# TTIC 31230, Fundamentals of Deep Learning

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Deep Graphical Models

aka, Energy Based Models

## Distributions on Exponentially Large Label Sets

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} E_{(x, \mathcal{Y}) \sim \operatorname{Pop}} - \ln P(\mathcal{Y}|x)$$

The structured case: The number of possible labels is exponentially large — iteration over the possible labels is infeasible.

#### Parsing and CKY

Consider the case where x is a sentence and y is a parse tree for x. There are exponentially many possible parse trees for a given sentence.

The Cocke–Kasami–Younger (CKY) algorithm is a dynamic programming algorithm for finding the most probably parse under a certain family of energy based models.

CKY is still the most accurate way to parse sentences where the energy based model is computed by a deep network.

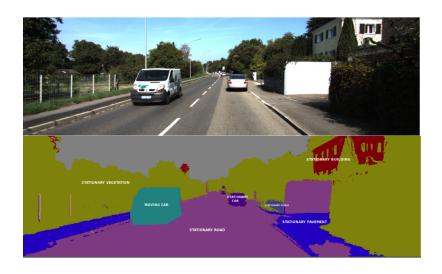
## Speech Recognition and CTC

Consider the case where x is the sound wave from a microphone and y is the transcription into written language. There are clearly exponentially many possible transcriptions.

Connectionist Temporal classification (CTC) is a dynamic programming algorithm for finding the most likely output under a certain family of energy based models.

CTC is still the most accurate way to do speech recognition where the energy based model is computed by a deep network.

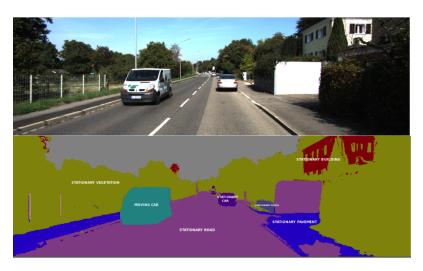
# Semantic Segmentation



We want to assign each pixel to one of L semantic classes.

For example "person", "car", "building", "sky" or "other".

## Semantic Segmentation



Although semantic segmentation is not currently done with energy based models, perhaps it should be.

Semantic segmentation is simpler than parsing or speech recognition and will be used as a simple example of energy based models.

## Distributions on Exponentially Large Sets: Notation

x is an input (e.g. an image).

 $\hat{\mathcal{Y}}[N]$  is a potential structured label for x — a vector  $\hat{\mathcal{Y}}[0], \dots, \hat{\mathcal{Y}}[N-1]$  with  $\hat{\mathcal{Y}}[n]$  an integer in  $\{1, \dots, L\}$ .

For example n might range over the pixels of an image and  $\hat{\mathcal{Y}}[n]$  names one of L a semantic labels for pixel n.

 $\mathcal{Y}[N]$  is the gold label for input x — the structured label assigned to x in the training data.

# **Exponential Softmax**

$$P_s(\hat{\mathcal{Y}}) = \operatorname{softmax}_{\hat{\mathcal{Y}}} s(\hat{\mathcal{Y}})$$
 all possible  $\hat{\mathcal{Y}}$ 

cross-entropy loss =  $-\ln P_s(\mathcal{Y})$  gold label (training label)  $\mathcal{Y}$ 

# Compactly Representing Scores on Exponentially Many Labels

We will call n a "node".

We will compute a "node potential" tensor  $s^N[N, L]$  that holds NL scores — a score each possible assignment of a label  $\ell$  to n.

We assume a set E of "edges" with  $E \subseteq N \times N$ .

We will compute an "edge potential" tensor  $s^{E}[E, L, L]$  that holds ELL scores — a score for each assignment of class labels  $\ell_1$  and  $\ell_2$  to the two nodes in the edge e.

#### Computing Scores

$$\frac{s(\hat{\mathcal{Y}})}{s} = \sum_{n} s^{N}[n, \hat{\mathcal{Y}}[n]] + \sum_{\langle n, m \rangle \in E} s^{E}[\langle n, m \rangle, \hat{\mathcal{Y}}[n], \hat{\mathcal{Y}}[m]]$$

The exponential softmax for scores of this form are intractible in general — the partition function  $Z_s$  requires summing over an exponentially large set and computing  $P_s(\mathcal{Y})$  is #P hard.

## Computing the Node and Edge Potential Tensors

For input x we use a network to compute the score tensors.

$$s^N[N,L] = f_{\Phi}^N(x)$$

$$s^{E}[E, L, L] = f_{\Phi}^{E}(x)$$

#### Back-Propagation Through Exponential Softmax

$$s^{N}[I,L] = f_{\Phi}^{N}(x)$$
  
$$s^{E}[E,L,L] = f_{\Phi}^{E}(x)$$

$$s(\hat{\mathcal{Y}}) = \sum_{n} s^{N}[n, \hat{\mathcal{Y}}[n]] + \sum_{\langle n, m \rangle \in \text{Edges}} s^{E}[\langle n, m \rangle, \hat{\mathcal{Y}}[n], \hat{\mathcal{Y}}[m]]$$

$$P_s(\hat{\mathcal{Y}}) = \operatorname{softmax} \ s(\hat{\mathcal{Y}}) \ \text{all possible } \hat{\mathcal{Y}}$$

$$\mathcal{L} = -\ln P_s(\mathcal{Y})$$
 gold label  $\mathcal{Y}$ 

We want the gradients  $s^N$ .grad[N, L] and  $s^E$ .grad[E, L, L].

# $\mathbf{END}$