gamma(x_1) \cap O_1 \neq \emptyset$, and every point around x_1 will also intersect O_1 . However, $y_2 \in \Gamma(x_1) \cap O_2 \neq \emptyset$, but no matter how small the δ , $\Gamma(x_1 - \delta) \cap O_2 = \emptyset$, meaning not every element in $\Gamma(x_1)$ is near the set-values of points near x_1 . Formally, $\Gamma^{-1}(O_2) = [x_1, x_2]$, which is not open in $[x_0, x_2]$.

But it is *uhc*: O_3 , and generally any set containing all of x_1 , will also contain the set value of every point around x_1 . Formally, $\Gamma^{-1}(O_3)$, or any such set, is $[x_0, x_2]$, the space itself, which is open.

2.4. Sequential Characterization of Hemicontinuity.

Remark 3. It not uncommon to encounter the sequential characterizations as the definition (in fact the very first time I learned what a correspondence was, I only encountered the sequential characterization of hemicontinuity). \square

Theorem 8. $\Gamma : X \rightrightarrows Y$. If $\forall (x_m) \in X, (y_m) \in Y$ s.t. $x_m \rightarrow x, y_m \in \Gamma(x_m) \exists y_{m_k} \rightarrow y$ for some $y \in \Gamma(x)$, then Γ is *uhc* at x . If Γ is compact-valued, the converse is also true.

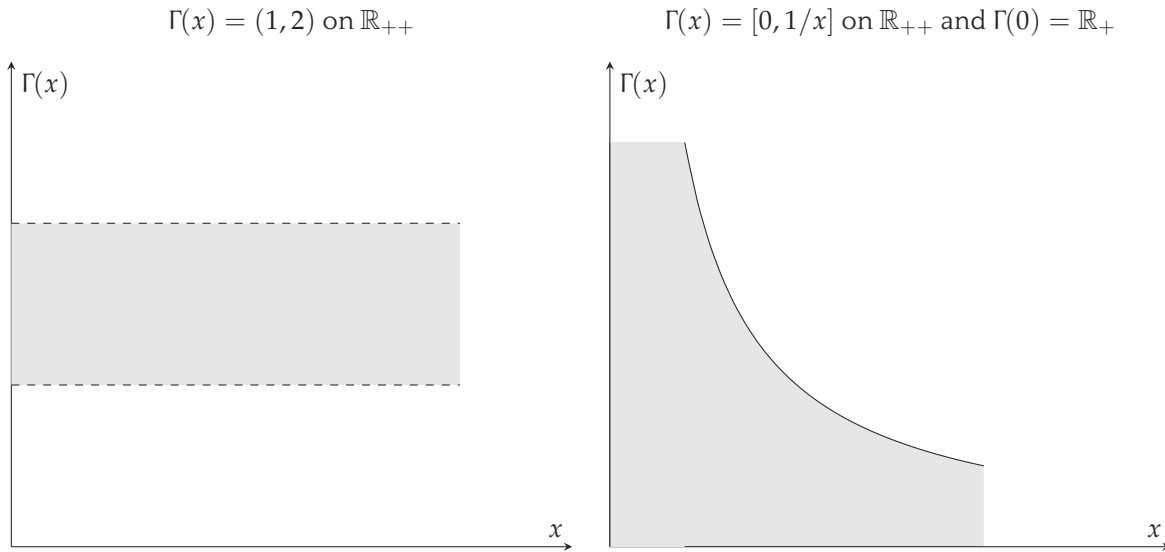
Some remarks:

- The definition says that for every sequence converging to x and every sequence in the set-values of x_m , $y_m \in \Gamma(x_m)$, there is a convergent sub-sequence to an element $y \in \Gamma(x)$.

Recall our intuition for uhc: Every point in $\Gamma(z)$, for z sufficiently “close” to x , is also “close” to *some* point of $\Gamma(x)$. This closely mirrors the sequential definition: If every time we get arbitrarily close to x (that is, $x_m \rightarrow x$) every point in those set values (arbitrary $y_m \in \Gamma(x_m)$) will be arbitrarily close to *some* point in $\Gamma(x)$ (there is some sub-sequence $y_{m_k} \rightarrow y \in \Gamma(x)$, which means that *every* sequence in $\Gamma(x_m)$ has infinitely many points near *some* value of $\Gamma(x)$).

- So why doesn't the converse hold? The above sequential definition requires the function to be uhc, but uhc correspondences don't have to be closed or bounded:

Figure 4



- The figure on the left is uhc: Since the function is constant, if $\Gamma(x) \subseteq O$ for any O , then $\Gamma(y) = \Gamma(x) \subseteq O$ for every $y \in (0, \infty)$. Thus $\Gamma^{-1}(O) = \mathbb{R}_{++}$. However, for $1/n \rightarrow 0$ and $1 + 1/n \in \Gamma(1/n)$, $1 + 1/n \rightarrow 1 \notin \Gamma(0) = (1, 2)$.
- The figure on the right is also uhc: Take any open $O \subset \mathbb{R}_+$ s.t. $\Gamma(x) \subseteq O$ and we have $\Gamma^{-1}(O) = (x, \infty)$. Last, if $\Gamma(0) \subseteq O \subseteq \mathbb{R}$ then $O = \mathbb{R}_+$, and $\Gamma^{-1}(\mathbb{R}_+) = [0, 1] = X$ (and, again, X is open relative to itself). However, take $1/n \rightarrow 0$ and $n \in \Gamma(1/n)$; $n \rightarrow \infty \notin \mathbb{R}_+$.
- Therefore uhc is not enough to guarantee that a sequence always exists. More precisely, it's not so much that we need the set-values of Γ to be closed and bounded: We need them to be compact, and that will guarantee the existence of a sub-sequence. (Recall here the link between compactness and sequential compactness, which would show up in a proof of [Theorem 8](#).)

Theorem 9. $\Gamma : X \rightrightarrows Y$ is *lhc* at $x \in X \iff \forall (x_m) \in X$ s.t. $x_m \rightarrow x \in X$ and $\forall y \in \Gamma(x) \exists (y_m) \in Y$ s.t. $y_m \rightarrow y$ and $y_m \in \Gamma(x_m)$.

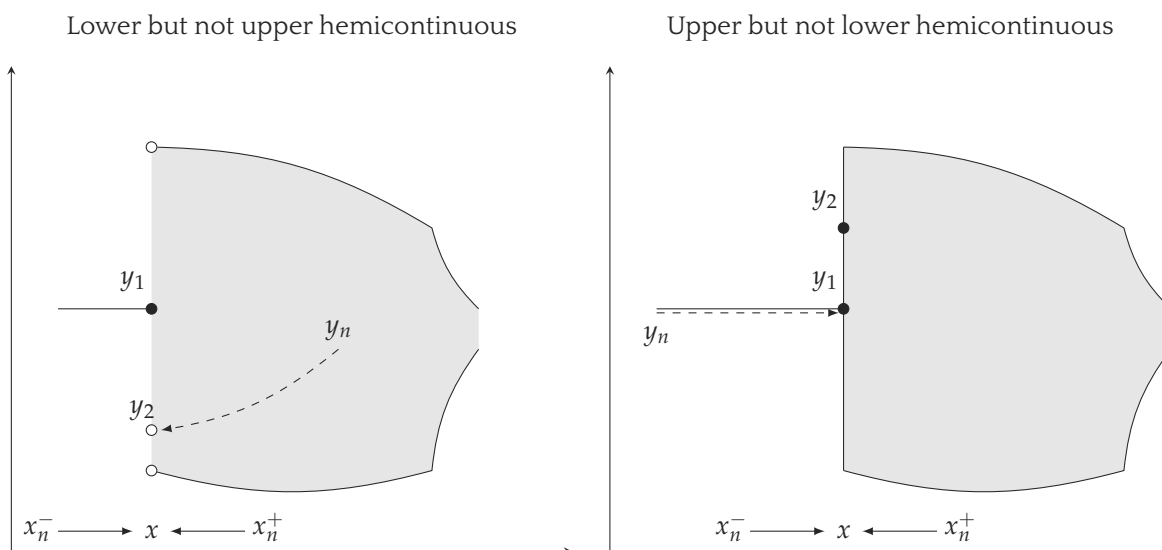
Given both sequential definitions of uhc and lhc, we repeat our intuition:

1. If Γ is uhc at x then every point $y \in \Gamma(z)$, for z arbitrarily close to x , is itself close to some point in $\Gamma(x)$. The limit definition follows this closely: As $x_m \rightarrow x$, every sequence $y_m \in \Gamma(x_m)$ will have infinitely many

elements arbitrarily close to *some* point in $\Gamma(x)$, so there will be *some* sub-sequence $y_{m_k} \rightarrow y \in \Gamma(x)$ (with the caveat that Γ is compact-valued).

2. If Γ is lhc at x and z is arbitrarily close to x , then every point $y \in \Gamma(x)$ must be arbitrarily close to *some* point in $\Gamma(z)$. Again, the limit definition follows this: As $x_m \rightarrow x$, every point $y \in \Gamma(x)$ will be arbitrarily close to *some* point in $\Gamma(x_m)$, so there will exist a sequence $y_m \in \Gamma(x_m)$ s.t. $y_m \rightarrow y$.

Figure 5: Upper and Lower Hemicontinuity (Sequences)



2.5. Closed Graph.

Definition 9. The **graph** of a correspondence $\Gamma : X \rightrightarrows Y$, denoted $Gr(\Gamma)$, is

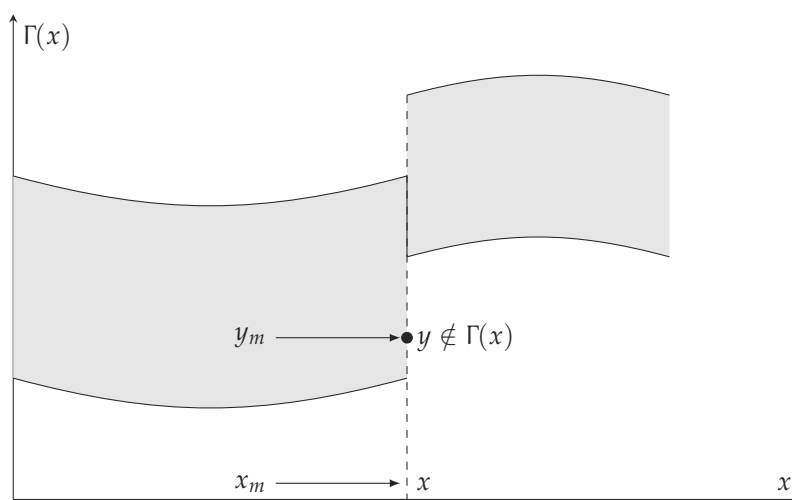
$$Gr(\Gamma) \equiv \{(x, y) \in X \times Y : y \in \Gamma(x)\}$$

Γ has a closed graph if ...its graph is closed.

Definition 10. Γ is **closed** at $x \in X$ if $\forall (x_m) \in X^\infty, (y_m) \in Y^\infty$ s.t. $x_m \rightarrow x \in X, y_m \rightarrow y \in Y$, and $y_m \in \Gamma(x_m)$ we also have $y \in \Gamma(x)$. Γ has a **closed graph** if it is closed at every $x \in X$.

This definition might seem complicated but if you look closely, it is just the sequential characterization of what it means for a set to be closed (it has all its limits).

Figure 6: Not Closed Graph



The idea is that every series in $\Gamma(x_m)$ that converges will converge to a point in $\Gamma(x)$ (if $x_m \rightarrow x$).

Remark 4. Closed graph is *not* the same as closed-valued!

The example in Figure 6 above is closed-valued but not closed graph, so the former need not imply the latter. Further, a closed graph is not the same as uhc: A uhc correspondence doesn't have to be closed-valued, which would mean that it would not have a closed graph (if $\Gamma(x)$ is not closed-valued, then there is some sequence in $\Gamma(x)$ that converges to a point outside of $\Gamma(x)$, contradicting the definition of closed graph).

Conversely, a correspondence can have a closed graph with a discontinuity. $\Gamma(x) = \{1/x\}$ if $x > 0$ and $\Gamma(x) = \{0\}$ if $x = 0$. Note that any sequence in $\Gamma(x)$ as $x \rightarrow 0^+$ will diverge, so there is no contradiction of the closed graph property. However, there is clearly a discontinuity at 0. \square

We can, however, say that closed graph, closed-valued, and uhc are related:

Claim 1. 1. If $\Gamma : X \rightrightarrows Y$ has a closed graph and Y is compact then Γ is uhc.

2. If Γ is uhc and closed-valued then it has a closed-graph.

2.6. Berge's Theorem of the Maximum.

Theorem 10 (Berge's Maximum Theorem). Let $\Gamma : \Theta \rightrightarrows X$ be compact-valued, $\varphi : X \times \Theta \rightarrow \mathbb{R}$ be continuous, and define

$$\sigma(\theta) \equiv \operatorname{argmax}_{x \in \Gamma(\theta)} \varphi(x, \theta)$$

$$\varphi^*(\theta) \equiv \max_{x \in \Gamma(\theta)} \varphi(x, \theta)$$

If Γ is both upper and lower hemi-continuous at some $\theta \in \Theta$ then

1. $\sigma : \Theta \rightrightarrows X$ is compact-valued everywhere, uhc at θ , and closed at θ .
2. $\varphi^* : \Theta \rightarrow \mathbb{R}$ is continuous at θ .

Application to Economics Recall the utility maximization problem with parameters $(p, w) \in \mathbb{R}_+^{N+1}$:

$$\begin{aligned} v(p, w) &\equiv \max u(x) \quad \text{s.t.} \quad p \cdot x \leq w \\ x(p, w) &\equiv \operatorname{argmax} u(x) \quad \text{s.t.} \quad p \cdot x \leq w \end{aligned}$$

Recall $B(p, w) = \{x : p \cdot x \leq w\}$ the budget correspondence is compact. It turns out it is also uhc and lhc, so we not only know that the maximum exists (if $u(x)$ continuous), but in particular the indirect utility function $v(p, w)$ is continuous and the demand correspondence $x(p, w)$ is compact-valued, uhc, and closed.

Remark 5. During class, I was asked how we know that the budget correspondence was compact, uhc, and lhc. This is not at all obvious! For the curious, I offer proofs in [Appendix A](#). \square

3. Fixed Point Theorems

Definition 11. A self-map $f : S \rightarrow S$ has a **fixed point** if $\exists x^* \in S$ s.t. $x^* = f(x^*)$.

Theorem 11 (Brouwer's FPT). Take any $S \subseteq \mathbb{R}$ compact, convex, and non-empty. If $f : S \rightarrow S$ is continuous then it has a fixed point.

Definition 12. A self-map correspondence $\Gamma : S \rightrightarrows S$ has a **fixed point** if $\exists x^* \in S$ s.t. $x^* \in \Gamma(x^*)$.

Definition 13. A set S is **convex** if $\forall x, y \in S$ and $\forall \alpha \in [0, 1]$ we have $\alpha x + (1 - \alpha)y \in S$.

Theorem 12 (Kakutani's FPT). Take any $S \subseteq \mathbb{R}^N$ compact, convex-valued, and non-empty. If a correspondence $\Gamma : S \rightrightarrows S$ is upper hemicontinuous then it has a fixed point.

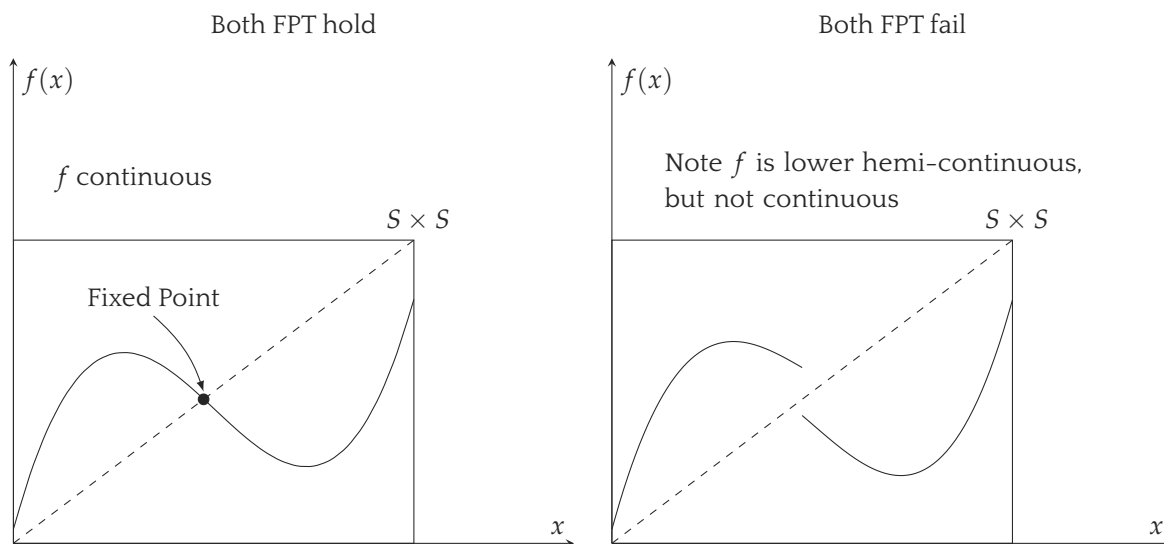
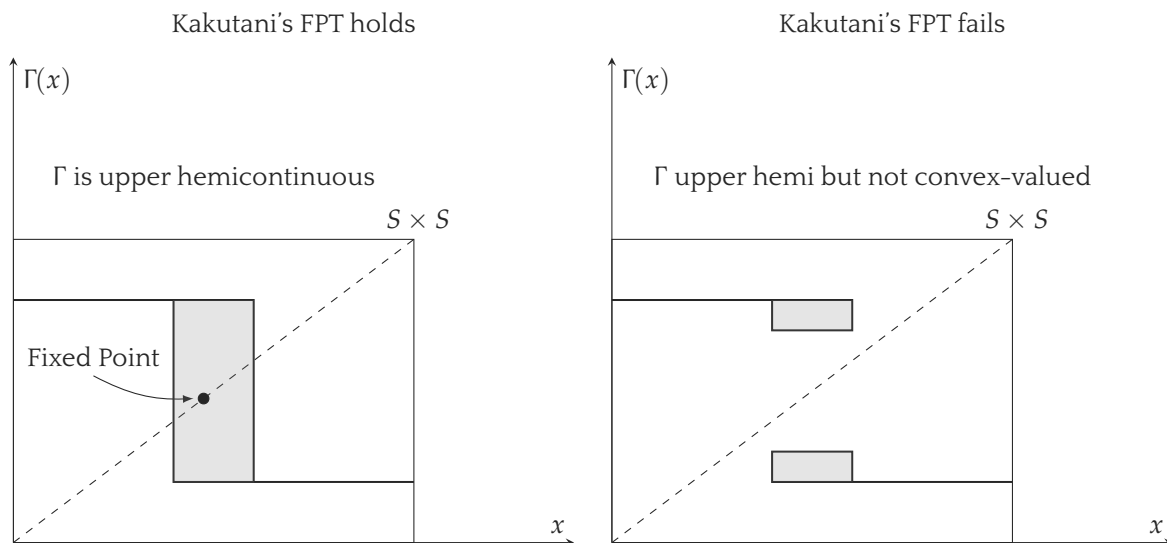


Figure 7: Examples of when f does or not have a fixed point

Figure 8: Examples of when Γ does or not have a fixed point

Application to Economics The proof of the existence of a Nash Equilibrium in game theory is an application of Kakutani's fixed point theorem.

- We have N players, $1, 2, \dots, N$ and the corresponding strategy sets, S_1, \dots, S_N .
- Let $s = (s_1, \dots, s_N)$ be any collection of strategies from all players, with $s_i \in S_i$.
- Let $s_{-i} = (s_1, \dots, s_{i-1}, s_{i+1}, \dots, s_N)$ the collection of strategies from all players other than i .
- For each player i we can define a *best-response* function to the strategies of other players,

$$b_i(s_{-i}) = \operatorname{argmax}_{s_i \in S_i} u_i(s_i; s_{-i})$$

the utility-maximizing strategy for i given the other player's strategies.

- Let $b(s) = (b_1(s_{-1}), \dots, b_N(s_{-N}))$ be the collection of best-response strategies from all players.

A Nash Equilibrium is then defined as a set of strategies such that no player has an incentive to deviate. That is, the strategy s_i^* chosen by player i is in the set of best responses to all the other strategies, s_{-i}^* , or $s_i^* \in b_i(s_{-i}^*) \quad \forall i$. We can hence express a Nash Equilibrium s^* as a fixed point of b ,

$$s^* \in b(s^*)$$

If S_i are compact, non-empty, and convex-valued, and u_i are continuous and quasiconcave, then we will be able to apply Kakutani's fixed point theorem to show that $s^* \in b(s^*)$ for some $s^* \in S = \prod_{i=1}^N S_i$ (with some work in between to show that $b : S \rightarrow S$ is upper hemicontinuous).

Appendix A. Budget Correspondence Properties

Since this came up in class, here are some formal proofs about some properties I claimed the budget correspondence had. Only for the very curious!

A.1. Compact. We invoke [Heine-Borel](#). First, let us see $B(p, w)$ is closed:

$$[B(p, w)]^C \equiv \mathbb{R}_+^N \setminus B(p, w) = \left\{ x \in \mathbb{R}_+^N : p \cdot x > w \right\}$$

Let $\delta = (p \cdot x - w) / \sum p_k$. Noting $\|x - z\| < \delta \implies |x_k - z_k| < \delta$, we have

$$\begin{aligned} p \cdot (x - z) &\leq p \cdot |x - z| < p \cdot \delta = \frac{p \cdot x - w}{\sum p_k} \sum p_k = p \cdot x - w \\ p \cdot x - p \cdot z &< p \cdot x - w \implies w < p \cdot z \implies z \in [B(p, w)]^C \end{aligned}$$

Hence $[B(p, w)]^C$ is open, meaning its complement, $B(p, w)$, is closed. To see its bounded,

$$\begin{aligned} w &\geq p \cdot x \geq \sum x_k \cdot \min p_k \\ \frac{w}{\min_k p_k} &\equiv M \geq \sum x_k \stackrel{!}{\geq} x_k \quad \forall k \end{aligned}$$

(to see why $\stackrel{!}{\geq}$ is true, recall $x \in \mathbb{R}_+^N \implies x_k \geq 0 \ \forall k$). Hence $x \in B(p, w) \implies 0 \leq x_k \leq M \ \forall k$, meaning $B(p, w)$ is bounded. Since $B(p, w)$ is a closed and bounded subset of \mathbb{R}_+^N , it is also compact.

A.2. Upper hemi-continuous. Fix any (p, w) and consider any arbitrary sequence $(p_m, w_m) \rightarrow (p, w)$ and any arbitrary sequence $x_m \in B(p_m, w_m)$. If we can show that $\exists x_{m_k} \rightarrow x$ for some $x \in B(p, w)$, then $B(p, w)$ is upper hemicontinuous (uhc).

1. First, find an arbitrary finite bound for x_m . For instance, let $\varepsilon = 1$; since $(p_m, w_m) \rightarrow (p, w)$ then $\exists M$ s.t.

$$m \geq M \implies \|(p_m, w_m) - (p, w)\| < \varepsilon \implies |p_{k,m} - p_k| < \varepsilon \quad \text{and} \quad |w_m - w| < \varepsilon$$

for each k . Therefore any $x_m \in B(p_m, w_m)$ is s.t.

$$(p - \varepsilon) \cdot x_m \leq p_m \cdot x_m \leq w_m \leq w + \varepsilon \implies x_m \in B(p - \varepsilon, w + \varepsilon)$$

for each $m \geq M$.

2. Now show that x_m has a convergent sub-sequence. In [Subsection A.1](#) we showed B is compact for any (p, w) , so $B(p - \varepsilon, w + \varepsilon)$ is compact and, in turn, sequentially compact. Hence $\exists x_{m_k} \rightarrow x$ for some $x \in B(p - 1, w + 1)$. Since $p_{m_k} \cdot x_{m_k}$ is continuous (it's just a linear function of p_{m_k} and x_{m_k}),

$$p_{m_k} \rightarrow p \quad \text{and} \quad x_{m_k} \rightarrow x \implies p_{m_k} \cdot x_{m_k} \rightarrow p \cdot x$$

3. Finally, $p_{m_k} \cdot x_{m_k} \rightarrow p \cdot x$ and $w_{m_k} \rightarrow w$ and $p_{m_k} \cdot x_{m_k} \leq w_{m_k} \ \forall k \implies p \cdot x \leq w \implies x \in B(p, w)$.

Therefore $\forall x_m \in B(p_m, w_m) \ \exists x_{m_k} \rightarrow x$ for some $x \in B(p, w)$, meaning $B(p, w)$ is uhc. In sum, to prove a correspondence is uhc the degree of freedom we have is that we can converge to any point in $B(p, w)$; however, the restriction is that the sequence is arbitrary. We used sequential compactness because that guarantees that a convergent sub-sequence exists, and then we showed the limit was in the correspondence.

A.3. Lower hemi-continuous. Fix any (p, w) and consider an arbitrary sequence $(p_m, w_m) \rightarrow (p, w)$ and any point $x \in B(p, w)$. If $\exists x_m \in B(p_m, w_m)$ s.t. $x_m \rightarrow x$ then $B(p, w)$ is lhc.

1. Here we are restricted in that every point in the correspondence must have a sequence that converges to it. However, the degree of freedom we have is that we can pick the sequence. Our strategy, then, is to construct a sequence that will be contained in $B(p_m, w_m)$.
2. Let $\tilde{x}_{n,k} \equiv \max\{x_k - 1/n, 0\}$. That is, $\tilde{x}_n \equiv \max\{x - 1/n, 0\}$ element-wise. We claim $\forall n > N \exists M_n$ s.t.

$$m \geq M_n \implies \tilde{x}_n \in B(p_m, w_m) \quad (\text{or, equivalently}) p_m \cdot \tilde{x}_n \leq w_m$$

3. Here we use the fact $(p_m, w_m) \rightarrow (p, w)$, so by definition $\forall \delta_n > 0 \exists M_n$ s.t.

$$m \geq M_n \implies \|(p_m, w_m) - (p, w)\| < \delta_n \implies |p_{k,m} - p_k| < \delta_n \quad \text{and} \quad |w_m - w| < \delta_n$$

4. Therefore, we want to find $\delta_n > 0$ s.t. $(p + \delta_n) \cdot \tilde{x}_n \leq (w - \delta_n)$. The corresponding M_n would give

$$m \geq M_n \implies p_m \cdot \tilde{x}_n \leq (p + \delta_n) \cdot \tilde{x}_n \leq (w - \delta_n) \leq w_m$$

Recall $x \in B(p, w)$, so $p \cdot x \leq w$, meaning it is sufficient for δ_n to be s.t.

$$\begin{aligned} \delta_n \cdot \left(x + \frac{1}{n}\right) + p \cdot \frac{1}{n} &\leq -\delta_n \\ \sum \delta_n x_k - \sum \frac{\delta_n}{n} - \sum \frac{p_k}{n} &\leq -\delta_n \\ \delta_n \sum x_k - N \frac{\delta_n}{n} - \frac{1}{n} \sum p_k &\leq -\delta_n \\ \delta_n \left(\sum x_k - \frac{N}{n} + 1\right) &\leq \frac{1}{n} \sum p_k \end{aligned}$$

Therefore we can see that

$$\delta_n \equiv \frac{\sum p_k}{n \sum x_k - N + n} \implies (p + \delta_n) \cdot \tilde{x}_n \leq (w - \delta_n) \implies p_m \cdot \tilde{x}_n \leq w_m \quad \forall m \geq M_n$$

where $\delta_k > 0$ because we set up $k > L$ and $p \gg 0$.

5. Last, we define the sequence that gives us the result:

- Let $x_m = 0$ for $m < M_{N+1}$ (0 is in every budget correspondence).
- Let $x_m = \tilde{x}_n$ for $m : M_n \leq m < M_{n+1}$ otherwise ($n \geq N + 1$).

since $1/n \rightarrow 0$ we have $\tilde{x}_n \rightarrow \max\{x, 0\} = x$ (recall $x \geq 0$ because $x \in \mathbb{R}_+^N$).

Hence for any $x \in B(p, w)$ we can construct a sequence $x_m \rightarrow x$ s.t. $x_m \in B(p_m, w_m)$ for each m , meaning $B(p, w)$ is lhc.

Keywords

closed, [14](#)
closed and bounded, [9](#)
closed graph, [14](#)
closed subset, [9](#)
co-domain, [10](#)
compact, [2](#)
convex, [16](#)
cover, [2](#)

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evt, [7](#), [9](#)

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