

IMAGE AUTO-ORIENTATION

ADVANCED MACHINE LEARNING - A.A. 2020/2021

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PROBLEM STATEMENT

Correctly rotating an image is a simple task for a human being, but it turns out to be a real challenge for a computer.

Most applications in the world of computer vision require images to be properly oriented before they can be processed.







THE GOAL

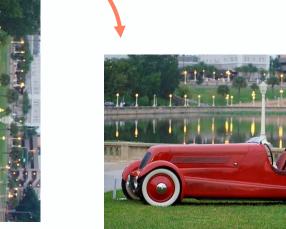
However rotating images is a tedious, time-consuming and error-prone activity.

The goal is therefore to exploit convolutional neural networks (CNNs) to automatically orient the images by multiple angles of 90°.









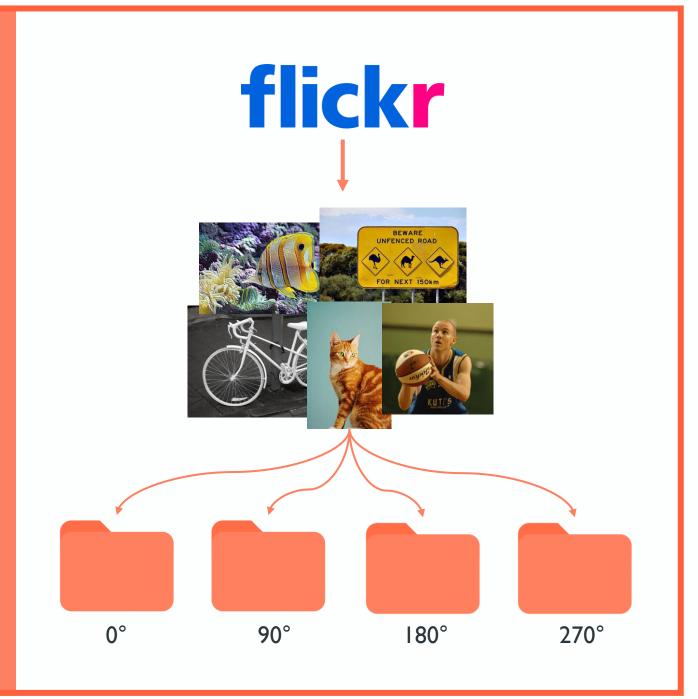


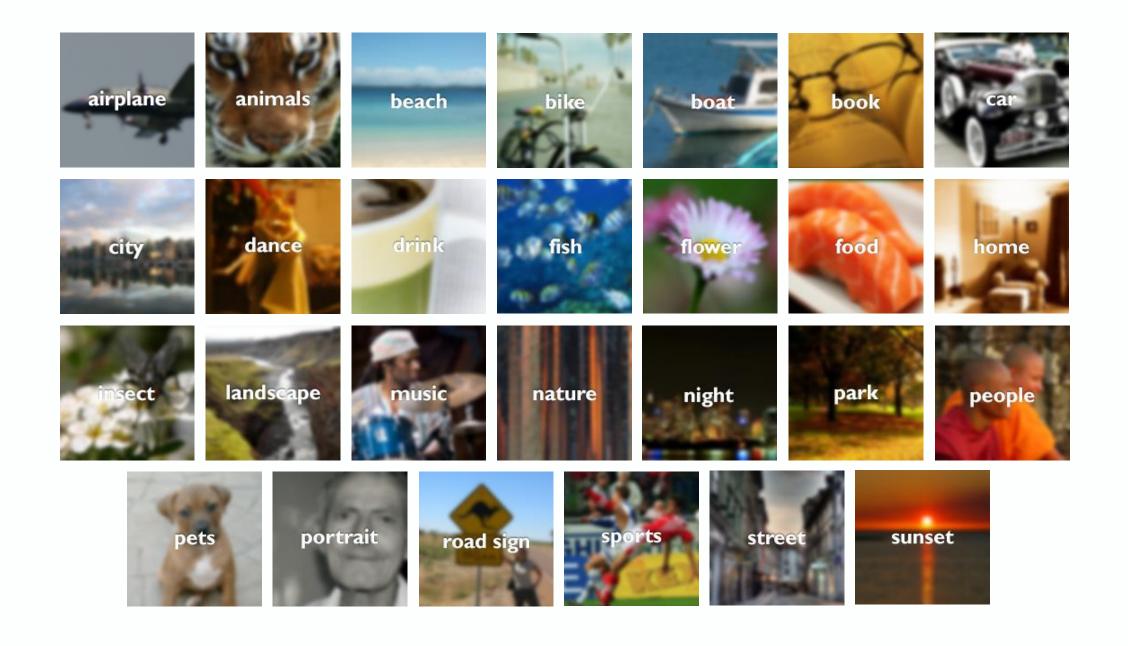
THE DATASET

The dataset is built from scratch using the APIs provided by Flickr.

27 of the most popular tags of all time and of the week were selected in order to obtain a generic dataset.

The images were artificially rotated in order to obtain a balanced dataset, consisting of 151,640 photographs.





ADDITIONAL DATASETS

Other famous datasets were selected in order to test the performance of the models on images that are different from those that can be found on flickr.

SUN2012



PASCAL VOC 2012



INRIA HOLIDAYS



IMAGE PADDING

The dataset is composed of images of various resolutions, while the CNNs used for the task work with inputs of 224x224 pixels.

For this reason, it has been decided to pad the pictures with black pixel, in order for the output to be a square.





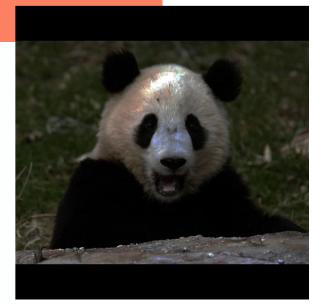
DATA AUGMENTATION

Using ImageDataGenerator from Keras, random transformations to input samples were applied during network training.

brightness_range and channel_shift_range have been chosen as parameters.







OVERVIEW

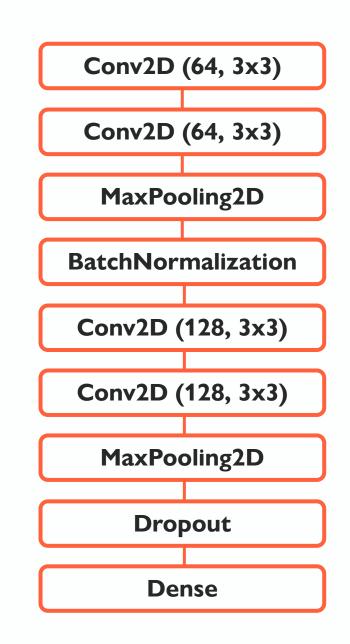


CUSTOM MODEL

The first model proposed for image orientation detection has been built from scratch.

The idea was to develop a simple neural network, with a restricted number of layers.

The results were good, but not completely satisfying.



train accuracy

73.53%

val. accuracy

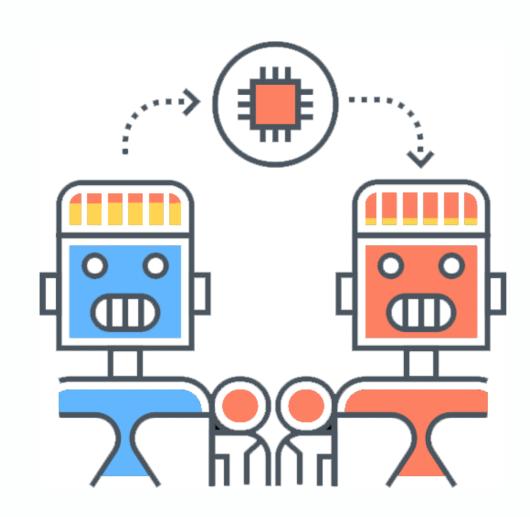
73.25%

TRANSFER LEARNING

Transfer learning is a machine learning method where a model developed for a task is reused as the starting point for a model on a second task.

Three models were selected:

- VGG16
- MobileNetV2
- DenseNet201



VGG16

Only the last part of the architecture has been replaced by the following layers:

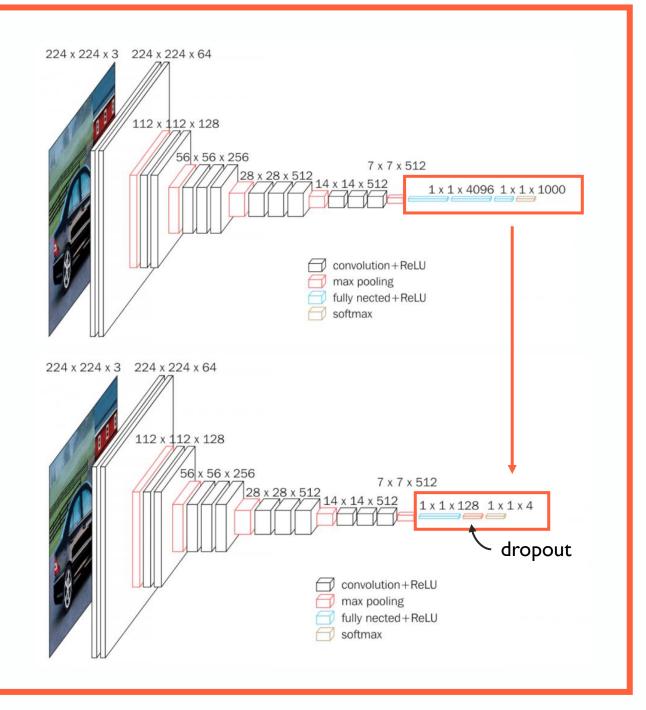
- dense (128, ReLU)
- dropout (0.7)
- dense (4, Softmax)

train accuracy

93.42%

val. accuracy

92.43%



MOBILENETV2

Just like before, only the last part of the architecture has been replaced by the following layers:

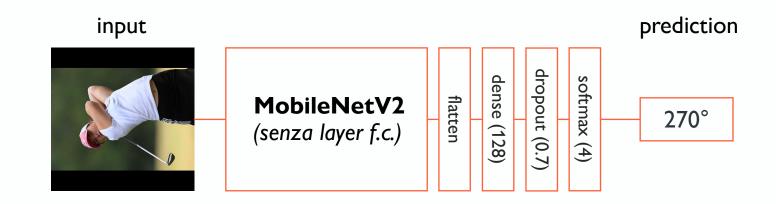
- dense (128, ReLU)
- dropout (0.7)
- dense (4, Softmax)

train accuracy

97.56%

val. accuracy

93.32%



DENSENET201

The network structure was left unchanged.

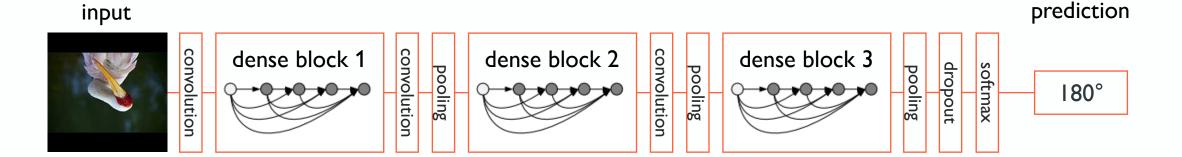
A dropout layer has been added and the last one has been replaced with a softmax.

train accuracy

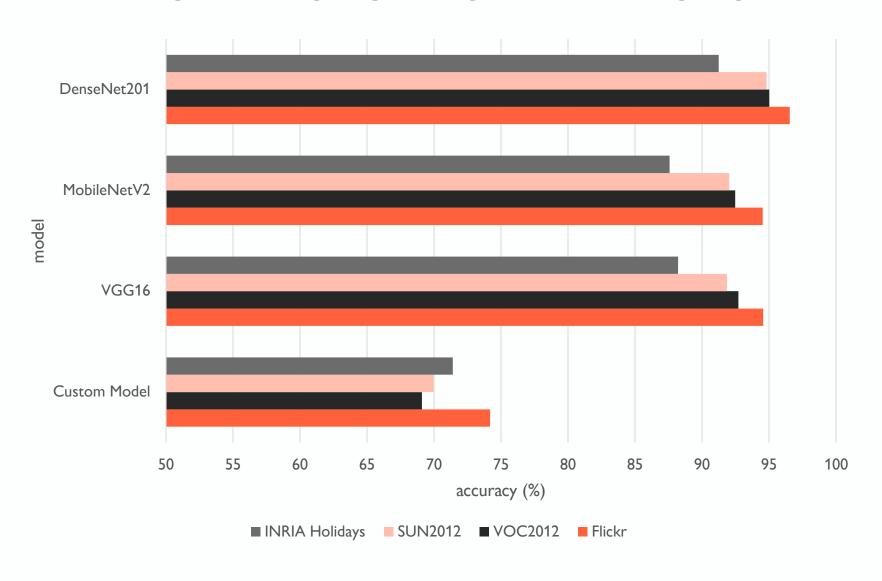
96.64%

val. accuracy

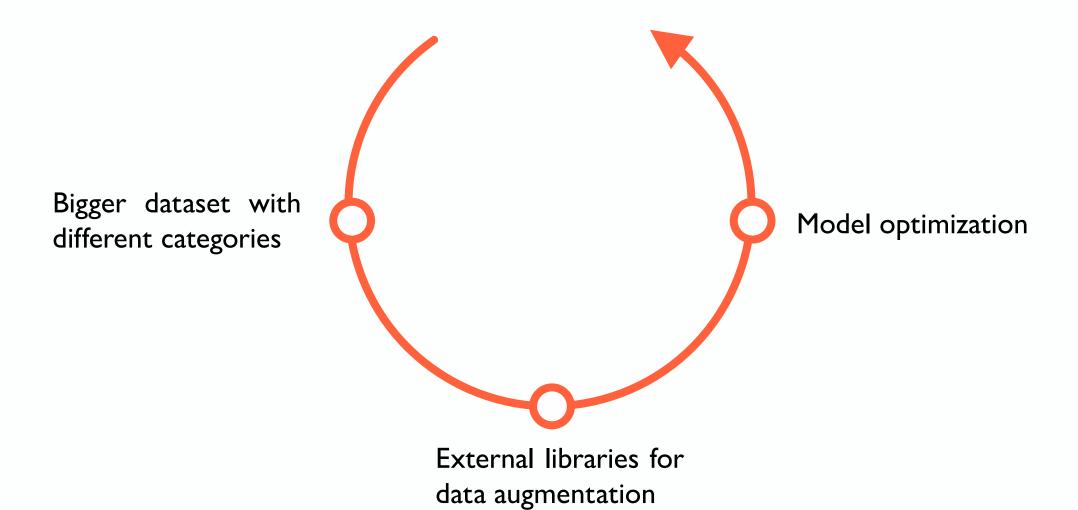
95.02%



PERFORMANCE ON MULTIPLE TEST SET



FUTURE IMPROVEMENTS



THANK YOU FOR YOUR ATTENTION